

A Review on SOCP Relaxations for QCQP

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The QCQP

We consider the QCQP,

$$\begin{aligned} \text{(HCQP)} \quad & \max \quad x^T Q x \\ \text{s.t.} \quad & x^T A_i x (\leq, =, \geq) b_i, \forall i = 1, \dots, m \\ & 0 \leq x \leq 1 \end{aligned} \tag{1}$$

and inhomogeneous QCQP,

$$\begin{aligned} \text{(QCQP)} \quad & \max \quad x^T Q x + q^T x \\ \text{s.t.} \quad & x^T A_i x + a_i^T x (\leq, =, \geq) b_i \\ & 0 \leq x \leq 1 \end{aligned} \tag{2}$$

Dilemma of SOCP relaxations

Scale every indefinite inequalities.

$$\begin{aligned} \max \quad & z \\ \text{s.t.} \quad & z - x^T Q x \leq 0 \\ & x^T (A_i) x + a_i^T x \leq b_i \cdot s, i = 1, \dots, m \end{aligned} \tag{3}$$

In the above case, let $t_i = \lambda_{\max}(Q_i)$, convexify by maximum eigenvalue. Call this **SCALE**

$$\begin{aligned} z + x^T (t_i I_n - Q_i) x &\leq t_i s \\ \|x\|^2 &= s \end{aligned}$$

1. Relaxation bounds are worse than SDR
2. Cannot produce feasible solutions along the way
3. Need more cutting planes

Recent results related to QP

1. **Aggregation** Second-order Cone Representable (SOCPr) sets and hidden convexity. [BTDH14].
2. **Aggregation** Aggregation based convexification. For two quadratic functions, [BKK17], [MV17]. For three quadratic functions [DMS21]
3. **Aggregation** Intersection of a quadratic set and polytope. [SD20]
4. **Maximal-S-Free** Maximal S-free sets, [CCD⁺15], [Mic13]. Note [Mic13] also discuss how to lift first-order cut planes for general quadratic function over nonconvex sets.
5. †Simultaneous Diagonalization ..., [Jia16], [WJ21], [WKK20]
6. †Disjunctive programming

† 5, 6 not yet covered. 1, 2 can be used to tighten convex relaxation. 4. use to generate cuts. 3. to be investigated.

Aggregation: idea I

Definition

(Aggregation of inequalities) Given a set of inequalities

$$X = \{x : f_i(x) \leq 0, i = 1, \dots, m\}$$

An aggregation by $\lambda \in \mathbb{R}_+^m$ is defined as,

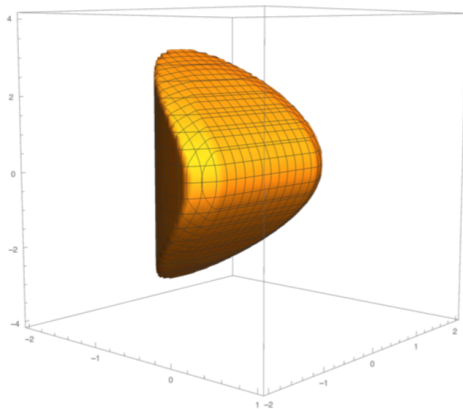
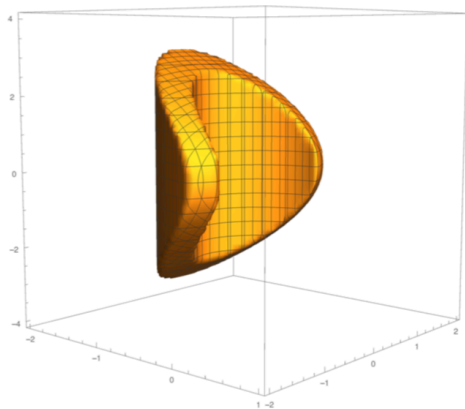
$$X(\lambda) = \left\{ x : \sum_i \lambda_i \cdot f_i(x) \leq 0 \right\} \quad (4)$$

Definition

(SOCPr sets) A cone F_+ is SOCr if it can be expressed as $F^+ = \{x : \|B^T x\| \leq b^T x\}$, where nonzeros columns in B are independent and $b \notin \text{range}(B)$

Aggregation: idea II

Some Illustration (Three quadratic functions) Example by [DMS21] and constructed convex hull



Aggregation for two inequalities

Consider intersection of two quadratic function.

$$F_0 = \{x : x^T A_0 x \leq 0\}, F_1 = \{x : x^T A_1 x \leq 0\}$$

$$F_s = \{x : x^T A_s x \leq 0\}, A_s = sA_1 + (1 - s)A_0$$

- ▶ Suppose F_0 is SOCr, F_1 is a general quadratic set.
- ▶ (2017) [BKK17] shows a unified approach to convexify intersection, similar results in [MV17], useful in Trust-region subproblems. problems like $\|x\|^2 \leq s$
- ▶ (2020) [SD20] consider one Q-constraint over a polytope, applied in a bilinear bipartite graph problem.
- ▶ (2021) [DMS21] shows conditions for existence of aggregation for three quadratic constraints.
- ▶ No easy answer to intersection of arbitrary number of Q-constraints

Some potential improvements to SOCP relaxations I

Problem: **SCALE** method is actually producing convex hull of,

$$\begin{aligned}x^T Q_i x + q_i x + b_i &\leq 0 \\ \|x\|^2 &\leq s\end{aligned}$$

verified by [BKK17], but we have to estimate s .

Workaround: use box $x \in [l, u]$ to replace $\|x\|^2 \leq s$, for any $\Sigma \succeq 0$

$$(x - l)^T \Sigma (x - u) \leq 0 \tag{5}$$

When $\Sigma \succeq 0$, it is an ellipsoid covering the box.

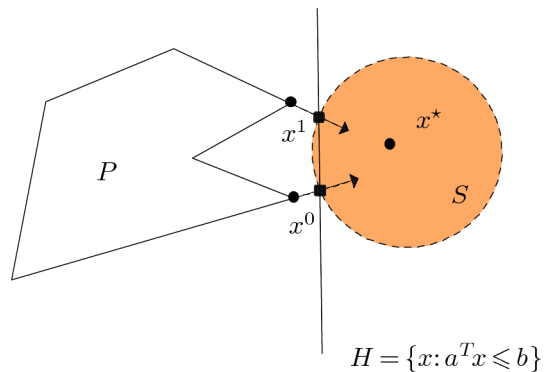
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Maximal S-Free and intersection cuts

Linear relaxation and quadratic free, [CMS21], illustration



Maximal S-Free and lifting

Lift a first order underestimation,

Consider $x^T Q x$ convex and minimize over $R^n - \text{int}(P)$, P is a good convex set like polytope.

$$\begin{aligned} z &\geq x^T Q x \\ &\geq 2y^T Q (x - y) + y^T Q y, \forall y \end{aligned}$$


$$\textbf{Lifting: } \dagger \alpha, p \quad \geq (2y^T Q + \alpha \cdot p^T)(x - y) + y^T Q y, \forall y$$


Get α, p by solving an optimization problem. \dagger is feasible for all $y \notin P$ **LFO**


Future Work

1. ~~Implement the workaround for $\|x\|^2 \leq s$~~
2. In **LFO** and **convexification**, both has to figure out a proper convex set P .
3. Summarize the readings in **disjunctive** and **simultaneous diagonalization**.

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