

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

Drift Potentials and Fields

Stepping

Software

To do

# Weighting Potential

Shockley-Ramo construction:

1. Identify one electrode,  $k$ .
2. Set to unit voltage, all others set to 0V.
3. Calculate its *weighting* potential  $\phi_{\text{weight},k}$  in the volume.
4. Calculate the associated E-field  $\vec{E}_{\text{weight},k}$ .
5. Calculate the overall *drift* potential and E-field  $\vec{E}_{\text{drift}}$ .

Induced current on the electrode  $k$  from charge  $q$  moving with velocity  $\vec{v}$ :

$$i_k = q \vec{E}_{\text{weight},k} \cdot \vec{v}$$

And, electron drift velocity, for given mobility  $\mu$ :

$$\vec{v} = \mu \vec{E}_{\text{drift}}$$

# Boundary Element Method for Electrostatic Potential

1. Discretize (mesh) boundary electrodes.
2. Define potential on each mesh element.
3. Integrate Laplace  $\nabla^2\phi = 0$ .
4. Fit integral equations to boundary values.
5. Evaluate solution on points in the volume.

# Element Methods: Boundary vs. Finite

## BEM

- ▶ Meshes the surfaces.
- ▶ Fast for low surface-to-volume.
- ▶ Performance relies on relatively new math discoveries.
- ▶ Relatively few software implementations.

## FEM

- ▶ Meshes the volume.
- ▶ Fast for high surface-to-volume.
- ▶ Adaptive meshes can improve performance.
- ▶ Many implementations, heavily used in industry.

# Stepping

Evolution of position  $\vec{r}_k \equiv \vec{r}(t_k)$  from step  $k$  to  $k + 1$ :

$$\vec{r}_k \rightarrow \vec{r}_{k+1} = \vec{r}_k + \vec{v}(\vec{r}_k) \times \Delta t_k$$

Use **Adaptive Runge-Kutta + Cash/Karp** ( $\sim 5^{\text{th}}$  order)

- ▶ From Numerical Recipes
- ▶ Take two different 6th order steps.
- ▶ Distance between each estimates error.
- ▶ Adjust  $\Delta t_{k+1}$  based on error
- ▶ Hugely more efficient than simple RK4
- ▶ Must still watch for stepping to get stuck at maximum.

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

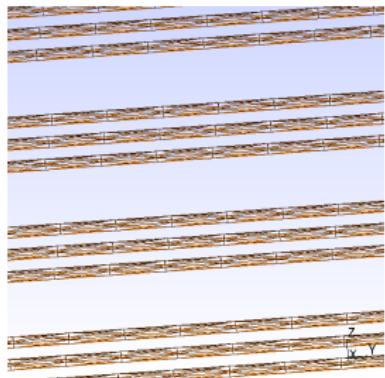
Drift Potentials and Fields

Stepping

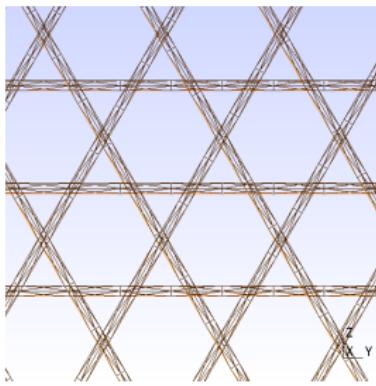
Software

To do

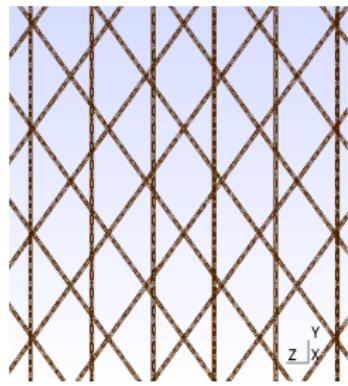
# Wires Meshes



“Parallel”:  
3mm pitch and gap  
all wires parallel

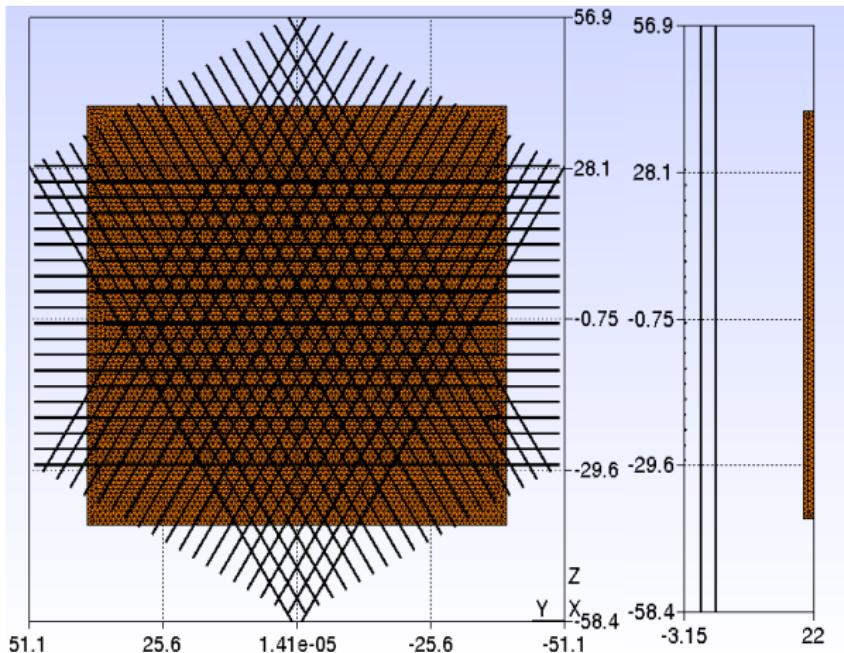


“MicroBooNE”:  
3mm pitch and gap  
 $60^\circ$  angles for U/V.



“DUNE”:  
5mm pitch and gap  
 $35.7^\circ$  angles for U/V.

# Add Cathode (MicroBooNE)



- ▶ “Cathode” is near wires with voltage adjusted to give 500V/cm.
- ▶ Do calculations at center, far enough away from edge effects.

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

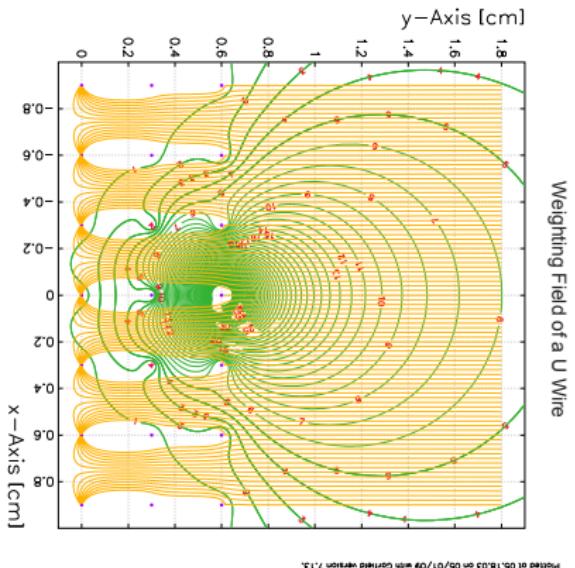
Drift Potentials and Fields

Stepping

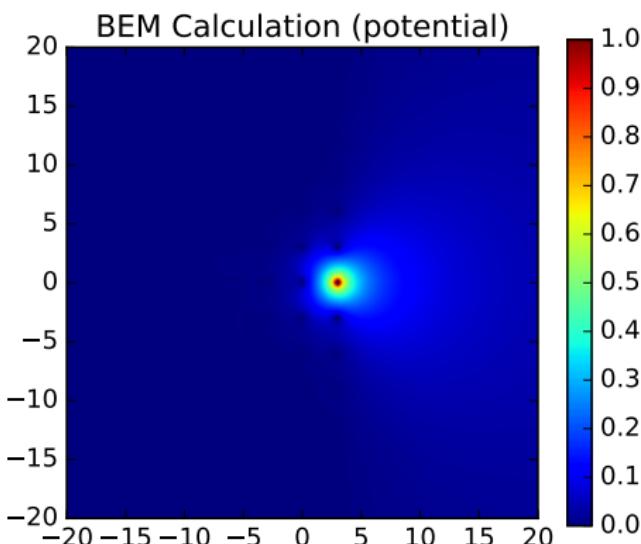
Software

To do

# Weighting Potential - 2D vs “2D”



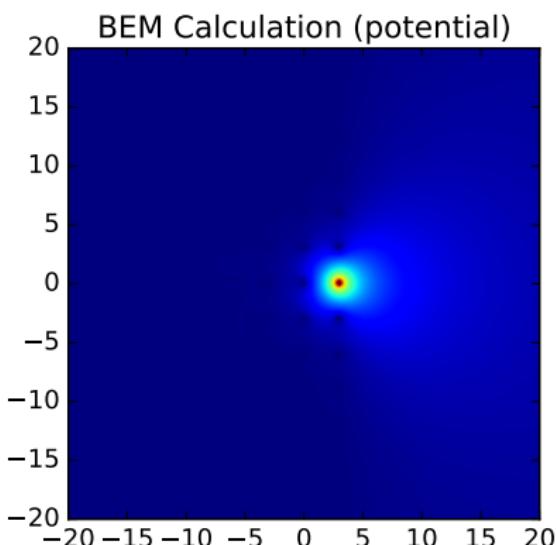
Garfield 2D calculation from Bo



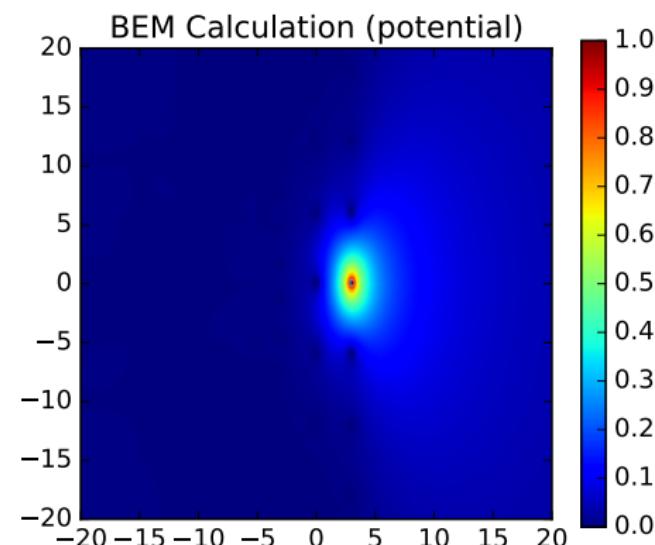
3D BEM, parallel wires, sliced at  $Y=0$ .

Initial, qualitative agreement. More checks needed.

# Weighting Potential - 2D vs. 3D wire pattern



Parallel wires



MicroBooNE wires.

Clear distortion in extent and shape. Not surprising.

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

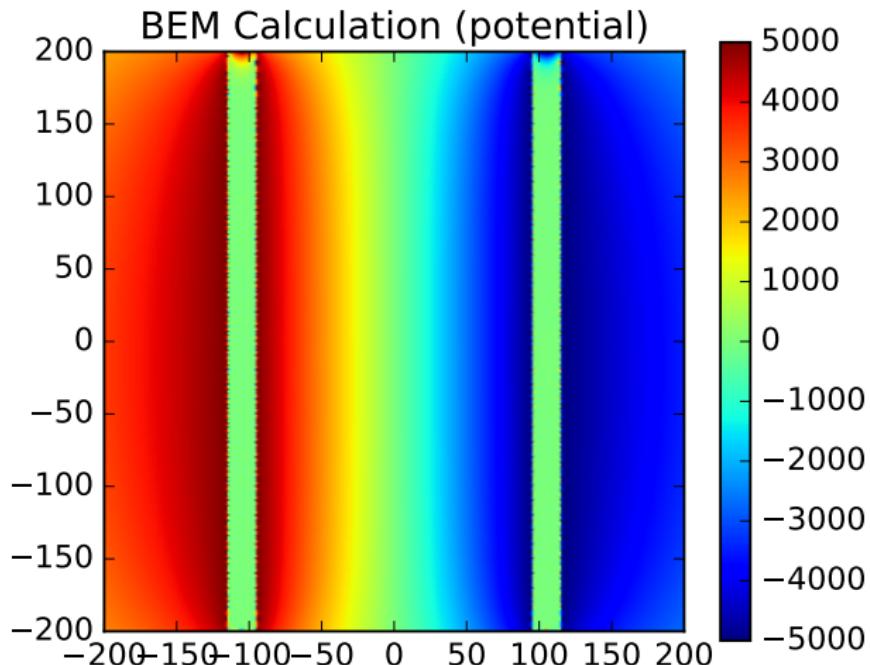
Drift Potentials and Fields

Stepping

Software

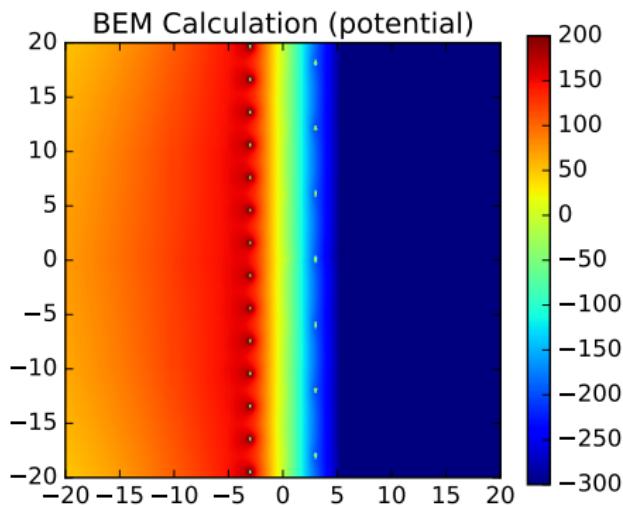
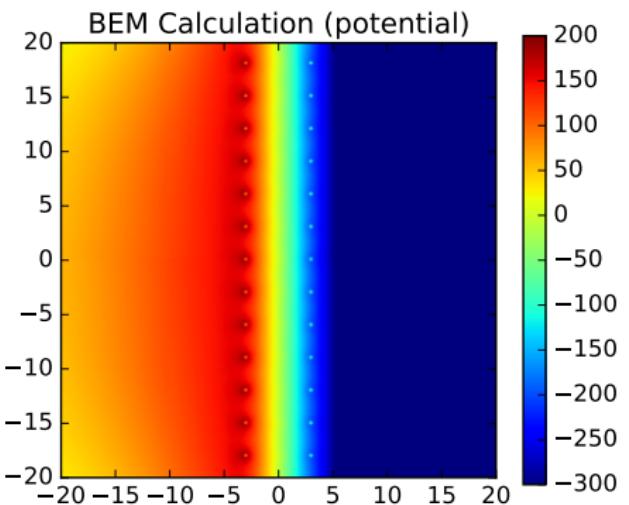
To do

# Capacitor



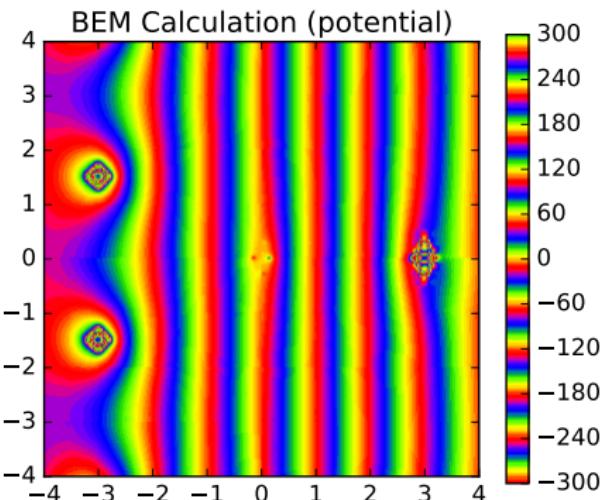
Simple test with parallel-plates at +/-5000V.

# Drift Potential - 2D vs. 3D wire pattern

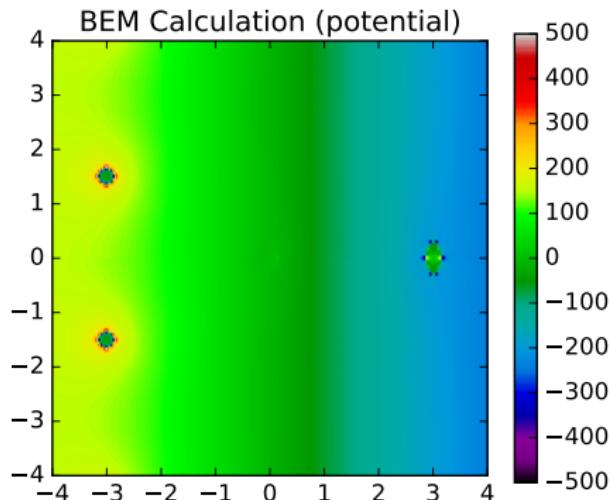


Electrodes (from left-to-right) W → V → U → Cathode (off scale)

# Problem: Mesh Granularity



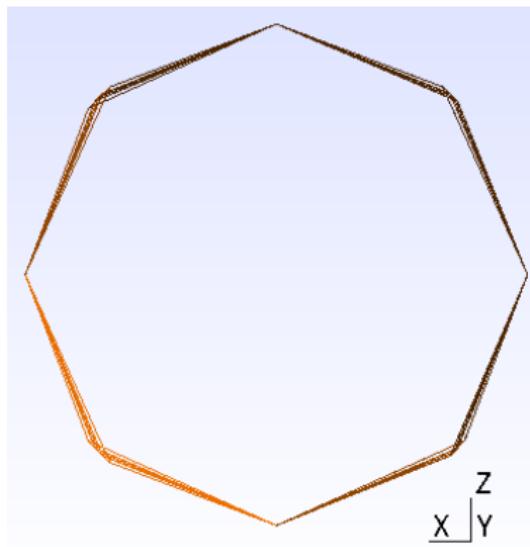
Major features look okay.



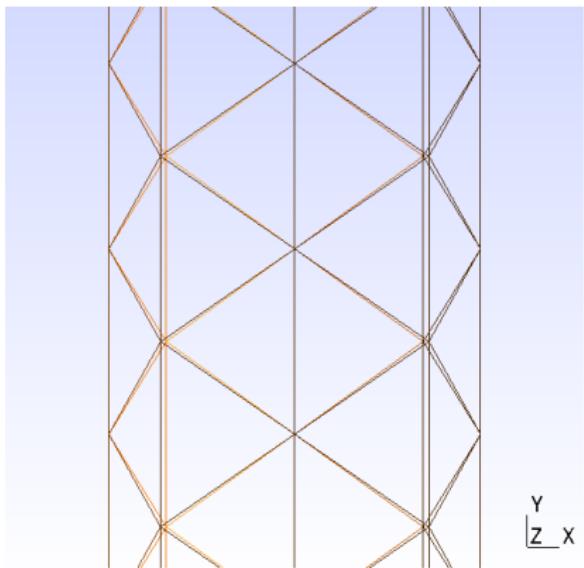
Large +/- fluctuations near wires.

- Drift potential has large fluctuations right near the wires.

# Wire Mesh Closeup



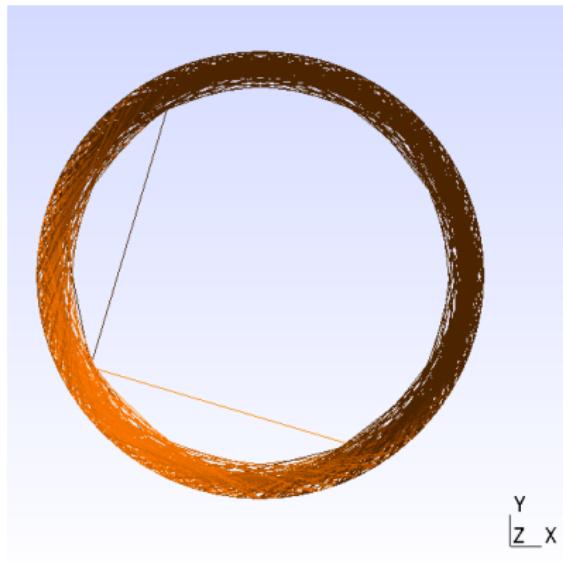
Wire cross section.



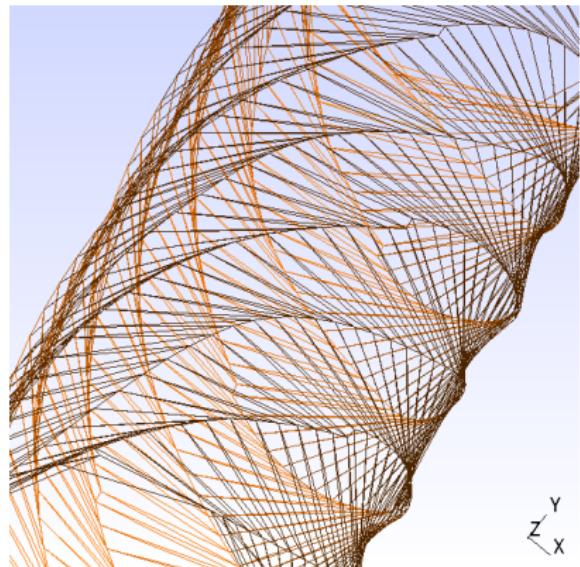
Wire side view.

- ▶ Trade-off between mesh granularity and CPU time.

# Mitigation: better mesh modeling



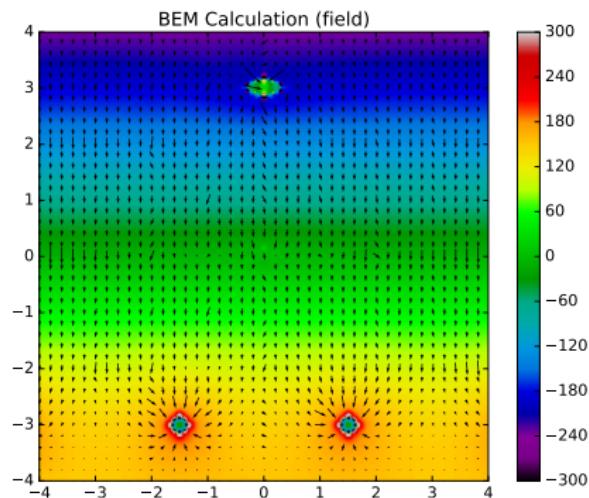
Wire cross section.



Wire side view.

- ▶ Increase number of circular segments
- ▶ Rotate circle through wire extrusion.

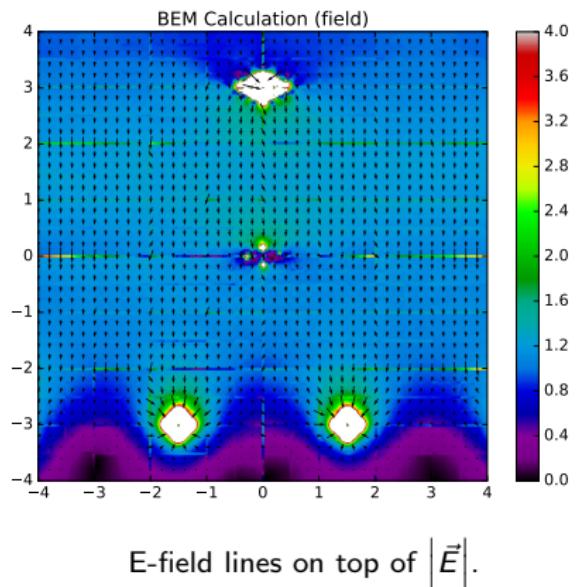
# An Initial E-Field Calculation



E-field lines on top of potential.

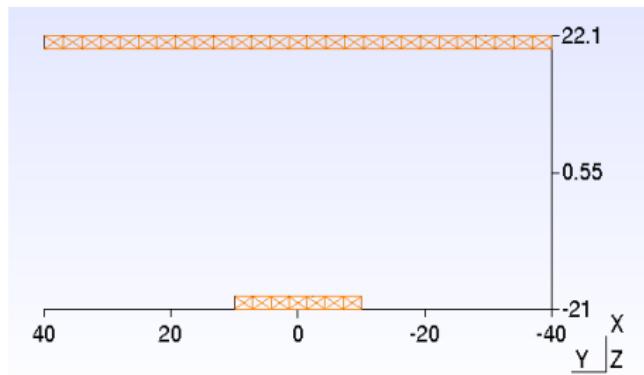
- ▶ This still uses the coarse wire mesh.
- ▶ Hint of a problem in some of the field lines

# Problem: Field Artifacts



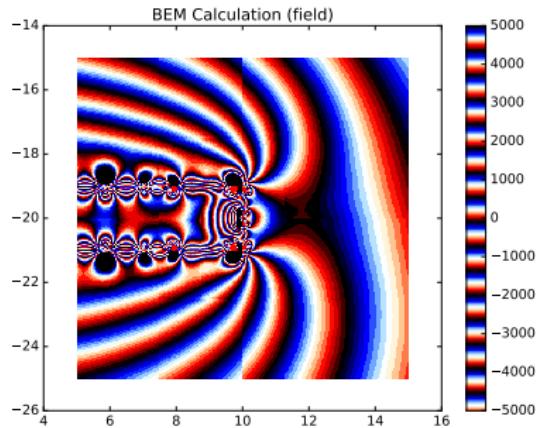
- More sensitive color scale shows clear artifacts at “special” values of the domain.

# Setup to look at artifacts

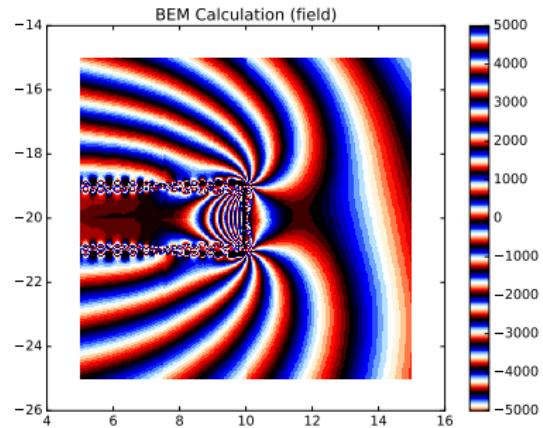


Construct simple asymmetric capacitor and focus on the end of the little electrode.

# Source of artifacts found



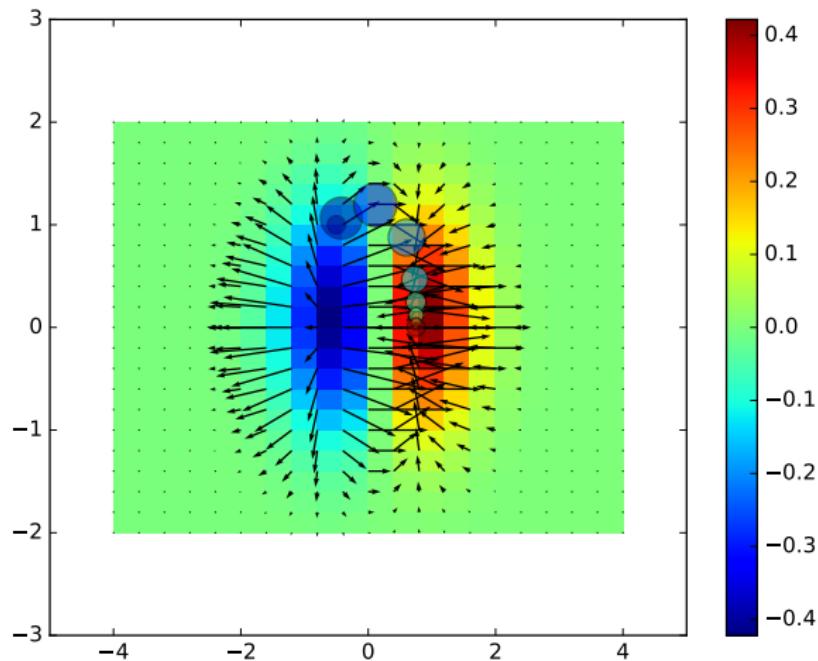
Nominal BEM precision.



Quadrupled BEM precision.

- ▶ BEM integrals evaluates potentials at points on pairs of triangles.
- ▶ Number of points determines precision
- ▶ BEM++ defines precision on 3 inter-triangle distance scales.

# Initial Stepping Tests



This is a made up "velocity potential". Arrows show local velocity. Circles are steps with time as color and step distance as area.

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

Drift Potentials and Fields

Stepping

Software

To do

# Main Dependencies

## BEM++

- ▶ Solves Laplace, Helmholtz and Maxwell eqns using BEM
- ▶ C++ with Python interface.
- ▶ General, but low-level. Requires some understanding.
- ▶ Multithreaded.

## GMSH

- ▶ 3D Grid generator and visualization.
- ▶ Volume and surface meshes.
- ▶ Interactive and scripted geometry definition.

## Python:

- ▶ NumPy, Matplotlib and **LARF**

# LARF - Liquid ARgon TPC Field Calculator

For now, code lives at:

<https://github.com/brettviren/larf>

```
$ larf mesh -o uboone.msh ubone
$ gmsh uboone.msh      # <-- to visualize the generated mesh
$ larf solve -d 11 -g near -o uboone-near-d11.npz uboone.msh
$ larf plot -p near -o uboone-near-d11.pdf uboone-near-d11.npz
```

Processing directed by a `larf.cfg` configuration file, specify things like:

- `geometry` naming the mesh generators and parameters
- `problem` to solve (weighting vs drift)
- `gridding` to use for both the solution and any plots
- `plot` describing what plotting code to apply to a solution

- ▶ Solution results are saved as Python NumPy array files.
- ▶ Will extend this as the to-do list is tackled.

# Status of Field Calculations

Methods

Geometries

Weighting Potentials

Drift Potentials and Fields

Stepping

Software

To do

# Much Still To Do

- ▶ Include calculations for DUNE detector geometry.
- ▶ Visualize E-fields, do more careful comparisons to 2D results.
- ▶ Go from 2D slices to full 3D volumetric data.
- ▶ Dynamics:
  - ▶ Charge drifting and wire-current signal generation.
  - ▶ Let's make a new simulated animation!
- ▶ Responses as a function of position.
  - ▶ Repeat Yichen's study on intra- and inter-wire-regions
- ▶ Finally, develop some response functions for signal extraction.
  - ▶ How detailed? (per-plane?, per wire?)
  - ▶ How to validate?
- ▶ Other ideas:
  - ▶ Jim: Edge effects near field cage, TPC-TPC gaps, inside APA.
  - ▶ Milind: calculate transparency of induction planes.
  - ▶ Others?

# Other Efforts - FEM

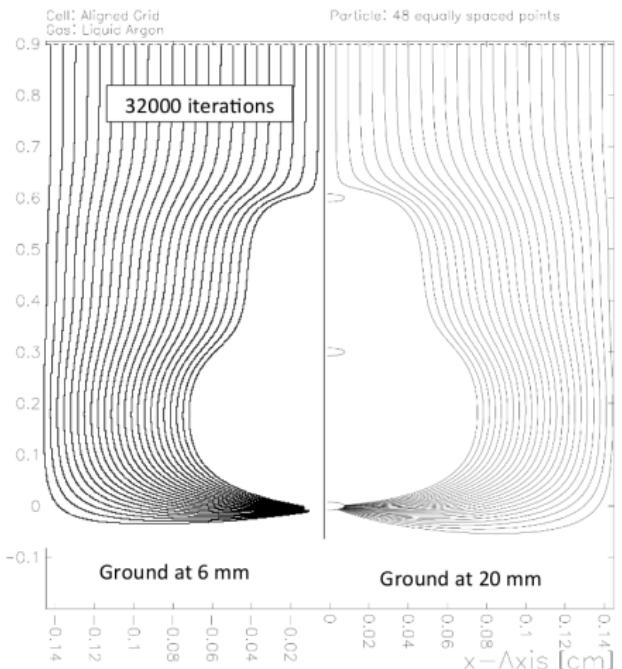
Leon Rochester @ SLAC

- ▶ MicroBooNE DocDB 5892
- ▶ FEM using custom code ("DIY Garfield")
- ▶ C++ rewritten from ICARUS FORTRAN.
- ▶ Good looking initial results on drift field and with particle stepping.
- ▶ I expect we will do a systematic comparison at some point.

Manhong Zhao @ BNL

- ▶ Initial discussions to do FEM using ANSYS + the "multi physics" module.
- ▶ Beefy workstation on order.

**Not to forget hardware-based measurements!**



Left half is Leon's FEM after 32k iterations with Garfield 2D on right half.