# Lecture 14 Concurrency

CS213 – Intro to Computer Systems Branden Ghena – Winter 2025

Slides adapted from:

St-Amour, Hardavellas, Bustamente (Northwestern), Bryant, O'Hallaron (CMU), Garcia, Weaver (UC Berkeley)

#### Administrivia

Attack Lab due Today

- SETI Lab releases soon
  - Today's lecture has 90%+ of the information you need for it
    - And everything you need to get started
  - Next Tuesday's lecture will add a few more details about optimization that could be helpful
    - But you don't really need it at all, and you certainly don't need it to do most of the work in the lab
- Reminder: no lecture on Thursday

# Today's Goals

Discuss goals of concurrency and how it is achieved in software

Understand the challenges of writing parallel software

Explore how to practically use parallelism for simple examples

#### **Outline**

Need for Parallelism

Processes and Threads

Concurrency Challenges

Using Threads

It's the mid 1990s and you work at Microsoft.

You need to double the speed of Excel in two years.

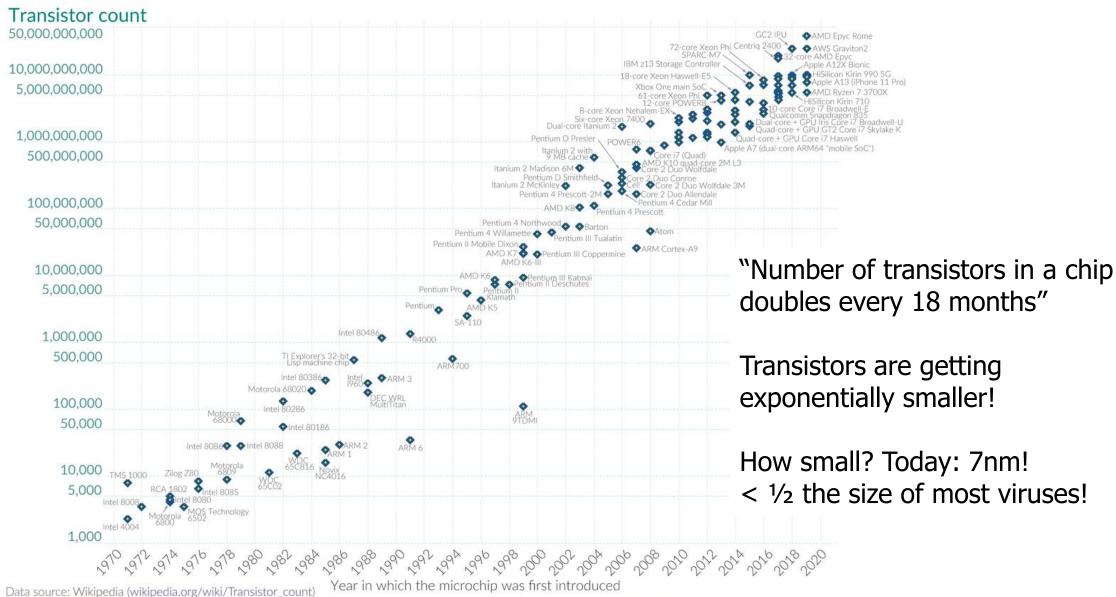
What do you do?

It's the mid 1990s and you work at Microsoft.

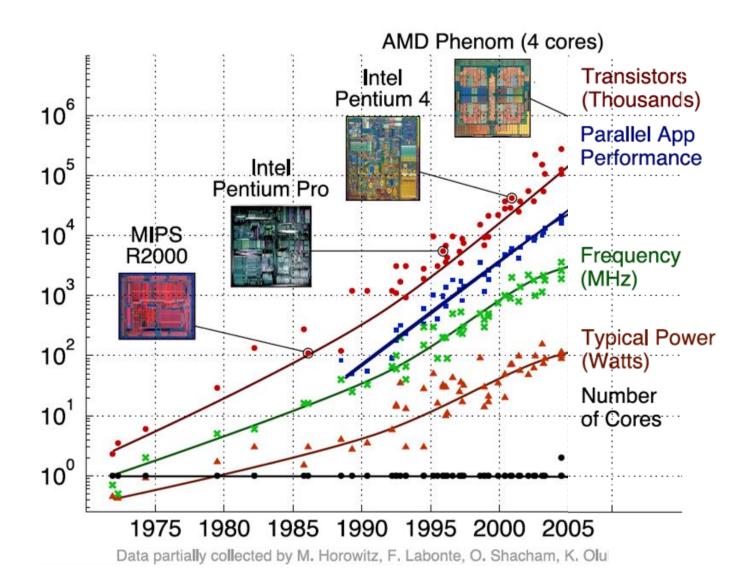
You need to double the speed of Excel in two years.

What do you do? **Take a vacation** 

#### Moore's Law – CPU transistors counts



# Processors kept getting faster too



### Power is a major limiting factor on speed

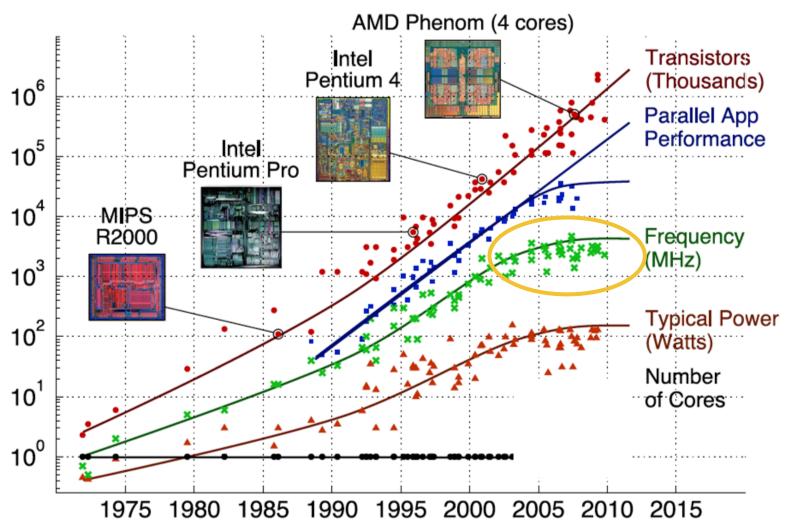
- We could make processors go very fast
  - But doing so uses more and more power
- More power means more heat generated
  - And chips typically work up to around 100°C
  - Hotter than that and things stop working
- We add heat sinks and fans and water coolers to keep chips cool
  - But it's hard to remove heat quickly enough from chips
- So, power consumption ends up limiting processor speed

### **Denard Scaling**

- Moore's Law corollary: Denard Scaling
  - As transistors get smaller, the power density stays the same
  - Which is to say that the power-per-transistor decreases!
- Making the processor clock speed faster uses more power
  - But the two balance out for roughly net even power
  - So not only do we get *more* transistors, but chip speed can be *faster* too

- From our Excel example:
  - In two years, new hardware would run the existing software twice as fast

### Then they stopped getting faster



~2006: Leakage current becomes significant

Now smaller transistors doesn't mean lower power

Data partially collected by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond

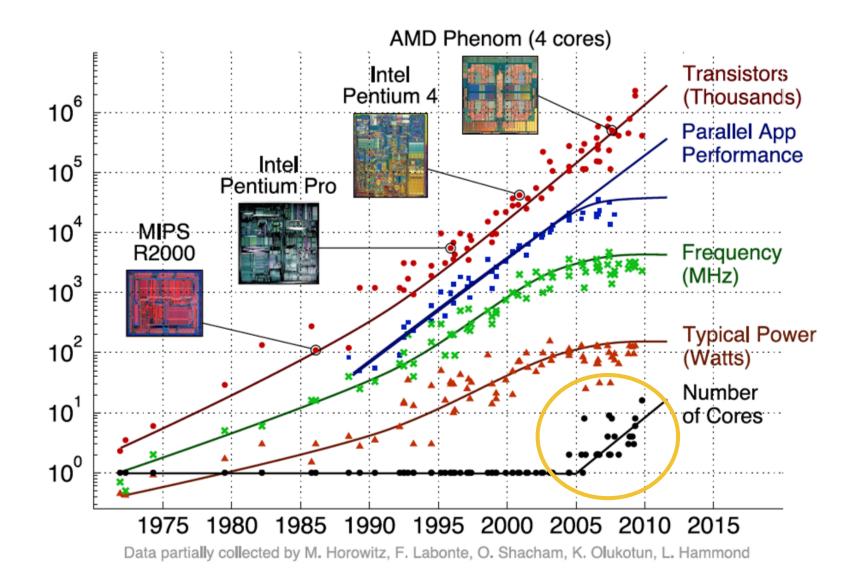
#### So... now what?

#### In summary:

- Making transistors smaller doesn't make them lower power,
- so if we were to make them faster, they would take more power,
- which will eventually lead to our processors melting...
- and because of that, we can't reliably make performance better by waiting for clock speeds to increase.

How do we continue to get better computation performance?

# Exploit parallelism!



# Parallelism Analogy

- I want to peel 100 potatoes as fast as possible:
  - I can learn to peel potatoes faster

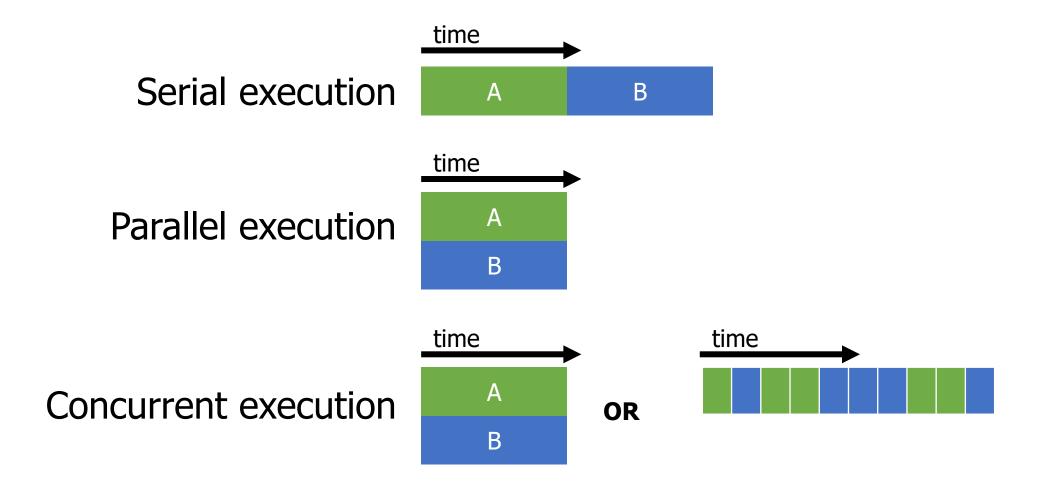
OR

- I can get 99 friends to help me
- Whenever one result doesn't depend on another, doing the task in parallel can be a big win!

### Parallelism versus Concurrency

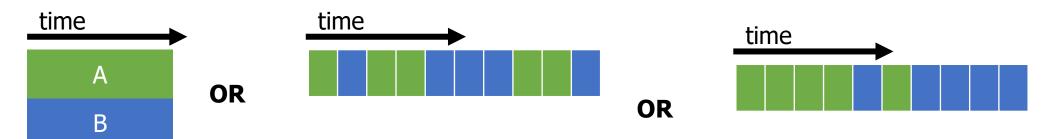
#### Two processes A and B





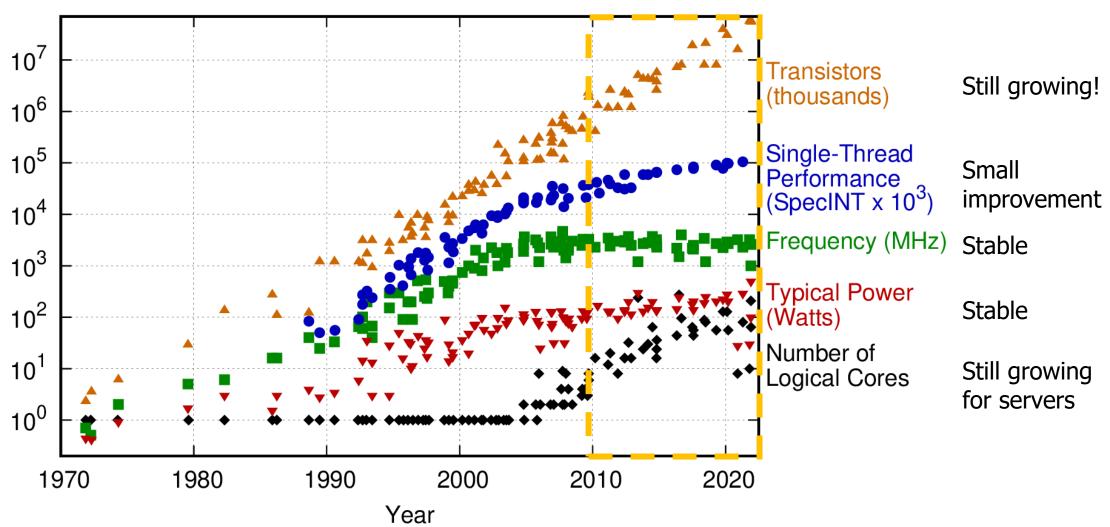
### Parallelism versus Concurrency

- Parallelism
  - Two things happen strictly simultaneously
- Concurrency
  - More general term
  - Two things happen in the same time window
    - Could be simultaneous, could be interleaved
  - Concurrent execution occurs whenever two processes are both active



#### Update: 2010-2021

#### 50 Years of Microprocessor Trend Data



Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten New plot and data collected for 2010-2021 by K. Rupp

#### **Outline**

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Using Threads

## How do we apply parallelism to software?

Goal: make computer faster by performing multiple tasks

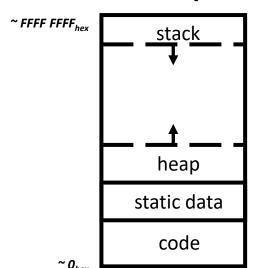
Need multiple different software tasks

- Two particular ways of creating a software task
  - Processes
  - Threads

### View of a process

- Process: a program that is currently being run
- Contents:

Address Space
 Registers



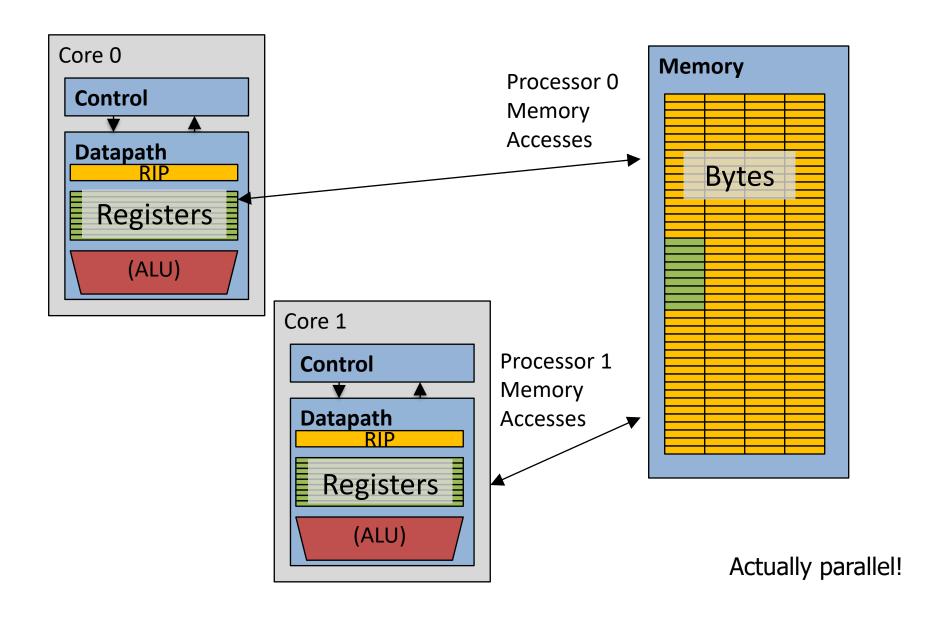
%rax	%eax	] %r8	%r8d
%rbx	%ebx	%r9	%r9d
%rcx	%ecx	%r10	%r10d
%rdx	%edx	%r11	%r11d
%rsi	%esi	%r12	%r12d
%rdi	%edi	%r13	%r13d
%rsp	%esp	%r14	%r14d
%rbp	%ebp	%r15	%r15d

- Instruction Pointer
- Condition Codes
- Etc.

#### Process use case: separate programs

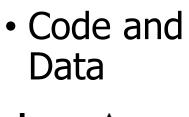
- Right now I am running:
  - Powerpoint
  - Chrome
  - Notion
- Each is a separate process
  - Have their own memory
  - Have their own registers
  - Operating System manages them
- No need for communication between them

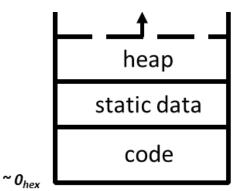
# Multiprocessor Systems (in pictures)



### Alternate view of a process

- Process: code and data, plus a thread
- Thread: execution state
  - Each process has at least one thread



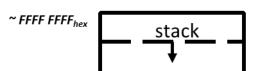


Registers

%rax	%eax	%r8	%r8d
%rbx	%ebx	%r9	%r9d
%rcx	%ecx	%r10	%r10d
%rdx	%edx	%r11	%r11d
%rsi	%esi	%r12	%r12d
%rdi	%edi	%r13	%r13d
%rsp	%esp	%r14	%r14d
%rbp	%ebp	%r15	%r15d

- Instruction Pointer
- Condition Codes

Stack

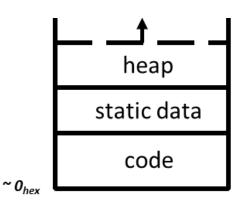


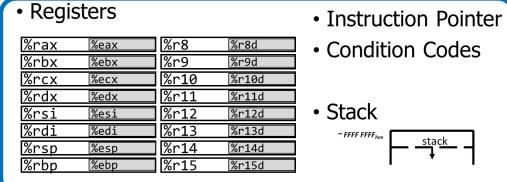
### Alternate view of a process

- A process could have multiple threads
  - Each with its own registers and stack

Registers

 Code and Data





ricgi	3(C) 3		
%rax	%eax	%r8	%r8d
%rbx	%ebx	%r9	%r9d
%rcx	%ecx	%r10	%r10d
%rdx	%edx	%r11	%r11d
%rsi	%esi	%r12	%r12d
%rdi	%edi	%r13	%r13d
%rsp	%esp	%r14	%r14d
%rbp	%ebp	%r15	%r15d

#### Threads have separate:

- Instruction Pointer
- Registers
- Stack Memory
- Condition Codes

#### Threads share:

- Code
- Global variables

#### Thread use case: web browser

Let's say you're implementing a web browser:

You want a tab for each web page you open:

- Each tab is its own thread
- The same code loads each website (shared code section)
- The same global settings are shared by each tab (shared data section)
- Each tab does have separate state (separate stack and registers)

Disclaimer: Actually, modern browsers use separate processes for each tab for a variety of reasons including performance and security. But they used to use threads.

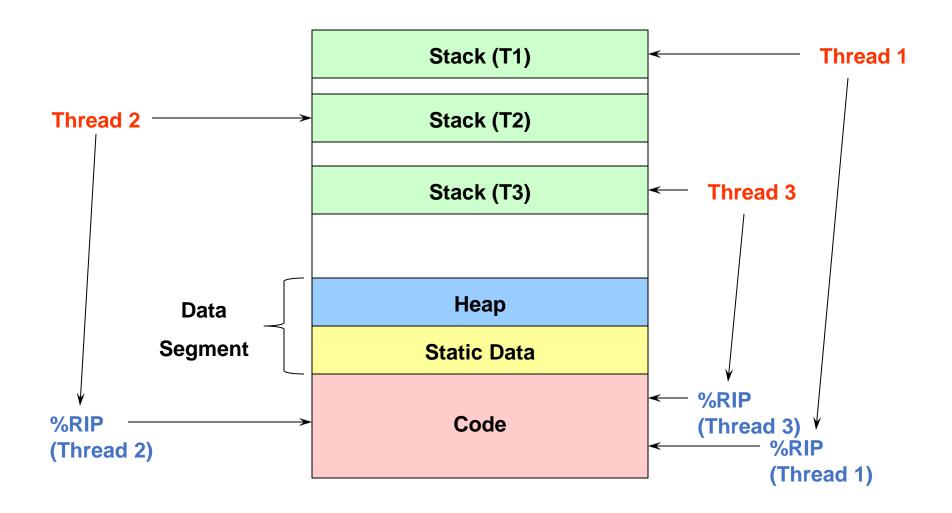
#### Thread use case: user interfaces

Even if there is only a single processor core, threads are useful

- Single-threaded User Interface
  - While processing actions, the UI is frozen

```
main() {
    while(true) {
        check_for_UI_interactions();
        process_UI_actions(); // UI freezes while processing
    }
}
```

# Process address space with multiple threads



### Multithreading processors

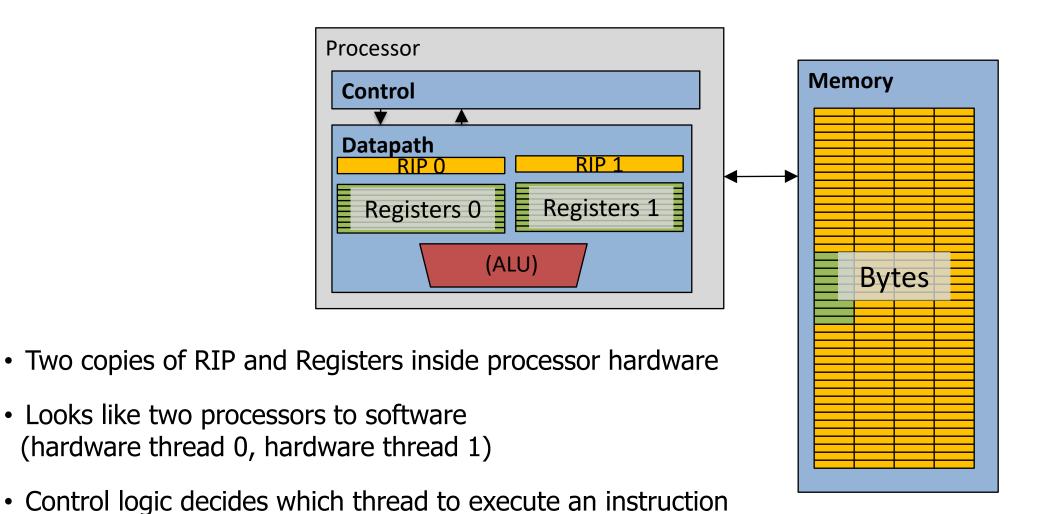
**Basic idea:** Processor resources are expensive and should not be left idle

Long memory latency to memory on cache miss?

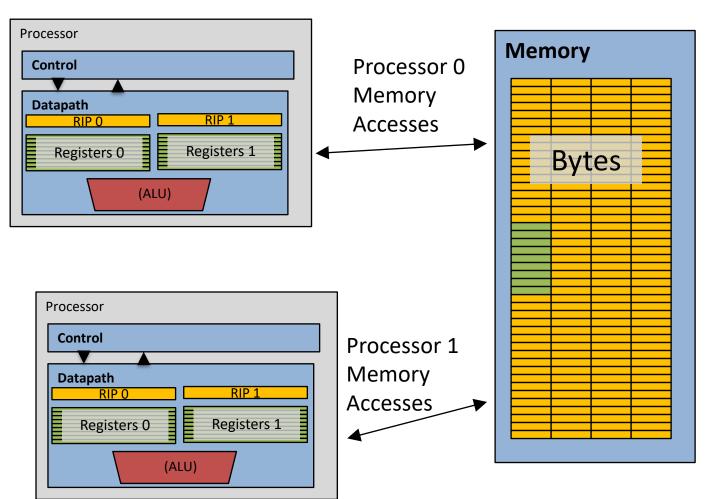
- Hardware switches threads to bring in other useful work while waiting for cache miss
- Swapping between threads in a process takes less time than waiting for memory, so we get back to work sooner!

#### Multithreading processor

from next (concurrent, but NOT parallel)



# Multithreading, multicore processors



 Combine capabilities of both designs

 Run two processes each with two threads

 Or run one process with four threads

# Example: i7 processor



# Break + Open Question

How many "cores" does a computer need?

#### Break + Open Question

- How many "cores" does a computer need?
  - Depends on the workload
  - Personal computer
    - ~2-10 processes running at once in the foreground
    - Plus ~100 in the background
  - Server
    - Could be serving thousands of requests simultaneously
    - Moore: 48 cores, Hanlon: 40 cores, Amdahl: 256 cores

#### **Outline**

Need for Parallelism

Processes and Threads

Concurrency Challenges

Using Threads

# Challenges to concurrency

Concurrency is great! We can do so many things!!

But what's the downside...?

- 1. How much speedup can we get from it?
- 2. How hard is it to write parallel programs?

Challenges to concurrency

Concurrency is great! We can do so many things!!

But what's the downside...?

- 1. How much speedup can we get from it?
- 2. How hard is it to write parallel programs?

# Speedup Example



Imagine a program that takes 100 seconds to run

- 95 seconds in the blue part
- 5 seconds in the green part

We're going to speed up the green part and take a look at the net result

# Speedup from improvements

Speedup with Improvement = improvement Execution time with improvement

$$5 \text{ s} -> 2.5 \text{ s}$$
: Speedup =  $100/97.5 = 1.026$ 

$$5 \text{ s} \rightarrow 1 \text{ s}$$
: Speedup =  $100/96$  =  $1.042$ 

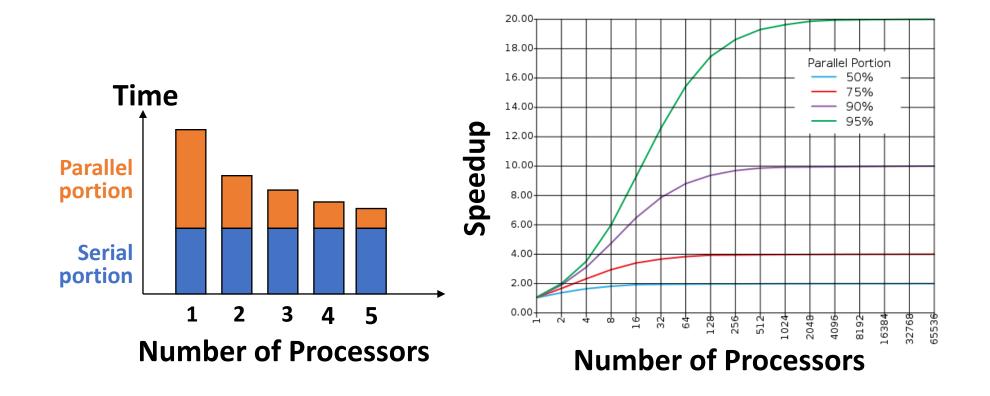
$$5 \text{ s} \rightarrow 0.001 \text{s}$$
: Speedup =  $100/95.001 = 1.053$ 

The impact of a performance improvement is relative to the importance of the part being improved!

Execution time without

# Amdahl's Law (in pictures)

- The amount of speedup that can be achieved through parallelism is limited by the non-parallel portion of your program!
  - And every program has at least some non-parallel parts



Challenges to concurrency

Concurrency is great! We can do so many things!!

But what's the downside...?

- 1. How much speedup can we get from it?
- 2. How hard is it to write parallel programs?

# Concurrency problem: data races

Consider two threads with a shared global variable: int count = 0

# Thread 1: void thread\_fn() { count += 1; }

```
Thread 2:

void thread_fn() {
  count += 1;
}
```

count could end up with a final value of 1 or 2. How?

# Concurrency problem: data races

Consider two threads with a shared global variable: int count = 0

# Thread 1: void thread\_fn() { mov \$0x8049a1c, %edi mov (%edi), %eax add \$0x1, %eax mov %eax, (%edi) }

```
Thread 2:

void thread_fn() {
  mov $0x8049a1c, %edi
  mov (%edi), %eax
  add $0x1, %eax
  mov %eax, (%edi)
}
```

Assuming "count" is in memory location 0x8049a1c

count could end up with a final value of 1 or 2. How? These instructions could be interleaved in any way.

#### Before this code starts

#### Time

Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	
Register	Value
%eax	???

Thread 2	
Register	Value
%eax	???

Memory	
Variable	Value
count	0

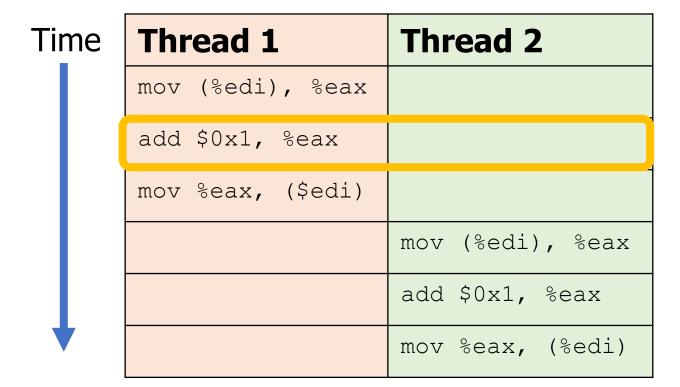
#### Time

Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	
Register	Value
%eax	0

Thread 2	
Register	Value
%eax	???

Memory	
Variable	Value
count	0



Thread 1		
Register	Value	
%eax	1	

Thread 2	
Register	Value
%eax	???

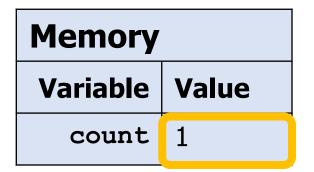
Memory	
Variable	Value
count	0



Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	
Register	Value
%eax	1

Thread 2	
Register	Value
%eax	???



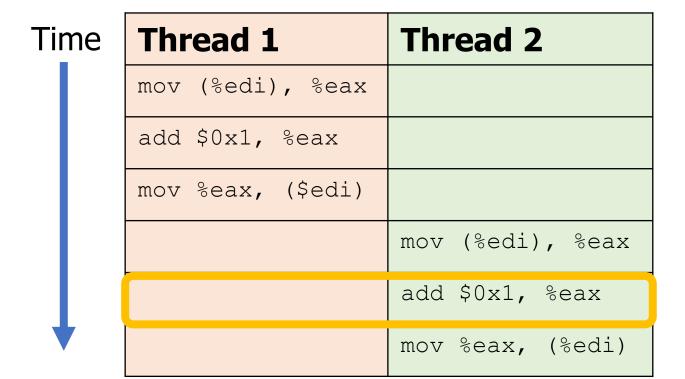
#### Time

Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	
Register	Value
%eax	1

Thread 2	
Register	Value
%eax	1

Memory	
Variable	Value
count	1



Thread 1		
Register	Value	
%eax	1	

Thread 2	
Register	Value
%eax	2

Memory	
Variable	Value
count	1

#### Time

Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	
Register	Value
%eax	1

Thread 2	
Register	Value
%eax	2

Memory	
Variable	Value
count	2

Theads do not have guaranteed ordering

BUT, there's no guarantee that the instructions occur in that order!

Since the two threads are running in parallel, the instructions could be interleaved in any way (both threads are really running simultaneously)

Before this code starts

#### Time

Thread 1	Thread 2
mov (%edi), %eax	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)
add \$0x1, %eax	
mov %eax, (%edi)	

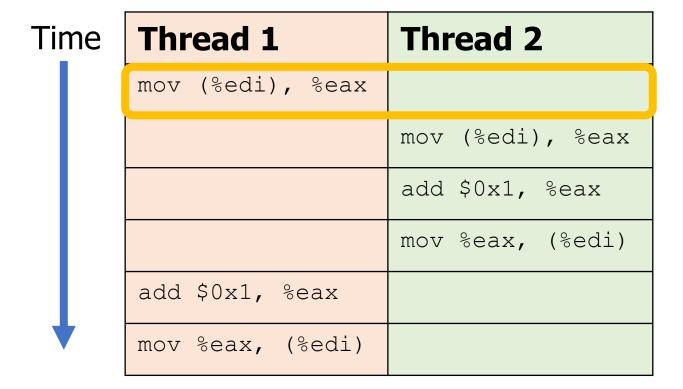
Remember, each thread has its own separate registers!

Thread 1	
Register	Value
%eax	???

Thread 2	
Register	Value
%eax	???

Memory	
Variable	Value
count	0

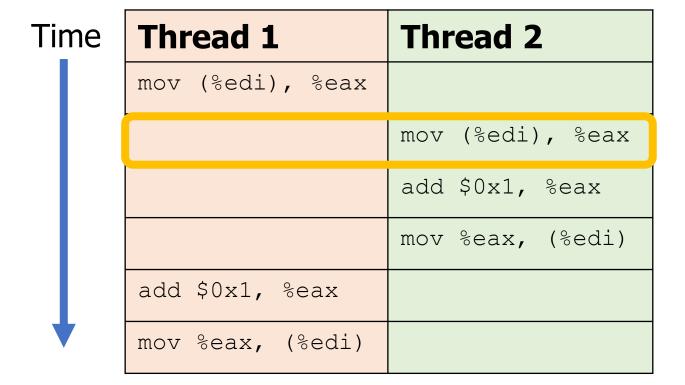
Assuming "count" is in memory location pointed to by <code>%edi</code>



Thread 1	
Register	Value
%eax	0

Thread 2	
Register	Value
%eax	???

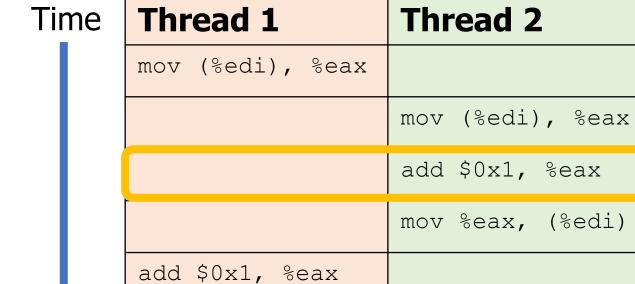
Memory	
Variable	Value
count	0



Thread 1	
Register	Value
%eax	0

Thread 2	
Register	Value
%eax	0

Memory	
Variable	Value
count	0



mov %eax, (%edi)

Thread 1	
Register	Value
%eax	0

Thread 2	
Register	Value
%eax	1

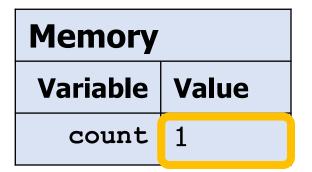
Memory	
Variable	Value
count	0

#### Time

Thread 1	Thread 2
mov (%edi), %eax	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)
add \$0x1, %eax	
mov %eax, (%edi)	

Thread 1	
Register	Value
%eax	0

Thread 2	
Register	Value
%eax	1



#### Time

Thread 1	Thread 2
mov (%edi), %eax	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)
add \$0x1, %eax	
mov %eax, (%edi)	

Thread 1	
Register	Value
%eax	1

Thread 2	
Register	Value
%eax	1

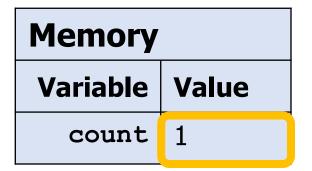
Memory	
Variable	Value
count	1

#### Time

Thread 1	Thread 2
mov (%edi), %eax	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)
add \$0x1, %eax	
mov %eax, (%edi)	

Thread 1	
Register	Value
%eax	1

Thread 2	
Register	Value
%eax	1



# Data race comparison

Assuming "count" is in memory location pointed to by %edi

Time

Thread 1	Thread 2
mov (%edi), %eax	
add \$0x1, %eax	
mov %eax, (\$edi)	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)

Thread 1	Thread 2
mov (%edi), %eax	
	mov (%edi), %eax
	add \$0x1, %eax
	mov %eax, (%edi)
add \$0x1, %eax	
mov %eax, (%edi)	

Final value of count: 2

Final value of count: 1

# Data race explanation

- Thread scheduling is non-deterministic
  - There is no guarantee that any thread will go first or last or not be interrupted at any point
- If different threads write to the **same** variable
  - The final value of the variable is also non-deterministic
  - This is a data race
- Avoid incorrect results by:
  - 1. Not writing to the same memory address!!

OR

2. Synchronizing reading and writing to get deterministic behavior

# Data race explanation

- Thread scheduling is non-deterministic
  - There is no guarantee that any thread will go first or last or not be interrupted at any point
- If different threads write to the same variable
  - The final value of the variable is also non-deterministic
  - This is a data race
- Avoid incorrect results by:
  - 1. Not writing to the same memory address!! We'll pick this one for CS213

OR

2. Synchronizing reading and writing to get deterministic behavior CS343 explores this in depth

# Avoiding shared memory data races

- Ensure that no two threads write to the same memory address
- Multiple threads reading from the same memory address is fine
  - As long as no thread writes to that memory
- Where do you put results then? Simple solution:
  - Make an array with a slot for each thread
  - Each thread only writes to their own slot in the array
  - After all threads are done, main thread iterates the array and determines the final result

# Question + Break

Consider three threads with a shared global variable: int count = 0

# Thread 1: void main(){ count += 1; }

```
Thread 2:

void main(){
  count -= 1;
}
```

```
Thread 3:
void main(){
  count += 2;
}
```

What are the possible values of count?

# Question + Break

Consider three threads with a shared global variable: int count = 0

#### Thread 1:

```
void main(){
  count += 1;
}
```

#### Thread 2:

```
void main(){
  count -= 1;
}
```

#### Thread 3:

```
void main(){
  count += 2;
}
```

#### What are the possible values of count?

How are you supposed to reason about this?! Need mechanisms for sharing memory.

-1, 0, 1, 2, 3

### **Outline**

Need for Parallelism

Processes and Threads

Concurrency Challenges

Using Threads

# Thread operations

- Create threads
  - **Shares** all memory with all threads of the process.
  - Scheduled independently of parent
- Join thread
  - Waits for a particular thread to finish
  - Can't continue computation until all threads finish
- That's it! Don't really need anything else (for this class)
  - Library also includes synchronization primitives to solve data races
- Can communicate between threads by reading/writing (shared) global variables
  - But we're only going to read from shared variables for safety
  - We'll write to separate memory locations

# POSIX Threads Library: pthreads

https://man7.org/linux/man-pages/man7/pthreads.7.html

```
int pthread_create(pthread_t* thread, const pthread_attr_t* attr,
void* (*start_routine)(void*), void* arg);
```

- Thread is created executing *start\_routine* with *arg* as its sole argument.
- Returning from the start routine exits the thread

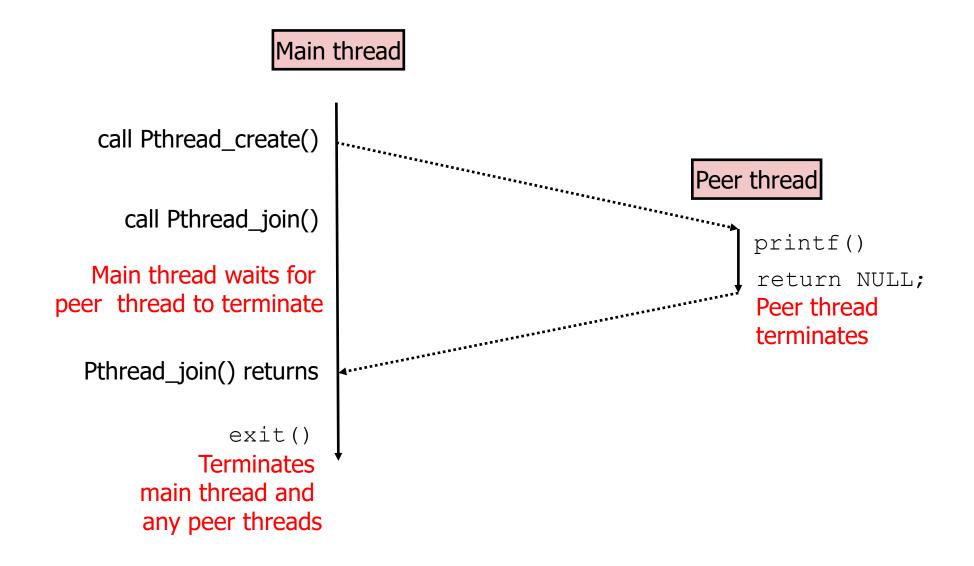
```
void pthread_exit(void* value_ptr);
```

Terminates the thread and makes value\_ptr available to any successful join

```
int pthread_join(pthread_t thread, void** value_ptr);
```

- Suspends execution of the calling thread until the target thread terminates.
- On return with a non-NULL *value\_ptr* the value passed to *pthread exit()* by the terminating thread is made available in the location referenced by *value\_ptr*.

# Basic thread example



```
double array[LEN] = {1, 2, 3, ..., LEN};

// determine result sequentially
double sequential_sum = 0;

for (int i=0; i<LEN; i++) {
   sequential_sum += array[i];
}</pre>
```

```
double array[LEN] = \{1, 2, 3, ..., LEN\};
```

#### Parallelization Plan

- 1. Create num\_threads different threads
- 2. Threads create "partial" sums for their portion of the work
  - Each thread does (LEN/num threads) work
  - Create an array for results with one slot per thread
- 3. Wait until done, then sum the partial results
  - Main thread calls join() to wait for each thread to complete
  - Main thread adds up results

1. Create num\_threads different threads

```
pthread_t tid[num_threads];
for (long i=0; i<num_threads; i++) {
   pthread_create(&(tid[i]), NULL, worker, (void*)i);
}</pre>
```

- Arguments to pthread\_create
  - thread\_handle, attributes, thread\_function, function\_argument

2. Threads create "partial" sums for their portion of the work

```
void* worker(void* arg) {
  long i = (long)arg;
  int mystart = i * (LEN/num threads);
  int myend = (i+1) * (LEN/num threads);
 partial sum[i] = 0;
  for (int j=mystart; j<myend; j++) {</pre>
   partial sum[i] += array[j];
 pthread exit(NULL); // Thread work is complete
```

Decide which portion of work this thread should do

2. Threads create "partial" sums for their portion of the work

```
void* worker(void* arg) {
  long i = (long)arg;
  int mystart = i * (LEN/num threads);
  int myend = (i+1) * (LEN/num threads);
 partial sum[i] = 0;
  for (int j=mystart; j<myend; j++) {</pre>
   partial sum[i] += array[j];
 pthread exit(NULL); // Thread work is complete
```

Do the work

Puts result in its own slot in the partial\_sum array (avoids data races)

## Example: parallel sum of array

3. Wait until done, then sum the partial results

```
for (int j=0; j<num_threads; j++) {</pre>
 pthread join(tid[j], NULL); // second argument is return result
double parallel sum = 0;
for (int k=0; k<num threads; k++) {</pre>
 parallel sum += partial sum[k];
```

# Trying this out for yourself

See SETI Lab for example code you can run yourself

• We just went through a slightly simplified version of parallel-sum-ex.c

\$ ./parallel-sum-ex 0 1 200000000
Sequential sum: 1999999900000000 ( 878576632 cycles)
Parallel sum: 0 (44 cycles)

Array of 200 million length

No threads created

Only the sequential version is run. Takes about ~878 million cycles to run

```
Sequential sum: 1999999900000000 ( 878576632 cycles)
Parallel sum: 0 (44 cycles)

$ ./parallel-sum-ex 1 1 20000000
Sequential sum: 1999999900000000 ( 902438479 cycles)
Parallel sum: 1999999900000000 (1169222739 cycles)
```

\$ ./parallel-sum-ex 0 1 20000000

Array of 200 million length

1 to thread created. No parallelism for a speedup. Actually, it takes LONGER to run.

Starting threads takes time! Need to make sure they're doing enough work to be worth it.

```
$ ./parallel-sum-ex 0 1 200000000

Sequential sum: 1999999900000000 (878576632 cycles)

Parallel sum: 0 (44 cycles)

$ ./parallel-sum-ex 1 1 200000000

Sequential sum: 1999999900000000 (902438479 cycles)

Parallel sum: 1999999900000000 (1169222739 cycles)

$ ./parallel-sum-ex 8 8 200000000

Sequential sum: 1999999900000000 (888810917 cycles)

Parallel sum: 1999999900000000 (1033659530 cycles)
```

Array of 200 million length

8 threads actually has some parallelism

Starts doing better than one thread but needs more parallelism for a big win.

```
$ ./parallel-sum-ex 0 1 200000000
Sequential sum: 1999999900000000 (878576632 cycles)
Parallel sum:
                 0 (44 cycles)
$ ./parallel-sum-ex 1 1 200000000
Sequential sum:
                19999999900000000 ( 902438479 cycles)
Parallel sum: 1999999900000000 (1169222739 cycles)
$ ./parallel-sum-ex 8 8 20000000
Sequential sum: 1999999900000000 (888810917 cycles)
Parallel sum: 1999999900000000 (1033659530 cycles)
$ ./parallel-sum-ex 16 16 200000000
Sequential sum:
                 19999999900000000 (895258209 cycles)
Parallel sum:
                 19999999900000000 (693511997 cycles)
```

Array of 200 million length

16 threads starts to win!

I don't actually have that many cores, but the system is swapping threads whenever memory reads stall to improve performance

```
$ ./parallel-sum-ex 0 1 20000000
Sequential sum: 1999999900000000 (878576632 cycles)
Parallel sum:
                0 (44 cycles)
$ ./parallel-sum-ex 1 1 200000000
Sequential sum: 1999999900000000 ( 902438479 cycles)
Parallel sum: 1999999900000000 (1169222739 cycles)
$ ./parallel-sum-ex 8 8 20000000
Sequential sum: 1999999900000000 (888810917 cycles)
Parallel sum: 1999999900000000 (1033659530 cycles)
$ ./parallel-sum-ex 16 16 200000000
Sequential sum:
                19999999900000000 (895258209 cycles)
Parallel sum: 1999999900000000 (693511997 cycles)
$ ./parallel-sum-ex 32 32 20000000
Sequential sum: 1999999900000000 (886174224 cycles)
Parallel sum: 1999999900000000 ( 609774231 cycles)
$ ./parallel-sum-ex 64 64 200000000
Sequential sum: 1999999900000000 (898098616 cycles)
Parallel sum:
                19999999900000000 (426420305 cycles)
```

Array of 200 million length

32 and 64 threads are really cruising

Down to half the time for the computation

```
$ ./parallel-sum-ex 0 1 20000000
Sequential sum: 1999999900000000 (878576632 cycles)
Parallel sum:
                 0 (44 cycles)
$ ./parallel-sum-ex 1 1 200000000
Sequential sum:
                19999999900000000 ( 902438479 cycles)
Parallel sum: 1999999900000000 (1169222739 cycles)
$ ./parallel-sum-ex 8 8 20000000
Sequential sum: 1999999900000000 (888810917 cycles)
Parallel sum: 1999999900000000 (1033659530 cycles)
$ ./parallel-sum-ex 16 16 200000000
Sequential sum:
                19999999900000000 (895258209 cycles)
Parallel sum:
                19999999900000000 (693511997 cycles)
$ ./parallel-sum-ex 32 32 20000000
Sequential sum: 1999999900000000 (886174224 cycles)
Parallel sum:
                19999999900000000 ( 609774231 cycles)
$ ./parallel-sum-ex 64 64 200000000
Sequential sum: 1999999900000000 (898098616 cycles)
Parallel sum: 1999999900000000 (426420305 cycles)
$ ./parallel-sum-ex 128 128 200000000
Sequential sum: 1999999900000000 (891919128 cycles)
Parallel sum: 1999999900000000 (493951974 cycles)
```

Array of 200 million length

128 threads is basically the same as 64 threads

Further parallelism isn't helping very much. (technically worse than 64, but it's within error bounds on timing)

## **Outline**

Need for Parallelism

Processes and Threads

Concurrency Challenges

Using Threads

# Outline

• Bonus: SIMD Instructions

## SIMD Architectures

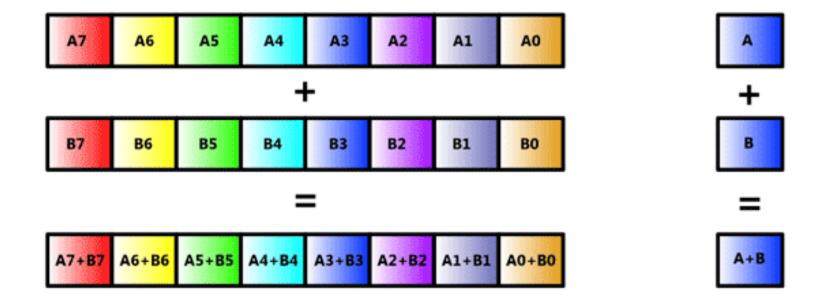
- Data-Level Parallelism (DLP): Executing one operation on multiple data streams
  - SIMD: Single Instruction Multiple Data
- Example: Multiplying a coefficient vector by a data vector (e.g. in filtering)

$$y[i] := c[i] \times x[i], 0 \le i < n$$

- Sources of performance improvement:
  - One instruction is fetched & decoded for entire operation
  - Multiplications are known to be independent
  - Pipelining/concurrency in memory access as well

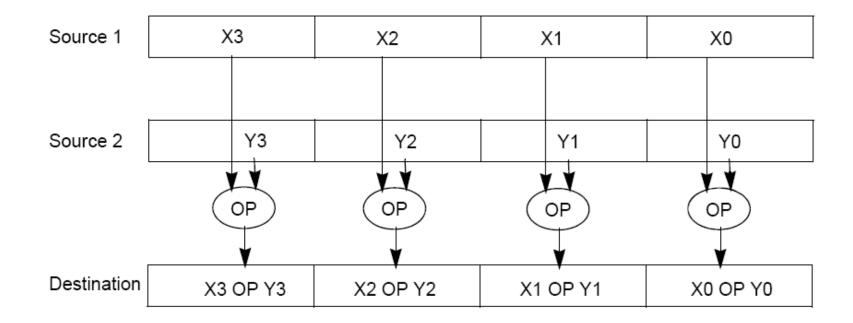
## **SIMD Mode**

## **Scalar Mode**



# **Example SIMD Instructions**

- To improve performance, Intel's SIMD instructions
  - Fetch one instruction, do the work of multiple instructions
  - MMX (MultiMedia eXtension, Pentium II processor family)
  - SSE (Streaming SIMD Extension, Pentium III and beyond)



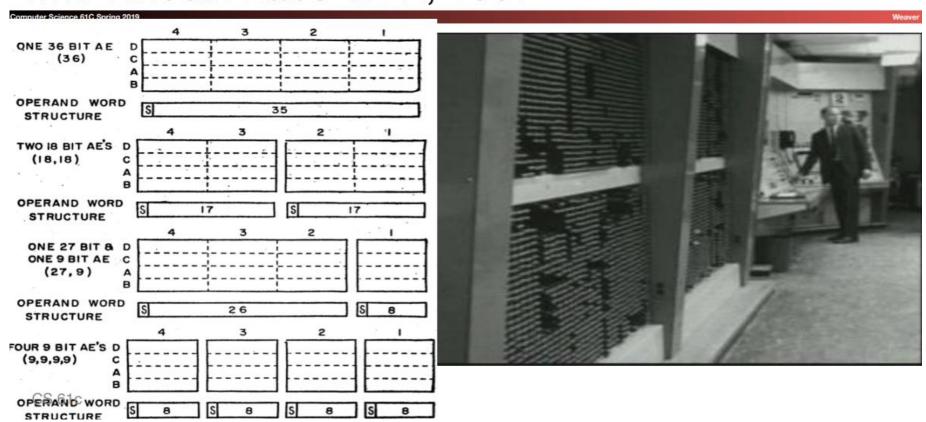
## Example: SIMD Array Processing

```
for each f in array
                                                        pseudocode
  f = sqrt(f)
for each f in array {
  load f to the floating-point register
  calculate the square root
                                                        SISD
  write the result from the register to memory
for each 4 members in array {
  load 4 members to the SSE register
  calculate 4 square roots in one operation
                                                        SIMD
  write the result from the register to memory
```

## SIMD in the Real World

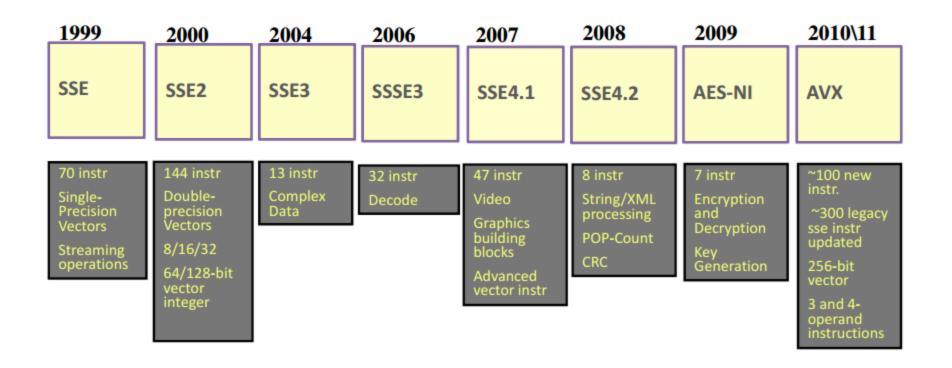
- Today's compilers can generate SIMD code!
  - But in some cases we get better results by hand
- Intel's x86 implements many SIMD instructions
  - Which have the benefit of being usable on lab machines
  - (and most of our own personal computers)

## First SIMD Extensions: MIT Lincoln Labs TX-2, 1957



# Intel SIMD has been continuously extended

#### SIMD: Continuous Evolution



## And it has increased in size a lot

#### Intel Advanced Vector eXtensions 2011 2012 2013 2015 2014 **Future AVX Registers getting wider, instruction set getting richer** 185 GFLOPS tbd GFLOPS tbd GFLOPS **87 GFLOPS** ~225 GFLOPS ~500 GFLOPS Sandy Ivy Bridge Haswell Broadwell Skylake Westmere Bridge 32 nm 14 nm 32 nm 22 nm 22 nm 14 nm SSE 4.2 AVX AVX 3.2 AVX2 DDR3 (256 bit (512 bit (new PCle2 registers) (instructions) registers)

DDR4

PCIe3

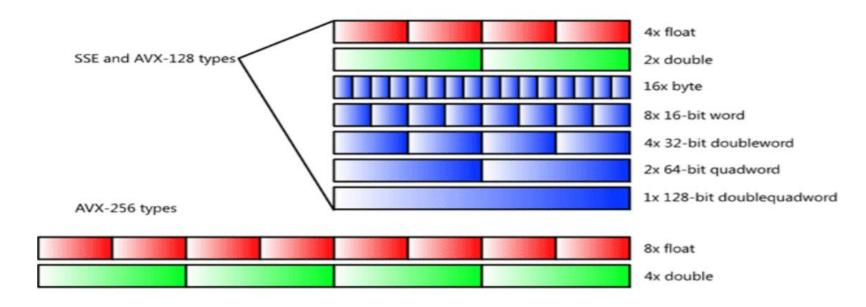
DDR3

PCle3

DDR4

PCIe4

## Intel SIMD Data Types



(Now also AVX-512 available (but not on Hive): 16x float and 8x double)

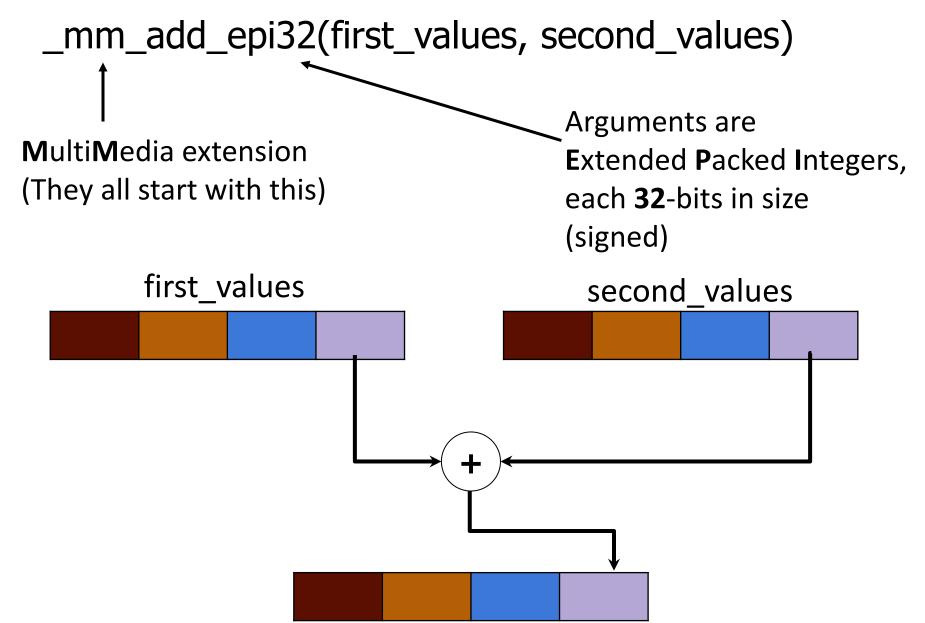
## SSE Instruction Categories for Multimedia Support

Instruction category	Operands
Unsigned add/subtract	Eight 8-bit or Four 16-bit
Saturating add/subtract	Eight 8-bit or Four 16-bit
Max/min/minimum	Eight 8-bit or Four 16-bit
Average	Eight 8-bit or Four 16-bit
Shift right/left	Eight 8-bit or Four 16-bit

 SSE-2+ supports wider data types to allow 16 × 8-bit and 8 × 16-bit operands

## How do we use these SIMD instructions?

- Intrinsics:
  - "function calls" that actually just execute an assembly instruction





#### **Technologies**

- □ MMX
- SSE
- SSE2
- SSE3
- SSSE3
- SSE4.1
- SSE4.2
- AVX
- AVX2
- FMA
- AVX-512
- KNC
- SVML
- Other

#### Categories

- Application-Targeted
- Arithmetic
- Bit Manipulation
- Cast
- Compare
- □ C-....

mm\_add\_epi32

```
__m128i _mm_add_epi32 (__m128i a, __m128i b)
```

#### Synopsis

```
__m128i _mm_add_epi32 (__m128i a, __m128i b)
#include <emmintrin.h>
Instruction: paddd xmm, xmm
CPUID Flags: SSE2
```

#### Description

Add packed 32-bit integers in a and b, and store the results in dst.

#### Operation

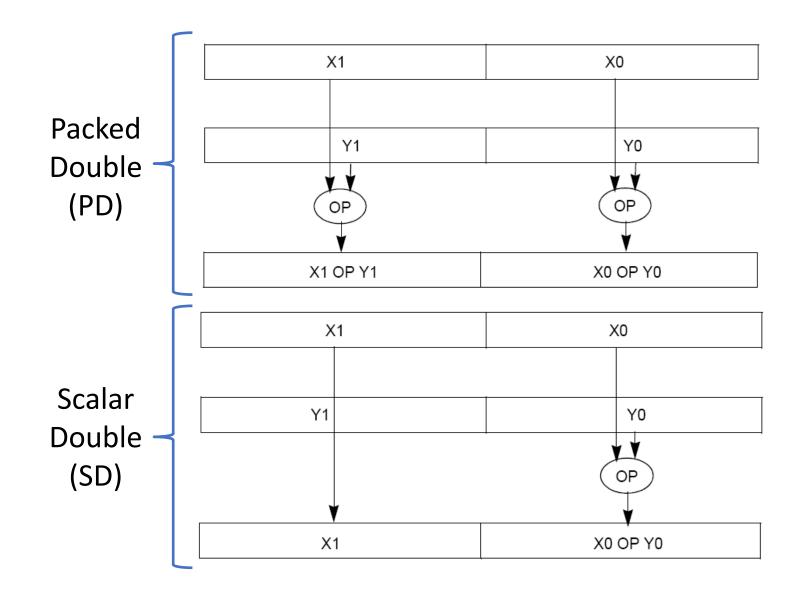
#### Performance

Architecture	Latency	Throughput (CPI)
Skylake	1	0.33
Broadwell	1	0.5
Haswell	1	0.5
Ivy Bridge	1	0.5

### Soooooo fast

```
int add no SSE(int size, int *first array, int *second array) {
    for (int i = 0; i < size; ++i) {
        first array[i] += second array[i];
int add SSE(int size, int *first array, int *second array) {
   for (int i=0; i + 4 <= size; i+=4) { // only works if (size%4) == 0
       // load 128-bit chunks of each array
       __m128i first_values = _mm_loadu_si128((__m128i*) &first_array[i]);
       m128i second values = _mm_loadu_si128(( m128i*) &second array[i]);
       // add each pair of 32-bit integers in the 128-bit chunks
       first_values = _mm_add_epi32(first_values, second_values);
       // store 128-bit chunk to first array
       mm storeu si128(( m128i*) &first array[i], first values);
         . . .
```

# You can do this with floating point numbers too!



# Example: Reversing an array in 7 steps (animated)

