```
import numpy as np
import matplotlib.pyplot as plt
\label{eq:condition} \mbox{def wing\_weight(W\_TO, n\_ult, A, del\_quar, S, lam, tcm, V\_H, W\_F, q):}
      wing_weight_USAF =
96.948*((W_{T0*n_ult}/(10**5))**(.65)*(A/np.cos(del_quar))**(.57)*(S/100)**(.61)*((1+lam)/2*(tcm))**(.36)*(1+V_H/500)**(.5))**(.993)
      wing_weight_ces = .04674*(W_TO)**(.397)*(S**.36)*n_ult**.397*A**1.712
       \#wing\_weight\_raymer = .036*S^**.758*(.5*W\_F)**.0035^*(A/((np.cos(del\_quar)))**2))*q**.006*lam**.04*(100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar)))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_quar))**(-100*tcm/np.cos(del\_qua
0.3) * (n ult*W TO) **.49
      return (wing_weight_USAF + wing_weight_ces) / 2
def empennage_weight(W_TO, n_ult, S_v, b_v, trv, A_v, del_quar_v):
      W_V_{tor} = .04*(n_ult*S_v**2)**.75
      empennage_weight = (W_V_USAF + W_V_tor)/2
      return empennage weight
\label{eq:condition} \mbox{def fuselage\_weight(W\_TO, n\_ult, l\_f, w\_f, h\_f, V\_C, N\_pax, S\_f, l\_t, q):}
      return (fuselage_weight_USAF + fuselage_weight_ces + fuselage_weight_raymer) / 3
def engine_weight(P_TO, N_e, N_p, N_bl, D_p, k_p=.55):
      #includes nacelle, air induction, propeller, propulsion system
      W_eng = k_p*P_TO
      engine_weight_USAF = 2.575*W_eng**(.992)*N_e
      W_n = .37 * P_TO
      W_prop = 31.92*N_p*N_bl**.391*((D_p)*P_TO/N_e/1000)**.782
      W p = 65
      \verb"engine_weight_ces" = W_eng + W_n + W_prop + W_p
      return (engine_weight_USAF + engine_weight_ces)/2
def fuel_system_weight(W_F, K_fsp, fracfuel, N_t, N_e):
      return (W_fs_USAF + W_fs_tor)/2
def flight control sys weight(W TO):
      W_fc_USAF = 1.066*(W_TO)**(.626)
W_fc_tor = .23*W_TO**(2/3)
      return (W_fc_USAF + W_fc_tor)/2
def electrical system weight(W fs, W iae, W TO):
      W_els_USAF = 426*((W_fs + W_iae)/1000)**(.51)
W_els_ces = .0268*(W_TO)
      return (W_els_USAF + W_els_ces)/2
def avionics_weight(N_pax):
      W iae = 33*N_pax
      return W_iae
def AC_weight(W_TO, N_pax, W_iae, M_D):
      W_{api} = .265*(W_{T0})**(.52)*(N_{pax})**(.68)*(W_{iae})**(.17)*M D**(.08)
      return W api
def APU_weight(W_TO):
      W_APU = .013*W_TO
      return W_APU
def furnishings_weight(N_pax, W_TO):
      W_fur = .412*N_pax**(1.145)*W_TO**(.489)
      return W_fur
def total_weight_calc():
      W TO = 10910
       #payload weight
      W_payload = 4000
       #passenger weight
      W_pax = 190
       #landing gear weight
      W lgm = 249
      W_lgf = 67
      #boom weight
      W_boom = 150
       #mission fuel weight [lbs]
      W F = 693.36
       #wing aspect ratio
      A = 10
       #wing quarter-chord sweep angle
      del_quar = np.deg2rad(5)
       #wing area [ft^2]
      S = 193.6
      #cruise dynamic pressure
q=(1/2*.002048 * 197.5**2)
       #wing taper ratio
      lam = 0.7
      #maximum wing thickness ratio
```

```
tcm = 0.18
          #maximum level speed at sealevel [kts]
         V_H = 394/309*117
          #vertical tail area [ft]
         Sv = 40.4624
          #vertical tail span [ft]
         b v = 8.9
          #distance from the wing quarter chord to tail quarter chord
         1 t = 21.4
          #vertical tail maximum root thickness [ft]
         trv = 0.16
          #vertical tail aspect ratio
         A v = 1.88
          #vertical tail quarter chord sweep angle
         del_quar_v = np.deg2rad(15)
          #fuselage length [ft]
          1 f = 35.5
          #max fuselage width [ft]
         w f = 4.4
          #max fuselage height [ft]
         h_f = 6.5
          #fuselage wetted area
         S f = 426.5
          #design cruise speed [KEAS]
         V C = 128
          #engine takeoff power [shp]
          P TO = 620
          #number of engine
         N = 1
          #number of propeller
         N_p = 1
          #number of propeller blades
         N bl = 5
          #diameter of propeller
         D_p = 9
           #constant
          K_fsp = 5.87
          #fuel fraction of tanks which are integral
         fracfuel = 1
          #number of separate engine tanks
          N t = 1
          #number of passengers
         N pax = 1
          #design dive mach number
         M_D = .438
          tolerance = .05
          iter = 0
         W TO new = 0
         W_TO_old = W TO
          while abs(W_TO_new-W_TO_old)/W_TO_old >= .05:
                 W_TO_old = W_TO
                  #positive design limit load factor
                 n_lim_pos = 2.1 + 24000/(W_TO + 10000)
#design ultimate load factor
                 n_ult = 1.5*n_lim_pos
                  #design landing weight [lbs]
                 W L = W TO-W payload
                 \label{eq:w_w} \textbf{W}\_\textbf{w} = \texttt{wing\_weight}(\textbf{W}\_\textbf{TO}, \ \textbf{n\_ult}, \ \textbf{A}, \ \texttt{del\_quar}, \ \textbf{S}, \ \texttt{lam}, \ \texttt{tcm}, \ \textbf{V}\_\textbf{H}, \ \textbf{W}\_\textbf{F}, \ \textbf{q})
                 \label{eq:weight} \textbf{W}\_\texttt{em} = \texttt{empennage}\_\texttt{weight} \, (\textbf{W}\_\texttt{TO}, \,\, \textbf{n}\_\texttt{ult}, \,\, \textbf{S}\_\texttt{v}, \,\, \textbf{b}\_\texttt{v}, \,\, \textbf{trv}, \,\, \textbf{A}\_\texttt{v}, \,\, \textbf{del}\_\texttt{quar}\_\texttt{v})
                 W_{fus} = fuselage_{eight}(W_{TO}, n_{ult}, l_f, w_f, h_f, V_C, N_{pax}, S_f, l_t, q)
                  W_eng = engine_weight(P_TO, N_e, N_p, N_bl, D_p, k_p=.55)
                 W_fs = fuel_system_weight(W_F, K_fsp, fracfuel, N_t, N_e)
                 W_fc = flight_control_sys_weight(W_TO)
                 W_iae = avionics_weight(N_pax)
                 W_els = electrical_system_weight(W_fs, W_iae, W_TO)
                  W_api = AC_weight(W_TO, N_pax, W_iae, M_D)
                 W APU = APU weight (W TO)
                 W_fur = furnishings_weight(N_pax, W_TO)
                 W_winglets = 1/12.7*2*W_w
                 W_{hopper} = 64.125*1.6
                  \overline{W}tfo = 44
                 + W_api + W_APU + W_fur + W_winglets + W_hopper + W_tfo
                 W_TO = W_TO_new
                 iter = iter +
         return iter, W_payload, W_F, W_pax, n_lim_pos, W_w, W_em, W_fus, W_lgm, W_lgf, W_eng, W_fs, W_fc, W_iae, W_els, W_api, W_APU,
  W_fur, W_winglets, W_hopper, W_tfo, W_boom, W_TO_new
  \\ \text{iter, W\_payload, W\_F, W\_pax, n\_lim\_pos, W\_w, W\_em, W\_fus, W\_lgf, W\_lgf, W\_eng, W\_fs, W\_fc, W\_iae, W\_els, W\_api, W\_APU, W\_fur, W\_lgf, W\_eng, W\_fs, W\_fc, W\_iae, W\_els, W\_api, W\_APU, W\_fur, W\_fur, W\_iae, W\_ia
 W_winglets, W_hopper, W_tfo, W_boom, W_TO_new = total_weight_calc()
 print("Iterations: ", iter)
print("Payload: ", W_payload)
 print("Fuel: ", W_F)
 print("Passenger: ", W pax)
print("Positive Load Limit:", n_lim_pos)
print("Wings: ", 2*W_w)
print("Winglets: ", W_winglets)
print("Empennage: ", W_em)
print("Fuselage: ", W_fus)
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```
print("Landing Gear: ", W_lgm, W_lgf)
print("Engine: ", W_eng)
print("Fuel Systems: ", W_fs)
print("Flight Control Systems: ", W fc)
 print("Avionics: ", W_iae)
print("Electrical Systems: ", W_els)
print("AC, Pressure, Anti-Ice Systems: ", W_api)
print("APU: ", W APU)
print("Furnishings: ", W_fur)
print("Hopper: ", W_hopper)
print("Trapped Fuel and Oil: ", W_tfo)
print("Boom: ", W boom)
print("Gross Takeoff Weight: ", W TO new)
 def cg_location(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F, W_pax, W_hopper, W_payload, W_boom, W_fc, W_els,
 W iae, W_api, W_APU, W_fur):
                      x_{cg} = (12.79*W_w + 33.69*W_w + 31.314*W_em + 22.142*W_winglets + 12.425*W_fus + 31.695*W_eng + 3.45*W_lgf + 21.725*W_lgm + 31.695*W_lgf + 21.725*W_lgm + 31.695*W_lgf + 21.725*W_lgf + 21.725
 22.8*\overline{\text{W}}\_\text{fs} + 10.364*\overline{\text{W}}\_\text{F} + 7.554*\overline{\text{W}}\_\text{pax} + 14.65*\overline{\text{W}}\_\text{hopper} + 14.65*\overline{\text{W}}\_\text{payload} + 13.838*\overline{\text{W}}\_\text{boom} + 22.\overline{1}42*\overline{\text{W}}\_\text{fc} + 3.\overline{4}34*\overline{\text{W}}\_\text{els} + 4.696*\overline{\text{W}}\_\text{iae}
  + 7.008*W_api + 2.485*W_APU + 6.717*W_fur)/(2*W_w + W_em + W_winglets + W_fus + W_eng + W_lgf + W_lgm + W_fs + W_F + W_pax + W_eng + W_lgf + W_lgm +
 W_hopper + W_payload + W_boom + W_fc + W_els + W_iae + W_api + W_APU + W_fur)
                        return x_cg
 def cg_location_gear_down(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F, W_pax, W_hopper, W_payload, W_boom, W_fc,
 W_els, W_iae, W_api, W_APU, W_fur):
                       x_{cg} = (12.79*W_w + 33.69*W_w + 31.314*W_em + 22.142*W_winglets + 12.425*W_fus + 31.695*W_eng + 2.155*W_lgf + 21.725*W_lgm + 31.695*W_eng + 2.155*W_lgf + 21.725*W_lgf 
22.8*W_fs + 10.364*W_F + 7.554*W_pax + 14.65*W_hopper + 14.65*W_payload + 13.838*W_boom + 22.142*W_fc + 3.434*W_els + 4.696*W_iae + 7.008*W_api + 2.485*W_APU + 6.717*W_fur)/( 2*W_w + W_em + W_winglets + W_fus + W_eng + W_lgf + W_lgm + W_fs + W_F + W_pax +
 W_hopper + W_payload + W_boom + W_fc + W_els + W_iae + W_api + W_APU + W_fur)
                        return x cg
 \textbf{x\_cg = cg\_location(W\_w, W\_em, W\_winglets, W\_fus, W\_eng, W\_lgf, W\_lgm, W\_fs, W\_F, W\_pax, W\_hopper, W\_payload, W\_boom, W\_fc, W\_els, W\_els, W\_fs, W\_
W_iae, W_api, W_APU, W_fur)
print("Center of Gravity: ", x_cg)
  \textbf{x\_cg\_empty} = \textbf{cg\_location} (\textbf{W\_w}, \textbf{W\_em}, \textbf{W\_winglets}, \textbf{W\_fus}, \textbf{W\_eng}, \textbf{W\_lgf}, \textbf{W\_lgm}, \textbf{W\_fs}, \textbf{0}, \textbf{W\_pax}, \textbf{W\_hopper}, \textbf{0}, \textbf{W\_boom}, \textbf{W\_fc}, \textbf{W\_els}, \textbf{W\_e
 W_{iae}, W_{api}, W_{APU}, W_{fur})
print("Empty Center of Gravity: ", x_cg_empty)
 w1 = 6.039
 w2 = 8.052
 w3 = 51.658
  w4 = 344.792
  w5 = 49.752
 w6 = 119.864
  \texttt{cg\_gear\_down\_TO} = \texttt{cg\_location\_gear\_down} (\texttt{W\_w}, \texttt{W\_em}, \texttt{W\_winglets}, \texttt{W\_fus}, \texttt{W\_eng}, \texttt{W\_lgf}, \texttt{W\_lgm}, \texttt{W\_fs}, \texttt{W\_F-w1}, \texttt{W\_pax}, \texttt{W\_hopper}, \texttt{W\_winglets}, \texttt{W\_winglets}, \texttt{W\_m_model} = \texttt{W\_lgf}, \texttt{W\_lgm}, \texttt{W\_lg
 \label{eq:w_payload} \mbox{$W$\_payload, $W$\_boom, $W$\_fc, $W$\_els, $W$\_iae, $W$\_api, $W$\_APU, $W$\_fur)}
  cg_takeoff_start = cg_location(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F-w1, W_pax, W_hopper, W_payload,
 W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
 cg_cruise_start = cg_location(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F-w1-w2, W_pax, W_hopper, W_payload,
 W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
 cg_spray_start = cg_location(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F-w1-w2-w3, W_pax, W_hopper, W_payload,
 W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
  \texttt{cg\_cruise\_back\_start} = \texttt{cg\_location}(\texttt{W\_w}, \texttt{W\_em}, \texttt{W\_winglets}, \texttt{W\_fus}, \texttt{W\_eng}, \texttt{W\_lgf}, \texttt{W\_lgm}, \texttt{W\_fs}, \texttt{W\_F-w1-w2-w3-w4}, \texttt{W\_pax}, \texttt{W\_hopper}, \texttt{W\_fus}, \texttt{W\_fus}
 W_payload-4000, W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
  \texttt{cg\_loiter\_start} = \texttt{cg\_location}(\texttt{W\_w}, \texttt{W\_em}, \texttt{W\_winglets}, \texttt{W\_fus}, \texttt{W\_eng}, \texttt{W\_lgf}, \texttt{W\_lgm}, \texttt{W\_fs}, \texttt{W\_F-w1-w2-w3-w4-w5}, \texttt{W\_pax}, \texttt{W\_hopper}, \texttt{W\_fus}, 
 \label{eq:w_payload-4000} \texttt{W\_payload-4000}, \ \texttt{W\_boom}, \ \texttt{W\_fc}, \ \texttt{W\_els}, \ \texttt{W\_iae}, \ \texttt{W\_api}, \ \texttt{W\_APU}, \ \texttt{W\_fur})
  cg_land_start = cg_location(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F-w1-w2-w3-w4-w5-w6, W_pax, W_hopper,
 W_payload-4000, W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
 cg_gear_down_land = cg_location_gear_down(W_w, W_em, W_winglets, W_fus, W_eng, W_lgf, W_lgm, W_fs, W_F-w1-w2-w3-w4-w5-w6, W_pax,
 W_hopper-4000, W_payload, W_boom, W_fc, W_els, W_iae, W_api, W_APU, W_fur)
 cg_envelope = [cg_gear_down_TO, cg_takeoff_start, cg_cruise_start, cg_spray_start, cg_cruise_back_start, cg_loiter_start,
cg_land_start, cg_gear_down_land]
print(cg_envelope)
 cg_location_envelope = np.zeros_like(cg_envelope)
 for i in range(len(cg_envelope)):
                        cg_location_envelope[i] = cg_envelope[i]/4.45
 print(cg_location_envelope)
  \texttt{cg\_weights} = [\texttt{W\_TO\_new-w1}, \ \texttt{W\_TO\_new-w1}, \ \texttt{W\_TO\_new-w1-w2}, \ \texttt{W\_TO\_new-w1-w2-w3}, \ \texttt{W\_TO\_new-w1-w2-w3-w4-4000}, \\ \texttt{w\_TO\_new-w1-w2-w3-w4-4000}, \ \texttt{w\_TO\_new-w1-w4-4000}, \\ \texttt{w\_TO\_new-w1-w4-w4-4000}, \ \texttt{w\_TO\_new-w1-w4-4000}, \\ \texttt{w\_TO\_new-w1-w4-4000}, \ \texttt{w\_TO\_new-w1-w4-4000}, \ \texttt{w\_TO\_new-w1-w4-4000}, \\ \texttt{w\_TO\_new-w1-w4-4000}, \ 
 print(cg_weights)
 plt.figure()
plt.plot(cg_location_envelope, cg_weights)
plt.axvline(x=16.9/4.45, linestyle='--')
plt.axvline (x=18.45/4.45, linestyle='--')
 \verb|plt.scatter(cg_location_envelope[0], cg_weights[0], color='black', s=10, zorder=2)|
plt.scatter(cg_location_envelope[1], cg_weights[1], color='black', s=10, zorder=2)
plt.scatter(cg_location_envelope[2], cg_weights[2], color='black', s=10, zorder=2)
plt.scatter(cg_location_envelope[3], cg_weights[3], color='black', s=10, zorder=2)
 plt.scatter(cg_location_envelope[4], cg_weights[4], color='black', s=10, zorder=2)
plt.scatter(cg_location_envelope[5], cg_weights[5], color='black', s=10, zorder=2)
plt.scatter(cg_location_envelope[6], cg_weights[6], color='black', s=10, zorder=2)
plt.scatter(cg_location_envelope[7], cg_weights[7], color='black', s=10, zorder=2)
```

plt.title("C.G. Location for Full Length Mission")

```
plt.xlabel("C.G. Location as a fraction of MAC $(\\frac{x_{c.g.}}{\\bar{c}})$")
plt.ylabel("Gross Weight ($W$) [lbs]")

plt.show()
```