course notebook commented

December 20, 2024

1 Practical modeling

This is the notebook we filled during the course, but with additional comments to make it more self-contained.

The jupyter notebook is an environment to execute code interactively, and to create a document that contains code and its ouput (including plots), as well as additional comments.

It consists of "code cells" (like the one above), starting with "In [...]" that contain Python code. These code cells can be executed by pressing "Shift + Return". In the simplest case, these can be used like a calculator:

```
[1]: 3+4
[1]: 7
```

```
[2]: print("Hello") # General Python code can be executed
```

Hello

A document can also contain "markdown cells", cells with text comments that support simple formatting (see basic markdown syntax), embedding links, images, etc. Of particular use for us is the ability to include equations using LaTeX syntax (enclosed in \$-signs). By double clicking on a markdown cell you can edit it, the "Shift + Return" combination that executes code cells will turn a markdown cell into nicely formatted text:

2 Headings

- bullet
- points

Some text. *italics* or **bold**.

```
\frac{dV}{dt} = \dots
```

```
[3]: from brian2 import * # We import "everything" from the brian2 package
```

```
[4]: # deactivate Brian's model → C++ code mechanism. Our models are too simple to⊔
⇒benefit from this:

prefs.codegen.target = 'numpy'
```

[5]: # jupter notebook/lab command for shorter error messages %xmode minimal

Exception reporting mode: Minimal

- [6]: # Brian adds a system for physical quantities
 x = 3*mV
 x + 500*uvolt # μV
- [6]: 3.5 mV
- [7]: # Units can be combined x * 1*nA
- [7]: $3.0 \,\mathrm{pW}$
- [8]: # Unit mismatches raise errors
 x + 1*nA

DimensionMismatchError: Cannot calculate 3. mV add 1. nA, the units do not matc. (units are V and A).

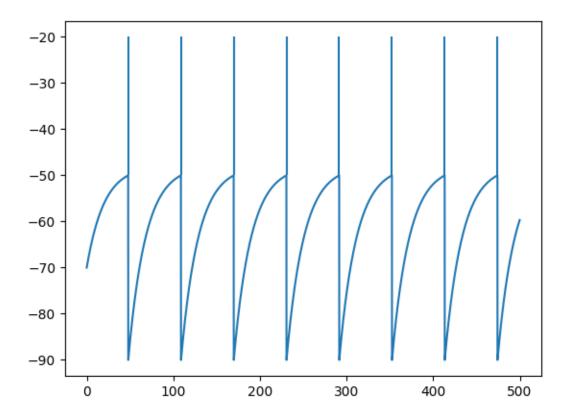
3 Part 1: Neurons

The basic equation for a leaky integrate-and-fire model:

$$\frac{dV}{dt} = (g_L(E_L - V) + I_{stim})/C_m$$

```
[9]: # The start_scope() is something that we only need when we run several Brian_
     ⇔simulations in a single
     # notebook or script. It means: "forget the models defined earlier". Without
     ⇔it, Brian would be confused
     # when we call "run(...)", since there are several models that could be run.
     start_scope()
     # We can write down the above equation for Brian in a very similar way to the
     ⇔original equation
     # The only Brian-specific syntax is the physical unit of the variable after the
     ⇔colon (here: volt for a voltage)
     eqs = "dV/dt = (g_L*(E_L - V) + I_stim)/C_m : volt"
     # The constants that are used in the above equations can be defined as Pythonu
     \rightarrow variables
     # Brian provides the units (nF, mV, nS, nA, ...) and knows how to combine/
     ⇔convert between them
     C m = 0.4*nF
     E_L = -70*mV
```

```
g_L = 20*nS
      I_stim = 0.44*nA
      # Now we put all the components together to create a group of neurons (here L
       ⇔with a single neuron).
      # In addition to the equations, we also define a threshold condition and all
       ⇔reset statement.
      \# method='exact' means to integrate the equations using their analytical \sqcup
       ⇔solution (only possible for
      # simple equations). Other possible choices are e.g. 'euler' (forward Euler
       ⇔method, very fast but not
      # accurate/stable) or 'rk4' (4th order Runge-Kutta method, very accurate but
       ⇔slow)
      neurons = NeuronGroup(1, model=eqs, threshold="V > -50*mV",
                             reset="V = -90*mV", method='exact')
      # All variables of our model (here, "V" is the only variable) are available as \Box
       ⇔attributes of the NeuronGroup
      \# object. We can ask for their values or set them to set the initial conditions \sqcup
       →at the start of the simulation
      neurons.V = E L
      # To record the values of variables during a simulation, we need a_{\sqcup}
       →"StateMonitor". Its arguments are
      # "which group to record from", "which variable to record", "which neurons to_{\sqcup}
       ⇔record from".
      state_mon = StateMonitor(neurons, "V", record=True) # True = all neurons
      # To record the information about which neuron spiked when, we use a_{\sqcup}
       \hookrightarrowSpikeMonitor
      spike_mon = SpikeMonitor(neurons)
      # Now we are ready to run the simulation
      run(500*ms)
[10]: # Plot the membrane potential of the 1st neuron (neuron with index 0) in mV_
       →against the time of the recordings
      # in ms
      plt.plot(state_mon.t/ms, state_mon.V[0]/mV)
      # Plot vertical lines from -50mV to -20mV for each spike
      plt.vlines(spike_mon.t/ms, -50, -20); # ← we can put a semicolon to avoid text_
       \hookrightarrow output
                                               # from plotting functions
```



We now turn our differential equation into a stochastic differential equation, by including a noise term. This is meant to make our model a bit more "realistic", since biological neurons are not perfectly smooth machines. Do not worry too much about the scaling with the $\sqrt(2/\tau)$ term, this is necessary for dimensional correctness (some remarks about this in the Brian documentation).

$$\frac{dV}{dt} = (g_L(E_L - V) + I_{const})/C_m + \sigma \sqrt{2/\tau} \xi$$

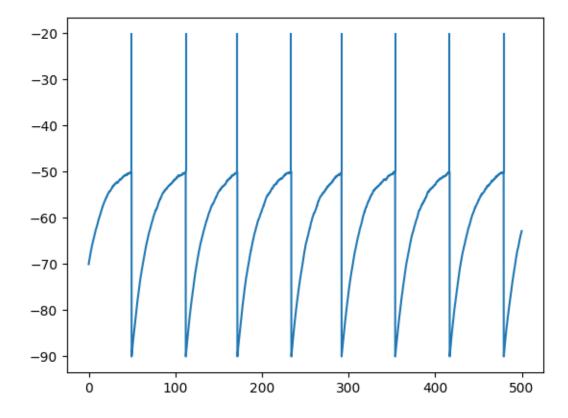
The time constant $\tau = C_m/g_L$ determines how fast the neuron reacts to changes in its input.

0.4 nF 20. nS 20. ms

```
[12]: start_scope()

# The equation refers to "xi", which is the predefined noise term
eqs = "dV/dt = (g_L*(E_L - V) + I_stim)/C_m + sigma*sqrt(2/tau)*xi: volt"
C_m = 0.4*nF
E_L = -70*mV
g_L = 20*nS
I_stim = 0.44*nA
sigma = 0.3*mV
tau = C_m/g_L
```

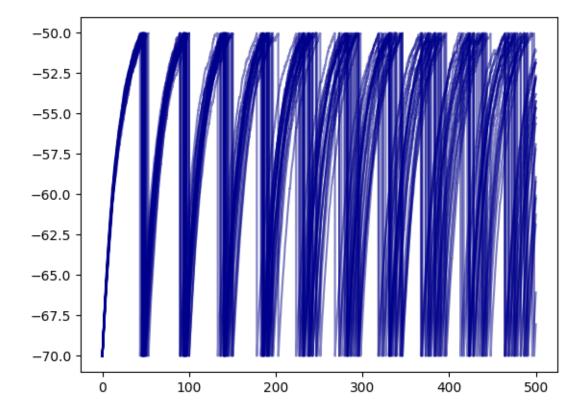
```
[13]: # If you look closely, you see that the lines are a bit "wiggly" now plt.plot(state_mon.t/ms, state_mon.V[0]/mV) plt.vlines(spike_mon.t/ms, -50, -20);
```



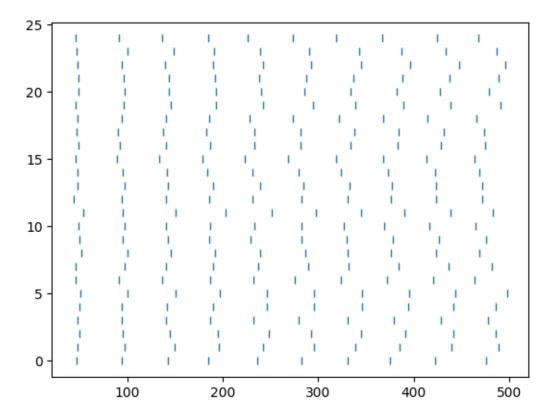
We can now reproduce the observation by Mainen & Sejnowski (1995) that a neuron spikes unreliably (different spike times in repeated trials) when stimulated with a constant current. Instead of running the simulation 25 times for a single neuron, we simulate a group of 25 independent neurons at once – this gives the exact same results (since all neurons are perfectly identical), but is a bit more compact to write and more efficient to simulate.

```
[14]: start_scope()
eqs = "dV/dt = (g_L*(E_L - V) + I_stim)/C_m + sigma*sqrt(2/tau)*xi: volt"
```

[15]: plt.plot(state_mon.t/ms, state_mon.V.T/mV, color='darkblue', alpha=0.5);

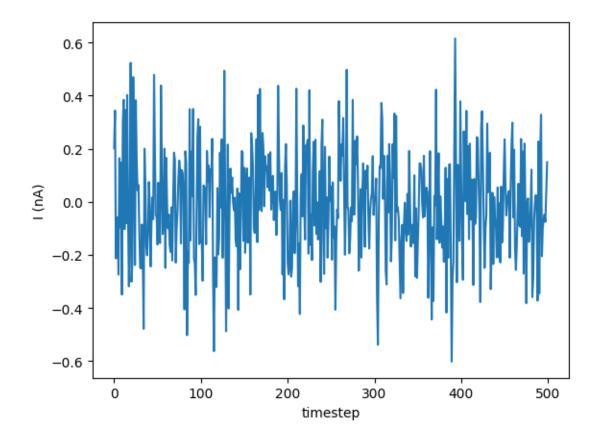


As we can see, initially the membrane potential trajectory is very similar across neurons, but quickly it starts to drift and become different. We can see the same in a raster plot:



Now, let us reproduce the second part of the experiment, i.e. the response of a neuron to a fluctuating input current. We can use Brian's equation machinery to generate this noise stimulus, it is not restricted to only model neurons and their properties. We generate a random input current first:

```
[17]: random_current = np.random.randn(500)*0.2*nA
    plt.plot(random_current/nA)
    plt.ylabel('I (nA)')
    plt.xlabel('timestep');
```

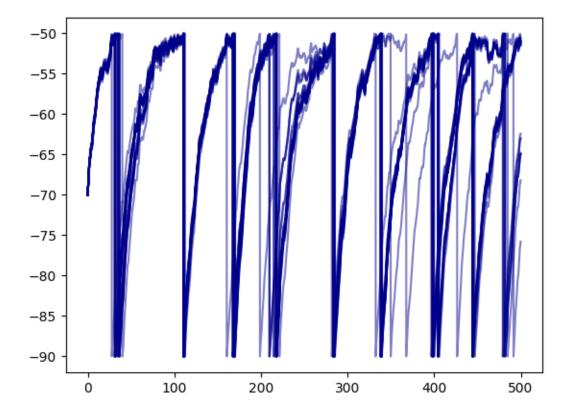


```
[18]: start_scope()
      \# By wrapping the noise current in a "TimedArray", we can access it in the \sqcup
      →equations as a function of time
      random_current = np.random.randn(500)*0.2*nA
      I_noise = TimedArray(random_current, dt=1*ms)
      # We add the fluctuating current to the constant current, so the mean input_{\sqcup}
      ⇔current will be the same as
      # before - the new current fluctuates around the value of the constant current.
      eqs = """dV/dt = (g_L*(E_L - V) + I_stim + I_noise(t))/C_m +
                       sigma*sqrt(2/tau)*xi: volt
            0.000
      C_m = 0.4*nF
      E_L = -70*mV
      g_L = 20*nS
      I_stim = 0.44*nA
      sigma = 0.3*mV
      tau = C_m/g_L
      neurons = NeuronGroup(25, model=eqs, threshold="V > -50*mV",
```

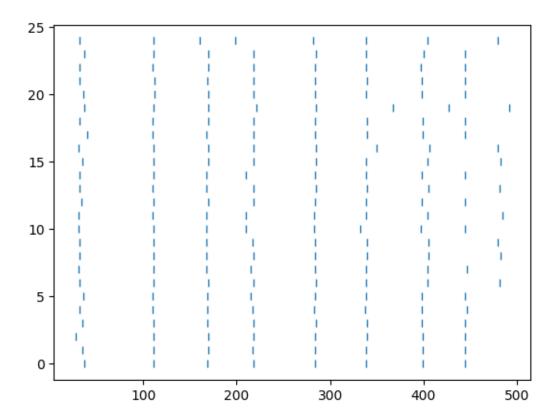
```
reset="V = -90*mV", method='euler')
neurons.V = E_L
state_mon = StateMonitor(neurons, "V", record=True) # True = all neurons
spike_mon = SpikeMonitor(neurons)
run(500*ms)
```

Now, the membrane potential traces over trials look much more similar. And instead of slowly drifting and becoming more different over time, differences are temporary and neurons will "realign" at a later stage:

```
[19]: plt.plot(state_mon.t/ms, state_mon.V.T/mV, color='darkblue', alpha=0.5);
```



```
[20]: plt.plot(spike_mon.t/ms, spike_mon.i, '|');
```

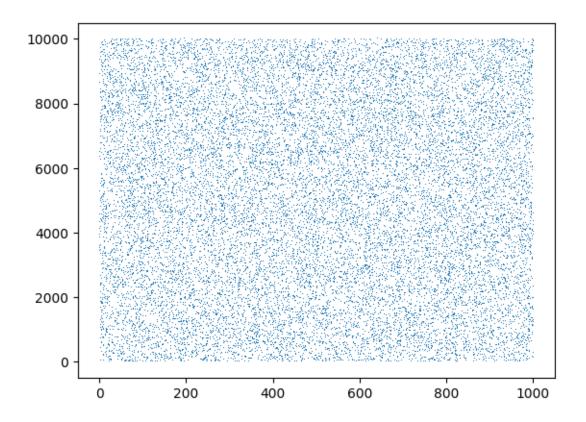


4 Part 2: networks

Let us look at how a neuron in cortex, which receives input from many other neurons, integrates the inputs and whether we can see a difference between a mean-driven and a fluctuation-driven regime. As an input source, we use a group of simplified "Poisson neurons", i.e. neurons that aren't modeled in any detail, but simply emit spikes according to a Poisson process:

```
[21]: start_scope()
    poisson_spikes = PoissonGroup(10000, rates=2/second)
    poisson_mon = SpikeMonitor(poisson_spikes)
    run(1000*ms)

[22]: plt.plot(poisson_mon.t/ms, poisson_mon.i, ',');
```

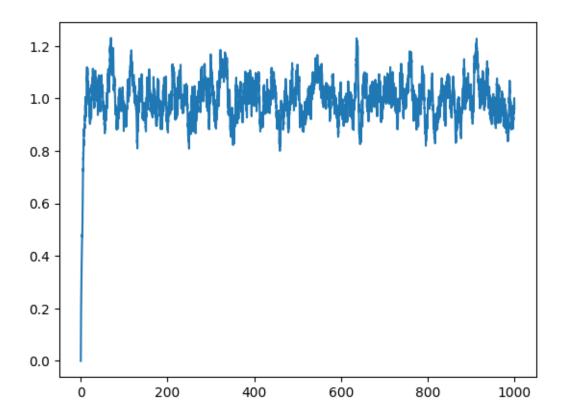


```
[23]: start_scope()
      poisson_spikes = PoissonGroup(10000, rates=2/second)
      # We now include a synaptic current in our neuron model, which replaces the
      ⇔previous constant/fluctuating
      # currents. In the absence of any incoming spikes, it goes back to 0 with time
      ⇔constant tau_syn:
      tau_syn = 5*ms
      eqs = """dV/dt = (g_L*(E_L - V) + I_syn)/C_m: volt
               dI_syn/dt = -I_syn/tau_syn : amp
            0.00
      C_m = 0.4*nF
      E_L = -70*mV
      g_L = 20*nS
     neurons = NeuronGroup(1, model=eqs, threshold="V > -50*mV",
                           reset="V = -90*mV", method='euler')
      neurons.V = E_L
      # We now create a description of our Synapses. In complicated models (synaptic_
       →plasticity, etc.), we'd have
```

```
\# equations describing the synapses. Here, we only state that "on the arrival"
⇔of an incoming pre-synaptic spike"
# ("on_pre"), increase the post-synaptic current I_syn by 0.01nA:
synapses = Synapses(poisson_spikes, neurons,
                    on_pre='I_syn += 0.01*nA')
# Our target group here only has a single neuron, but in more complex networks \Box
→we'd now decide how to connect
# neurons in the source group to neurons in the target group (e.g. all-to-all,
or with certain rules based e.g. on
# their distance, or randomly with a given probability, etc.). Here we simply \Box
⇔call "connect()" which connects
# all neurons in the source group to "all" (there's only one) neurons in the
⇔target group.
synapses.connect()
\# in addition to V, we also record the synaptic current I\_syn
state_mon = StateMonitor(neurons, ["V", "I_syn"], record=True)
spike_mon = SpikeMonitor(neurons)
run(1000*ms)
```

[24]: plt.plot(state_mon.t/ms, state_mon.I_syn[0]/nA);
print("mean current:", np.mean(state_mon.I_syn[0]))

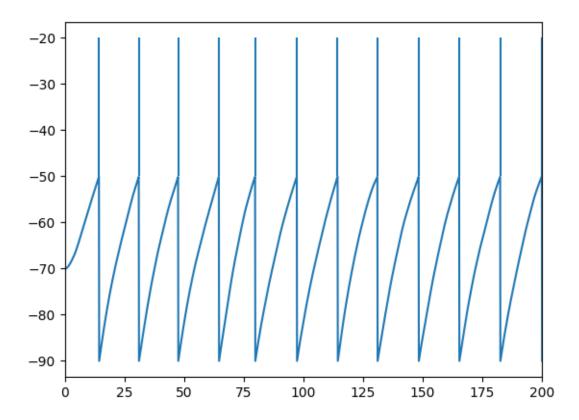
mean current: 0.99503286 nA



The input that the neuron receives is fairly constant (due to the large number of incoming spikes), and its mean is well above the threshold of the neuron. As a consequence, the neuron fires regularly:

```
[25]: plt.plot(state_mon.t/ms, state_mon.V[0]/mV); plt.vlines(spike_mon.t/ms, -50, -20) plt.xlim(0, 200) # focussing on the first 200ms for a clearer picture
```

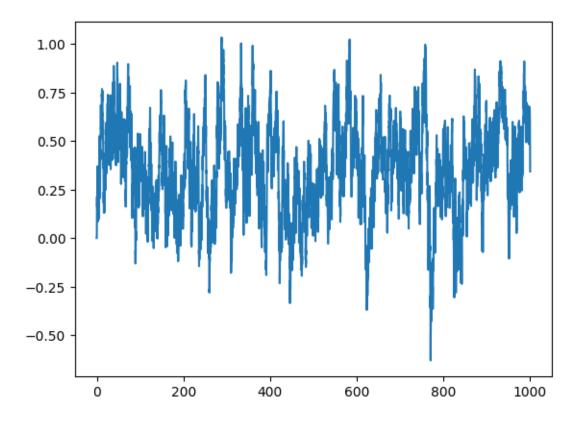
[25]: (0.0, 200.0)



In the above "network", there were only excitatory connections. Real neurons recieve both excitatory and inhibitory input. In cortex, about 80% of the cells are excitatory and 20% are inhibitory, but this is partly compensated by the fact that inhibitory connections tend to be stronger. Let's separate our input "neurons" and divide them into excitatory and inhibitory, which get connected with corresponding connections to our target neuron:

```
[27]: plt.plot(state_mon.t/ms, state_mon.I_syn[0]/nA); print("mean current:", np.mean(state_mon.I_syn[0]))
```

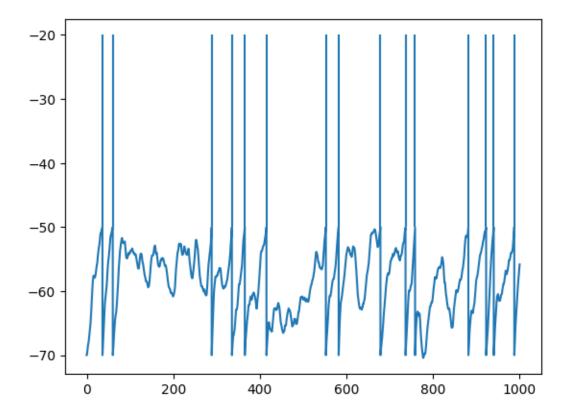
mean current: 0.35497956 nA



The total received input is now much weaker (and more variable), leading to a neuron that fires

irregularly:

```
[28]: plt.plot(state_mon.t/ms, state_mon.V[0]/mV);
plt.vlines(spike_mon.t/ms, -50, -20);
```



Instead of simulating a single neuron with random external input, let's simulate a network of cells that connect to each other. Since without any external input, no neuron would spike, we additionally add a (super-threshold) input current.

```
# all of them spike at exactly the same time. To avoid this artificial
 synchronization at the beginning
# of the simulation, we initialize the membrane potential to a random value for
 ⇔each cell
# (between -70mV and -50mV)
neurons.V = "E L + rand()*20*mV"
exc_neurons = neurons[:800]
inh_neurons = neurons[800:]
# We connect the 800 excitatory neurons to all neurons with excitatory
 ⇔synapses, but only connect each
# possible pair of connections with a probability of 2% (i.e. each neuron_
 ⇔receives on average 800×0.02=16
# excitatory inputs)
exc_synapses = Synapses(exc_neurons, neurons, on_pre='I_syn_post += 100*pA')
exc_synapses.connect(p=0.02)
# We do the same for the inhibitory neurons. Since there are fewer inhibitory
 ⇔neurons, each neuron will
# only receive 4 inhibitory inputs on average.
inh_synapses = Synapses(inh_neurons, neurons, on_pre='I_syn_post -= 200*pA')
inh_synapses.connect(p=0.02)
state_mon = StateMonitor(neurons, 'V', record=True)
current_mon = StateMonitor(neurons, 'I_syn', record=True)
spike_mon = SpikeMonitor(neurons)
run(1*second, report='text')
```

Starting simulation at t=0. s for a duration of 1. s 1. s (100%) simulated in < 1s

Without the network connections, all neurons would fire regularly with the same rate. Due to the input from the network (and the random connectivity), the neurons fire asynchronously and irregularly:

```
[30]: plt.plot(spike_mon.t/ms, spike_mon.i, '.');
# Zoom in on a subset of cells and time
plt.xlim(400, 600)
plt.ylim(0, 100);
```

