

all times. For example, with circuit-switched TDM, if a one-second frame is divided into 10 time slots of 100 ms each, then each user would be allocated one time slot per frame.

Thus, the circuit-switched link can support only 10 ($= 1 \text{ Mbps}/100 \text{ kbps}$) simultaneous users. With packet switching, the probability that a specific user is active is 0.1 (that is, 10 percent). If there are 35 users, the probability that there are 11 or more simultaneously active users is approximately 0.0004. (Homework Problem P8 outlines how this probability is obtained.) When there are 10 or fewer simultaneously active users (which happens with probability 0.9996), the aggregate arrival rate of data is less than or equal to 1 Mbps, the output rate of the link. Thus, when there are 10 or fewer active users, users' packets flow through the link essentially without delay, as is the case with circuit switching. When there are more than 10 simultaneously active users, then the aggregate arrival rate of packets exceeds the output capacity of the link, and the output queue will begin to grow. (It continues to grow until the aggregate input rate falls back below 1 Mbps, at which point the queue will begin to diminish in length.) Because the probability of having more than 10 simultaneously active users is minuscule in this example, packet switching provides essentially the same performance as circuit switching, *but does so while allowing for more than three times the number of users*.

Let's now consider a second simple example. Suppose there are 10 users and that one user suddenly generates one thousand 1,000-bit packets, while other users remain quiescent and do not generate packets. Under TDM circuit switching with 10 slots per frame and each slot consisting of 1,000 bits, the active user can only use its one time slot per frame to transmit data, while the remaining nine time slots in each frame remain idle. It will be 10 seconds before all of the active user's one million bits of data has been transmitted. In the case of packet switching, the active user can continuously send its packets at the full link rate of 1 Mbps, since there are no other users generating packets that need to be multiplexed with the active user's packets. In this case, all of the active user's data will be transmitted within 1 second.

The above examples illustrate two ways in which the performance of packet switching can be superior to that of circuit switching. They also highlight the crucial difference between the two forms of sharing a link's transmission rate among multiple data streams. Circuit switching pre-allocates use of the transmission link regardless of demand, with allocated but unneeded link time going unused. Packet switching on the other hand allocates link use *on demand*. Link transmission capacity will be shared on a packet-by-packet basis only among those users who have packets that need to be transmitted over the link.

Although packet switching and circuit switching are both prevalent in today's telecommunication networks, the trend has certainly been in the direction of packet switching. Even many of today's circuit-switched telephone networks are slowly migrating toward packet switching. In particular, telephone networks often use packet switching for the expensive overseas portion of a telephone call.

1.3.3 A Network of Networks

We saw earlier that end systems (PCs, smartphones, Web servers, mail servers, and so on) connect into the Internet via an access ISP. The access ISP can provide either wired or wireless connectivity, using an array of access technologies including DSL, cable, FTTH, Wi-Fi, and cellular. Note that the access ISP does not have to be a telco or a cable company; instead it can be, for example, a university (providing Internet access to students, staff, and faculty), or a company (providing access for its employees). But connecting end users and content providers into an access ISP is only a small piece of solving the puzzle of connecting the billions of end systems that make up the Internet. To complete this puzzle, the access ISPs themselves must be interconnected. This is done by creating a *network of networks*—understanding this phrase is the key to understanding the Internet.

Over the years, the network of networks that forms the Internet has evolved into a very complex structure. Much of this evolution is driven by economics and national policy, rather than by performance considerations. In order to understand today's Internet network structure, let's incrementally build a series of network structures, with each new structure being a better approximation of the complex Internet that we have today. Recall that the overarching goal is to interconnect the access ISPs so that all end systems can send packets to each other. One naive approach would be to have each access ISP *directly* connect with every other access ISP. Such a mesh design is, of course, much too costly for the access ISPs, as it would require each access ISP to have a separate communication link to each of the hundreds of thousands of other access ISPs all over the world.

Our first network structure, *Network Structure 1*, interconnects all of the access ISPs with a *single global transit ISP*. Our (imaginary) global transit ISP is a network of routers and communication links that not only spans the globe, but also has at least one router near each of the hundreds of thousands of access ISPs. Of course, it would be very costly for the global ISP to build such an extensive network. To be profitable, it would naturally charge each of the access ISPs for connectivity, with the pricing reflecting (but not necessarily directly proportional to) the amount of traffic an access ISP exchanges with the global ISP. Since the access ISP pays the global transit ISP, the access ISP is said to be a **customer** and the global transit ISP is said to be a **provider**.

Now if some company builds and operates a global transit ISP that is profitable, then it is natural for other companies to build their own global transit ISPs and compete with the original global transit ISP. This leads to *Network Structure 2*, which consists of the hundreds of thousands of access ISPs and *multiple* global transit ISPs. The access ISPs certainly prefer Network Structure 2 over Network Structure 1 since they can now choose among the competing global transit providers as a function of their pricing and services. Note, however, that the global transit ISPs

themselves must interconnect: Otherwise access ISPs connected to one of the global transit providers would not be able to communicate with access ISPs connected to the other global transit providers.

Network Structure 2, just described, is a two-tier hierarchy with global transit providers residing at the top tier and access ISPs at the bottom tier. This assumes that global transit ISPs are not only capable of getting close to each and every access ISP, but also find it economically desirable to do so. In reality, although some ISPs do have impressive global coverage and do directly connect with many access ISPs, no ISP has presence in each and every city in the world. Instead, in any given region, there may be a **regional ISP** to which the access ISPs in the region connect. Each regional ISP then connects to **tier-1 ISPs**. Tier-1 ISPs are similar to our (imaginary) global transit ISP; but tier-1 ISPs, which actually do exist, do not have a presence in every city in the world. There are approximately a dozen tier-1 ISPs, including Level 3 Communications, AT&T, Sprint, and NTT. Interestingly, no group officially sanctions tier-1 status; as the saying goes—if you have to ask if you’re a member of a group, you’re probably not.

Returning to this network of networks, not only are there multiple competing tier-1 ISPs, there may be multiple competing regional ISPs in a region. In such a hierarchy, each access ISP pays the regional ISP to which it connects, and each regional ISP pays the tier-1 ISP to which it connects. (An access ISP can also connect directly to a tier-1 ISP, in which case it pays the tier-1 ISP). Thus, there is customer-provider relationship at each level of the hierarchy. Note that the tier-1 ISPs do not pay anyone as they are at the top of the hierarchy. To further complicate matters, in some regions, there may be a larger regional ISP (possibly spanning an entire country) to which the smaller regional ISPs in that region connect; the larger regional ISP then connects to a tier-1 ISP. For example, in China, there are access ISPs in each city, which connect to provincial ISPs, which in turn connect to national ISPs, which finally connect to tier-1 ISPs [Tian 2012]. We refer to this multi-tier hierarchy, which is still only a crude approximation of today’s Internet, as *Network Structure 3*.

To build a network that more closely resembles today’s Internet, we must add points of presence (PoPs), multi-homing, peering, and Internet exchange points (IXPs) to the hierarchical Network Structure 3. PoPs exist in all levels of the hierarchy, except for the bottom (access ISP) level. A **PoP** is simply a group of one or more routers (at the same location) in the provider’s network where customer ISPs can connect into the provider ISP. For a customer network to connect to a provider’s PoP, it can lease a high-speed link from a third-party telecommunications provider to directly connect one of its routers to a router at the PoP. Any ISP (except for tier-1 ISPs) may choose to **multi-home**, that is, to connect to two or more provider ISPs. So, for example, an access ISP may multi-home with two regional ISPs, or it may multi-home with two regional ISPs and also with a tier-1 ISP. Similarly, a regional ISP may multi-home with multiple tier-1 ISPs. When an

ISP multi-homes, it can continue to send and receive packets into the Internet even if one of its providers has a failure.

As we just learned, customer ISPs pay their provider ISPs to obtain global Internet interconnectivity. The amount that a customer ISP pays a provider ISP reflects the amount of traffic it exchanges with the provider. To reduce these costs, a pair of nearby ISPs at the same level of the hierarchy can **peer**, that is, they can directly connect their networks together so that all the traffic between them passes over the direct connection rather than through upstream intermediaries. When two ISPs peer, it is typically settlement-free, that is, neither ISP pays the other. As noted earlier, tier-1 ISPs also peer with one another, settlement-free. For a readable discussion of peering and customer-provider relationships, see [Van der Berg 2008]. Along these same lines, a third-party company can create an **Internet Exchange Point (IXP)** (typically in a stand-alone building with its own switches), which is a meeting point where multiple ISPs can peer together. There are roughly 300 IXPs in the Internet today [Augustin 2009]. We refer to this ecosystem—consisting of access ISPs, regional ISPs, tier-1 ISPs, PoPs, multi-homing, peering, and IXPs—as *Network Structure 4*.

We now finally arrive at *Network Structure 5*, which describes the Internet of 2012. Network Structure 5, illustrated in Figure 1.15, builds on top of Network Structure 4 by adding **content provider networks**. Google is currently one of the leading examples of such a content provider network. As of this writing, it is estimated that Google has 30 to 50 data centers distributed across North America, Europe, Asia, South America, and Australia. Some of these data centers house over one hundred thousand servers, while other data centers are smaller, housing only hundreds of servers. The Google data centers are all interconnected via Google’s private TCP/IP network, which spans the entire globe but is nevertheless separate from the public Internet. Importantly, the Google private network only

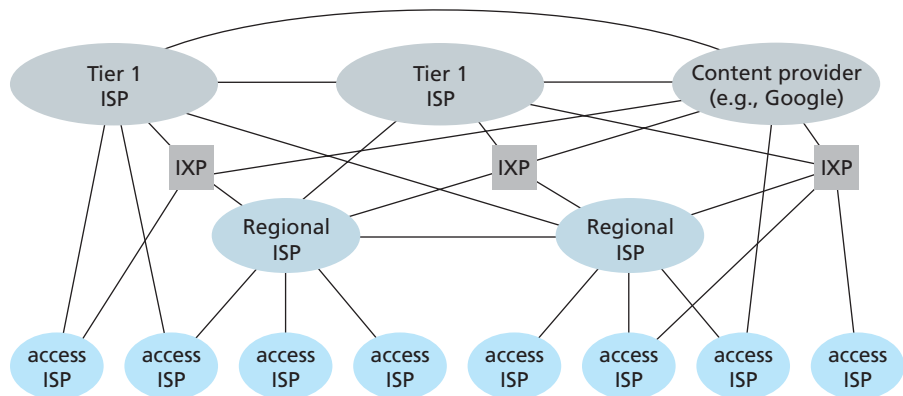


Figure 1.15 ♦ Interconnection of ISPs

carries traffic to/from Google servers. As shown in Figure 1.15, the Google private network attempts to “bypass” the upper tiers of the Internet by peering (settlement free) with lower-tier ISPs, either by directly connecting with them or by connecting with them at IXPs [Labovitz 2010]. However, because many access ISPs can still only be reached by transiting through tier-1 networks, the Google network also connects to tier-1 ISPs, and pays those ISPs for the traffic it exchanges with them. By creating its own network, a content provider not only reduces its payments to upper-tier ISPs, but also has greater control of how its services are ultimately delivered to end users. Google’s network infrastructure is described in greater detail in Section 7.2.4.

In summary, today’s Internet—a network of networks—is complex, consisting of a dozen or so tier-1 ISPs and hundreds of thousands of lower-tier ISPs. The ISPs are diverse in their coverage, with some spanning multiple continents and oceans, and others limited to narrow geographic regions. The lower-tier ISPs connect to the higher-tier ISPs, and the higher-tier ISPs interconnect with one another. Users and content providers are customers of lower-tier ISPs, and lower-tier ISPs are customers of higher-tier ISPs. In recent years, major content providers have also created their own networks and connect directly into lower-tier ISPs where possible.

1.4 Delay, Loss, and Throughput in Packet-Switched Networks

Back in Section 1.1 we said that the Internet can be viewed as an infrastructure that provides services to distributed applications running on end systems. Ideally, we would like Internet services to be able to move as much data as we want between any two end systems, instantaneously, without any loss of data. Alas, this is a lofty goal, one that is unachievable in reality. Instead, computer networks necessarily constrain throughput (the amount of data per second that can be transferred) between end systems, introduce delays between end systems, and can actually lose packets. On one hand, it is unfortunate that the physical laws of reality introduce delay and loss as well as constrain throughput. On the other hand, because computer networks have these problems, there are many fascinating issues surrounding how to deal with the problems—more than enough issues to fill a course on computer networking and to motivate thousands of PhD theses! In this section, we’ll begin to examine and quantify delay, loss, and throughput in computer networks.

1.4.1 Overview of Delay in Packet-Switched Networks

Recall that a packet starts in a host (the source), passes through a series of routers, and ends its journey in another host (the destination). As a packet travels from one node (host or router) to the subsequent node (host or router) along this path, the

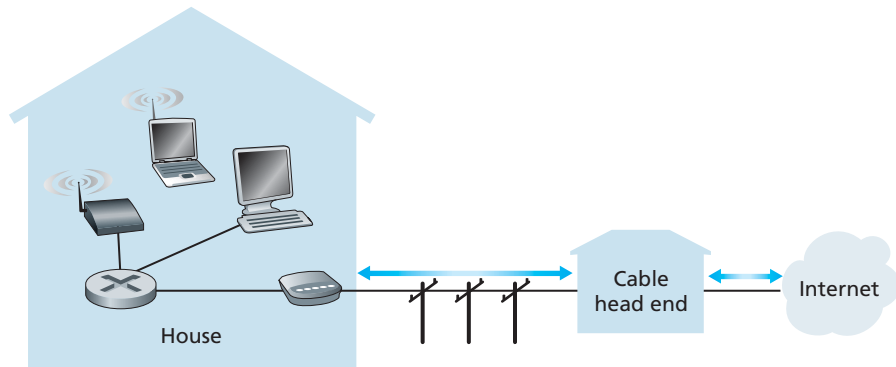


Figure 1.9 ♦ A typical home network

Wide-Area Wireless Access: 3G and LTE

Increasingly, devices such as iPhones, BlackBerrys, and Android devices are being used to send email, surf the Web, Tweet, and download music while on the run. These devices employ the same wireless infrastructure used for cellular telephony to send/receive packets through a base station that is operated by the cellular network provider. Unlike WiFi, a user need only be within a few tens of kilometers (as opposed to a few tens of meters) of the base station.

Telecommunications companies have made enormous investments in so-called third-generation (3G) wireless, which provides packet-switched wide-area wireless Internet access at speeds in excess of 1 Mbps. But even higher-speed wide-area access technologies—a fourth-generation (4G) of wide-area wireless networks—are already being deployed. LTE (for “Long-Term Evolution”—a candidate for Bad Acronym of the Year Award) has its roots in 3G technology, and can potentially achieve rates in excess of 10 Mbps. LTE downstream rates of many tens of Mbps have been reported in commercial deployments. We’ll cover the basic principles of wireless networks and mobility, as well as WiFi, 3G, and LTE technologies (and more!) in Chapter 6.

1.2.2 Physical Media

In the previous subsection, we gave an overview of some of the most important network access technologies in the Internet. As we described these technologies, we also indicated the physical media used. For example, we said that HFC uses a combination of fiber cable and coaxial cable. We said that DSL and Ethernet use copper wire. And we said that mobile access networks use the radio spectrum.

In this subsection we provide a brief overview of these and other transmission media that are commonly used in the Internet.

In order to define what is meant by a physical medium, let us reflect on the brief life of a bit. Consider a bit traveling from one end system, through a series of links and routers, to another end system. This poor bit gets kicked around and transmitted many, many times! The source end system first transmits the bit, and shortly thereafter the first router in the series receives the bit; the first router then transmits the bit, and shortly thereafter the second router receives the bit; and so on. Thus our bit, when traveling from source to destination, passes through a series of transmitter-receiver pairs. For each transmitter-receiver pair, the bit is sent by propagating electromagnetic waves or optical pulses across a **physical medium**. The physical medium can take many shapes and forms and does not have to be of the same type for each transmitter-receiver pair along the path. Examples of physical media include twisted-pair copper wire, coaxial cable, multimode fiber-optic cable, terrestrial radio spectrum, and satellite radio spectrum. Physical media fall into two categories: **guided media** and **unguided media**. With guided media, the waves are guided along a solid medium, such as a fiber-optic cable, a twisted-pair copper wire, or a coaxial cable. With unguided media, the waves propagate in the atmosphere and in outer space, such as in a wireless LAN or a digital satellite channel.

But before we get into the characteristics of the various media types, let us say a few words about their costs. The actual cost of the physical link (copper wire, fiber-optic cable, and so on) is often relatively minor compared with other networking costs. In particular, the labor cost associated with the installation of the physical link can be orders of magnitude higher than the cost of the material. For this reason, many builders install twisted pair, optical fiber, and coaxial cable in every room in a building. Even if only one medium is initially used, there is a good chance that another medium could be used in the near future, and so money is saved by not having to lay additional wires in the future.

Twisted-Pair Copper Wire

The least expensive and most commonly used guided transmission medium is twisted-pair copper wire. For over a hundred years it has been used by telephone networks. In fact, more than 99 percent of the wired connections from the telephone handset to the local telephone switch use twisted-pair copper wire. Most of us have seen twisted pair in our homes and work environments. Twisted pair consists of two insulated copper wires, each about 1 mm thick, arranged in a regular spiral pattern. The wires are twisted together to reduce the electrical interference from similar pairs close by. Typically, a number of pairs are bundled together in a cable by wrapping the pairs in a protective shield. A wire pair constitutes a single communication link. **Unshielded twisted pair (UTP)** is commonly used for

computer networks within a building, that is, for LANs. Data rates for LANs using twisted pair today range from 10 Mbps to 10 Gbps. The data rates that can be achieved depend on the thickness of the wire and the distance between transmitter and receiver.

When fiber-optic technology emerged in the 1980s, many people disparaged twisted pair because of its relatively low bit rates. Some people even felt that fiber-optic technology would completely replace twisted pair. But twisted pair did not give up so easily. Modern twisted-pair technology, such as category 6a cable, can achieve data rates of 10 Gbps for distances up to a hundred meters. In the end, twisted pair has emerged as the dominant solution for high-speed LAN networking.

As discussed earlier, twisted pair is also commonly used for residential Internet access. We saw that dial-up modem technology enables access at rates of up to 56 kbps over twisted pair. We also saw that DSL (digital subscriber line) technology has enabled residential users to access the Internet at tens of Mbps over twisted pair (when users live close to the ISP's modem).

Coaxial Cable

Like twisted pair, coaxial cable consists of two copper conductors, but the two conductors are concentric rather than parallel. With this construction and special insulation and shielding, coaxial cable can achieve high data transmission rates. Coaxial cable is quite common in cable television systems. As we saw earlier, cable television systems have recently been coupled with cable modems to provide residential users with Internet access at rates of tens of Mbps. In cable television and cable Internet access, the transmitter shifts the digital signal to a specific frequency band, and the resulting analog signal is sent from the transmitter to one or more receivers. Coaxial cable can be used as a guided **shared medium**. Specifically, a number of end systems can be connected directly to the cable, with each of the end systems receiving whatever is sent by the other end systems.

Fiber Optics

An optical fiber is a thin, flexible medium that conducts pulses of light, with each pulse representing a bit. A single optical fiber can support tremendous bit rates, up to tens or even hundreds of gigabits per second. They are immune to electromagnetic interference, have very low signal attenuation up to 100 kilometers, and are very hard to tap. These characteristics have made fiber optics the preferred long-haul guided transmission media, particularly for overseas links. Many of the long-distance telephone networks in the United States and elsewhere now use fiber optics exclusively. Fiber optics is also prevalent in the backbone of the Internet. However, the high cost of optical devices—such as transmitters, receivers, and switches—has hindered their deployment for short-haul transport, such as in a LAN or into the

home in a residential access network. The Optical Carrier (OC) standard link speeds range from 51.8 Mbps to 39.8 Gbps; these specifications are often referred to as OC- n , where the link speed equals $n \times 51.8$ Mbps. Standards in use today include OC-1, OC-3, OC-12, OC-24, OC-48, OC-96, OC-192, OC-768. [Mukherjee 2006, Ramaswamy 2010] provide coverage of various aspects of optical networking.

Terrestrial Radio Channels

Radio channels carry signals in the electromagnetic spectrum. They are an attractive medium because they require no physical wire to be installed, can penetrate walls, provide connectivity to a mobile user, and can potentially carry a signal for long distances. The characteristics of a radio channel depend significantly on the propagation environment and the distance over which a signal is to be carried. Environmental considerations determine path loss and shadow fading (which decrease the signal strength as the signal travels over a distance and around/through obstructing objects), multipath fading (due to signal reflection off of interfering objects), and interference (due to other transmissions and electromagnetic signals).

Terrestrial radio channels can be broadly classified into three groups: those that operate over very short distance (e.g., with one or two meters); those that operate in local areas, typically spanning from ten to a few hundred meters; and those that operate in the wide area, spanning tens of kilometers. Personal devices such as wireless headsets, keyboards, and medical devices operate over short distances; the wireless LAN technologies described in Section 1.2.1 use local-area radio channels; the cellular access technologies use wide-area radio channels. We'll discuss radio channels in detail in Chapter 6.

Satellite Radio Channels

A communication satellite links two or more Earth-based microwave transmitter/receivers, known as ground stations. The satellite receives transmissions on one frequency band, regenerates the signal using a repeater (discussed below), and transmits the signal on another frequency. Two types of satellites are used in communications: **geostationary satellites** and **low-earth orbiting (LEO) satellites**.

Geostationary satellites permanently remain above the same spot on Earth. This stationary presence is achieved by placing the satellite in orbit at 36,000 kilometers above Earth's surface. This huge distance from ground station through satellite back to ground station introduces a substantial signal propagation delay of 280 milliseconds. Nevertheless, satellite links, which can operate at speeds of hundreds of Mbps, are often used in areas without access to DSL or cable-based Internet access.

LEO satellites are placed much closer to Earth and do not remain permanently above one spot on Earth. They rotate around Earth (just as the Moon does) and may communicate with each other, as well as with ground stations. To provide continuous

coverage to an area, many satellites need to be placed in orbit. There are currently many low-altitude communication systems in development. Lloyd's satellite constellations Web page [Wood 2012] provides and collects information on satellite constellation systems for communications. LEO satellite technology may be used for Internet access sometime in the future.

1.3 The Network Core

Having examined the Internet's edge, let us now delve more deeply inside the network core—the mesh of packet switches and links that interconnects the Internet's end systems. Figure 1.10 highlights the network core with thick, shaded lines.

1.3.1 Packet Switching

In a network application, end systems exchange **messages** with each other. Messages can contain anything the application designer wants. Messages may perform a control function (for example, the “Hi” messages in our handshaking example in Figure 1.2) or can contain data, such as an email message, a JPEG image, or an MP3 audio file. To send a message from a source end system to a destination end system, the source breaks long messages into smaller chunks of data known as **packets**. Between source and destination, each packet travels through communication links and **packet switches** (for which there are two predominant types, **routers** and **link-layer switches**). Packets are transmitted over each communication link at a rate equal to the *full* transmission rate of the link. So, if a source end system or a packet switch is sending a packet of L bits over a link with transmission rate R bits/sec, then the time to transmit the packet is L/R seconds.

Store-and-Forward Transmission

Most packet switches use **store-and-forward transmission** at the inputs to the links. Store-and-forward transmission means that the packet switch must receive the entire packet before it can begin to transmit the first bit of the packet onto the outbound link. To explore store-and-forward transmission in more detail, consider a simple network consisting of two end systems connected by a single router, as shown in Figure 1.11. A router will typically have many incident links, since its job is to switch an incoming packet onto an outgoing link; in this simple example, the router has the rather simple task of transferring a packet from one (input) link to the only other attached link. In this example, the source has three packets, each consisting of L bits, to send to the destination. At the snapshot of time shown in Figure 1.11, the source has transmitted some of packet 1, and the front of packet 1 has already arrived at the router. Because the router employs store-and-forwarding, at this instant of time, the router cannot transmit the bits it has received; instead it

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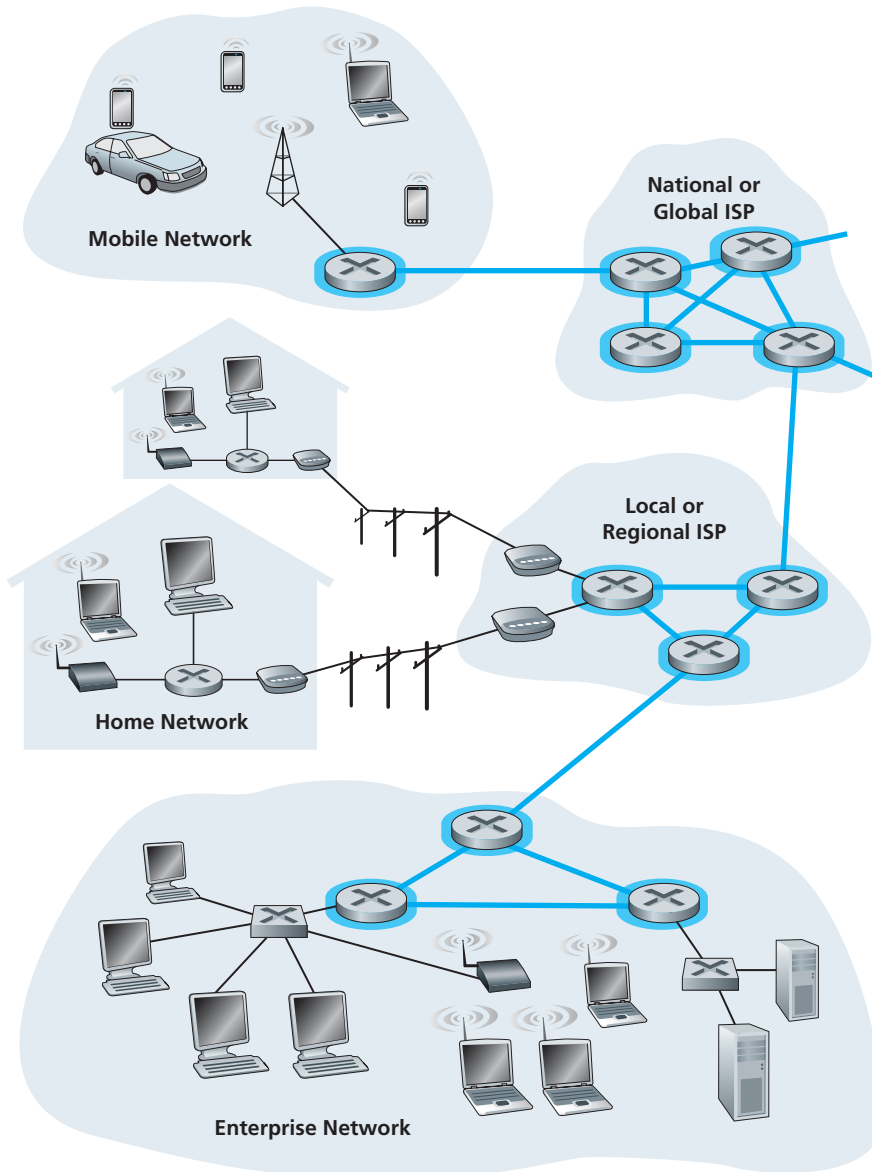


Figure 1.10 ♦ The network core

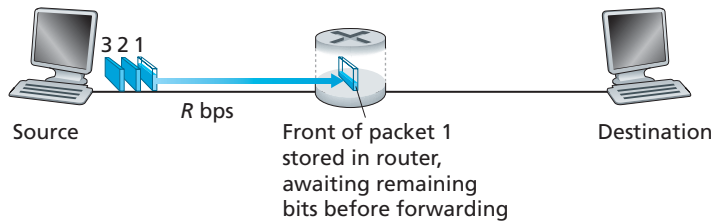


Figure 1.11 ♦ Store-and-forward packet switching

must first buffer (i.e., “store”) the packet’s bits. Only after the router has received *all* of the packet’s bits can it begin to transmit (i.e., “forward”) the packet onto the outbound link. To gain some insight into store-and-forward transmission, let’s now calculate the amount of time that elapses from when the source begins to send the packet until the destination has received the entire packet. (Here we will ignore propagation delay—the time it takes for the bits to travel across the wire at near the speed of light—which will be discussed in Section 1.4.) The source begins to transmit at time 0; at time L/R seconds, the source has transmitted the entire packet, and the entire packet has been received and stored at the router (since there is no propagation delay). At time L/R seconds, since the router has just received the entire packet, it can begin to transmit the packet onto the outbound link towards the destination; at time $2L/R$, the router has transmitted the entire packet, and the entire packet has been received by the destination. Thus, the total delay is $2L/R$. If the switch instead forwarded bits as soon as they arrive (without first receiving the entire packet), then the total delay would be L/R since bits are not held up at the router. But, as we will discuss in Section 1.4, routers need to receive, store, and process the entire packet before forwarding.

Now let’s calculate the amount of time that elapses from when the source begins to send the first packet until the destination has received all three packets. As before, at time L/R , the router begins to forward the first packet. But also at time L/R the source will begin to send the second packet, since it has just finished sending the entire first packet. Thus, at time $2L/R$, the destination has received the first packet and the router has received the second packet. Similarly, at time $3L/R$, the destination has received the first two packets and the router has received the third packet. Finally, at time $4L/R$ the destination has received all three packets!

Let’s now consider the general case of sending one packet from source to destination over a path consisting of N links each of rate R (thus, there are $N-1$ routers between source and destination). Applying the same logic as above, we see that the end-to-end delay is:

$$d_{\text{end-to-end}} = N \frac{L}{R} \quad (1.1)$$

You may now want to try to determine what the delay would be for P packets sent over a series of N links.

Queuing Delays and Packet Loss

Each packet switch has multiple links attached to it. For each attached link, the packet switch has an **output buffer** (also called an **output queue**), which stores packets that the router is about to send into that link. The output buffers play a key role in packet switching. If an arriving packet needs to be transmitted onto a link but finds the link busy with the transmission of another packet, the arriving packet must wait in the output buffer. Thus, in addition to the store-and-forward delays, packets suffer output buffer **queuing delays**. These delays are variable and depend on the level of congestion in the network. Since the amount of buffer space is finite, an arriving packet may find that the buffer is completely full with other packets waiting for transmission. In this case, **packet loss** will occur—either the arriving packet or one of the already-queued packets will be dropped.

Figure 1.12 illustrates a simple packet-switched network. As in Figure 1.11, packets are represented by three-dimensional slabs. The width of a slab represents the number of bits in the packet. In this figure, all packets have the same width and hence the same length. Suppose Hosts A and B are sending packets to Host E. Hosts A and B first send their packets along 10 Mbps Ethernet links to the first router. The router then directs these packets to the 1.5 Mbps link. If, during a short interval of time, the arrival rate of packets to the router (when converted to bits per second) exceeds 1.5 Mbps, congestion will occur at the router as packets queue in the link's output buffer before being transmitted onto the link. For example, if Host A and B each send a burst of five packets back-to-back at the same time, then most of these packets will spend some time waiting in the queue. The situation is, in fact, entirely analogous to many common-day situations—for example, when we wait in line for a bank teller or wait in front of a tollbooth. We'll examine this queuing delay in more detail in Section 1.4.

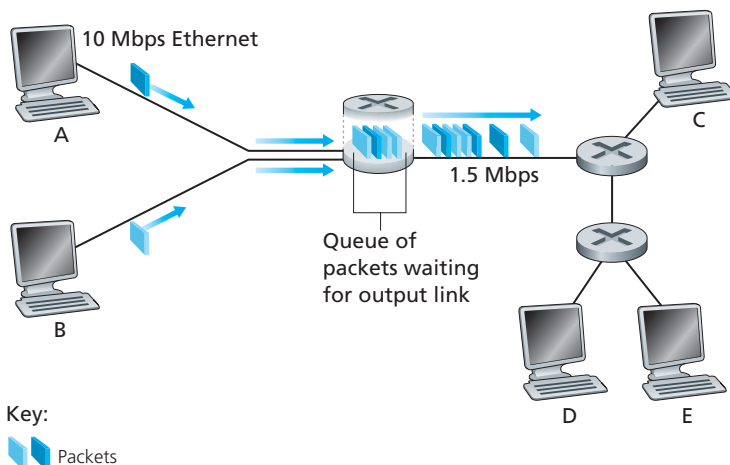


Figure 1.12 ♦ Packet switching

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In summary, today’s Internet—a network of networks—is complex, consisting of a dozen or so tier-1 ISPs and hundreds of thousands of lower-tier ISPs. The ISPs are diverse in their coverage, with some spanning multiple continents and oceans, and others limited to narrow geographic regions. The lower-tier ISPs connect to the higher-tier ISPs, and the higher-tier ISPs interconnect with one another. Users and content providers are customers of lower-tier ISPs, and lower-tier ISPs are customers of higher-tier ISPs. In recent years, major content providers have also created their own networks and connect directly into lower-tier ISPs where possible.

1.4 Delay, Loss, and Throughput in Packet-Switched Networks

Back in Section 1.1 we said that the Internet can be viewed as an infrastructure that provides services to distributed applications running on end systems. Ideally, we would like Internet services to be able to move as much data as we want between any two end systems, instantaneously, without any loss of data. Alas, this is a lofty goal, one that is unachievable in reality. Instead, computer networks necessarily constrain throughput (the amount of data per second that can be transferred) between end systems, introduce delays between end systems, and can actually lose packets. On one hand, it is unfortunate that the physical laws of reality introduce delay and loss as well as constrain throughput. On the other hand, because computer networks have these problems, there are many fascinating issues surrounding how to deal with the problems—more than enough issues to fill a course on computer networking and to motivate thousands of PhD theses! In this section, we’ll begin to examine and quantify delay, loss, and throughput in computer networks.

1.4.1 Overview of Delay in Packet-Switched Networks

Recall that a packet starts in a host (the source), passes through a series of routers, and ends its journey in another host (the destination). As a packet travels from one node (host or router) to the subsequent node (host or router) along this path, the

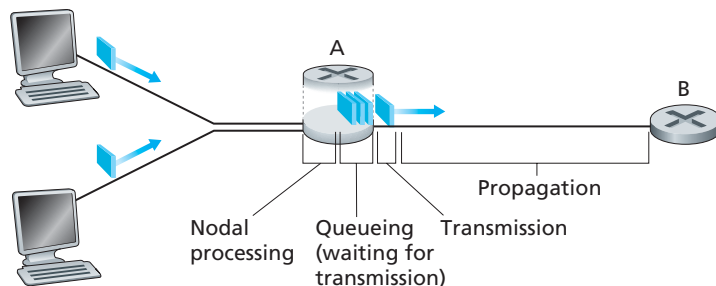


Figure 1.16 ♦ The nodal delay at router A

packet suffers from several types of delays at *each* node along the path. The most important of these delays are the **nodal processing delay**, **queuing delay**, **transmission delay**, and **propagation delay**; together, these delays accumulate to give a **total nodal delay**. The performance of many Internet applications—such as search, Web browsing, email, maps, instant messaging, and voice-over-IP—are greatly affected by network delays. In order to acquire a deep understanding of packet switching and computer networks, we must understand the nature and importance of these delays.

Types of Delay

Let's explore these delays in the context of Figure 1.16. As part of its end-to-end route between source and destination, a packet is sent from the upstream node through router A to router B. Our goal is to characterize the nodal delay at router A. Note that router A has an outbound link leading to router B. This link is preceded by a queue (also known as a buffer). When the packet arrives at router A from the upstream node, router A examines the packet's header to determine the appropriate outbound link for the packet and then directs the packet to this link. In this example, the outbound link for the packet is the one that leads to router B. A packet can be transmitted on a link only if there is no other packet currently being transmitted on the link and if there are no other packets preceding it in the queue; if the link is currently busy or if there are other packets already queued for the link, the newly arriving packet will then join the queue.

Processing Delay

The time required to examine the packet's header and determine where to direct the packet is part of the **processing delay**. The processing delay can also include other factors, such as the time needed to check for bit-level errors in the packet that occurred in transmitting the packet's bits from the upstream node to router A. Processing delays

in high-speed routers are typically on the order of microseconds or less. After this nodal processing, the router directs the packet to the queue that precedes the link to router B. (In Chapter 4 we'll study the details of how a router operates.)

Queuing Delay

At the queue, the packet experiences a **queuing delay** as it waits to be transmitted onto the link. The length of the queuing delay of a specific packet will depend on the number of earlier-arriving packets that are queued and waiting for transmission onto the link. If the queue is empty and no other packet is currently being transmitted, then our packet's queuing delay will be zero. On the other hand, if the traffic is heavy and many other packets are also waiting to be transmitted, the queuing delay will be long. We will see shortly that the number of packets that an arriving packet might expect to find is a function of the intensity and nature of the traffic arriving at the queue. Queuing delays can be on the order of microseconds to milliseconds in practice.

Transmission Delay

Assuming that packets are transmitted in a first-come-first-served manner, as is common in packet-switched networks, our packet can be transmitted only after all the packets that have arrived before it have been transmitted. Denote the length of the packet by L bits, and denote the transmission rate of the link from router A to router B by R bits/sec. For example, for a 10 Mbps Ethernet link, the rate is $R = 10$ Mbps; for a 100 Mbps Ethernet link, the rate is $R = 100$ Mbps. The **transmission delay** is L/R . This is the amount of time required to push (that is, transmit) all of the packet's bits into the link. Transmission delays are typically on the order of microseconds to milliseconds in practice.

Propagation Delay

Once a bit is pushed into the link, it needs to propagate to router B. The time required to propagate from the beginning of the link to router B is the **propagation delay**. The bit propagates at the propagation speed of the link. The propagation speed depends on the physical medium of the link (that is, fiber optics, twisted-pair copper wire, and so on) and is in the range of

$$2 \cdot 10^8 \text{ meters/sec to } 3 \cdot 10^8 \text{ meters/sec}$$

which is equal to, or a little less than, the speed of light. The propagation delay is the distance between two routers divided by the propagation speed. That is, the propagation delay is d/s , where d is the distance between router A and router B and s is the propagation speed of the link. Once the last bit of the packet propagates to node B, it and all the preceding bits of the packet are stored in router B. The whole

coverage to an area, many satellites need to be placed in orbit. There are currently many low-altitude communication systems in development. Lloyd's satellite constellations Web page [Wood 2012] provides and collects information on satellite constellation systems for communications. LEO satellite technology may be used for Internet access sometime in the future.

1.3 The Network Core

Having examined the Internet's edge, let us now delve more deeply inside the network core—the mesh of packet switches and links that interconnects the Internet's end systems. Figure 1.10 highlights the network core with thick, shaded lines.

1.3.1 Packet Switching

In a network application, end systems exchange **messages** with each other. Messages can contain anything the application designer wants. Messages may perform a control function (for example, the “Hi” messages in our handshaking example in Figure 1.2) or can contain data, such as an email message, a JPEG image, or an MP3 audio file. To send a message from a source end system to a destination end system, the source breaks long messages into smaller chunks of data known as **packets**. Between source and destination, each packet travels through communication links and **packet switches** (for which there are two predominant types, **routers** and **link-layer switches**). Packets are transmitted over each communication link at a rate equal to the *full* transmission rate of the link. So, if a source end system or a packet switch is sending a packet of L bits over a link with transmission rate R bits/sec, then the time to transmit the packet is L/R seconds.

Store-and-Forward Transmission

Most packet switches use **store-and-forward transmission** at the inputs to the links. Store-and-forward transmission means that the packet switch must receive the entire packet before it can begin to transmit the first bit of the packet onto the outbound link. To explore store-and-forward transmission in more detail, consider a simple network consisting of two end systems connected by a single router, as shown in Figure 1.11. A router will typically have many incident links, since its job is to switch an incoming packet onto an outgoing link; in this simple example, the router has the rather simple task of transferring a packet from one (input) link to the only other attached link. In this example, the source has three packets, each consisting of L bits, to send to the destination. At the snapshot of time shown in Figure 1.11, the source has transmitted some of packet 1, and the front of packet 1 has already arrived at the router. Because the router employs store-and-forwarding, at this instant of time, the router cannot transmit the bits it has received; instead it

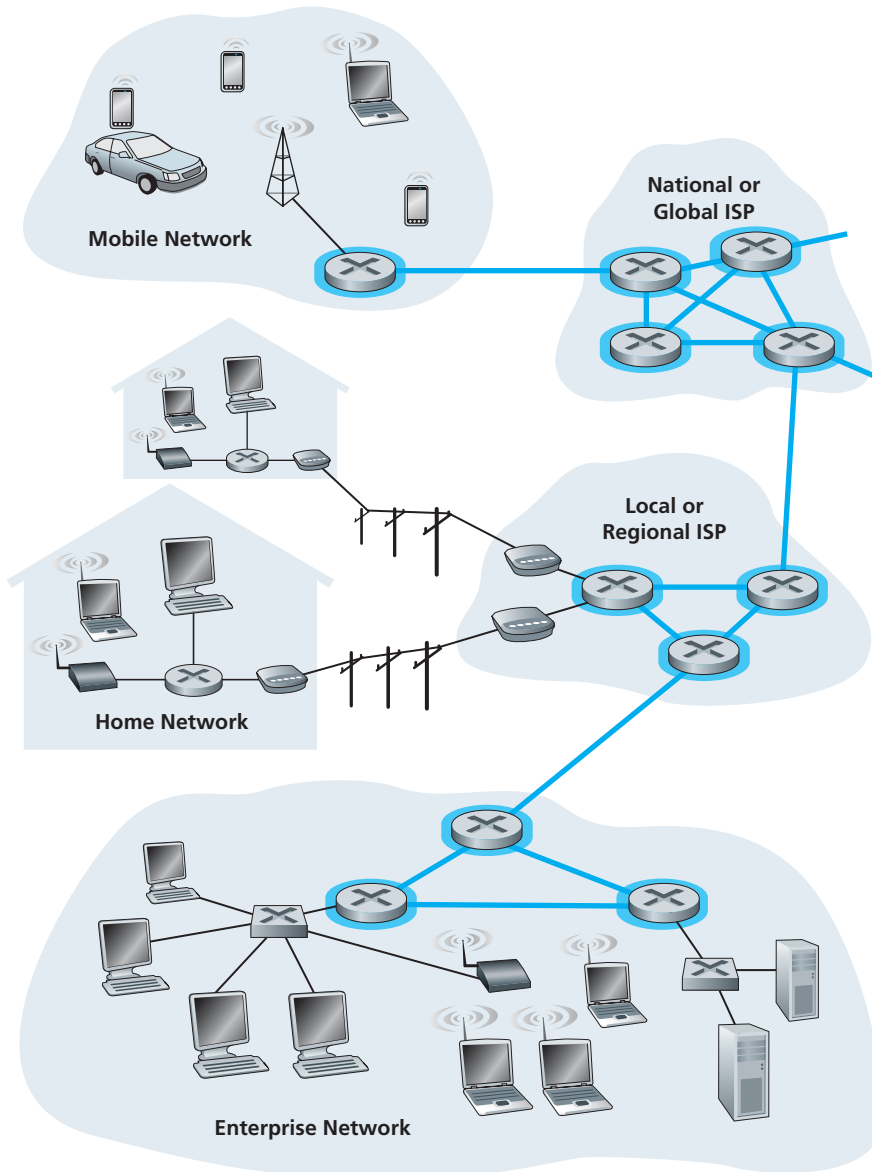


Figure 1.10 ♦ The network core

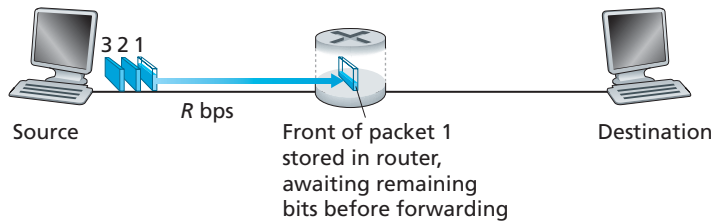


Figure 1.11 ♦ Store-and-forward packet switching

must first buffer (i.e., “store”) the packet’s bits. Only after the router has received *all* of the packet’s bits can it begin to transmit (i.e., “forward”) the packet onto the outbound link. To gain some insight into store-and-forward transmission, let’s now calculate the amount of time that elapses from when the source begins to send the packet until the destination has received the entire packet. (Here we will ignore propagation delay—the time it takes for the bits to travel across the wire at near the speed of light—which will be discussed in Section 1.4.) The source begins to transmit at time 0; at time L/R seconds, the source has transmitted the entire packet, and the entire packet has been received and stored at the router (since there is no propagation delay). At time L/R seconds, since the router has just received the entire packet, it can begin to transmit the packet onto the outbound link towards the destination; at time $2L/R$, the router has transmitted the entire packet, and the entire packet has been received by the destination. Thus, the total delay is $2L/R$. If the switch instead forwarded bits as soon as they arrive (without first receiving the entire packet), then the total delay would be L/R since bits are not held up at the router. But, as we will discuss in Section 1.4, routers need to receive, store, and process the entire packet before forwarding.

Now let’s calculate the amount of time that elapses from when the source begins to send the first packet until the destination has received all three packets. As before, at time L/R , the router begins to forward the first packet. But also at time L/R the source will begin to send the second packet, since it has just finished sending the entire first packet. Thus, at time $2L/R$, the destination has received the first packet and the router has received the second packet. Similarly, at time $3L/R$, the destination has received the first two packets and the router has received the third packet. Finally, at time $4L/R$ the destination has received all three packets!

Let’s now consider the general case of sending one packet from source to destination over a path consisting of N links each of rate R (thus, there are $N-1$ routers between source and destination). Applying the same logic as above, we see that the end-to-end delay is:

$$d_{\text{end-to-end}} = N \frac{L}{R} \quad (1.1)$$

You may now want to try to determine what the delay would be for P packets sent over a series of N links.

Queuing Delays and Packet Loss

Each packet switch has multiple links attached to it. For each attached link, the packet switch has an **output buffer** (also called an **output queue**), which stores packets that the router is about to send into that link. The output buffers play a key role in packet switching. If an arriving packet needs to be transmitted onto a link but finds the link busy with the transmission of another packet, the arriving packet must wait in the output buffer. Thus, in addition to the store-and-forward delays, packets suffer output buffer **queuing delays**. These delays are variable and depend on the level of congestion in the network. Since the amount of buffer space is finite, an arriving packet may find that the buffer is completely full with other packets waiting for transmission. In this case, **packet loss** will occur—either the arriving packet or one of the already-queued packets will be dropped.

Figure 1.12 illustrates a simple packet-switched network. As in Figure 1.11, packets are represented by three-dimensional slabs. The width of a slab represents the number of bits in the packet. In this figure, all packets have the same width and hence the same length. Suppose Hosts A and B are sending packets to Host E. Hosts A and B first send their packets along 10 Mbps Ethernet links to the first router. The router then directs these packets to the 1.5 Mbps link. If, during a short interval of time, the arrival rate of packets to the router (when converted to bits per second) exceeds 1.5 Mbps, congestion will occur at the router as packets queue in the link's output buffer before being transmitted onto the link. For example, if Host A and B each send a burst of five packets back-to-back at the same time, then most of these packets will spend some time waiting in the queue. The situation is, in fact, entirely analogous to many common-day situations—for example, when we wait in line for a bank teller or wait in front of a tollbooth. We'll examine this queuing delay in more detail in Section 1.4.

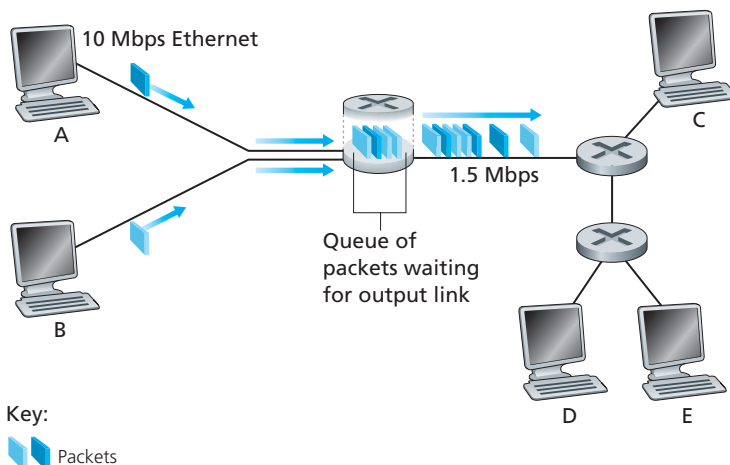


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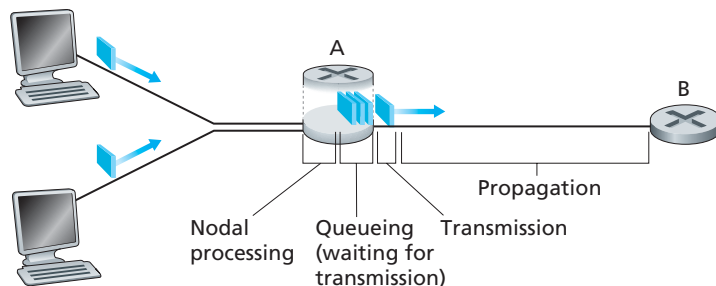


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chapter, if TCP is being used at the transport layer, then TCP will recover from this loss by having the source retransmit the data in the original datagram.

We have just learned that IP fragmentation plays an important role in gluing together the many disparate link-layer technologies. But fragmentation also has its costs. First, it complicates routers and end systems, which need to be designed to accommodate datagram fragmentation and reassembly. Second, fragmentation can be used to create lethal DoS attacks, whereby the attacker sends a series of bizarre and unexpected fragments. A classic example is the Jolt2 attack, where the attacker sends a stream of small fragments to the target host, none of which has an offset of zero. The target can collapse as it attempts to rebuild datagrams out of the degenerate packets. Another class of exploits sends overlapping IP fragments, that is, fragments whose offset values are set so that the fragments do not align properly. Vulnerable operating systems, not knowing what to do with overlapping fragments, can crash [Skoudis 2006]. As we'll see at the end of this section, a new version of the IP protocol, IPv6, does away with fragmentation altogether, thereby streamlining IP packet processing and making IP less vulnerable to attack.

At this book's Web site, we provide a Java applet that generates fragments. You provide the incoming datagram size, the MTU, and the incoming datagram identification. The applet automatically generates the fragments for you. See <http://www.awl.com/kurose-ross>.

4.4.2 IPv4 Addressing

We now turn our attention to IPv4 addressing. Although you may be thinking that addressing must be a straightforward topic, hopefully by the end of this chapter you'll be convinced that Internet addressing is not only a juicy, subtle, and interesting topic but also one that is of central importance to the Internet. Excellent treatments of IPv4 addressing are [3Com Addressing 2012] and the first chapter in [Stewart 1999].

Before discussing IP addressing, however, we'll need to say a few words about how hosts and routers are connected into the network. A host typically has only a single link into the network; when IP in the host wants to send a datagram, it does so over this link. The boundary between the host and the physical link is called an **interface**. Now consider a router and its interfaces. Because a router's job is to receive a datagram on one link and forward the datagram on some other link, a router necessarily has two or more links to which it is connected. The boundary between the router and any one of its links is also called an interface. A router thus has multiple interfaces, one for each of its links. Because every host and router is capable of sending and receiving IP datagrams, IP requires each host and router interface to have its own IP address. Thus, an IP address is technically associated with an interface, rather than with the host or router containing that interface.

Each IP address is 32 bits long (equivalently, 4 bytes), and there are thus a total of 2^{32} possible IP addresses. By approximating 2^{10} by 10^3 , it is easy to see that there

are about 4 billion possible IP addresses. These addresses are typically written in so-called **dotted-decimal notation**, in which each byte of the address is written in its decimal form and is separated by a period (dot) from other bytes in the address. For example, consider the IP address 193.32.216.9. The 193 is the decimal equivalent of the first 8 bits of the address; the 32 is the decimal equivalent of the second 8 bits of the address, and so on. Thus, the address 193.32.216.9 in binary notation is

11000001 00100000 11011000 00001001

Each interface on every host and router in the global Internet must have an IP address that is globally unique (except for interfaces behind NATs, as discussed at the end of this section). These addresses cannot be chosen in a willy-nilly manner, however. A portion of an interface's IP address will be determined by the subnet to which it is connected.

Figure 4.15 provides an example of IP addressing and interfaces. In this figure, one router (with three interfaces) is used to interconnect seven hosts. Take a close look at the IP addresses assigned to the host and router interfaces, as there are several things to notice. The three hosts in the upper-left portion of Figure 4.15, and the router interface to which they are connected, all have an IP address of the form 223.1.1.xxx. That is, they all have the same leftmost 24 bits in their IP address. The four interfaces are also interconnected to each other by a network *that contains no routers*. This network

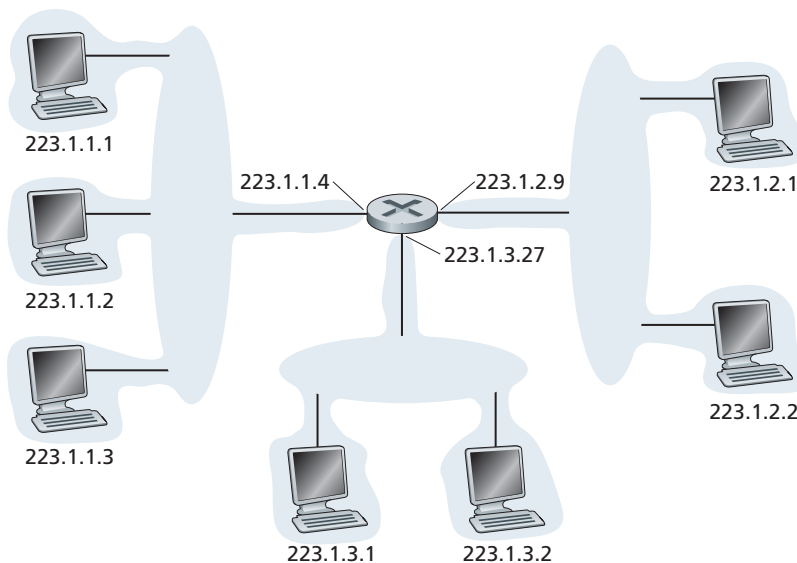


Figure 4.15 ♦ Interface addresses and subnets

additional subnets in this example as well: one subnet, 223.1.9.0/24, for the interfaces that connect routers R1 and R2; another subnet, 223.1.8.0/24, for the interfaces that connect routers R2 and R3; and a third subnet, 223.1.7.0/24, for the interfaces that connect routers R3 and R1. For a general interconnected system of routers and hosts, we can use the following recipe to define the subnets in the system:

*To determine the subnets, detach each interface from its host or router, creating islands of isolated networks, with interfaces terminating the end points of the isolated networks. Each of these isolated networks is called a **subnet**.*

If we apply this procedure to the interconnected system in Figure 4.17, we get six islands or subnets.

From the discussion above, it's clear that an organization (such as a company or academic institution) with multiple Ethernet segments and point-to-point links will have multiple subnets, with all of the devices on a given subnet having the same subnet address. In principle, the different subnets could have quite different subnet addresses. In practice, however, their subnet addresses often have much in common. To understand why, let's next turn our attention to how addressing is handled in the global Internet.

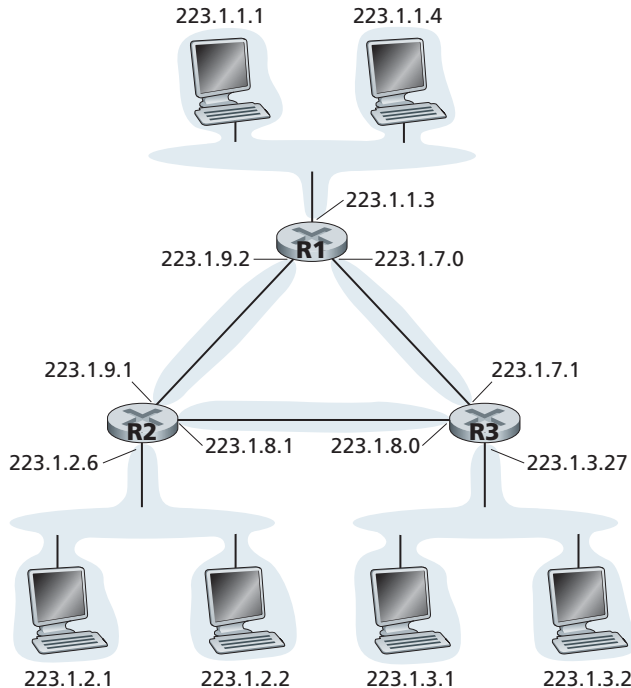


Figure 4.17 ♦ Three routers interconnecting six subnets

The Internet's address assignment strategy is known as **Classless Interdomain Routing (CIDR)**—pronounced *cider*) [RFC 4632]. CIDR generalizes the notion of subnet addressing. As with subnet addressing, the 32-bit IP address is divided into two parts and again has the dotted-decimal form $a.b.c.d/x$, where x indicates the number of bits in the first part of the address.

The x most significant bits of an address of the form $a.b.c.d/x$ constitute the network portion of the IP address, and are often referred to as the **prefix** (or *network prefix*) of the address. An organization is typically assigned a block of contiguous addresses, that is, a range of addresses with a common prefix (see the Principles in Practice sidebar). In this case, the IP addresses of devices within the organization will share the common prefix. When we cover the Internet's BGP



PRINCIPLES IN PRACTICE

This example of an ISP that connects eight organizations to the Internet nicely illustrates how carefully allocated CIDRized addresses facilitate routing. Suppose, as shown in Figure 4.18, that the ISP (which we'll call Fly-By-Night-ISP) advertises to the outside world that it should be sent any datagrams whose first 20 address bits match 200.23.16.0/20. The rest of the world need not know that within the address block 200.23.16.0/20 there are in fact eight other organizations, each with its own subnets. This ability to use a single prefix to advertise multiple networks is often referred to as **address aggregation** (also **route aggregation** or **route summarization**).

Address aggregation works extremely well when addresses are allocated in blocks to ISPs and then from ISPs to client organizations. But what happens when addresses are not allocated in such a hierarchical manner? What would happen, for example, if Fly-By-Night-ISP acquires ISPs-R-Us and then has Organization 1 connect to the Internet through its subsidiary ISPs-R-Us? As shown in Figure 4.18, the subsidiary ISPs-R-Us owns the address block 199.31.0.0/16, but Organization 1's IP addresses are unfortunately outside of this address block. What should be done here? Certainly, Organization 1 could renumber all of its routers and hosts to have addresses within the ISPs-R-Us address block. But this is a costly solution, and Organization 1 might well be reassigned to another subsidiary in the future. The solution typically adopted is for Organization 1 to keep its IP addresses in 200.23.18.0/23. In this case, as shown in Figure 4.19, Fly-By-Night-ISP continues to advertise the address block 200.23.16.0/20 and ISPs-R-Us continues to advertise 199.31.0.0/16. However, ISPs-R-Us now *also* advertises the block of addresses for Organization 1, 200.23.18.0/23. When other routers in the larger Internet see the address blocks 200.23.16.0/20 (from Fly-By-Night-ISP) and 200.23.18.0/23 (from ISPs-R-Us) and want to route to an address in the block 200.23.18.0/23, they will use longest prefix matching (see Section 4.2.2), and route toward ISPs-R-Us, as it advertises the longest (most specific) address prefix that matches the destination address.

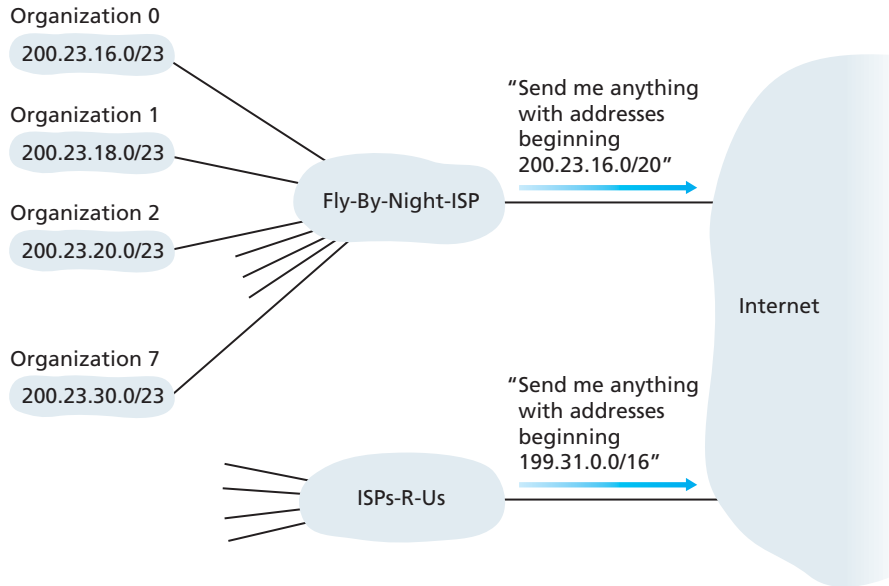


Figure 4.18 ♦ Hierarchical addressing and route aggregation

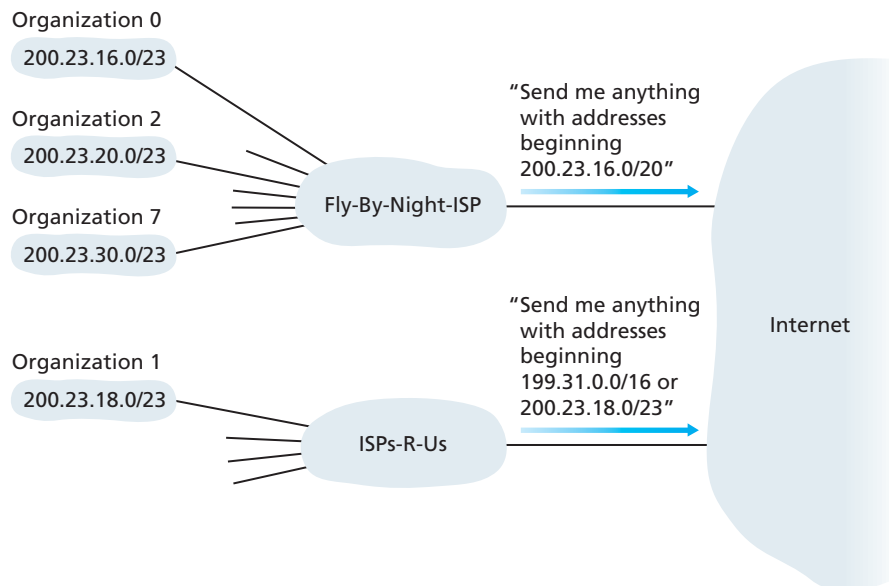


Figure 4.19 ♦ ISPs-R-Us has a more specific route to Organization 1

routing protocol in Section 4.6, we'll see that only these x leading prefix bits are considered by routers outside the organization's network. That is, when a router outside the organization forwards a datagram whose destination address is inside the organization, only the leading x bits of the address need be considered. This considerably reduces the size of the forwarding table in these routers, since a *single* entry of the form $a.b.c.d/x$ will be sufficient to forward packets to *any* destination within the organization.

The remaining $32-x$ bits of an address can be thought of as distinguishing among the devices *within* the organization, all of which have the same network prefix. These are the bits that will be considered when forwarding packets at routers *within* the organization. These lower-order bits may (or may not) have an additional subnetting structure, such as that discussed above. For example, suppose the first 21 bits of the CIDRized address $a.b.c.d/21$ specify the organization's network prefix and are common to the IP addresses of all devices in that organization. The remaining 11 bits then identify the specific hosts in the organization. The organization's internal structure might be such that these 11 rightmost bits are used for subnetting within the organization, as discussed above. For example, $a.b.c.d/24$ might refer to a specific subnet within the organization.

Before CIDR was adopted, the network portions of an IP address were constrained to be 8, 16, or 24 bits in length, an addressing scheme known as **classful addressing**, since subnets with 8-, 16-, and 24-bit subnet addresses were known as class A, B, and C networks, respectively. The requirement that the subnet portion of an IP address be exactly 1, 2, or 3 bytes long turned out to be problematic for supporting the rapidly growing number of organizations with small and medium-sized subnets. A class C (/24) subnet could accommodate only up to $2^8 - 2 = 254$ hosts (two of the $2^8 = 256$ addresses are reserved for special use)—too small for many organizations. However, a class B (/16) subnet, which supports up to 65,534 hosts, was too large. Under classful addressing, an organization with, say, 2,000 hosts was typically allocated a class B (/16) subnet address. This led to a rapid depletion of the class B address space and poor utilization of the assigned address space. For example, the organization that used a class B address for its 2,000 hosts was allocated enough of the address space for up to 65,534 interfaces—leaving more than 63,000 addresses that could not be used by other organizations.

We would be remiss if we did not mention yet another type of IP address, the IP broadcast address 255.255.255.255. When a host sends a datagram with destination address 255.255.255.255, the message is delivered to all hosts on the same subnet. Routers optionally forward the message into neighboring subnets as well (although they usually don't).

Having now studied IP addressing in detail, we need to know how hosts and subnets get their addresses in the first place. Let's begin by looking at how an organization gets a block of addresses for its devices, and then look at how a device (such as a host) is assigned an address from within the organization's block of addresses.

Obtaining a Block of Addresses

In order to obtain a block of IP addresses for use within an organization's subnet, a network administrator might first contact its ISP, which would provide addresses from a larger block of addresses that had already been allocated to the ISP. For example, the ISP may itself have been allocated the address block 200.23.16.0/20. The ISP, in turn, could divide its address block into eight equal-sized contiguous address blocks and give one of these address blocks out to each of up to eight organizations that are supported by this ISP, as shown below. (We have underlined the subnet part of these addresses for your convenience.)

ISP's block	200.23.16.0/20	<u>11001000</u> <u>00010111</u> <u>00010000</u> 00000000
Organization 0	200.23.16.0/23	<u>11001000</u> <u>00010111</u> <u>00010000</u> 00000000
Organization 1	200.23.18.0/23	<u>11001000</u> <u>00010111</u> <u>00010010</u> 00000000
Organization 2	200.23.20.0/23	<u>11001000</u> <u>00010111</u> <u>00010100</u> 00000000
...
Organization 7	200.23.30.0/23	<u>11001000</u> <u>00010111</u> <u>00011110</u> 00000000

While obtaining a set of addresses from an ISP is one way to get a block of addresses, it is not the only way. Clearly, there must also be a way for the ISP itself to get a block of addresses. Is there a global authority that has ultimate responsibility for managing the IP address space and allocating address blocks to ISPs and other organizations? Indeed there is! IP addresses are managed under the authority of the Internet Corporation for Assigned Names and Numbers (ICANN) [ICANN 2012], based on guidelines set forth in [RFC 2050]. The role of the nonprofit ICANN organization [NTIA 1998] is not only to allocate IP addresses, but also to manage the DNS root servers. It also has the very contentious job of assigning domain names and resolving domain name disputes. The ICANN allocates addresses to regional Internet registries (for example, ARIN, RIPE, APNIC, and LACNIC, which together form the Address Supporting Organization of ICANN [ASO-ICANN 2012]), and handle the allocation/management of addresses within their regions.

Obtaining a Host Address: the Dynamic Host Configuration Protocol

Once an organization has obtained a block of addresses, it can assign individual IP addresses to the host and router interfaces in its organization. A system administrator will typically manually configure the IP addresses into the router (often remotely, with a network management tool). Host addresses can also be configured manually, but more often this task is now done using the **Dynamic Host Configuration Protocol (DHCP)** [RFC 2131]. DHCP allows a host to obtain (be allocated) an IP address automatically. A network administrator can configure DHCP so that a

given host receives the same IP address each time it connects to the network, or a host may be assigned a **temporary IP address** that will be different each time the host connects to the network. In addition to host IP address assignment, DHCP also allows a host to learn additional information, such as its subnet mask, the address of its first-hop router (often called the default gateway), and the address of its local DNS server.

Because of DHCP's ability to automate the network-related aspects of connecting a host into a network, it is often referred to as a **plug-and-play protocol**. This capability makes it *very* attractive to the network administrator who would otherwise have to perform these tasks manually! DHCP is also enjoying widespread use in residential Internet access networks and in wireless LANs, where hosts join and leave the network frequently. Consider, for example, the student who carries a laptop from a dormitory room to a library to a classroom. It is likely that in each location, the student will be connecting into a new subnet and hence will need a new IP address at each location. DHCP is ideally suited to this situation, as there are many users coming and going, and addresses are needed for only a limited amount of time. DHCP is similarly useful in residential ISP access networks. Consider, for example, a residential ISP that has 2,000 customers, but no more than 400 customers are ever online at the same time. In this case, rather than needing a block of 2,048 addresses, a DHCP server that assigns addresses dynamically needs only a block of 512 addresses (for example, a block of the form a.b.c.d/23). As the hosts join and leave, the DHCP server needs to update its list of available IP addresses. Each time a host joins, the DHCP server allocates an arbitrary address from its current pool of available addresses; each time a host leaves, its address is returned to the pool.

DHCP is a client-server protocol. A client is typically a newly arriving host wanting to obtain network configuration information, including an IP address for itself. In the simplest case, each subnet (in the addressing sense of Figure 4.17) will have a DHCP server. If no server is present on the subnet, a DHCP relay agent (typically a router) that knows the address of a DHCP server for that network is needed. Figure 4.20 shows a DHCP server attached to subnet 223.1.2/24, with the router serving as the relay agent for arriving clients attached to subnets 223.1.1/24 and 223.1.3/24. In our discussion below, we'll assume that a DHCP server is available on the subnet.

For a newly arriving host, the DHCP protocol is a four-step process, as shown in Figure 4.21 for the network setting shown in Figure 4.20. In this figure, *yiaddr* (as in "your Internet address") indicates the address being allocated to the newly arriving client. The four steps are:

- *DHCP server discovery.* The first task of a newly arriving host is to find a DHCP server with which to interact. This is done using a **DHCP discover message**, which a client sends within a UDP packet to port 67. The UDP packet is encapsulated in an IP datagram. But to whom should this datagram be sent? The host doesn't even know the IP address of the network to which it is attaching, much

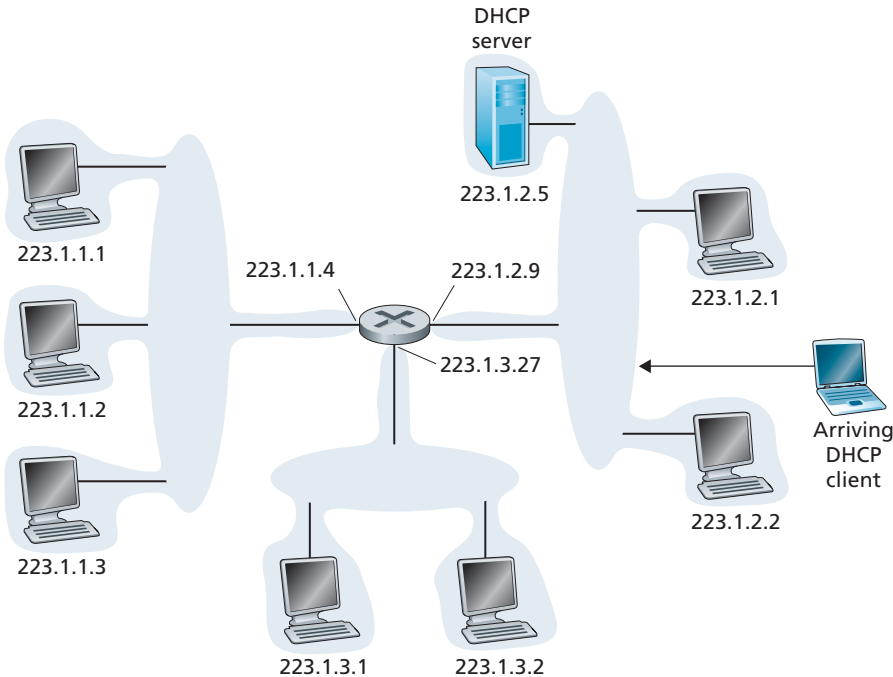


Figure 4.20 ♦ DHCP client-server scenario

less the address of a DHCP server for this network. Given this, the DHCP client creates an IP datagram containing its DHCP discover message along with the broadcast destination IP address of 255.255.255.255 and a “this host” source IP address of 0.0.0.0. The DHCP client passes the IP datagram to the link layer, which then broadcasts this frame to all nodes attached to the subnet (we will cover the details of link-layer broadcasting in Section 5.4).

- *DHCP server offer(s).* A DHCP server receiving a DHCP discover message responds to the client with a **DHCP offer message** that is broadcast to all nodes on the subnet, again using the IP broadcast address of 255.255.255.255. (You might want to think about why this server reply must also be broadcast). Since several DHCP servers can be present on the subnet, the client may find itself in the enviable position of being able to choose from among several offers. Each server offer message contains the transaction ID of the received discover message, the proposed IP address for the client, the network mask, and an **IP address lease time**—the amount of time for which the IP address will be valid. It is common for the server to set the lease time to several hours or days [Droms 2002].

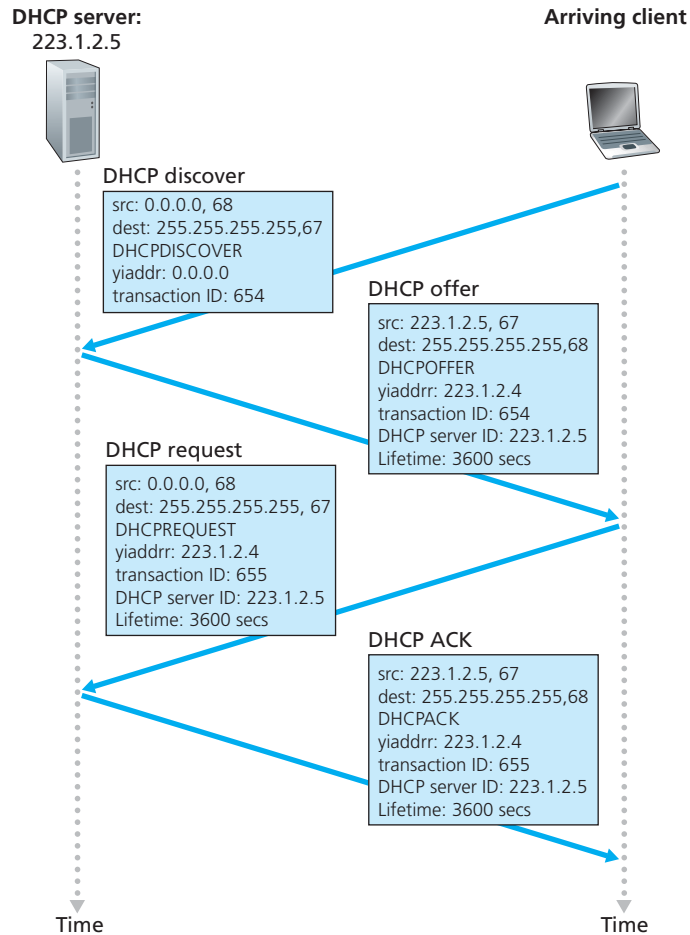


Figure 4.21 ♦ DHCP client-server interaction

- *DHCP request.* The newly arriving client will choose from among one or more server offers and respond to its selected offer with a **DHCP request message**, echoing back the configuration parameters.
- *DHCP ACK.* The server responds to the DHCP request message with a **DHCP ACK message**, confirming the requested parameters.

Once the client receives the DHCP ACK, the interaction is complete and the client can use the DHCP-allocated IP address for the lease duration. Since a client

may want to use its address beyond the lease's expiration, DHCP also provides a mechanism that allows a client to renew its lease on an IP address.

The value of DHCP's plug-and-play capability is clear, considering the fact that the alternative is to manually configure a host's IP address. Consider the student who moves from classroom to library to dorm room with a laptop, joins a new subnet, and thus obtains a new IP address at each location. It is unimaginable that a system administrator would have to reconfigure laptops at each location, and few students (except those taking a computer networking class!) would have the expertise to configure their laptops manually. From a mobility aspect, however, DHCP does have shortcomings. Since a new IP address is obtained from DHCP each time a node connects to a new subnet, a TCP connection to a remote application cannot be maintained as a mobile node moves between subnets. In Chapter 6, we will examine mobile IP—a recent extension to the IP infrastructure that allows a mobile node to use a single permanent address as it moves between subnets. Additional details about DHCP can be found in [Droms 2002] and [dhc 2012]. An open source reference implementation of DHCP is available from the Internet Systems Consortium [ISC 2012].

Network Address Translation (NAT)

Given our discussion about Internet addresses and the IPv4 datagram format, we're now well aware that every IP-capable device needs an IP address. With the proliferation of small office, home office (SOHO) subnets, this would seem to imply that whenever a SOHO wants to install a LAN to connect multiple machines, a range of addresses would need to be allocated by the ISP to cover all of the SOHO's machines. If the subnet grew bigger (for example, the kids at home have not only their own computers, but have smartphones and networked Game Boys as well), a larger block of addresses would have to be allocated. But what if the ISP had already allocated the contiguous portions of the SOHO network's current address range? And what typical homeowner wants (or should need) to know how to manage IP addresses in the first place? Fortunately, there is a simpler approach to address allocation that has found increasingly widespread use in such scenarios: **network address translation (NAT)** [RFC 2663; RFC 3022; Zhang 2007].

Figure 4.22 shows the operation of a NAT-enabled router. The NAT-enabled router, residing in the home, has an interface that is part of the home network on the right of Figure 4.22. Addressing within the home network is exactly as we have seen above—all four interfaces in the home network have the same subnet address of 10.0.0/24. The address space 10.0.0.0/8 is one of three portions of the IP address space that is reserved in [RFC 1918] for a private network or a **realm** with private addresses, such as the home network in Figure 4.22. A *realm with private addresses* refers to a network whose addresses only have meaning to devices within that network. To see why this is important, consider the fact that there are hundreds of

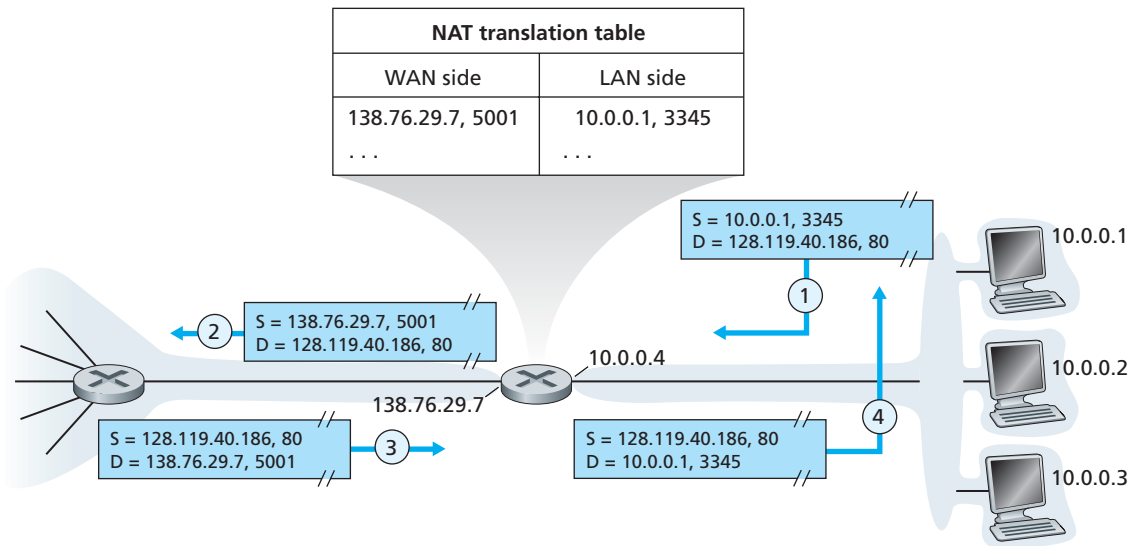


Figure 4.22 ♦ Network address translation

thousands of home networks, many using the same address space, 10.0.0.0/24. Devices within a given home network can send packets to each other using 10.0.0.0/24 addressing. However, packets forwarded *beyond* the home network into the larger global Internet clearly cannot use these addresses (as either a source or a destination address) because there are hundreds of thousands of networks using this block of addresses. That is, the 10.0.0.0/24 addresses can only have meaning within the given home network. But if private addresses only have meaning within a given network, how is addressing handled when packets are sent to or received from the global Internet, where addresses are necessarily unique? The answer lies in understanding NAT.

The NAT-enabled router does not *look* like a router to the outside world. Instead the NAT router behaves to the outside world as a *single* device with a *single* IP address. In Figure 4.22, all traffic leaving the home router for the larger Internet has a source IP address of 138.76.29.7, and all traffic entering the home router must have a destination address of 138.76.29.7. In essence, the NAT-enabled router is hiding the details of the home network from the outside world. (As an aside, you might wonder where the home network computers get their addresses and where the router gets its single IP address. Often, the answer is the same—DHCP! The router gets its address from the ISP’s DHCP server, and the router runs a DHCP server to provide addresses to computers within the NAT-DHCP-router-controlled home network’s address space.)

If all datagrams arriving at the NAT router from the WAN have the same destination IP address (specifically, that of the WAN-side interface of the NAT router), then how does the router know the internal host to which it should forward a given datagram? The trick is to use a **NAT translation table** at the NAT router, and to include port numbers as well as IP addresses in the table entries.

Consider the example in Figure 4.22. Suppose a user sitting in a home network behind host 10.0.0.1 requests a Web page on some Web server (port 80) with IP address 128.119.40.186. The host 10.0.0.1 assigns the (arbitrary) source port number 3345 and sends the datagram into the LAN. The NAT router receives the datagram, generates a new source port number 5001 for the datagram, replaces the source IP address with its WAN-side IP address 138.76.29.7, and replaces the original source port number 3345 with the new source port number 5001. When generating a new source port number, the NAT router can select any source port number that is not currently in the NAT translation table. (Note that because a port number field is 16 bits long, the NAT protocol can support over 60,000 simultaneous connections with a single WAN-side IP address for the router!) NAT in the router also adds an entry to its NAT translation table. The Web server, blissfully unaware that the arriving datagram containing the HTTP request has been manipulated by the NAT router, responds with a datagram whose destination address is the IP address of the NAT router, and whose destination port number is 5001. When this datagram arrives at the NAT router, the router indexes the NAT translation table using the destination IP address and destination port number to obtain the appropriate IP address (10.0.0.1) and destination port number (3345) for the browser in the home network. The router then rewrites the datagram's destination address and destination port number, and forwards the datagram into the home network.

NAT has enjoyed widespread deployment in recent years. But we should mention that many purists in the IETF community loudly object to NAT. First, they argue, port numbers are meant to be used for addressing processes, not for addressing hosts. (This violation can indeed cause problems for servers running on the home network, since, as we have seen in Chapter 2, server processes wait for incoming requests at well-known port numbers.) Second, they argue, routers are supposed to process packets only up to layer 3. Third, they argue, the NAT protocol violates the so-called end-to-end argument; that is, hosts should be talking directly with each other, without interfering nodes modifying IP addresses and port numbers. And fourth, they argue, we should use IPv6 (see Section 4.4.4) to solve the shortage of IP addresses, rather than recklessly patching up the problem with a stopgap solution like NAT. But like it or not, NAT has become an important component of the Internet.

Yet another major problem with NAT is that it interferes with P2P applications, including P2P file-sharing applications and P2P Voice-over-IP applications. Recall from Chapter 2 that in a P2P application, any participating Peer A should be able to initiate a TCP connection to any other participating Peer B. The essence of the problem is that if Peer B is behind a NAT, it cannot act as a server and accept TCP

connections. As we'll see in the homework problems, this NAT problem can be circumvented if Peer A is not behind a NAT. In this case, Peer A can first contact Peer B through an intermediate Peer C, which is not behind a NAT and to which B has established an ongoing TCP connection. Peer A can then ask Peer B, via Peer C, to initiate a TCP connection directly back to Peer A. Once the direct P2P TCP connection is established between Peers A and B, the two peers can exchange messages or files. This hack, called **connection reversal**, is actually used by many P2P applications for **NAT traversal**. If both Peer A and Peer B are behind their own NATs, the situation is a bit trickier but can be handled using application relays, as we saw with Skype relays in Chapter 2.

UPnP

NAT traversal is increasingly provided by Universal Plug and Play (UPnP), which is a protocol that allows a host to discover and configure a nearby NAT [UPnP Forum 2012]. UPnP requires that both the host and the NAT be UPnP compatible. With UPnP, an application running in a host can request a NAT mapping between its (*private IP address, private port number*) and the (*public IP address, public port number*) for some requested public port number. If the NAT accepts the request and creates the mapping, then nodes from the outside can initiate TCP connections to (*public IP address, public port number*). Furthermore, UPnP lets the application know the value of (*public IP address, public port number*), so that the application can advertise it to the outside world.

As an example, suppose your host, behind a UPnP-enabled NAT, has private address 10.0.0.1 and is running BitTorrent on port 3345. Also suppose that the public IP address of the NAT is 138.76.29.7. Your BitTorrent application naturally wants to be able to accept connections from other hosts, so that it can trade chunks with them. To this end, the BitTorrent application in your host asks the NAT to create a “hole” that maps (10.0.0.1, 3345) to (138.76.29.7, 5001). (The public port number 5001 is chosen by the application.) The BitTorrent application in your host could also advertise to its tracker that it is available at (138.76.29.7, 5001). In this manner, an external host running BitTorrent can contact the tracker and learn that your BitTorrent application is running at (138.76.29.7, 5001). The external host can send a TCP SYN packet to (138.76.29.7, 5001). When the NAT receives the SYN packet, it will change the destination IP address and port number in the packet to (10.0.0.1, 3345) and forward the packet through the NAT.

In summary, UPnP allows external hosts to initiate communication sessions to NATed hosts, using either TCP or UDP. NATs have long been a nemesis for P2P applications; UPnP, providing an effective and robust NAT traversal solution, may be their savior. Our discussion of NAT and UPnP here has been necessarily brief. For more detailed discussions of NAT see [Huston 2004, Cisco NAT 2012].

4.4.3 Internet Control Message Protocol (ICMP)

Recall that the network layer of the Internet has three main components: the IP protocol, discussed in the previous section; the Internet routing protocols (including RIP, OSPF, and BGP), which are covered in Section 4.6; and ICMP, which is the subject of this section.

ICMP, specified in [RFC 792], is used by hosts and routers to communicate network-layer information to each other. The most typical use of ICMP is for error reporting. For example, when running a Telnet, FTP, or HTTP session, you may have encountered an error message such as “Destination network unreachable.” This message had its origins in ICMP. At some point, an IP router was unable to find a path to the host specified in your Telnet, FTP, or HTTP application. That router created and sent a type-3 ICMP message to your host indicating the error.

ICMP is often considered part of IP but architecturally it lies just above IP, as ICMP messages are carried inside IP datagrams. That is, ICMP messages are carried as IP payload, just as TCP or UDP segments are carried as IP payload. Similarly, when a host receives an IP datagram with ICMP specified as the upper-layer protocol, it demultiplexes the datagram’s contents to ICMP, just as it would demultiplex a datagram’s content to TCP or UDP.

ICMP messages have a type and a code field, and contain the header and the first 8 bytes of the IP datagram that caused the ICMP message to be generated in the first place (so that the sender can determine the datagram that caused the error). Selected ICMP message types are shown in Figure 4.23. Note that ICMP messages are used not only for signaling error conditions.

The well-known ping program sends an ICMP type 8 code 0 message to the specified host. The destination host, seeing the echo request, sends back a type 0 code 0 ICMP echo reply. Most TCP/IP implementations support the ping server directly in the operating system; that is, the server is not a process. Chapter 11 of [Stevens 1990] provides the source code for the ping client program. Note that the client program needs to be able to instruct the operating system to generate an ICMP message of type 8 code 0.

Another interesting ICMP message is the source quench message. This message is seldom used in practice. Its original purpose was to perform congestion control—to allow a congested router to send an ICMP source quench message to a host to force that host to reduce its transmission rate. We have seen in Chapter 3 that TCP has its own congestion-control mechanism that operates at the transport layer, without the use of network-layer feedback such as the ICMP source quench message.

In Chapter 1 we introduced the Traceroute program, which allows us to trace a route from a host to any other host in the world. Interestingly, Traceroute is implemented with ICMP messages. To determine the names and addresses of the routers between source and destination, Traceroute in the source sends a series of ordinary IP datagrams to the destination. Each of these datagrams carries a UDP segment with an unlikely UDP port number. The first of these datagrams has a TTL of 1, the

ICMP Type	Code	Description
0	0	echo reply (to ping)
3	0	destination network unreachable
3	1	destination host unreachable
3	2	destination protocol unreachable
3	3	destination port unreachable
3	6	destination network unknown
3	7	destination host unknown
4	0	source quench (congestion control)
8	0	echo request
9	0	router advertisement
10	0	router discovery
11	0	TTL expired
12	0	IP header bad

Figure 4.23 ♦ ICMP message types

second of 2, the third of 3, and so on. The source also starts timers for each of the datagrams. When the n th datagram arrives at the n th router, the n th router observes that the TTL of the datagram has just expired. According to the rules of the IP protocol, the router discards the datagram and sends an ICMP warning message to the source (type 11 code 0). This warning message includes the name of the router and its IP address. When this ICMP message arrives back at the source, the source obtains the round-trip time from the timer and the name and IP address of the n th router from the ICMP message.

How does a Traceroute source know when to stop sending UDP segments? Recall that the source increments the TTL field for each datagram it sends. Thus, one of the datagrams will eventually make it all the way to the destination host. Because this datagram contains a UDP segment with an unlikely port number, the destination host sends a port unreachable ICMP message (type 3 code 3) back to the source. When the source host receives this particular ICMP message, it knows it does not need to send additional probe packets. (The standard Traceroute program actually sends sets of three packets with the same TTL; thus the Traceroute output provides three results for each TTL.)



FOCUS ON SECURITY

INSPECTING DATAGRAMS: FIREWALLS AND INTRUSION DETECTION SYSTEMS

Suppose you are assigned the task of administering a home, departmental, university, or corporate network. Attackers, knowing the IP address range of your network, can easily send IP datagrams to addresses in your range. These datagrams can do all kinds of devious things, including mapping your network with ping sweeps and port scans, crashing vulnerable hosts with malformed packets, flooding servers with a deluge of ICMP packets, and infecting hosts by including malware in the packets. As the network administrator, what are you going to do about all those bad guys out there, each capable of sending malicious packets into your network? Two popular defense mechanisms to malicious packet attacks are firewalls and intrusion detection systems (IDSs).

As a network administrator, you may first try installing a firewall between your network and the Internet. (Most access routers today have firewall capability.) Firewalls inspect the datagram and segment header fields, denying suspicious datagrams entry into the internal network. For example, a firewall may be configured to block all ICMP echo request packets, thereby preventing an attacker from doing a traditional ping sweep across your IP address range. Firewalls can also block packets based on source and destination IP addresses and port numbers. Additionally, firewalls can be configured to track TCP connections, granting entry only to datagrams that belong to approved connections.

Additional protection can be provided with an IDS. An IDS, typically situated at the network boundary, performs “deep packet inspection,” examining not only header fields but also the payloads in the datagram (including application-layer data). An IDS has a database of packet signatures that are known to be part of attacks. This database is automatically updated as new attacks are discovered. As packets pass through the IDS, the IDS attempts to match header fields and payloads to the signatures in its signature database. If such a match is found, an alert is created. An intrusion prevention system (IPS) is similar to an IDS, except that it actually blocks packets in addition to creating alerts. In Chapter 8, we’ll explore firewalls and IDSs in more detail.

Can firewalls and IDSs fully shield your network from all attacks? The answer is clearly no, as attackers continually find new attacks for which signatures are not yet available. But firewalls and traditional signature-based IDSs are useful in protecting your network from known attacks.

In this manner, the source host learns the number and the identities of routers that lie between it and the destination host and the round-trip time between the two hosts. Note that the Traceroute client program must be able to instruct the operating system to generate UDP datagrams with specific TTL values and must also be able to be notified by its operating system when ICMP messages arrive. Now that you understand how Traceroute works, you may want to go back and play with it some more.

4.4.4 IPv6

In the early 1990s, the Internet Engineering Task Force began an effort to develop a successor to the IPv4 protocol. A prime motivation for this effort was the realization that the 32-bit IP address space was beginning to be used up, with new subnets and IP nodes being attached to the Internet (and being allocated unique IP addresses) at a breathtaking rate. To respond to this need for a large IP address space, a new IP protocol, IPv6, was developed. The designers of IPv6 also took this opportunity to tweak and augment other aspects of IPv4, based on the accumulated operational experience with IPv4.

The point in time when IPv4 addresses would be completely allocated (and hence no new networks could attach to the Internet) was the subject of considerable debate. The estimates of the two leaders of the IETF's Address Lifetime Expectations working group were that addresses would become exhausted in 2008 and 2018, respectively [Solensky 1996]. In February 2011, IANA allocated out the last remaining pool of unassigned IPv4 addresses to a regional registry. While these registries still have available IPv4 addresses within their pool, once these addresses are exhausted, there are no more available address blocks that can be allocated from a central pool [Huston 2011a]. Although the mid-1990s estimates of IPv4 address depletion suggested that a considerable amount of time might be left until the IPv4 address space was exhausted, it was realized that considerable time would be needed to deploy a new technology on such an extensive scale, and so the Next Generation IP (IPng) effort [Bradner 1996; RFC 1752] was begun. The result of this effort was the specification of IP version 6 (IPv6) [RFC 2460] which we'll discuss below. (An often-asked question is what happened to IPv5? It was initially envisioned that the ST-2 protocol would become IPv5, but ST-2 was later dropped.) Excellent sources of information about IPv6 are [Huitema 1998, IPv6 2012].

IPv6 Datagram Format

The format of the IPv6 datagram is shown in Figure 4.24. The most important changes introduced in IPv6 are evident in the datagram format:

- *Expanded addressing capabilities.* IPv6 increases the size of the IP address from 32 to 128 bits. This ensures that the world won't run out of IP addresses. Now, every grain of sand on the planet can be IP-addressable. In addition to unicast and multicast addresses, IPv6 has introduced a new type of address, called an **anycast address**, which allows a datagram to be delivered to any one of a group of hosts. (This feature could be used, for example, to send an HTTP GET to the nearest of a number of mirror sites that contain a given document.)
- *A streamlined 40-byte header.* As discussed below, a number of IPv4 fields have been dropped or made optional. The resulting 40-byte fixed-length header allows



Application Layer

Network applications are the *raison d'être* of a computer network—if we couldn't conceive of any useful applications, there wouldn't be any need for networking protocols that support these applications. Since the Internet's inception, numerous useful and entertaining applications have indeed been created. These applications have been the driving force behind the Internet's success, motivating people in homes, schools, governments, and businesses to make the Internet an integral part of their daily activities.

Internet applications include the classic text-based applications that became popular in the 1970s and 1980s: text email, remote access to computers, file transfers, and newsgroups. They include *the* killer application of the mid-1990s, the World Wide Web, encompassing Web surfing, search, and electronic commerce. They include instant messaging and P2P file sharing, the two killer applications introduced at the end of the millennium. Since 2000, we have seen an explosion of popular voice and video applications, including: voice-over-IP (VoIP) and video conferencing over IP such as Skype; user-generated video distribution such as YouTube; and movies on demand such as Netflix. During this same period we have also seen the emergence of highly engaging multi-player online games, including Second Life and World of Warcraft. And most recently, we have seen the emergence of a new generation of social networking applications, such as Facebook and Twitter, which have created engaging human networks on top of the Internet's network of routers and communication links. Clearly, there has been no slowing down of new

and exciting Internet applications. Perhaps some of the readers of this text will create the next generation of killer Internet applications!

In this chapter we study the conceptual and implementation aspects of network applications. We begin by defining key application-layer concepts, including network services required by applications, clients and servers, processes, and transport-layer interfaces. We examine several network applications in detail, including the Web, e-mail, DNS, and peer-to-peer (P2P) file distribution (Chapter 8 focuses on multimedia applications, including streaming video and VoIP). We then cover network application development, over both TCP and UDP. In particular, we study the socket API and walk through some simple client-server applications in Python. We also provide several fun and interesting socket programming assignments at the end of the chapter.

The application layer is a particularly good place to start our study of protocols. It's familiar ground. We're acquainted with many of the applications that rely on the protocols we'll study. It will give us a good feel for what protocols are all about and will introduce us to many of the same issues that we'll see again when we study transport, network, and link layer protocols.

2.1 Principles of Network Applications

Suppose you have an idea for a new network application. Perhaps this application will be a great service to humanity, or will please your professor, or will bring you great wealth, or will simply be fun to develop. Whatever the motivation may be, let's now examine how you transform the idea into a real-world network application.

At the core of network application development is writing programs that run on different end systems and communicate with each other over the network. For example, in the Web application there are two distinct programs that communicate with each other: the browser program running in the user's host (desktop, laptop, tablet, smartphone, and so on); and the Web server program running in the Web server host. As another example, in a P2P file-sharing system there is a program in each host that participates in the file-sharing community. In this case, the programs in the various hosts may be similar or identical.

Thus, when developing your new application, you need to write software that will run on multiple end systems. This software could be written, for example, in C, Java, or Python. Importantly, you do not need to write software that runs on network-core devices, such as routers or link-layer switches. Even if you wanted to write application software for these network-core devices, you wouldn't be able to do so. As we learned in Chapter 1, and as shown earlier in Figure 1.24, network-core devices do not function at the application layer but instead function at lower layers—specifically at the network layer and below. This basic design—namely, confining application software to the end systems—as shown in Figure 2.1, has facilitated the rapid development and deployment of a vast array of network applications.

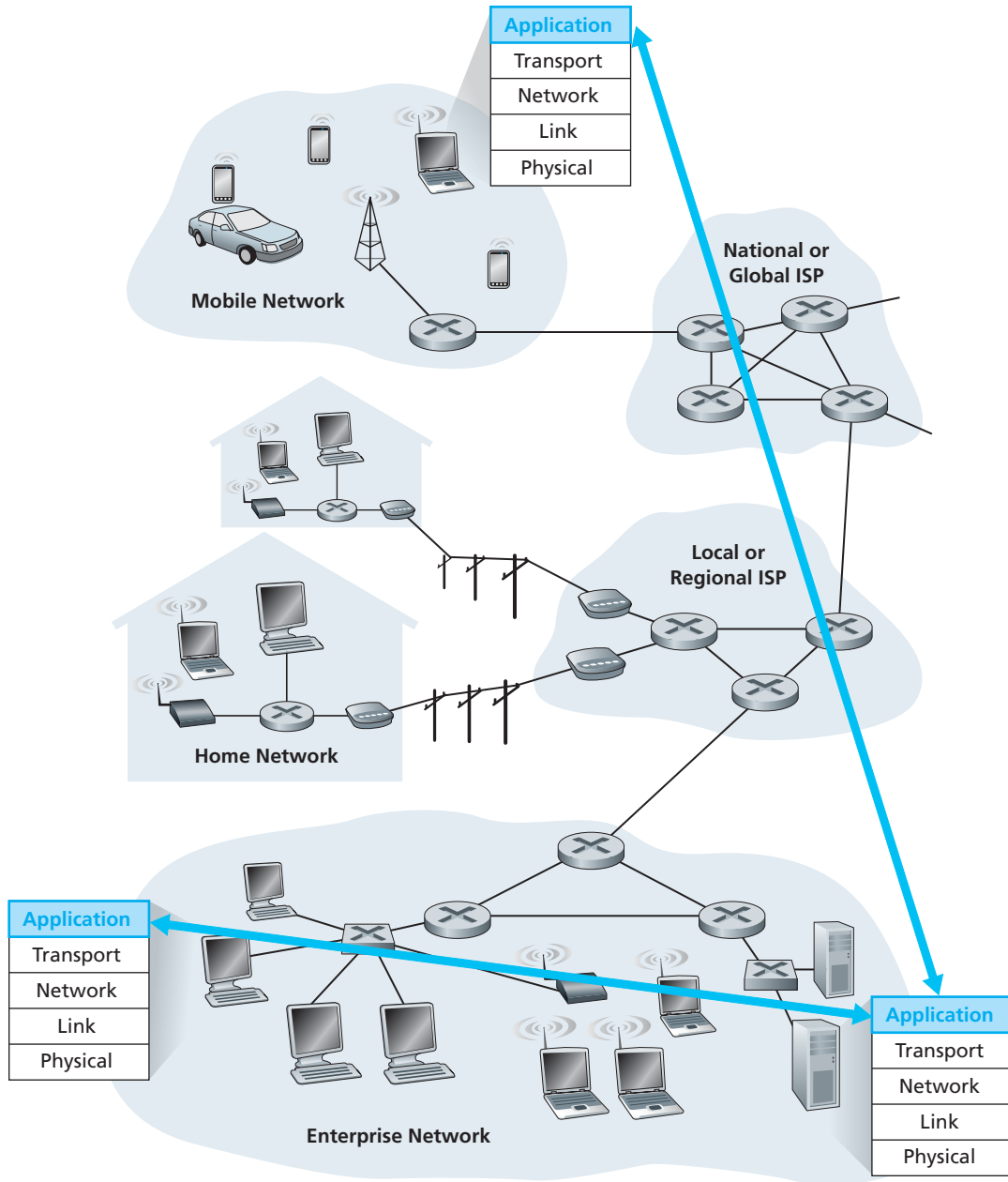


Figure 2.1 ♦ Communication for a network application takes place between end systems at the application layer

2.1.1 Network Application Architectures

Before diving into software coding, you should have a broad architectural plan for your application. Keep in mind that an application's architecture is distinctly different from the network architecture (e.g., the five-layer Internet architecture discussed in Chapter 1). From the application developer's perspective, the network architecture is fixed and provides a specific set of services to applications. The **application architecture**, on the other hand, is designed by the application developer and dictates how the application is structured over the various end systems. In choosing the application architecture, an application developer will likely draw on one of the two predominant architectural paradigms used in modern network applications: the client-server architecture or the peer-to-peer (P2P) architecture

In a **client-server architecture**, there is an always-on host, called the *server*, which services requests from many other hosts, called *clients*. A classic example is the Web application for which an always-on Web server services requests from browsers running on client hosts. When a Web server receives a request for an object from a client host, it responds by sending the requested object to the client host. Note that with the client-server architecture, clients do not directly communicate with each other; for example, in the Web application, two browsers do not directly communicate. Another characteristic of the client-server architecture is that the server has a fixed, well-known address, called an IP address (which we'll discuss soon). Because the server has a fixed, well-known address, and because the server is always on, a client can always contact the server by sending a packet to the server's IP address. Some of the better-known applications with a client-server architecture include the Web, FTP, Telnet, and e-mail. The client-server architecture is shown in Figure 2.2(a).

Often in a client-server application, a single-server host is incapable of keeping up with all the requests from clients. For example, a popular social-networking site can quickly become overwhelmed if it has only one server handling all of its requests. For this reason, a **data center**, housing a large number of hosts, is often used to create a powerful virtual server. The most popular Internet services—such as search engines (e.g., Google and Bing), Internet commerce (e.g., Amazon and e-Bay), Web-based email (e.g., Gmail and Yahoo Mail), social networking (e.g., Facebook and Twitter)—employ one or more data centers. As discussed in Section 1.3.3, Google has 30 to 50 data centers distributed around the world, which collectively handle search, YouTube, Gmail, and other services. A data center can have hundreds of thousands of servers, which must be powered and maintained. Additionally, the service providers must pay recurring interconnection and bandwidth costs for sending data from their data centers.

In a **P2P architecture**, there is minimal (or no) reliance on dedicated servers in data centers. Instead the application exploits direct communication between pairs of intermittently connected hosts, called *peers*. The peers are not owned by the service provider, but are instead desktops and laptops controlled by users, with most of the peers residing in homes, universities, and offices. Because the peers communicate without passing through a dedicated server, the architecture is called peer-to-peer. Many of today's most popular and traffic-intensive applications are based on P2P architectures. These applications include file sharing (e.g., BitTorrent), peer-assisted

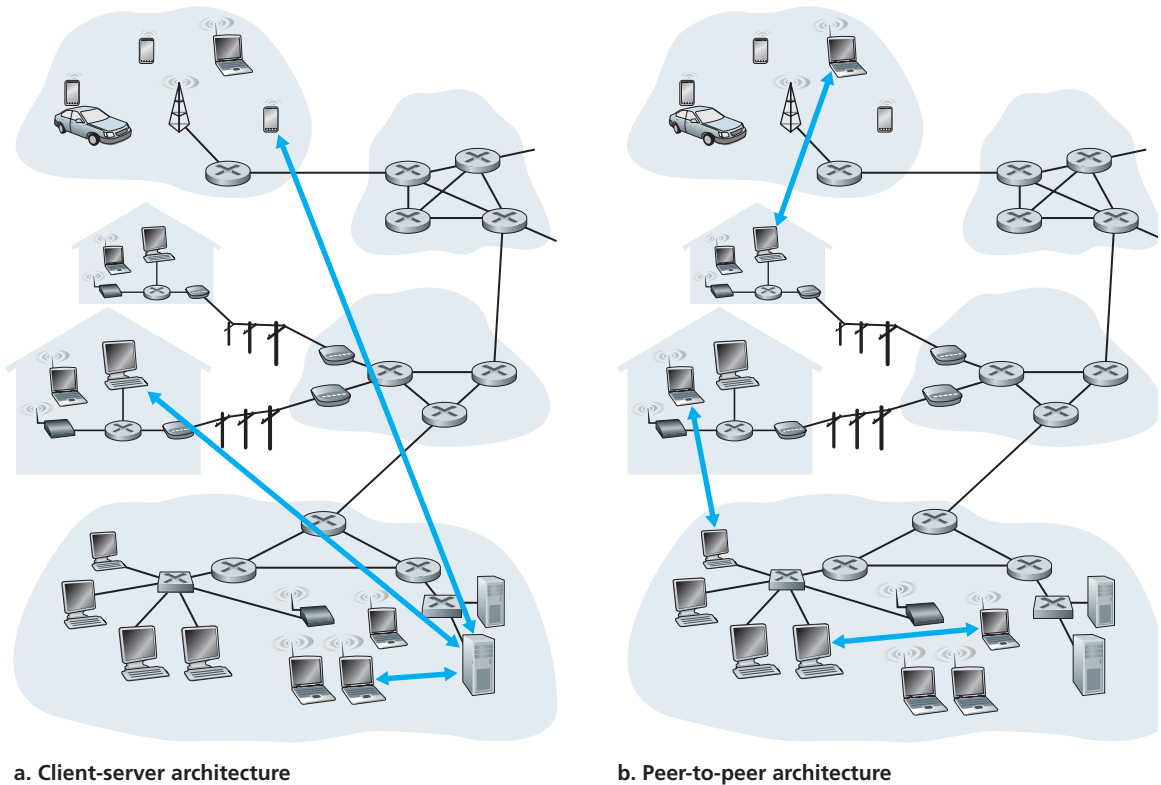


Figure 2.2 ♦ (a) Client-server architecture; (b) P2P architecture

download acceleration (e.g., Xunlei), Internet Telephony (e.g., Skype), and IPTV (e.g., Kankan and PPstream). The P2P architecture is illustrated in Figure 2.2(b). We mention that some applications have hybrid architectures, combining both client-server and P2P elements. For example, for many instant messaging applications, servers are used to track the IP addresses of users, but user-to-user messages are sent directly between user hosts (without passing through intermediate servers).

One of the most compelling features of P2P architectures is their **self-scalability**. For example, in a P2P file-sharing application, although each peer generates workload by requesting files, each peer also adds service capacity to the system by distributing files to other peers. P2P architectures are also cost effective, since they normally don't require significant server infrastructure and server bandwidth (in contrast with clients-server designs with datacenters). However, future P2P applications face three major challenges:

1. *ISP Friendly*. Most residential ISPs (including DSL and cable ISPs) have been dimensioned for “asymmetrical” bandwidth usage, that is, for much more

downstream than upstream traffic. But P2P video streaming and file distribution applications shift upstream traffic from servers to residential ISPs, thereby putting significant stress on the ISPs. Future P2P applications need to be designed so that they are friendly to ISPs [Xie 2008].

2. *Security*. Because of their highly distributed and open nature, P2P applications can be a challenge to secure [Doucer 2002; Yu 2006; Liang 2006; Naoumov 2006; Dhungel 2008; LeBlond 2011].
3. *Incentives*. The success of future P2P applications also depends on convincing users to volunteer bandwidth, storage, and computation resources to the applications, which is the challenge of incentive design [Feldman 2005; Piatek 2008; Aperjis 2008; Liu 2010].

2.1.2 Processes Communicating

Before building your network application, you also need a basic understanding of how the programs, running in multiple end systems, communicate with each other. In the jargon of operating systems, it is not actually programs but **processes** that communicate. A process can be thought of as a program that is running within an end system. When processes are running on the same end system, they can communicate with each other with interprocess communication, using rules that are governed by the end system's operating system. But in this book we are not particularly interested in how processes in the same host communicate, but instead in how processes running on *different* hosts (with potentially different operating systems) communicate.

Processes on two different end systems communicate with each other by exchanging **messages** across the computer network. A sending process creates and sends messages into the network; a receiving process receives these messages and possibly responds by sending messages back. Figure 2.1 illustrates that processes communicating with each other reside in the application layer of the five-layer protocol stack.

Client and Server Processes

A network application consists of pairs of processes that send messages to each other over a network. For example, in the Web application a client browser process exchanges messages with a Web server process. In a P2P file-sharing system, a file is transferred from a process in one peer to a process in another peer. For each pair of communicating processes, we typically label one of the two processes as the **client** and the other process as the **server**. With the Web, a browser is a client process and a Web server is a server process. With P2P file sharing, the peer that is downloading the file is labeled as the client, and the peer that is uploading the file is labeled as the server.

You may have observed that in some applications, such as in P2P file sharing, a process can be both a client and a server. Indeed, a process in a P2P file-sharing system can both upload and download files. Nevertheless, in the context of any given

communication session between a pair of processes, we can still label one process as the client and the other process as the server. We define the client and server processes as follows:

*In the context of a communication session between a pair of processes, the process that initiates the communication (that is, initially contacts the other process at the beginning of the session) is labeled as the **client**. The process that waits to be contacted to begin the session is the **server**.*

In the Web, a browser process initializes contact with a Web server process; hence the browser process is the client and the Web server process is the server. In P2P file sharing, when Peer A asks Peer B to send a specific file, Peer A is the client and Peer B is the server in the context of this specific communication session. When there's no confusion, we'll sometimes also use the terminology "client side and server side of an application." At the end of this chapter, we'll step through simple code for both the client and server sides of network applications.

The Interface Between the Process and the Computer Network

As noted above, most applications consist of pairs of communicating processes, with the two processes in each pair sending messages to each other. Any message sent from one process to another must go through the underlying network. A process sends messages into, and receives messages from, the network through a software interface called a **socket**. Let's consider an analogy to help us understand processes and sockets. A process is analogous to a house and its socket is analogous to its door. When a process wants to send a message to another process on another host, it shoves the message out its door (socket). This sending process assumes that there is a transportation infrastructure on the other side of its door that will transport the message to the door of the destination process. Once the message arrives at the destination host, the message passes through the receiving process's door (socket), and the receiving process then acts on the message.

Figure 2.3 illustrates socket communication between two processes that communicate over the Internet. (Figure 2.3 assumes that the underlying transport protocol used by the processes is the Internet's TCP protocol.) As shown in this figure, a socket is the interface between the application layer and the transport layer within a host. It is also referred to as the **Application Programming Interface (API)** between the application and the network, since the socket is the programming interface with which network applications are built. The application developer has control of everything on the application-layer side of the socket but has little control of the transport-layer side of the socket. The only control that the application developer has on the transport-layer side is (1) the choice of transport protocol and (2) perhaps the ability to fix a few transport-layer parameters such as maximum buffer and maximum segment sizes (to be covered in Chapter 3). Once the application developer chooses a transport protocol (if a choice is available),

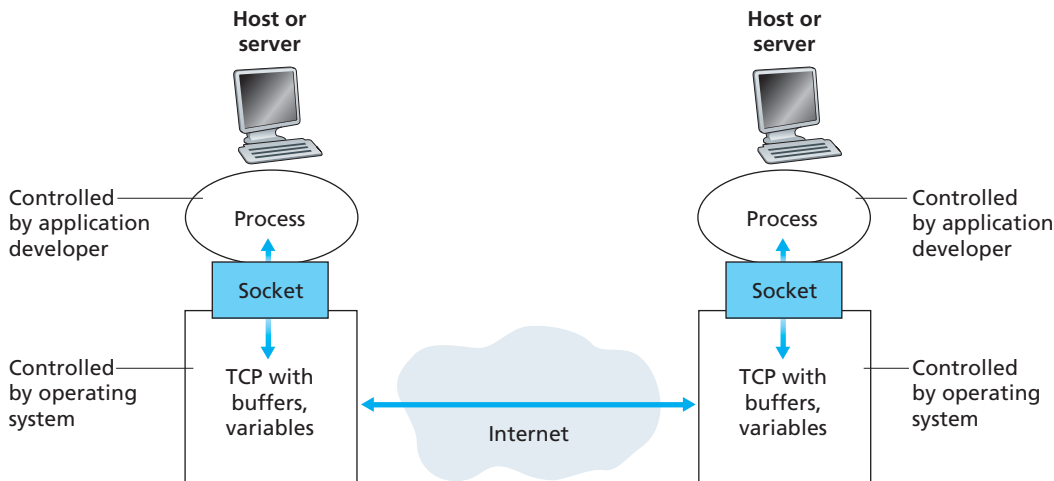


Figure 2.3 ♦ Application processes, sockets, and underlying transport protocol

the application is built using the transport-layer services provided by that protocol. We'll explore sockets in some detail in Section 2.7.

Addressing Processes

In order to send postal mail to a particular destination, the destination needs to have an address. Similarly, in order for a process running on one host to send packets to a process running on another host, the receiving process needs to have an address. To identify the receiving process, two pieces of information need to be specified: (1) the address of the host and (2) an identifier that specifies the receiving process in the destination host.

In the Internet, the host is identified by its **IP address**. We'll discuss IP addresses in great detail in Chapter 4. For now, all we need to know is that an IP address is a 32-bit quantity that we can think of as uniquely identifying the host. In addition to knowing the address of the host to which a message is destined, the sending process must also identify the receiving process (more specifically, the receiving socket) running in the host. This information is needed because in general a host could be running many network applications. A destination **port number** serves this purpose. Popular applications have been assigned specific port numbers. For example, a Web server is identified by port number 80. A mail server process (using the SMTP protocol) is identified by port number 25. A list of well-known port numbers for all Internet standard protocols can be found at <http://www.iana.org>. We'll examine port numbers in detail in Chapter 3.

2.1.3 Transport Services Available to Applications

Recall that a socket is the interface between the application process and the transport-layer protocol. The application at the sending side pushes messages through the socket. At the other side of the socket, the transport-layer protocol has the responsibility of getting the messages to the socket of the receiving process.

Many networks, including the Internet, provide more than one transport-layer protocol. When you develop an application, you must choose one of the available transport-layer protocols. How do you make this choice? Most likely, you would study the services provided by the available transport-layer protocols, and then pick the protocol with the services that best match your application's needs. The situation is similar to choosing either train or airplane transport for travel between two cities. You have to choose one or the other, and each transportation mode offers different services. (For example, the train offers downtown pickup and drop-off, whereas the plane offers shorter travel time.)

What are the services that a transport-layer protocol can offer to applications invoking it? We can broadly classify the possible services along four dimensions: reliable data transfer, throughput, timing, and security.

Reliable Data Transfer

As discussed in Chapter 1, packets can get lost within a computer network. For example, a packet can overflow a buffer in a router, or can be discarded by a host or router after having some of its bits corrupted. For many applications—such as electronic mail, file transfer, remote host access, Web document transfers, and financial applications—data loss can have devastating consequences (in the latter case, for either the bank or the customer!). Thus, to support these applications, something has to be done to guarantee that the data sent by one end of the application is delivered correctly and completely to the other end of the application. If a protocol provides such a guaranteed data delivery service, it is said to provide **reliable data transfer**. One important service that a transport-layer protocol can potentially provide to an application is process-to-process reliable data transfer. When a transport protocol provides this service, the sending process can just pass its data into the socket and know with complete confidence that the data will arrive without errors at the receiving process.

When a transport-layer protocol doesn't provide reliable data transfer, some of the data sent by the sending process may never arrive at the receiving process. This may be acceptable for **loss-tolerant applications**, most notably multimedia applications such as conversational audio/video that can tolerate some amount of data loss. In these multimedia applications, lost data might result in a small glitch in the audio/video—not a crucial impairment.

Throughput

In Chapter 1 we introduced the concept of available throughput, which, in the context of a communication session between two processes along a network path, is the rate at which the sending process can deliver bits to the receiving process. Because other sessions will be sharing the bandwidth along the network path, and because these other sessions will be coming and going, the available throughput can fluctuate with time. These observations lead to another natural service that a transport-layer protocol could provide, namely, guaranteed available throughput at some specified rate. With such a service, the application could request a guaranteed throughput of r bits/sec, and the transport protocol would then ensure that the available throughput is always at least r bits/sec. Such a guaranteed throughput service would appeal to many applications. For example, if an Internet telephony application encodes voice at 32 kbps, it needs to send data into the network and have data delivered to the receiving application at this rate. If the transport protocol cannot provide this throughput, the application would need to encode at a lower rate (and receive enough throughput to sustain this lower coding rate) or may have to give up, since receiving, say, half of the needed throughput is of little or no use to this Internet telephony application. Applications that have throughput requirements are said to be **bandwidth-sensitive applications**. Many current multimedia applications are bandwidth sensitive, although some multimedia applications may use adaptive coding techniques to encode digitized voice or video at a rate that matches the currently available throughput.

While bandwidth-sensitive applications have specific throughput requirements, **elastic applications** can make use of as much, or as little, throughput as happens to be available. Electronic mail, file transfer, and Web transfers are all elastic applications. Of course, the more throughput, the better. There's an adage that says that one cannot be too rich, too thin, or have too much throughput!

Timing

A transport-layer protocol can also provide timing guarantees. As with throughput guarantees, timing guarantees can come in many shapes and forms. An example guarantee might be that every bit that the sender pumps into the socket arrives at the receiver's socket no more than 100 msec later. Such a service would be appealing to interactive real-time applications, such as Internet telephony, virtual environments, teleconferencing, and multiplayer games, all of which require tight timing constraints on data delivery in order to be effective. (See Chapter 7, [Gauthier 1999; Ramjee 1994].) Long delays in Internet telephony, for example, tend to result in unnatural pauses in the conversation; in a multiplayer game or virtual interactive environment, a long delay between taking an action and seeing the response from the environment (for example, from another player at the end of an end-to-end connection) makes the application feel less realistic. For non-real-time applications,