GPS Track Demo

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We will plot tracks from GPS files (GPX, TCX, etc.) using R and ggmap. Specifically, we will use the get_map() "smart function" to get the base map. While get_map() includes a zoom='auto' feature, we will develop our own function for determining an appropriate zoom level.

See: get_map {ggmap} for more information about the features of the get_map() function.

User-defined Functions for Code Reuse

As a practical example of user-defined functions, we will make several maps using GPS tracks. We will create several functions to reuse code which will perform important calculations allowing us to choose the approproate base map location and zoom level. We will repeat the process for several GPS tracks for both Google and OpenStreetMap (OSM) base maps.

Set Options

First we will set a few knitr options to control document rendering.

```
suppressPackageStartupMessages(library(knitr))
opts_chunk$set(echo=TRUE, warning=FALSE, message=FALSE, cache=FALSE)
```

Install Packages

Then we will install ggmap if it is not already installed and load the package.

```
if (!require(ggmap)) install.packages("ggmap", repos="http://cran.fhcrc.org")
library(ggmap)
```

Convert GPS File to CSV

Now, we convert our GPS file to a CSV for importing into R using GPSBabel.

This particular GPS track was created from a smartphone using the MapMyWalk app and downloaded as a TCX file from the MapMyWalk website.

The following command is run from the "shell" prompt of the computer's operating system, such as Bash, DOS, or PowerShell.

```
gpsbabel -t -i gtrnctr -f mywalk.tcx -o unicsv -F mywalk.csv
```

Import the CSV

We can import this CSV file into R with read.csv.

```
gps <- read.csv('mywalk.csv', header = TRUE)</pre>
```

Get the Base Map

Zoom Level

First we need to find an appropriate zoom level or scale. The zoom level (as defined by Google) could be determined by trial-and-error, knowing the range should be between 0 (whole world) and 21 (building) with 10 suggested for a "city" zoom level.

```
zoomLevel <- 14
```

That would give us a map that was roughly twice as wide as our route area.

However, we will calculate this level from an algorithm found online. This will allow us to "autozoom" our map, regardless of the size of the GPS track area we are using. Let's also make this calculation into a function so we can reuse it.

```
autoZoom <- function(lon, lat) {
    globeWidth <- 256
    west <- min(lon)
    east <- max(lon)
    north <- max(lat)
    south <- min(lat)

angle <- east - west
    angle2 <- north - south

if (angle2 > angle) angle <- angle2
    if (angle < 0) angle <- angle + 360

zoom <- floor(log(960 * 360 / angle / globeWidth) / log(2)) - 2
    return(zoom)
}
zoomLevel <- autoZoom(gps$Longitude, gps$Latitude)</pre>
```

[1] 14

This is the same zoom level we had discovered earlier by trial-and-error.

Calculate Route Location and Size

To get the right base map location, we need to perform some more calculations. We want to know the center coordinates of the GPS track. We will create a one-line function to calculate the center point of the GPS track and map.

```
getCenter <- function(lat, lon) c(lon = median(lon), lat = median(lat))
centerLocation <- getCenter(gps$Latitude, gps$Longitude)</pre>
```

Google Map

Now we can get the base map using this zoomLevel and center location. We will make another new function for this procedure.

We can get our base map from Google.

Let's make a function to automatically calculate the map scale then execute the get_map() function.

OpenStreetMap

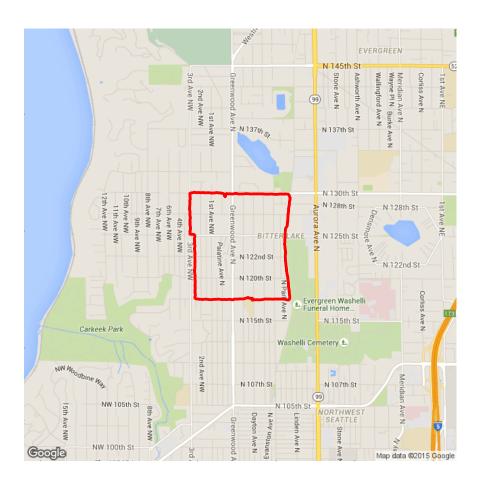
We can also use a base map from OpenStreetMap, using the function we just defined.

```
openStreetMapImageData <- fetchMap(centerLocation, 'osm', zoomLevel)</pre>
```

Plot the Track on the Map

Google Map

Here is the GPS track plotted over a Google base map, using a function we define.



${\bf OpenStreetMap}$

And here is the same GPS track plotted on an OpenStreetMap.

makeMap(openStreetMapImageData)



Plot Another Track

We will check our zoom and scale settings with a different track. This one, instead of being square, is longer than it is wide.

```
gpsbabel -t -i gtrnctr -f myride.tcx -o unicsv -F myride.csv
```

After converting myride.tcx to myride.csv, we can import into R and calculate the zoom level and center location.

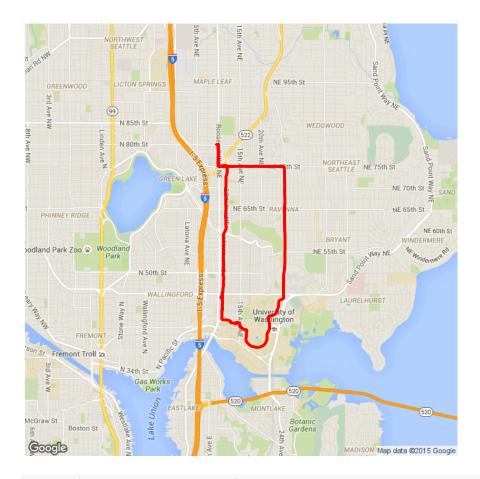
```
gps <- read.csv('myride.csv', header = TRUE)
zoomLevel <- autoZoom(gps$Longitude, gps$Latitude)
centerLocation <- getCenter(gps$Latitude, gps$Longitude)</pre>
```

Now we can fetch the base maps.

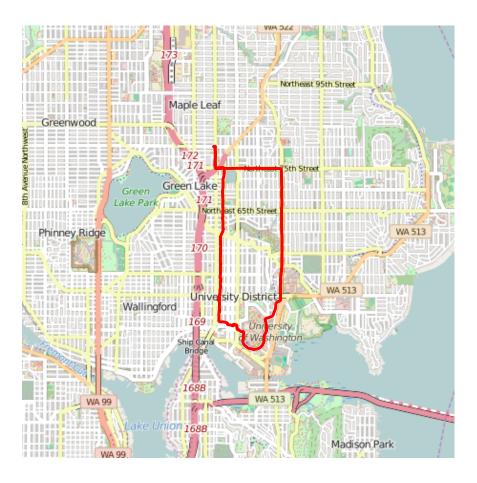
```
googleMapImageData <- fetchMap(centerLocation, 'google', zoomLevel)
openStreetMapImageData <- fetchMap(centerLocation, 'osm', zoomLevel)</pre>
```

And then make the maps.

```
makeMap(googleMapImageData)
```



makeMap(openStreetMapImageData)



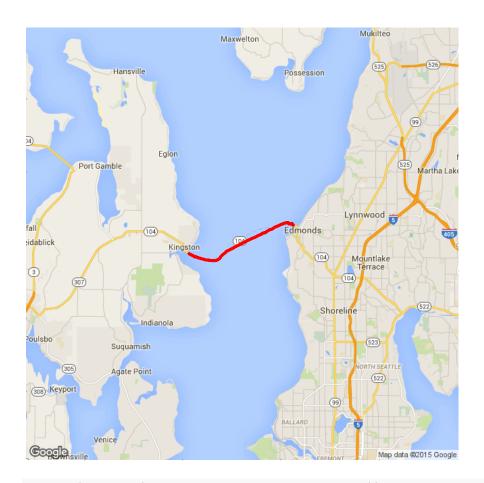
Plot a Third Track

As a final check that our autoZoom() function is working as we would like, let's plot a track that is wider than it is long.

```
gpsbabel -t -i gtrnctr -f myferryride.tcx -o unicsv -F myferryride.csv
```

After converting myferryride.tcx to myferryride.csv, we can make the maps.

```
gps <- read.csv('myferryride.csv', header = TRUE)
zoomLevel <- autoZoom(gps$Longitude, gps$Latitude)
centerLocation <- getCenter(gps$Latitude, gps$Longitude)
makeMap(fetchMap(centerLocation, 'google', zoomLevel))</pre>
```



makeMap(fetchMap(centerLocation, 'osm', zoomLevel))

