GPS Track Demo

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This is one way to plot a track from a GPS file (GPX, TCX, etc.) file using R and ggmap.

Based on: Mapping GPS Tracks in R by Shawn Mollie Taylor. Here is the Gist.

Set Options

First we will set a few knitr options to control document rendering.

```
suppressPackageStartupMessages(library(knitr))
opts_chunk$set(echo=TRUE, warning=FALSE, message=FALSE, cache=FALSE)
```

Install Packages

Then we will install ggmap if it is not already installed and load the package.

```
if (!require(ggmap)) install.packages("ggmap", repos="http://cran.fhcrc.org")
library(ggmap)
```

Convert GPS File to CSV

Now, we convert our GPS file to a CSV for importing into R using GPSBabel.

This particular GPS track was created from a smartphone using the MapMyWalk app and downloaded as a TCX file from the MapMyWalk website.

The following command is run from the "shell" prompt of the computer's operating system, such as Bash, DOS, or PowerShell.

```
gpsbabel -t -i gtrnctr -f mywalk.tcx -o unicsv -F mywalk.csv
```

Import the CSV

We can import this CSV file into R with read.csv.

```
gps <- read.csv('mywalk.csv', header = TRUE)</pre>
```

Get the Base Map

Zoom Level

First we need to find an appropriate zoom level or scale. The zoom level (as defined by Google) could be determined by trial-and-error, knowing the range should be between 3 (continent) and 21 (building) with 10 suggested for a "city" zoom level.

```
zoomlevel <- 15
```

That would give us a map that was roughly twice as wide as our route area.

However, we will calculate this level from an algorithm found online. This will allow us to "autoscale" our map, regardless of the size of the GPS track area we are using.

```
GLOBE WIDTH = 256
west <- min(gps$Longitude)</pre>
east <- max(gps$Longitude)</pre>
angle <- east - west
north <- max(gps$Latitude)</pre>
south <- min(gps$Latitude)</pre>
delta <- 0
angle2 <- north - south
if (angle2 > angle) {
    angle <- angle2
    delta <- 3
}
if (angle < 0) {
    angle <- angle + 360
}
zoomlevel <- ceiling(log(960 * 360 / angle / GLOBE_WIDTH) / log(2)) - 2 - delta;
zoomlevel
```

[1] 15

This is the same zoom level we had discovered earlier by trial-and-error.

Calculate Route Location and Size

To get the right base map location, we need to perform some more calculations. We want to know the center coordinates and the width and height of the route.

```
centerLon <- median(gps$Longitude)
centerLat <- median(gps$Latitude)
routeWidth <- abs(east - west)
routeHeight <- abs(north - south)</pre>
```

The first two variables will be used to get the Google base map. All four of these variables will be used to get the OpenStreetMap base map.

Google Map

Now we can get the base map using this zoomlevel, location, and size.

We can get our base map from Google.

```
googleMapImageData <- get_googlemap(
   center = c(lon = centerLon, lat = centerLat),
   zoom = zoomlevel, maptype = c("terrain")
)</pre>
```

OpenStreetMap

We can also use a base map from OpenStreetMap.

The value we chose for scale approximates the zoom chosen for the Google Map and was based on a formula found online for converting the Google zoom level to map scale.

Plot the Track on the Map

Google Map

Here is the GPS track plotted over a Google base map.



${\bf OpenStreetMap}$

And here is the same GPS track plotted on an OpenStreetMap.

