Oscillations and Waves Exam 1 — Naval Battle

Hexi's Solution

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You only have work to do in Parts 1, 2, 4, 5, 6, and 8. The biggest part is Part 5. Glance ahead to that part so you know where you are going, and then get started on Part 1.

Warmup — Using NestList[] (2 pts)

(a) Write a super-simple function that doubles whatever it gets and returns that as its result. I have started the function for you:

In[235]:=

doubler[valueToDouble_] := 2 valueToDouble

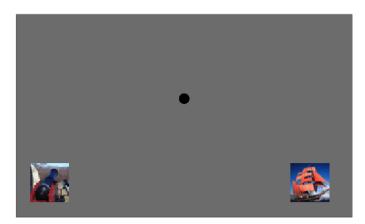
(b) Repeatedly call the function you just wrote using NestList[]. Start with 1 as the original value. After NestList does 5 calls of **doubler**[], **NestList**[] should return {1, 2, 4, 8, 16, 32}. **NestList**[] takes three arguments that I have called rooster, pig, and rabbit. That is what you are fixing up:

2. Naval Battle Graphics (3 pts)

In[237]:=



The goal of Part 2 is to make a graphic that looks likes this:

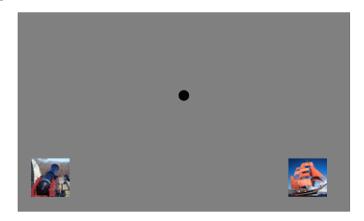


You will be starting with the **cannonballGraphic**[] function below.

- (a) Add a line that insets sailingShip to position {6.0,0.0}.
- (b) Add one point, with the position specified by the argument cannonballPosition. Your point should be styled to have a point size of 0.03.

In[239]:= cannonballGraphic[cannonballPosition_] := Graphics[{ (* the first line makes a gray rectangle *) {EdgeForm[Thin], Gray, Polygon[{{-1, -0.8}, {7, -0.8}, {7, 4}, {-1, 4}}]}, (* Don't mess with the next line -- that puts the cannon in *) Inset[cannon, {-0.2, 0.0}], (* (a) now you add a oneliner that puts the sailing ship in the graphics at (6.0, 0.0) *)Inset[sailingShip, {6.0, 0.0}], (* (b) then add a oneliner that puts the cannonball in at cannonballPosition *) PointSize[0.03], Point[cannonballPosition] (* and styles the point to have point size 0.03! *) }] cannonballGraphic[{3, 2}]

Out[240]=



3. Initial Conditions

There is nothing for you to do in Part 3 yet! You will be coming back to it at the very end, but do glance through it,

especially the three-line comment towards the end.

```
In[241]:=
      muzzleVelocity = 0.3; (* cannonball muzzle velocity in miles / second *)
      muzzleAngle = 60°; (* you will be adjusting this -- initially it is set to 60° *)
      mass = 100; (* a 100 pound cannonball *)
      initialx = 0.0;
      initialy = 0.3;
      initialVx = muzzleVelocity Cos[muzzleAngle];
      initialVy = muzzleVelocity Sin[muzzleAngle];
      tInitial = 0.0;
      tFinal = 100.0;
      (* This is the first time you have ever
       seen a problem with both x and y coordinates *)
      (* we need t, the x position, the y position,
      the x velocity and the y velocity *)
      (* in cc[[1]], cc[[2]], cc[[3]], cc[[4]], and cc[[5]]. *)
      initialConditions = N[{tInitial, initialx, initialy, initialVx, initialVy}];
```

4. Forces on the Cannonball — Getting Acceleration (3 pts)

```
In[251]:=
      dragCoefficient = 12.0;
       (* the units of the drag coefficient are a screwball unit *)
       (* similar to but not precisely pounds/(mile/second)^2 *)
      dragFx[vx_, vy_] := -dragCoefficient vx Sqrt[vx² + vy²]
      dragFy[vx_, vy_] := -dragCoefficient vy Sqrt[vx² + vy²]
      forceOfGravity[] := -mass 0.007
       (* gravity in miles/second<sup>2</sup> is very small because a mile is a big unit *)
In[255]:=
      dragFx[1, 1]
Out[255]=
       -16.9706
```

In this problem there is an x-component and a y-component to the motion, and so we need to define an acceleration in the x-direction and an acceleration in the y-direction. What you are about to code is:

```
a_x = F_x/m where F_x is the drag force's x-component I have given you above
a_v = F_v / m where F_v is the sum of the drag force's y-component plus the force of gravity
```

(a) Code the acceleration in the x direction.

```
In[256]:=
       ax[vx_, vy_] := dragFx[vx, vy] / mass
```

(b) Code the acceleration in the y direction (include the drag force's y-component and the force of gravity):

```
In[257]:=
       ay[vx_, vy_] := (dragFy[vx, vy] + forceOfGravity[]) / mass
```

5. Implementing Second-Order Runge-Kutta (8 pts)

```
In[258]:=
       steps = 5000;
       deltaT = (tFinal - tInitial) / steps;
```

Your job is to finish implementing rungeKutta2[] below. To make implementation easier, I am going to go straight to the midpoint version of Runge-Kutta ($\lambda = 1/2$). Then the Second-Order Runge-Kutta equations simplify a bunch. Also, notice that in Part 4(a) and 4(b) ax and ay only depended on v_x and v_{ν} . So that makes your Second-Order Runge-Kutta easier to implement too! Here are all seven equations you will be implementing:

$$V_X^* = V_X(t_i) + a_X(V_X(t_i), V_Y(t_i)) \cdot \frac{\Delta t}{2}$$

$$v_y^* = v_y(t_i) + a_y(v_x(t_i), v_y(t_i)) \cdot \frac{\Delta t}{2}$$

$$t_{i+1} = t_i + \Delta t$$

$$v_x(t_{i+1}) = v_x(t_i) + a_x(v_x^*, v_y^*) \cdot \Delta t$$

$$v_y(t_{i+1}) = v_y(t_i) + a_y(v_x^*, v_y^*) \cdot \Delta t$$

$$x(t_{i+1}) = x(t_i) + (v_x(t_i) + v_x(t_{i+1})) \frac{\Delta t}{2}$$

$$y(t_{i+1}) = y(t_i) + \left(v_y(t_i) + v_y(t_{i+1})\right) \tfrac{\Delta t}{2}$$

In[260]:=

```
rungeKutta2[cc_] := |
         currentTime = cc[[1]];
         currentx = cc[2];
         (* What is missing here!? *)
         currenty = cc[3];
         currentVx = cc[4];
         (* And what is missing here!? *)
         currentVy = cc[[5]];
         (* Your main work is the next seven lines: *)
         vxStar = currentVx + ax[currentVx, currentVy] \frac{\text{deltaT}}{2};
         vyStar = currentVy + ay[currentVx, currentVy] \frac{\text{deltaT}}{2};
         newTime = currentTime + deltaT;
         newVx = currentVx + ax[vxStar, vyStar] deltaT;
         newVy = currentVy + ay[vxStar, vyStar] deltaT;
         newx = currentx + (currentVx + newVx) \frac{deltaT}{2};
         newy = currenty + (currentVy + newVy) \frac{\text{deltaT}}{2};
         (* Do not mess with the rest of this stuff. *)
         (* It stops the cannonball from going off the right edge of the \star)
         (* graphic, and also stops it from going below the water. *)
         newx = If[newx \geq 6.7, 6.7, newx];
         newy = If[newy \leq -0.2, -0.2, newy];
         {newTime, newx, newy, newVx, newVy}
       (* As a test, your function should return *)
       (* {0.018,0.00269913,0.304674,0.149903, 0.259513} *)
       (* when given the initial conditions. *)
       rungeKutta2[initialConditions]
Out[261]=
       \{0.02, 0.00299892, 0.305193, 0.149892, 0.259481\}
```

6. Computing and Collecting the Results (2 pts)

You are going to call NestList[] on your rungeKutta2 functions, with initialConditions as the original value, and make **NestList**[] do **steps** calls of the function.

- (a) Fix up the call to **NestList**[].
- (b) After NestList[] does all the hard work, you also need to do the right thing with Transpose[] to get positions to be a list of all the $\{x, y\}$ pairs.

Can't remember what to do? Go back to Part 1(b) and look at what you did in that warmup problem.

```
In[262]:=
      (* fix up the NestList call *)
      results = NestList[rungeKutta2, initialConditions, steps];
      transposedResults = Transpose[results];
      times = transposedResults[1];
      xPositions = transposedResults[2];
      yPositions = transposedResults[3];
      (* assemble xPositions and yPositions into a bunch of points *)
      positions = Transpose[{xPositions, yPositions}];
```

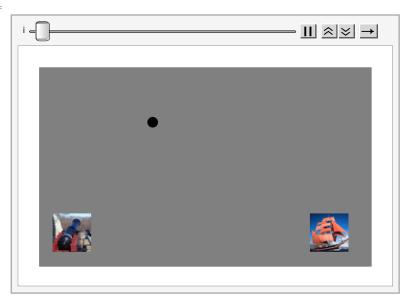
7. Animating the Results

There is nothing for you to do in this part. If everything has gone well, you will see an animation.

In[268]:=

Animate[cannonballGraphic[positions[i]], {i, 1, steps, 1}]

Out[268]=



8. Initial Conditions — Adjusting the Muzzle Angle (2 pts)

Now you get to go back to Part 3 and do something. You are going to adjust the muzzle angle.

Try every 10° from 10° to 60°. That's six different re-executions of the notebook.

For which angles does the cannonball do a broadside into the ship? (I find two such angles.)

- (a) Low angle that causes the best broadside: _____20°____ (nearest 10°)
- (b) High angle that causes the best broadside: _____60°____ (nearest 10°)

9. Game Over

Thank you for playing!

I hope that was educational and fun!