# **Square Drumhead**

Completed and Analyzed in class, March 25, 2025

This is the fourteenth notebook for you to complete. It is our first notebook that is has a two-dimensional network of masses. We'll make those two dimensions be the *x* and *y* directions. The two-dimensional network of masses will oscillate vertically (in the *z* direction).

#### **Initial Conditions**

```
Set up the duration, steps, and deltaT:
```

```
In[25]:= tInitial = 0.0;
    tFinal = 10.0;
    steps = 5000;
    deltaT = (tFinal - tInitial) / steps;
```

Set up the size of the grid (enough masses so that the grid looks like a drumhead, but not so many that we tax our computers):

```
In[29]:= nx = 3; (* There is actually going to be 19, but both x edges will be fixed. *)
    (* So the net number that are actually moving will be 17 in the x-direction. *)
    ny = 4; (* There is actually going to be 25, but both y edges will be fixed. *)
    (* So the net number that are actually moving will be 23 in the y-direction. *)
    (* 17 * 23 means that the computer has to simulate a grid of 391 masses. *)
```

We are going to make initial conditions that are a product of sine functions. What sine function specifically is specified by the modes.

```
In[79]:= modex = 1;
      modey = 2;
      maxz = 0.5;
      initialzs =
         Table [\max z \sin[Pi \bmod ex (j-1)/nx] \sin[Pi \bmod ex (k-1)/ny], \{j, nx + 1\}, \{k, ny + 1\}];
      initialvs = Table[0, {k, ny + 1}, {j, nx + 1}];
      initialConditions = {tInitial, initialzs, initialvs};
In[91]:= initialzs // Grid
Out[91]=
      0.
             0.
                   0.
                          0.
      0. 0.433013 0. -0.433013 0.
      0. 0.433013 0. -0.433013 0.
      0.
             0. 0. 0.
```

## Formulas for the Accelerations — Recap from Theory

The acceleration formula

$$a_{j,k} = -\omega_0^2 (z_{j,k+1} + z_{j,k-1} + z_{j+1,k} + z_{j-1,k} - 4z_{j,k})$$

is valid except for the ends, and we have to handle those separately.

#### **Fixed Edges**

A drumhead is normally fixed at the edges, and we are going to deal with the edges by just freezing the edge masses to have z = 0. So  $z_{1,k} = 0$ ,  $z_{n_x+1,k} = 0$ ,  $z_{j,1} = 0$ , and  $z_{j,n_y+1} = 0$ .

Conceptually, you can think of the index j as running from 0 to  $n_x$  and the index k as running from from 0 to  $n_{\nu}$ , but that goes against the grain of the way Mathematica indexes its arrays, so we are going to have to be super-careful about off-by-one errors. The index j will run from 1 to  $n_x$  + 1 and the index k will run from 1 to  $n_v + 1$ .

You can see that the necessary care has already been taken in the initial Conditions above.

#### Implementing the Accelerations

```
In[67]:= omega0 = 4 Pi;
     (* The following is on the right track, but it doesn't work for the ends \star)
     a[j_{k}, k_{n}] := -omega0^{2} If[j := 1 || j := nx + 1 || k := 1 || k := ny + 1,
         0, (* no acceleration at the edges *)
         allzs[j, k+1] + allzs[j, k-1] + allzs[j+1, k] + allzs[j, k-1] - 4 allzs[j, k]
        ]
```

## Second-Order Runge-Kutta — Implementation

Now we implement Runge-Kutta 2:

```
In[44]:= initialzs
Out[44]=
        \{\{0., 0., 0., 0., 0., 0.\}, \{0., 0.433013, 0., -0.433013, 0.\},
         \{0., 0.433013, 0., -0.433013, 0.\}, \{0., 0., 0., 0., 0.\}\}
 In[54]:= Range[{nx + 1, ny + 1}]
Out[54]=
       \{\{1, 2, 3, 4\}, \{1, 2, 3, 4, 5\}\}
 ln[56]:= Array[{\#1, \#2} \&, {nx + 1, ny + 1}]
Out[56]=
        \{\{\{1,1\},\{1,2\},\{1,3\},\{1,4\},\{1,5\}\},\{\{2,1\},\{2,2\},\{2,3\},\{2,4\},\{2,5\}\},
         \{3, 1\}, \{3, 2\}, \{3, 3\}, \{3, 4\}, \{3, 5\}\}, \{\{4, 1\}, \{4, 2\}, \{4, 3\}, \{4, 4\}, \{4, 5\}\}\}
```

```
In[71]:= initialzs
Out[71]=
       \{\{0., 0., 0., 0.\}, \{0., 0.433013, 0.433013, 0.\},
        \{0., 0., 0., 0.\}, \{0., -0.433013, -0.433013, 0.\}, \{0., 0., 0., 0.\}\}
ln[86]:= as = Table[a[j, k, initialzs], {j, 1, nx + 1}, {k, 1, ny + 1}];
```

\$Aborted

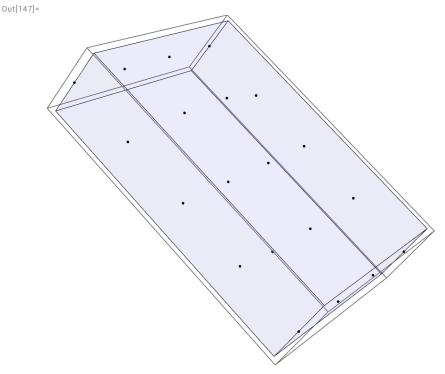
Out[88]=

••• Part: Part 2 of rk2Results does not exist. 1

### 3D Graphics

We need a graphics implementation with  $(n_x + 1)(n_y + 1)$  masses. Space the masses equally across the x and y axes of the cuboid.

```
In[140]:=
      halfHeight = 1;
      halfDepth = 4;
      halfWidth = 3;
      xspacing = 2 halfWidth / nx;
      yspacing = 2 halfDepth / ny;
      region = {FaceForm[{Blue, Opacity[0.04]}], Cuboid[
           {-halfWidth, -halfDepth, -halfHeight}, {halfWidth, halfDepth, halfHeight}]};
      drumheadGraphic[zs_] := Graphics3D[Flatten[{
            {region},
            Table[
             Point[{-halfWidth + (j - 1) xspacing, -halfDepth + (k - 1) yspacing, zs[j, k]]}],
             {j, nx + 1}, {k, ny + 1}
            ]},
           1]];
      drumheadGraphic[initialzs]
```



## Animating the 3D Graphics

It's also nice to have an animation, arranged so that the default duration of the animation is the actual

duration of the animation:

```
Animate[drumheadGraphic[zs[step]]],
 {step, 0, steps, 1}, DefaultDuration → tFinal - tInitial]
```