Parlr: Parallelized Record Linkage in R

Brian Kundinger

Introduction

Most methods for conducting record linkage, the task of identifying duplicate records across datasets, are derived from the foundational article by Fellegi and Sunter in 1969. Within this family of methods, two methods have notable strengths: fastlink, proposed by Enamorado et al (2019), continues a is able to conduct linkage on incredibly large datasets

Notation and Assumptions

Our notation and assumptions closely follow that of Sadinle (2017). Denote two files as A and B, with n_A and n_B records respectively, and with records indexed as $i \in \{1, \ldots, n_A\}$ in A and $j \in \{1, \ldots, n_B\}$ in B. Without loss of generality, label the files such that $n_A \geq n_B$. We also assume there are no duplicates within files, only across. For each record pair under consideration, we generate a comparison vector $\gamma_{ij} = \{\gamma_{ij}^1, \ldots, \gamma_{ij}^F\}$, where F is the number of fields used in the linkage and each γ_{ij}^f takes on a value $l \in \{1, \ldots, L_f\}$ indicating level agreement between the two records on a specified field.

To indicate matching status, we adopt the *linkage structure parameter* $\mathbf{Z} = (Z_1, \dots, Z_{n_B})$ from Sadinle 2017, defined as

$$Z_j = \begin{cases} i, & \text{if records } i \in A \text{ and } j \in B \text{ refer to the same entity;} \\ n_A + 1, & \text{if record } j \in B \text{ does not have a match in file } A; \end{cases}$$

This provides more memory efficient storage for the linkage information than a $n_A \times n_B$ sparse matrix of indicators.

Following the Fellegi Sunter framework, we define $m^{fl} := P(\gamma_{ij}^f = l | Z_j = i)$ to be the probability of observing agreement level l in field f for records i and j given that the records are a match, and similarly define $u^{fl} := P(\gamma_{ij}^f = l | Z_j \neq i)$, for non-matches. We denote λ to be the (marginal) probability that some record $j \in B$ has a match in A.

Wherever possible, we reserve superscripts for denoting field and level, while reserving subscripts for record indices. For example, $\mathbf{m}^f = (m^{f1}, \dots, m^{fL_f})$ is the probability distribution governing field f for matching records, and $\mathbf{m}_{ij} = \prod_{f=1}^F \prod_{l=1}^{L_f} \left(m^{fl}\right)^{\mathbf{1}_{\gamma_{ij}^f=l}} = P(\gamma_{ij}|Z_j=i)$ is product of the relevant of the appropriate \mathbf{m} parameters for record pair (i,j). We hope that these conventions avoid overloaded notation in the likelihood and subsequent derivations.

Model Specification

(This will be revised to talk more explicitly about sampling Z_i independently)

Our model differs from that of Sadinle 2017 through its explicit dependence on a beta random variable λ that models the rate of matching across records. Sadinle marginalizes over such a random variable in his derivations of the "beta prior for bipartite matching," but here we provide derivations without marginalizing in order to specify differing rates of matching for different linkage clusters.

Prior Distributions and Likelihood

For fields $f \in \{1, ..., F\}$ and levels $l \in \{1, ..., L_f\}$ we adopt the following likelihood and prior distributions.

$$P(\Gamma | \mathbf{Z}, \mathbf{m}, \mathbf{u}, \lambda) = \prod_{j=1}^{n_B} \prod_{i=1}^{n_A} \mathbf{m}_{ij}^{\mathbf{1}_{z_j = i}} \mathbf{u}_{ij}^{\mathbf{1}_{z_j \neq i}}$$

$$\mathbf{m}^{\mathbf{f}} \sim \text{Dirichlet}(\alpha^{f1}, \dots, \alpha^{fL_f})$$

$$\mathbf{u}^{\mathbf{f}} \sim \text{Dirichlet}(\beta^{f1}, \dots, \beta^{fL_f})$$

$$Z_j | \lambda = \begin{cases} \frac{1}{n_A} \lambda & z_j \leq n_A; \\ 1 - \lambda & z_j = n_A + 1 \end{cases}$$

$$\lambda \sim \text{Beta}(\alpha_\lambda, \beta_\lambda)$$

The prior for Z_j has equal probability of matching to all records $i \in A$, and non-matching probability governed by λ . Therefore a $\lambda \sim \text{Beta}(1,1)$ corresponds to a prior belief that nonmatches and matches are equally likely, and a $\lambda \sim \text{Beta}(1,\frac{1}{n_A})$ prior corresponds to a uniform prior on the labeling of **Z**.

Posterior Sampling

We work with the following factorization of the joint distribution:

$$p(\Gamma, \mathbf{Z}, \mathbf{m}, \mathbf{u}, \lambda) = p(\Gamma | \mathbf{Z}, \mathbf{m}, \mathbf{u}) p(\mathbf{Z} | \lambda) p(\mathbf{m}, \mathbf{u}) p(\lambda)$$

This factorization leads to following Gibbs Sampler:

Sample $\mathbf{m}^{(s+1)} \mathbf{u}^{(s+1)} | \Gamma, \mathbf{Z}^{(s)}$: The \mathbf{m} and \mathbf{u} parameters are updated through standard multinomial-dirichlet mechanics. Thus we have

$$\mathbf{m}^f | \mathbf{Z}, \Gamma \sim \text{Dirichlet}(\alpha^{f1}(\mathbf{Z}), \dots, \alpha^{fL_f}(\mathbf{Z}))$$

$$\mathbf{u}^f|\mathbf{Z}, \Gamma \sim \mathrm{Dirichlet}(\beta^{f1}(\mathbf{Z}), \dots, \beta^{fL_f}(\mathbf{Z}))$$
 where $\alpha_{fl}(\mathbf{Z}) = \sum_{i,j} \mathbf{1}_{obs(\gamma_{ij}^f)} \mathbf{1}_{\gamma_{ij}^f = l} \mathbf{1}_{z_j = i}$ and $\beta_{fl}(\mathbf{Z}) = \mathbf{1}_{obs(\gamma_{ij}^f)} \mathbf{1}_{\gamma_{ij}^f = l} \mathbf{1}_{z_j \neq i}$.

Sample $\lambda^{(s+1)}|\mathbf{Z}^{(s)}$: As a function of λ , the linkage structure parameter \mathbf{Z} is sequence of successes (when $z_j < n_A + 1$) and failures (when $z_j = n_A + 1$), and therefore $p(\mathbf{Z}|\lambda) = \mathcal{L}(\lambda|\mathbf{Z})$ is determined only by the number of duplicates $D = \sum_{i=1}^{n_B} \mathbf{1}_{z_j < n_A + 1}$ encoded by \mathbf{Z} . Thus we have

$$p(\lambda|\mathbf{Z}) \propto p(\mathbf{Z}|\lambda)p(\lambda)$$

$$\propto \lambda^{D} (1-\lambda)^{n_{B}-D} \lambda^{\alpha_{\lambda}-1} (1-\lambda)^{\beta_{\lambda}-1}$$

$$\propto \lambda^{D+\alpha_{\lambda}-1} (1-\lambda)^{n_{B}-D+\beta_{\lambda}-1}$$

$$\implies \lambda^{(s+1)}|\mathbf{Z}^{(s+1)} \sim \text{Beta}(D+\alpha_{\lambda}, n_{B}-D+\beta_{\lambda})$$

Sample $\mathbf{Z}^{(s+1)}|\Gamma,\mathbf{m}^{(s+1)},\mathbf{u}^{(s+1)},\lambda^{(s+1)}$: Because we sample Z_j independently of all other $\overline{Z_{j'}}$, we use only the full conditional for an individual Z_j . Let $\Gamma_{.j}$ denote the set of n_A comparison vectors with $j\in B$, and note that as a function of Z_j , the likelihood $p(\Gamma_{.j}|Z_j,\mathbf{m},\mathbf{u})=\mathcal{L}(Z_j|\Gamma_{.j},\mathbf{m},\mathbf{u})$ is a discrete distribution with probabilities proportional to

$$p(\Gamma_{.j}|Z_j = z_j, \mathbf{m}, \mathbf{u}) \propto \prod_{i=1}^{n_A} \mathbf{m}_{ij}^{\mathbf{1}_{z_j = i}} \mathbf{u}_{ij}^{\mathbf{1}_{z_j \neq i}}$$

$$\propto \prod_{i=1}^{n_A} \left(\frac{\mathbf{m}_{ij}}{\mathbf{u}_{ij}}\right)^{\mathbf{1}_{z_j = i}}$$

$$= \begin{cases} w_{ij} & z_j \leq n_A; \\ 1 & z_j = n_A + 1 \end{cases}$$
By dividing through by $\prod_{i=1}^{n_A} \mathbf{u}_{ij}$

where $w_{ij} = \frac{\mathbf{m}_{ij}}{\mathbf{u}_{ij}} = \frac{P(\gamma_{ij}|Z_j=i)}{P(\gamma_{ij}|Z_j\neq i)}$. The interested reader should note that these are precisely the likelihood ratios used in the Fellegi-Sunter model to classify matches and non-matches, and we therefore refer to w_{ij} as the *Fellegi Sunter weights*.

With the likelihood in this form, we can derive the full conditional

$$p(Z_j|\Gamma_{.j}, \mathbf{m}, \mathbf{u}, \lambda) \propto p(\Gamma_{.j}|Z_j, \mathbf{m}, \mathbf{u})P(Z_j|\lambda)$$

$$\propto \left(\sum_{i=1}^{n_A} w_{ij} \mathbf{1}_{z_j=i} + \mathbf{1}_{z_j=n_A+1}\right) \left(\lambda \sum_{i=1}^{n_A} \frac{1}{n_A} \mathbf{1}_{z_j=i} + (1-\lambda) \mathbf{1}_{z_j=n_A+1}\right)$$

$$= \frac{\lambda}{n_A} \sum_{i=1}^{n_A} w_{ij} \mathbf{1}_{z_j=i} + (1-\lambda) \mathbf{1}_{z_j=n_A+1}$$

$$\implies Z_j^{(s+1)} | \mathbf{m}, \mathbf{u}, \Gamma, \lambda \propto \begin{cases} \frac{\lambda}{n_A} w_{ij} & z_j \leq n_A; \\ 1-\lambda & z_j = n_A+1 \end{cases}$$

In order to make fair comparisons against the Sadinle 2017 model, we integrate over the posterior of λ and rearrange terms to produce the final full conditional:

$$p\left(Z_j^{(s+1)} = i | \mathbf{m}, \mathbf{u}, \mathbf{Z}^{(s)}\right) \propto \begin{cases} w_{ij} & i \leq n_A; \\ n_A \frac{n_B - D + \beta_\lambda}{D + \alpha_\lambda} & i = n_A + 1 \end{cases}$$

Bayes Estimate

Our Gibbs sampler provides posterior samples of **Z** which we use to make our final decisions about the linkage structure. In the case where we false matches and missed matches contribute the same loss, we declare (i,j) to be a match whenever $P(Z_j = i) > \frac{1}{2}$ according to these posterior samples. We can create more elaborate decisions by attributing different loss values to different kinds of error, and allowing pairings with middling posterior probabilities to be left unlabeled by the algorithm so that the modeler can address those manually. For further discussion, see Sadinle 2017.

Efficient Computation

Broadly speaking, we increase our computational efficiency by recognizing that record pairs contribute to posterior calculations only through the agreement pattern of the γ_{ij} vector. Let H be the set of unique agreement patterns in the data, let P denote the total number of unique agreement patterns. Note that P is bounded above by $\prod_{f=1}^F L_f$, and that this bound does not scale with n_A or n_B . We index these agreement patterns by $p \in \{1, \ldots, P\}$, and say $(i, j) \in h_p$ when the (i, j) pair exhibits the p^{th} agreement pattern. Wherever possible, we conduct calculations over these P agreement patterns rather than the $n_A \times n_B$ record pairs.

Data Representation and Hashing

In the classic Fellegi Sunter framework, Γ is a $n_A n_B \times F$ matrix, with each row providing the comparison vector for a different (i,j) pair. We however do not store these comparison vectors themselves, but instead only the a hashed value corresponding to the agreement

pattern of the (i, j) pair. Enamorado et al (2019) provided the hashing function

$$\sum_{f=1}^{F} \mathbf{1}_{\gamma_{(i,j)}^{f} > 0} 2^{\gamma_{(i,j)}^{f} + \mathbf{1}_{f > 1} \times \sum_{e=1}^{f-1} (L_{e} - 1)}$$

to map each agreement pattern to a unique value, but packages like dplyr in R are capable of this as well.

We store this information in a nested list $\tilde{\Gamma}$ where the p^{th} component of the j^{th} list contains a vector of records in A that share agreement pattern h_p with record $j \in B$. For each p, we also calculate $|h_p| = \sum_{i=1}^{n_A} \sum_{j=1}^{n_B} \mathbf{1}_{(i,j) \in h_p}$ total instances of agreement pattern h_p throughout the data, and also for each j, we calculate $|h_p|_j = \sum_{i=1}^{n_A} \mathbf{1}_{(i,j) \in h_p}$ the instances of agreement pattern p among the comparison vectors between record $j \in B$ and each of the n_A records in A.

For large data, we can partition the two datasets A and B into smaller blocks $\{A_m\}$ and $\{B_m\}$ for more manageable computations. On a single machine, we can read-in data sequentially, conduct hashing, collect results, and delete the original data from memory before continuing with the next chunk of data. With multiple cores or multiple machines, this can be done in parallel. Storing this hashed information still becomes burdensome for large data, but this hashing method greatly expands the capabilities of the Fellegi-Sunter framework.

Lastly, the classic Fellegi Sunter method represents the γ_{ij} comparison vector as vector of length F, with each component γ_{ij}^f taking on values in $\{0,\ldots,L_f-1\}$. To ease computations, we instead represent the comparison as a concatenation of F many binary indicator vectors of lengths L_f . For example, if $L_1 = L_2 = 2$ and $L_3 = 3$, then $\gamma_{ij} = (1,0,2)$ under the classical framework becomes $\gamma_{ij} = (0,1,1,0,0,0,1)$ under our framework. This is a bijective transformation that does not change the meaning of the data, but this representation will ease calculations and posterior updates.

Gibbs Sampling

After receiving matching statuses from \mathbf{Z} , the Sadinle method calculates $\alpha_{fl}(\mathbf{Z})$ and $\beta_{fl}(\mathbf{Z})$ for each field and level. This constitutes $2 \times \sum L_f$ many summations over $n_A \times n_B$ quantities, and becomes computationally burdensome with large data. In contrast, we recognize that each unique agreement pattern contributes to the posterior $\alpha(\mathbf{Z})$ and $\beta(\mathbf{Z})$ vectors in the same way. In fact, if we denote $\mathbf{Z}(h_p) = \sum_{j=1}^{n_B} \mathbf{1}_{(Z_j,j) \in h_p}$ to be the number of matching record pairs with agreement pattern h_p , then the contribution of pairs of pattern h_p to the $\alpha(\mathbf{Z})$ vector is simply $\mathbf{Z}(h_p) \times h_p$. Thus our posterior updates are simply $\alpha(\mathbf{Z}) = \alpha_0 + \sum_{p=1}^{P} \mathbf{Z}(h_p) \times h_p$ and $\beta(\mathbf{Z}) = \beta_0 + \sum_{p=1}^{P} |h_p| - (\mathbf{Z}(h_p) \times h_p)$. Note that this constitutes P many summations over n_B quantities, and thus avoids the $n_A \times n_B$ summation from the original method.

Sadinle uses a prior for **Z** that induces the a full conditional for Z_j that strictly enforces

one-to-one matching. Particular, this sampler removed previously matches records from the set of candidate records when sampling Z_j , creating a dependency that makes the sampler *inherently serial*. By weakening the one-to-one requirement, our full conditional for Z does not depend on the rest of the \mathbf{Z}_{-j} vector, and thus can be computed in parallel. More importantly, since only the agreement pattern of Z_j is used for calculations within the Gibbs sampler, and not the particular record label, we can conduct this sampling only at the level of the unique agreement patterns. This boosts computation time far greater than parallelization.

To do this we calculate the Fellegi Sunter weight w_{h_p} for each unique pattern and sample the agreement pattern $h(Z_i)$ following the modified full conditional:

$$h\left(Z_j^{(s+1)}\right) | \mathbf{m}, \mathbf{u}, \mathbf{Z^{(s)}} \propto \begin{cases} w_{h_p} \times |h_p|_j & h(z_j) \in H; \\ n_A \frac{n_B - D + \beta_\lambda}{D + \alpha_\lambda} & z_j = n_A + 1 \end{cases}$$

We complete the entire Gibbs procedure at the level of the P agreement patterns. After, we can back-fill the records corresponding to the agreement patterns by sampling uniformly at random among candidate records stored in $\tilde{\Gamma}$.

Enforcing Bipartite Matching

Add this

Simulation Studies

- Replicating the Sadinle Study
- parlr and BRL speed comparison

Data Analysis

• Necessary? El Salvador data? Or perhaps needs to be a bigger dataset?