

Efficient and Scalable Bipartite Matching with Fast Beta Linkage (`fabl`)

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Abstract

In this paper, we propose the *fast beta linkage* method (`fabl`), which extends a recent Bayesian Fellegi Sunter model for increased efficiency and scalability. Specifically, we relax the one-to-one matching requirement of the Beta Record Linkage method of (Sadinle, 2017) and propose independent priors over the matching space. This allows us to employ hashing techniques that hasten calculations and reduce the overall computational complexity. In addition, we are able to complete pairwise record comparisons over large datasets through parallel computing and reduce memory costs through a new technique called *storage efficient indexing*. Through simulation studies and a case study of homicides from the El Salvadoran Civil War, we show that our method has markedly increased speed with minimal loss of accuracy. Finally, we discuss our work and future directions.

Keywords: bipartite record linkage, Bayesian methods, Gibbs sampling, hashing techniques, Markov chain Monte carlo, parallel/distributed computing

1 INTRODUCTION

Record linkage is the task of identifying duplicate records across multiple data sources, often in the absence of a unique identifier (Christen, 2012). This is an increasingly important task in “data cleaning,” and is used for inferential and predictive analyses in fields such as statistics, computer science, machine learning, political science, economics, precision medicine, official statistics, and others. In this paper, we consider bipartite record linkage, which is merging two databases that contain duplication across the two databases, but do not contain any duplications within each database.

Many statistical record linkage methods are extensions of seminal work of Fellegi and Sunter (1969) and Newcombe et al. (1959). Specifically, Fellegi and Sunter (1969) created comparison vectors for each pair of records in the data and independently classified those pairs as a match or a non-match using a likelihood ratio test. Recent work in the statistical literature has extended this approach for a wide variety of applications (Winkler and Thibaudeau, 1991; Fair, 2004; Wagner et al., 2014; Gill and Goldacre, 2003). Although the need to compute comparisons for all record pairs initially restricted this family of methods, recent work by Enamorado et al. (2019) used innovative hashing techniques to scale the approach to handle large datasets.

The independent pairwise matching assumption from Fellegi and Sunter is popular mainly for its mathematical simplicity, but is often unreasonable in practice. In many situations, we know that there are no duplications within a database, meaning that one record from one database should be linked with at most one record in the other database. Here, additional declared matches are known by assumption to be false. Many extensions to Fellegi and Sunter (1969) resolve these false matches as a post-processing step (Jaro, 1989), but this model misspecification can still lead to poor results (Sadinle, 2017).

Alternatively, one can embed one-to-one matching requirements into the model specification itself, at an additional computational cost. Larsen (2005) employed a Metropolis-Hastings algorithm to only allow sampling matches that respected one-to-one assumptions, but such algorithms exhibit slow mixing due to the combinatorial nature of the constrained matching space. Fortunato (2010) used simulated annealing to target the space of permitted

matches under the one-to-one constraint, but the method was so computationally intensive it could be used to link databases of less than 100 records. Most recently, Sadinle (2017) proposed *Beta Record Linkage* (BRL), using an innovative prior over the space of bipartite matchings to strictly enforce one-to-one requirements throughout his Gibbs sampler. Additionally, he introduced a class of loss functions that allows for a flexible estimation of the linkage structure, such that the modeller can weight the relative importance of false positives and false negatives, and identify records pairings to be decided through clerical review. Although it was shown to work on larger tasks than previous one-to-one methods, BRL becomes slow when working with larger datasets, and unusable when the number of pairwise record comparisons becomes too large.

In this paper, we propose the *fast beta linkage* method (**fabl**), which extends the BRL model for increased efficiency and scalability. Specifically, we relax the one-to-one matching requirement of the Beta Record Linkage method of (Sadinle, 2017) and propose independent priors over the matching space, creating a “many-to-one” model for record linkage. This allows us to employ hashing techniques that hasten calculations and reduce computational costs. Furthermore, we can compute the pairwise record comparisons over large datasets via parallel computing and reduce memory costs through our proposed method of *storage efficient indexing*. Throughout, we argue that even in cases where a bipartite matching is desired, **our proposed approach and relaxation** (with a simple post-processing procedure) provides equivalently accurate estimation of the linkage structure and other parameters, more information through which to assess model misspecification, and greatly enhanced speed. Open source software to use **fabl** in R is available through Github.

In what follows, Section 2 reviews more thoroughly the Fellegi Sunter and Beta Record Linkage methods. Then, Section 3 provides the model specification under **fabl** and derives the Gibbs sampler for posterior inference. Next, Section 4 introduces the hashing technique and storage efficient indexing used to increase the speed of calculations and the scale of the linkage tasks we can undertake. Lastly, in Sections 5 and 6 we use simulation studies and a case study of homicides from the El Salvadoran Civil War to show that our method has markedly increased speed with minimal loss of accuracy when compared to BRL. We

conclude in Section 7 with a discussion of directions for future work.

2 REVIEW OF PRIOR WORK

Consider two databases \mathbf{X}_1 and \mathbf{X}_2 with respective sizes n_1 and n_2 . Without loss of generality, denote files such that $n_1 \geq n_2$. In the context of bipartite matching, we assume that there are duplications across, but not within, each database. Under this framework, the set of matches across datasets can be represented in two equivalent ways. First, we may use a matrix $\Delta \in \{0, 1\}^{n_1 \times n_2}$, where

$$\Delta_{ij} = \begin{cases} 1 & \text{if records } i \in \mathbf{X}_1 \text{ and } j \in \mathbf{X}_2 \text{ refer to the same entity;} \\ 0 & \text{otherwise.} \end{cases} \quad (1)$$

Though intuitive, this sparse matrix representation can become costly for large linkage tasks or for long posterior samplers. More compactly, bipartite matching can also be viewed as a labeling $\mathbf{Z} = (Z_1, \dots, Z_{n_2})$ for the records in database \mathbf{X}_2 such that

$$Z_j = \begin{cases} i & \text{if records } i \in \mathbf{X}_1 \text{ and } j \in \mathbf{X}_2 \text{ refer to the same entity;} \\ n_1 + j & \text{if records } j \in \mathbf{X}_2 \text{ does not have a match in database } \mathbf{X}_1. \end{cases} \quad (2)$$

Depending on which representation is the most convenient, we can go back and forth between the two using $\Delta_{ij} = I(Z_j = i)$, where $I(\cdot)$ is the indicator function.

Denote the set of matches by $\mathbf{M} = \{(i, j) : i \in \mathbf{X}_1, j \in \mathbf{X}_2, \Delta_{ij} = 1\}$, and the set of non-matches by $\mathbf{U} = \{(i, j) : i \in \mathbf{X}_1, j \in \mathbf{X}_2, \Delta_{ij} = 0\}$. The record linkage task can be viewed as identifying the sets of \mathbf{M} and \mathbf{U} . We refer to record pairs that are estimated as matches as “links”, and record pairs that are estimated as non-matches as “non-links”.

2.1 Comparison Data

Intuitively, records that are co-referent or rather refer to the same entity should be similar; records that are non co-referent and refer to different entities should not be similar. Fellegi and Sunter (1969) proposed encoding this is using a comparison vector γ_{ij} computed for each record pair (i, j) in $\mathbf{X}_1 \times \mathbf{X}_2$. Denote the number of criteria for comparing records by

F , such that $\gamma_{ij} = (\gamma_{ij}^1, \gamma_{ij}^2, \dots, \gamma_{ij}^f, \dots, \gamma_{ij}^F)$. In most cases, γ_{ij} consists of one comparison for each feature shared between the two datasets.

The simplest way to compare two records is check for agreement or disagreement, and this is commonly used for categorical variables. For more complex measurements, we can take into account partial agreement to more richly characterize the comparison; for numerical data, we can use absolute difference, and for text data, we can use string distance metrics such as Levenstein or Jaro-Winkler distance. This allows us to divide our records into a set of similarity values into different levels of disagreement (Bilenko and Mooney, 2006; Elmagarmid et al., 2007). Let $\mathcal{S}_f(i, j)$ denote a general similarity measure for feature f of records i and j , where the range of \mathcal{S}_f can be divided into $L_f + 1$ intervals denoted by $I_{f0}, I_{f1}, \dots, I_{fL_f}$. Following convention, I_{f0} represents the highest level of agreement (inclusive of complete agreement) and I_{fL_f} represents the highest level of disagreement (including complete disagreement). Thus, we can construct comparison vectors in the following way:

$$\gamma_{ij}^f = \ell \text{ if } \mathcal{S}_f(i, j) \in I_{f\ell}.$$

The choice of $I_{f\ell}$ are application specific, which we discuss in our simulation and case study.

2.2 Fellegi-Sunter Model

The comparison data γ_{ij} is not sufficient to determine whether a record is a match or nonmatch because of errors that naturally occur in the data. This motivated Fellegi and Sunter (1969) to consider the following likelihood ratio

$$w_{ij} = \frac{P(\gamma_{ij} \mid \Delta_{ij} = 1)}{P(\gamma_{ij} \mid \Delta_{ij} = 0)} \quad (3)$$

as a weight to estimate if record pairs are a match or nonmatch. This ratio will be large if there is strong evidence of the pair being a match, and small otherwise.

In practice $P(\cdot \mid \Delta_{ij} = 1)$ and $P(\cdot \mid \Delta_{ij} = 0)$ are unknown to the modeler, and thus must be estimated. Under the Fellegi Sunter model, we assume that comparison vectors are independent given their matching status, and that match status of the record pairs

are independent, allowing us to model the comparison data using mixture models in the following way:

$$\begin{aligned}\Gamma_{ij} = \gamma_{ij} \mid \Delta_{ij} = 1 &\stackrel{iid}{\sim} \mathcal{M}(\mathbf{m}), \\ \Gamma_{ij} = \gamma_{ij} \mid \Delta_{ij} = 0 &\stackrel{iid}{\sim} \mathcal{U}(\mathbf{u}), \\ \Delta_{ij} &\stackrel{iid}{\sim} \text{Bernoulli}(p),\end{aligned}\tag{4}$$

where p is the proportion of records that match, and \mathbf{m} and \mathbf{u} are vectors of parameters for the matching and nonmatching record pairs. These unknown parameters are often estimated using the EM algorithm.

After estimating \mathbf{m} and \mathbf{u} , the Fellegi Sunter method uses thresholds T_m and T_u such that all record pairs with $w_{ij} > T_m$ are declared as links, and all those with $w_{ij} < T_u$ declared as nonlinks (with those such that $T_u < w_{ij} < T_m$ left undetermined). This is a problem in practice as transitive closures are violated. Since each w_{ij} is calculated independently, there are often situation in which both $w_{ij} > T_m$ and $w_{i'j} > T_m$, so both (i, j) and (i, j') are declared as links, even though such a matching is not allowed by assumption.

To address this issue, Jaro (1989) proposed solving the following linear sum assignment problem:

$$\begin{aligned}\max_{\Delta} \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} w_{ij} \Delta_{ij} \quad \text{subject to} \quad \Delta_{ij} \in \{0, 1\}; \\ \sum_{i=1}^{n_1} \Delta_{ij} \leq 1, j = 1, 2, \dots, n_2; \text{ and} \\ \sum_{j=1}^{n_2} \Delta_{ij} \leq 1, j = 1, 2, \dots, n_1.\end{aligned}\tag{5}$$

The solution to this problem, for which several simple algorithms exist, is a bipartite matching that maximizes the sum of the Fellegi Sunter weights among matched pairs. Jaro (1989) provided no theoretical justification for using this approach, however Sadinle (2017) recently showed that under certain conditions, equation 5 is the maximum likelihood estimate.

2.3 Beta Record Linkage Model

One criticism of using mixture models is that the decision rule will lead to “many-to-many assignments,” breaking one-to-one matching assumptions. One way of resolving this issue to incorporate the constraint directly into the model as follows:

$$\begin{aligned}\boldsymbol{\Gamma}_{ij} \mid Z_j = i &\stackrel{iid}{\sim} \mathcal{M}(\mathbf{m}) \\ \boldsymbol{\Gamma}_{ij} \mid Z_j \neq i &\stackrel{iid}{\sim} \mathcal{U}(\mathbf{u}) \\ \mathbf{Z} &\sim \mathcal{B},\end{aligned}\tag{6}$$

where \mathcal{B} represents a prior on the space of bipartite matchings, and $\mathcal{M}(\mathbf{m}), \mathcal{U}(\mathbf{u})$ are models for the comparison vectors of matches and non-matches. For BRL, Sadinle (2017) proposed the *beta distribution for bipartite matching*, given by

$$P(\mathbf{Z} \mid \alpha_\pi, \beta_\pi) = \frac{(n_1 - n_{12}(\mathbf{Z}))!}{n_1!} \frac{B(n_{12}(\mathbf{Z}) + \alpha_\pi, n_2 - \mathbf{Z}) - \beta_\pi}{B(\alpha_\pi, \beta_\pi)}$$

where $B(\cdot, \cdot)$ represents the Beta function, and hyper parameters α_π and β_π encode prior beliefs about the proportion of records in \mathbf{X}_2 that have matches in \mathbf{X}_1 . This prior induces a Gibbs sampler that strictly enforces one-to-one matching, removing previously matched records from the set of candidate records when sampling Z_j . This creates a dependency that makes the sampler *inherently serial*, which makes the sampler slow when working on large linkage tasks.

2.4 Blocking

In practice, it is not feasible to make all-to-all record comparisons as the computational complexity is of the order $O(n_1 \times n_2)$. The most common solution is utilize blocking, which places similar records into partitions, or “blocks” to reduces this computational burden. In deterministic blocking, the modeller chooses a field thought to be highly reliable, and only compares records that agree on that field. The record linkage method is then applied independently across all blocks, which can be done in parallel for additional speed gains. However, blocking on an unreliable field can lead to many missed matches, making this form of blocking undesirable in many situations.

In this paper, we use hashing and new technique called storage efficient indexing to increase the scale of the linkage tasks we can undertake without the need for blocking. This is useful when there is no reliable blocking field available, or one desires estimates of model parameters for the entire sample in question. In practice, the method the follows can be combined with blocking for even greater computational gains, but all derivations, simulations, and case studies are presented without blocking.

3 FAST BETA LINKAGE

Recall our compact representation of the matching structure $\mathbf{Z} = (Z_1, Z_2, \dots, Z_{n_2})$ with $Z_j \in \{1, 2, \dots, n_1, n_1 + j\}$, where $Z_j < n_1$ indicates a link and $Z_j = n_1 + j$ indicates a nonlink. In contrast to the prior over the vector \mathbf{Z} from Sadinle (2017), we propose independent priors for each component Z_j . We denote the *fast beta prior* as follows:

$$Z_j | \pi = \begin{cases} \frac{1}{n_1} \pi & z_j \leq n_1; \\ 1 - \pi & z_j = n_1 + j \end{cases}$$

$$\pi \sim \text{Beta}(\alpha_\pi, \beta_\pi)$$

Intuitively, this set of priors says that record $j \in \mathbf{X}_2$ has some match in \mathbf{X}_1 with probability π , and that each record $i \in \mathbf{X}_1$ is equally likely to be that match. π itself is given a prior distribution with hyperparameters α_π and β_π to encode prior beliefs about the proportion of records in \mathbf{X}_2 that have matches in \mathbf{X}_1 . One choice of uninformative prior might be $\pi \sim \text{Beta}(1, 1)$, which corresponds to a prior belief that nonmatches and matches are equally likely, and another might be $\pi \sim \text{Beta}\left(1, \frac{1}{n_1}\right)$, which corresponds to a uniform prior on the labeling of \mathbf{Z} . We encourage the reader to integrate out π from the $Z_j | \pi$ under these two settings to gain deeper intuition about this prior.

Note that linkage in this setting is conducted at the *record* level, rather than at the *record pair* level as in the Fellegi Sunter model. That is, π under **fabl** estimates the proportion of records in \mathbf{X}_2 that have matches, while λ in Fellegi Sunter estimate that proportion of record pairs that have matches. We find π to be more interpretable parameter than λ , especially considering that the overwhelming majority of pairs are non matches, meaning

that λ necessarily tends towards 0 as the size of the linkage task grows. Additionally, we emphasize that while the Fellegi Sunter model makes $n_1 \times n_2$ many independent matching decisions and BRL makes n_2 many dependent matching decisions, **fabl** strikes a middle ground between the two, making n_2 many independent matching decisions. As shown in Sections 5 and 6, this allows us to achieve many of the accuracy gains from BRL while maintaining the efficiency gains possible by exploiting independence.

Importantly, this independence means that we have relaxed one-to-one requirement from BRL; our sampler does ensure that each record in \mathbf{X}_2 can be matched to at most one record in \mathbf{X}_1 , but allows for the possibility that multiple records in \mathbf{X}_2 match to the same record in \mathbf{X}_1 . This behavior may be desirable in its own right; Newcombe and Rhynas (1962) was interested in matching birth records to marriage certificates, a situation in which such “many-to-one” matchings are reasonable. In situations when a bipartite estimate is desired, we can use a simple post processing procedure shown in 3.3 to resolve illegal matchings.

3.1 Model Specification

As commonly done in the record linkage literature, we assume that agreement levels across features are conditionally independent. Additionally, we assume that any missing data is missing at random. Let $m_{f\ell} = P(\Gamma_{ij}^f = \ell \mid Z_j = i)$ denote the probability of that matching records have level ℓ of disagreement in feature f , and $u_{f\ell} = P(\Gamma_{ij}^f = \ell \mid Z_j \neq i)$ represent the same probability for non-matches. In addition, denote $\mathbf{m}_f = (m_{f1}, \dots, m_{fL_f})$, $\mathbf{u}_f = (u_{f1}, \dots, u_{fL_f})$, $\mathbf{m} = (m_1, \dots, m_F)$, $\mathbf{u} = (u_1, \dots, u_F)$, and $\Phi = (\mathbf{m}, \mathbf{u})$. The model can then be specified as follows:

$$\begin{aligned} \mathcal{L}(\mathbf{Z}, \Phi \mid \Gamma) &= \prod_{j=1}^{n_1} \prod_{i=1}^{n_2} \left[\prod_{f=1}^F \prod_{l=1}^{L_f} m_{fl}^{I(Z_j=i)} u_{fl}^{I(Z_j \neq i)} \right]^{I(\gamma_{ij}^f=l)I_{obs}(\gamma_{ij}^f)} \\ \mathbf{m}_f &\sim \text{Dirichlet}(\alpha_{f0}, \dots, \alpha_{fL_f}) \\ \mathbf{u}_f &\sim \text{Dirichlet}(\beta_{f0}, \dots, \beta_{fL_f}). \\ Z_j \mid \pi &= \begin{cases} \frac{1}{n_1} \pi & z_j \leq n_1; \\ 1 - \pi & z_j = n_1 + j \end{cases} \end{aligned}$$

$$\pi \sim \text{Beta}(\alpha_\pi, \beta_\pi)$$

3.2 Gibbs Sampler

We work with the following factorization of the joint posterior distribution:

$$\begin{aligned} p(\mathbf{Z}, \Phi, \pi | \Gamma) &\propto \mathcal{L}(\mathbf{Z}, \Phi | \Gamma^{obs}) p(\mathbf{Z} | \pi) p(\Phi) p(\pi) \\ &\propto \prod_{j=1}^{n_2} \prod_{i=1}^{n_1} \left[\prod_{f=1}^F \prod_{l=1}^{L_f} m_{fl}^{I(Z_j=i)} u_{fl}^{I(Z_j \neq i)} \right]^{I(\gamma_{ij}^f=l) I_{obs}(\gamma_{ij}^f)} \\ &\times \prod_{f=1}^F \prod_{l=1}^{L_f} m_{fl}^{\alpha_{fl}-1} \times \prod_{f=1}^F \prod_{l=1}^{L_f} u_{fl}^{\beta_{fl}-1} \\ &\times \prod_{j=1}^{n_2} \left[I(Z_j \leq n_1) \frac{1}{n_1} \pi + I(Z_j > n_1) (1 - \pi) \right] \\ &\times \pi^{\alpha_\pi-1} (1 - \pi)^{\beta_\pi-1} \end{aligned}$$

This factorization leads to following Gibbs Sampler:

Sample $\Phi^{(s+1)} | \Gamma, \mathbf{Z}^{(s)}$: The \mathbf{m} and \mathbf{u} parameters are updated through standard multinomial-dirichlet mechanics. Thus we have

$$\mathbf{m}_f | \mathbf{Z}, \Gamma \sim \text{Dirichlet}(\alpha_{f1}(\mathbf{Z}), \dots, \alpha_{fL_f}(\mathbf{Z}))$$

$$\mathbf{u}_f | \mathbf{Z}, \Gamma \sim \text{Dirichlet}(\beta_{f1}(\mathbf{Z}), \dots, \beta_{fL_f}(\mathbf{Z}))$$

where $\alpha_{fl}(\mathbf{Z}) = \alpha_{fl} + \sum_{i,j} I_{obs}(\gamma_{ij}^f) I(\gamma_{ij}^f = l) I(z_j = i)$ and $\beta_{fl}(\mathbf{Z}) = \beta_{fl} + \sum_{i,j} I_{obs}(\gamma_{ij}^f) I(\gamma_{ij}^f = l) I(z_j \neq i)$.

Sample $\pi^{(s+1)} | \mathbf{Z}^{(s)}$: As a function of π , the linkage structure parameter \mathbf{Z} is sequence of successes (when $z_j < n_A + 1$) and failures (when $z_j = n_A + 1$), and therefore $p(\mathbf{Z} | \pi) = \mathcal{L}(\pi | \mathbf{Z})$ is determined only by the number of duplicates $n_{12}(\mathbf{Z}) = \sum_{i=1}^{n_2} I(z_j < n_1 + 1)$ encoded by \mathbf{Z} . Thus we have

$$\begin{aligned}
p(\pi|\mathbf{Z}) &\propto p(\mathbf{Z}|\pi)p(\pi) \\
&\propto \pi^{n_{12}(\mathbf{Z})}(1-\pi)^{n_2-(n_{12}(\mathbf{Z}))}\pi^{\alpha_\pi-1}(1-\pi)^{\beta_\pi-1} \\
&\propto \pi^{n_{12}(\mathbf{Z})+\alpha_\pi-1}(1-\pi)^{n_1-n_{12}(\mathbf{Z})+\beta_\pi-1} \\
&\implies \pi^{(s+1)}|\mathbf{Z}^{(s+1)} \sim \text{Beta}(D + \alpha_\pi, n_2 - n_{12}(\mathbf{Z}) + \beta_\pi)
\end{aligned}$$

Sample $\mathbf{Z}^{(s+1)}|\Gamma, \Phi^{(s+1)}, \pi^{(s+1)}$: Because we sample Z_j independently of all other $Z_{j'}$, we use only the full conditional for an individual Z_j . Let $\Gamma_{.j}$ denote the set of n_1 comparison vectors with $j \in \mathbf{X}_2$, and note that as a function of Z_j , the likelihood $p(\Gamma_{.j}|Z_j, \Phi) = \mathcal{L}(Z_j|\Gamma_{.j}, \Phi)$ is a discrete distribution with probabilities proportional to

$$\begin{aligned}
p(\Gamma_{.j}|Z_j = z_j, \Phi) &\propto \prod_{i=1}^{n_1} \left[\prod_{f=1}^F \prod_{l=1}^{L_f} m_{fl}^{I(Z_j=i)} u_{fl}^{I(Z_j \neq i)} \right]^{I(\gamma_{ij}^f=l)I_{obs}(\gamma_{ij}^f)} \\
&\propto \prod_{i=1}^{n_1} \left(\prod_{f=1}^F \prod_{l=1}^{L_f} \frac{m_{fl}}{u_{fl}} \right)^{I(z_j=i)I(\gamma_{ij}^f=l)I_{obs}(\gamma_{ij}^f)} \\
&= \begin{cases} w_{ij} & z_j \leq n_1; \\ 1 & z_j = n_1 + j \end{cases}
\end{aligned}$$

where $w_{ij} = \left(\frac{\prod_{f=1}^F \prod_{l=1}^{L_f} m_{fl}}{\prod_{f=1}^F \prod_{l=1}^{L_f} u_{fl}} \right)^{I(\gamma_{ij}^f=l)I_{obs}(\gamma_{ij}^f)} = \frac{P(\gamma_{ij}|Z_j=i)}{P(\gamma_{ij}|Z_j \neq i)}$. The interested reader should note that these are precisely the likelihood ratios used in the Fellegi-Sunter model to classify matches and non-matches, and we therefore refer to w_{ij} as the *Fellegi Sunter weights*.

With the likelihood in this form, we can derive the full conditional

$$\begin{aligned}
p(Z_j|\Gamma_{.j}, \Phi, \pi) &\propto p(\Gamma_{.j}|Z_j, \Phi)P(Z_j|\pi) \\
&\propto \left(\sum_{i=1}^{n_1} w_{ij} \mathbf{1}_{z_j=i} + \mathbf{1}_{z_j=n_1+1} \right) \left(\pi \sum_{i=1}^{n_1} \frac{1}{n_1} \mathbf{1}_{z_j=i} + (1-\pi) \mathbf{1}_{z_j=n_1+1} \right)
\end{aligned}$$

$$\begin{aligned}
&= \frac{\pi}{n_1} \sum_{i=1}^{n_1} w_{ij} \mathbf{1}_{z_j=i} + (1 - \pi) \mathbf{1}_{z_j=n_1+1} \\
\Rightarrow Z_j^{(s+1)} | \Phi, \Gamma, \pi &\propto \begin{cases} \frac{\pi}{n_1} w_{ij} & z_j \leq n_1; \\ 1 - \pi & z_j = n_1 + 1 \end{cases}
\end{aligned}$$

In order to make fair comparisons against the (Sadinle, 2017) model, we integrate over the posterior of π and rearrange terms to produce the final full conditional:

$$p\left(Z_j^{(s+1)} = i | \Phi, \mathbf{Z}^{(s)}\right) \propto \begin{cases} w_{ij} & i \leq n_1; \\ n_1 \frac{n_2 - n_{12}(\mathbf{Z}) + \beta_\pi}{n_{12}(\mathbf{Z}) + \alpha_\pi} & i = n_1 + 1 \end{cases}$$

3.3 Bayes Estimate

We calculate a Bayes estimate $\hat{\mathbf{Z}}$ for the linkage parameter \mathbf{Z} by assigning different positive losses to different types of errors, and minimizing posterior expected loss. We adopt the loss function proposed in Sadinle (2017), in which $\hat{Z}_j \in \{1, \dots, n_A + 1, R\}$, with R representing the option to leave the matching undetermined by the model. Specifically, we have

$$L(\hat{Z}_j, Z_j) = \begin{cases} 0 & \text{if } Z_j = \hat{Z}_j; \\ \theta_R, & \text{if } \hat{Z}_j = R; \\ \theta_{10}, & \text{if } Z_j \leq n_A, \hat{Z}_j = n_A + 1; \\ \theta_{01}, & \text{if } Z_j = n_A + 1, \hat{Z}_j \leq n_A; \\ \theta_{11}, & \text{if } Z_j, \hat{Z}_j \leq n_A, Z_j \neq \hat{Z}_j; \end{cases}$$

Here, θ_R is the loss from not making a decision on the linkage status, θ_{10} is the loss from a false non-match, θ_{01} is the loss from a false match, and θ_{11} is the loss from the special case of a false match in which the record has a true match other than the one estimated by the model.

We seek to minimize the posterior expected loss, given by $\mathbb{E}[L(\hat{\mathbf{Z}}, \mathbf{Z}) | \Gamma^{obs}] = \sum_{\mathbf{Z}} L(\hat{\mathbf{Z}}, \mathbf{Z}) P(\mathbf{Z} | \Gamma^{obs})$. In this paper, we adopt losses $\theta_R = \infty, \theta_{10} = 1, \theta_{01} = 1, \theta_{11} = 2$, inducing the intuitive decision rule

$$\hat{Z}_j = \begin{cases} i, & \text{if } P(Z_j = i|\Gamma) > \frac{1}{2}; \\ 0, & \text{otherwise;} \end{cases}$$

For a more in-depth explanation of this function and the induced Bayes estimate, see (Sadinle, 2017).

Since our Gibbs procedure does not strictly enforce one-to-one matching, it is possible for this Bayes estimate to link multiple records in \mathbf{X}_2 to one record in \mathbf{X}_1 . It is often desirable to see such matches, because they provide evidence of model misspecification; specifically, large numbers of “many to one” matches indicate that the assumption of no duplicates within files may not be reasonable. We will explore this issue more deeply through the El Salvador homicide case study.

To achieve a Bayes estimate that fulfills one-to-one matching requirement, we simply minimize the expected loss subject to the constraint that $\hat{Z}_j \neq \hat{Z}_{j'}$ for all $j \neq j'$. In the event that we have two records j and j' such that both $P(Z_j = i|\Gamma) > \frac{1}{2}$ and $P(Z_{j'} = i|\Gamma) > \frac{1}{2}$, this constraint means we accept the match with the highest posterior probability, and declare the other to have no match. A similar approach can be seen in the most probable maximal matching sets used by (Steorts, 2013) to match records to latent entities, and is justified within this Bayesian framework.

4 EFFICIENT AND SCALABLE IMPLEMENTATION

To increase the speed of our Gibbs sampler and expand the scale of the linkage tasks we can undertake, we employ hashing methods similar to those used by Enamorado et al. (2019) in the creation of **fastlink**, a fast and scalable implementation of the Fellegi Sunter method. The key insight is to recognize that record pairs contribute to posterior calculations only through the agreement pattern of the γ_{ij} vector. To make this more precise, let h_1, \dots, h_P denote the unique agreement patterns, collect these unique patterns in the set $\mathcal{P} = \{h_1, \dots, h_P\}$. Here, $P = |\mathcal{P}|$ is the total number of unique agreement patterns; observe that P is bounded above by $\prod_{f=1}^F L_f$, and that this bound does not depend on n_1 or n_2 . In this context, the integers $1, \dots, P$ serve as *hashed values* that encode the same information

as the original vectors themselves. Whenever possible, we conduct calculations over these P agreement patterns, instead of the typical $n_1 \times n_2$ record pairs.

Additionally, we store “one-hot encodings” of these patterns rather than the original Fellegi Sunter comparison vectors, to aid in vectorized computations.

4.1 Data Representation, Hashing, and Storage

First, we hash record pairs of the same agreement pattern to unique integer values. (Enamorado et al., 2019) accomplished this efficiently through the hashing function

$$h^*(i, j) = \sum_{f=1}^F I(\gamma_{ij}^f > 0) 2^{\gamma_{ij}^f + I(k>1) \sum_{e=1}^{k-1} (L_e - 1)}$$

This function maps each agreement pattern to a unique integer, allowing us to store a scalar quantity instead of an entire vector for each record pair. For computational ease, we then map these integers to sequential integers from $1, \dots, P$ corresponding to the enumerated patterns in \mathcal{P} . When the (i, j) pair exhibits the p^{th} pattern, we say $(i, j) \in h_p$.

With all record pairs converted to hashed values, we can create a more compact nested list

$$\mathcal{R} = \left\{ \{r_{jp}\}_{p=1}^P \right\}_{j=1}^{n_2}$$

where $r_{jp} = \{i \in \mathbf{X}_1 | (i, j) \in h_p\}$. This representation is useful because it allows us to easily compute sufficient statistics

$$H_{jp} = \sum_i I((i, j) \in h_p) = ||r_{jp}||$$

and

$$H_p = \sum_{i,j} I((i, j) \in h_p) = \sum_j H_{jp}$$

For convenience, denote this set of sufficient statistics $\mathcal{H} = \{\{H_{jp}\}, \{H_p\}\}$. As will be shown in Section 4.3, all posterior calculations are conducted through these sufficient statistics. Note that \mathcal{P} , \mathcal{R} , and \mathcal{H} fully characterize the comparison matrix Γ with no loss of information, so we proceed with $\tilde{\Gamma} = \{\mathcal{P}, \mathcal{R}, \mathcal{H}\}$ for our efficient posterior inference.

4.2 Working with Large Data

The hashing procedure described above considerably reduces the memory needed to store the comparison information. That is, instead of storing $n_1 \times n_2$ comparison vectors, we only store the P unique vectors, and then $n_1 \times n_2$ scalar quantities relating record pairs to those vectors. However, even storing these $n_1 \times n_2$ scalar labels can become burdensome with large data. Worse, the overwhelming majority of these labels relate to record pairs that are clear non-matches.

To address this issue, we propose a new method called *storage efficient indexing* (SEI). In standard indexing, one decides a priori certain criteria that they expect all true matching pairs to satisfy, and labels any record pairs that do not meet that criteria as non-matches. For example, one might only consider pairs with a certain similarity score on a field deemed to be important (like first name), or only pairs with exact matching on a specified number of fields. While generally chosen to be quite loose, establishing these criteria requires knowledge of the problem and invites room for human error.

With SEI however, we can reduce comparison space, and its associated storage costs, while avoiding these drawbacks. Observe that all records of the same agreement pattern have the same probability when sampling Z_j . Therefore we know that records inr_{j_p} such that H_{j_p} is large are very unlikely to be sampled consistently enough to be deemed a match through the Bayes estimate. We know this regardless of the form of the agreement pattern itself, or its associated probabilities. Therefore, rather than store all of these unlikely record labels, we choose to store only a small number S of them in a new nested listed \mathcal{R}^{SEI} . Rather than storing $n_1 \times n_2$ record labels, SEI allows us to store at most $n_2 \times P \times S$ labels, regardless of how large n_1 might be. Posterior calculations still attribute the appropriate weight to all records through the summary statistics in \mathcal{H} , and thus we can proceed with posterior inference through the memory reduced $\tilde{\Gamma}^{\text{SEI}} = \{\mathcal{P}, \mathcal{R}^{\text{SEI}}, \mathcal{H}\}$. For simplicity, we suppress “SEI” in future notation, and use $\tilde{\Gamma}$ without loss of generality.

Lastly, for large data, we can partition the two datasets \mathbf{X}_1 and \mathbf{X}_2 into smaller blocks $\{\mathbf{X}_{1m}\}$ and $\{\mathbf{X}_{2n}\}$ for more manageable computations. On a single machine, we can read-in data sequentially, conduct hashing, compress information through SEI, and delete the

original data from memory before continuing with the next chunk of data. With multiple cores or multiple machines, this can be done in parallel. Summary statistics from each pairwise chunk comparison can then be easily synthesized to recover sufficient statistics for the larger linkage task. Thus, the combination of hashing, SEI, and partitioning allows us to conduct linkage tasks over much larger datasets.

4.3 Efficient Posterior Inference

Sample $\Phi^{(s+1)}|\tilde{\Gamma}, \mathbf{Z}^{(s)}$: Calculated at the level of the record pairs, updating $\alpha_{fl}(\mathbf{Z})$ and $\beta_{fl}(\mathbf{Z})$ for each field and level in the linkage task constitutes $2 \times \sum L_f$ many summations over $n_A \times n_B$ quantities. These are simple calculations, but become computationally burdensome when working on large linkage tasks.

Instead, we use one-hot encodings of the agreement patterns \mathcal{P} for more efficient calculations. Denote $H_p^m = \sum_{j=1}^{n_B} \mathbf{1}_{(Z_j, j) \in h_p}$ to be the number of matching record pairs with agreement pattern p . We can also easily calculate the number of nonmatching record pairs with agreement pattern p as $H_p^u = H_p - H_p^m$. Then, if α_0 and β_0 are vectors of prior parameters for the \mathbf{m} and \mathbf{u} distributions respectively, the posterior update becomes simply

$$\begin{aligned}\alpha(\mathbf{Z}) &= \alpha_0 + \sum_{p=1}^P H_p^m \times h_p \\ \beta(\mathbf{Z}) &= \beta_0 + \sum_{p=1}^P H_p^u \times h_p\end{aligned}$$

Note that these constitute P many summations over n_B quantities, and thus avoid the $n_A \times n_B$ summation from the original method.

Sample $\mathbf{Z}^{(s+1)}|\tilde{\Gamma}, \Phi^{(s+1)}$: Although sampling Z_j from a the full conditional provided earlier is conceptually straightforward, it becomes computational burdensome when n_1 is large. This is because sampling a value from n_1 many options with unequal weights requires normalizing the weights to probabilities, which has a computational cost that scales with n_1 . To speed up computation, we break this sampling step into two simpler steps. First, we calculate the Fellegi Sunter weight w_p associated with each unique pattern and sample the agreement pattern between j and its potential match. Second, we sample the record label

uniformly among records associated with that agreement pattern for that particular $j \in B$. More concretely, define $h(Z_j)$ to be the agreement pattern between j and its potential match, and say $h(Z_j) = h_{P+1}$ when $Z_j = n_A + 1$. Then,

$$P\left(h\left(Z_j^{(s+1)}\right) = p \mid \Phi, \mathbf{Z}^{(s)}\right) \propto \begin{cases} w_p \times H_{j_p} & p \leq P; \\ n_A \frac{n_B - D + \beta_\lambda}{D + \alpha_\lambda} & p = P + 1 \end{cases}$$

$$P\left(Z_j^{(s+1)} = i \mid h\left(Z_j^{(s+1)}\right) = p\right) \begin{cases} \frac{1}{H_{j_p}} & (i, j) \in h_p \\ 0 & \text{otherwise} \end{cases}$$

Lastly, we recognize that all posterior updates are governed by the agreement patterns of the record pairs rather than the record labels themselves. Thus we complete the entire Gibbs procedure first at the level of the P agreement patterns with the first equation above. After all Gibbs iterations are complete, we can back-fill the records corresponding to the agreement patterns through the second equation.

We emphasize the computational gains of this split sampler: the first step is a sample from P many options, where P does not scale with the size of the linkage task; and the second step is sampling uniformly at random, which is computationally simple even for large sets of candidate records. These changes in themselves drastically improves the speed of the sampler, and each can be parallelized if desired for additional computational gains.

To aid the reader, we provide summary of the **fabl** method through pseudocode:

4.4 Computational Complexity

The computational complexity of **fabl** is determined by its two steps: constructing comparison vectors and Gibbs sampling. The computational complexity of all pairwise comparisons across files \mathbf{X}_1 and \mathbf{X}_2 is $O(Fn_1n_2)$. Since **fabl** is able to compute these comparisons in parallel, we can split these computations across B equally sized partitions, so the complexity becomes $O(\frac{F}{B}n_1n_2)$.

Without hashing, the computational complexity of updating the \mathbf{m} and \mathbf{u} parameters is $O(Fn_1n_2)$. However, by doing calculations over the agreement patterns rather than the individual record, hashing reduces the complexity to $O(FP)$.

Algorithm 1 Summary of fabl algorithm

```
1: procedure HASHING AND PREPROCESSING
2:   Partition files  $A$  and  $B$  into chunks  $\{A_I\}, \{B_J\}$ 
3:   for each  $I, J$  do
4:     Create comparison vectors between  $A_I$  and  $B_J$ 
5:     Hash results and calculate summary statistics
6:     Use SEI to reduce memory usage
7:   end for
8:   Synthesize results across pairings
9: end procedure
10: procedure GIBBS SAMPLING
11:   Initialize  $m, u$ , and  $Z$  parameters
12:   for  $t \in \{1, \dots, T\}$  do
13:     Sample  $m^{t+1}|Z^t, \Gamma$  and  $u^{t+1}|Z^t, \Gamma$ 
14:     Sample  $H(Z^{t+1})|m^{t+1}, u^{t+1}, \Gamma$   $\triangleright$  Sample agreement pattern, not record
15:   end for
16:   Sample  $Z|H(Z), \Gamma$   $\triangleright$  Fills in record label based on agreement pattern
17: end procedure
```

The complexity of updating Z sequentially at the record level is $O(n_1 n_2)$. With hashing, we split this sampling into two steps; first we sample that agreement pattern of the match with complexity $O(n_2 P)$, and then we sample the record that exhibits that pattern with complexity $O(n_2)$. Thus we have reduced the complexity of the Gibbs sampler under BRL from $O(F n_1 n_2)$ to $O(n_2 P)$.

Overall, the computational complexity under the complete **fabl** framework is $O(\frac{F}{B} n_1 n_2) + O(n_2 P)$.

5 SIMULATION STUDIES

In this section, we replicate a simulation study from Sadinle (2017) to compare **fabl** against BRL on several simulated datasets with varying amounts of error and overlap. We use first name, last name, age, and occupation for this linkage, and create comparison vectors according to the default settings of the `compareRecords` function from the BRL package. See Table 1 for details on the construction of comparison vectors. Each simulation identifies duplicated individuals between two datasets, each with 500 records. We conduct linkage when matching records exhibit 1, 2, and 3 errors across the four fields, and when there are 50, 250, and 450 individuals in common across datasets. We use flat priors for all m and u parameters, run the Gibbs Sampler for 1000 iterations, and discard the first 100 as burn-in.

		Level of Disagreement			
		1	2	3	4
Fields	Similarity				
First and Last Name	Levenstein	0	(0, .25]	(.25, .5]	(.5, 1]
Age and Occupation	Binary	Agree	Disagree		

Table 1: Construction of comparison vectors for accuracy study with simulated datasets

5.1 Precision, Recall, and F-measure

In this section, we compare **fabl** to BRL in terms of precision, recall, and f-measure, which are commonly defined record linkage evaluation metrics that are defined in (Christen, 2012). In cases when there are only one or two errors in matching records, and in cases with low to moderate duplication across records, we see that **fabl** provides approximately equivalent accuracy as BRL. We find that our method only has weakened performance in the most extreme scenario of very high errors and very high overlap across files. In these situations, BRL is removing large numbers of records from consideration throughout the Gibbs Sampler, making its implementation most different from **fabl**. However, such extreme linkage tasks, which such high amounts of errors and overlap, are extremely rare in practice.

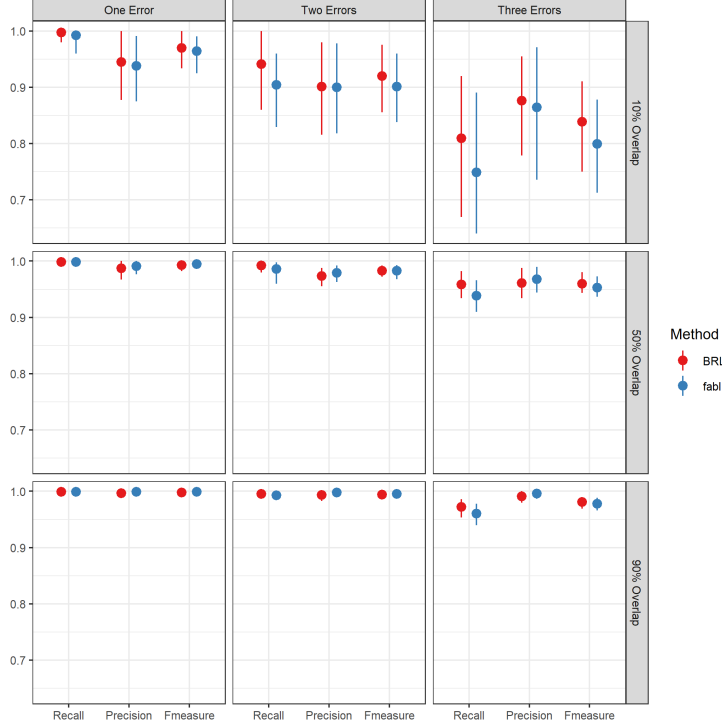


Figure 1: Posterior means and credible intervals for accuracy metrics under the replication of simulation study from Sadinle (2017). For each level of overlap and each level of error, we have 100 paired sets of 500 records.

5.2 Accuracy under Partial Estimates

Lastly, we review the performance of **fabl** and **BRL** using loss functions that allow partial estimates of the linkage parameter. By leaving $\theta_{10} = \theta_{01} = 1$ and $\theta_{11} = 2$, but setting $\theta_R = 0.1$, we allow the model to decline to decide a match for certain records, with nonassignment being 10% as costly as a false match. In this context, we are no longer focused on finding all true matches, but rather protecting against false matches. Thus, instead of recall, we use the *negative predictive value* (NPV), defined as the proportion of non-links that are actual non-matches. Mathematically, $NPV = \sum_{j=1}^{n_2} I(\hat{Z}_j = Z_j = n_1 + j) / \sum_{j=1}^{n_2} I(\hat{Z}_j = n_1 + j)$. We continue to use the precision, which is renamed the *positive predictive value* in this context. Lastly, we also report that rejection rate (RR), or how often the model declines to make a linkage decision, defined as $RR = \sum_{j=1}^{n_2} I(\hat{Z}_j = R)$.

We see that **fabl** maintains equivalently strong PPV as **BRL** across all linkage settings. However, with high amounts of overlap and high amounts of error, the rejection rate under **fabl** rises, leading to a decrease in NPV. This is reasonable because large numbers of errors lead to situations where one record in \mathbf{X}_2 has multiple plausible matches in \mathbf{X}_1 , so that posterior match probability is split across more records. Since **BRL** removes previously matched records from the set of available records for a new match, it is able to retain higher confidence in matches. In practice, this partial estimate approach is not often used, so we remain confident in **fabl**'s performance. If one wishes to use partial estimates, **fabl** will possibly leave more linkages for the modeller to match by hand that would be left under **BRL**, but the decisions made by each method will have nearly equal accuracy.

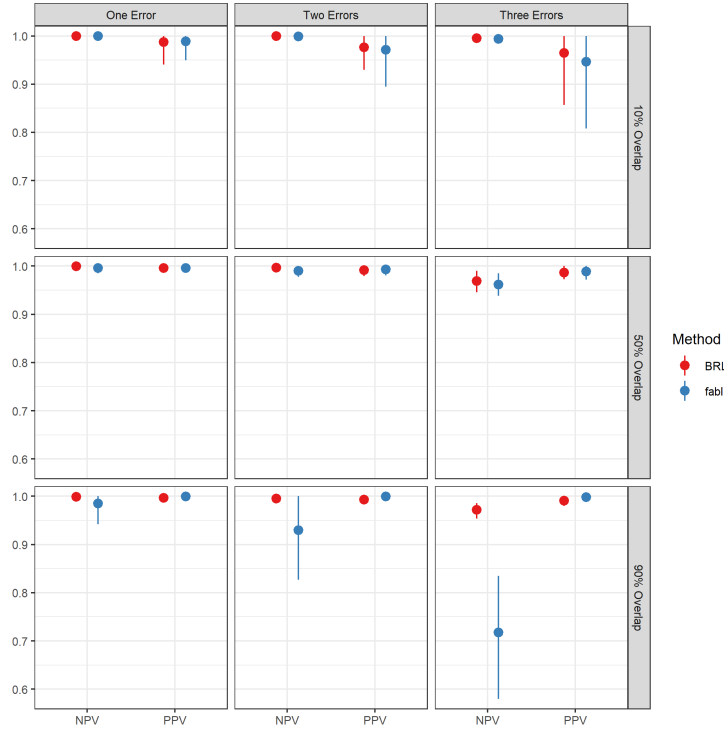


Figure 2: Negative predictive value (NPV) and positive predictive value (PPV) on simulated datasets

5.3 Speed

To demonstrate speed, we generate comparison vectors from pre-specified distributions so that we can easily increase the size of the linkage problem. Distributions are meant to emulate the behavior of similarity scores across first name, last name, and day, month. For example, $u^{\text{month}, 1} = P(\text{Records have same birth-month} \mid \text{Nonmatch}) = \frac{1}{12}$. For simplicity, we consider only exact matching, so a vector $(1, 0)$ corresponds to agreement and $(0, 1)$ to disagreement. We simulate these data for different values of n_A and n_B , and compare the run-time of **fabl** against **BRL**. Note that the number of unique patterns P is bounded above by $2^5 = 32$, a bound which is consistently attained in the larger simulations.

We see that at low data size, **BRL** outperforms, but that **fabl** is significantly faster at handling larger data. In particular, run-time for **BRL** seems to grow quadratically (or linearly with the size of both A and B) while run-time for **fabl** seems to grow linearly (in the size of B).

	m	u
fname	$(\frac{19}{20}, \frac{1}{20})$	$(\frac{1}{100}, \frac{99}{100})$
lname	$(\frac{19}{20}, \frac{1}{20})$	$(\frac{1}{100}, \frac{99}{100})$
day	$(\frac{19}{20}, \frac{1}{20})$	$(\frac{1}{30}, \frac{29}{30})$
month	$(\frac{19}{20}, \frac{1}{20})$	$(\frac{1}{12}, \frac{11}{12})$
year	$(\frac{19}{20}, \frac{1}{20})$	$(\frac{1}{12}, \frac{11}{12})$

Table 2: Distributions used for m and u probabilities in simulation studies

The above discussion suggests that for fixed n_B , computation time should remain mostly constant with growing n_A . Simulation study suggests that this is true. In the plot below, fixing $n_B = 500$, we see linear growth for the run-time under **BRL** as n_A increases, with much more static run-time under **fabl**. The slight increases in run-time that we do see are due primarily to the hashing step, which again can be run in parallel for large data.

We note here that **BRL** is coded in C, which makes for unfair comparison against **fabl**, currently only built in R. Additionally, although **fabl** is amenable to parallelization, this simulation was run on a single core. Running **fabl** in C++ with parallelization for the

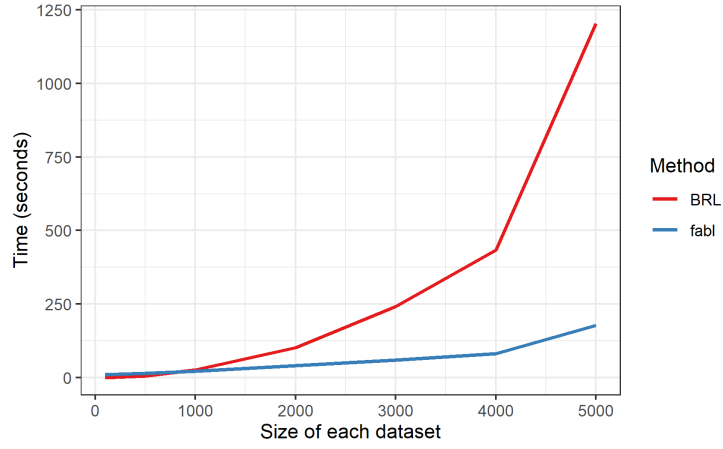


Figure 3: Run-time for BRL and fabl to run 1000 Gibbs iterations, including hashing step for fabl, for increasing values of both n_A and n_B . We see near quadratic growth in runtime for BRL, and near linear growth for fabl.

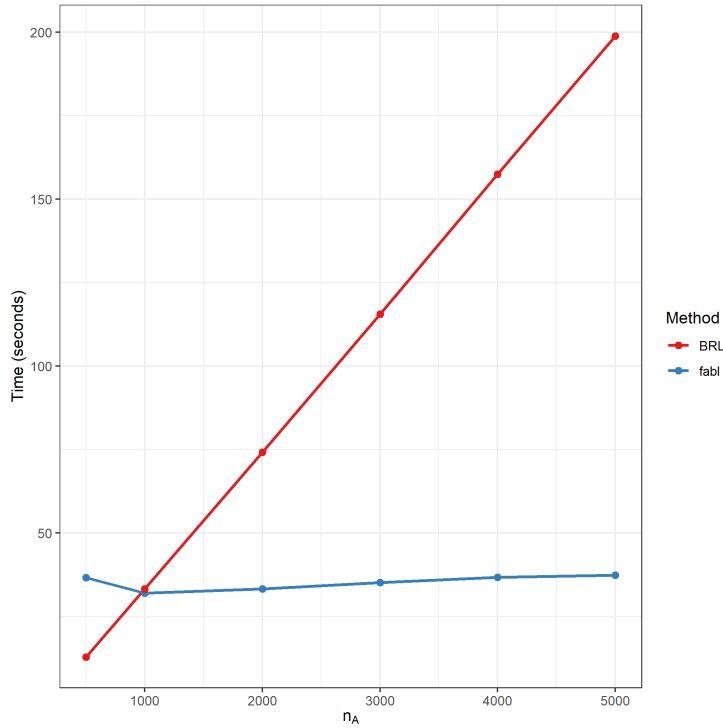


Figure 4: Run-time for BRL and fabl to run 1000 Gibbs iterations, including hashing step for fabl, with increasing n_A , and n_B fixed at 500. We see linear growth in runtime for BRL, and near constant runtime for fabl.

hashing step and sampling the matching status of the record pairs should lead to even more computational gains.

5.4 Scaling to a Larger Simulation Study

In this section, we investigate scaling to larger data sets using our proposed methodology.

Specifically, we demonstrate how partitioning and hashing the data through `fabl` method allows us undertake significantly larger linkage tasks. We concatenate two sets of 40 simulated datasets from the original simulation studies of to create two larger files, each of 20,000 records (40,000 records total). Under standard Fellegi Sunter procedures, this would require 400,000,000 comparison vectors, each consisting for four integers, resulting a final comparison matrix about 6.4 GB in size. Under default settings on a personal computer, R does not allow storing an object this size, so BRL is not usable on this linkage task. Through `fabl` however, using just one machine, we sequentially compare records across chunks, hash results, and then synthesize summary statistics for the entire simulation.

For simplicity, we partition one dataset into 20 smaller chunks, and leave the second dataset fully intact. We compare records, hash results, and then synthesize summary statistics for all 20 chunk comparisons. The resulting data object is now only 90 MB, about 1% the size of the object required under the standard method. Executed sequentially, these comparisons and the Gibbs sampler take about one hour to run. However, this could be substantially sped up using distributed computing.

Turning to evaluation metrics, this simulation achieved 96.5% recall and 97.7% precision, with an overall F-measure of 97.1% F-measure. The reader will note that this slightly worse performance than witnessed in the smaller simulation studies; this is expected because it is naturally more difficult to link more files with the same amount of information. With more linkage fields `fabl` maintains the high accuracy seen above.

6 APPLICATION TO CIVILIAN CASUALTIES FROM THE EL SALVADORAN CIVIL WAR

In this section, we revisit an application to the El Salvadoran Civil War, where we estimate the number of individuals recorded in each dataset. Though the data files used here are small, this study shows how the computational complexity of `fabl` depends on the number of unique agreement patterns found in the data, and how significant computational gains can be achieved by simplifying the construction of the comparison vectors. This case study also considers the ramifications of independently sampling Z_j rather than strictly enforcing one-to-one matching as done by BRL.

6.1 El Salvadoran Civil War

The country of El Salvador was immersed in civil war from 1980 to 1991, and throughout the time, several organizations attempted to document casualties of the conflict. When estimating the total number of casualties, one cannot simply sum the numbers recorded by each organization, as it is likely that the same individuals are recorded in multiple casualty lists. This is an important step in estimating the total number of deaths from a conflict using multiple systems estimation (Lum et al., 2013). Thanks to the Human Rights Data Analysis Group (HRDAG), we utilize two different sources, namely, El Rescate - Tutela Regal (ERTL) and the Salvadoran Human Rights Commission (CDHES, by its acronym in Spanish). The ERTL dataset consists of digitized denunciations that had been published throughout the conflict, and additional investigation was required before the ERTL recorded them as human rights abuses, giving us confidence in its accuracy Howland (2008). The CDHES dataset consists of casualties that had been reported directly to the organization, and later digitized; since reports were taken soon after the events occurred, this dataset is also thought to be fairly reliable. Ball (2000).

There are several challenges with working with such data. Firstly, both datasets have been automatically digitized, which inherently leads to some degree of typographical error. Secondly, the CDHES records are all second hand accounts reported by individuals, which

Fields	Similarity	Level of Disagreement			
		1	2	3	4
First and Last Name	Modified Levenstein	0	(0, .25]	(.25, .5]	(5, 1]
Year of Death	Absolute Difference	0	1	2	3+
Month of Death	Absolute Difference	0	1	2-3	4+
Day of Death	Absolute Difference	0	1-2	3-7	8+
Municipality	Binary	Agree	Disagree		

Table 3: Construction of comparison vectors for El Salvador data resembling original implementation from (Sadinle, 2018). This set up leads to 2048 possible agreement patterns in total

can result in additional errors. Lastly, the only fields recorded are given name, last name, date of death, and place of death; it is relatively common for a parent and child to share the same given name, resulting in indistinguishable records for two different individuals. This last point nearly breaks the earlier mentioned assumption that there are no duplicates within files, and reveals a key difference between BRL and our proposed method.

In this paper, we utilize records that have non-missing entries for given and last name, which results in $n_1 = 4420$ files in CHDES and $n_2 = 1323$ files in ERTL. We standardized names to account for common misspellings in the Spanish language. The string distance used is a modified Levenstein distance to account for the fact that second names are often omitted. Place of death is recorded by municipality and department within that municipality; however, since department was missing in 95% of records in CHDES and 80% of records in ERTL, this was excluded from our analyses. Thus, we conduct record linkage using given name, last name, municipality, and day, month, and year of death. We again use flat priors for the \mathbf{m} and \mathbf{u} parameters. To our knowledge, we have followed the same guidelines/settings in Sadinle (2017).

To mirror the original implementation of Sadinle (2017), we construct the comparison vectors using four levels of agreement for each field, according to the thresholds provided in Table 3. Gibbs sampling for these comparison vectors took 422 seconds for our proposed

Fields	Similarity	Level of Disagreement		
		1	2	3
First and Last Name	Modified Levenstein	0	(0, .25]	(.25, 1]
Year of Death	Binary	Agree	Disagree	
Month of Death	Binary	Agree	Disagree	
Day of Death	Absolute Difference	0	1	2+
Municipality	Binary	Agree	Disagree	

Table 4: Construction of comparison vectors for El Salvador for increased speed under **fabl**. This set up leads to 216 possible agreement patterns in total

method, **fabl**, and 240 for **BRL**. However, we observed that posterior distributions of several levels of the **m** and **u** parameters were nearly identical, and that of the $4^5 \times 2 = 2048$ possible agreement patterns, only 1173 are realized in the data. This leads us to believe that such high number of agreement levels creates unnecessary distinctions in the data and makes the comparison vectors less interpretable.

Therefore we re-ran our analysis with fewer agreement levels for each field according to Table 4, and obtained analogous results. With 216 possible agreement patterns, 159 were realized in the data, and our proposed method, **fabl** became much faster, finishing in 61 seconds. Meanwhile **BRL** took 239 seconds, relatively unchanged from the first implementation. This demonstrates the way that the computational complexity of our method depends on the number of unique agreement patterns, and how significant computational gains can be made by simplifying the construction of the comparison vectors. The estimates of the **m** parameters under each method are very similar, as shown in Figure 6.

Through **fabl**, we arrive at a Bayes estimate of 179 individuals recorded in both datasets. We calculate posterior samples of size of the overlap across files by summing the number of matches found in each iteration of the Gibbs sampler, and subtracting the number of matches that violate one-to-one matching. The posterior 95% credible interval for the overlap across files is (206, 238), indicating that the Bayes estimate is quite conservative. This is because there a large number of records in ERTL for which there are multiple plausible matches

in CDHES; `fabl` recognizes that a match exists among the several options, but is unable to definitely declare a specific pair a match in the Bayes estimate. We also compute a partial estimate of the linkage structure, using $\theta_{10} = \theta_{01} = 1$, $\theta_{11} = 2$, and $\theta_R = 0.1$ as in the simulation study. Here, the Bayes estimate provides 136 matches of which the model is quite confident, and 175 records to verify manually; this means that after clerical review, the number of individuals replicated across datasets would fall in the interval (136, 311), encapsulating the posterior credible interval. More or fewer records could be indentified for clerical review by decreasing or increasing θ_R .

We see similar results under BRL, with a Bayes estimate of 181 individuals recorded in both datasets, a posterior 95% credible interval of (211, 244), and a range of (140, 294) after the partial estimate and clerical review.

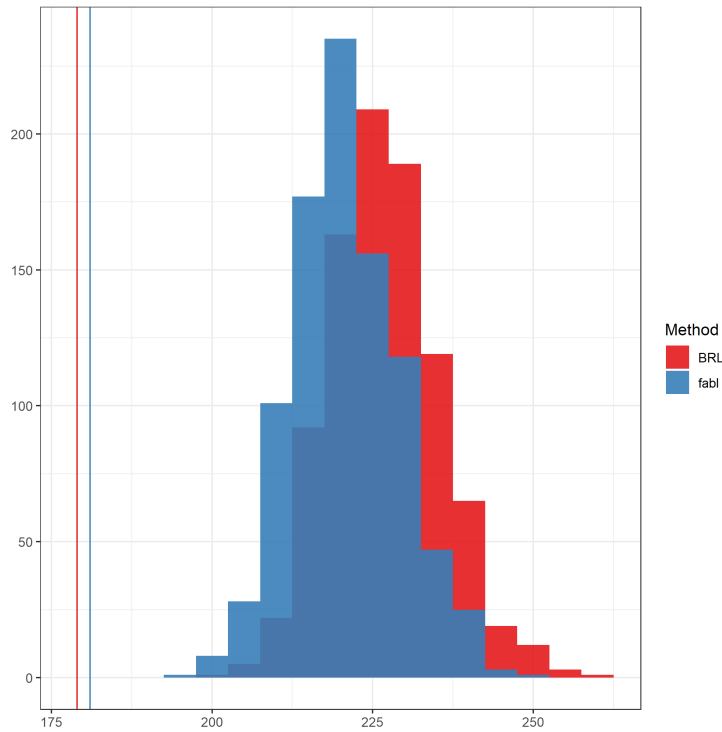


Figure 5: Posterior distribution and Bayes estimate of overlap across the two files. We note they are quite similar under both methods.

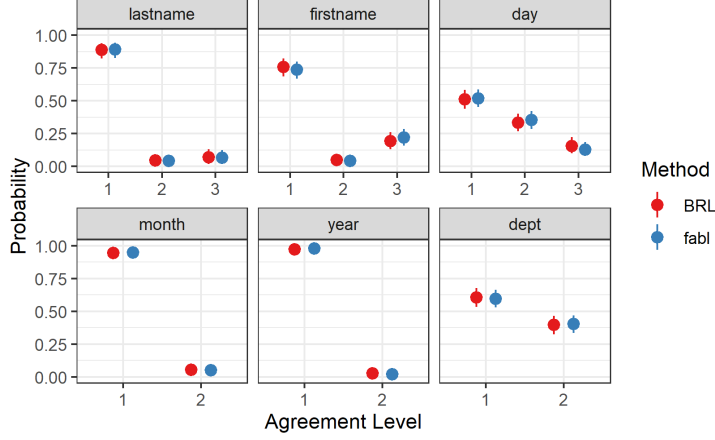


Figure 6: Posterior estimates of m parameters with 95% credible intervals. We note they are quite similar across the two methods.

Violations of One-to-One Matching As noted previously, the application exhibits many situations in which bipartite matching is difficult. To explore further, we calculate the number of matchings throughout the **fabl** Gibbs sampler that violate our one-to-one assumption, and find on average 26.17 matchings in violation. These matchings are impossible under the BRL Gibbs sampler, so examining these more closely can provide insight how each model handles situations in which one file in \mathbf{X}_1 has multiple plausible matches in \mathbf{X}_2 .

Figure ?? illustrates an example. Note that these records present a near violation of our assumption that there are no duplications within files; we continue to assume that records 825 and 826 in ERTL correspond to different individuals, but their records are nearly identical. In addition, using the modified Levenshtein distance, the comparison vectors $\gamma_{2776,825}$ and $\gamma_{2776,826}$ are exactly identical.

Figure 7 shows the values that Z_{825} and Z_{826} take on throughout the Gibbs sampler, and demonstrates how each method handles this situation. Under **fabl**, both records in \mathbf{X}_2 match to the same record in \mathbf{X}_1 throughout the Gibbs process, creating consistent violations of one-to-one matching. Under BRL, the Gibbs process creates one matching configuration and stays there for a while. However, if one pair “unmatches,” then the other record has a chance to latch on. Then, the Gibbs process is stuck with that matching status

Record Number	dataset	lastname	firstname	day	month	year	dept
825	CDHES	Pineda	Rosa	6	4	1984	NA
826	CDHES	Pineda	Rosa Maria	6	4	1984	NA
2776	ERTL	Pineda	Rosa Maria	4	4	1984	NA

Table 5: Example of linkage situation in which record 2776 in ERTL has multiple plausible matches in CDHES, leading to undesirable behavior both **fabl** and **BRL**.

for a while, resulting in a Gibbs process with poor mixing. In addition, **fabl** allows the modeler to inspect records with multiple plausible matches, and if they desire, to then choose the record pairing with the highest posterior probability. **BRL** in contrast, in strictly enforcing one-to-one matching throughout the sampler, can lead to situations where none of the plausible matches reach the threshold to be identified through the Bayes estimate. In short, we have pointed out why one may not wish to imbed this constraint in a model, and proposed a simple alternative that performs about the same as **BRL**, while scaling to much larger data sets.

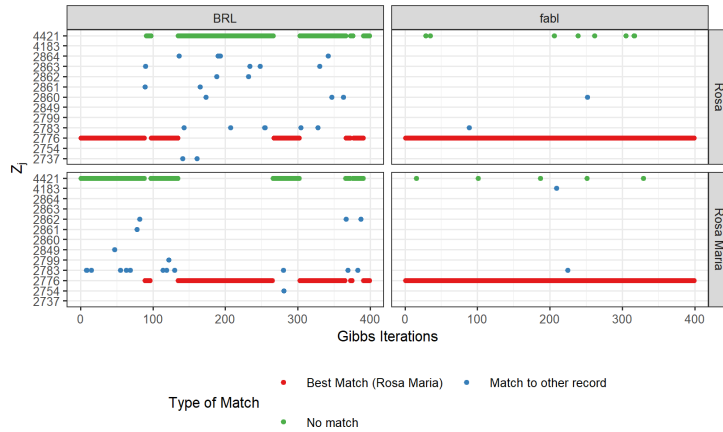


Figure 7: Gibbs sampling in situation with multiple plausible matches. Under **BRL**, two records in ERTL compete for their most similar record, splitting the posterior probability. Under **fabl**, both record consistently match with their most similar record, consistently violating one-to-one matching.

7 DISCUSSION

We have presented a method for Bayesian record linkage that is feasible for large datasets. In particular, our hashing procedure and model assumptions allow for a linkage procedure whose computational complexity does not scale with the size of the larger dataset, making this method particularly powerful in linking records when one datafile is substantially smaller than the other.

In our case study, we included an exploration of how to conduct record linkage when modeling assumptions are not met in practice. We explored “one-to-many” scenarios in which one record in A has multiple plausible matches in B , and showed how both **fabl** and **BRL** demonstrated undesirable qualities. Other issues arise under “many-to-one” scenarios, where one record in B has multiple plausible matches in A , and “many-to-many” scenarios in which there is duplication both across and within datasets. Tuning **fabl** for use in these scenarios is one potential avenue for future work.

8 APPENDIX

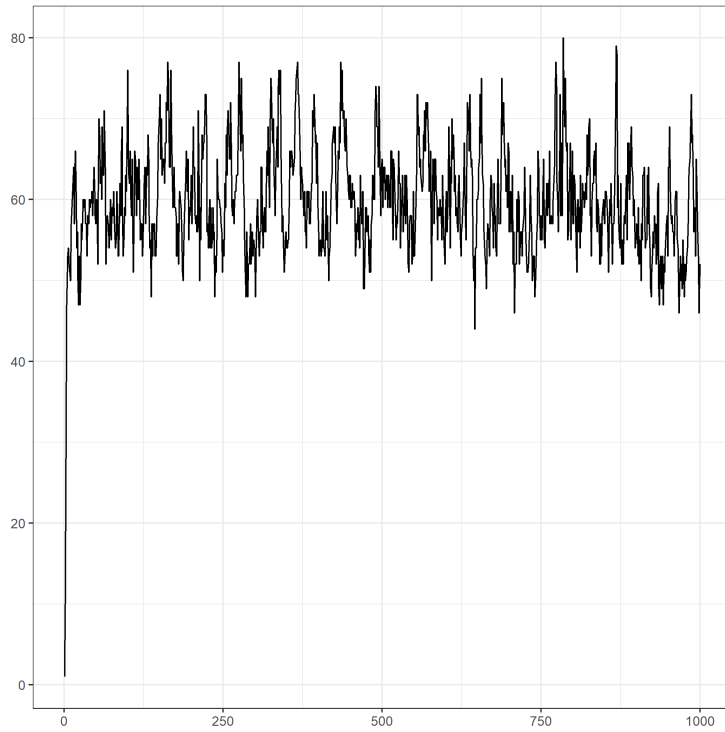


Figure 8: Representative traceplot of overlap between files from simulation study in 5.1

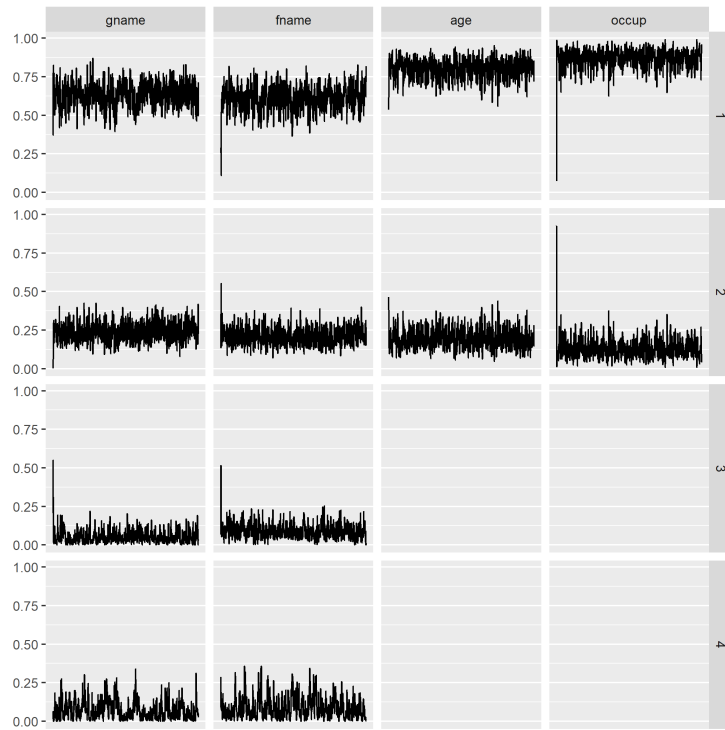


Figure 9: Representative traceplot of m parameter from simulation study in 5.1

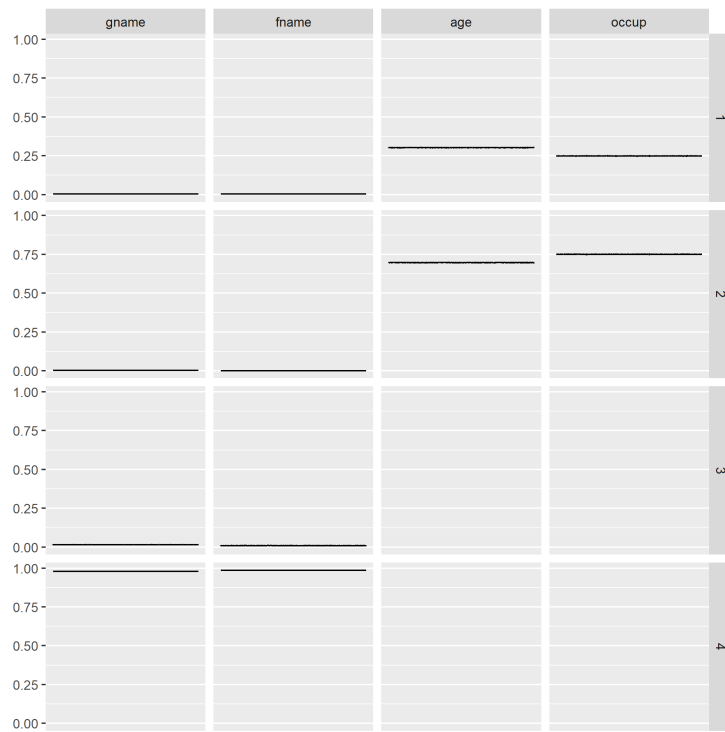


Figure 10: Representative traceplot of u parameters from simulation study in 5.1

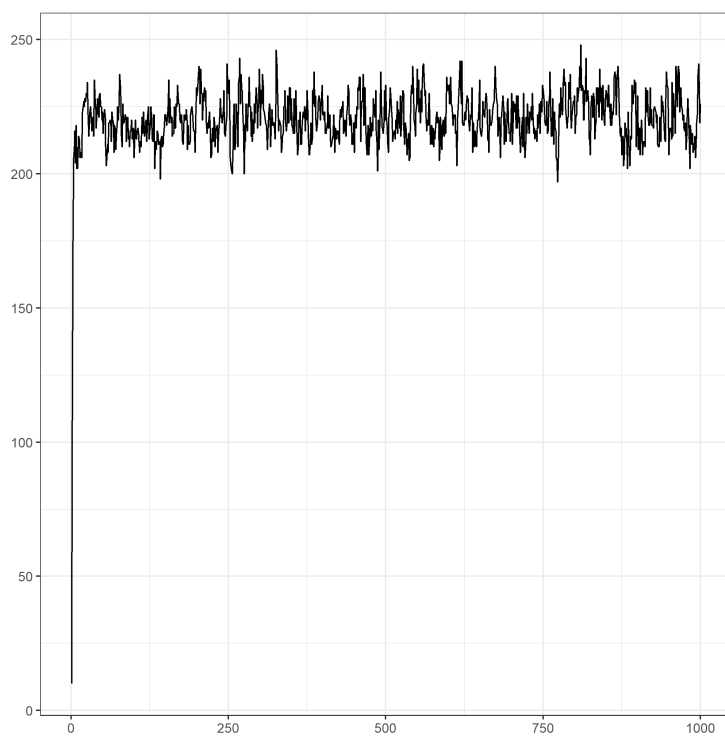


Figure 11: Traceplot for number of matches found across datasets in El Salvador case study

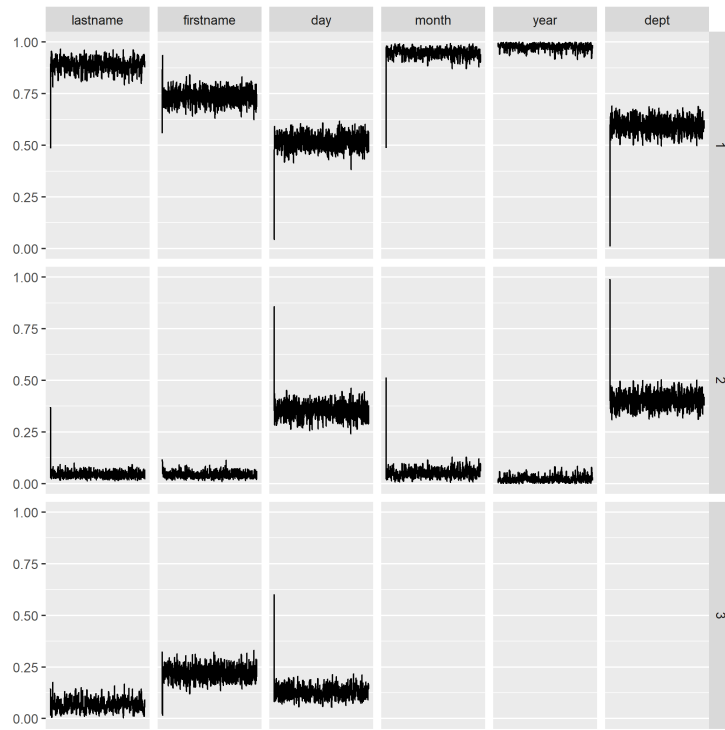


Figure 12: Traceplot for m parameter in El Salvador case study

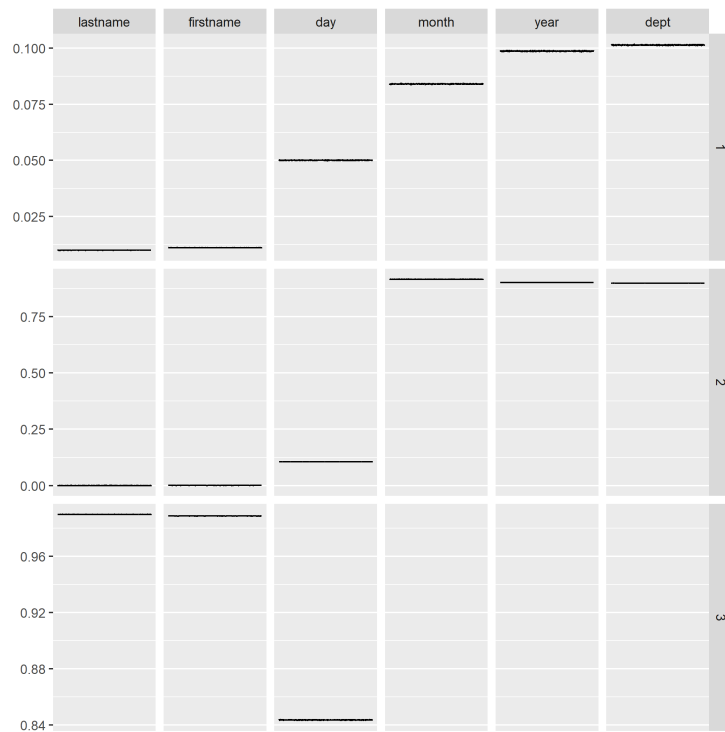


Figure 13: Traceplot for u parameter in El Salvador case study

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