A Distributed Hash Table for Shared Memory

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August 31, 2015

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- 2 Contribution 1: Resolving Hash Collisions
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Main challenge

Building a fast and CPU-efficient shared hash table:

- Minimal latency
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- Cheaper scalability
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Specialized algorithms and data structures needed!

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■ Contribution: Reducing roundtrips while CPU-efficient

High-performance Networking

Infiniband hardware

Specialized hardware used to construct high-performance networks:

- Comparable in price to Ethernet
- Supports bandwidths up to 100 Gb/s
- Direct access to memory via PCI-E bus

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Directly access to remote memory without invoking remote CPUs

- Zero-copy networking
- Kernel bypassing
- No participation from remote CPUs

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Performance: one-sided RDMA vs TCP

Roundtrips latency: $< 3\mu s$ (Infiniband) vs $60\mu s$ (traditional Ethernet)

Hash Table: Challenges

Notation: Hash table

 $T = \langle b_0, \dots, b_{n-1} \rangle$ as a sequence of buckets b_i , where:

- n the hash table size and m the number of used entries
- $\alpha = \frac{m}{n}$ the load factor

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Takes a data element d as parameter, and:

- if $d \in T$, return found
- if $d \notin T$, insert d and return inserted
- if $d \notin T$ and d cannot be inserted, return full

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Design: Challenges

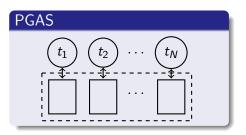
- How to *distribute* and access $T = \langle b_0, \dots, b_{n-1} \rangle$ efficiently?
- How to *design* find-or-put to perform efficiently?

PGAS: Partitioned Global Address Space

Details

Assuming *N* participating threads:

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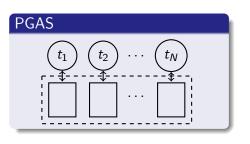


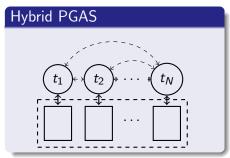
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Assuming *N* participating threads:

■ **PGAS:** shared + distributed memory model

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- **Hybrid PGAS:** PGAS + message passing (dashed edges)

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Efficiency: Resolving Hash Collisions

Occurs when h(x) = h(y) for data elements $x \neq y$

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- Nessie, 2014 (Cuckoo)
- FaRM, 2014 (Hopscotch)
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Best strategy for find-or-put

Which strategy requires the least number of roundtrips?



Chained Hashing

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- Dynamic mem. management
- Storing pointers

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- + Buckets are consecutive
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Linear Probing versus Hopscotch

- Due to Hopscotch invariant, lookups may be more expensive, but
- Inserts are arguably cheaper (amortized complexity)

Knuth, 1997

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$$\frac{1}{2}\Big(1+\frac{1}{(1-\alpha)^2}\Big)$$

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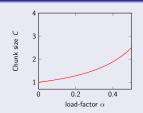
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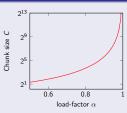
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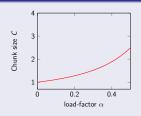
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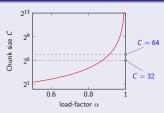


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Linear Probing: Hiding Latency

Contribution: Asynchronous queries

Before chunk iteration, first request the next chunk:

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Defining query-chunk(i, d)

Obtains the *i*-th chunk, starting from bucket $b_{h(d)}$

Returns a handle s

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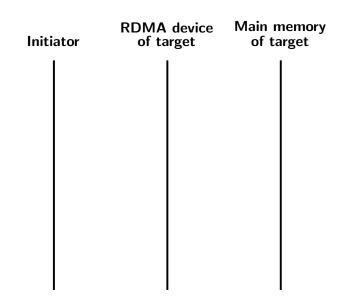
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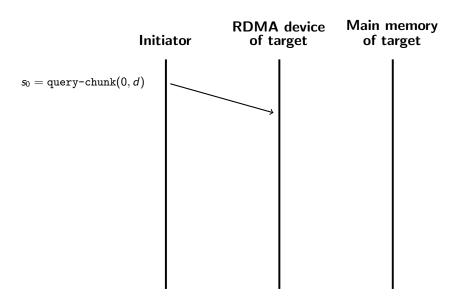
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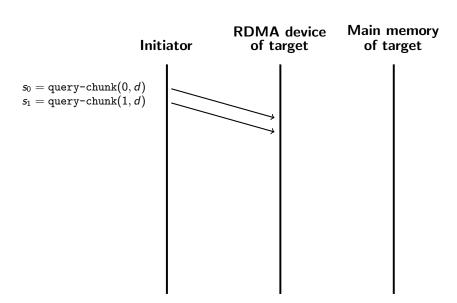
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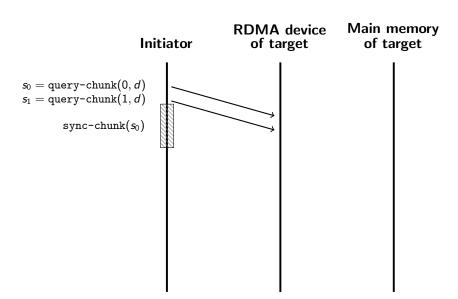
Defining sync-chunk(s)

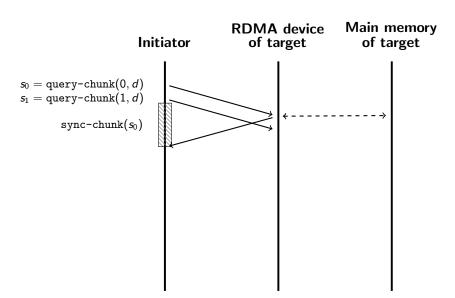
Takes a handle s as parameter, waits until the *corresponding* query has been completed.

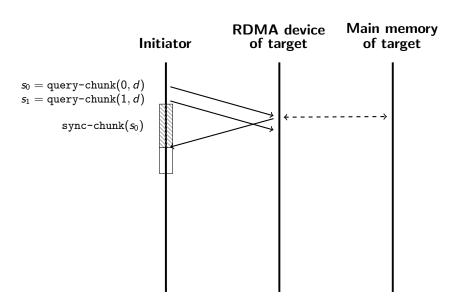


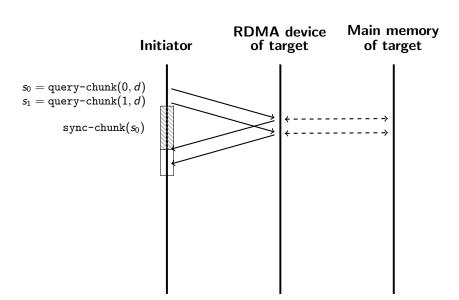


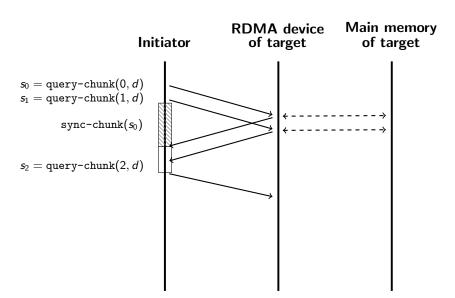


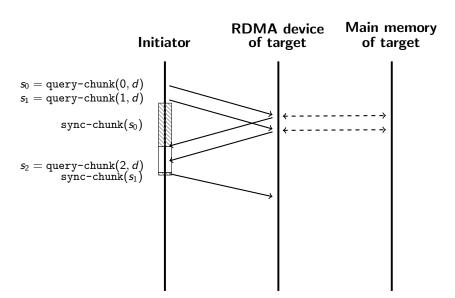


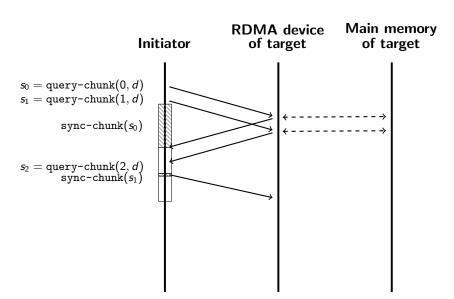












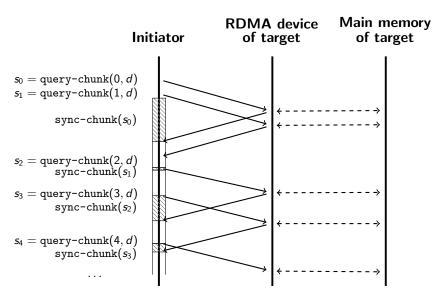


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Hash Table: Evaluation

Experimental Setup

All experiments have been perfored on the DAS-5 cluster:

- 66 machines
- 16 cores each (Intel E5-2630v3)
- 64 GB internal memory each
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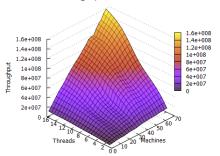
Benchmarks

Under different workloads, we measured:

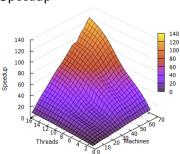
- Throughput of find-or-put
- Latency of find-or-put
- Roundtrips of find-or-put

Hash Table: Throughput

Total Throughput

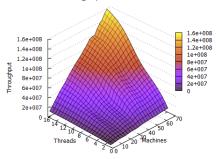


Speedup

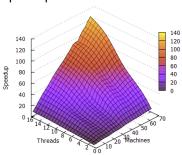


Hash Table: Throughput

Total Throughput



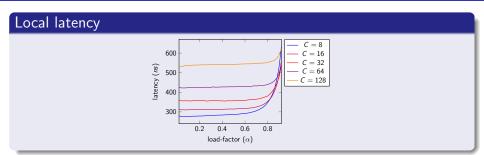
Speedup



Observations

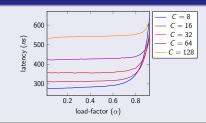
- Throughputs up to 140×10^6 reached (66 machines)
- Remote speedup up to 110 obtained
- Local throughput of 495×10^6 reached (1 threads)

Hash Table: Latency

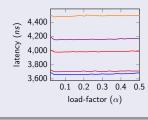


Hash Table: Latency

Local latency



Remote latency



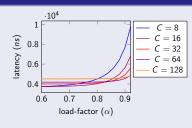


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Performance Indication

- FaRM: Inserts take $\sim 35 \mu s$
- Pilaf: Operations take $\sim 30 \mu s$
- Nessie: Inserts take $\sim 25 \mu s$

