

# Special Topics

# Types of machine learning

	Supervised Learning	Unsupervised Learning	Reinforcement Learning
Goal	<b>Predict</b> ...from examples	<b>Describe</b> ...structure in data	<b>Strategize</b> learn by trial and error
Data	$(x, y)$	$x$	delayed feedback
Types	<ul style="list-style-type: none"><li>• Classification</li><li>• Regression</li></ul>	<ul style="list-style-type: none"><li>• Density estimation</li><li>• Clustering</li><li>• Dimensionality reduction</li><li>• Anomaly detection</li></ul>	<ul style="list-style-type: none"><li>• Model-free learning</li><li>• Model-based learning</li></ul>

# Special Topics

Semi-supervised learning

Self-supervised learning

Other Practical Considerations

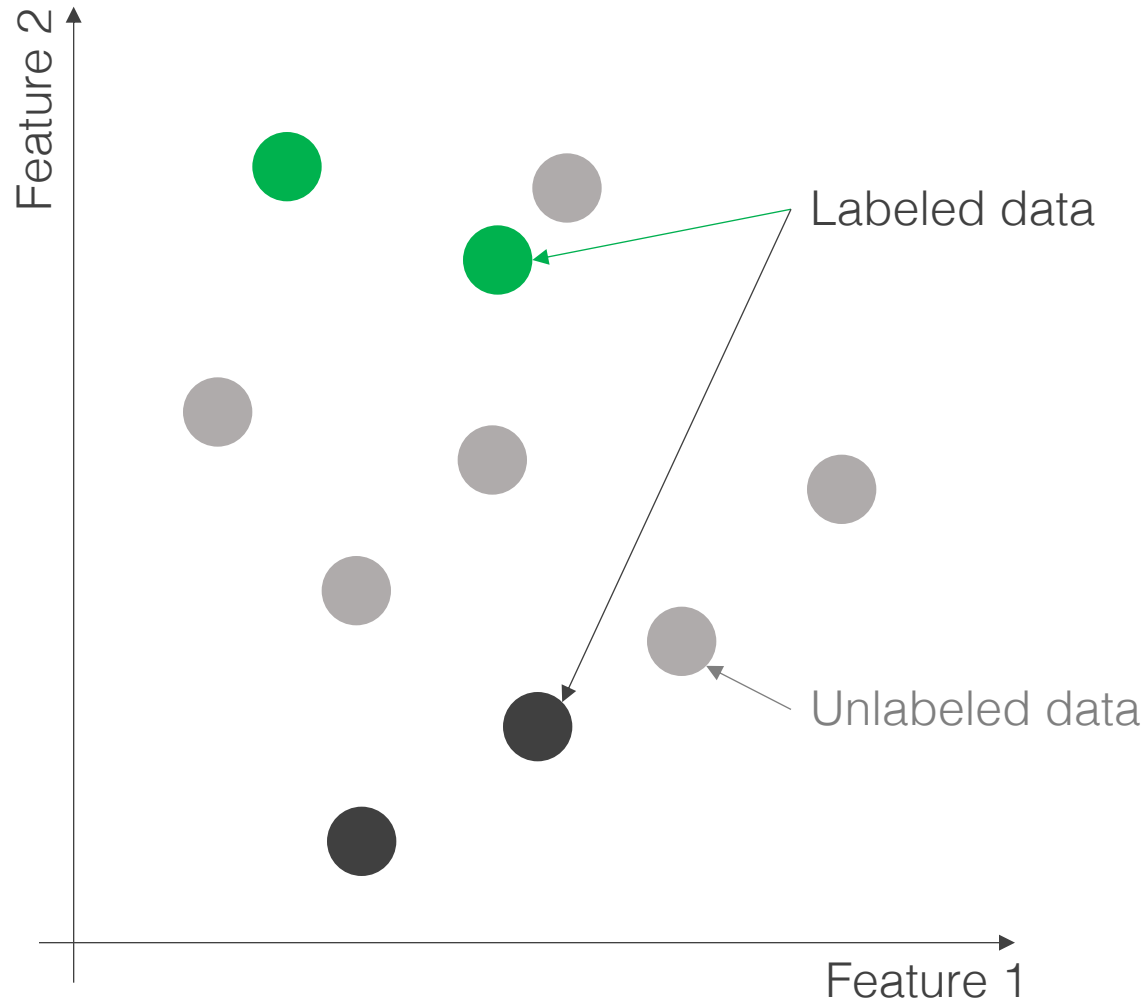
# Special Topics

**Semi-supervised learning**

Self-supervised learning

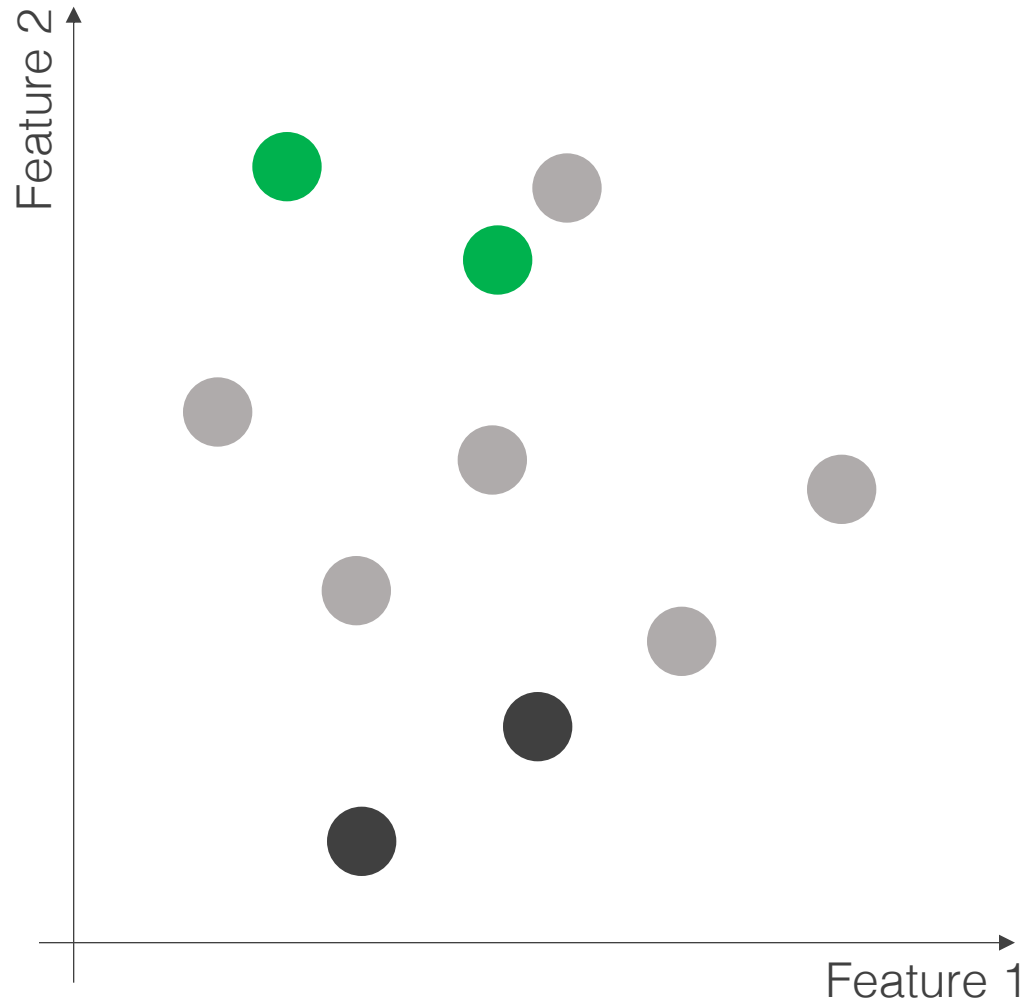
Other Practical Considerations

# Semi-supervised learning

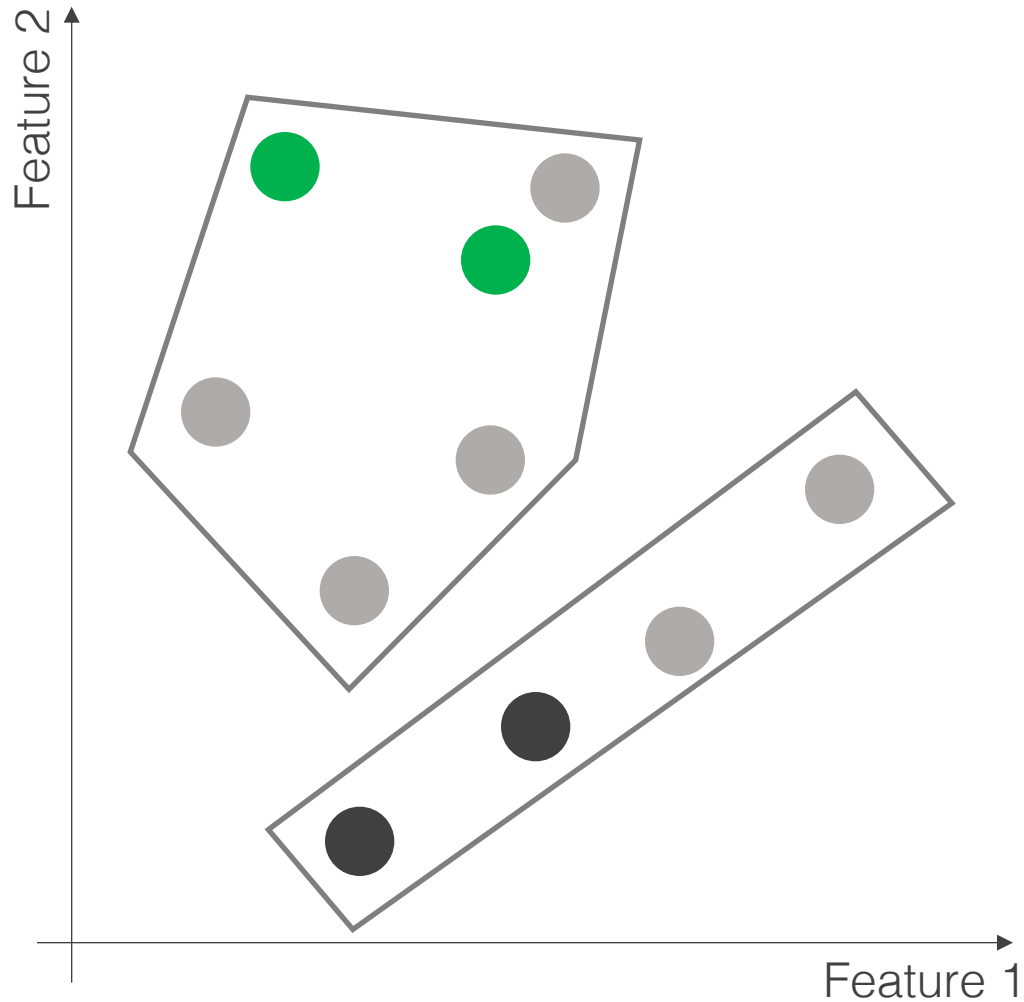


- Have a mix of labeled and unlabeled data
- Want to make predictions from a supervised learning model,  $\hat{f}(\mathbf{x})$
- Use BOTH the labeled AND unlabeled data for model training

# Semi-supervised learning: **label propagation**

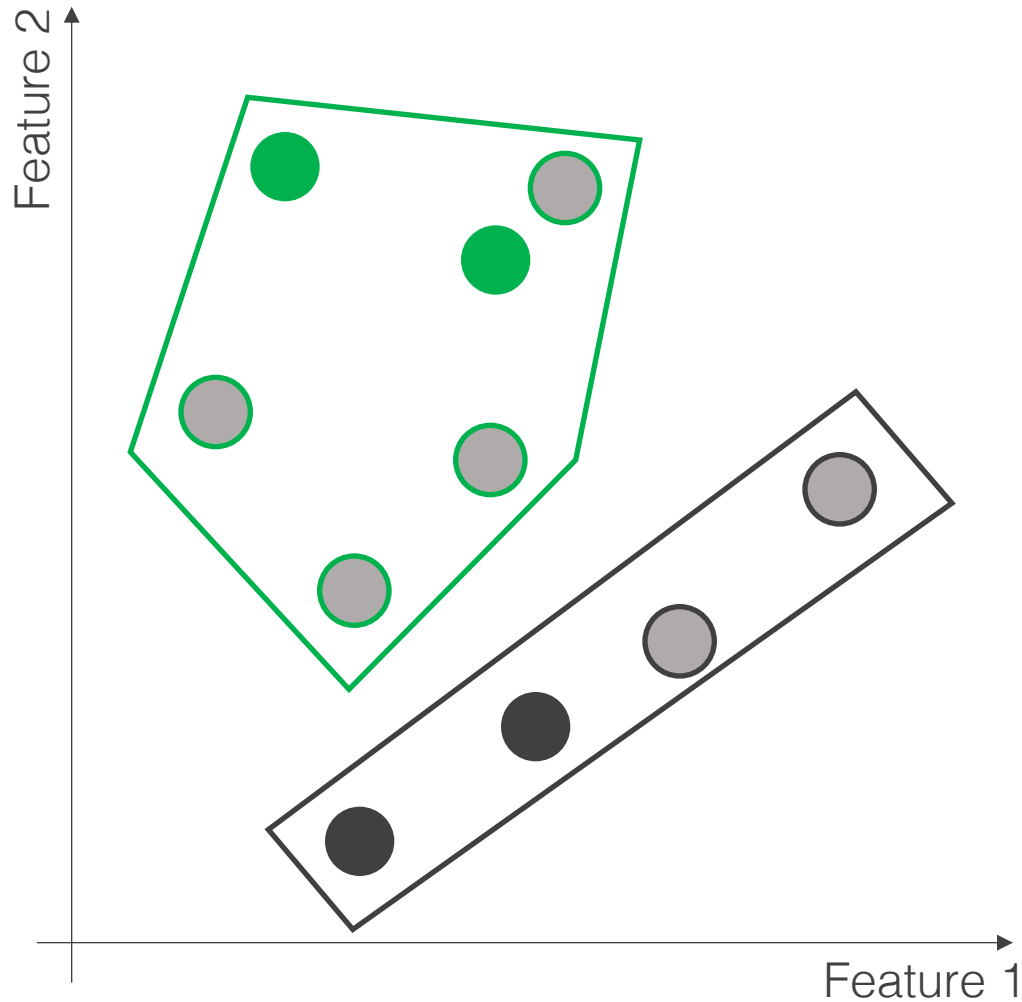


# Semi-supervised learning: **label propagation**



- 1 Cluster the data such that each cluster has at most one class of labeled data

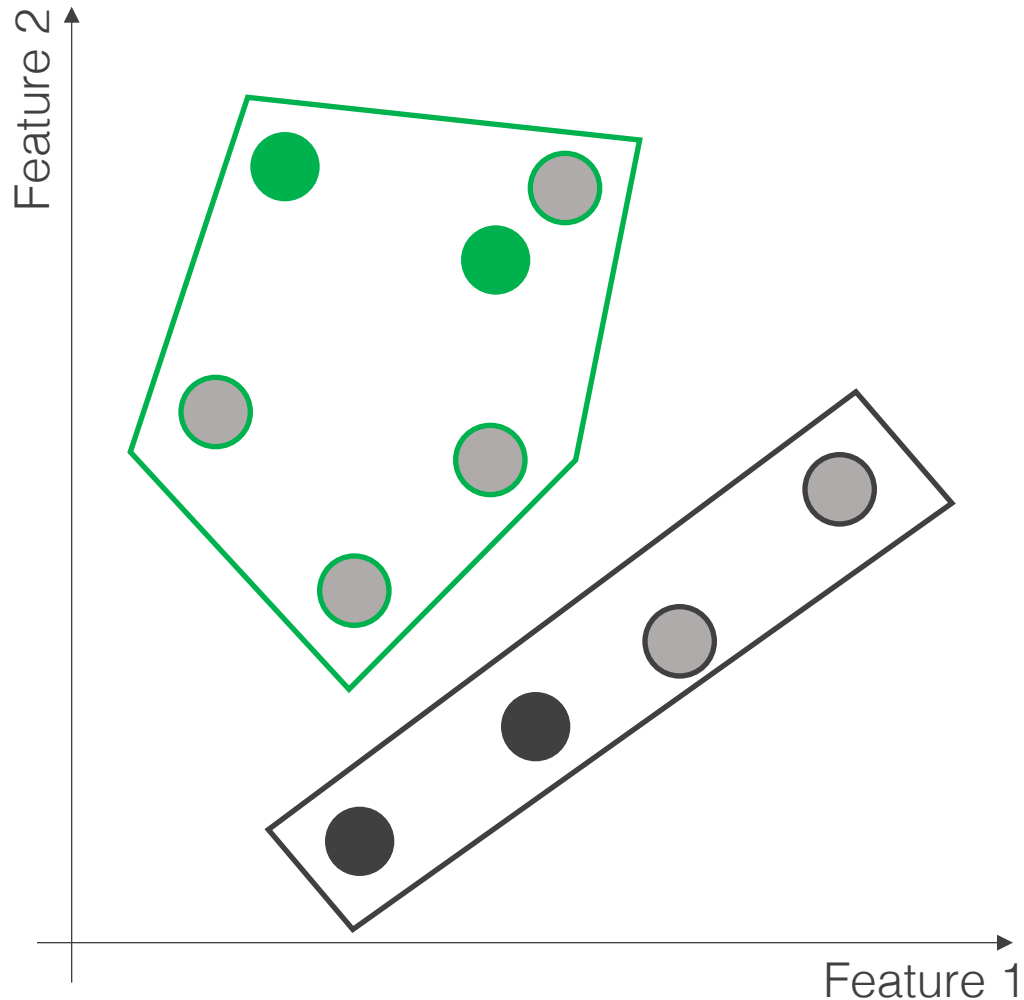
# Semi-supervised learning: **label propagation**



- 1** Cluster the data such that each cluster has at most one class of labeled data
- 2** Assign each sample in each cluster to the corresponding class

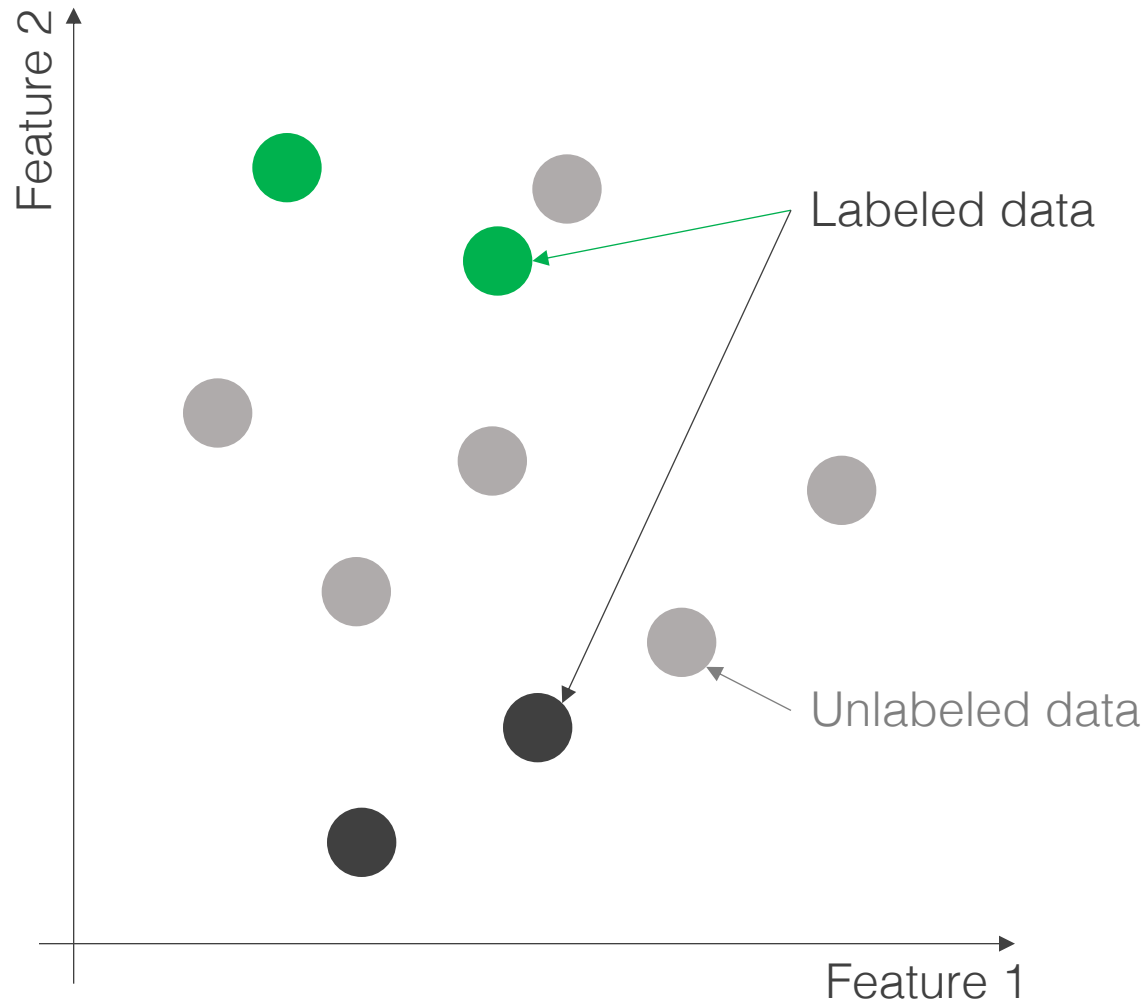


# Semi-supervised learning: **label propagation**

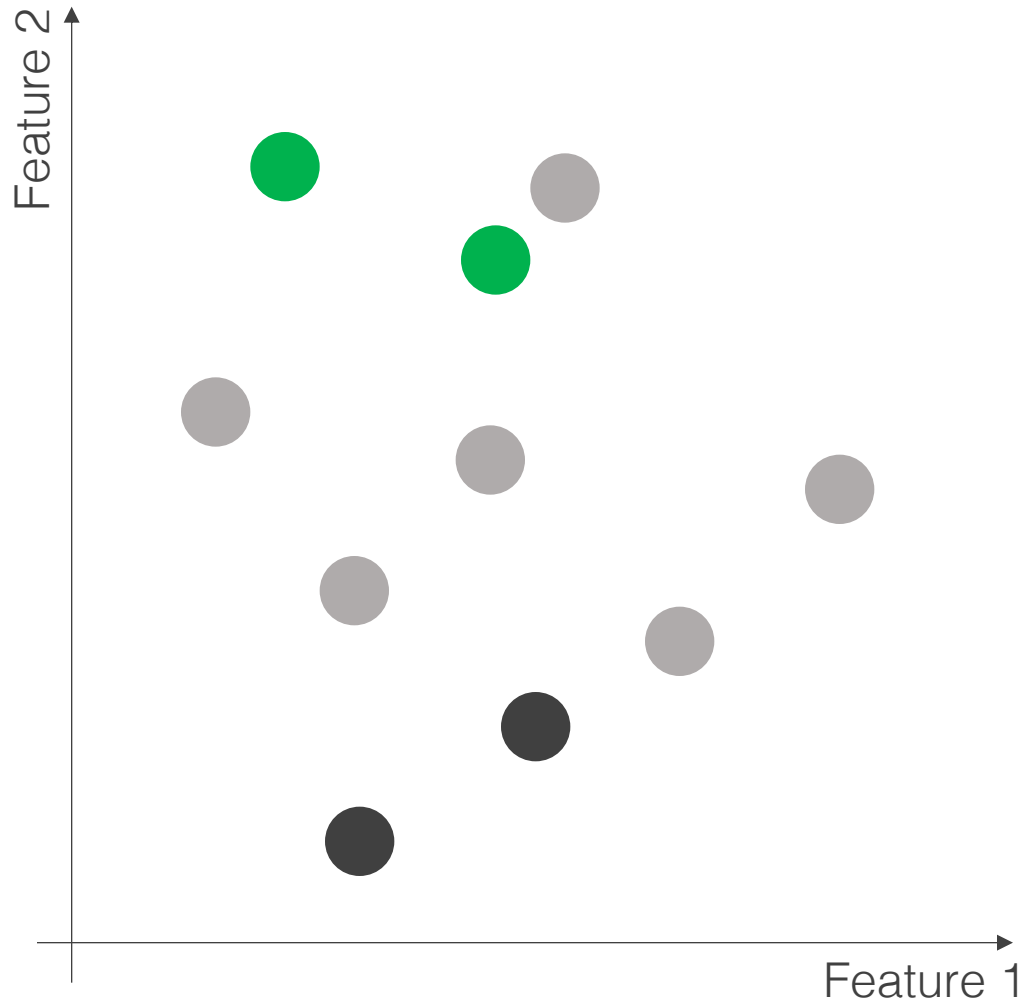


- 1** Cluster the data such that each cluster has at most one class of labeled data
  - 2** Assign each sample in each cluster to the corresponding class
  - 3** Train a supervised model,  $\hat{f}(\mathbf{x})$ , on the labeled data plus the pseudo-labeled data
- The method of defining clusters / measuring similarity may vary
  - Assumes that "similar" points in feature space have similar labels or that clusters share labels

# Semi-supervised learning: self-training

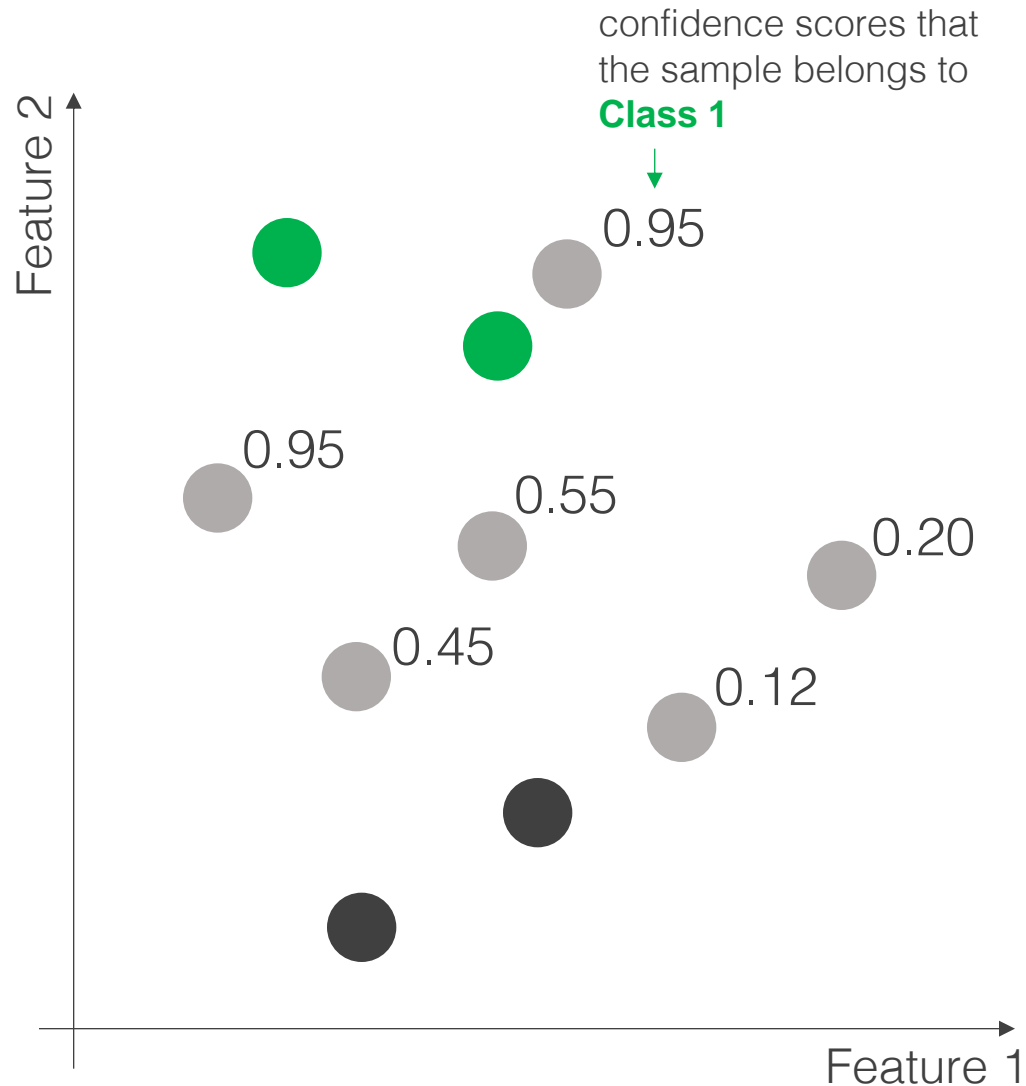


# Semi-supervised learning: self-training



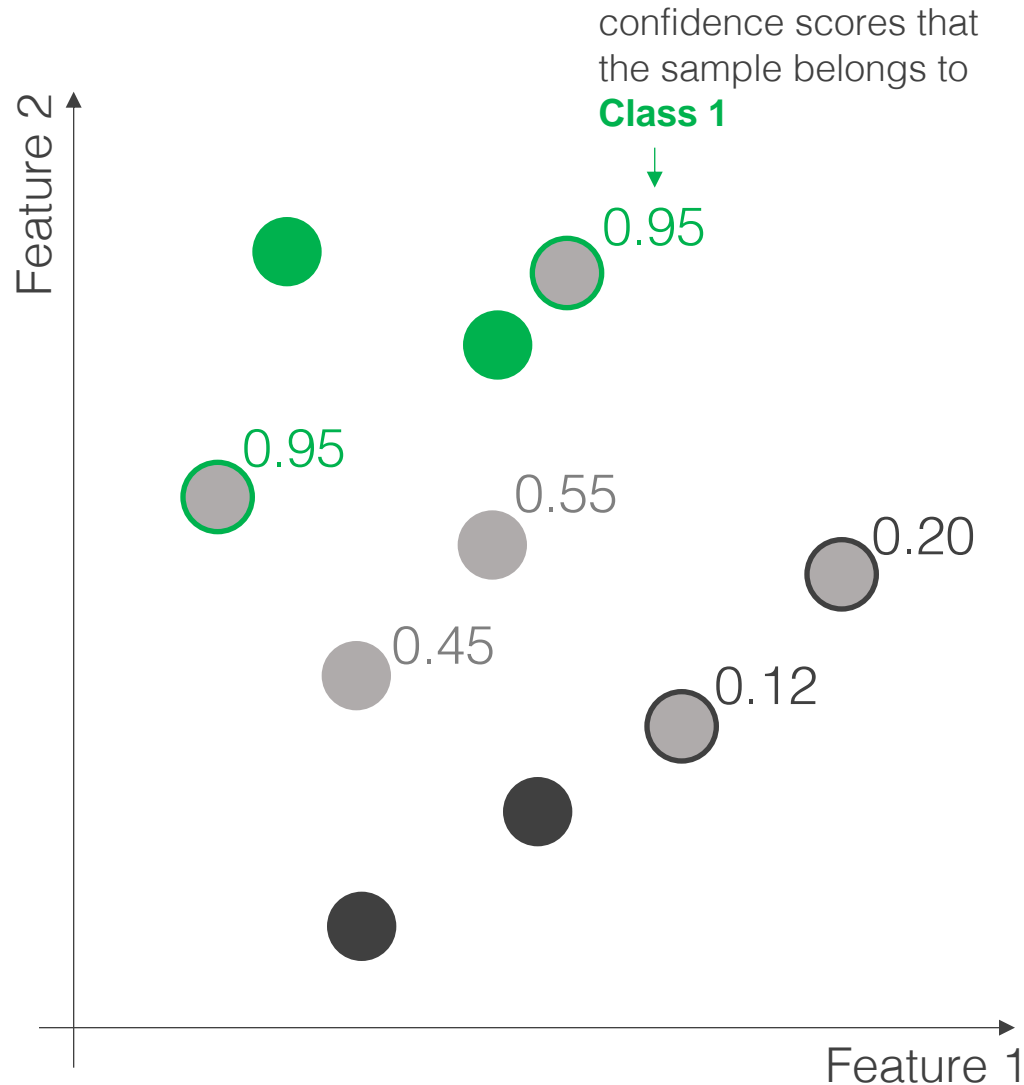
- 1 Train a supervised model on the labeled data,  $\hat{f}(x)$

# Semi-supervised learning: self-training



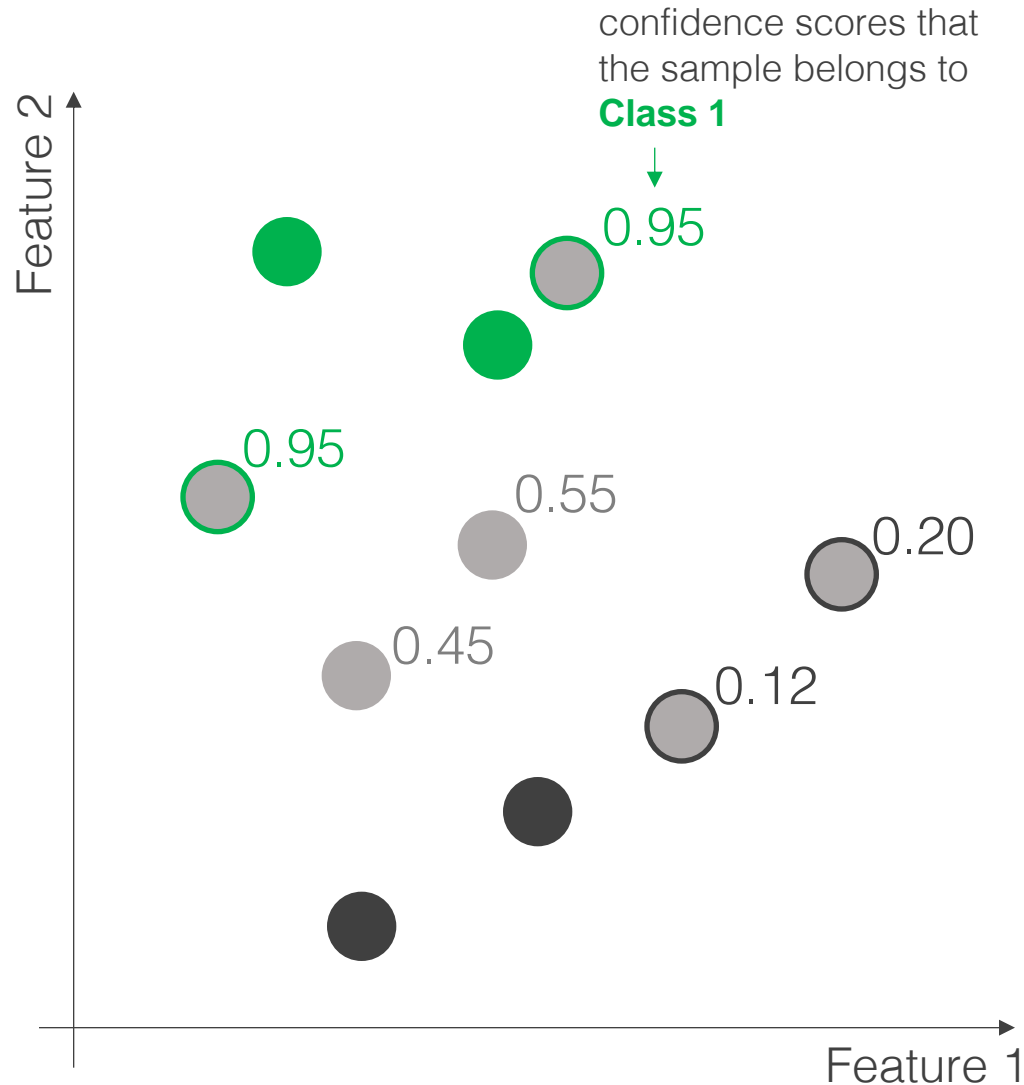
- 1 Train a supervised model on the labeled data,  $\hat{f}(x)$
- 2 Make predictions on the unlabeled data using  $\hat{f}(x)$

# Semi-supervised learning: self-training



- 1 Train a supervised model on the labeled data,  $\hat{f}(x)$
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- 3 Use the predictions to assign pseudo-labels to the samples for which the prediction is most confident

# Semi-supervised learning: self-training



- 1 Train a supervised model on the labeled data,  $\hat{f}(x)$
- 2 Make predictions on the unlabeled data using  $\hat{f}(x)$
- 3 Use the predictions to assign pseudo-labels to the samples for which the prediction is most confident
- 4 Retrain the model,  $\hat{f}(x)$ , using BOTH the labels and pseudo-labels

# Refresher: Loss / Cost functions

$$L(\mathbf{X}, \mathbf{y}, \mathbf{w}) = E(\mathbf{X}, \mathbf{y}) \quad + \quad \lambda R(\mathbf{w})$$

Regression  
(mean squared error)

$$L(\mathbf{X}, \mathbf{y}, \mathbf{w}) = \frac{1}{N} \sum_{i=1}^N \left( y_i - \hat{f}(\mathbf{x}_i) \right)^2$$

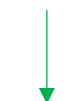
↑  
Mean square error

$$+ \quad \lambda \sum_{j=1}^p w_j^2$$

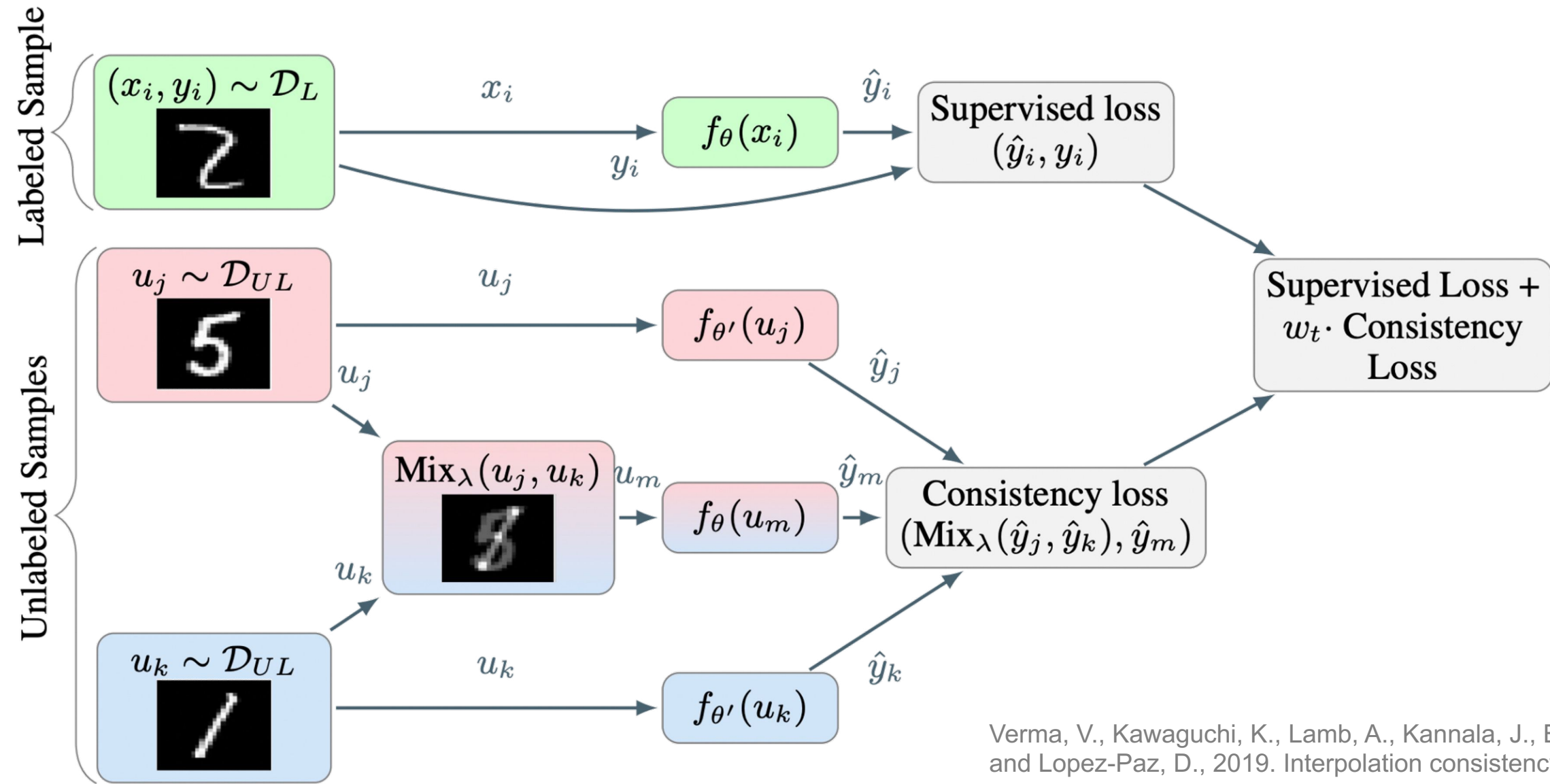
↑  
L<sub>2</sub> regularization penalty can  
be added to either

Classification  
(average binary cross entropy)

$$L(\mathbf{X}, \mathbf{y}, \mathbf{w}) = -\frac{1}{N} \left[ y_i \log \left( \hat{f}(\mathbf{x}_i) \right) + (1 - y_i) \log \left( 1 - \hat{f}(\mathbf{x}_i) \right) \right] + \lambda \sum_{j=1}^p w_j^2$$



# Semi-supervised learning: consistency regularization



Verma, V., Kawaguchi, K., Lamb, A., Kannala, J., Bengio, Y. and Lopez-Paz, D., 2019. Interpolation consistency training for semi-supervised learning. *arXiv preprint arXiv:1903.03825*.



# Semi-supervised learning summary

Allows the use of BOTH labeled and unlabeled data

Reduces the cost of labeling processes

Requires making some strong assumptions about the data, e.g.:

- Points that are close to each other are more likely to share a label
- Points exist in clusters and are likely to share the same label within a cluster

Does not always improve performance

# Special Topics

Semi-supervised learning

**Self-supervised learning**

Recommender systems

Other Practical Considerations

# Self-supervised learning

The data do not come with labels – **we “make” our own labels**

The approaches used are **supervised** in nature

These methods can then be used for supervised learning problems through **transfer learning**

# Recall Autoencoders

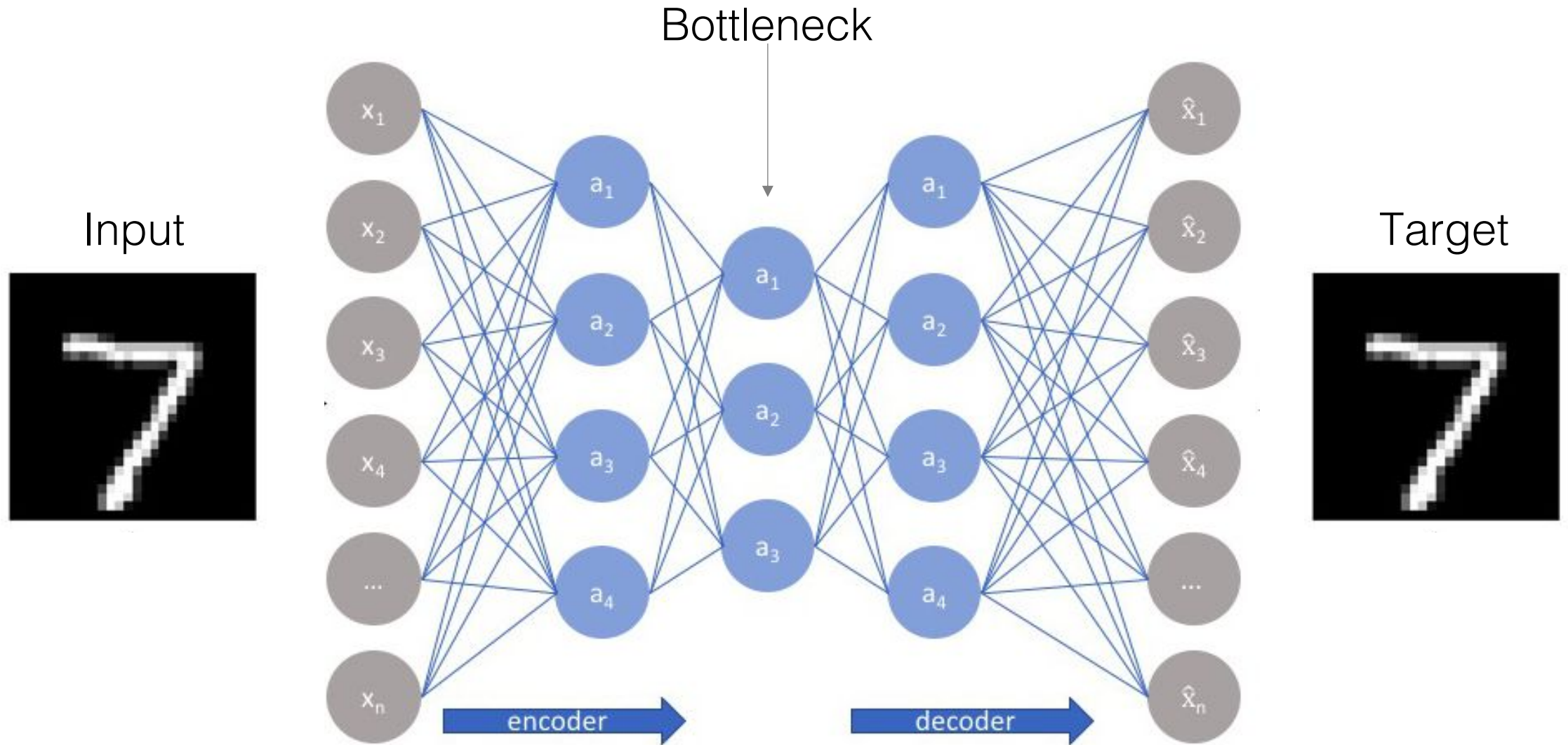
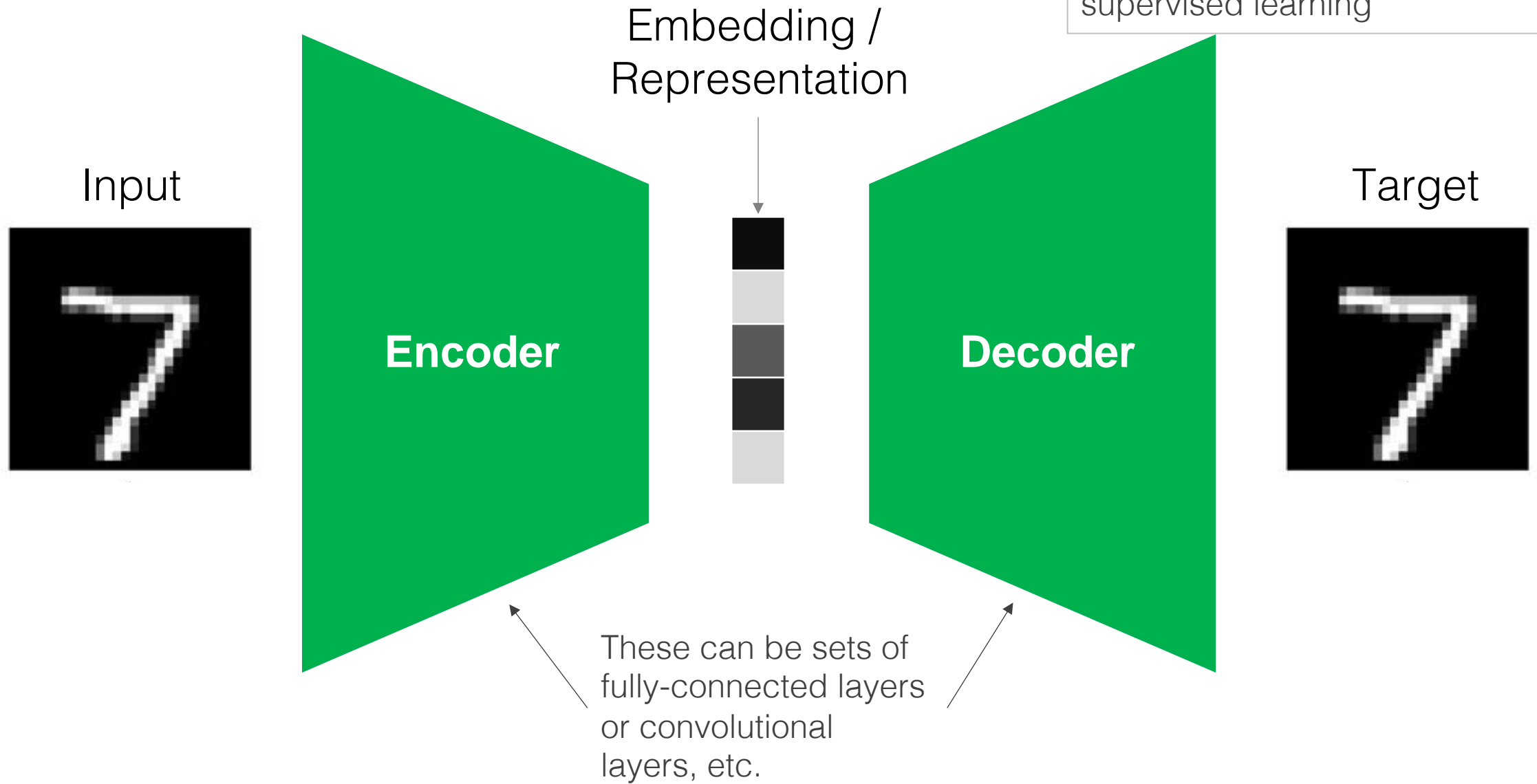


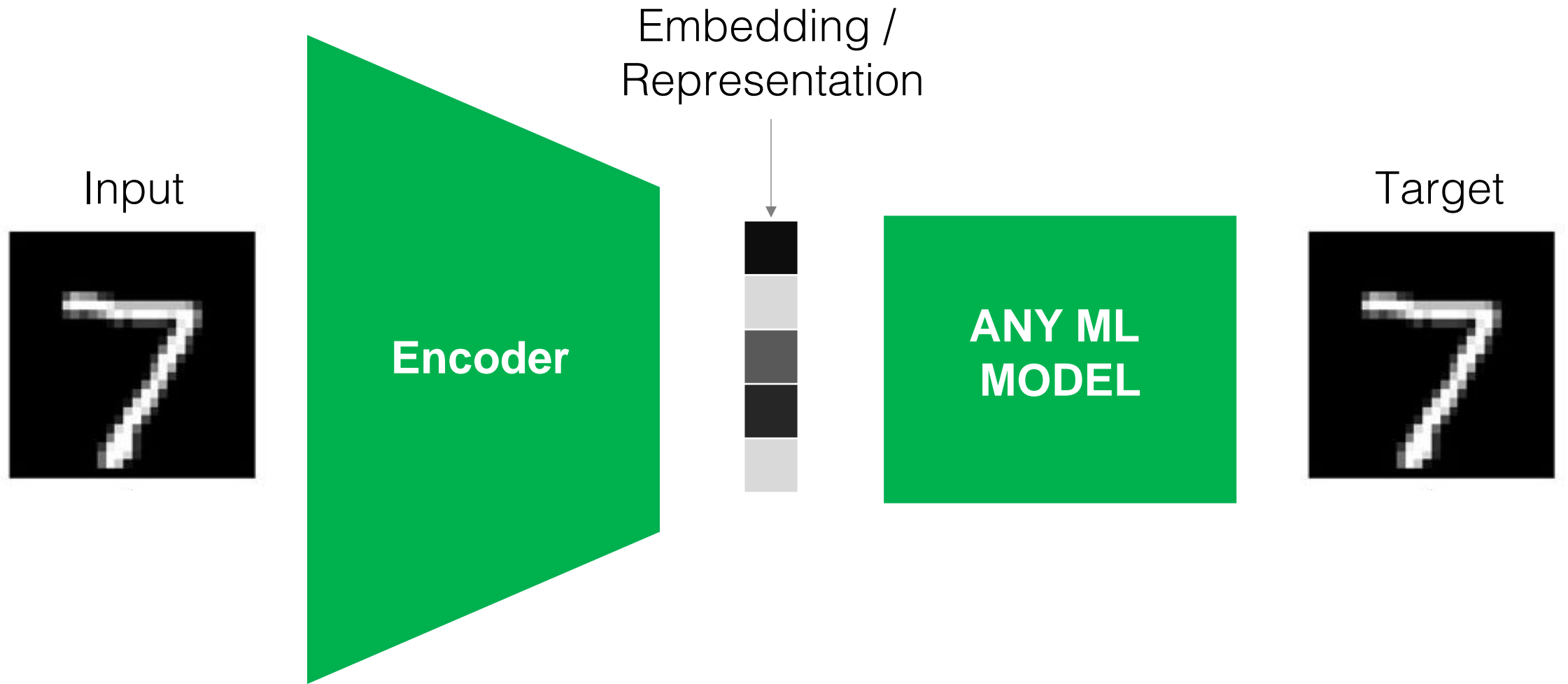
Image from: <https://www.jeremyjordan.me/autoencoders/>

# Recall Autoencoders

Our goal is often to develop a good **encoder** that represents our features well: this is a core insight of self-supervised learning

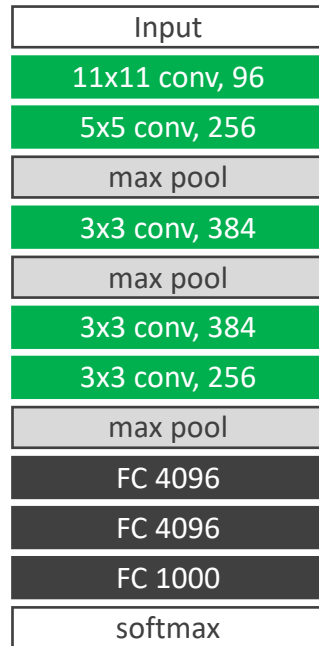


# Recall Autoencoders



# Transfer learned feature representations

AlexNet  
(simple example)

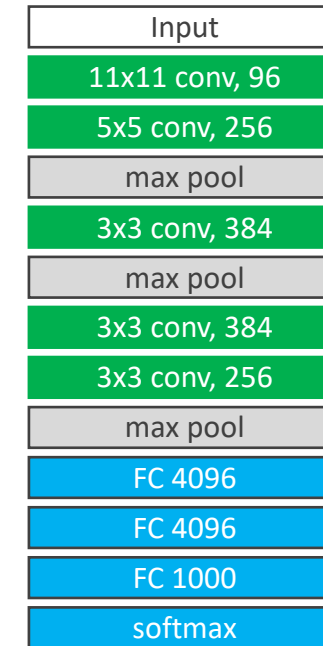


Encoder:  
Feature  
extraction

Decoder:  
Classification /  
Regression

Save all the feature  
extraction weights

Reconfigure the  
prediction algorithm  
for the new problem



Train a model on  
dataset A

Can either use features as-is OR  
fine-tune a model on dataset B

(fine-tune = retrain model a little with saved weights)

# Self-supervised learning: **contrastive learning**

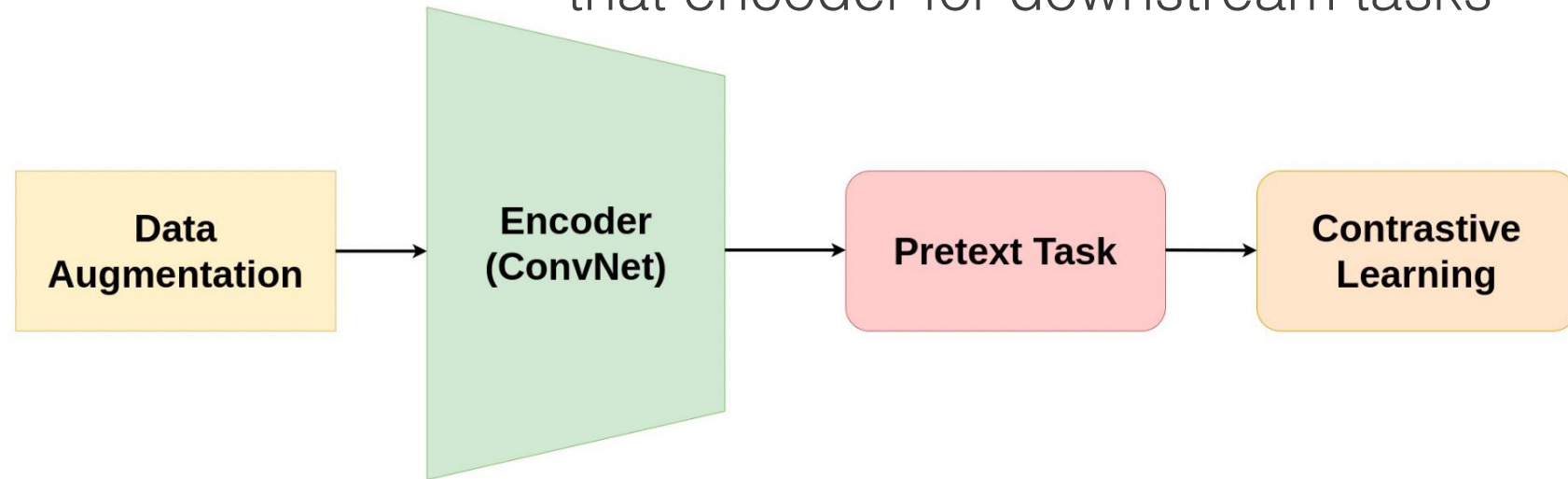
Concept: Train an encoder on a “pretext” task that develops a good representation of the image (i.e. a good feature extractor) then use that encoder for downstream tasks



⋮



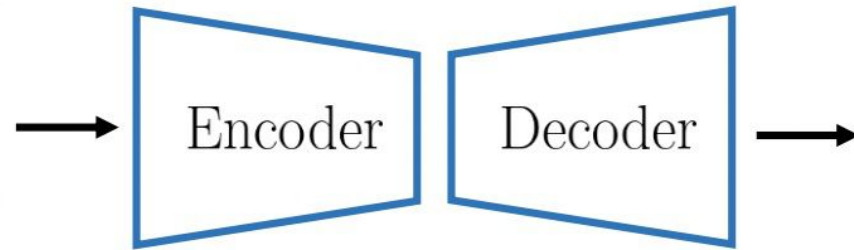
(Unlabeled Images)



Jaiswal, A., Babu, A.R., Zadeh, M.Z., Banerjee, D. and Makedon, F., 2020. A survey on contrastive self-supervised learning. *Technologies*, 9(1), p.2.



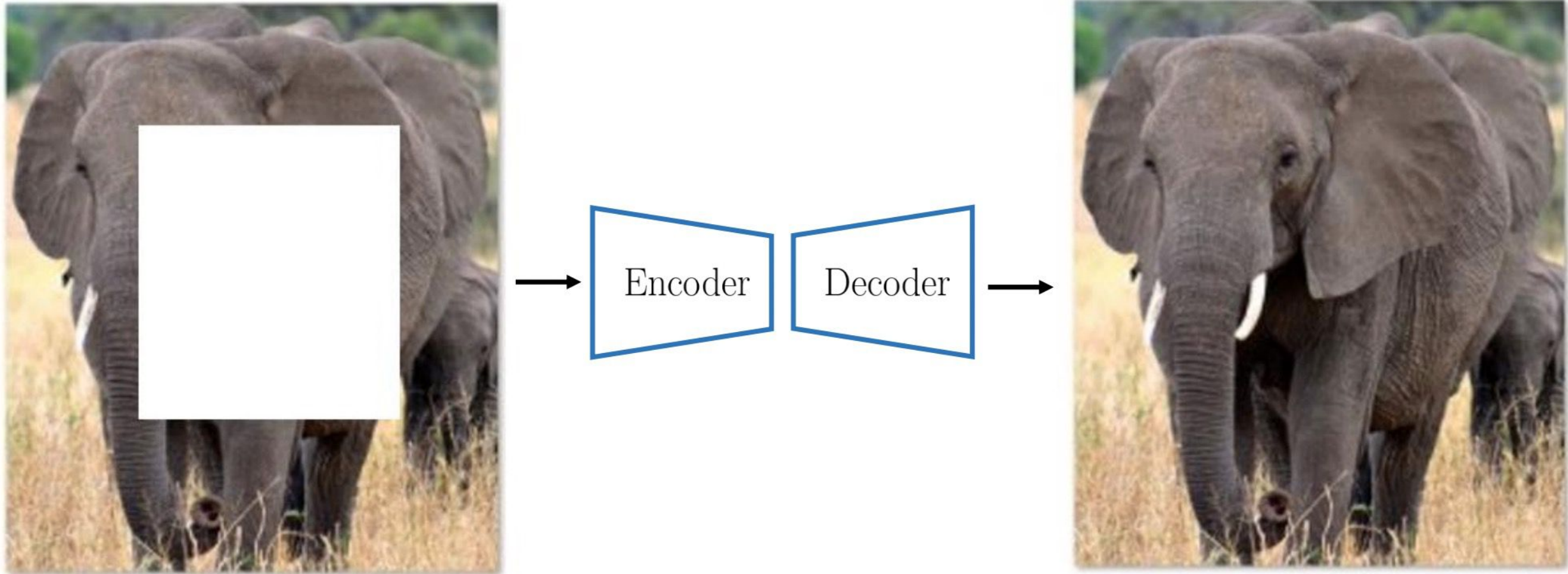
# Pretext task example: denoising



**A pretext task creates labeled data from unlabeled data**

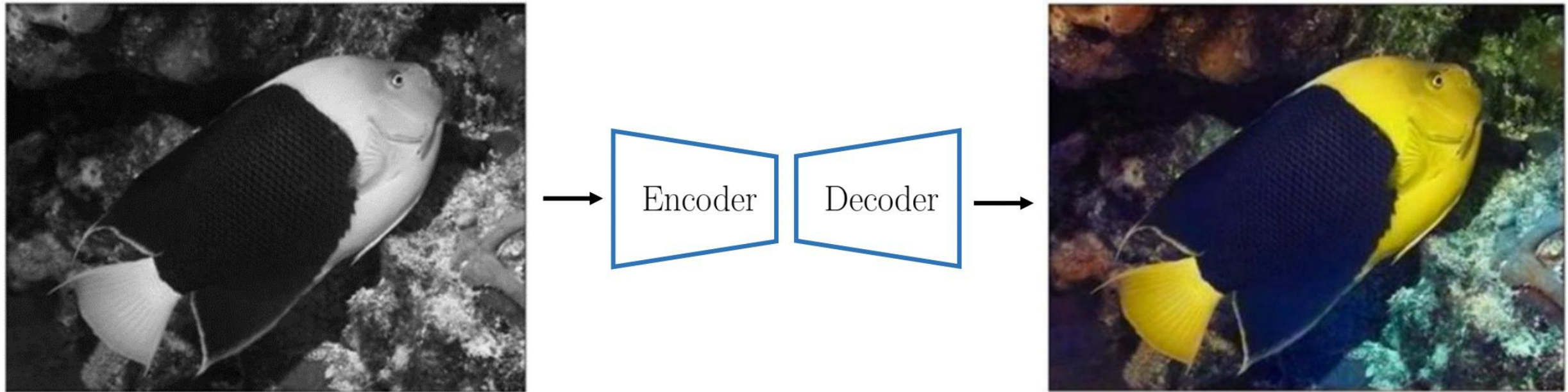
Spyros Gidaris and Andrei Bursuc. 2021. Teacher-student feature prediction approaches. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

# Pretext task example: image inpainting



Spyros Gidaris and Andrei Bursuc. 2021. Teacher-student feature prediction approaches. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

# Pretext task example: colorization

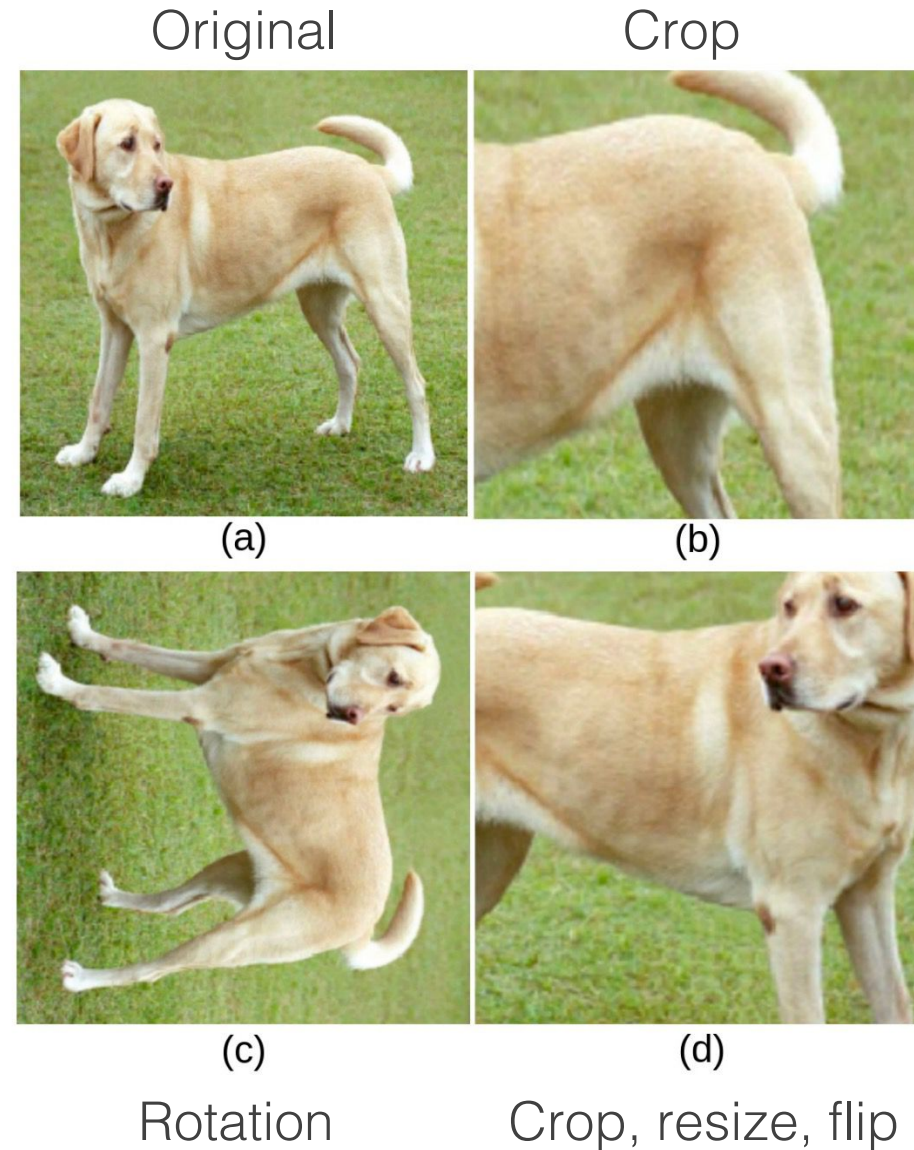
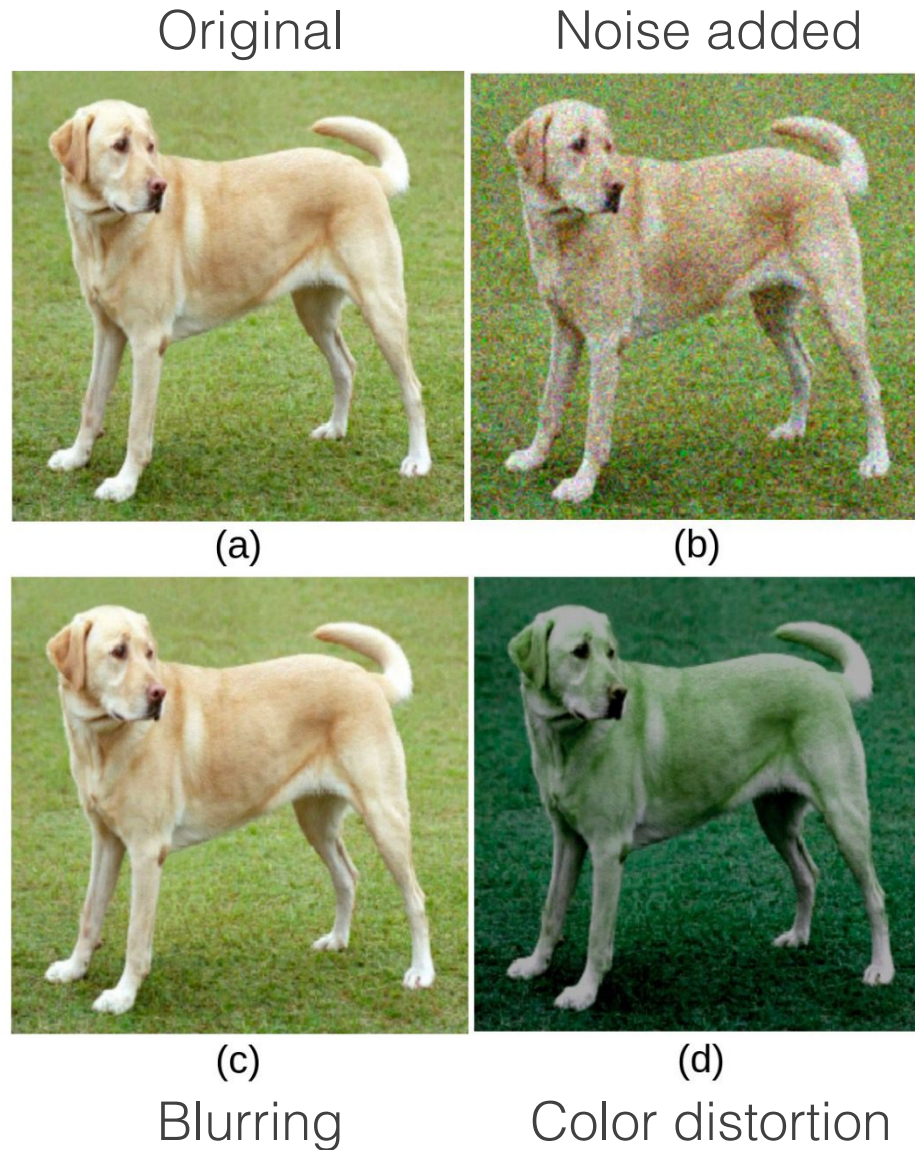


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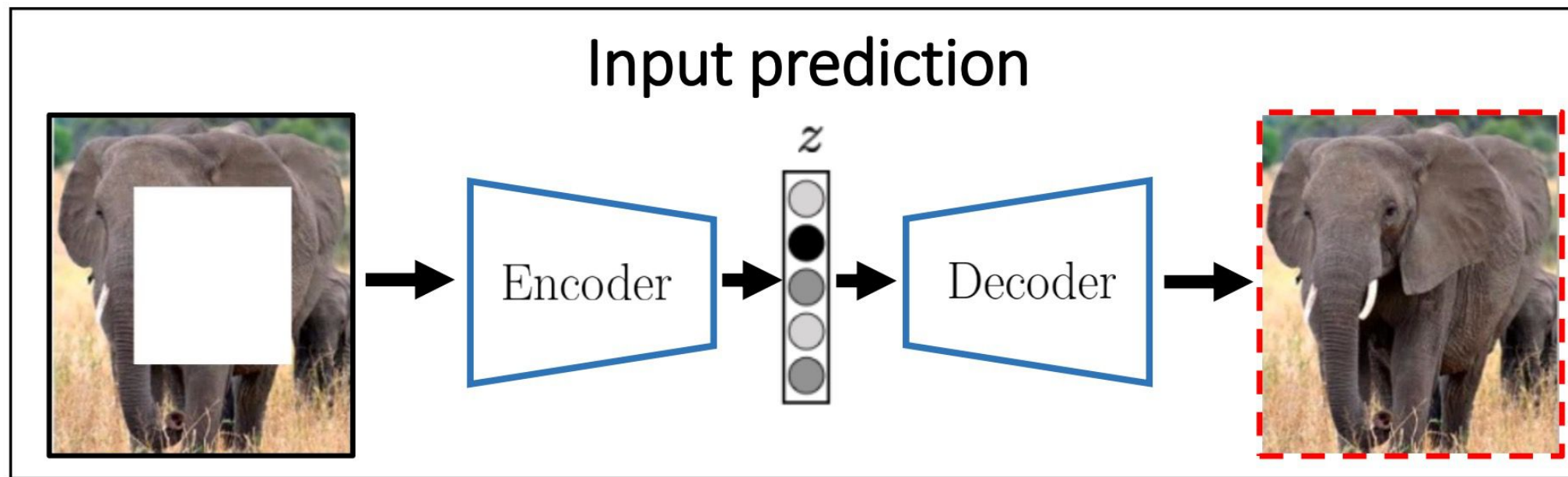
# Augmentations that may be used as pretext tasks for images

Color transformations



Geometric transformations

Jaiswal, A., Babu, A.R., Zadeh, M.Z., Banerjee, D. and Makedon, F., 2020. A survey on contrastive self-supervised learning. Technologies, 9(1), p.2



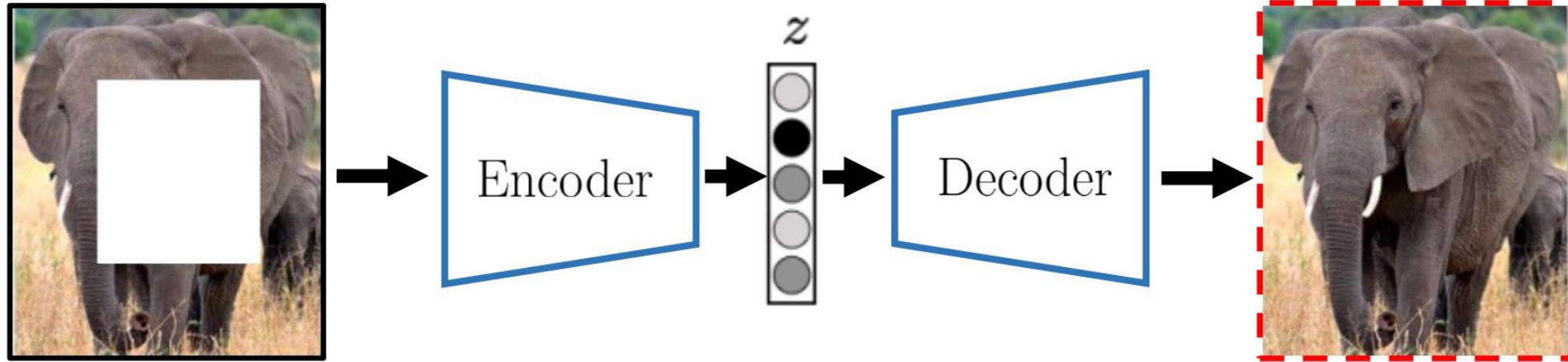
Problem: this approach focuses on a lot of “useless” work: specific details of color, texture, and shapes

We want to have the algorithm represent the “concept” of the elephant and tell that the two images are the same

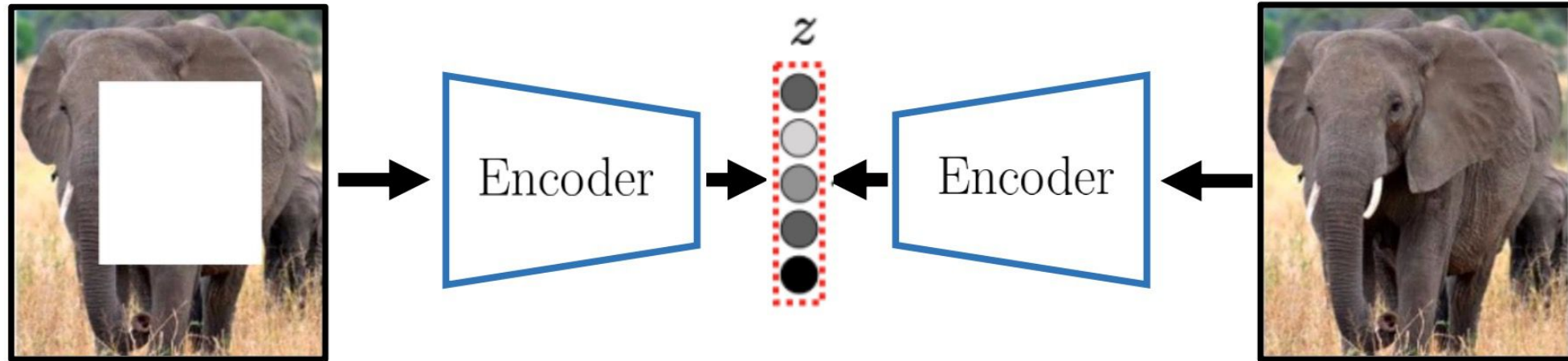
Spyros Gidaris and Andrei Bursuc. 2021. Teacher-student feature prediction approaches. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).



## Input prediction



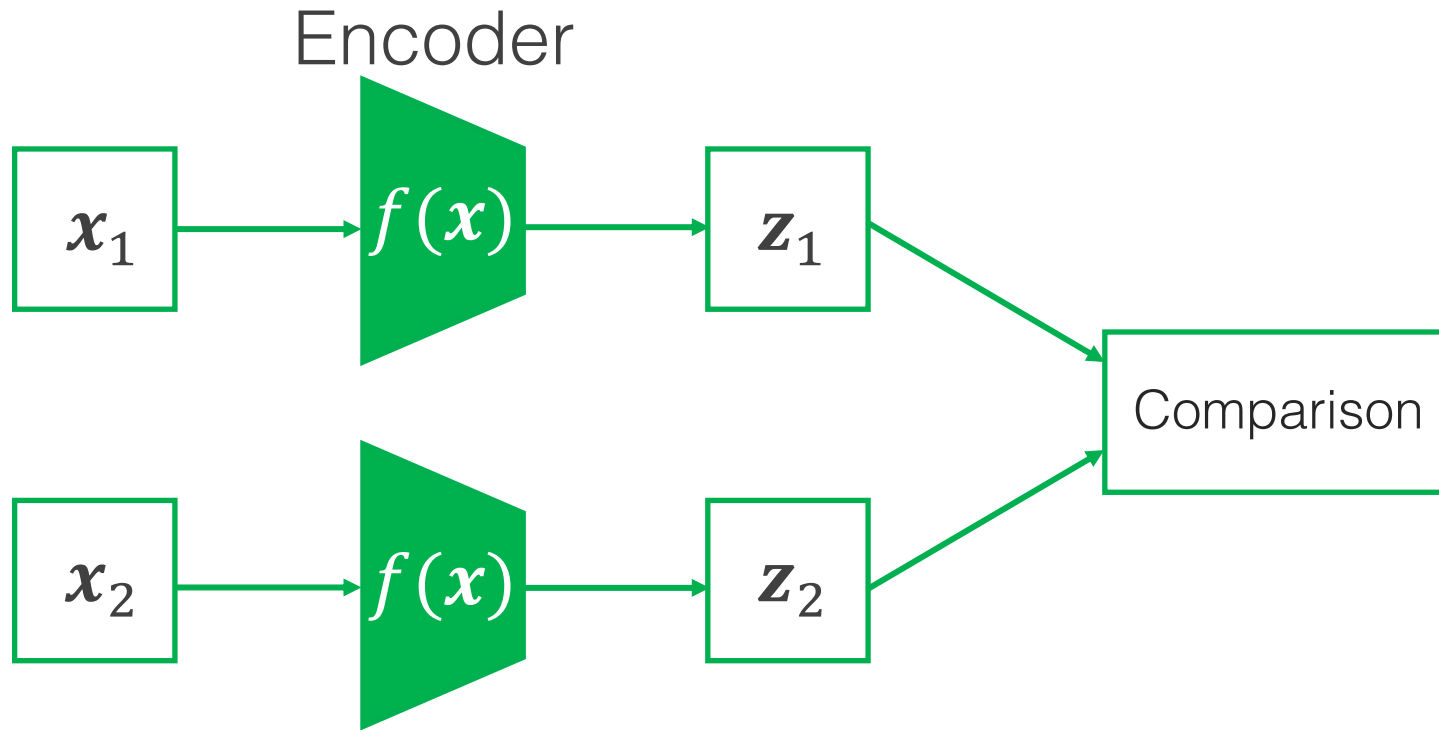
## Contrastive prediction



Spyros Gidaris and Andrei Bursuc. 2021. Teacher-student feature prediction approaches. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

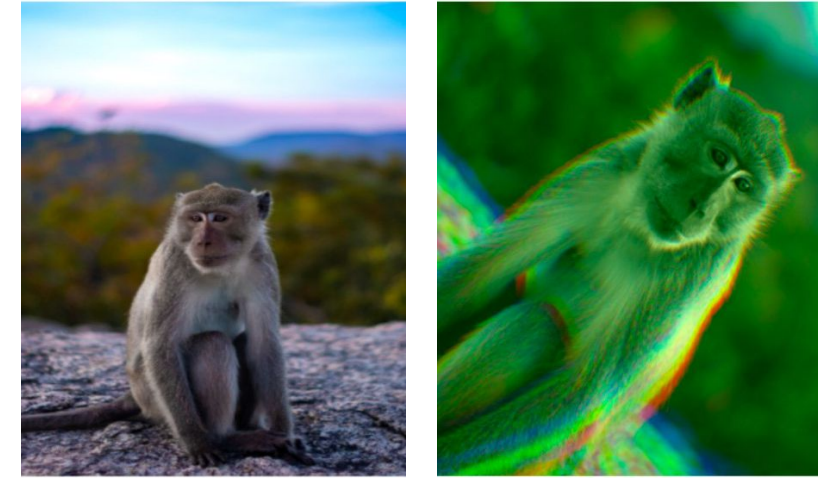
Contrastive learning adjusts the loss / cost function to train the representation  $z$  to be similar for both images

# Self-supervised contrastive learning



Jaiswal, A., Babu, A.R., Zadeh, M.Z., Banerjee, D. and Makedon, F., 2020.  
A survey on contrastive self-supervised learning. Technologies, 9(1), p.2.

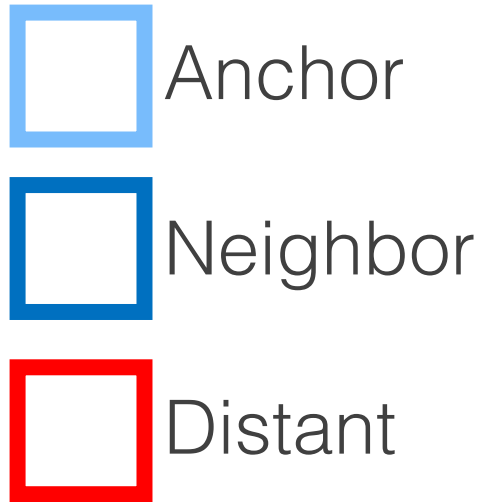
Minimize the representation distance  
between the “similar” samples



Maximize the representation distance  
between the “similar” samples



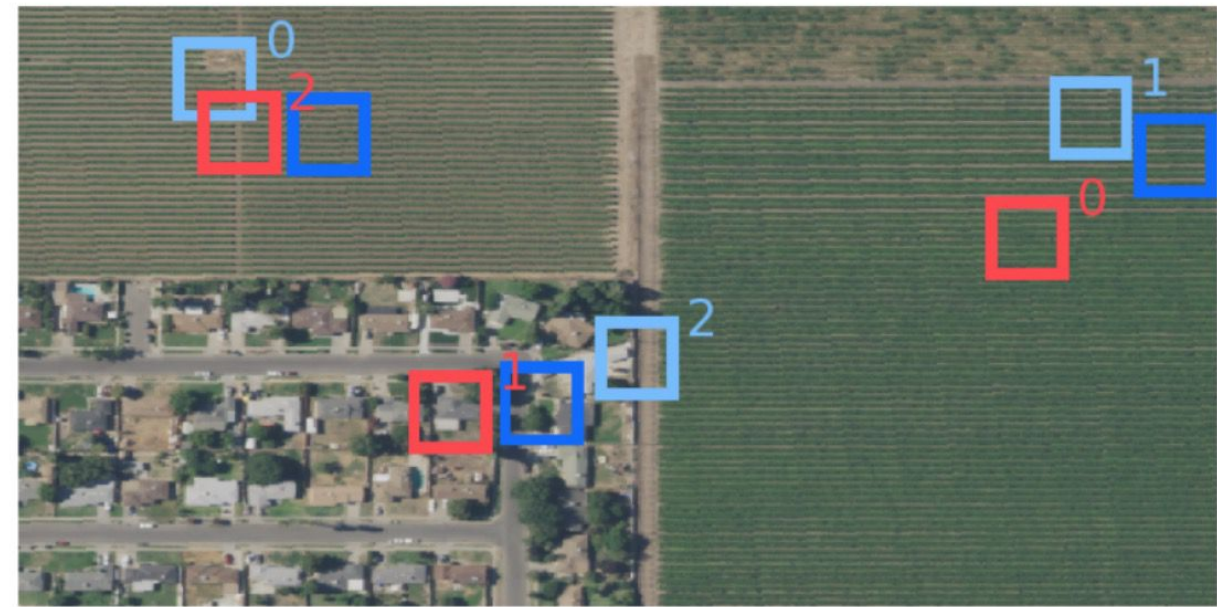
# Triplet loss



$$L(\mathbf{x}_a, \mathbf{x}_n, \mathbf{x}_d) = \left\| \hat{f}(\mathbf{x}_a) - \hat{f}(\mathbf{x}_n) \right\|_2 - \left\| \hat{f}(\mathbf{x}_a) - \hat{f}(\mathbf{x}_d) \right\|_2$$

Minimize the distance of the neighbors

Maximize the distance of the “distant” images

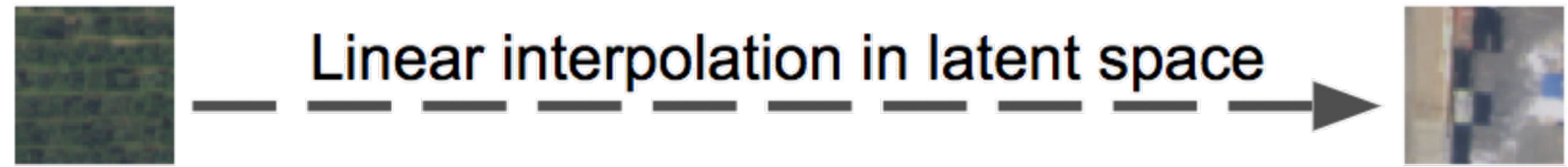


	Anchor	Neighbor	Distant	Anchor Walnuts	Neighbor Walnuts	Distant Grapes
0						
1						
2						

Jean, N., Wang, S., Samar, A., Azzari, G., Lobell, D. and Ermon, S., 2019, July. Tile2vec: Unsupervised representation learning for spatially distributed data. In Proceedings of the AAAI Conference on Artificial Intelligence (Vol. 33, No. 01, pp. 3967-3974).



# Triplet loss Results

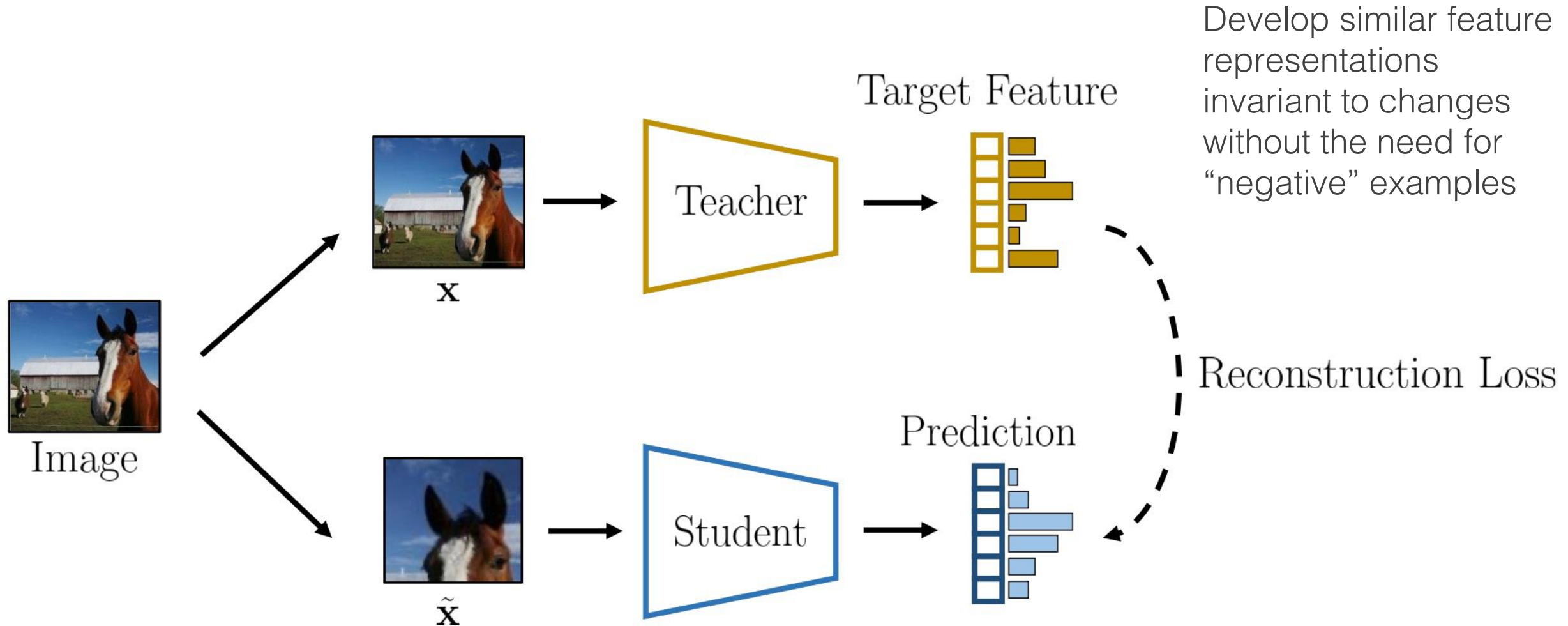


Nearest neighbors at each interpolation step



Jean, N., Wang, S., Samar, A., Azzari, G., Lobell, D. and Ermon, S., 2019, July. Tile2vec: Unsupervised representation learning for spatially distributed data. In Proceedings of the AAAI Conference on Artificial Intelligence (Vol. 33, No. 01, pp. 3967-3974).

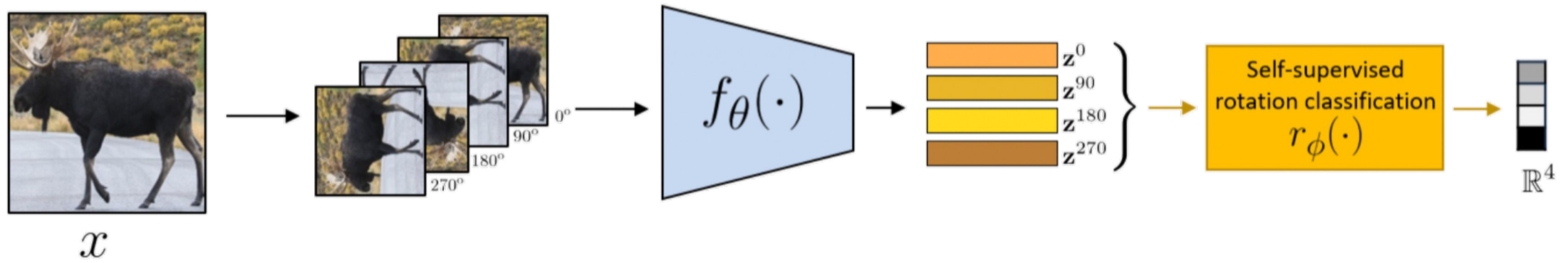
# Self-supervised teacher-student models



Spyros Gidaris and Andrei Bursuc. 2021. Teacher-student feature prediction approaches. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

# Self-supervised learning → downstream tasks

**Stage 1:** Train network on pretext task (without human labels)

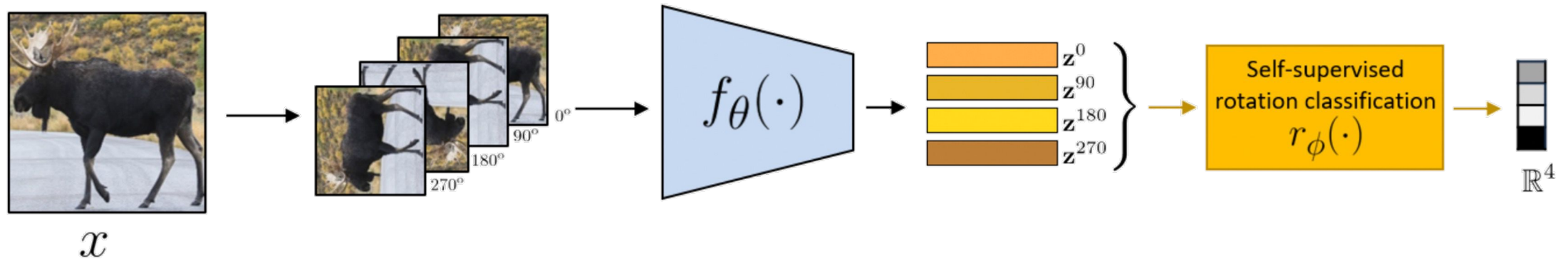


Andrei Bursuc and Spyros Gidaris. 2021.  
Introduction to Self-supervised Learning.  
CVPR 2021 Tutorial on Leave Those Nets  
Alone: Advances in Self-Supervised Learning  
([link](#)).



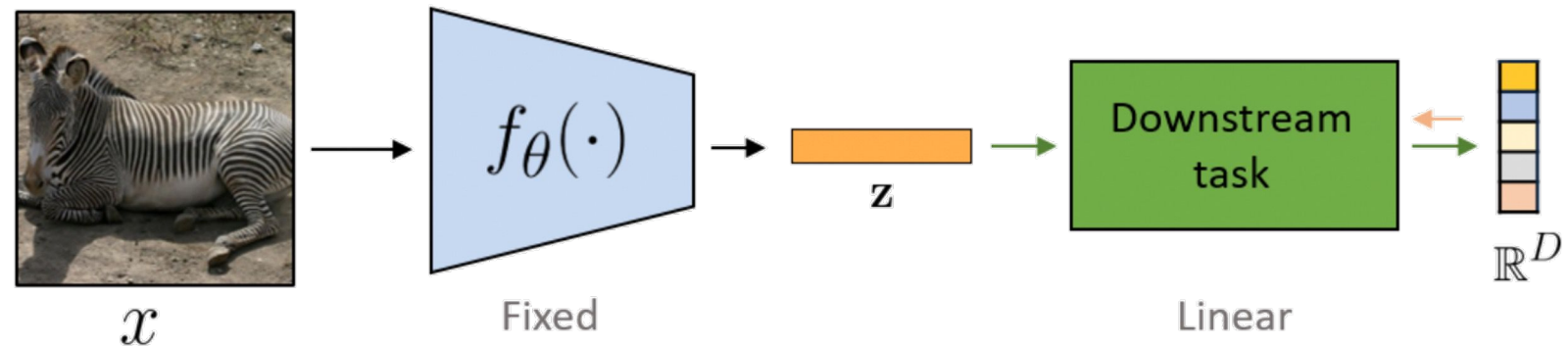
# Self-supervised learning → downstream tasks

**Stage 1:** Train network on pretext task (without human labels)



**Stage 2:** Train classifier on learned features for new task with fewer labels

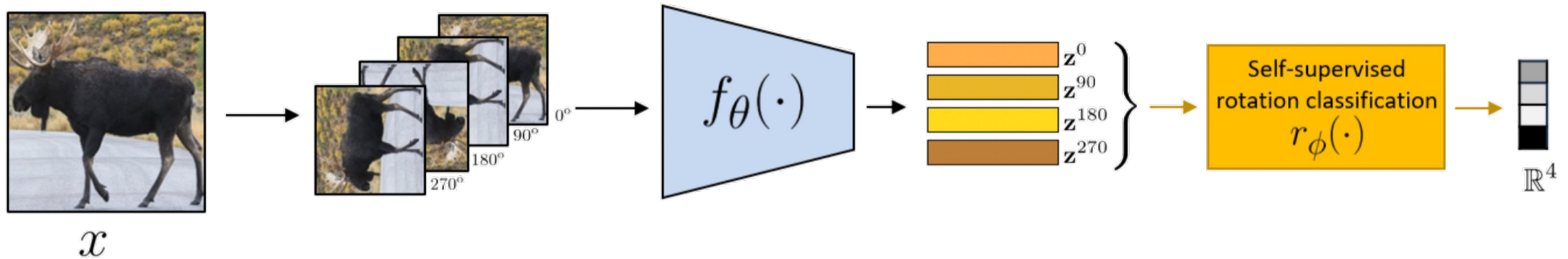
The encoder becomes a pretrained model for downstream tasks through transfer learning



Andrei Bursuc and Spyros Gidaris. 2021. Introduction to Self-supervised Learning. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

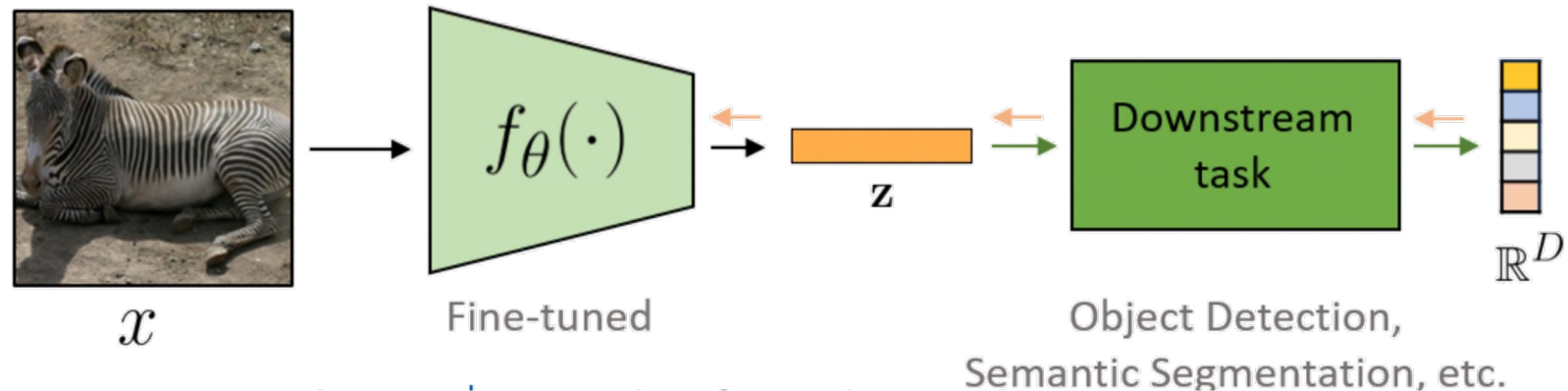
# Self-supervised learning → downstream tasks

**Stage 1:** Train network on pretext task (without human labels)



**Stage 2:** Fine-tune network for new task with fewer labels

The encoder becomes a pretrained model for downstream tasks through transfer learning



Andrei Bursuc and Spyros Gidaris. 2021. Introduction to Self-supervised Learning. CVPR 2021 Tutorial on Leave Those Nets Alone: Advances in Self-Supervised Learning ([link](#)).

# NLP Pretext task examples

Center word  
prediction

A quick brown fox jumps over the lazy dog

Neighbor  
prediction

A quick brown fox jumps over the lazy dog

Masked  
word  
prediction

Randomly  
masked

A quick [MASK] fox jumps over the [MASK] dog

↓

Predict

A quick brown fox jumps over the lazy dog

Other examples include: sentence order prediction, sentence shuffling

Images from Amit Chaudhary: <https://amitnness.com/2020/05/self-supervised-learning-nlp/>

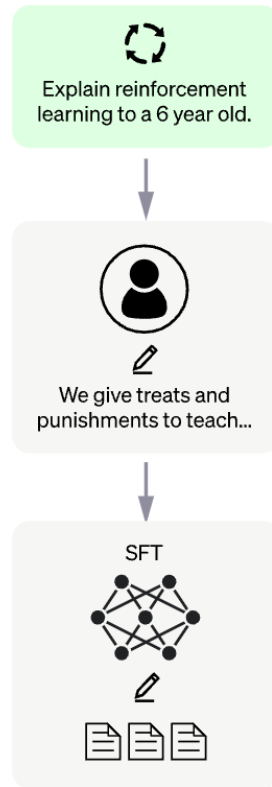
# SSL is the pretraining process for ChatGPT

**Collect demonstration data and train a supervised policy.**

A prompt is sampled from our prompt dataset.

A labeler demonstrates the desired output behavior.

This data is used to fine-tune GPT-3.5 with supervised learning.

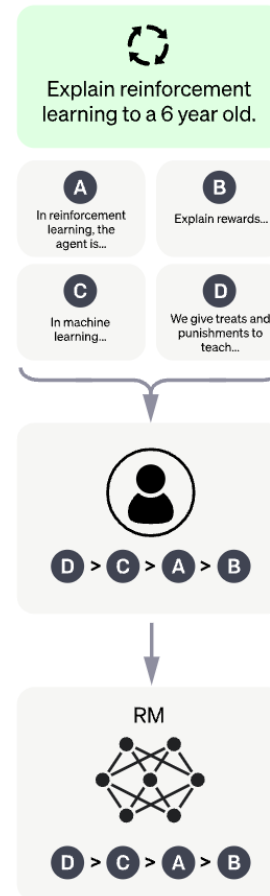


**Collect comparison data and train a reward model.**

A prompt and several model outputs are sampled.

A labeler ranks the outputs from best to worst.

This data is used to train our reward model.



**Optimize a policy against the reward model using the PPO reinforcement learning algorithm.**

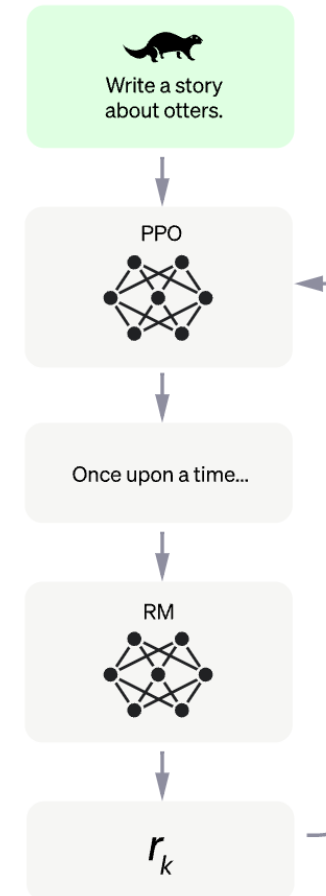
A new prompt is sampled from the dataset.

The PPO model is initialized from the supervised policy.

The policy generates an output.

The reward model calculates a reward for the output.

The reward is used to update the policy using PPO.



PPO = Proximal Policy Optimization  
(Instead of estimating action-value functions, it searches the policy space directly)

# Self-supervised learning summary

Comes in many flavors: contrastive, teacher-student, etc.

Has generated exceptional NLP models: BERT, GPT-3, word2vec

No labels required!

Large unlabeled dataset required

Massive computation required!



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Other Practical Considerations

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Semi-supervised learning

Self-supervised learning

**Other Practical Considerations**

# Practical Considerations for Machine Learning

1. Let your problem/question drive your design choices
  2. Set a reasonable goal and clear metric of success
  3. Ask yourself if there are non-ML approaches that would work
  4. Develop an end-to-end pipeline as soon as you're able and keep it maintained (data preparation & preprocessing, analysis, and performance evaluation)
  5. Start with the simplest solution you can and layer on complexity as needed
- Features / representations are **often more important** than algorithms
  - **Experimental design** is often more important than algorithms

Adapted from Google: <https://developers.google.com/machine-learning/guides/rules-of-ml>

# More advice

- ALWAYS look at your data – before you begin, the inputs/outputs, etc.
- Check your distributions
- Explore outliers to get insights on the model
- Report confidence intervals whenever possible (make sure your “better” model is not just a noisy aberration)
- When comparing supervised models, make sure you’re comparing on the same validation set
- Make sure you NEVER mix training and validation information

Adapted from <https://www.unofficialgoogledatascience.com/2016/10/practical-advice-for-analysis-of-large.html>

# References for further exploration

- [Semi-supervised learning](#)
- [Self-supervised learning CVPR tutorial](#)
- Jaiswal, A., Babu, A.R., Zadeh, M.Z., Banerjee, D. and Makedon, F., 2020. A survey on contrastive self-supervised learning. Technologies, 9(1), p.2. ([link](#))