

Brian Park

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EDUCATION

- **Carnegie Mellon University** Pittsburgh, PA
M.S. Computer Vision
Courses: Computer Vision, Robot Learning
Aug 2024 - Dec 2025
- **University of California, Los Angeles** Los Angeles, CA
B.S. Computer Science and Engineering; GPA: 3.69; 2021, 2022 Dean's Honor List
Courses: Algorithms & Data Structures, Operating Systems, Deep Learning, Machine Learning, Computer Graphics, Computer Architecture
Sep 2020 - Mar 2024

EXPERIENCE

- **NVIDIA** Santa Clara, CA
Perception Software Engineer Intern, Autonomous Vehicles
May 2024 - Aug 2024
 - Integrated a Bird's Eye View (BEV) semantic segmentation model for parking edge detection into ParkNet DNN, achieving a 0.98 DICE score and 0.62 precision using PyTorch, OpenCV.
 - Utilized Meta AI's Segment Anything Model (SAM) to evaluate the geometric precision of parking space ground truth labels, driving optimized localization and data mining for parking space detection.
- **NVIDIA** Santa Clara, CA
Perception Software Engineer Intern, Autonomous Vehicles
Jun 2023 - Sept 2023
 - Perform data augmentation on the SQLite training dataset of parking spaces with inferred entry-line labels, led to the generation of 1.7 million scenes of Augmented Reality data with wheel stoppers, utilizing PyTorch, NumPy, SQLite. Awarded 2nd Place at NVIDIA Global Intern Project Showcase.
 - Implement 13 Key Performance Indicator (KPI) metrics, including Intersection Over Union (IOU), Positional Error, and Hausdorff Distance, to evaluate the performance of ParkNet Deep Neural Network, using PyTorch, NumPy, Pandas.
- **Structures-Computer Interaction at UCLA** Los Angeles, CA
Undergraduate Researcher; Advisors: Prof. Jungseock Joo and Prof. M. Khalid Jawed
Sept 2022 - Current
 - Devise a sampling pipeline utilizing NVIDIA Instant-NGP, Unity C# Engine, NumPy, and OpenCV to generate neural radiance field objects (NeRFs) for 3D Reconstructions of agricultural fields, achieving a 98.3% reduction in baseline sampling time.
 - Build autonomous robotics software and Computer Vision algorithms for leading research development of self driving precision agricultural robots in collaboration with the U.S. Department of Agriculture.
 - Formulated mBEST Perception Algorithm to perform realtime detection of Deformable Linear Objects; Obtained ground truth labels of the mBEST and FASTDLO dataset using OpenCV, NumPy.
- **Miravel** Los Angeles, CA
Software Engineer Intern
Jan 2021 - October 2021
 - Created subscription service with HTML, CSS, JavaScript, REST APIs for customers to edit account information and create transactions.
 - Implemented an account management system that over 360 users ordered, viewed, and edited products to purchase seeds for their autonomous indoor garden.
- **iD Tech** Los Angeles, CA
Academy Instructor
Jun 2022 - Aug 2022
 - Led iD Tech's "Machine Learning: Coding Deep Neural Networks" course to 30 high school students.
 - Guided students in training Convolutional Neural Networks on the CIFAR-10 dataset using Tensorflow and Recurrent Neural Networks for cooking recipe generation using Python, Tensorflow, pandas, BeautifulSoup.
- **Association for Computing Machinery, Artificial Intelligence at UCLA** Los Angeles, CA
Outreach Officer
Oct 2020 - Sept 2023
 - Developed and instructed a UCLA-certified machine learning curriculum weekly to cohorts of 20 students at North Hollywood High School and Girls Academic Leadership Academy.
 - Hosted "You Belong in AI," a podcast with over 1300 listeners that explores diversity and inclusion within AI, featuring leaders of artificial intelligence organizations within Google, NVIDIA, DeepMind, MITRE.

PUBLICATIONS

- Choi, A., Tong, D., **Park, B.**, Terzopoulos, D., Joo, J., Jawed, M. "mBEST: Realtime Deformable Linear Object Detection Through Minimal Bending Energy Skeleton Pixel Traversals", IEEE Robotics and Automation Letters, 2023

SKILLS

- Languages: Python, C++, C, C#, HTML, CSS, JavaScript, Haskell, Bash, SQL.
- Technologies: PyTorch, Tensorflow, OpenCV, NumPy, Pandas, scikit-learn, Unity, ReactJS, Firebase, SQLite, Git.