### LECTURE 4

# Moduli spaces of sheaves, I

Last time we showed that the Hilbert scheme of n points in  $A^2$  is non-singular and equivalent to the quotient of

(1) 
$$\widetilde{H}_n^s = \{(X, Y, i) \mid [X, Y] = 0, \text{ and stability}\} \subset \operatorname{End}(\mathbf{C}^n)^{\oplus 2} \oplus \mathbf{C}^n.$$

by the natural  $GL(n, \mathbb{C})$  action. Today we will wrap up this discussion with a computation of the dimension of  $\operatorname{Hilb}_n(\mathbf{A}^2)$  and some examples of Hilbert schemes for small values of n. Then, we turn to a sheaf-theoretic description of the Hilbert scheme.

### 4.1. Dimension of the Hilbert scheme

For  $(X, Y, i) \in \widetilde{H}_n^s$  let  $(C^{\bullet}, d)$  be the following complex

(2) 
$$\operatorname{End}(\mathbf{C}^n) \xrightarrow{\mathrm{d}_1} \operatorname{End}(\mathbf{C}^n)^{\oplus 2} \oplus \mathbf{C}^n \xrightarrow{\mathrm{d}_2} \operatorname{End}(\mathbf{C}^n)$$

where the first arrow is the derivative of the  $GL(n, \mathbb{C})$  action

(3) 
$$d_1(A) = ([A, X], [A, Y], Ai)$$

and the second arrow is

(4) 
$$d_2(A, B, v) = [X, A] + [Y, B].$$

Then

(5) 
$$T_{(X,Y,i)} \operatorname{Hilb}_n(\mathbf{A}^2) \simeq H^1(C,d).$$

We have already shown that the dimension of the cokernel of  $d_2$  is n. By the stability condition we have  $\ker d_1 = 0$ . This shows that  $\dim H^1(C) = 2n$ .

## 4.2. Examples

Let's consider some examples of  $\operatorname{Hilb}_n(\mathbf{A}^2)$  for small n. For n=1 we have X=x,Y=y for some numbers  $x,y\in \mathbf{C}$ . Furthermore, the stability condition implies that  $i\neq 0$ . Using the  $\mathbf{C}^\times$ -action we can assume that i=1. The idea corresponding to the pair x,y is

(6) 
$$I = \{ f(z_1, z_2) \in \mathbf{C}[z_1, z_2] \mid f(x, y) = 0 \}.$$

This is simply the maximal idea corresponding to  $(x,y) \in \mathbf{A}^2$ . Thus  $\mathrm{Hilb}_1(\mathbf{A}^2) = \mathbf{A}^2$ .

Next we look at n = 2. Then X, Y are  $2 \times 2$  matrices. Suppose that at least X, Y have distinct eigenvalues. Since [X, Y] = 0 we can assume that

(7) 
$$X = \begin{pmatrix} x_1 & 0 \\ 0 & x_2 \end{pmatrix}, \quad Y = \begin{pmatrix} y_1 & 0 \\ 0 & y_2 \end{pmatrix}$$

with  $(x_1, y_1) \neq (x_2, y_2)$ . By the stability condition we can take

$$i(1) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

The corresponding ideal is

(9) 
$$I = \{ f(z_1, z_2) \in \mathbf{C}[z_1, z_2] \mid f(x_i, y_i) = 0 \},$$

which corresponds to two distinct points in  $A^2$ . Thus away from the diagonal in  $A^2 \times A^2$  the Hilbert scheme agrees with  $S^2A^2$ .

The interesting stuff happens when we assume that X, Y each have one eigenvalue. We cannot assume that X, Y are both diagonalizable as this violates the stability condition. Thus, we have

(10) 
$$X = \begin{pmatrix} x & a \\ 0 & x \end{pmatrix}, \quad Y = \begin{pmatrix} y & b \\ 0 & y \end{pmatrix}$$

for some  $(a, b) \in \mathbf{A}^2 - 0$ . In this basis we can assume that

$$i(1) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The corresponding ideal is

(12) 
$$I = \left\{ f(z_1, z_2) \in \mathbf{C}[z_1, z_2] \mid f(x, y) = \left( a \frac{\partial f}{\partial z_1} + b \frac{\partial f}{\partial z_2} \right) (x, y) = 0 \right\}.$$

This corresponds to two infinitesimally close points in  $A^2$  at (x,y) which point to each other in the direction of the vector field  $a\frac{\partial}{\partial z_1} + b\frac{\partial}{\partial z_2}$ .

### 4.3. TORSION-FREE SHEAVES

A quasi-coherent sheaf  $\mathcal F$  on an algebraic variety X is **torsion-free** if for every affine open subset  $U\subset X$  the space of local sections  $\mathcal F(U)$  is torsion-free as a module over the ring of functions  $\mathcal O(U)$  on U. That is, for ever nonzero section  $s\in \mathcal F(U)$  and nonzero function  $f\colon U\to \mathbf C$  one has  $f\cdot s\neq 0$ . A typical example of a torsion-free sheaf is the sheaf of sections of a vector bundle; the condition of being a locally free implies torsion-free. We will mostly be concerned with coherent torsion-free sheaves.

For any quasi-coherent sheaf  $\mathcal{F}$  there is a canonical morphism

$$\mathfrak{F} \to (\mathfrak{F}^{\vee})^{\vee} = \mathfrak{F}^{\vee \vee}$$

where  $\mathcal{F}^{\vee} = \text{Hom}_{\text{Mod}_{\mathcal{O}}}(\mathcal{F}, \mathcal{O})$  is the dual sheaf.<sup>1</sup> The main technical result about torsion-free sheaves that we will use is the following.

THEOREM 4.3.1 ([??]). Let X be a non-singular algebraic variety and suppose  $\mathcal{F}$  is a coherent torsion-free sheaf on X. Then:

<sup>&</sup>lt;sup>1</sup>A quasi-coherent sheaf which is isomorphic to its double dual is called reflexive.

- there exists a Zariski open set  $U \subset X$  of codimension  $\geq 2$  such that  $\mathfrak{F}|_U$  is locally free.
- If dim X=2 then the sheaf  $\mathcal{F}^{\vee\vee}$  is locally free of finite rank and the morphism  $\mathcal{F}\to\mathcal{F}^{\vee\vee}$  is injective. Restriction of this morphism to U results in an isomorphism  $\mathcal{F}|_{U} \xrightarrow{\sim} \mathcal{F}^{\vee\vee}|_{U}$ .

#### 4.4. CHERN CLASSES

Let *X* be a smooth algebraic variety over **C**, which you are free to think of as just complex manifold. The *j*th Chern class of a complex vector bundle *E* over *X* is an element

$$(14) c_j(E) \in H^{2j}(X; \mathbf{R}).$$

The total Chern class is usually denoted

(15) 
$$c(E) = \sum_{j \ge 0} c_j(E) \in H^{2\bullet}(X; \mathbf{R}).$$

The Chern classes are determined by the following axioms.

- *The zeroeth Chern class.* For any bundle  $E \to X$  one has  $c_0(E) = 1$ .
- *Naturality*. For any bundle  $E \to X$  and smooth map  $f: Y \to X$  one has

$$c(f^*E) = f^*c(E) \in H^{2\bullet}(X; \mathbf{R}).$$

• Whitney sum. For a finite collection of bundles  $E_i$  one has

$$c(\oplus_i E_i) = \sum_i c(E_i).$$

• *Normalization*. Let O(1) be the dual of the tautological line bundle over  $\mathbb{CP}^1$ . Then

(18) 
$$\int_{\mathbf{CP}^1} c_1(\mathfrak{O}(1)) = 1.$$

We will need to extend the definition of Chern classes to coherent sheaves. Let Coh(X) be the category of coherent sheaves on X and let  $Vect(X) \subset Coh(X)$  be the subcategory of locally free coherent sheaves. This subcategory is equivalent to the category of holomorphic vector bundles on X; the equivalence is obtained by taking the sheaf of holomorphic sections of a given holomorphic vector bundle. Both Coh(X) and Vect(X) are abelian categories.

**Construction 4.4.1.** Given any abelian category  $\mathcal{A}$  we can look at the free abelian group  $\mathbf{Z}[\mathcal{A}]$  which is generated by the isomorphism classes of objects of  $\mathcal{A}$ . Given a short exact sequence

$$(19) 0 \to A \to B \to C \to 0$$

in A we can form the element

(20) 
$$-[A] + [B] - [C] \in \mathbf{Z}[A].$$

Let E(A) be the subgroup of  $\mathbf{Z}[A]$  generated by elements of this form. The *Grothendieck group* of the abelian category A is defined as the quotient group

(21) 
$$K_0(A) \stackrel{\text{def}}{=} \mathbf{Z}[A]/E(A).$$

By definition, if (19) is a short exact sequence then we have the relation

$$[B] = [A] + [C]$$

in  $K_0(A)$ .

Consider the free abelian group generated by isomorphism classes of vector bundles on X

(23) 
$$\mathbf{Z}[\operatorname{Vect}(X)].$$

This has the structure of a commutative ring where multiplication is the tensor product (over  $\mathcal{O}_X$ ) of coherent sheaves. In the sequence we denote the Grothendieck group of Vect(X) by  $K_0(X) \stackrel{\text{def}}{=} K_0(\text{Vect}(X))$ .

**Lemma 4.4.2.** *Let X be a smooth complex variety or a complex manifold.* 

- (1) The subring  $E(\text{Vect}(X)) \subset \mathbf{Z}[\text{Vect}(X)]$  is an ideal, and therefore  $K_0(X)$  has the structure of a commutative ring with unit given by the trivial rank one vector bundle.
- (2) The group  $K_0(Coh(X))$  is naturally a module for  $K_0(X)$ .
- (3) The embedding  $\mathbf{Z}[\operatorname{Vect}(X)] \hookrightarrow \mathbf{Z}[\operatorname{Coh}(X)]$  determines a group homomorphism

$$i: K_0(X) \to K_0(\operatorname{Coh}(X)).$$

Notice that by construction the total Chern class defines a group homomorphism

$$c: K_0(X) \to H^{\bullet}(X).$$

**Remark 4.4.3.** In fact, there is a more refined relationship between  $K_0(X)$  and the cohomology of X.

The Chern character of a complex vector bundle  $E \rightarrow X$  is an element

$$ch(E) \in H^{2\bullet}(X; \mathbf{R})$$

defined formally as follows. Suppose that  $\xi_i$  are constants and x is a formal variable such that

(27) 
$$\sum_{i} c_i(E) x^i = \prod_{i} (1 + \xi_i x).$$

Then the Chern character is defined by

$$ch(E) = \sum_{i} e^{\xi_i}.$$

The Chern character enjoys a similar sum rule  $\operatorname{ch}(\oplus_i E_i) = \sum_i \operatorname{ch}(E_i)$  and also a product identity

(29) 
$$\operatorname{ch}(\otimes_i E_i) = \prod_i \operatorname{ch}(E_i).$$

Immediately, then, we see that the Chern character defines a ring homomorphism

$$(30) ch: K_0(X) \to H^{\bullet}(X).$$

Now, we can state how to extend Chern classes to coherent sheaves. Given a coherent sheaf  $\mathcal{F}$  on a smooth projective algebraic variety over  $\mathbf{C}$  there exists a locally free resolution of  $\mathcal{F}$  (that is, a resolution by vector bundles) of the form

$$(31) 0 \to \mathcal{E}_{-n} \to \mathcal{E}_{-n+1} \cdots \to \mathcal{E}_{-1} \to \mathcal{E}_0 \to \mathcal{F} \to 0.$$

In the case of a general complex manifold such a resolution is only guaranteed to exist locally. Using such a resolution we define

(32) 
$$c(\mathcal{F}) \stackrel{\text{def}}{=} \sum_{i} (-1)^{i} c(\mathcal{E}_{i}) \in H^{\bullet}(X).$$

One can show that this definition does not depend on the resolution.

This construction can be refined to providing an inverse j to the ring homomorphism  $i: K_0(X) \to K_0(\text{Coh}(X))$  by the formula

(33) 
$$j([\mathcal{F}]) = \sum_{i} (-1)^{i} [\mathcal{E}_{i}].$$

The proof of the fact that these homomorphisms are inverses to each other is outside of the scope of these notes.