## |Chapter 3 Vectors

# **Coordinate Systems**

- Used to describe the position of a point in space
- With reference to the origin
  - (0, 0) for 2D
  - (0, 0, 0) for 3D
- Specific axes with scales and labels

### **Cartesian Coordinate System**

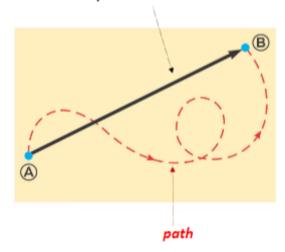
- Rectangular coordinate system
- x-axis and y-axis intersect at the origin
- (x, y)

## **Vectors**

Written as  $\overset{\longrightarrow}{A}$  or  ${\bf A}$  Magnitude of a vector written as |A| or A

### Example





The displacement vector is independent of the path.

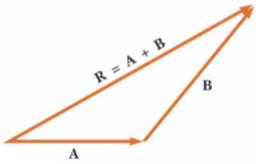
## **Equality of Two Vectors**

- Two vectors are **equal** if they have the same **magnitude and direction**.
- $\bullet \ \ \, \overrightarrow{A} = \overrightarrow{B} \text{ and } |A| = |B| \text{, they point along parallel lines in the same direction}$

### **Adding Vectors**

- Direction must be taken into account
- Units must be the same

## **Adding Vectors Graphically**

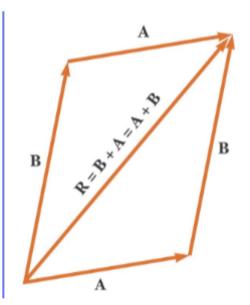


draw the vectors from "head-to-tail".

#### Rules

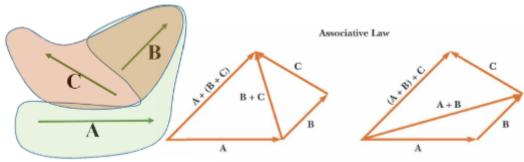
Commutative Law of Addition: When two vectors are added, the sum is independent of the order of the addition.

$$\overrightarrow{A} + \overrightarrow{B} = \overrightarrow{B} = \overrightarrow{A}$$



Associative Property of Addition: When adding three or more vectors, their sum is independent of the way in which the individual vectors are grouped

$$\overrightarrow{A} + (\overrightarrow{B} + \overrightarrow{C}) = (\overrightarrow{A} + \overrightarrow{B}) + \overrightarrow{C}$$



All units must be the same, cm cannot be added to m

## **Negative of a Vector**

Same magnitude but point to the opposite direction  $-\overrightarrow{A}$   $\overrightarrow{A}+(-\overrightarrow{A})=0$  if added to the original vector will result 0

## **Subtracting Vectors**

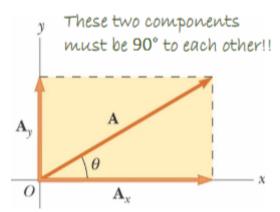
instead of  $\overrightarrow{A}-\overrightarrow{B}$  , use  $\overrightarrow{A}+(-\overrightarrow{B})$ 

## Multiplying or Dividing a Vector by a Scalar

$$2 imes\overrightarrow{A}=2\overrightarrow{A},-0.8 imes\overrightarrow{A}=-0.8\overrightarrow{A}$$

if the scalar is negative, the resultant vector will also be negative

## **Components of a Vector**



Parts of a vector, one along the x-axis and one along the y-axis

 $\overrightarrow{A}_x$  and  $\overrightarrow{A}_y$  are the component vector of  $\overrightarrow{A}$ 

The components are scalar.

the projections are  $\overrightarrow{A}_x = \overrightarrow{A}\cos\theta$  and  $\overrightarrow{A}_y = \overrightarrow{A}\sin\theta$ , thus  $\overrightarrow{A} = \overrightarrow{A}_x + \overrightarrow{A}_y$ 

and 
$$\overrightarrow{A}=\sqrt{\overrightarrow{A_x^2}+\overrightarrow{A_y^2}}$$
 and  $heta= an^{-1}rac{\overrightarrow{A_y}}{\overrightarrow{A_x}}$ 

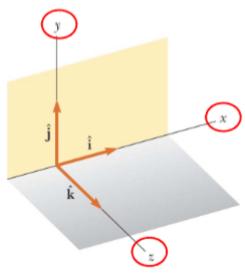
	sin		y	all		
$A_{\lambda}$	nega	tive	$A_x$	positiv	e	
$A_{y}$	A <sub>y</sub> positive			$A_y$ positive		
$A_{\mathfrak{p}}$	$A_x$ negative			$A_x$ positive		
$A_{y}$	nega	tive	$A_y$	negativ	ve	

Components can be positive and negative and will have the same unit as the original vector, vector in the 3rd quadrant, both the x and y will be negative.

#### **Unit Vectors**

- A unit vector is a dimensionless vector with a magnitude of exactly 1.
- They are only used to specify a direction.
- Symbols are  $\hat{i},\,\hat{j}$  and  $\hat{k}$

• They follow right-hand rules



- Since they are dimensionless, thus  $\overset{
  ightharpoonup}{A}_x \cdot \hat{i}$  is the same as  $\overset{
  ightharpoonup}{A}_y \cdot \hat{j}$
- And thus,  $\overrightarrow{A} = \overrightarrow{A}_x\,\hat{i} + \overrightarrow{A}_y\,\hat{j} + \overrightarrow{A}_z\,\hat{k}$

## **Adding Vectors Using Unit Vectors**

Using resultant vector

$$R = \overrightarrow{A} + \overrightarrow{B}$$

$$R = (\overrightarrow{A}_x\,\hat{i} + \overrightarrow{A}_y\,\hat{j}) + (\overrightarrow{B}_x\,\hat{i} + \overrightarrow{B}_y\,\hat{j})$$

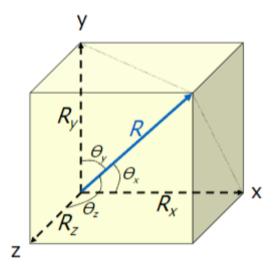
$$R = (\overrightarrow{A}_x + \overrightarrow{B}_x)\,\hat{i} + (\overrightarrow{A}_y + \overrightarrow{B}_y)\,\hat{j}$$

$$R = R_x + R_y$$

$$R_x = A_x + B_x$$
 and  $R_y = A_y + B_y$ 

$$R=\sqrt{R_x^2+R_y^2}$$
 and  $heta= an^{-1}rac{R_y}{R_x}$ 

## **Angle of Vector in 3D**



$$\begin{split} R &= \sqrt{R_x^2 + R_y^2 + R_z^2} \\ \theta_x &= \cos^{-1} \frac{R_x}{R} \\ \theta_y &= \cos^{-1} \frac{R_y}{R} \\ \theta_z &= \cos^{-1} \frac{R_z}{R} \end{split}$$

$$\theta_x = \cos^{-1} rac{R_x}{R}$$

$$\theta_y = \cos^{-1} \frac{R}{I}$$

$$heta_y = \cos^{-1} rac{R}{R_z}$$