

Chapter 8 Conservation of Energy

Isolated System

An isolated system is one for which there are **no energy transfers across the boundary**. The *energy in such system is conserved at anytime* the **sum is a constant** but its form can change in part or in whole

- A block sliding across a frictionless table is moving in an isolated system
- If there is friction on the table (rough surface), the block is not sliding in an isolated system anymore.

Conservative Forces in Isolated System

- Work done by a conservative force on a particle moving between any two points is *independent* of the path taken by the particle
- Work done by a conservative force on a particle moving through any closed path is zero

Gravitational Potential Energy

- Gravitational potential energy is the energy associated with the **height** (configuration) of a system of objects that exert forces on each other.
 - Higher altitude = More G.P.E
- When conservative forces *act within an isolated system*, the kinetic energy gained (or lost) by the system as its members **change their relative positions is balanced by an equal loss (or gain) in potential energy**
- This is **Conservation of Mechanical Energy**

Conservation of Mechanical Energy

$$E_{mech} = K + U_g$$

Isolated system (final sum = initial sum):

$$K_f + U_f = K_i + U_i$$

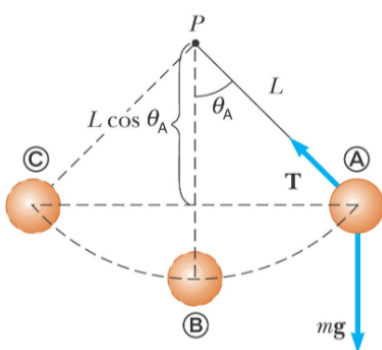
Example:

- Initial conditions:
 - $E_i = K + U_i = mgh$
 - The ball is dropped from rest, so $K_i = 0$
- The configuration for *zero potential energy* is when the ball hits the ground, the **potential energy will become 0**
- Conservation rules at some point y above ground gives
 - $\frac{1}{2}mv_f^2 + mgy = mgh$

Elastic Potential Energy

- Elastic Potential Energy is associated with a spring
- The force the spring exerts is $F_s = -kx$
- The work done by an external applied force on a spring-block system is
 - $W = \frac{1}{2}kx_f^2 - \frac{1}{2}kx_i^2$
 - The work is equal to the **difference between the initial and final values** of an expression related to the configuration of the system
- The elastic potential energy (U) **stored in a spring is zero** whenever the spring is not deformed ($U = 0$ when $x = 0$)
 - The energy stored in the spring only when the spring is *stretched or compressed*
- The elastic potential energy is *maximum when the spring has reached its maximum extension or compression*
- The elastic potential energy will always be positive as x^2 will always be positive

Pendulum



- As the pendulum swings, there is a continuous change between potential and kinetic energies
- At **A**, the energy is *potential*

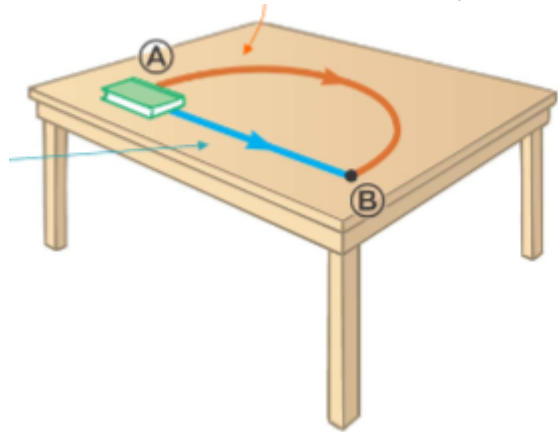
- At **B**, all the potential energy at A is *transformed into kinetic energy*
 - Let zero potential energy be at B
- At **C**, the kinetic energy has been *transformed back into potential energy*

If a system is isolated (no energy leakage at the boundary), the mechanical energy will be conserved, that is, the *sum* of **potential energy** and **kinetic energy** will be constant at all times

The loss in KE will be a gain in PE, $\Delta KE + \Delta PE = 0$

Non-conservative Forces

A **non-conservative force** does not satisfy the conditions of conservative forces, it causes a *change* in the mechanical energy of the system



The work done against friction is greater along the **brown path** than along the **blue path**, as the work done depends on the path, friction is a non-conservative force.

Non-conservative Forces in Mechanical Energy

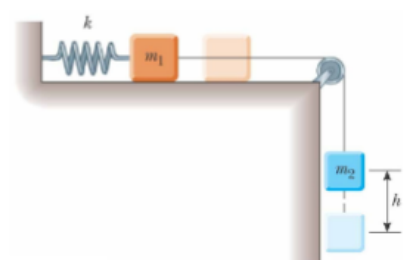
$$\Delta E_{mech} = \Delta K + \Delta U = -f_k d$$

If *friction is zero*, this equation becomes the same as Conservation of Mechanical Energy, $\Delta E_{mech} = 0$, no change in mechanical energy.

Non-conservative Forces in Spring-Mass

- *Without friction*, the energy continues to be transformed between kinetic and elastic potential energies and the total energy remains the same
- If *friction is present*, the energy decreases $\Delta E_{mech} = -f_k d$

Non-conservative Forces in Connected Blocks



- The system consists of the two blocks, the spring and Earth
- Gravitational and potential energies are involved, and friction is not 0
- The kinetic energy is zero if out initial and final configurations are at rest
- Block 2 undergoes a change in gravitational potential energy, while the spring undergoes a change in elastic potential energy
- The coefficient of *kinetic friction* can be measured
- $m_2 g h - (\mu_k m_1 g) \times h = \frac{1}{2} k h^2$