# Notes on Physical Chemistry

Notes I took based loosely on the Natural Sciences curriculum, and then some

Compiled By

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Physical	Chemistry

# **Contents**

I	Qua	antum	mechanics and applications	1	
1	Quantum Mechanics				
	1.1	Introd	luction	3	
		1.1.1	Normalisation	3	
		1.1.2	Momentum	5	
		1.1.3	The uncertainty principle	7	
	1.2	Time-	independent Schrödinger equation	10	
		1.2.1	Stationary states	10	
		1.2.2	The infinite square well	14	
		1.2.3	The harmonic oscillator	20	
			1.2.3.1 Ladder operator	21	
			1.2.3.2 Analytic Method	31	
			1.2.3.3 The Morse potential	38	
		1.2.4	The free particle	40	
		1.2.5	The delta-function potential	46	
			1.2.5.1 Bound states and scattering states	46	
			1.2.5.2 The Dirac delta function	46	

		1.2.5.3	Delta potential: bound states	48
		1.2.5.4	Delta potential: scattering states	50
1.3	Forma	alism		52
	1.3.1	Hilbert	space	52
	1.3.2	Observa	ables	53
		1.3.2.1	Hermitian operators	53
		1.3.2.2	Determinate states	55
	1.3.3	Eigenfu	nctions of a hermitian operator	56
		1.3.3.1	Discrete spectra	56
		1.3.3.2	Continuous spectra	57
	1.3.4	General	ised statistical interpretation	59
	1.3.5	The unc	certainty principle	61
		1.3.5.1	Proof of the generalised uncertainty principle	61
		1.3.5.2	The minimum-uncertainty wave packet	65
		1.3.5.3	The energy-time uncertainty principle	66
	1.3.6	Dirac N	otation	70
1.4	Quan	tum mech	nanics in three dimensions	72
	1.4.1	Schrödi	nger equation in 3D with non-Coulombic potentials	72
		1.4.1.1	Preparatory work	72
		1.4.1.2	The angular equation	74
		1.4.1.3	The radial equation	80
	1.4.2	The hyd	lrogen atom	82
		1.4.2.1	Setting up the radial equation	82
		1.4.2.2	Solving the radial equation	83

127

2 Spectroscopy

		1.4.2.3	Larger nuclei	87
		1.4.2.4	Discussion of hydrogen atomic orbitals	88
	1.4.3	Angulai	r momentum	91
		1.4.3.1	Operator properties	91
		1.4.3.2	Angular momentum ladder operators	92
		1.4.3.3	Eigenfunctions	97
	1.4.4	The rigi	d rotor	100
	1.4.5	Spin		101
		1.4.5.1	Formalism	101
		1.4.5.2	Spin one half	102
		1.4.5.3	Addition of angular momenta - the intuitive way	105
		1.4.5.4	Addition of angular momenta - the ground-up way	106
		1.4.5.5	Permitted values of total momentum	108
		1.4.5.6	Relation between coupling schemes	109
		1.4.5.7	Atomic term symbols	111
		1.4.5.8	Molecular term symbols	115
1.5	Identi	cal partic	les	118
	1.5.1	Two par	rticle systems	118
		1.5.1.1	The Schrödinger equation	118
		1.5.1.2	Centre-of-mass coordinates	118
		1.5.1.3	Bosons and fermions	120
		1.5.1.4	Exchange forces	122

	2.1	Atomi	ic spectro	scopy	127
		2.1.1	Selection	n rules	127
		2.1.2	Fine stru	acture	129
			2.1.2.1	Orbital and spin magnetic moments	129
			2.1.2.2	Spin-orbit coupling	131
	2.2	Molec	ular spec	troscopy	135
		2.2.1	Spectros	scopic methods	135
			2.2.1.1	IR spectroscopy	135
			2.2.1.2	Raman spectroscopy	136
		2.2.2	Transitio	on frequencies	138
			2.2.2.1	The vibrating rotor	138
			2.2.2.2	Determination of rotational constants	140
			2.2.2.3	Q-branch	141
		2.2.3	Polyator	mic molecules	143
			2.2.3.1	Normal coordinates	143
			2.2.3.2	Symmetry of vibrational wavefunctions	144
			2.2.3.3	Symmetry selection rules for infrared	145
		2.2.4	Electron	nic spectroscopy	146
			2.2.4.1	The Franck-Condon principle	146
3	Ann	rovima	ntion met	hads	149
J				method	
	3.1			method	150
		3.1.1	-		150
		3.1.2	Example	es	151

		3.1.3	Secular determinants	155
		3.1.4	The Hückel approximations	157
			3.1.4.1 Example 1	158
	3.2	Pertur	bation theory	162
		3.2.1	Nondegenerate theory	162
		3.2.2	Examples	165
		3.2.3	Degenerate theory	166
	3.3	The H	lartree-Fock method	172
		3.3.1	Self-consistent field method	172
		3.3.2	Accounting for spin	173
		3.3.3	The Hartree-Fock method	175
4	Cro	up theo	orsv	179
<b>T</b>	GIU	up med	bi y	1//
	4.1	The ba	are minimum	179
	4.1	The ba	Symmetry elements and symmetry operations	179 179
	4.1			179
	4.1	4.1.1	Symmetry elements and symmetry operations	179 180
	4.1	4.1.1 4.1.2 4.1.3	Symmetry elements and symmetry operations	179 180
		4.1.1 4.1.2 4.1.3	Symmetry elements and symmetry operations	179 180 180
		4.1.1 4.1.2 4.1.3 Mathe	Symmetry elements and symmetry operations	179 180 180 182
		4.1.1 4.1.2 4.1.3 Mathe	Symmetry elements and symmetry operations	179 180 180 182 182
		4.1.1 4.1.2 4.1.3 Mathe 4.2.1 4.2.2	Symmetry elements and symmetry operations	179 180 180 182 182
		4.1.1 4.1.2 4.1.3 Mathe 4.2.1 4.2.2 4.2.3	Symmetry elements and symmetry operations	179 180 180 182 182 182

		4.2.7	The full rotation group	192
		4.2.8	Group theory and angular momenta	195
	4.3	Appli	cations	197
		4.3.1	Vanishing integrals	197
		4.3.2	Degeneracy	198
		4.3.3	Chemical bonding	200
		4.3.4	LCAOs	201
		4.3.5	Molecular orbital correlation diagrams	201
		4.3.6	Molecular vibrations	203
		4.3.7	Particular vibrations	205
		4.3.8	Projection operator method	205
_	Col:	منعناه	ah ami'atur	200
5	Soli	d state	chemistry	209
5	<b>Soli</b> 5.1		<b>chemistry</b> ninary	<b>209</b> 209
5				
5		Prelin	ninary	<ul><li>209</li><li>209</li></ul>
5		Prelin	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li></ul>
5		Prelin	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li></ul>
5		Prelin	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li><li>210</li></ul>
5		Prelin	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li><li>210</li><li>211</li></ul>
5		Prelim 5.1.1	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li><li>210</li><li>211</li><li>212</li><li>212</li></ul>
5		Prelim 5.1.1	Bravais lattices	<ul><li>209</li><li>209</li><li>209</li><li>210</li><li>211</li><li>212</li><li>212</li></ul>
5		Prelim 5.1.1 5.1.2	Bravais lattices	<ul> <li>209</li> <li>209</li> <li>210</li> <li>211</li> <li>212</li> <li>212</li> <li>214</li> </ul>

		5.2.1.1	One-dimensional FEG	216
		5.2.1.2	Three-dimensional FEG	216
	5.2.2	Quantiz	ation	217
	5.2.3	Fermi-D	Dirac distribution	219
	5.2.4	Propert	ies of the FEG	220
		5.2.4.1	Density of states	220
		5.2.4.2	Fermi quantities	221
		5.2.4.3	Average energy	222
		5.2.4.4	Heat capacity	222
		5.2.4.5	Bulk modulus	223
		5.2.4.6	Electrical conductivity	224
	5.2.5	The nea	rly-free electron gas	225
		5.2.5.1	Failure of the FEG and Brillouin zones	225
		5.2.5.2	Reciprocal lattice	226
		5.2.5.3	Boundary cases	228
5.3	Tight-	binding 1	model	230
	5.3.1	Atomic	orbital bases	230
		5.3.1.1	LCAO method	230
		5.3.1.2	Mixing	232
	5.3.2	Hybrid	orbital bases	233
	5.3.3	Two-orb	pital bases	233
5.4	Semic	onductor	s	234
	5.4.1	Properti	ies of intrinsic semiconductors	234
		5.4.1.1	Conductivity	234

II	Th	ermod	ynamics and statistical mechanics	237
6	namics	237		
	6.1	Entrop	py and the Boltzmann law	237
	6.2	The fu	undamental thermodynamic equations	241
		6.2.1	The fundamental equations	241
		6.2.2	The ideal gas law	242
		6.2.3	Second law and equilibria	244
			6.2.3.1 The second law	244
	6.3	The fir	rst and second laws in depth	249
		6.3.1	The First Law	249
			6.3.1.1 Energy	249
			6.3.1.2 Isothermal and Adiabatic Processes	251
		6.3.2	The Second Law	252
			6.3.2.1 Heat Engines	252
			6.3.2.2 Clausius' theorem	256
		6.3.3	Entropy	258
	6.4	Mathe	ematical methods	260
		6.4.1	Legendre transforms	260
		6.4.2	Euler-Maclaurin formula	263
		6.4.3	Homogeneous functions	264
	6.5	Free e	nergies	265
		6.5.1	Helmholtz free energy	265
			6.5.1.1 Inspiration	265

			6.5.1.2 A microscopic look at Helmholtz I: Dimerisation	267
			6.5.1.3 A microscopic look at Helmholtz II: Polymer collapse	268
		6.5.2	Enthalpy	269
		6.5.3	Gibbs free energy	270
		6.5.4	More on thermodynamic functions	271
			6.5.4.1 Functional dependencies	271
			6.5.4.2 Non-standard states	272
			6.5.4.3 Gibbs-Helmholtz equation	273
		6.5.5	The Euler and Gibbs-Duhem equations	274
			6.5.5.1 The Euler equation	274
			6.5.5.2 The Gibbs-Duhem equation	275
	6.6	Maxw	rell's relations and mixtures	277
		6.6.1	Designing a fundamental equation	277
		6.6.2	Maxwell's relations	278
		6.6.3	Susceptiblities	279
		6.6.4	Entropic and enthalpic components	280
		6.6.5	Partial molar properties	282
_	<b>.</b>	1		205
7	Stat	istical i	nechanics	285
	7.1	The Bo	oltzmann distribution law	285
		7.1.1	The canonical ensemble	285
			7.1.1.1 Derivation	285
		7.1.2	Derivation of Boltzmann distribution	286
			7.1.2.1 Via a Lagrange multiplier	286

		7.1.2.2	From the canonical distribution	289
	7.1.3	Interpre	etation of partition function	290
		7.1.3.1	Physical meaning of the partition function	290
		7.1.3.2	Distinguishability	290
		7.1.3.3	Gibb's paradox	292
	7.1.4	Applica	ations of the Boltzmann distribution	293
		7.1.4.1	Population of states	293
		7.1.4.2	Density of states	294
		7.1.4.3	Non-equilibrium states	295
		7.1.4.4	Maxwell-Boltzmann distribution of velocities	295
	7.1.5	Thermo	odynamic properties from partition functions	297
		7.1.5.1	Distinguishable particles	297
		7.1.5.2	Indistinguishable particles	298
	7.1.6	Example	es of the two-state model	299
		7.1.6.1	The Schottky model	299
		7.1.6.2	Curie's law of paramagnetism	300
		7.1.6.3	Modelling a protein loop	301
7.2	The st	atistical n	mechanics of simple gases	302
	7.2.1	Molecul	lar partition function	302
		7.2.1.1	Translational partition function	302
		7.2.1.2	Vibrational partition function	303
		7.2.1.3	Rotational partition function	304
		7.2.1.4	Electronic partition function	305
	7.2.2	Interal e	energy and heat capacity	306

	7.2.3	Entropy		308
	7.2.4	Nuclear	spin partition function	310
		7.2.4.1	Nuclear exchange	311
		7.2.4.2	Consequences on spectroscopy	311
		7.2.4.3	Consequences on rotational partition function	315
7.3	Chem	ical equili	brium	316
	7.3.1	Prelimir	naries	316
		7.3.1.1	Chemical potential	316
		7.3.1.2	Choice of energy zero	317
	7.3.2	Equilibr	ium constants	317
		7.3.2.1	Calculation of $K_c$	317
		7.3.2.2	Calculation of $K_p$	319
	7.3.3	Example	es	320
		7.3.3.1	Dissociation of a diatomic	320
		7.3.3.2	Ionisation of atoms	321
		7.3.3.3	Adsorption of a gas	322
7.4	Rate c	onstants		327
	7.4.1	Transitio	on state theory	327
		7.4.1.1	The theory	327
		7.4.1.2	Calculation of rate constant	328
	7.4.2	Applicat	tions of transition state theory	329
		7.4.2.1	Rate constant calculation	329
		7.4.2.2	Steric factor	330
		7.4.2.3	Kinetic isotope effects	332

7.4.3	Thermodynamic formulation of transition state theory		333
	7.4.3.1	Transition Gibbs energy	333
	7.4.3.2	Relationship to the Arrhenius equation	334
	7.4.3.3	Experimental determination of $\Delta_r S^{\circ,\ddagger}$ and $\Delta_r H^{\circ,\ddagger}$	337
	7.4.3.4	Volume of activation	337
	7.4.3.5	Interpretation of experimental data	338
A Quick refe	rence		343

## Part I

# Quantum mechanics and applications

Physical Chemistry

## Chapter 5

# Solid state chemistry

## 5.1 Preliminary

## 5.1.1 Bravais lattices

## 5.1.1.1 Definitions

We establish definitions below.

**Definition 5.1.1.1** (Bravais cystal lattice). The *Bravais cystal lattice* is one way to describe crystal lattices, as a translationally periodic array of indistinguishable mathematical points called the *lattice points*. These lattice points are generated by *primitive lattice vectors* (see below).

**Definition 5.1.1.2** (Lattice motif or basis). The lattice points are not, in general, the positions of the atoms or molecules that constitute the physical lattice, however, they are imagined to be identically attached to each of the lattice points in a *motif* or *basis*. The motif can be a single atom, a pair of ions (say with one on the lattic point and one a fixed translation away) and so on.

**Definition 5.1.1.3** (Lattice vectors). *Lattice vectors* are any vectors connecting one lattice point with another.

**Definition 5.1.1.4** (Primitive lattice vectors). *Primitive lattice vectors* can generate the whole lattice by starting at an arbitrary starting lattice point and move by integer multiples of these vectors. These define the edges of *primitive unit cells*.

**Definition 5.1.1.5** (Unit cells). Any non-collinear lattice vectors can define the edges of a *unit cell*. These are *not unique*. They are said to tessellate the entire lattice.

**Definition 5.1.1.6** (Lattice point count). A unit cell can contain any number of lattice point. They are imagined as 'pies' that are cut by the edges, or wholly contained by the cell. For example, a vertex of a cube on the lattice point will account for  $\frac{1}{8}$  of a lattice point and an edge point will account for  $\frac{1}{4}$  of a lattice point.

**Definition 5.1.1.7** (Primitive unit cells). *Primitive unit cells* are unit cells that contain just one lattice point. These are also *not unique*.

## 5.1.1.2 Types of Bravais lattices

There are 14 possible Bravais lattices in three dimensions. They are classed first by their lattice systems, which contains requirements for the three lattice angles, the three cell edge lengths (not necessarily primitive lattice vector lengths unless the lattice is primitive), and the symmetry requirements.

Each lattice system can give rise to a maximum of 4 unit cell types:

- 1. **Primitive** (**P**): Unit cell formed by primitive lattice vectors therefore has a lattice point at each corner.
- 2. **Body-centered** (**I**): Primitive with one lattice point at the centre of the cell.
- 3. **Face-centered** (**F**): Primitive with one lattice point at the centre of each face.
- 4. **Base-centered** (**C**): Face-centered but with lattice points at the center of only one pair of opposing faces, which are conventionally oriented to be the base.

We are only going to look at the cubic lattice system, which says  $\alpha=\beta=\gamma=90^\circ$  and a=b=c, and requires the symmetry of at least four threefold axes at  $109^\circ28'$  (the tetrahedral angle) to each other. The symmetry requirement excludes the base-centered unit cell type. We have three left to study in detail.

### 5.1.1.3 The cubic lattices

## Simple cubic (cubic P)

The unit cell is just a cube with lattice points at the corners, with side length a, the primitive lattice vectors are

$$\mathbf{a}_1 = a(1,0,0) \ \mathbf{a}_2 = a(0,1,0) \ \mathbf{a}_3 = a(0,0,1) \ V_c = a^3$$

## Packing fraction

Imagine spheres centered at the lattice points and they keep expanding until they just touch each other - in this case the spheres on the edges will touch first with  $r=\frac{a}{2}$ . This means the packing fraction,  $\rho$ , of primitive cubic is

$$\rho = \frac{V_{\text{spheres}}}{V_{\text{cell}}} = \frac{\frac{4}{3}\pi r^3}{a^3} = \frac{\frac{4}{3}\pi(\frac{a}{2})^3}{a^3} = \frac{\pi}{6} \approx 52\%$$
 (5.1.1)

## Body-centered cubic (cubic I)

The unit cell that's easiest to picture and work with is a non-primitive unit cell that was described in section 5.1.1.2. The primitive vectors and unit cell volumes are

$$\mathbf{a}_1 = \frac{1}{2}a(1, 1, -1) \ \mathbf{a}_2 = \frac{1}{2}a(-1, 1, 1) \ \mathbf{a}_3 = \frac{1}{2}a(1, -1, 1) \ V_c = \frac{1}{2}a^3$$

*Packing fraction* The spheres along the body diagonal touch first and is equal to 4 radii. The length of the body diagonal is  $\sqrt{3}a = 3r$ , so  $a = 4r/\sqrt{3}$ . There are 2 spheres contained in the unit cell considered, whose volume is  $a^3$ . The packing fraction is then given as

$$\rho = \frac{V_{\text{spheres}}}{V_{\text{cell}}} = \frac{2 \times \frac{4}{3}\pi r^3}{a^3} = \frac{2 \times \frac{4}{3}\pi r^3}{(4r/\sqrt{3})^3} = \frac{\sqrt{3}\pi}{8} \approx 68\%$$
 (5.1.2)

## Face-centered cubic (cubic F)

The unit cell is again non-primitive. The primitive lattice vectors and volume of primitive unit cell are

$$\mathbf{a}_1 = \frac{1}{2}a(1,1,0) \ \mathbf{a}_2 = \frac{1}{2}a(0,1,1) \ \mathbf{a}_3 = \frac{1}{2}a(1,0,1) \ V_c = \frac{1}{4}a^3$$
 (5.1.3)

*Packing fraction* In this case the spheres on the face diagonals touch first and is equal to 4 radii. The length of the face diagonal is  $\sqrt{2}a$ , so  $a = 4r/\sqrt{2}$ . The unit cell contains 4

spheres. The packing fraction is therefore

$$\rho = \frac{V_{\text{spheres}}}{V_{\text{cell}}} = \frac{4 \times \frac{4}{3}\pi r^3}{(4r/\sqrt{2})^3} = \frac{\pi}{3\sqrt{2}} \approx 74\%$$
 (5.1.4)

This is the greatest packing density possible. Therefore the cubic face-centered lattice is also known as *cubic close-packed*.

#### 5.1.1.4 Lattices with a motif

Consider a face-centered cubic lattice, with sodium ions on the lattice points, and chloride ions  $(0,0,\frac{1}{2}a)$  away. A pair of sodium and chloride ions forms the motif for the archetypal NaCl lattice.

## 5.1.2 The ionic model

#### **5.1.2.1** The model

Consider now a 1-D array of alternating negative and positive charges with  $z_{-}$  and  $z_{+}$  charges respectively, spaced a apart. Starting arbitrarily from a positive charge and consider it the origin, looking to the right, the net electrostatic interaction is

$$-\frac{z_{+}z_{-}e^{2}}{4\pi\epsilon_{0}a} + \frac{z_{+}z_{-}e^{2}}{4\pi\epsilon_{0}(2a)} - \frac{z_{+}z_{-}e^{2}}{4\pi\epsilon_{0}(3a)} + \dots$$
 (5.1.5)

Now looking left as well and multiplying by the Avogadro's number we have

$$E_{\text{electrostatic}} = -2N_A \frac{z_+ z_- e^2}{4\pi\epsilon_0 a} \left(1 - \frac{1}{2} + \frac{1}{3} + \dots\right)$$

$$= -2\ln 2N_A \frac{z_+ z_-}{4\pi\epsilon_0 a}$$

$$\equiv -\mathcal{A}N_A \frac{z_+ z_- e^2}{4\pi\epsilon_0 a}$$

$$(5.1.6)$$

where  $A = 2 \ln 2$  is the *Madelung constant*, specific to each lattice under consideration.

However this presents the problem that the interaction energy is always attractive and predicts lattice collapse. An *ansatz* repulsion term  $B/a^n$  has to be introduced, corresponding to quantum mechanical repulsion between filled orbitals. The order n (typically 9 or greater) is fitted *post-hoc* from experimental data on equilibrium lattice spacing, and the constant B can be eliminated as we will show below. The total energy as a function of

lattice spacing a is written as

$$E(a) = -\frac{N_A A z_+ z_- e^2}{4\pi \epsilon_0 a} + \frac{B}{a_n}$$
 (5.1.7)

At equilibrium, dE/da = 0 and  $a = a_0$ , we can write

$$\frac{nB}{a_0^{n+1}} = \frac{N_A \mathcal{A} z_+ z_- e^2}{4\pi \epsilon_0 a_0^2} \tag{5.1.8}$$

which means we can eliminate B by multiplying  $a_0/n$  throughout:

$$\frac{B}{a_0^n} = \frac{N_A \mathcal{A} z_+ z_- e^2}{4\pi \epsilon_0 a_0 n} \tag{5.1.9}$$

So the equilibrium energy is

$$E_0 = -\frac{N_A A z_+ z_- e^2}{4\pi \epsilon_0 a_0} \left( 1 - \frac{1}{n} \right)$$
 (5.1.10)

To get an approximation for lattice energy, which involves the process of

$$MX(s) \longrightarrow M^+(g) + X^-(g)$$

we assume that infinitely separated ions have zero energy, and so  $\Delta U = -E_0$ , and under such a simplistic model is it acceptable to approximate  $\Delta H \approx \Delta U$ , so

**Theorem 5.1.2.1** (Lattice energy). The lattice energy arising from the ionic model is given as

$$\Delta_L H^\circ \approx \frac{N_A \mathcal{A} z_+ z_- e^2}{4\pi\epsilon_0 a_0} \left( 1 - \frac{1}{n} \right)$$
(5.1.11)

The Madelung constant for different lattices are given below

example	coordination	$\mathcal{A}$
CsCl	8:8	1.763
CaF <sub>2</sub>	8:4	2.519
NaCl	6:6	1.748
$TiO_2$	6:3	2.408
ZnS	4:4	1.638
	CsCl CaF <sub>2</sub> NaCl TiO <sub>2</sub>	CsCl 8:8 $CaF_2$ 8:4 NaCl 6:6 $TiO_2$ 6:3

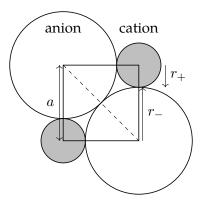
#### 5.1.2.2 Radius ratios

It is not always possible for the ions to touch if say the cations are very large, Cs<sup>+</sup> for example and the anion is very small, F<sup>-</sup> for example, the cations will touch first before the anions can touch the cation *optimally*, meaning doing so while it still resides on the motif points. If this happens the lattice energy is not as large as it can be, and a different lattice may be adopted to allow closest approach of the ions.

We can work out the lowest value of  $r_+/r_-$  for each lattice type:

#### Rock salt

We can work out the minimum radius ratio by drawing out the limiting scenario:



in which the diagonal  $\sqrt{2}a = 2r_{-}$ , and  $a = r_{-} + r_{+}$ , so we can conclude that

$$\frac{r_{+}}{r_{-}} = \frac{a - \sqrt{2}a/2}{\sqrt{2}a/2} = \sqrt{2} - 1 \approx 0.414$$
 (5.1.12)

The minimum radius ratios for other lattice types have been worked out:

lattice	coordination	minimum radius ratio	$\mathcal{A}$
caesium chloride	8:8	0.732	1.763
rock salt	6:6	0.414	1.748
sphalerite	4:4	0.225	1.638

Keeping in mind that  $E \propto \mathcal{A}$ , the lattice would like to keep the lattice energy as high as possible while maintaining maximum contact. For example, for MgO,  $r_+/r_- \approx 0.51$ , which is too small for the caesium chloride structure. So it can 'choose' either rock salt

of sphalerite. As rock salt has higher Madelung constant, it should be preferred, and is indeed the case.

## 5.2 Free-electron gas model

## 5.2.1 Unconstrained FEG

### 5.2.1.1 One-dimensional FEG

This model assumes that electrons do not interact with each other or the nuclei. Essentially they are treated as unconstrained gas molecules. In one dimension, the Schrödinger equation equation was solved in section 1.2.4, with

$$\hat{H} = -\frac{\hbar^2}{2m_e} \frac{\mathrm{d}^2}{\mathrm{d}x^2} \tag{5.2.1}$$

so the Schrödinger equation reads

$$-\frac{\hbar^2}{2m_e}\frac{\mathrm{d}^2\psi}{\mathrm{d}x^2} = E\psi \quad \Rightarrow \quad \frac{\mathrm{d}^2\psi}{\mathrm{d}x^2} = -k^2\psi \tag{5.2.2}$$

where  $k=\frac{2m_{e}E}{\hbar}$  or  $E_{k}=\hbar^{2}k^{2}/2m_{e}$  , the time-dependent solution is

$$|\Psi_k(x,t)\rangle = Ae^{i(kx-\hbar k^2t/2m)}$$
(5.2.3)

with momentum

$$\hat{p}|\Psi_k\rangle = \hbar k \tag{5.2.4}$$

The wavelength can be defined as distance before the phase is reset, so in this case

$$\lambda = \frac{2\pi}{|k|} \tag{5.2.5}$$

## 5.2.1.2 Three-dimensional FEG

In three dimensions, the solution is

$$|\Psi_{\mathbf{k}}(\mathbf{r},t)\rangle = Ae^{i\mathbf{k}\cdot\mathbf{r}-\hbar|\mathbf{k}|^2t/2m}$$
 (5.2.6)

where

$$E_{\mathbf{k}} = \frac{\hbar^2 |\mathbf{k}|^2}{2m_e} \tag{5.2.7}$$

and the momentum is

$$p = \hbar k \tag{5.2.8}$$

and the wavelength is

$$\lambda = \frac{2\pi}{|\boldsymbol{k}|} \tag{5.2.9}$$

Now we need to introduce the important concept of

**Definition 5.2.1.1** (k-space). As the three-dimensional wavefunctions are defined uniquely by the wavevector k, these wavevectors can be thought to correspond to a point in the k-space. The squared distance from the origin is proportional to energy.

## 5.2.2 Quantization

The unconstrained systems above are, of course, not quantised, which is a major problem. We must introduce some sort of boundary condition:

**Theorem 5.2.2.1** (The Born von Karman boundary conditions). The BvG boundary conditions posits that the two edges of the crystals are condinuous, *i.e.*,

$$\Psi(\mathbf{r},t) = \Psi(\mathbf{r} + L_i \mathbf{a}_i, t) \tag{5.2.10}$$

where  $L_i$  is the number of cells in the  $a_i$  direction. In effect, it requires that

$$kL_1 a_i = 2n_1 \pi \implies k = n_1 \left(\frac{2\pi}{L_1 a_1}\right)$$
 (5.2.11)

## Justification of BvK boundary condition

There are two ways to introduce boundary conditions:

- Particle-in-a-box boundary conditions (linear wire)
- BvK boundary conditions (circular wire)

The table below compares the two boundary conditions

	Linear wire	Circular wire
Boundary conditions	$kL = n\pi, n \in \mathbb{Z}^+$	$kL=2n\pi$ , $n\in\mathbb{Z}$
Energies	$E_n = \hbar^2 \pi^2 n^2 / 2mL^2$	$E_n = 4\hbar^2 \pi^2 n^2 / 2mL^2$
Eigenfunctions	$A\sin(n\pi x/L)$	$B\exp(2ni\pi x/L)$

Basically, the energy levels for the two models look like this

Linear wire Circular wire 
$$E_n \uparrow \\ n=4, E_n=16 - \\ n=3, E_n=9 - \\ n=2, E_n=4 - \\ n=1, E_n=1 - \\ -n=0, E_n=0$$

And in the limit that  $N \to \infty$ , the density of states is approximately the same, and also the HOMO, now Fermi level, is also the same.

So what's different? The reason for choosing the circular wire is threefold:

- 1. The eigenfunctions of the linear wire are not eigenfunctions of the momentum operator, while the circular wire ones are, yielding  $\hbar k$  naturally.
- 2. By ignoring the surface effects, the boundary conditions of the linear wire do not arise as there's no 'outside' where  $V(x)=\infty$ .
- 3. The circular wire allows potential energy functions of symmetry V(x+Na)=V(x), while the linear wire does not. This is important in the full theory.

Simply put, the crystal is imagined to be infinite so that the edge effects are ignored.

In the k-space, the allowed wavefunctions (states) are just a series of points spaced  $2\pi/L_1a_1$  apart. The density of BvK allowed states in 1D is therefore

$$\frac{L_1 a_1}{2\pi} \equiv \frac{\mathcal{L}}{2\pi} \tag{5.2.12}$$

where  $\mathcal{L} = L_1 a_1$  is called the BvK length.

In two and three dimensions the density of BvK allowed states are readily generalised to

2D: 
$$\frac{L_1 L_2 A_c}{(2\pi)^2} \equiv \frac{\mathcal{A}}{(2\pi)^2}$$
  
3D:  $\frac{L_1 L_2 L_3 V_c}{(2\pi)^2} \equiv \frac{\mathcal{V}}{(2\pi)^3}$  (5.2.13)

## 5.2.3 Fermi-Dirac distribution

The Maxwell-Boltzmann distribution assumes that the particles are distinguishable and any number of particles can occupy a level. However that is clearly not applicable to electrons, which are fermions. The Pauli exclusion principle states that two of more *identical fermions* cannot occupy the same quantum state. A distribution adhering to the Pauli exclusion principle is the

**Theorem 5.2.3.1** (Fermi-Dirac distribution). The distribution states that the average number of fermions in a single-particle state i is given by

$$\langle n_i \rangle = \frac{1}{\exp[(\epsilon_i - \mu)/kT] + 1} \tag{5.2.14}$$

where we can write  $\langle n_i \rangle$  as  $f(\epsilon_i)$ , and approximate the chemical potential  $\mu$  with the *Fermi energy*,  $\epsilon_F$ , to give

$$f(\epsilon_i) = \frac{1}{\exp[(\epsilon_i - \epsilon_F)/kT] + 1}$$
 (5.2.15)

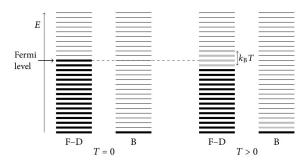
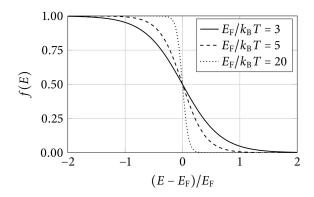


Figure 5.1: Comparison between the predictions of Fermi-Dirac and Maxwell-Boltzmann distributions

The result is a logistic function ranging from 1 for energies much lower than the Fermi level to 0 for energies much higher than the Fermi level. Raising the temperature has the effect of exciting particles near the Fermi level, 'blurring' the distribution:



**Figure 5.2:** The blurring of the Fermi-Dirac distribution occurs at higher temperatures. Notice it always runs from 1 to 0, as required by the Pauli exclusion principle.

**Definition 5.2.3.1** (Fermi quantities). The *Fermi energy* is defined only at 0 K, which is defined as the highest filled level at 0K.

The *Fermi level*,  $E_{\rm F}$  is the energy level correponding to Fermi energy, but remains defined for all temperatures.

The *Fermi wavevector*,  $k_{\rm F}$  is the wavevector corresponding to the Fermi level.

Alternatively, the Fermi level can be approximately seen to be the energy level that has half occupancy at non-zero temperatures.

## 5.2.4 Properties of the FEG

## 5.2.4.1 Density of states

The density of BvK states in 3D is

$$W(E) = \underbrace{\frac{4}{3}\pi |\mathbf{k}|^3}_{\text{'volume'}} \times \underbrace{\frac{\mathcal{V}}{(2\pi)^3}}_{\text{density}}$$
(5.2.16)

and we know that

$$|\mathbf{k}| = \left(\frac{2m_e E}{\hbar^2}\right)^{\frac{1}{2}} \tag{5.2.17}$$

Keeping in mind that we although each level can accept only one *identical* Fermion, electrons have two spin states and they spin-pair so each level can be doubly occupied, so a

factor of two is applied in front:

$$W(E) = 2 \times \frac{4}{3}\pi |\mathbf{k}|^3 \times \frac{\mathcal{V}}{(2\pi)^3} = \frac{|\mathbf{k}|^3 \mathcal{V}}{3\pi^2} = \frac{\mathcal{V}}{3\pi^2} \left(\frac{2m_e E}{\hbar^2}\right)^{\frac{3}{2}}$$
(5.2.18)

Density of states soon follows by simple differentiation

**Theorem 5.2.4.1** (Density of BvK states). The number of BvK states with energy up to E is given as

$$W(E) = \frac{V}{3\pi^2} \left(\frac{2m_e E}{\hbar^2}\right)^{\frac{3}{2}}$$
 (5.2.19)

so the density of states is given as

$$D(E) = \frac{dW(E)}{dE} = \frac{V}{2\pi^2} \left(\frac{2m_e}{\hbar^2}\right)^{\frac{3}{2}} E^{\frac{1}{2}}$$
 (5.2.20)

We note that the density of states increase with energy.

## 5.2.4.2 Fermi quantities

Suppose that the number density of electrons in the metal is  $n_e$ , so there are  $n_e \mathcal{V}$  electrons in the BvK volume. At absolute zero, where Fermi energy is defined, we can say that the number of states filled are equal to the number of electrons<sup>1</sup>, which is to say

$$W(E_{\rm F}) = n_e \mathcal{V} \tag{5.2.21}$$

so

$$\frac{\mathcal{V}}{3\pi^2} \left(\frac{2m_e E_F}{\hbar^2}\right)^{\frac{3}{2}} = n_e \mathcal{V}$$

$$\Rightarrow E_F = \left(\frac{\hbar^2}{2m_e}\right) (3\pi^2 n_e)^{3/2} \tag{5.2.22}$$

And the Fermi wavevector can also be worked out:

$$|\mathbf{k}|_{\rm F} = (3\pi^2 n_e)^{1/3} \tag{5.2.23}$$

To summarise

<sup>&</sup>lt;sup>1</sup>Although we commonly think of the levels as being doubly filled, for the formalism of the BvK we think of two degenerate levels at the same energy, one for the spin up electron one for the spin down.

**Theorem 5.2.4.2** (Fermi level and wavevector). For a metal with eletron density  $n_e$ , the Fermi level and Fermi wavevector are given as

$$E_{\rm F} = \left(\frac{\hbar^2}{2m_e}\right) (3\pi^2 n_e)^{3/2}$$

$$|\mathbf{k}|_{\rm F} = (3\pi^2 n_e)^{1/3}$$
(5.2.24)

## 5.2.4.3 Average energy

At absolute zero the average energy is

$$\langle E \rangle = \frac{\text{total energy}}{\text{number of states}} = \frac{\int_0^{E_F} E \times D(E) \, dE}{\int_0^{E_F} D(E) \, dE}$$
 (5.2.25)

The integrals are straightforward and the result is

**Theorem 5.2.4.3** (Average energy at absolute zero). The Fermi-Dirac distribution predicts that for a free electron gas, the average energy at absolute zero is

$$\langle E \rangle = \frac{3}{5} E_{\rm F} \tag{5.2.26}$$

## 5.2.4.4 Heat capacity

Assuming that the metal atom has only 1 valence electron, one mole of the metal contains  $N_A$  valence electrons. To a crude approximation, the number of excited electrons (those within kT of Fermi level) is

$$n = N_A \times \frac{kT}{E_F} = \frac{RT}{E_F} \tag{5.2.27}$$

Again, to an approximation, these electrons on average has kT more in energy<sup>2</sup>, so the total increase in energy as a result of raised temperature is

$$\Delta U = kT \frac{RT}{E_{\rm F}} \equiv \frac{R}{T_{\rm F}} T^2 \tag{5.2.28}$$

where  $T_{\rm F} = E_{\rm F}/k$  is the Fermi temperature, so the heat capacity is roughly

$$C_{V,m} = \frac{2R}{T_{\rm F}} \times T \tag{5.2.29}$$

<sup>&</sup>lt;sup>2</sup>They already had some intrinsic kinetic energy as a consequence of the Fermi-Dirac distribution, and now they have an additional kT in 'thermal' energy, which is just additional kinetic energy.

This treatment gives poor agreement with data, as the estimation of the number of electrons is poor and does not take into account the density of states. A more sophisticated treatment gives

$$C_{V,m} = \frac{\pi^2 RT}{2T_{\rm F}} \tag{5.2.30}$$

## 5.2.4.5 Bulk modulus

The bulk modulus is the ratio between the pressure change and the fractional change in volume, which, in calculus terms is

$$B = -V \left(\frac{\partial p}{\partial V}\right)_{T,N} \tag{5.2.31}$$

Also the definition of pressure in terms of the internal energy is

$$p = -\left(\frac{\partial U}{\partial V}\right)_{N} \tag{5.2.32}$$

At absolute zero, we know the average energy, so the internal energy is

$$U = N\langle E \rangle = \frac{3}{5}NE_{\rm F} \tag{5.2.33}$$

The Fermi energy is

$$E_{\rm F} = \left(\frac{\hbar^2}{2m_e}\right) (3\pi^2 n_e)^{2/3} \tag{5.2.34}$$

The electron number density, in the formalism of BvK is just

$$n_e = \frac{N}{V} \tag{5.2.35}$$

So we can write

$$U = \frac{3}{5}N\underbrace{\left(\frac{\hbar^2}{2m_e}\right)(3\pi^2N)^{2/3}}_{c}\mathcal{V}^{-2/3}$$
(5.2.36)

So

$$p = \frac{2}{5}Nc\mathcal{V}^{-5/3} \tag{5.2.37}$$

and the bulk modulus is

$$B = \frac{2}{3}Nc\mathcal{V}^{-5/3} \tag{5.2.38}$$

Since  $E_{\rm F} = c \mathcal{V}^{-2/3}$ , we can finally write

$$B = \frac{2}{3}E_{\rm F}N/\mathcal{V} = \frac{2}{3}E_{\rm F}n_e \tag{5.2.39}$$

## 5.2.4.6 Electrical conductivity

The 'ground state' of a 2-dimensional FEG in the k-space at 0 K will show occupied k-states within a circle of radius  $|\mathbf{k}|$  centred at (0,0), as the highest occupied level is the Fermi level (at 0 K), and the momentum given by  $\hbar \mathbf{k}$  is on average zero. The circle is called the *Fermi circle*.

Now after the application of an electric field along the x-direction, the average momentum will be in the x-direction<sup>3</sup>, so the centre of the Fermi circle will be shifted to the right.

It is important to note that the only reason conduction can happen is because there are vacant states just outside the Fermi circle.

A simple model that can give us the conductivity is the

**Theorem 5.2.4.4** (The Drude model). The Drude model says that the drift velocity,  $v_{\rm d}$  is given by

$$v_{\rm d} = e\mathcal{E}\tau/m_{\rm e} \tag{5.2.40}$$

*Proof.* The net acceleration experienced by the electron due to the field is  $e\mathcal{E}/m_{\rm e}$ . Supposing that the average time between collisions is  $\tau$ , which knocks the speed down to zero again, the average velocity is just accleration times time, which gives the result required.

The current density is defined as the charge per unit time per unit area, which can be written as

$$j = \frac{n_{\rm e}v_{\rm d}\Delta t Ae}{\Delta t A} = n_{\rm e}v_{\rm d}e = n_{\rm e}e^2 \mathcal{E}\tau/m_{\rm e}$$
 (5.2.41)

The Ohm's law says that

$$j = \sigma \mathcal{E} \tag{5.2.42}$$

so we can extract

$$\sigma = n_{\rm e}e^2\tau/m_{\rm e} \tag{5.2.43}$$

<sup>&</sup>lt;sup>3</sup>It is not infinite because electrons are scattered so a steady-state *drift velocity* is reached.

The *electron mobility*,  $\mu_e$  (not magnetic susceptibility) is

$$\mu_{\rm e} \equiv \frac{v_{\rm d}}{\mathcal{E}} = \frac{e\tau}{m_{\rm e}} \tag{5.2.44}$$

## 5.2.5 The nearly-free electron gas

#### 5.2.5.1 Failure of the FEG and Brillouin zones

The free electron gas assumes no interactions whatsoever with the underlying lattice, which is of course not true. The FEG model notably fails when the wavefunctions  $\psi_k$  are diffracted by the lattice. To take this into account, the Brillouin zone is defined:

**Definition 5.2.5.1** (Brillouin zone). The boundaries of the *Brillouin zone* in k-space are collections of wavefunctions that undergo Bragg diffraction<sup>a</sup>. These boundaries are therefore also called Bragg planes. The first Brillouin zone correspond to the collection of k-states reachable from the origin without having to cross a Bragg plane, while the second Brillouin zone are such points reachable by crossing just one Bragg plane, and so on.

<sup>a</sup>This means the waves are refracted by atoms on a series of parallel planes in the *real space*.

We need to find the Bragg planes in k-space now. Referring to draw diagram, we can see that the Bragg condition is

$$2a\sin\theta = n\lambda\tag{5.2.45}$$

where n is the integer and will be the order of the Brillouin zone. The de Broglie relation of the incoming waves says

$$\lambda = \frac{h}{|\mathbf{p}|} = \frac{h}{\hbar |\mathbf{k}|} = \frac{2\pi}{|\mathbf{k}|} \tag{5.2.46}$$

So we now have

$$2a\sin\theta = \frac{2\pi n}{|\mathbf{k}|}\tag{5.2.47}$$

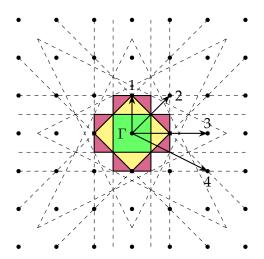
Realising that  $|\mathbf{k}| \sin \theta$  is the component of the wavevector perpendicular to the diffracting plane<sup>4</sup>, we can just write

$$k_{\perp} = \frac{n\pi}{a} \tag{5.2.48}$$

In one dimension, as  $|\mathbf{k}| = k_{\perp}$ , the Bragg planes are just scalar points at integer multiples of  $n\pi/a$ . In two dimensions, the construction method is to draw perpendicular bisectors connecting the origin and the closest four points in the *reciprocal lattice*, which will enclose

<sup>&</sup>lt;sup>4</sup>Remember that  $p = \hbar k$ , so the wavevector just lies in the direction of propagation / incidence.

the first Brillouin zone, and then the same is repeated for the next four closest points, for the second Brillouin zone and so on, always extend the Bragg planes as long as possible so you don't get confused whether you've crossed a Bragg plane or not.



Note that the fourth Brillouin zone is not coloured in.

## 5.2.5.2 Reciprocal lattice

The motivation for defining a reciprocal lattice is to construct a lattice in k-space with a periodicity that's related to the real space lattice. The simplest way to fulfil that is to consider a collection of waves in real space such that

$$\Psi_{\mathbf{k}}(\mathbf{r}) = \Psi_{\mathbf{k}}(\mathbf{r} + \mathbf{R}) \tag{5.2.49}$$

where R is any lattice vector (not just primitive vectors). Essentially, their phase differ by some integer multiple between  $2\pi$  between lattice points. A collection of these waves in k-space forms the reciprocal lattice. The equation above can be further developed:

$$\Psi_0 e^{i\mathbf{k}\cdot\mathbf{r}} = \Psi_0 e^{i\mathbf{k}\cdot(\mathbf{r}+\mathbf{R})}$$

$$\Rightarrow e^{i\mathbf{k}\cdot\mathbf{R}} = 1$$

$$\Rightarrow \mathbf{k} \cdot \mathbf{R} = 2n\pi$$
(5.2.50)

Considering that  $\mathbf{R} = \sum A_i \mathbf{a}_i$  and  $\mathbf{k} = \sum B_i \mathbf{b}_i$ , we can choose the simplest basis<sup>5</sup> so that

$$\boldsymbol{b}_i \cdot \boldsymbol{a}_j = \delta_{ij} \tag{5.2.52}$$

This way we can construct a reciprocal lattice from a real lattice. The above relation is general and easily applied in 2D cases, however in 3D the following relation, derive from the expression above, can come in handy:

$$\boldsymbol{b}_3 = \frac{2\pi(\boldsymbol{a}_1 \times \boldsymbol{a}_2)}{\boldsymbol{a}_3 \cdot (\boldsymbol{a}_1 \times \boldsymbol{a}_2)} \tag{5.2.53}$$

and cyclic permutations thereof.

The derivation is simple once we note that

$$\frac{(\boldsymbol{a}_1 \times \boldsymbol{a}_2)}{\boldsymbol{a}_3 \cdot (\boldsymbol{a}_1 \times \boldsymbol{a}_2)} = \frac{\boldsymbol{a}_3}{|\boldsymbol{a}_3|}$$
 (5.2.54)

We also note that  $a_3 \cdot (a_1 \times a_2) = V_c$ , the volume of unit cell. The foregoing is summarised below

**Theorem 5.2.5.1** (Construction of reciprocal lattice). The reciprocal lattice primitive vectors are given, in general

$$\boldsymbol{b}_i \cdot \boldsymbol{a}_j = \delta_{ij} \tag{5.2.55}$$

and in 3D,

$$\boldsymbol{b}_3 = \frac{2\pi(\boldsymbol{a}_1 \times \boldsymbol{a}_2)}{V_c} \tag{5.2.56}$$

and cyclic permutations thereof.

The volume of the reciprocal lattice unit cell is

$$\Omega = \boldsymbol{b}_1 \cdot (\boldsymbol{b}_2 \times \boldsymbol{b}_3) \tag{5.2.57}$$

which is

$$\Omega = \frac{(2\pi)^2}{V_c^3} (\boldsymbol{a}_1 \times \boldsymbol{a}_2) \cdot [(\boldsymbol{a}_2 \times \boldsymbol{a}_3) \times (\boldsymbol{a}_3 \times \boldsymbol{a}_1)]$$
 (5.2.58)

the big vectorial mess at the end is a number since overall it's a dot product, and since it

$$\begin{pmatrix}
B_1 & B_2 & B_3
\end{pmatrix}
\begin{pmatrix}
\mathbf{b}_1 \cdot \mathbf{a}_1 & \mathbf{b}_1 \cdot \mathbf{a}_2 & \mathbf{b}_1 \cdot \mathbf{a}_3 \\
\mathbf{b}_2 \cdot \mathbf{a}_1 & \mathbf{b}_2 \cdot \mathbf{a}_2 & \mathbf{b}_2 \cdot \mathbf{a}_3 \\
\mathbf{b}_3 \cdot \mathbf{a}_1 & \mathbf{b}_3 \cdot \mathbf{a}_2 & \mathbf{b}_3 \cdot \mathbf{a}_3
\end{pmatrix}
\begin{pmatrix}
A_1 \\
A_2 \\
A_3
\end{pmatrix} = 2n\pi$$
(5.2.51)

so there can be more than one way to choose the basis set  $\{b_i\}$ , but obviously the easiest way out is to make it orthogonal to  $\{a_i\}$ . The remaining coefficients must have  $\sum A_iB_i = n$ , since the  $A_i$ 's are integers and l is a integer, the  $B_i$ 's have to be integers as well, *i.e.*, the  $b_i$ 's are primitive vectors for the reciprocal lattice.

 $<sup>{}^5</sup>$ The matrix equation is

involves every vector twice, it's just  $V_c^2$ , so the reciprocal unit cell volume is

$$\Omega = \frac{(2\pi)^3}{V_c} \tag{5.2.59}$$

## 5.2.5.3 Boundary cases

The foregoing discussion pointed out the FEG approximations fail at Bragg planes, which is to say the dispersion curve have *discontinuities* at Bragg planes. This provides a motivation for us to study the k-states near the discontinuities more closely.

One way to take the interactions into account is by still looking at the wavefunction predicted by the FEG at the lattice points, and taking that as an indication of how strongly the wavefunction will interact with the lattice at that point.

We note that plane waves with wavenumbers k and  $k+n\times(2\pi/a)$  have the same amplitude at all the lattice points spaced a apart. This leads to the idea that the dispersion curve for the entire k-space can be drawn within  $-\pi/a$  to  $+\pi/a$ , as curves stacked on top of each other. This is known as the *reduced zone representation*. draw diagram

Now we can add in the interactions. We single out the k-points  $\pm \pi/a$ , whose corresponding wavefunctions are

$$\psi_{+} = \exp(+i\pi x/a) \ \psi_{-} = \exp(-i\pi x/a)$$
 (5.2.60)

These are complex functions, but they are degenerate, so any linear combinations of the two are eigenfunctions too:

$$\psi_{c} = \frac{1}{2}(\psi_{+} + \psi_{-}) = \cos(\pi x/a) \quad \psi_{s} = \frac{1}{2i}(\psi_{+} - \psi_{-}) = \sin(\pi x/a)$$
 (5.2.61)

From draw diagram,  $\psi_s$  has amplitude 0 at all lattice points and  $\psi_c$  has  $\pm 1$  (maximum) at all of them. The consequence is that the two eigenfunctions is no longer degenerate, with  $\psi_c$  raised in energy. This leads to the creation of a band gap, separating the first and second Brillouin zones.

## Predictions about conductivity

The density of BvK states<sup>6</sup> in one dimension is  $La/2\pi$ , so in the first Brillouin zone, in the range of  $-\pi/a$  to  $+\pi/a$ , there are L BvK states. So for a metal with one valence eletron,

<sup>&</sup>lt;sup>6</sup>These can be doubly filled.

the first zone is only half filled. We can visualise it by thinking of a Fermi circle of half the area of the first Brillouin zone, as long as it doesn't touch the Bragg planes, otherwise the circle will be 'flattened' to avoid crossing over the band gap to the second zone.

For metals with two valence electrons, the 1D model will predict that it'll behave like a thermally activated conductor, *i.e.*, a semiconductor, as the band gap must be crossed to produce mobile electrons.

However for a metal with three valence electrons the theory predicts it to be a conductor again, and so on. We obviously don't observe the alternating conductor-semiconductor trend for real metals, and in part it's because we're using the 1D theory for 3D metallic lattices. And from the discussions about Fermi circle above, a Fermi sphere in 3D will behave in even more complicated ways, and quantifying anything becomes increasingly difficult. Clearly, a better, more qualitative theory is needed.

## 5.3 TIGHT-BINDING MODEL

## 5.3.1 Atomic orbital bases

#### 5.3.1.1 LCAO method

### Forming crystal orbitals

Consider a lattice with an orbital suitable for forming bands at each lattice. Using the LCAO method, we create linear combinations, called *crystal orbitals*, written as

$$\psi_k = \sum_{r=1}^{N} c_k^{(r)} \phi_r \tag{5.3.1}$$

There must be N different crystal orbitals arising from N lattice orbitals, hence the index N. The index r means position.

#### Boundary conditions

We apply the BvK boundary conditions as before (assuming the wavefunction is continuous between position 1 and position N, i.e., N orbitals form a ring.) The Schrödinger equation equation is

$$\hat{H}\psi_k = E\psi_k \tag{5.3.2}$$

and the coefficients  $ck^{(r)}$  arise exactly:

$$c_k^{(r)} = e^{ikra}, \ kNa = 2m\pi, \ m = 0, \pm 1, \pm 2, \dots$$
 (5.3.3)

notice that this is essentially the same quantisation we got from the FEG, see Theorem 5.2.2.1. One important thing to note is that, as we switched to the tight-binding model, we can't say V(x)=0, so the Hamiltonian no longer communtes with the momentum operator, so k is no longer proportional to momentum. Instead, k serves as the *symmetry label* for the crystal orbital supply proof. But much like the FEG, we can show that all the unique symmetry labels lie within the first Brillouin zone.

## Energy calculation with Hückel approxmiations

The energies of the crystal orbitals are simply

$$E_k = \frac{\langle \psi_k | H | \psi_k \rangle}{\langle \psi_k | \psi_k \rangle} \tag{5.3.4}$$

The Hückel approximations apply to the *atomic orbitals*, whose linear combinations make up  $\psi_k$ , with atomic energy  $\alpha$  and neighbour interactions  $\beta$ . So the denominator is

$$\langle \psi_k | \psi_k \rangle = \int \left( \sum_{r=1}^N e^{-ikra} \phi_r^* \right) \left( \sum_{r'=1}^N e^{-ikr'a} \phi_{r'} \right) d\tau$$

$$= \int \sum_{r=1}^N \phi_r^* \phi_r d\tau = N$$
(5.3.5)

The numerator is

$$\langle \psi_k | H | \psi_k \rangle = \int \left( \sum_{r=1}^N e^{-ikra} \phi_r^* \right) H \left( \sum_{r'=1}^N e^{-ikr'a} \phi_{r'} \right) d\tau$$

$$= \sum_{r,r'} \int e^{ik(r'-r)a} \phi_r^* H \phi_{r'} d\tau$$
(5.3.6)

#### complete this when you have time

**Theorem 5.3.1.1** (One-dimensional crystal orbitals and energies). In one dimension, an  $ss - \sigma$ -type band has the orbitals and energies

$$E_k = \alpha + 2\beta \cos(ka) - \pi/a \le k \le +\pi/a$$

$$\psi_k = N^{-1/2} \sum_{r=1}^N e^{ikra} \phi_r \ k = m \left(\frac{2\pi}{Na}\right) \ m = 0, \pm 1, \pm 2, \dots, \pm N/2$$
(5.3.7)

A  $pp - \sigma$ -type band has same orbitals but the energies are 'bent' the other way:

$$E_k = \alpha - 2\beta \cos(ka) - \pi/a \le k \le +\pi/a \tag{5.3.8}$$

It is important to note that these are *spatial orbitals*, so each can accommodate 2 electrons. So all in the band can accommodate 2N electrons in total.

The density of *spatial states*<sup>7</sup> can be derived by first computing the number of states W(E), which we can write in an implicit form with respect to k, since we know the k-spacings

<sup>&</sup>lt;sup>7</sup>For the FEG, we derived the density of *spin states* since the properties we derived from the FEG was mostly bulk properties of electrons, like conductivity. But with the tight binding model we tend to draw analogy to the LCAO method, in which spatial orbitals are used.

between states are  $2\pi/Na$ :

$$W(E) = \frac{2k}{2\pi/Na} = \frac{Nka}{\pi} \tag{5.3.9}$$

and the derivative can be computed with the chain rule:

$$D(E) = \frac{\mathrm{d}W(E)}{\mathrm{d}E} = \frac{\mathrm{d}W(E)}{\mathrm{d}k} \times \frac{\mathrm{d}k}{\mathrm{d}E}$$

$$= \frac{Na}{\pi} \frac{1}{\frac{\mathrm{d}k}{\mathrm{d}E}}$$

$$= \frac{Na}{\pi} \frac{1}{-2\beta a \sin(ka)}$$

$$= \frac{-N}{2\pi\beta} \csc(ka)$$
(5.3.10)

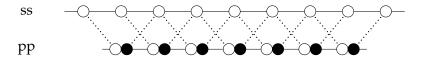
We note that the density of states asymptotes to infinity at k=0 and  $\pm \pi/a$  (band boundaries).

## 5.3.1.2 Mixing

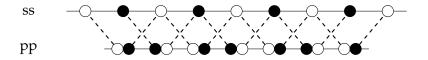
As mentioned above, k is the symmetry label for crystal orbitals. Therefore we expect orbitals with the same k to mix. However, mixing does not promise energetic benefits, as the Hamiltonian term can turn out to be zero, as we'll see below.

The case of k = 0 and  $k = \pi/a$ 

At k=0, the orbitals are made up of  $\phi_r$ 's with the same coefficient, and the interactions look like follows



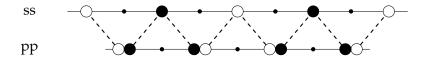
at  $k=\pi/a$ , the orbitals are made up of  $\phi_r$ 's with alternating coefficients (real part), and the interactions look like follows



Clearly, half the interactions are constructive and half are destructive, so there's overall no net mixing.

The case of  $k = \pi/2a$ 

At  $k = \pi/2a$ , the coefficients cycle in  $\{1, 0, -1, 0\}$ , so we have the following interactions. Note that the diagram is drawn by taking the real part of the ss band and the imaginary part of the pp band<sup>8</sup>:



In summary, mixing does not happen at k=0 or  $k=\pi/a$ , the band boundary, and is strongest at  $k=\pi/2a$ .

## 5.3.2 Hybrid orbital bases

Instead of mixing s and p orbitals after formation of crystal orbitals, we can just hybridise them first. We follow the following guidelines

- 1. Form left and right pointing arrays of HAOs in the same phase
- 2. Overlap these constructively and destructively into  $\sigma$  and  $\sigma^*$
- 3. incomplete

## 5.3.3 Two-orbital bases

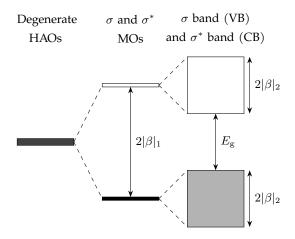
incomplete

<sup>&</sup>lt;sup>8</sup>This is justified by thinking about the actual integral in the secular equation, which is incomplete

## 5.4 Semiconductors

## 5.4.1 Properties of intrinsic semiconductors

Classic intrinsic semiconductors include Group 14 elements such silicon and germanium, which are tetrahedral solids. The bonding is much the same as discussed in 1D, with neighbouring  $sp^3$  hybrids forming  $\sigma$  and  $\sigma^*$  MOs, the neighbouring MOs then interact to form bands, as shown below



On descending Group 14,  $|\beta|_1$ , which results from overlap of the directly pointing hybrids, decrease in magnitude, as the orbitals become more diffuse; however  $|\beta|_2$  which is proportional how? to  $\alpha_p - \alpha_s$ , becomes larger as the s-p separation increases down the group. The overall result is that the *band gap decreases down the group*:

	Diamond	Si	Ge	$\alpha$ -Sn	Pt
$E_{\rm g}$ (eV)	5.3	1.14	0.67	0.08	Not tetrahedral

Note lead is not tetrahedral due to the high promotion energy to form hybrids.

## 5.4.1.1 Conductivity

#### **Definitions**

- **Resistivity** is the inherent property of a material  $\rho = RA/l$ , with units of  $\Omega$  m.
- Conductance is the reciprocal resistance, G = 1/R, with units of Siemens, S, which is equivalent of  $\Omega^{-1}$ .

• Conductivity is the reciprocal resistivity,  $\sigma = 1/\rho = Gl/A$ , with units of S m<sup>-1</sup>.

Conductivity is governed by the equation

$$\sigma = n_{\rm e}e\mu_{\rm e} + n_{\rm h}e\mu_{\rm h} \tag{5.4.1}$$

where the  $\mu_i$ 's are again not permittivity constants but *mobility* of electrons and holes.

## Part II

# Thermodynamics and statistical mechanics

Physical Chemistry	

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