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# **CS722/822: Machine Learning**

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# Model Evaluation

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- Metrics for Performance Evaluation
  - How to evaluate the performance of a model?
- Methods for Performance Evaluation
  - How to obtain reliable estimates?
- **Methods for Model Comparison**
  - How to compare the relative performance among competing models?

# ROC (Receiver Operating Characteristic)

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- Developed in 1950s for signal detection theory to analyze noisy signals
  - Characterize the trade-off between positive hits and false alarms
- ROC curve plots TPR (on the y-axis) against FPR (on the x-axis)
- A pair of (TPR, FPR) is represented as a point on the ROC curve
- Adjusting certain parameter of a detector can generate a series of (TPR, FPR) pairs, which lead to a curve
- A classifier has similar behavior to a signal detector, when it returns a real-valued prediction
  - Also need to balance the TPR and FPR
  - Changing the classification threshold changes the location of the point

# ROC Curve

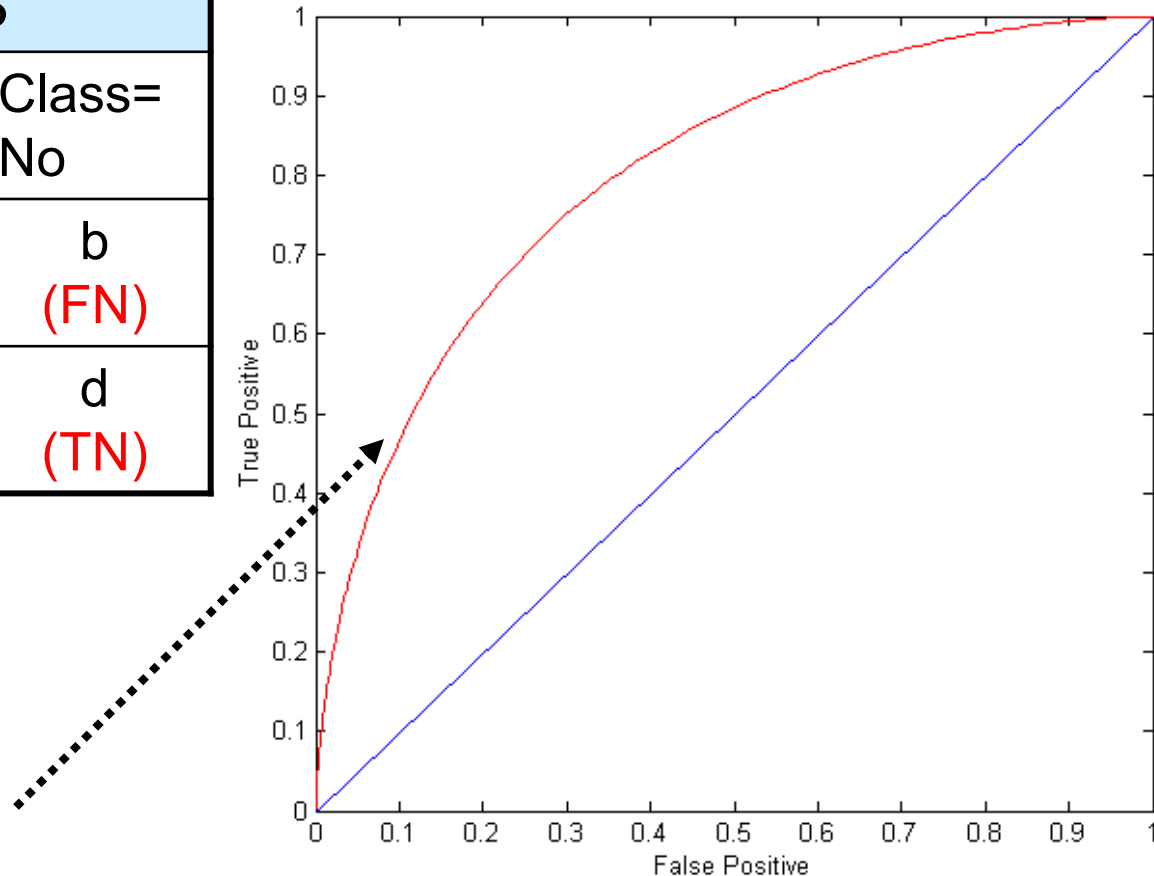
ACTUAL CLASS	PREDICTED CLASS	
	Class =Yes	Class= No
	Class =Yes a (TP)	b (FN)
Class =No	c (FP)	d (TN)

$$\text{TPR} = \text{TP}/(\text{TP}+\text{FN})$$

$$\text{FPR} = \text{FP}/(\text{FP}+\text{TN})$$

At threshold t:

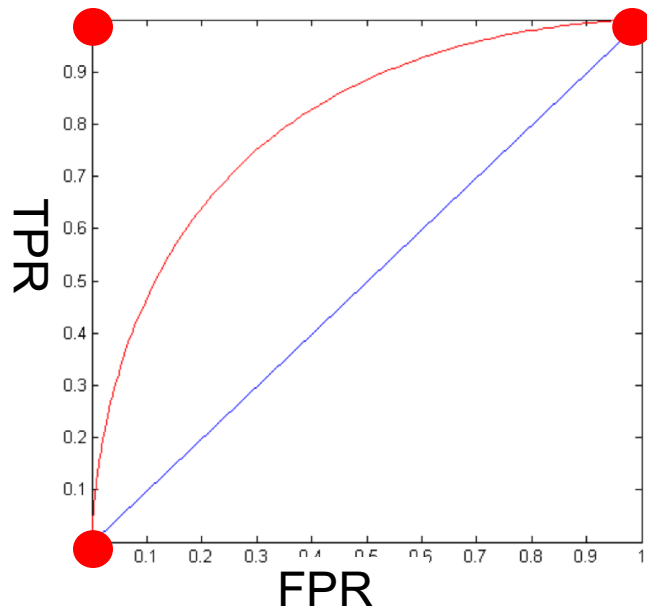
TP=50, FN=50, FP=12, TN=88



# ROC Curve

ACTUAL CLASS	PREDICTED CLASS	
		Class=Yes Class=No
	Class=Yes	Class=No
		Class=Yes Class=No
	Class=Yes	a (TP)      b (FN)
	Class=No	c (FP)      d (TN)

**TPR** =  $TP / (TP + FN)$ ; **FPR** =  $FP / (FP + TN)$



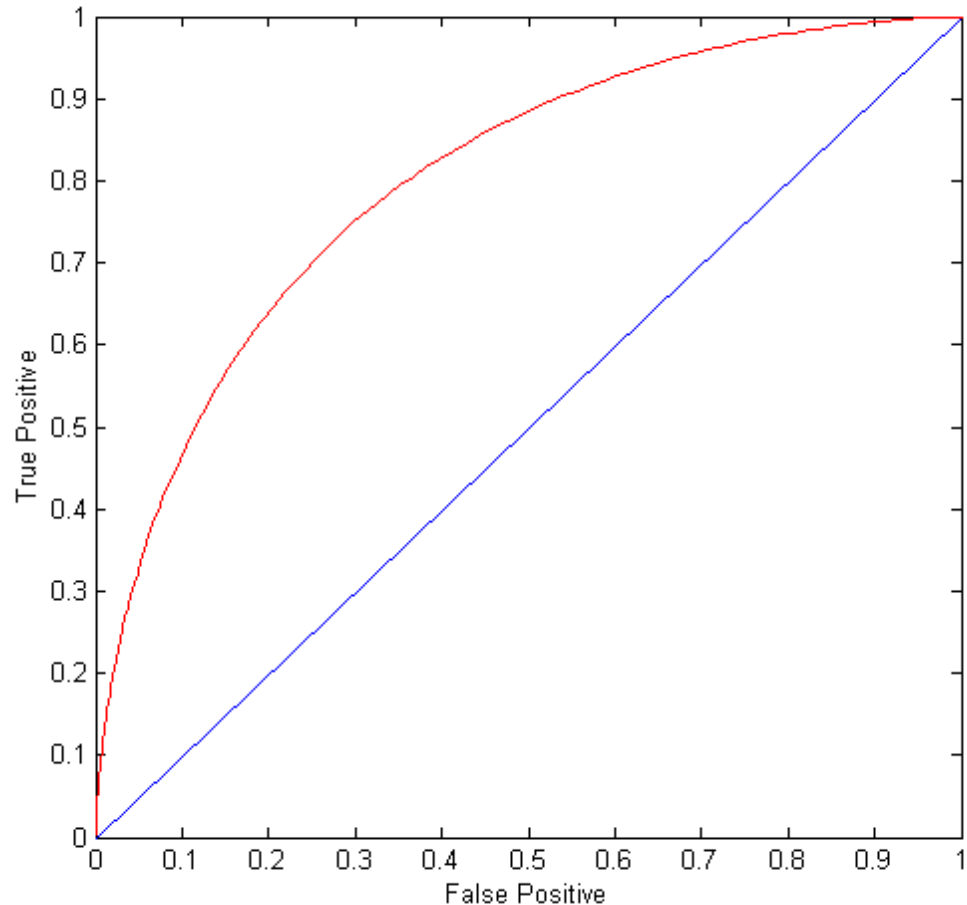
(TPR, FPR):

- (0,0): declare everything to be negative class
  - $TP=0, FP=0$
- (1,1): declare everything to be positive class
  - $FN=0, TN=0$
- (1,0): ideal
  - $FN=0, FP=0$

# ROC Curve

(TPR, FPR):

- (0,0): declare everything to be negative class
- (1,1): declare everything to be positive class
- (1,0): ideal
- Diagonal line:
  - Random guessing
  - Below diagonal line:
    - ◆ prediction is opposite of the true class



# How to Construct an ROC curve

Instance	$P(+ A)$	True Class
1	0.95	+
2	0.93	+
3	0.87	-
4	0.85	-
5	0.85	-
6	0.85	+
7	0.76	-
8	0.53	+
9	0.43	-
10	0.25	+

- Use classifier that produces posterior probability for each test instance  $P(+|A)$
- Sort the instances according to  $P(+|A)$  in decreasing order
- Apply threshold at each unique value of  $P(+|A)$
- Count the number of TP, FP, TN, FN at each threshold
- TP rate,  $TPR = TP/(TP+FN)$
- FP rate,  $FPR = FP/(FP + TN)$

# How to Construct an ROC curve

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10	0.25	+

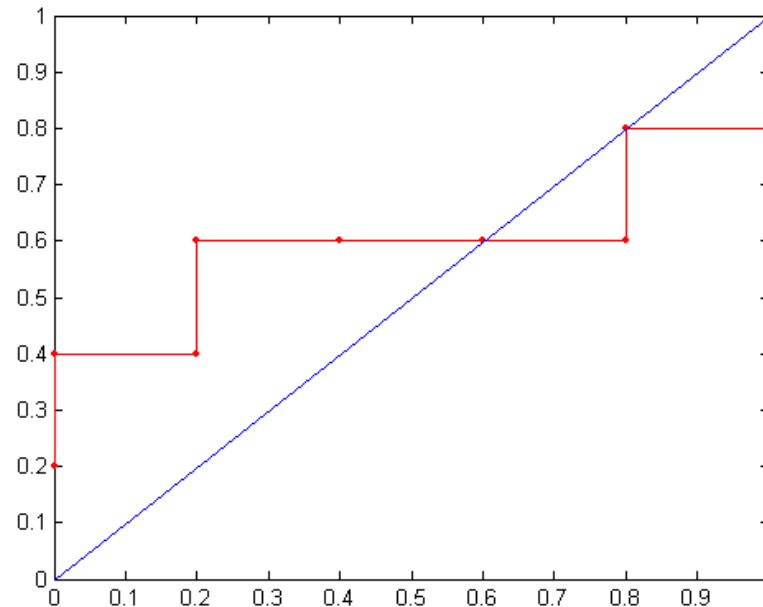
- Use classifier that produces posterior probability for each test instance  $P(+|A)$
- Sort the instances according to  $P(+|A)$  in decreasing order
- **Pick a threshold 0.85**
- $p \geq 0.85$ , predicted to P
- $p < 0.85$ , predicted to N
- TP = 3, FP=3, TN=2, FN=2
- TP rate, TPR =  $3/5=60\%$
- FP rate, FPR =  $3/5=60\%$



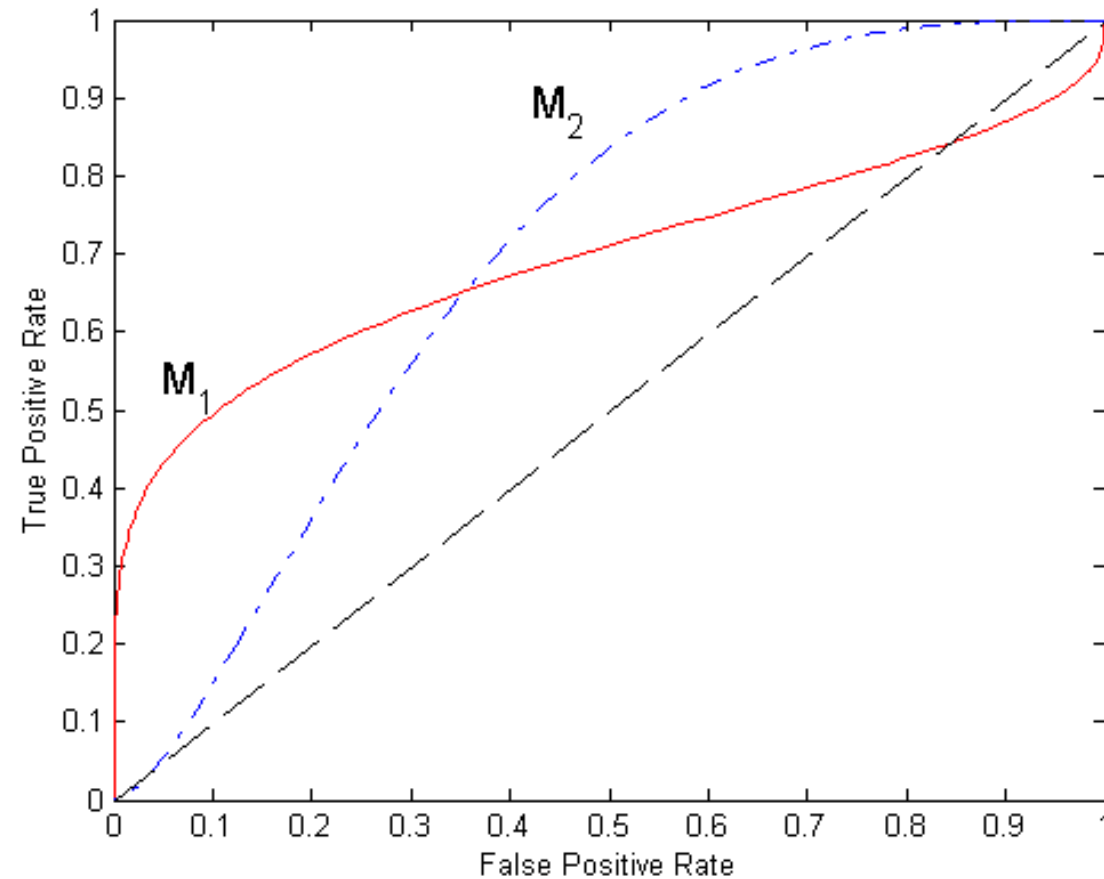
# How to construct an ROC curve

Class	+	-	+	-	-	-	+	-	+	+	
Threshold >=	0.25	0.43	0.53	0.76	0.85	0.85	0.85	0.87	0.93	0.95	1.00
TP	5	4	4	3	3	3	3	2	2	1	0
FP	5	5	4	4	3	2	1	1	0	0	0
TN	0	0	1	1	2	3	4	4	5	5	5
FN	0	1	1	2	2	2	2	3	3	4	5
→ TPR	1	0.8	0.8	0.6	0.6	0.6	0.6	0.4	0.4	0.2	0
→ FPR	1	1	0.8	0.8	0.6	0.4	0.2	0.2	0	0	0

ROC Curve:



# Using ROC for Model Comparison



- No model consistently outperforms the other
  - $M_1$  is better for small FPR
  - $M_2$  is better for large FPR
- Area Under the ROC curve (AUC)
  - Ideal:
    - Area = 1
  - Random guess:
    - Area = 0.5

# Data normalization

- Example-wise normalization

- Each example  $i$  is normalized and mapped to unit sphere

$$\mathbf{x}^{(i)} / \|\mathbf{x}^{(i)}\|$$

- Feature-wise normalization

- $[0,1]$ -normalization: normalize each feature  $i$  into a unit space

$$(\mathbf{x}_i - \min(\mathbf{x}_i)) / (\max(\mathbf{x}_i) - \min(\mathbf{x}_i))$$

$\mathbf{x}_i$  is the data vector of feature  $i$ ,  $\min(\mathbf{x}_i)$  is the minimum value in the vector,  $\max(\mathbf{x}_i)$  is the maximum value

- Standard normalization: normalize each feature  $i$  to have mean 0 and standard deviation 1

$$(\mathbf{x}_i - \mu_i) / \sigma_i$$

$\mu_i$  and  $\sigma_i$  is the sample mean and variance of feature  $i$

