

Exponential Growth - Simple Dynamic System

- ❖ differential equation
- ❖ $dP / dt = rP$
- ❖ an analytic solution exists so we can write Population as a function of time (integrating both sides)
 - ❖ $P = P_0 * \exp(rt)$

Numerical Integration

- ❖ differential equation
- ❖ $dP / dt = rP$
- ❖ We can also solve by numerical integration - less precise
- ❖ Many techniques are available to do numerical integration
- ❖ ODE - is a numerical integration tool in R - it does it for you

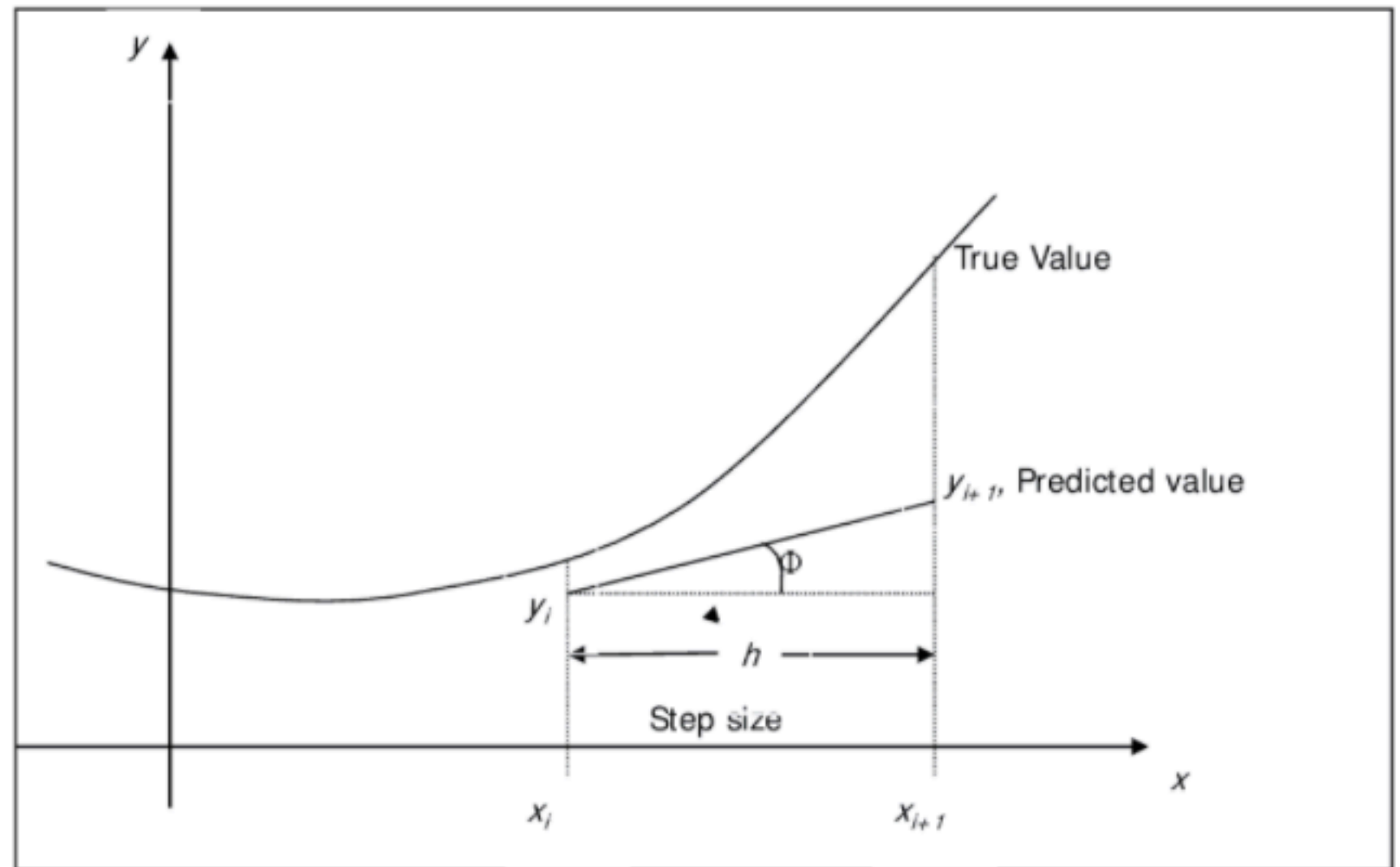
Numerical Integration

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Basic Concept

$$y_{i+1} = y_i + f(x_i, y_i)h$$

$$h = x_{i+1} - x_i$$



You next value (e.g Population at the next time step), is
Current value + derivative at the value

But since the derivate itself changes with the value, your time steps should be
infinitely small -

Numerical Integration Challenges

Dealing with the sensitivity to step size - is the main challenge

Many techniques for dealing this this - some use higher order derivatives etc.

(see see method under *help(ode)*)

Which one is the best to use depends on the derivative equation - and the values that you need answer for (e.g what periods of time, for derivatives of time)

Why YOU need to know this

- * explains why sometimes solves (like ODE) don't work
- * Explains what some of the parameters are for the ODE solver
- * Reminds you that you should seek expert help if you are having issues with your solver
- * Cautions you about step size when you do integration by hand...

Example: Dynamic Systems

❖ Diffusion - Ficks Law

❖ flux (mass / time) =

$$Q_x = -D (dC / dx)$$

Diffusivity (D) - depends on characteristics of the fluid (you can imagine how a pollutant might diffuse less rapidly in oil versus water)

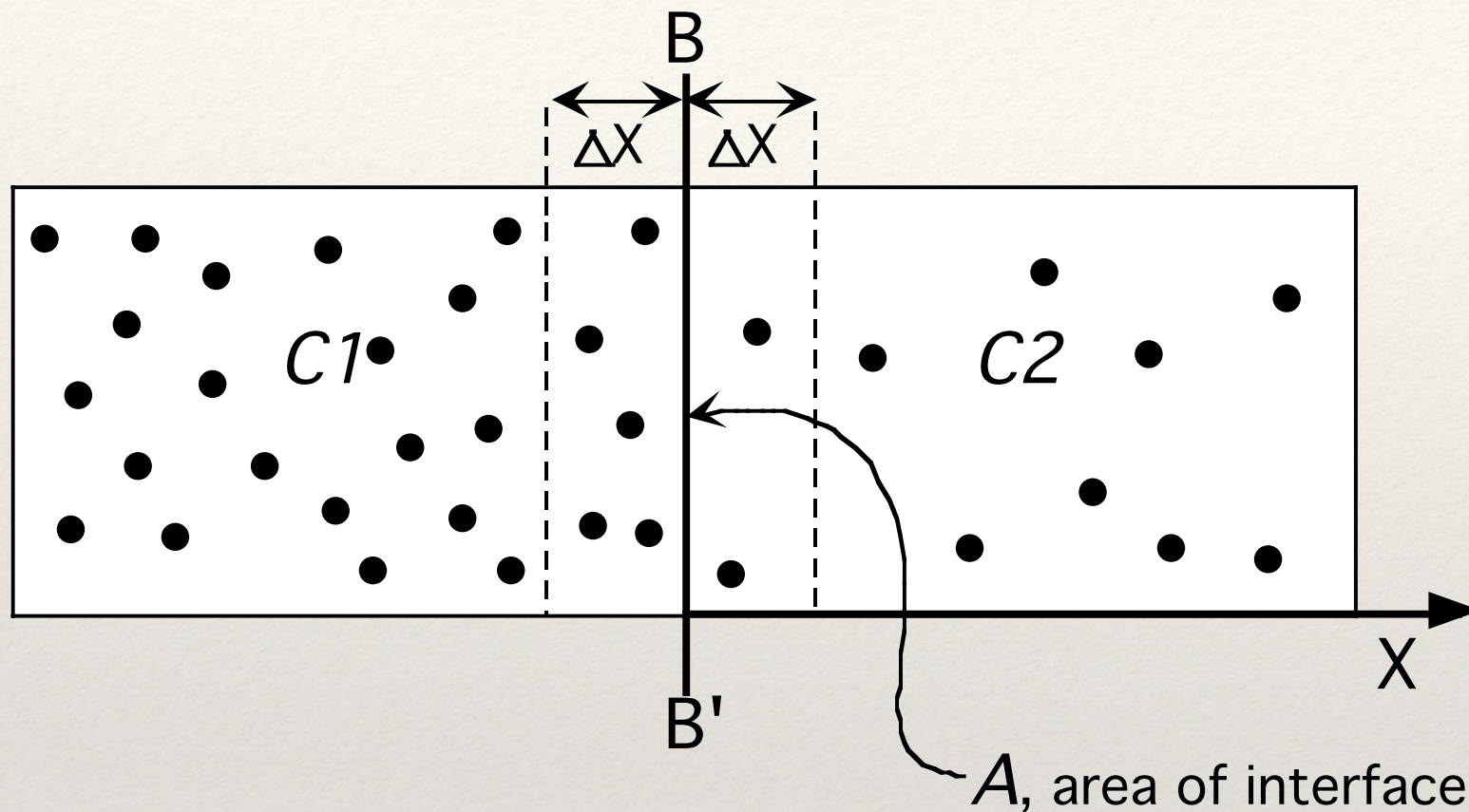
D is sometimes broken in to $D * A$ (where A is the cross sectional area at the boundary between the two fluids,) and D then is related to fluid type itself

This is a first order differential equation - changes only with x

Where x is the direction of diffusion

Diffusion

❖ Diffusion



How big that delta X is, depends on characteristics of the particles - often represented as a diffusivity (D) term

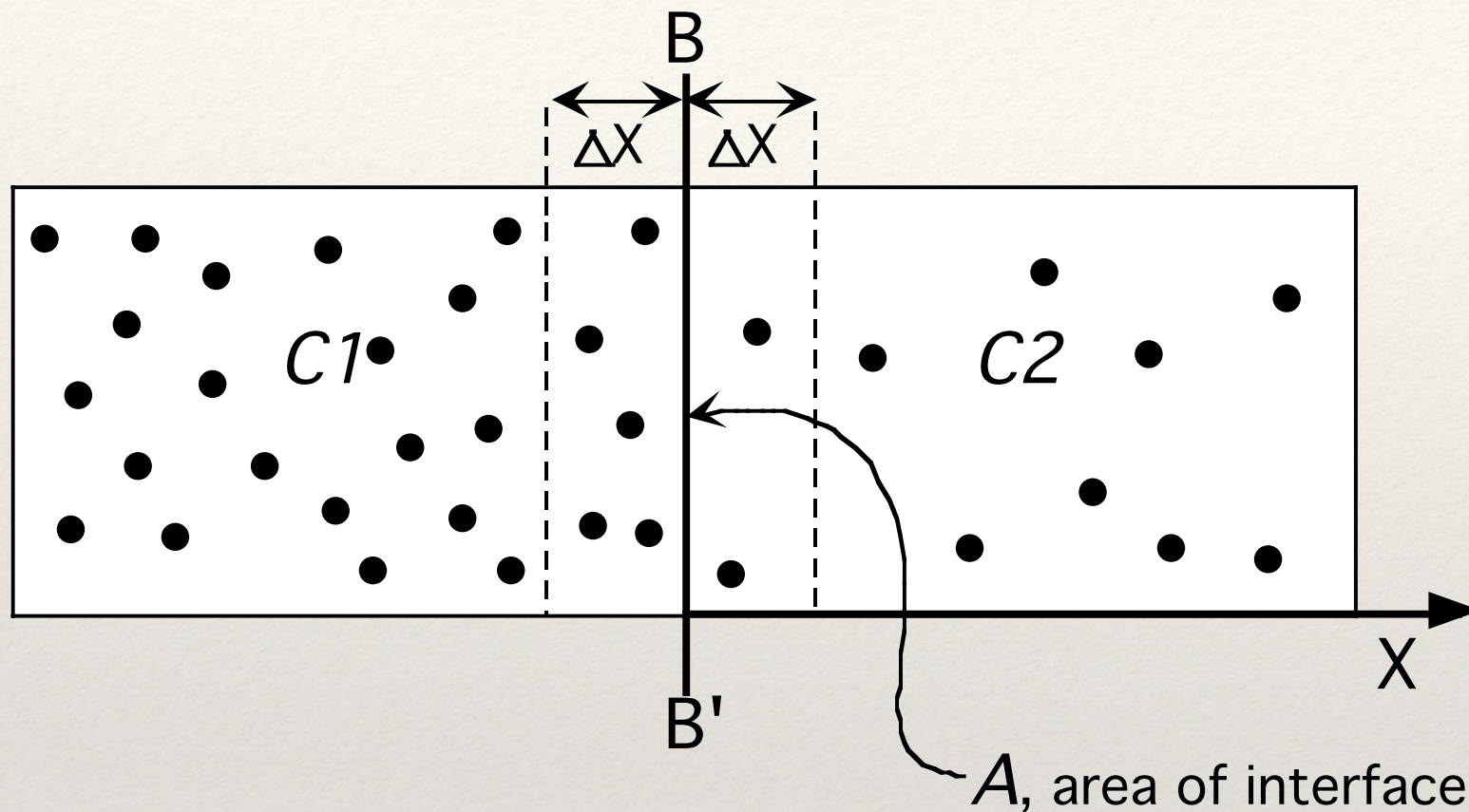
Flux at any instant is and any point along x

$$Q_t = 0.5 * D * A * (C2 - C1)$$

But as soon as particles move - $C1$ and $C2$ will change!!! - so we also need derivatives with respect to time

Diffusion

❖ Diffusion



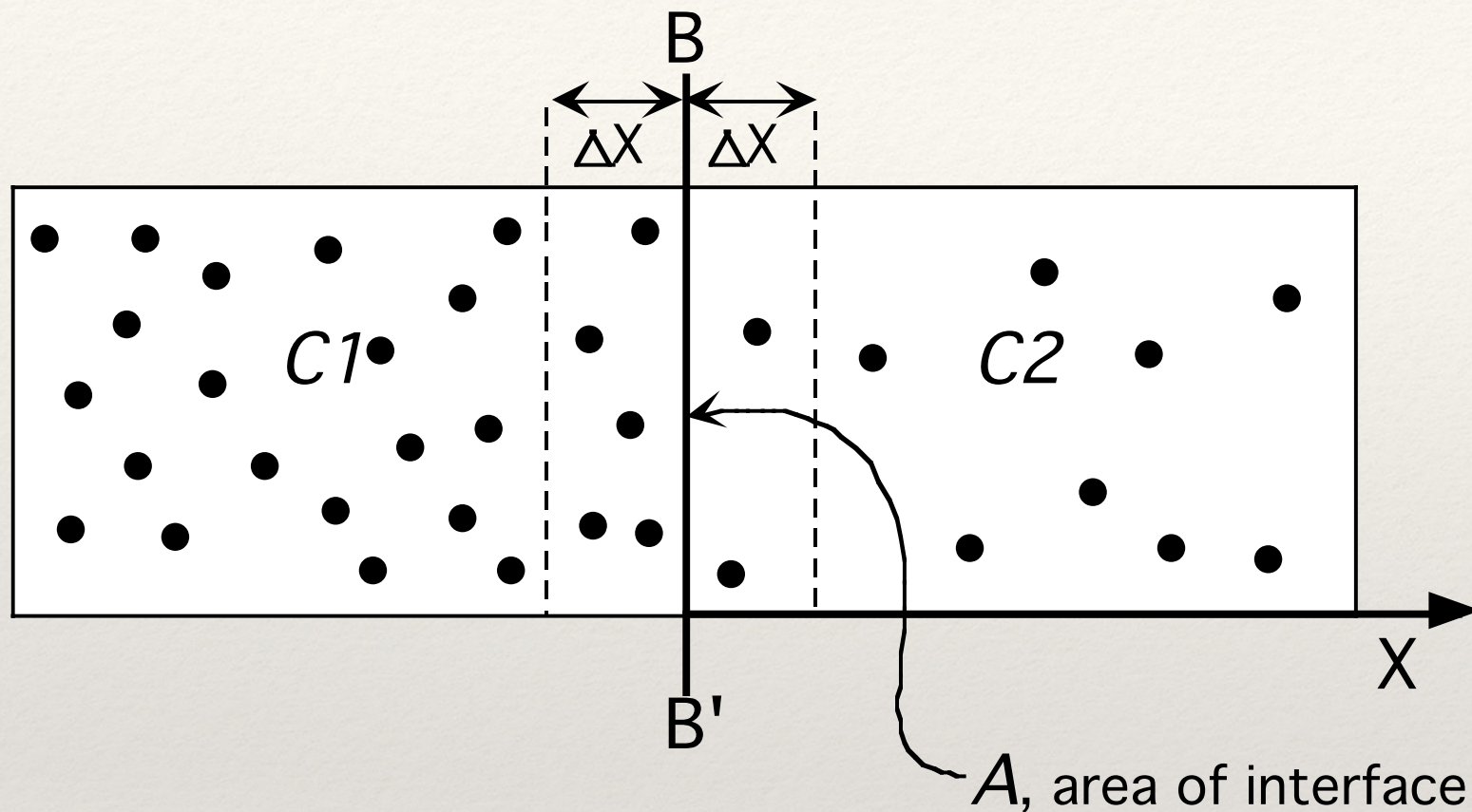
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$$\text{Fick's Second Law: } \frac{dC}{dt} = D \frac{d^2C}{dx^2}$$

This is a partial differential equation (derivatives with respect to t and x), there are solutions for this

Diffusion: Numerical Approximation: Difference Equation

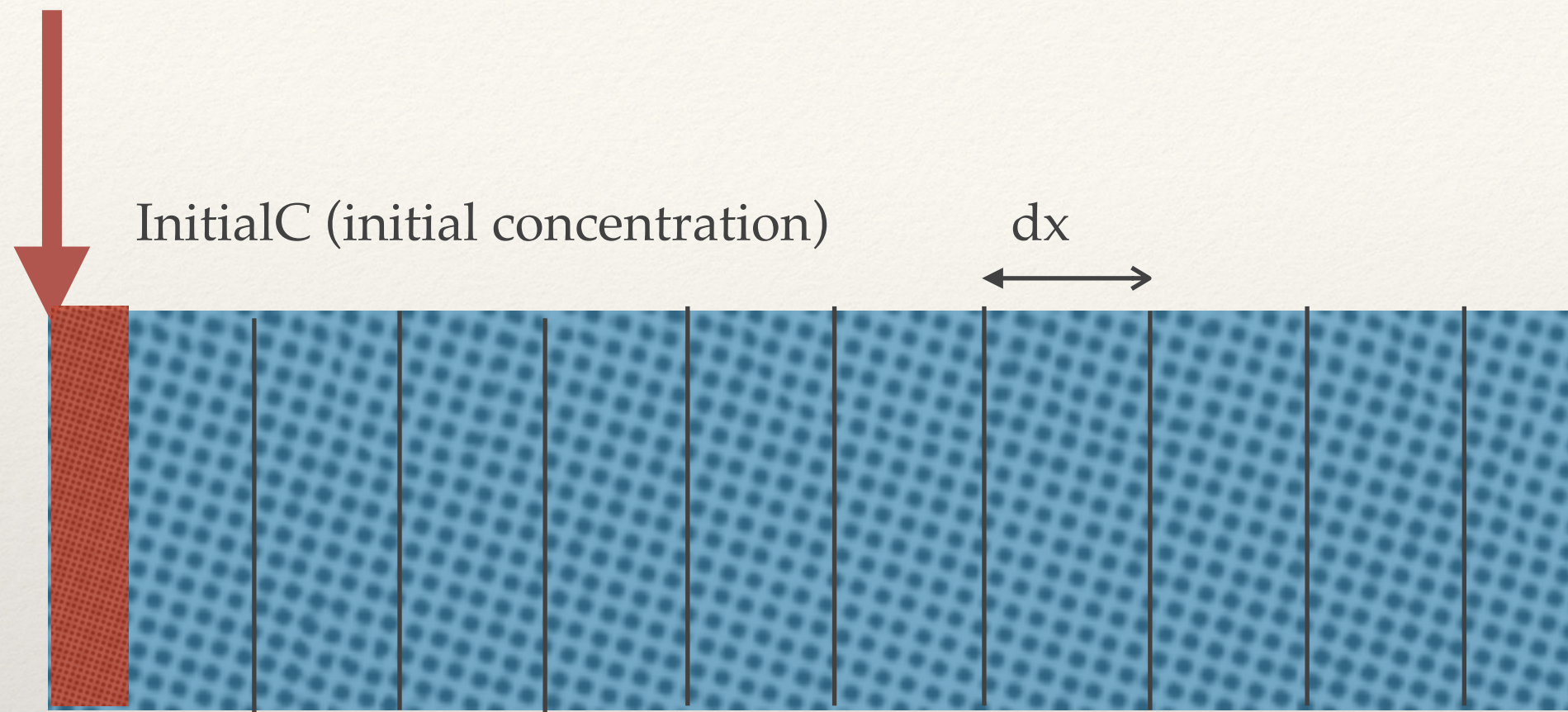
❖ Diffusion



BUT if we break up x into lots of little boxes, and time into small time chunks

$$Q_t = 0.5 * D * A * (C_{x2} - C_{x1})$$

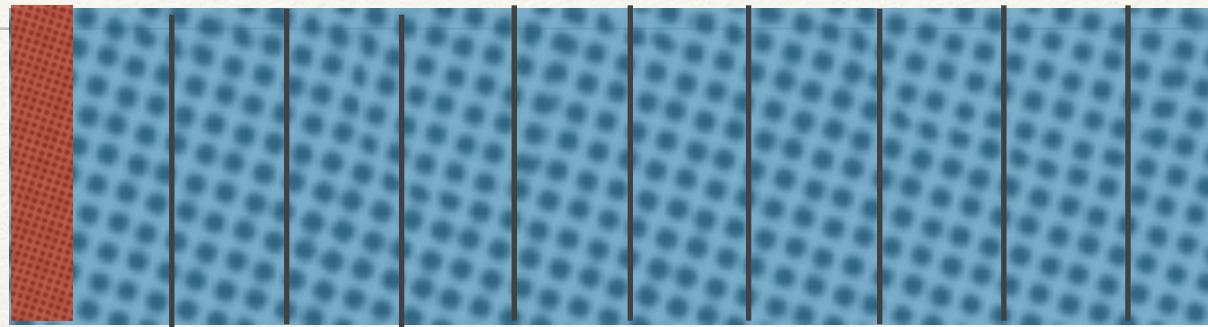
Diffusion as a difference equation



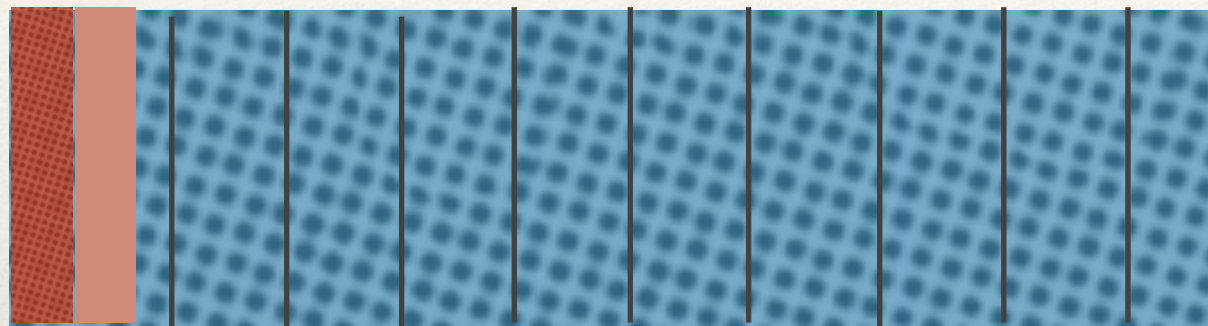
$$\text{Length} = n_x * dx$$

N_x : number of boxes you are breaking space into
dx size of each box

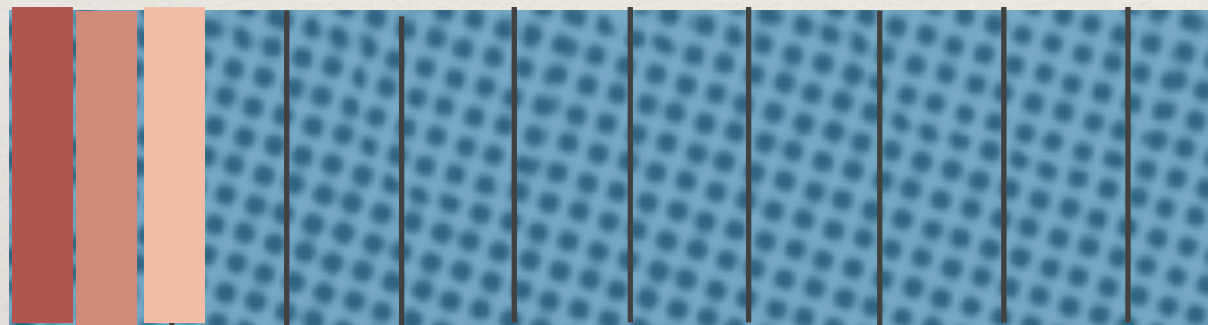
Diffusion Example



Timestep 1

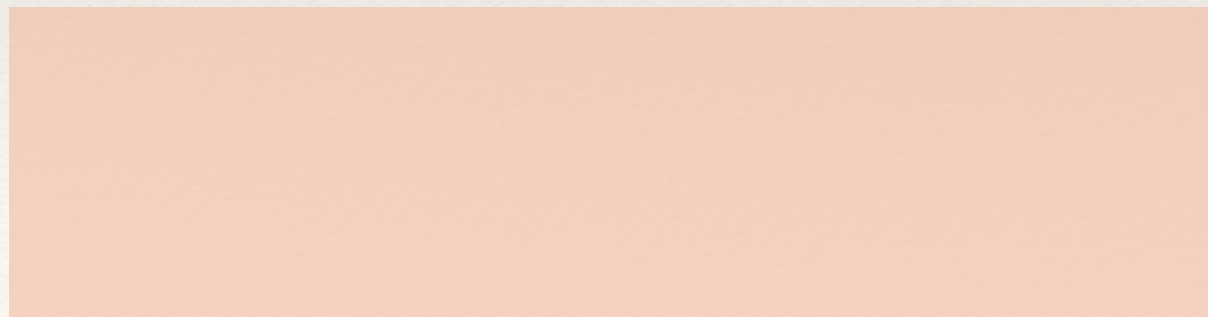


Timestep 2



Timestep 3

...



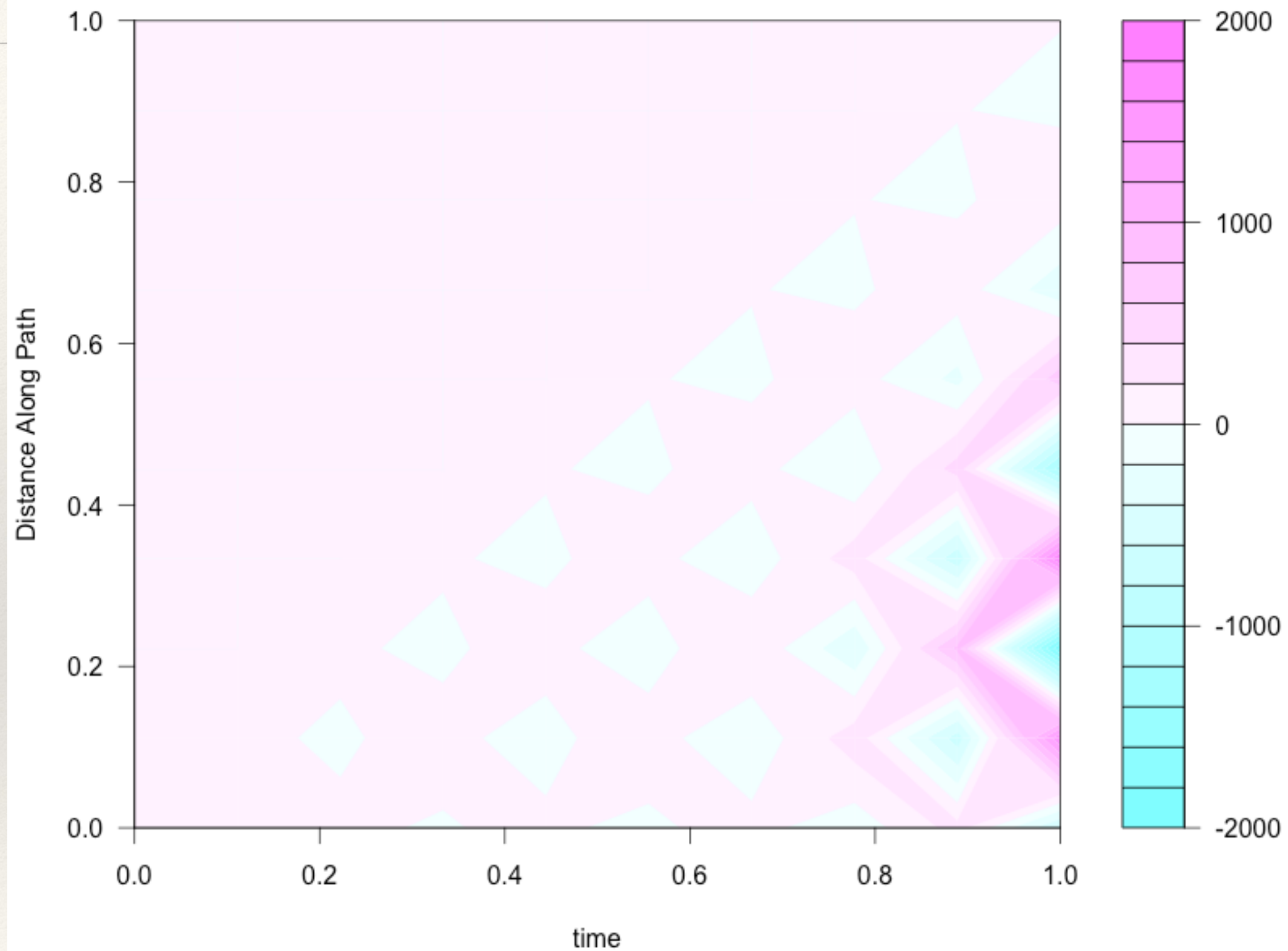
**State evolves through time
(state space trajectory)**

nt - number of time steps
dt - size of time step

Total Simulation time = $nt \cdot dt$

Playing with the diffuse model

- ❖ vary the time and space steps - what happens? why?
- ❖ vary other parameters (diffusivity, initial concentration)



```
filled.contour(diff1(10,10,1,10,30,0.6,1)$conc, xlab="time",ylab="Distance Along Path")
```

Dynamic - Diffusion modeling

- ❖ Choosing the appropriate time and space step is important
 - if either are too large then it is easy to overshoot and create unstable oscillations
- ❖ These are a due to using a discrete / difference model (dividing things into units) to model what is actually a continuous process
- ❖ Trade-off - computational efficiency vs stability
- ❖ Differential equations help us to think through this problem - but often implemented in discrete ways