# Linear Lists – Array Representation

Slides and figures have been collected from various publicly available Internet sources for preparing the lecture slides of IT2001 course. I acknowledge and thank all the original authors for their contribution to prepare the content.

- Data Object
  - a set of instances or values
  - Examples:
    - Boolean = {false, true}
    - Digit =  $\{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$
    - Letter = {A, B, C, ..., Z, a, b, c, ..., z}
    - String = {a, b, ..., aa, ab, ac,...}
  - An individual instance is either primitive or composite.
  - An element is the individual component of a composite instance.

#### Data Structure

- data object together with the relationships among instances and elements that comprise an instance
- Among instances of integer

```
369 < 370
```

$$280+4 = 284$$

Among elements that comprise an instance

369

3 is more significant than 6

3 is immediately to the left of 6

9 is immediately to the right of 6

- Abstract Data Type (ADT)
  - mathematical model of the data objects that make up a data type as well as the functions that operate on these objects. There are no standard conventions for defining them. (WiKipedia)
  - ADT is a collection of data and a set of operations that can be performed on the data.
  - It enables us to think abstractly about the data.
  - Typically, we choose a data structure and algorithms that provide an implementation of an ADT.

#### Data structures: Classification

- Data structures are classified into 2 categories:
  - Linear
  - Non-linear
- Linear data structures organize their data elements in a linear fashion, where data elements are attached one after the other.
- Data elements in a liner data structure are traversed one after the other and only one element can be directly reached while traversing.
- Consider the examples: ordered lists
  - Days of the week: (mon, tue, wed, thu, fri, sat, sun)
  - Student's roll number in a class
  - E.g., Array, Linked List, Stack, Queue

#### Data structures: Classification

- In nonlinear data structures, data elements are not organized in a sequential fashion.
- A data item in a nonlinear data structure could be attached to several other data elements to reflect a special relationship among them and all the data items cannot be traversed in a single run.
- E.g., Tree, Graphs

## Linear List

#### Definitions

- Linear list is a data object whose instances are of the form  $(e_1, e_2, ..., e_n)$
- e<sub>i</sub> is an element of the list.
- $-e_1$  is the first element, and  $e_n$  is the last element.
- n is the length of the list.
- When n = 0, it is called an empty list.
- $-e_1$  comes before  $e_2$ ,  $e_2$  comes before  $e_3$ , and so on.

#### Examples

- student names order by their alphabets
- a list of exam scores sorted by descending order

## **ADT for Linear List**

```
AbstractDataType LinearList {
   instances
         ordered finite collections of zero or more elements
   operations
         Create():create an empty linear list
         Destroy():
                            erase the list
         IsEmpty():
                            return true if empty, false otherwise
         Length():
                            return the list size
         Find(k,x):
                            return the kth element of the list in x
         Search(x):
                            return the position of x in the list
         Delete(k,x):
                            delete the kth element and return it in x
         Insert(k,x):
                            insert x just after the k<sup>th</sup> element
         Output(out):
                            put the list into the output stream out
```

## Implementations of Linear List

- Array-based (Formula-based)
  - Uses a mathematical formula to determine where (i.e., the memory address) to store each element of a list
- Linked list (Pointer-based)
  - The elements of a list may be stored in any arbitrary set of locations
  - Each element has an explicit pointer (or link) to the next element
- Indirect addressing
  - The elements of a list may be stored in any arbitrary set of locations
  - Maintain a table such that the ith table entry tells us where the ith element is stored
- Simulated pointer
  - Similar to linked representation but integers replace the C++ pointers

## Array-based Representation of Linear List

- It uses an array to store the elements of linear list.
- Individual element is located in the array using a mathematical formula.
- typical formula

$$location(i) = i - 1$$

 $\rightarrow$  ith element of the list is in position i-1 of the array

## Construct 'LinearList'

```
Void LinearList(int MaxSize)
{    // Construction of array-based linear list
    int element[MaxSize];
}
```

• The time complexity is:  $\Theta(1)$ 

# Operation 'Find'

```
#define true 1
#define false 0
typedef int bool;
bool Find(int k, int x)
{ // Set x to the k<sup>th</sup> element in the list if it exists
   if (k < 1 \mid k > length)
        return false;
  x = element[k-1];
   return true;
• The time complexity is: \Theta(1)
```

## Operation 'Search'

```
int Search( int element[ ], int x )
{    // Locate x and return the position of x if found
    for (int i = 0; i < length; i++)
        if (element[i] == x)
            return ++i;
    return 0;
}</pre>
```

The time complexity is: O(length)

# Operation 'Delete'

```
Delete(int element[], int k, int x)
{    // Delete the k'th element if it exists.
    if (Find(k, x)) {
        for (int i = k, i < length; i++)
            element[i-1] = element[i];
        length--;
        }
}</pre>
```

The time complexity is O(length)

# Operation 'Insert'

```
Insert(int k, x)
{ // Insert x after the k'th element.
  //length: # of elements in the list
  if (k < 0 \mid k > length) error
  if (length == MaxSize) error
  for (i = length-1; i >= k; i--)
      element[i+1] = element[i];
  element[k] = x;
  length++;
• The time complexity is O(length))
```

## Operation 'Output'

```
Output(element [])
{ // print out the list
  for (int i = 0; i < length; i++)
      printf("%d", element[i]);
}</pre>
```

The time complexity is Θ(length)

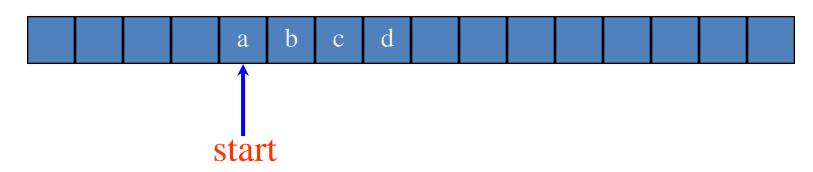
# Arrays and Matrices

- Data is often available in tabular form
- Tabular data is often represented in arrays
- Matrix is an example of tabular data and is often represented as a 2-dimensional array
  - Matrices are normally indexed beginning at 1 rather than 0
  - Matrices also support operations such as add, multiply, and transpose, which are NOT supported by C/C++'s 2D array

- It is possible to reduce time and space using a <u>customized</u> representation of multidimensional arrays
- Focus on
  - Row- and column-major ordering and representations of multidimensional arrays
  - Special matrices
    - Diagonal, tridiagonal, triangular, symmetric, sparse

## 1D Array Representation in C/C++

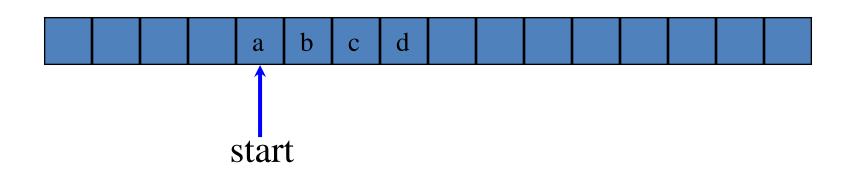
#### Memory



- 1-dimensional array x = [a, b, c, d]
- map into contiguous memory locations
- location(x[i]) = start + i

#### **Space Overhead**

#### Memory



space overhead = 4 bytes for start
(excludes space needed for the elements of array x)

## **2D Arrays**

The elements of a 2-dimensional array a declared as: int a[3][4];

```
may be shown as a table
```

```
a[0][0] a[0][1] a[0][2] a[0][3]
a[1][0] a[1][1] a[1][2] a[1][3]
a[2][0] a[2][1] a[2][2] a[2][3]
```

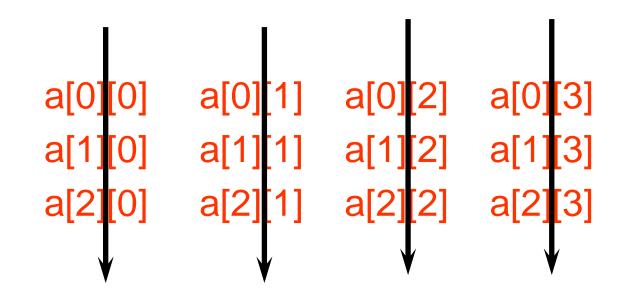
## **Rows of a 2D Array**

```
a[0][0] a[0][1] a[0][2] a[0][3] \rightarrow row 0

a[1][0] a[1][1] a[1][2] a[1][3] \rightarrow row 1

a[2][0] a[2][1] a[2][2] a[2][3] \rightarrow row 2
```

## **Columns of a 2D Array**



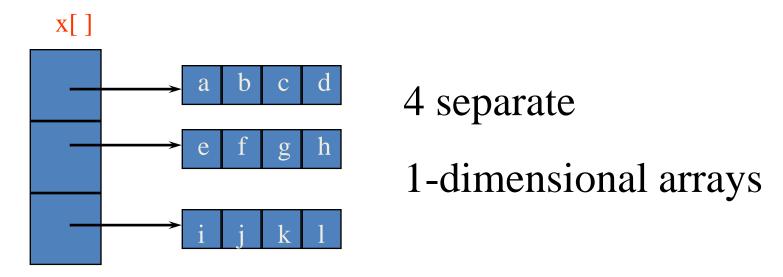
column 0 column 1 column 2 column 3

## 2D Array Representation in C/C++

## 2-dimensional array x

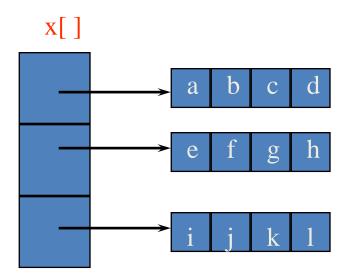
```
a, b, c, d
                          e, f, g, h
                          i, j, k, 1
view 2D array as a 1D array of rows
  x = [row0, row1, row 2]
  row 0 = [a, b, c, d]
  row 1 = [e, f, g, h]
  row 2 = [i, j, k, l]
and store as 4 1D arrays
```

## 2D Array Representation in C/C++



- space overhead = overhead for 4 1D arrays
  - = 4 \* 4 bytes
  - = 16 bytes
  - = (number of rows + 1) x 4 bytes

### Array Representation in C/C++



- This representation is called the array-of-arrays representation.
- Requires contiguous memory of size 3, 4, 4, and 4 for the 4 1D arrays.
- 1 memory block of size number of rows and number of rows blocks of size number of columns

### **Row-Major Mapping**

• Example 3 x 4 array:

```
a bcde f g hi i k l
```

- Convert into 1D array y by collecting elements by rows.
- Within a row elements are collected from left to right.
- Rows are collected from top to bottom.
- We get y[] = {a, b, c, d, e, f, g, h, i, j, k, l}

row 0	row 1	row 2		row i	
10 W 0	IOW I	10 W 2	• • •	1 O VV 1	

### Locating Element x[i][j]

0 c 2c 3c ic

row 0 row 1 row 2 ... row i

- assume x has r rows and c columns
- each row has c elements
- i rows to the left of row i
- so ic elements to the left of x[i][0]
- x[i][j] is mapped to position

ic + j of the 1D array

### **Space Overhead**



- 4 bytes for start of 1D array +
- 4 bytes for c (number of columns)
- = 8 bytes

Note that we need contiguous memory of size rc.

### Column-Major Mapping

```
abcd
efgh
ijkl
```

- Convert into 1D array y by collecting elements by columns.
- Within a column elements are collected from top to bottom.
- Columns are collected from left to right.
- We get y[] = {a, e, i, b, f, j, c, g, k, d, h, l}

### Row- and Column-Major Mappings

```
2D Array int a[3][6];
```

```
a[0][0] a[0][1] a[0][2] a[0][3] a[0][4] a[0][5]
a[1][0] a[1][1] a[1][2] a[1][3] a[1][4] a[1][5]
a[2][0] a[2][1] a[2][2] a[2][3] a[2][4] a[2][5]
```

```
      0
      1
      2
      3
      4
      5
      0
      3
      6
      9
      12
      15

      6
      7
      8
      9
      10
      11
      1
      4
      7
      10
      13
      16

      12
      13
      14
      15
      16
      17
      2
      5
      8
      11
      14
      17
```

(a) Row-major mapping (b) Column-major mapping

## Row- and Column-Major Mappings

Row-major order mapping functions

$$map(i_1, i_2) = i_1 u_2 + i_2$$
 for 2D arrays  $map(i_1, i_2, i_3) = i_1 u_2 u_3 + i_2 u_3 + i_3$  for 3D arrays

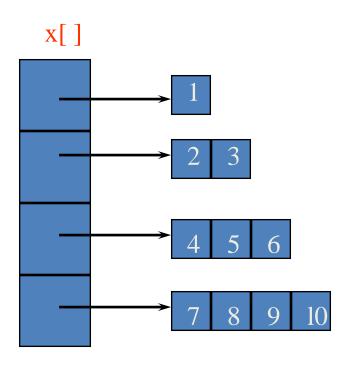
What is the mapping function?

```
map(i_1,i_2) = 6i_1+i_2

map(2,3) = ?
```

Column-major order mapping functions
 // do this as an exercise

### Irregular 2D Arrays



Irregular 2-D array: the length of rows is not required to be the same.

## Matrices

- $m \times n$  matrix is a table with m rows and n columns.
- M(i,j) denotes the element in row i and column j.
- Common matrix operations

<ul><li>transpose</li></ul>		col 1	col 2	col 3	col 4
<ul><li>addition</li></ul>	row 1	7	2	0	9
<ul><li>multiplication</li></ul>	row 2	0	1	0	5
	row 3	6	4	2	0
	row 4	8	2	7	3
	row 5	1	4	9	6

## **Matrix Operations**

#### Transpose

— The result of transposing an  $m \times n$  matrix is an  $n \times m$  matrix with property:

$$M^{T}(j,i) = M(i,j), 1 <= i <= m, 1 <= j <= n$$

#### Addition

- The sum of matrices is only defined for matrices that have the same dimensions.
- The sum of two m x n matrices A and B is an m x n matrix with the property:

$$C(i,j) = A(i,j) + B(i,j), 1 <= i <= m, 1 <= j <= n$$

## **Matrix Operations**

### Multiplication

- The product of matrices A and B is only defined when the number of columns in A is equal to the number of rows in B.
- Let A be  $m \times n$  matrix and B be a  $n \times q$  matrix. A\*B will produce an  $m \times q$  matrix with the following property:

```
C(i,j) = \Sigma(k=1...n) A(i,k) * B(k,j)
where 1 <= i <= m and 1 <= j <= q
```

## Shortcomings of using a 2D Array for a Matrix

- Indexes are off by 1.
- C/C++ arrays do not support matrix operations such as add, transpose, multiply, and so on.
  - Suppose that x and y are 2D arrays. Cannot do x + y, x -y, x \* y, etc. in C/C++.