

Team Code :- **PNT2022TMIS21811**

```
int buzz=4;

int pir=7;

int echo=5;

int trigg=6;

int pir_led=12;

int us_led=13;

int time ;

int dist;

void setup()

{

    Serial.begin(9600);

    pinMode(pir_led, OUTPUT);

    pinMode(us_led, OUTPUT);

    pinMode(buzz, OUTPUT);

    pinMode(pir, INPUT);

    pinMode(echo, INPUT);

    pinMode(trigg, OUTPUT);

}

void loop()

{

    if (digitalRead(pir)==HIGH){

        Serial.println("There is a person...");

        digitalWrite(pir_led,HIGH);

        delay(1000);

    }

    digitalWrite(pir_led,LOW);

    digitalWrite(trigg,HIGH);

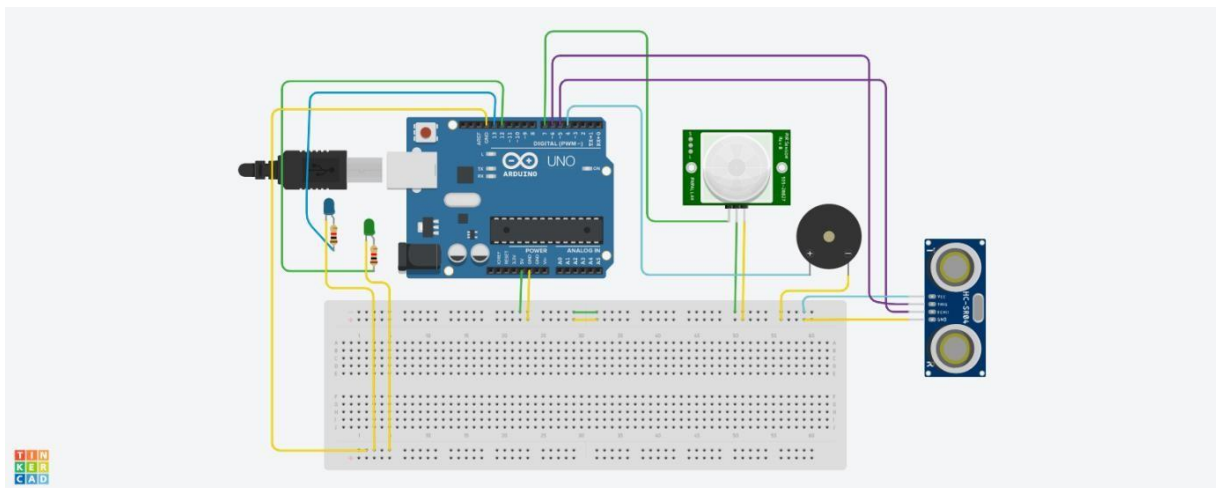
    delayMicroseconds(10);

    digitalWrite(trigg,LOW);
```

```

time=pulseIn(echo,HIGH);
dist= (time*0.034)/2;
if (dist<=50)
{
  Serial.println("A person Near...");
  digitalWrite(us_led,HIGH);
  analogWrite(buzz,HIGH);
  delay(1000);
}
else
{
  digitalWrite(us_led,LOW);
  analogWrite(buzz,LOW);
  delay(1000);
}
}

```



<https://www.tinkercad.com/things/9isSjSIVRG6-glorious-kasi/editel?sharecode=vni04c-U5jZdcG7G2uKm9pSedL-ILUhw-JwfhX9orzI>