

Problem 2)

a.) Write the general form of an ARIMA(p,d,q) process.

Let $D^d Y_t = w_t$. Then

$$w_t = \theta_0 + \phi_1 w_{t-1} + \phi_2 w_{t-2} + \dots + \phi_p w_{t-p} + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2} - \dots - \theta_q e_{t-q} \sim \text{ARIMA}(p,d,q)$$

b.) Write the general form of an ARIMA(p,d,q) process using the backshift operator.

$$\varPhi(B)(1-B)^d Y_t = \Theta(B) e_t$$

c.) State the necessary and sufficient conditions for stationarity and invertibility of ARMA(1,1) and ARMA(2,2) processes that do not use statements about the characteristic equation.

ARMA(1,1):

$$Y_t = \phi Y_{t-1} + e_t - \Theta e_{t-1}$$

We have stationarity iff $|\phi| < 1$

We have invertibility iff $|\Theta| < 1$

ARMA(2,2):

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2}$$

We have the following necessary conditions for stationarity:

$$\begin{aligned}1.) \quad & \phi_1 + \phi_2 < 1 \\2.) \quad & |\phi_1| < 1\end{aligned}$$

Adding the following 3rd condition makes the set of 3 conditions sufficient and necessary:

$$3.) \quad \phi_2 - \phi_1 < 1$$

In a similar manner, the process is invertible iff the roots of the MA characteristic equation:

$$1 - \theta_1 x - \theta_2 x^2 = 0$$

all lie outside the unit disk. Thus, we can come to the conclusion that the following three conditions are necessary and sufficient for invertibility:

$$\begin{aligned}1.) \quad & \theta_1 + \theta_2 < 1 \\2.) \quad & |\theta_1| < 1 \\3.) \quad & \theta_2 - \theta_1 < 1\end{aligned}$$

Q) Give an example of a stationary ARMA(3,1) process and a non-stationary process that resembles ARMA(3,1):

We can construct a stationary ARMA(3,1) process by starting with a characteristic equation with roots outside the unit disk:

$$\begin{aligned}(x-2)(x-3)(x-4) &= 0 \\ \Rightarrow x^3 - 9x^2 + 26x - 24 &= 0 \\ \Rightarrow 1 - \frac{26}{24}x + \frac{9}{24}x^2 - \frac{1}{24}x^3 &= 0 \\ \Rightarrow 1 - \frac{13}{12}x + \frac{3}{8}x^2 - \frac{1}{24}x^3 &= 0 \\ \Rightarrow \phi_1 = -\frac{13}{12}, \phi_2 = \frac{3}{8}, \phi_3 = -\frac{1}{24} &\end{aligned}$$

Thus,

$$Y_t = -\frac{13}{12} Y_{t-1} + \frac{3}{8} Y_{t-2} - \frac{1}{24} Y_{t-3} + e_t - \frac{1}{2} e_{t-1}$$

Is a stationary ARMA(3,1) process.

A process which appears like an ARMA(3,1) process but is not stationary is

$$L^{-1} Y_t = \frac{1}{2} Y_{t-1} + \frac{1}{9} Y_{t-2} + \frac{1}{4} Y_{t-3} + e_t$$

Since it violates $\sum |\phi_i| < 1$.

e.) Give an example of a nonstationary time-series with $\text{cov}(Y_t, Y_{t-k})$ and $\text{Var}(Y_t)$ free of t for all $k \geq 1$.

The simplest such series is of the form

$$Y_t = e_t + t$$

Since:

$$\mathbb{E}(Y_t) = t$$

$$\begin{aligned} \text{cov}(Y_t, Y_{t-k}) &= \text{cov}(e_t + t, e_{t-k} + t - k) \\ &= \text{cov}(e_t, e_{t-k}) + \text{cov}(e_t, (t-k)) + \text{cov}(t, e_{t-k}) \\ &\quad + \text{cov}(t, t - k) \\ &= 0 \end{aligned}$$

f) Give an example of a non-stationary time-series which can be made stationary after differencing 4 times.

Any such time-series must follow:

$$\nabla^4 Y_t \sim \text{ARIMA}(p, 4, q)$$

Thus, we pick a simple ARMA model:

$$\begin{aligned} \nabla^4 Y_t &= e_t - 0.1e_{t-1} \\ \Rightarrow (1-B)^4 Y_t &= e_t - 0.1e_{t-1} \\ \Rightarrow (1-4B + 6B^2 - 4B^3 + B^4)Y_t &= e_t - 0.1e_{t-1} \\ \Rightarrow Y_t - 4Y_{t-1} + 6Y_{t-2} - 4Y_{t-3} + Y_{t-4} &= e_t - 0.1e_{t-1} \\ \Rightarrow Y_t = 4Y_{t-1} - 6Y_{t-2} + 4Y_{t-3} - Y_{t-4} + e_t - 0.1e_{t-1} \end{aligned}$$

And Y_t is visibly nonstationary since:

$$\begin{aligned} \phi_1 + \phi_2 + \phi_3 + \phi_4 &= 4 - 6 + 4 - 1 \\ &= -8 + 7 \\ &= 1 \neq 1 \end{aligned}$$

Problem 2 Identify the specific ARMA models

$$a) Y_t = 3Y_{t-1} - 3Y_{t-2} + Y_{t-3} + e_t - 0.1e_{t-1}$$

$$\Rightarrow Y_t - 3Y_{t-1} + 3Y_{t-2} - Y_{t-3} = e_t - 0.1e_{t-1}$$

$$\Rightarrow (1 - 3B + 3B^2 - B^3) Y_t = e_t - 0.1e_{t-1}$$

$$\Rightarrow (1-B)^3 Y_t = e_t - 0.1e_{t-1}$$

$$\Rightarrow D^3 Y_t = e_t - 0.1e_{t-1}$$

Thus, $Y_t \sim ARIMA(0, 3, 1)$

$$b) Y_t = 1.2Y_{t-1} - 0.25Y_{t-2} + e_t - 0.6e_{t-1} - 0.2e_{t-2}$$

Note that:

$$\phi_1 + \phi_2 = 1.2 - 0.25 \\ = 0.95 < 1$$

$$\phi_2 - \phi_1 = -0.25 - 1.2 \\ = -1.45 < 1$$

$$|\phi_2| = | -0.25 | \\ = 0.25 < 1$$

Thus, $Y_t \sim ARIMA(2, 0, 2)$

$$c) Y_t = 0.6Y_{t-2} + e_t - 0.7e_{t-1} - 0.2e_{t-2}$$

Note that $Y_t \sim ARMA(1, 2)$, thus
 $Y_t \sim ARIMAC(1, 0, 2)$

$$d) Y_t = e_t - 0.1e_{t-1} - 0.3e_{t-2} + 0.7e_{t-4}$$

This is simply a MA(4) model, thus
 $Y_t \sim ARIMAC(0, 0, 4)$

$$e.) Y_t = e_{t+2} - 0.4 e_{t+4}$$

Clearly, this is a MA(q) model. To find q, we must study its behavior:

$$\gamma_k = \text{cov}(Y_t, Y_{t-k})$$

$$= \text{cov}(e_{t+2} - 0.4 e_{t+4}, e_{t+2-k} - 0.4 e_{t+4-k})$$

$$= \text{cov}(e_{t+2}, e_{t+2-k}) + \text{cov}(e_{t+2}, -0.4 e_{t+4-k}) + \text{cov}(-0.4 e_{t+4}, e_{t+2-k}) \\ + \text{cov}(-0.4 e_{t+4}, -0.4 e_{t+4-k})$$

$$= \sigma_e \delta(t+2, t+2-k) - 0.4 \sigma_e \delta(t+2, t+4-k) - 0.4 \sigma_e \delta(t+4, t+2-k) \\ + 0.016 \sigma_e \delta(t+4, t+4-k)$$

$$= \sigma_e \delta(0, k) + \sigma_e \delta(-2, k) + \sigma_e \delta(2, k) + \sigma_e \delta(0, k) \\ = \sigma_e \delta(0, k) + \sigma_e \delta(2, k) + \sigma_e \delta(0, k)$$

$$\Rightarrow \gamma_k = \begin{cases} 2\sigma_e & k=0 \\ 0 & k=1 \\ \sigma_e & k=2 \end{cases}$$

Thus, this time-series behaves as MA(2)

Problem 3) Derive the auto covariance and autocorrelation for the following processes:

a) MA(1)

$$Y_t = -\theta e_{t-1} + e_t$$

$$\gamma_k = \text{corr}(Y_t, Y_{t+k})$$

$$= \text{corr}(-\theta e_{t-1} + e_t, -\theta e_{t-k-1} + e_{t+k})$$

$$= \theta^2 \text{corr}(e_{t-1}, e_{t-k-1}) + \theta_1 \text{corr}(e_{t-1}, e_{t+k}) - \theta_1 (e_t, e_{t-k-1}) \\ + \text{corr}(e_t, e_{t+k})$$

$$= \theta^2 \sigma_e^2 \delta(-1, -k-1) - \theta_1 \sigma_e \delta(-1, -k) - \theta_1 \sigma_e \delta(0, -k-1) + \sigma_e^2 \delta(0, k)$$

$$= \theta^2 \sigma_e^2 \delta(0, k) - \theta_1 \sigma_e \delta(1, k) - \theta_1 \sigma_e \delta(-1, k) + \sigma_e^2 \delta(0, k)$$

$$\Rightarrow \gamma_k = \begin{cases} (1 + \theta_1^2) \sigma_e^2 & k=0 \\ -\theta_1 \sigma_e & k=1 \\ 0 & k>1 \end{cases}$$

$$\Rightarrow \rho_k = \frac{\gamma_k}{\gamma_0} = \begin{cases} -\frac{\theta_1}{1 + \theta_1^2} & k=1 \\ 0 & k>1 \end{cases}$$

b.) MA(2)

$$Y_t = e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2}$$

$$\begin{aligned}\gamma_k &= \text{cov}(Y_t, Y_{t+k}) = \text{cov}(e_t - \theta_1 e_{t-1} - \theta_2 e_{t-2}, e_{t+k} - \theta_1 e_{t+k-1} - \theta_2 e_{t+k-2}) \\ &= \text{cov}(e_t, e_{t+k}) - \theta_1 \text{cov}(e_{t-1}, e_{t+k}) + \theta_1^2 \text{cov}(e_{t-2}, e_{t+k}) \\ &\quad + \theta_1 \theta_2 \text{corr}(e_{t-1}, e_{t+k-2}) - \theta_2 \text{corr}(e_{t-2}, e_{t+k}) + \theta_1 \theta_2 \text{corr}(e_{t-2}, e_{t+k-1}) \\ &\quad + \theta_2^2 \text{corr}(e_{t-2}, e_{t+k-2}) \\ &= \sigma_e \delta(0, k) - \theta_1 \sigma_e \delta(1, k) + \theta_1^2 \sigma_e \delta(0, k) - \theta_2 \sigma_e \delta(2, k) \\ &\quad + \theta_1 \theta_2 \sigma_e \delta(1, k) + \theta_2^2 \sigma_e \delta(0, k) \\ &= \delta(0, k) [\sigma_e + \theta_1^2 \sigma_e + \theta_2^2 \sigma_e] + \delta(1, k) [-\theta_1 \sigma_e + \theta_1 \theta_2 \sigma_e] \\ &\quad + \delta(2, k) [-\theta_2 \sigma_e]\end{aligned}$$

$$\Rightarrow \gamma_k = \begin{cases} \sigma_e (1 + \theta_1^2 + \theta_2^2) & k=0 \\ \sigma_e \theta_1 (\theta_2 - 1) & k=1 \\ -\theta_2 \sigma_e & k=2 \\ 0 & k>2 \end{cases}$$

$$\Rightarrow \rho_k = \frac{\gamma_k}{\gamma_0} = \begin{cases} \frac{\theta_1(\theta_2 - 1)}{1 + \theta_1^2 + \theta_2^2} & k=1 \\ \frac{-\theta_2}{1 + \theta_1^2 + \theta_2^2} & k=2 \\ 0 & k>2 \end{cases}$$

c) AR(1)

$$Y_t = \phi_1 Y_{t-1} + e_t$$

$$E(Y_t) = E(\phi_1 Y_{t-1} + e_t)$$

$$\Rightarrow E(Y_t) = \phi_1 E(Y_{t-1})$$

$$\Rightarrow E(Y_t) = \phi_1 E(Y_t)$$

$$\Rightarrow E(Y_t) = 0$$

Thus:

$$\gamma_k = \text{cov}(Y_t, Y_{t-k}), k > 0$$

$$= E(Y_t Y_{t-k}) - E(Y_t) E(Y_{t-k})$$

$$= E(Y_t Y_{t-k})$$

$$= E[(\phi_1 Y_{t-1} + e_t) Y_{t-k}]$$

$$= E[\phi_1 Y_{t-1} Y_{t-k} + e_t Y_{t-k}]$$

$$= \phi_1 E[Y_{t-1} Y_{t-k}] + E[e_t Y_{t-k}]$$

$$= \phi_1 \gamma_{k-1}$$

$$\Rightarrow \gamma_k = \phi_1 \gamma_{k-1}$$

$$\Rightarrow \gamma_k = \phi_1^2 \gamma_{k-2}$$

$$\Rightarrow \gamma_k = \phi_1^k \gamma_0$$

And $\gamma_0 = \text{Var}(Y_t)$

$$= E(Y_t^2) - E(Y_t)^2$$

$$= E(Y_t^2)$$

$$= E[\phi_1^2 Y_{t-1}^2 + 2\phi_1 Y_{t-1} e_t + e_t^2]$$

$$= \phi_1^2 E[Y_{t-1}^2] + E(e_t^2)$$

$$\Rightarrow \gamma_0 = \phi_1^2 \gamma_0 + \sigma_e^2$$

$$\Rightarrow \gamma_0 - \phi_1^2 \gamma_0 = \sigma_e^2$$

$$\Rightarrow \gamma_0 = \frac{\sigma_e^2}{1 - \phi_1^2}$$

$$\Rightarrow \gamma_k = \frac{\phi_1^k}{1 - \phi_1^2} \sigma_e^2, k > 0$$

And thus,

$$\boxed{S_k = \phi^k}$$

d) AR(2)

$$Y_t = \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t$$

$$\begin{aligned} E(Y_t) &= E(\phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t) \\ &= \phi_1 E(Y_{t-1}) + \phi_2 E(Y_{t-2}) \\ \Rightarrow M_t &= \phi_1 M_{t-1} + \phi_2 M_{t-2} \\ \Rightarrow M_t &= M_t (\phi_1 + \phi_2) \\ \Rightarrow M_t &= 0 \end{aligned}$$

$$\text{Thus, } \text{cov}(Y_t, Y_{t-k}) = E(Y_t Y_{t-k})$$

$$\begin{aligned} &= \phi_1 E(Y_{t-1} Y_{t-k}) + \phi_2 E(Y_{t-2} Y_{t-k}) + E(e_t Y_{t-k}) \\ \Rightarrow \bar{Y}_k &= \phi_1 \bar{Y}_{k-1} + \phi_2 \bar{Y}_{k-2} \\ \Rightarrow \bar{S}_k &= \phi_1 \bar{S}_{k-1} + \phi_2 \bar{S}_{k-2} \end{aligned}$$

We can compute \bar{Y}_0 by:

$$\begin{aligned} \text{Var}(Y_t) &= \text{Var}(\phi_1 Y_{t-1} + \phi_2 Y_{t-2} + e_t) \\ &= \text{Var}(\phi_1 Y_{t-1} + \phi_2 Y_{t-2}) + \text{cov}(\phi_1 Y_{t-1} + \phi_2 Y_{t-2}, e_t) + \text{Var}(e_t) \\ &= \phi_1^2 \text{Var}(Y_{t-1}) + \phi_2^2 \text{Var}(Y_{t-2}) + \phi_1 \phi_2 \text{cov}(Y_{t-1}, Y_{t-2}) + \sigma_e^2 \\ \Rightarrow Y_0 &= \phi_1^2 \bar{Y}_0 + \phi_2^2 \bar{Y}_0 + \phi_1 \phi_2 \bar{Y}_1 + \sigma_e^2 \end{aligned}$$

Thus we have:

$$\begin{cases} \bar{Y}_0 = \phi_1^2 \bar{Y}_0 + \phi_2^2 \bar{Y}_0 + \phi_1 \phi_2 \bar{Y}_1 + \sigma_e^2 \\ \bar{Y}_1 = \phi_1 \bar{Y}_0 + \phi_2 \bar{Y}_1 \\ \Rightarrow \bar{Y}_1 (1 - \phi_1) = \phi_1 \bar{Y}_0 \\ \Rightarrow \bar{Y}_1 = \frac{\phi_1 \bar{Y}_0}{1 - \phi_1} \end{cases}$$

$$\Rightarrow \bar{x}_0 = \phi_1^2 \bar{x}_0 + \phi_2^2 \bar{x}_0 + \phi_1 \phi_2 \left(\frac{\phi_1 \bar{x}_0}{1-\phi_2} \right) + \sigma_e^2$$

$$\Rightarrow \bar{x}_0 - \phi_1^2 \bar{x}_0 - \phi_2^2 \bar{x}_0 - \phi_1 \phi_2 \left(\frac{\phi_1 \bar{x}_0}{1-\phi_2} \right) = \sigma_e^2$$

$$\Rightarrow \bar{x}_0 \left(1 - \phi_1^2 - \phi_2^2 - \phi_1 \phi_2 \cdot \frac{\phi_1}{1-\phi_2} \right) = \sigma_e^2$$

$$\Rightarrow \bar{x}_0 = \frac{\sigma_e^2}{1 - \phi_1^2 - \phi_2^2 - \frac{\phi_1^2 \phi_2}{1-\phi_2}}$$

$$= \frac{\sigma_e^2 (1-\phi_2)}{(1-\phi_2)(1-\phi_1^2 - \phi_2^2) - \phi_1^2 \phi_2}$$

$$= \frac{\sigma_e^2 (1-\phi_2)}{1 - \phi_1^2 - \phi_2^2 - \phi_1^2 + \phi_1^2 \phi_2 - \phi_2^3 - \phi_1^2 \phi_2}$$

$$= \frac{\sigma_e^2 (1-\phi_2)}{(1-\phi_2)^2 - \phi_1^2} \cdot \left(\frac{1-\phi_2}{1+\phi_2} \right)$$

e.) ARMA(1,1)

$$Y_t = \phi Y_{t-1} + e_t - \theta e_{t-1}$$

Before proceeding, note that:

$$E(Y_t) = 0$$

$$\begin{aligned} E(Y_t e_t) &= \underbrace{\phi E(Y_{t-1} e_t)}_{= \sigma_e^2} + E(e_t e_t) - \theta E(e_{t-1} e_t) \\ &= \sigma_e^2 \end{aligned}$$

$$\begin{aligned} E(Y_t e_{t-1}) &= \phi E(Y_{t-1} e_t) + E(e_t e_{t-1}) - \theta E(e_{t-1} e_t) \\ &= \phi \sigma_e^2 - \theta \sigma_e^2 \\ &= (\phi - \theta) \sigma_e^2 \end{aligned}$$

Thus,

$$\begin{aligned} \text{cov}(Y_t, Y_{t-k}) &= E(Y_t Y_{t-k}) \\ &= E(\phi Y_{t-1} Y_{t-k} + e_t Y_{t-k} - \theta e_{t-1} Y_{t-k}) \\ &= \phi \bar{\gamma}_{k-1} + [1 - \theta(\phi - \theta)] \sigma_e^2 \end{aligned}$$

$$\begin{aligned} \text{Var}(Y_t) &= E(Y_t Y_t) \\ \Rightarrow \bar{\gamma}_0 &= E(\phi Y_{t-1} Y_t + e_t Y_t - \theta e_{t-1} Y_t) \\ &= \phi \bar{\gamma}_1 + \sigma_e^2 - \theta(\phi - \theta) \sigma_e^2 \\ &= \phi \bar{\gamma}_1 + [1 - \theta(\phi - \theta)] \sigma_e^2 \end{aligned}$$

$$\begin{aligned} \bar{\gamma}_1 &= E(Y_t Y_{t-1}) \\ &= E(\phi Y_{t-1} Y_{t-1} + e_t Y_{t-1} - \theta e_{t-2} Y_{t-1}) \\ &= \phi \bar{\gamma}_0 - \theta \sigma_e^2 \end{aligned}$$

$$\Rightarrow \begin{cases} \bar{\gamma}_0 = \phi \bar{\gamma}_1 + [1 - \theta(\phi - \theta)] \sigma_e^2 \\ \bar{\gamma}_1 = \phi \bar{\gamma}_0 - \theta \sigma_e^2 \\ \bar{\gamma}_2 = \phi \bar{\gamma}_{-1} \end{cases}$$

$$\Rightarrow \gamma_0 = \phi [\phi_1 \gamma_0 - \theta \sigma_e^2] + [1 - \theta(\phi - \theta)] \sigma_e^2$$

$$\Rightarrow \gamma_0 = \phi^2 \gamma_0 - \phi \theta \sigma_e^2 + [1 - \theta(\phi - \theta)] \sigma_e^2$$

$$\Rightarrow \gamma_0 (1 - \phi^2) = [-\phi \theta + 1 - \theta(\phi - \theta)] \sigma_e^2$$

$$= [1 - \theta(2\phi - \theta)] \sigma_e^2$$

$$\Rightarrow \gamma_0 = \frac{1 - \theta(2\phi - \theta)}{1 - \phi^2} \sigma_e^2$$

$$\Rightarrow \gamma_0 = \frac{\theta^2 - 2\phi\theta + 1}{1 - \phi^2} \sigma_e^2$$

Thus,

$$\gamma_k = \phi \gamma_{k-1}$$

$$= \phi^{k-1} \gamma_1$$

$$= \phi^{k-1} (\phi_1 \gamma_0 - \theta \sigma_e^2)$$

$$= \phi \gamma_0 - \phi^{k-1} \theta \sigma_e^2$$

$$= \frac{\theta^2 - 2\phi\theta + 1}{1 - \phi^2} \phi^k \sigma_e^2 - \phi^{k-1} \theta \sigma_e^2$$

$$= \left(\frac{\theta^2 - 2\phi\theta + 1}{1 - \phi^2} \phi^k - \phi^{k-1} \theta \right) \sigma_e^2$$

$$= \left(\frac{\theta^2 - 2\phi\theta + 1}{1 - \phi^2} \phi - \theta \right) \phi^{k-1} \sigma_e^2$$

$$= \left(\frac{\theta^2 \phi - 2\phi^2 \theta + \phi - \theta + \phi^2 \theta}{1 - \phi^2} \right) \phi^{k-1} \sigma_e^2$$

$$\Rightarrow \boxed{\gamma_k = \frac{\theta^2 \phi - \phi^2 \theta + \phi - \theta}{1 - \phi^2} \phi^{k-1} \sigma_e^2}$$

$$\gamma_1 = \frac{\theta^2 \phi - \phi^2 \theta + \phi - \theta}{1 - \phi^2} \sigma_e^2$$

$$\gamma_0 = \frac{\theta^2 - 2\phi\theta + 1}{1 - \phi^2} \sigma_e^2$$

and,

$$S_k = \frac{x_k}{x_0}$$

$$= \phi^{k-1} (\phi_1 x_0 - \theta \sigma_e^2) / x_0$$

$$= \phi^k - \theta \sigma_e^2 / x_0$$

$$\boxed{S_k = \phi^k - \frac{1-\phi^2}{\theta^2 - 2\phi\theta + 1} \theta \quad k \geq 1}$$