Video 24: Elements of Dynamic Programming COMS10017 - Algorithms 1

Dr Christian Konrad

Solving a Problem with Dynamic Programming:

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Solving a Problem with Dynamic Programming:

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Discussion:

- Steps 1 and 2 requires studying the problem at hand
- Steps 3 and 4 are usually straightforward

Optimal Substructure

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• MATRIX-CHAIN-PARENTHESIZATION: If in *OPT* final multiplication is $A_{1k} \times A_{(k+1)n}$ then *OPT* contains optimal parenthesizations of $A_1 \times \cdots \times A_k$ and $A_{k+1} \times \cdots \times A_n$

$$(A_1 \times (A_2 \times A_3)) \times ((A_4 \times A_5) \times A_6)$$

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 - OPT contains optimal parenthesizations for subproducts
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 - OPT contains optimal parenthesizations for subproducts
 - $A_i \times \cdots \times A_i$
 - \rightarrow Store optimal parenthesizations for every subproduct
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 $m[i,j] := \min$. # scalar mult. to compute $A_i \times A_{i+1} \times \cdots \times A_j$

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$$m[i,j] := \min$$
. # scalar mult. to compute $A_i \times A_{i+1} \times \cdots \times A_j$

$$m[i,j] = \min_{i \le k < j} m[i,k] + m[k+1,j] + \text{``cost for computing } A_{ik} \times A_{(k+1)j}$$
''

Two Possibilities:

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$$m[i] = \max_{1 \le k \le i} p_k + m_{i-k}$$

0	1	2	3	4	5	6	7	8	9	10
-	-	-	-	-	-	-	-	-	-	-

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Example: Bottom-up for Pole-Cutting

length
$$i$$
 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |

price $p(i)$ | 1 | 5 | 8 | 9 | 10 | 17 | 17 | 20 | 24 | 30 |

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-	-	-	-	-	-	-	-	-	-	-

Initialize base cases: m[0] = 0 and $m[1] = p_1$

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0	1	2	3	4	5	6	7	8	9	10
0	1	-	-	-	-	-	-	-	-	-

$$m[2] = \max\{p_1 + m_1, p_2 + m_0\} = \max\{1 + 1, 5 + 0\} = 5$$

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$$m[3] = \max\{p_1 + m_2, p_2 + m_1, p_3 + m_0\} = \max\{1+5, 5+1, 8+0\} = 8$$

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0	1	2	3	4	5	6	7	8	9	10
0	1	5	8	-	-	-	-	-	-	-

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$$m[4] = \max\{p_1 + m_3, p_2 + m_2, p_3 + m_1, p_4 + m_0\} = \max\{1 + 8, 5 + 5, 8 + 1, 9\} = 10$$

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$$m[5] = \max\{p_1 + m_4, p_2 + m_3, p_3 + m_2, p_4 + m_1, p_5 + m_0\} = \max\{1 + 10, 5 + 8, 8 + 2, 9 + 1, 10\} = 13$$

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Example: Bottom-up for Pole-Cutting

length
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 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 10 | 10 | 5 | 8 | 9 | 10 | 17 | 17 | 20 | 24 | 30 | $m[i] = \max_{i} p_{i} + m_{i}$

$$m[i] = \max_{1 \le k \le i} p_k + m_{i-k}$$

0	1	2	3	4	5	6	7	8	9	10
0	1	5	8	10	13	-	-	-	-	-

. . .

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The maximum revenue obtainable for a pole of length 10 is 30

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But how can we find out how to cut the pole?

Step 4: Construct Optimal Solution

Keep Track of Optimal Choices: store optimal choices in array s

```
Require: Integer n, array p of length n with prices Let r[0 \dots n] be a new array r[0] \leftarrow 0 for j = 1 \dots n do r[j] \leftarrow -\infty for i = 1 \dots j do r[j] \leftarrow \max\{r[j], p[i] + r[j-i]\} return r[n]
```

Algorithm BOTTOM-UP-CUT-POLE(p, n)

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Require: Integer n, array p of length n with prices
  Let r[0...n] be a new array, let s[1...n] be a new array
  r[0] \leftarrow 0
  for j = 1 \dots n do
     r[i] \leftarrow -\infty
     for i = 1 \dots j do
        if p[i] + r[j-i] > q then
           r[i] \leftarrow p[i] + r[i-i]
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Algorithm BOTTOM-UP-CUT-POLE(p, n)

- s[i] contains position of first cut in optimal solution
- Easy to reconstruct all cuts

Subproblem Graph

Subproblem Graph

• One node for each subproblem

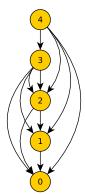
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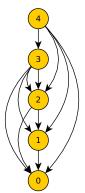


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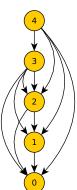
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Runtime of Dynamic Programming Algorithm:

• Total number of subproblems t



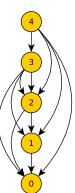
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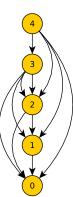
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Runtime of Dynamic Programming Algorithm:

- Total number of subproblems t
- Maximum number of subproblems a subproblem depends on s
- Runtime: $O(s \cdot t)$ (assuming that computing solution takes time O(s))



Fibonacci Numbers

Fibonacci Numbers:

$$F_0 = 0, F_1 = 1$$

 $F_n = F_{n-1} + F_{n-2} \text{ for } n \ge 2$.

```
Require: Integer n \ge 0

if n \le 1 then

return n

else

A \leftarrow \text{ array of size } n

A[0] \leftarrow 1, A[1] \leftarrow 1

for i \leftarrow 2 \dots n do

A[i] \leftarrow A[i-2] + A[i-1]

return A[n]
```

DynPrgFib
$$(n)$$

Why is this a dynamic programming algorithm?

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Compute Optimal Costs & Compute Optimal Solution

- Cost and solution is identical for Fibonacci numbers
- There is no need to keep track of optimal choices, since there is only a single choice

Problem: Maximum-Subarray

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- **Input:** Array A of n numbers
- **Output:** Indices $0 \le i \le j \le n-1$ such that $\sum_{l=i}^{j} A[l]$ is maximum.

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Divide-and-Conquer Algorithm

• In lecture 7 we gave a divide-and-conquer algorithm with runtime $O(n \log n)$

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Divide-and-Conquer Algorithm

- In lecture 7 we gave a divide-and-conquer algorithm with runtime $O(n \log n)$
- We will give now a faster dynamic programming algorithm

Related Problem: Maximum-Suffix-Array

Related Problem: MAXIMUM-SUFFIX-ARRAY

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Related Problem: MAXIMUM-SUFFIX-ARRAY

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Optimal Substructure for Maximum-Subarray:

• Let i, j be the indices of the optimal solution

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- Let i, j be the indices of the optimal solution
- Then i is the optimal solution for MAXIMUM-SUFFIX-ARRAY on input A[0...j]

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But then $\sum_{j=i'}^{n-1} A[j] > \sum_{j=i}^{n-1} A[j]$, a contradiction to the fact that i is optimal for A.

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	0	1	2	3	4	5	6	7	8	9	10
Α	-25	20	-3	-16	-23	18	20	-7	12	-5	1
m											

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Α	-25	20	-3	-16	-23	18	20	-7	12	-5	1
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	-25								12	-5	1
m	-25	20	17	1	-22	18	38				,

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	-25									-5	1
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\overline{A}	-25	20	-3	-16	-23	18	20	-7	12	-5	1
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	0	l					1	1			
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Example: Bottom-up Computation

				3							
	-25										
m	-25	20	17	1	-22	18	38	31	43	38	39

Maximum constitutes optimal solution to MAXIMUM-SUBARRAY!

Dynamic Programming Algorithm for Maximum Subarray

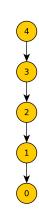
Algorithm: Input is an array A of integers of length n

- Compute dyn. prog. table for MAXIMUM-SUFFIX-ARRAY
- Return the maximum value in the table

```
Require: Array A of n integers
  Let m[0...n-1] be a new array
  m[0] \leftarrow A[0]
  q \leftarrow A[0]
  for i = 1 ... n - 1 do
     if m[i-1] < 0 then
        m[i] \leftarrow A[i]
     else
        m[i] \leftarrow A[i] + m[i-1]
     q \leftarrow \max\{q, m[i]\}
  return q
```

Kadane's Algorithm for MAXIMUM-SUBARRAY

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• Runtime: O(n) (n subproblems, only one subproblem needed to compute current value)



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- Runtime: O(n) (n subproblems, only one subproblem needed to compute current value)
- Recall that Divide-and-Conquer solution has a runtime of O(n log n)
- \bullet Observe that for Maximum-Subarray Dynamic Programming and Divide-and-Conquer is applicable

Challenges:

- Compute max. subarray of size at most k, for some k
- Compute subarray A[i,j] such that

$$\frac{\sum_{k=i}^{j} A[k]}{\sqrt{j-i+1}}$$

is maximized.

