

Elements of Dynamic Programming

COMS10018 - Algorithms

Dr Christian Konrad

Solving a Problem with Dynamic Programming:

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- ① Identify optimal substructure

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- Steps 1 and 2 requires studying the problem at hand

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- ① Identify optimal substructure
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Discussion:

- Steps 1 and 2 requires studying the problem at hand
- Steps 3 and 4 are usually straightforward

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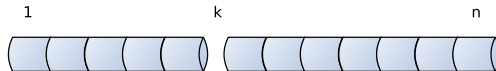
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- **POLE-CUTTING:** If *OPT* cuts at position k then cuts within $\{1, \dots, k-1\}$ form opt. solution to pole of len. k , and cuts within $\{k+1, \dots, n\}$ form opt. solution to pole of len. $n-k$.



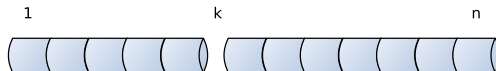
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- **MATRIX-CHAIN-PARENTHEZIZATION:**

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- **MATRIX-CHAIN-PARENTHEZIZATION:** If in *OPT* final multiplication is $A_{1k} \times A_{(k+1)n}$ then *OPT* contains optimal parenthesizations of $A_1 \times \dots \times A_k$ and $A_{k+1} \times \dots \times A_n$

$$(A_1 \times (A_2 \times A_3)) \times ((A_4 \times A_5) \times A_6)$$

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 $A_i \times \dots \times A_j$ (table of size n^2)

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$$\begin{aligned} m[i, j] &= \min_{i \leq k < j} m[i, k] + m[k+1, j] \\ &\quad + \text{"cost for computing } A_{ik} \times A_{(k+1)j} \text{"} \end{aligned}$$

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length i	1	2	3	4	5	6	7	8	9	10
price $p(i)$	1	5	8	9	10	17	17	20	24	30

$$m[i] = \max_{1 \leq k \leq i} p_k + m_{i-k}$$

0	1	2	3	4	5	6	7	8	9	10
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Initialize base cases: $m[0] = 0$ and $m[1] = p_1$

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$$m[2] = \max\{p_1 + m_1, p_2 + m_0\} = \max\{1 + 1, 5 + 0\} = 5$$

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0	1	5	-	-	-	-	-	-	-	-

$$m[3] = \max\{p_1 + m_2, p_2 + m_1, p_3 + m_0\} = \max\{1+5, 5+1, 8+0\} = 8$$

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$$m[4] = \max\{p_1 + m_3, p_2 + m_2, p_3 + m_1, p_4 + m_0\} = \max\{1 + 8, 5 + 5, 8 + 1, 9\} = 10$$

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0	1	5	8	10	-	-	-	-	-	-

$$m[5] = \max\{p_1 + m_4, p_2 + m_3, p_3 + m_2, p_4 + m_1, p_5 + m_0\} = \max\{1 + 10, 5 + 8, 8 + 2, 9 + 1, 10\} = 13$$

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The maximum revenue obtainable for a pole of length 10 is 30

Compute Optimal Costs

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But how can we find out how to cut the pole?

Step 4: Construct Optimal Solution

Keep Track of Optimal Choices: store optimal choices in array s

Require: Integer n , array p of length n with prices

Let $r[0 \dots n]$ be a new array

$r[0] \leftarrow 0$

for $j = 1 \dots n$ **do**

$r[j] \leftarrow -\infty$

for $i = 1 \dots j$ **do**

$r[j] \leftarrow \max\{r[j], p[i] + r[j - i]\}$

return $r[n]$

Algorithm BOTTOM-UP-CUT-POLE(p, n)

Step 4: Construct Optimal Solution

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Require: Integer  $n$ , array  $p$  of length  $n$  with prices  
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  for  $i = 1 \dots j$  do  
    if  $p[i] + r[j - i] > q$  then  
       $r[j] \leftarrow p[i] + r[j - i]$   
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Algorithm BOTTOM-UP-CUT-POLE(p, n)

- $s[i]$ contains position of first cut in optimal solution
- Easy to reconstruct all cuts

Subproblem Graph

Subproblem Graph and Runtime

Subproblem Graph

- One node for each subproblem

Subproblem Graph

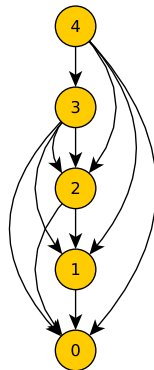
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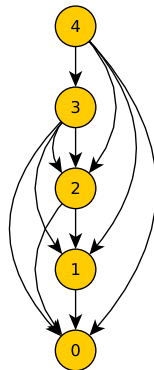
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Runtime of Dynamic Programming Algorithm:



Subproblem Graph and Runtime

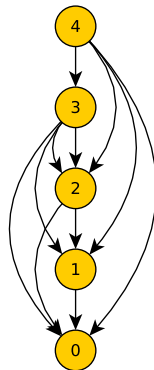
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- Total number of subproblems t



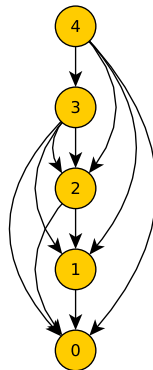
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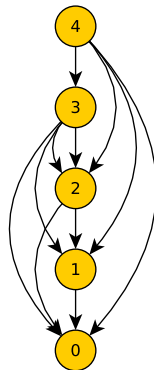
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Runtime of Dynamic Programming Algorithm:

- Total number of subproblems t
- Maximum number of subproblems a subproblem depends on s
- Runtime: $O(s \cdot t)$ (assuming that computing solution takes time $O(s)$)



Fibonacci Numbers

Fibonacci Numbers:

$$F_0 = 0, F_1 = 1$$

$$F_n = F_{n-1} + F_{n-2} \text{ for } n \geq 2.$$

Require: Integer $n \geq 0$

if $n \leq 1$ **then**

return n

else

$A \leftarrow$ array of size n

$A[0] \leftarrow 1, A[1] \leftarrow 1$

for $i \leftarrow 2 \dots n$ **do**

$A[i] \leftarrow A[i-2] + A[i-1]$

return $A[n]$

DYNPRGFIB(n)

Why is this a dynamic programming algorithm?

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Give Recursive Solution:

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Compute Optimal Costs & Compute Optimal Solution

Identify Optimal Substructure:

- Recall: $F_n = F_{n-1} + F_{n-2}$
- (Optimal) solution to size n problem equals sum of (optimal) solutions to subproblems of sizes $n - 1$ and $n - 2$ ✓

Give Recursive Solution:

- Recursive solution is already given in the problem description
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- Cost and solution is identical for Fibonacci numbers
- There is no need to keep track of optimal choices, since there is only a single choice

Maximum Subarray Problem

Problem: MAXIMUM-SUBARRAY

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- **Input:** Array A of n numbers
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- In lecture 7 we gave a divide-and-conquer algorithm with runtime $O(n \log n)$

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- In lecture 7 we gave a divide-and-conquer algorithm with runtime $O(n \log n)$
- We will give now a faster dynamic programming algorithm

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Let A be an array of length n . Let i be the optimal solution for MAXIMUM-SUFFIX-ARRAY on A . If $i < n - 1$ then the optimal solution to MAXIMUM-SUFFIX-ARRAY on $A[0 \dots n - 2]$ is also i .

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Proof.

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Proof. Suppose that the lemma is not true and suppose that $i' \neq i$ is the optimal solution to MAXIMUM-SUFFIX-ARRAY on $A[0 \dots n - 2]$.

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But then $\sum_{j=i'}^{n-1} A[j] > \sum_{j=i}^{n-1} A[j]$, a contradiction to the fact that i is optimal for A . □

Recursive Solution to Maximum Suffix Array

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A	-25	20	-3	-16	-23	18	20	-7	12	-5	1
m											

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Maximum constitutes optimal solution to MAXIMUM-SUBARRAY!

Dynamic Programming Algorithm for Maximum Subarray

Algorithm: Input is an array A of integers of length n

- 1 Compute dyn. prog. table for MAXIMUM-SUFFIX-ARRAY
- 2 Return the maximum value in the table

Require: Array A of n integers

Let $m[0 \dots n-1]$ be a new array

$m[0] \leftarrow A[0]$

$q \leftarrow A[0]$

for $i = 1 \dots n-1$ **do**

if $m[i-1] < 0$ **then**

$m[i] \leftarrow A[i]$

else

$m[i] \leftarrow A[i] + m[i-1]$

$q \leftarrow \max\{q, m[i]\}$

return q

Kadane's Algorithm for MAXIMUM-SUBARRAY

Kadane's Algorithm



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- Runtime: $O(n)$ (n subproblems, only one subproblem needed to compute current value)



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Kadane's Algorithm

- Runtime: $O(n)$ (n subproblems, only one subproblem needed to compute current value)
- Recall that Divide-and-Conquer solution has a runtime of $O(n \log n)$
- Observe that for MAXIMUM-SUBARRAY Dynamic Programming and Divide-and-Conquer is applicable

Challenges:

- Compute max. subarray of size at most k , for some k
- Compute subarray $A[i, j]$ such that

$$\frac{\sum_{k=i}^j A[k]}{\sqrt{j-i+1}}$$

is maximized.

