STORE: DYNAMICS

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Reading: PFPL §34.1.2, 34.1.3

Recall that a **store** is a finite map μ : Loc \rightharpoonup StoreVal, and that we write $\mu = \mu' \otimes \{a \mapsto v\}$ to mean that μ maps the location $a \in \text{Loc}$ to the value v (i.e. $\mu(a) \simeq v$), and that μ' is the rest of the store.

The dynamics of stores consist of the following judgements.

$$e$$
 val

$$m \parallel \mu$$
 fina

$$e \longmapsto e'$$

$$m \parallel \mu$$
 final $e \longmapsto e'$ $m \parallel \mu \longmapsto_{\Sigma} m' \parallel \mu'$

Values and Final States

e val is the same as for PCF expressions (but indexed by Σ) with one additional rule:

$$\frac{\text{Val-Cmd}}{\text{cmd}(m) \text{ val}}$$

The new judgement $m \parallel \mu$ final states that the command m has finished running, leaving the store in state μ . Only one command is final, viz. the one that returns a value:

$$\frac{e \text{ val}}{\text{ret}(e) \parallel \mu \text{ final}}$$

Transitions

The expression transitions $e \longmapsto e'$ are much the same as in PCF. The new command transitions are these:

$$\begin{array}{c} \text{D-GeT} \\ \hline \text{get}[a] \parallel \mu \otimes \{a \mapsto e\} & \cdots \mapsto_{\Sigma,a} \operatorname{ret}(e) \parallel \mu \otimes \{a \mapsto e\} \\ \hline \text{get}[a] \parallel \mu \otimes \{a \mapsto e\} & \cdots \mapsto_{\Sigma,a} \operatorname{set}[a](e') \parallel \mu \\ \hline \text{D-Set} \\ \hline \text{set}[a](e) \parallel \mu \otimes \{a \mapsto_{-}\} & \cdots \mapsto_{\Sigma,a} \operatorname{ret}(e) \parallel \mu \otimes \{a \mapsto_{-}e\} \\ \hline \text{D-Bnd-1} \\ \hline e \mapsto_{-}e' \\ \hline \text{bnd}(e;x.m) \parallel \mu \mapsto_{\Sigma} \operatorname{bnd}(e';x.m) \parallel \mu \\ \hline \hline \text{D-Bnd-CMD} \\ \hline m_1 \parallel \mu \mapsto_{\Sigma} m'_1 \parallel \mu' \\ \hline \text{bnd}(\operatorname{cmd}(m_1);x.m_2) \parallel \mu \mapsto_{\Sigma} \operatorname{bnd}(\operatorname{cmd}(m'_1);x.m_2) \parallel \mu' \\ \hline \hline \text{D-Bnd-Ret} \\ \hline e \text{ val} \\ \hline \hline \text{bnd}(\operatorname{cmd}(\operatorname{ret}(e));x.m) \parallel \mu \mapsto_{\Sigma} m[e/x] \parallel \mu \\ \hline \hline \text{D-Dcl-1} \\ \hline e \text{ val} \\ \hline \hline \text{dcl}(e;a.m) \parallel \mu \mapsto_{\Sigma} \operatorname{dcl}(e';a.m) \parallel \mu \\ \hline \hline \end{array}$$

The rules D-Dcl-1, D-Dcl-2, and D-Dcl-Ret implicitly define the concept of **block structure**. As a result, this language can be implemented using just a stack: there is no heap allocation! (Hence everything is deterministic.)

3 Type safety

We define

$$\mu: \Sigma \stackrel{\text{def}}{=} \forall a \in \Sigma. \ \exists e. \ \mu(a) \simeq e \ \land \ e \ \text{val} \land \ \vdash_{\emptyset} e: \text{Nat}$$

Type safety is given by the following two theorems. Both are shown by **simultaneous induction**.

Theorem 1 (Preservation).

- 1. If $\vdash_{\Sigma} e : \tau$ and $e \longmapsto e'$ then $\vdash_{\Sigma} e' : \tau$.
- 2. If $\vdash_{\Sigma} m$ ok, $\mu : \Sigma$, and $m \parallel \mu \longmapsto_{\Sigma} m' \parallel \mu'$ then $\vdash_{\Sigma} m'$ ok and $\mu' : \Sigma$.

Theorem 2 (Progress).

- 1. If $\vdash_{\Sigma} e : \tau$ then either e val or $e \longmapsto e'$ for some e'.
- 2. If $\vdash_{\Sigma} m$ ok and $\mu : \Sigma$ then either $m \parallel \mu$ final or $m \parallel \mu \longmapsto_{\Sigma} m \parallel \mu'$ for some m', μ' .

4 Whence CBV?

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