STORE

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Reading: PFPL §34.1.1, 34.2

Imperative programs are distinguished from functional programs by the use of a **store** (US English: **memory**). We will present Modernised Algol (MA), an imperative language which extends PCF with a store.

1 Stores

Mathematically, a store can be modelled as a finite partial function

$$\mu : \mathsf{Loc} \rightharpoonup \mathsf{StoreVal}$$

from a set Loc of **locations** to the set StoreVal of **storable values**. Loc is usually required to be infinite, so that we can always allocate more memory; for example we may pick $\mathsf{Loc} \stackrel{\text{def}}{=} \mathbb{N}$.

The set of storable values determines what can be put in the store. In many languages only first-order data (e.g. integers, booleans, ...) and aggregates thereof (e.g. structs, records, ...) are storable. However, languages like OCaml, Scala and JavaScript have a **higher-order store**, i.e. functions can be stored in memory. In this unit we will focus on a **first-order store**, so we pick $\mathsf{StoreVal} \stackrel{\text{def}}{=} \{v \mid \vdash v : \mathsf{Nat} \wedge v \, \mathsf{val}\}$.

Finally, the function μ is **finite**, i.e. its domain $\mathrm{dom}(\mu)$ is a finite set; in other words, we are only allowed to use a finite number of locations at any point in time.

We will write $\mu = \mu' \otimes \{a \mapsto v\}$ to mean that μ maps the location $a \in \mathsf{Loc}$ to the value v (i.e. $\mu(a) \simeq v$), and that μ' is the rest of the store (i.e. $a \notin \mathrm{dom}(\mu')$).

2 Commands

In addition to the **terms** of PCF, MA will have **commands**. While the purpose of expressions is to evaluate to a value, the purpose of commands will be to **change the store**, before also evaluating to a value.

The syntax chart is that of PCF plus the following extensions.

types	τ	::=	Nat		natural numbers
			$\tau_1 \rightharpoonup \tau_2$		(partial) function type
			Cmd		unevaluated commands
pre-terms	e	::=	...		
			$\mathsf{cmd}(m)$		unevaluated command
pre-commands	m	::=	$\mathsf{ret}(e)$	$\mathsf{ret}\ e$	return value
			$\mathsf{bnd}(e; x.\, m)$	$\mathsf{bind}\ x \leftarrow e; m$	sequence
			$\mathsf{dcl}(e; a.\, m)$	$\mathsf{decl}\ a := e\ \mathsf{in}\ m$	allocate
			$\mathsf{get}[a]$	$@\, a$	fetch location contents
			$\mathsf{set}[a](e)$	$a := e$	set location contents

The statics of the language have two sorts of judgment:

$$\Gamma \vdash_\Sigma e : \tau \qquad\qquad\qquad \Gamma \vdash_\Sigma m \, \mathsf{ok}$$

Both are parameterised in a finite set $\Sigma \subseteq \mathsf{Loc}$ of locations in use. The first judgement is the usual term typing. The second confirms that m is a well-formed command, using values from the context Γ.

The statics of the language are those of PCF (with the additional Σ inserted everywhere) plus the following rules.

$$\frac{}{\Gamma \vdash_{\Sigma,a} \mathsf{get}[a] \; \mathsf{ok}} \textsc{Fetch}$$

$$\textsc{Assign} \quad \frac{\Gamma \vdash_{\Sigma,a} e : \mathsf{Nat}}{\Gamma \vdash_{\Sigma,a} \mathsf{set}[a](e) \; \mathsf{ok}}$$

$$\textsc{Ret} \quad \frac{\Gamma \vdash_{\Sigma} e : \mathsf{Nat}}{\Gamma \vdash_{\Sigma} \mathsf{ret}(e) \; \mathsf{ok}}$$

$$\textsc{Cmd} \quad \frac{\Gamma \vdash_{\Sigma} m \; \mathsf{ok}}{\Gamma \vdash_{\Sigma} \mathsf{cmd}(m) : \mathsf{Cmd}}$$

$$\textsc{Bind} \quad \frac{\Gamma \vdash_{\Sigma} e : \mathsf{Cmd} \qquad \Gamma, x : \mathsf{Nat} \vdash_{\Sigma} m \; \mathsf{ok}}{\Gamma \vdash_{\Sigma} \mathsf{bnd}(e; x.\, m) \; \mathsf{ok}}$$

$$\textsc{Decl} \quad \frac{\Gamma \vdash_{\Sigma} e : \mathsf{Nat} \qquad \Gamma \vdash_{\Sigma,a} m \; \mathsf{ok}}{\Gamma \vdash_{\Sigma} \mathsf{dcl}(e; a.\, m) \; \mathsf{ok}}$$

Commands potentially change the store, and then return a value.

The commands $\mathsf{get}[a]$ and $\mathsf{set}[a](e)$ respectively fetch the value at location a, and assign the value of $e : \mathsf{Nat}$ at location a. Notice that the location needs to be allocated, i.e. included in the subscript.

The command $\mathsf{ret}(e)$ simply returns the value of a natural number expression, without changing the store.

The rule $\textsc{Cmd}$ says that any command m can be seen as an expression $\mathsf{cmd}(m) : \mathsf{Cmd}$. The command is *not* executed when this term is evaluated, but remains frozen in place. Thus, terms of the form $\mathsf{cmd}(m)$ are values.

The command $\mathsf{bnd}(e; x.\, m)$ is a **sequencing** construct. It evaluates e until it becomes a value $\mathsf{cmd}(p)$, and then runs p. The value returned by p is then bound to x, and the next command m is run.

$\mathsf{dcl}(e; a.\, m)$ declares the new location a by assigning the value of term e to it. Notice that the typing of m ensures that a is a valid location (it is included in the subscript). The **scope** of this declaration is the command m, which runs after the allocation. When its execution is complete, the location a gets de-allocated. Thus, this construct creates **block structure**, and hence enforces a **stack discipline** (= a stack suffices to implement it).

3   Examples

To relate Modernised Algol to common programming idioms we may define the following shorthands.

$$\{x \leftarrow m_1; m_2\} \overset{\text{def}}{=} \mathsf{bnd}(\mathsf{cmd}(m_1); x.\, m_2) \qquad \{m_1; m_2\} \overset{\text{def}}{=} \mathsf{bnd}(\mathsf{cmd}(m_1); \_.\, m_2) \qquad \mathsf{do}\; e \overset{\text{def}}{=} \mathsf{bnd}(e; x.\, \mathsf{ret}(x))$$

We sometimes write $\{m_1; m_2; \ldots; m_n\} \overset{\text{def}}{=} \{m_1; \{m_2; \{\ldots; m_n\}\}\}$, and similarly if we have bindings.

Armed with these shorthands we can write **conditionals** and **loops** as follows:

$$\mathsf{if}\; m \;\mathsf{then}\; m_1 \;\mathsf{else}\; m_2 \overset{\text{def}}{=} \{x \leftarrow m; \mathsf{do}\; \mathsf{ifz}(x; \mathsf{cmd}(m_1); \_.\, \mathsf{cmd}(m_2))\}$$

$$\mathsf{while}\, (m)\{m^\star\} \overset{\text{def}}{=} \mathsf{do}\; \mathsf{fix}(r : \mathsf{Cmd}.\, \mathsf{cmd}(\mathsf{if}\; m \;\mathsf{then}\; (\mathsf{ret}\; \mathsf{zero}) \;\mathsf{else}\; \{m^\star; \mathsf{do}\; r\}))$$

A **procedure** is a term $f : \tau \rightharpoonup \mathsf{Cmd}$. We define

$$\mathsf{proc}\, (x : \tau)\, \{m\} \overset{\text{def}}{=} \lambda x : \tau.\, \mathsf{cmd}(m) \qquad\qquad \mathsf{call}\; e_1(e_2) \overset{\text{def}}{=} \mathsf{do}\; e_1(e_2)$$

We can then write programs like the following one, which computes the factorial of x.

```
proc (x : nat) {
  decl r := 1 in
  decl a := x in
  {
    while (@a) {
      y ← @r; z ← @a;
      r := y * (x - z + 1);          //  r := r * (x - a + 1)
      a := z - 1;                    //  a := a - 1
    };
    x ← @ r;
    ret x
  }
}
```

The invariant for this loop is @r = (x − @a)!, so at the end @r = x!.