Homework 3- Some Noises

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Original image:



%%upload image ---MAİN-----

clc;

close all;

[fname, path] = uigetfile('*.jpg', 'Select an Image');

fname = strcat(path,fname);

im = imread(fname);

im2 = im2double(imread(fname));

%gaussian_noise(im); %add gaussian noise

%saltPepper_noise(im); %add salt and pepper noise

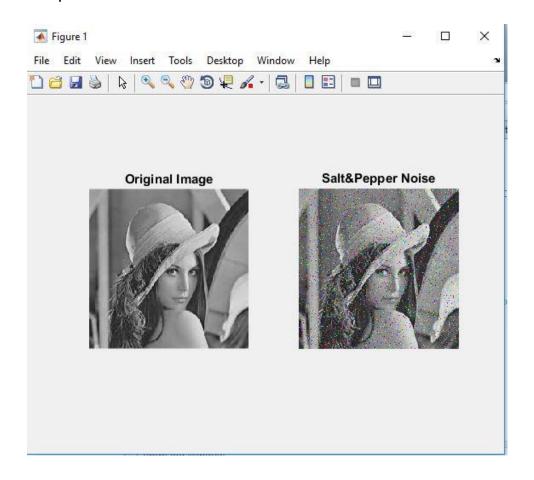
%medianFilter(im,4); %removed gaussian and salt&pepper noise

%periodic_noise_and_removed(im); %periodic noise and removed periodic noise

Salt and Pepper noise:

```
function out = saltPepper_noise(im)
J = im;
p3= 0.05;
x = rand(size(J));%n*n boyutun 0-1 arası elemanları olan matrix üretir
d = find(x < p3/2);%find() sıfır olmayan indisleri verir
J(d) = 0; %Minimum valued
d = find(x >= p3/2 \& x < p3);
J(d) = 255; %Maximum(saturated) valueimshow(J)
imwrite(J, 'salt&pepper.jpg', 'quality', 95);%%salt and pepper noise image save
figure;
subplot(121)
imshow(im)
title('Original Image')
subplot(122)
imshow(J)
title('Salt&Pepper Noise')
end
```

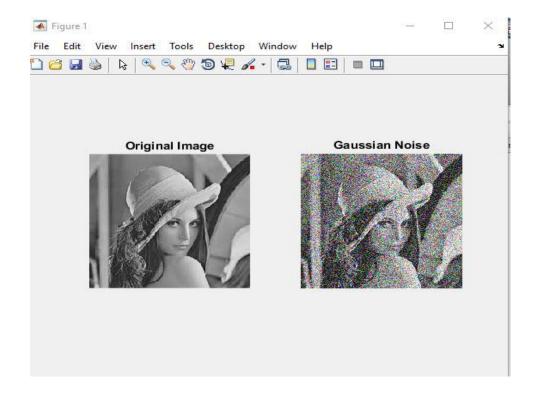
Output1:



Gaussian noise:

```
function out = gaussian_noise(im)
J = im;
p3= 0;p4 = 0.05;
J = im2double(J);
b = J + sqrt(p4)*randn(size(J)) + p3;
imwrite(b, 'gaussian.jpg', 'quality', 95);%%gaussian noise image save
figure;
subplot(121)
imshow(im)
title('Original Image')
subplot(122)
imshow(b)
title('Gaussian Noise')
end
```

Output2:



Removed Salt & Pepper noise and Gaussian noise with median filter technique:

%-removes salt and pepper noise from image.

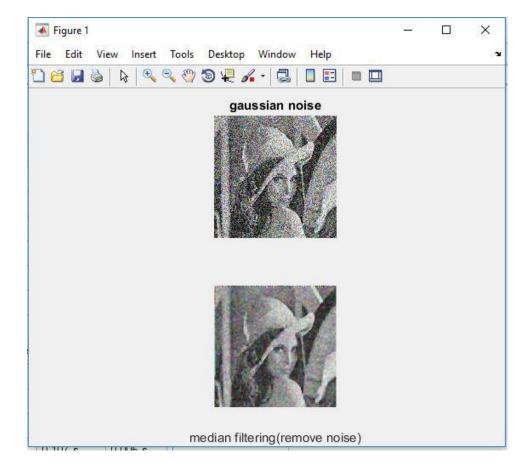
%-removes gaussian noise from image.

%With median filter, gaussian and salt and pepper noise are removed

```
function out = medianFilter(Im,n)
[height,width] = size(Im);
Im1 = double(Im);
out = Im1;
out = Im1;
center = round((n+1)/2);
for i = 1:height-n+1
    for j = 1:width-n+1
    temp = Im1(i:i+n-1,j:j+n-1);
    ele = temp(1,:);
    for count = 2:n
    ele = [ele,temp(count,:)];
```

```
end
med = median(ele);
out(i+center,j+center) = med;
end
end

out = uint8(out);
figure
subplot(2,1,1)
imshow(Im)
subplot(2,1,2)
imshow(out)
xlabel('median filtering(remove noise)')
end
```



Periodic noise and removed periodic noise:

```
function [out] = periodic_noise_and_removed(im)
A = rgb2gray(im);
[w,q] = size (A);
[x, y] = meshgrid(1:q, 1:w);
s1 = 1 + sin (x + y);
A2 = im2double(A) + s1;
tgpf = fftshift ( fft2 (A2) );
subplot(2,3,1); imshow(mat2gray (A*1.2)) ;title ('original gray');
subplot(2,3,2); imshow((A2/2));title('noisy image in Spatial domain');
subplot(2,3,3);imshow (mat2gray( log ( abs(tgpf) ) ) ) ; title('noisy image in Freq. domain ');
```

```
k = sqrt ( (x - q/2).^2 + (y - w/2).^2 );
F= ( k < 130 | k > 140 );
resf = tgpf .* F;
resi = ifft2 ( resf );
subplot(2,3,4);
imshow (mat2gray( log (1+ abs(resf) ) ) );
title ('noisy image X Ring filter ');
subplot (2,3,5);
imshow (mat2gray ( log (1+ abs(resi) ) ) );
title('F= ( z < 130 | z > 140 );');
F2= (k < 30 | k > 200);
resf2 = tgpf .* F2;
resi2 = ifft2 ( resf2 );
subplot(2,3,6);
imshow (mat2gray ( log (1+ abs(resi2) ) ) );
title('F2= ( z < 30 \mid z > 200 ); ');
end
```

Output4:

