

# Color Image Processing with Biomedical Applications

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School of Engineering

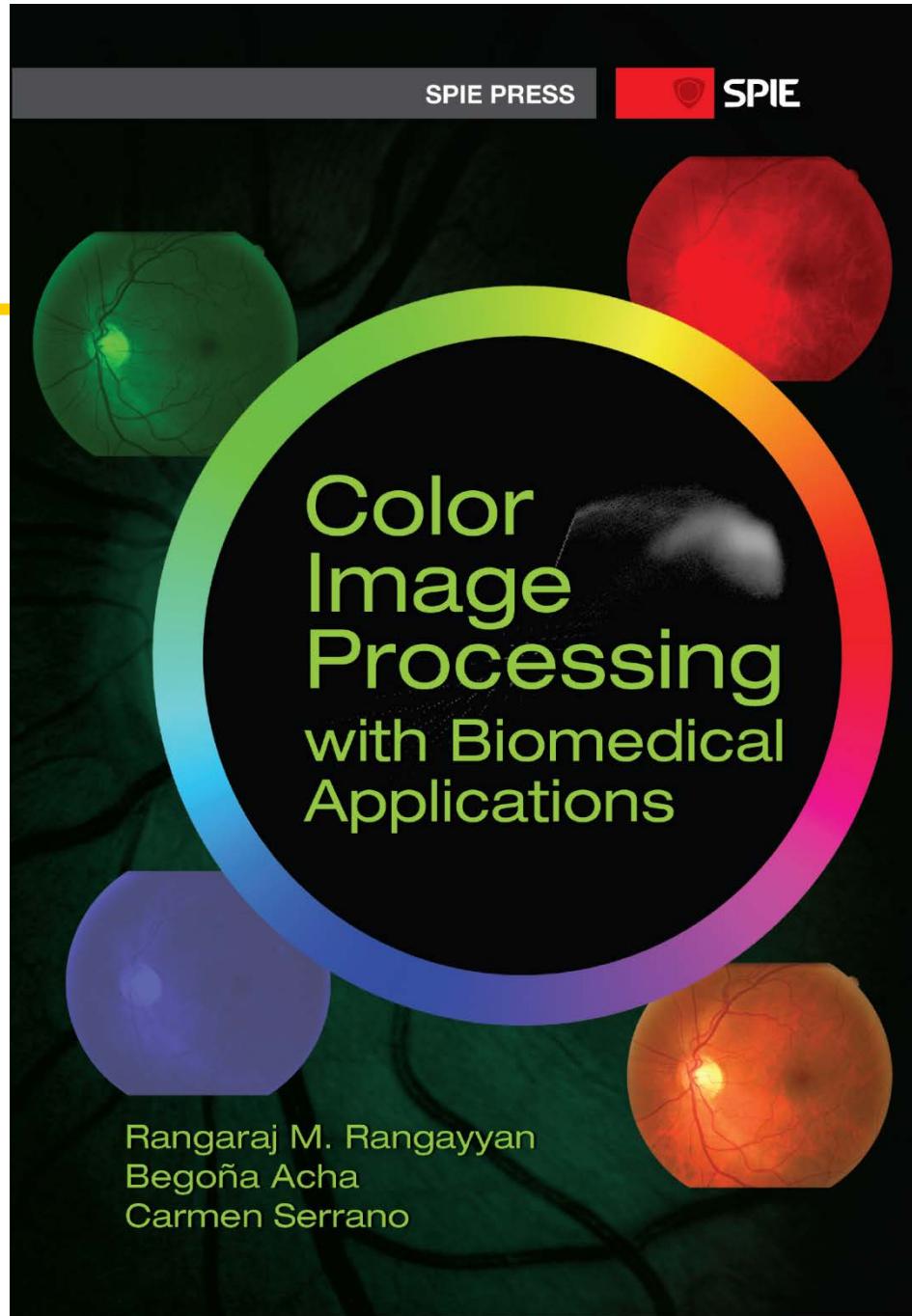


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AND COMPUTER ENGINEERING



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2011  
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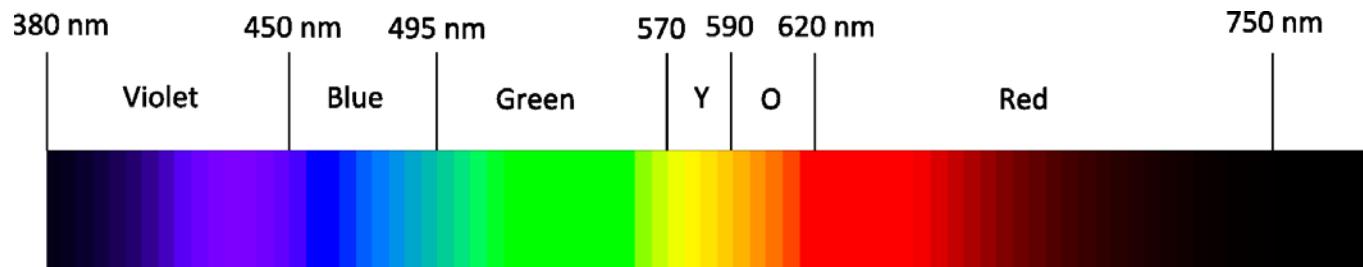


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# The Nature of Color Images



*Photo courtesy  
of Chris Pawluk*





# Color Attributes



**Hue:** dominant wavelength or band

**Saturation:** quality or colorfulness,  
not diluted with white

**Intensity or Brightness:** primary visual sensation  
related to physical luminance

Also used: Chroma, Lightness



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# Color Perception and Trichromacy

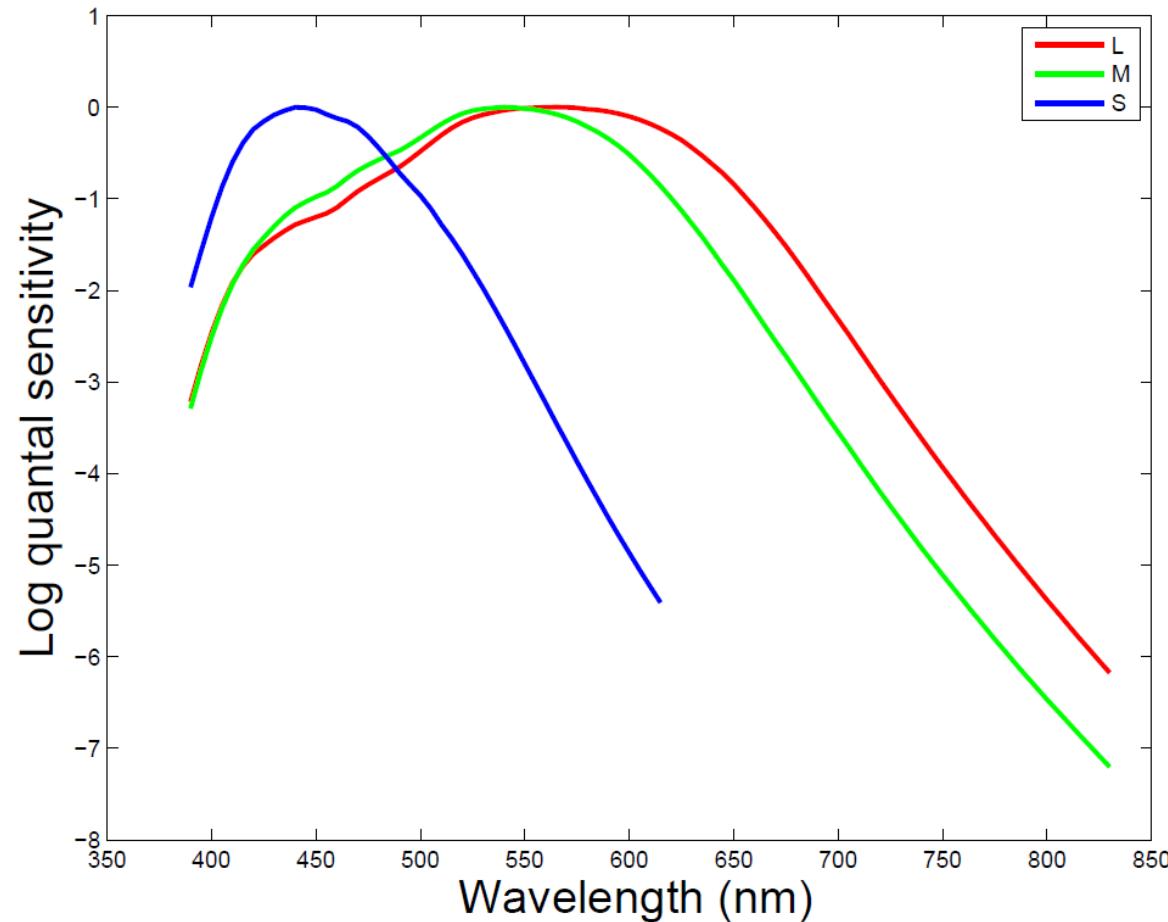


Figure 1.7 Spectral sensitivities of the *L* (red), *M* (green), and *S* (blue) cones.



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# Representation of Color Images: Color Spaces



A color image may be represented using the following standard representations:

- [red, green, blue] or RGB
- [cyan, magenta, yellow, black] or CMYK
- [hue, saturation, intensity] or HSI
- $L^*u^*v^*$ ,  $L^*a^*b^*$
- YIQ, YUV, CIE RGB, CIE XYZ
- others...



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# Color-matching Functions

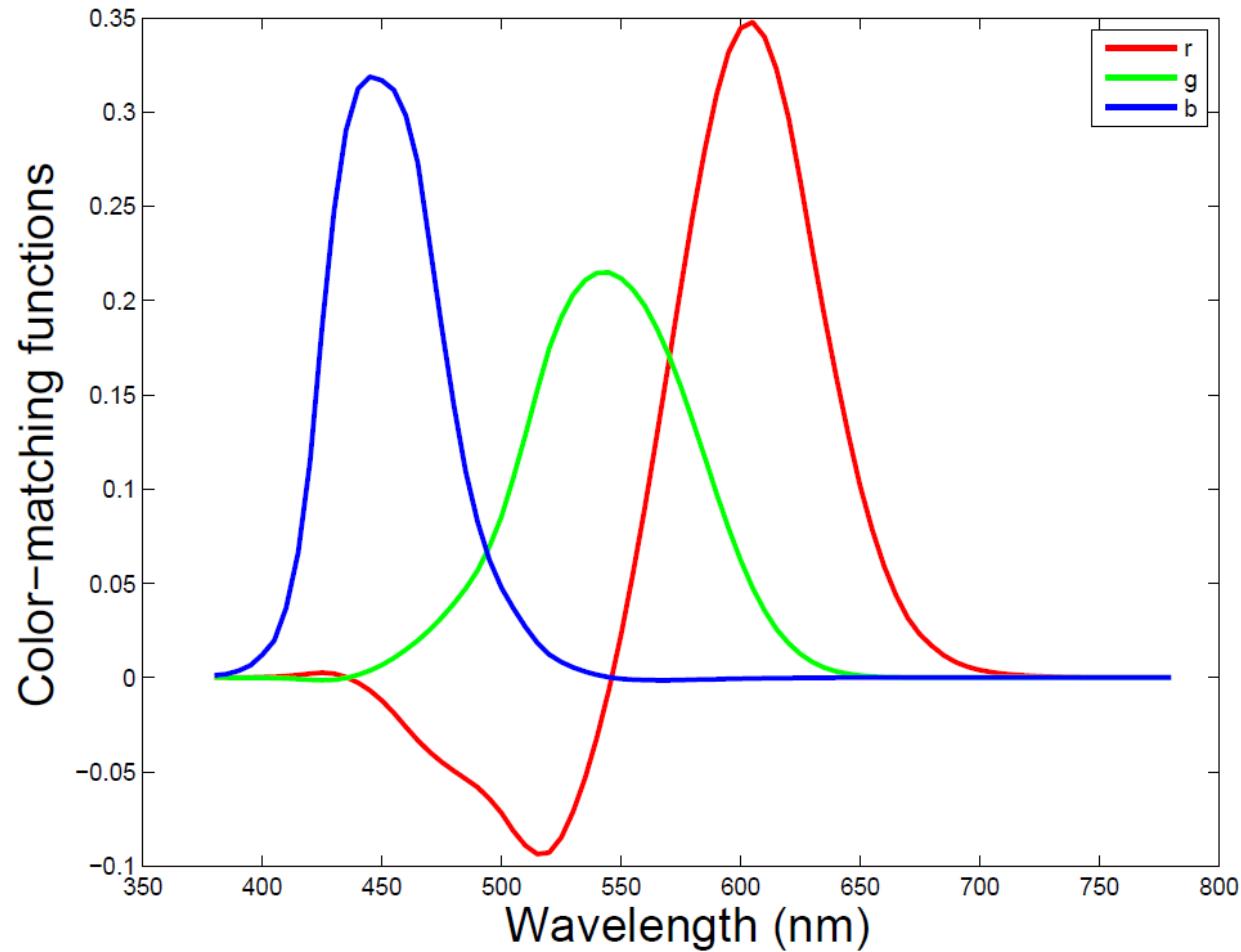


Figure 1.8 The  $\bar{r}$ ,  $\bar{g}$ , and  $\bar{b}$  color-matching functions.



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# Color-matching Functions

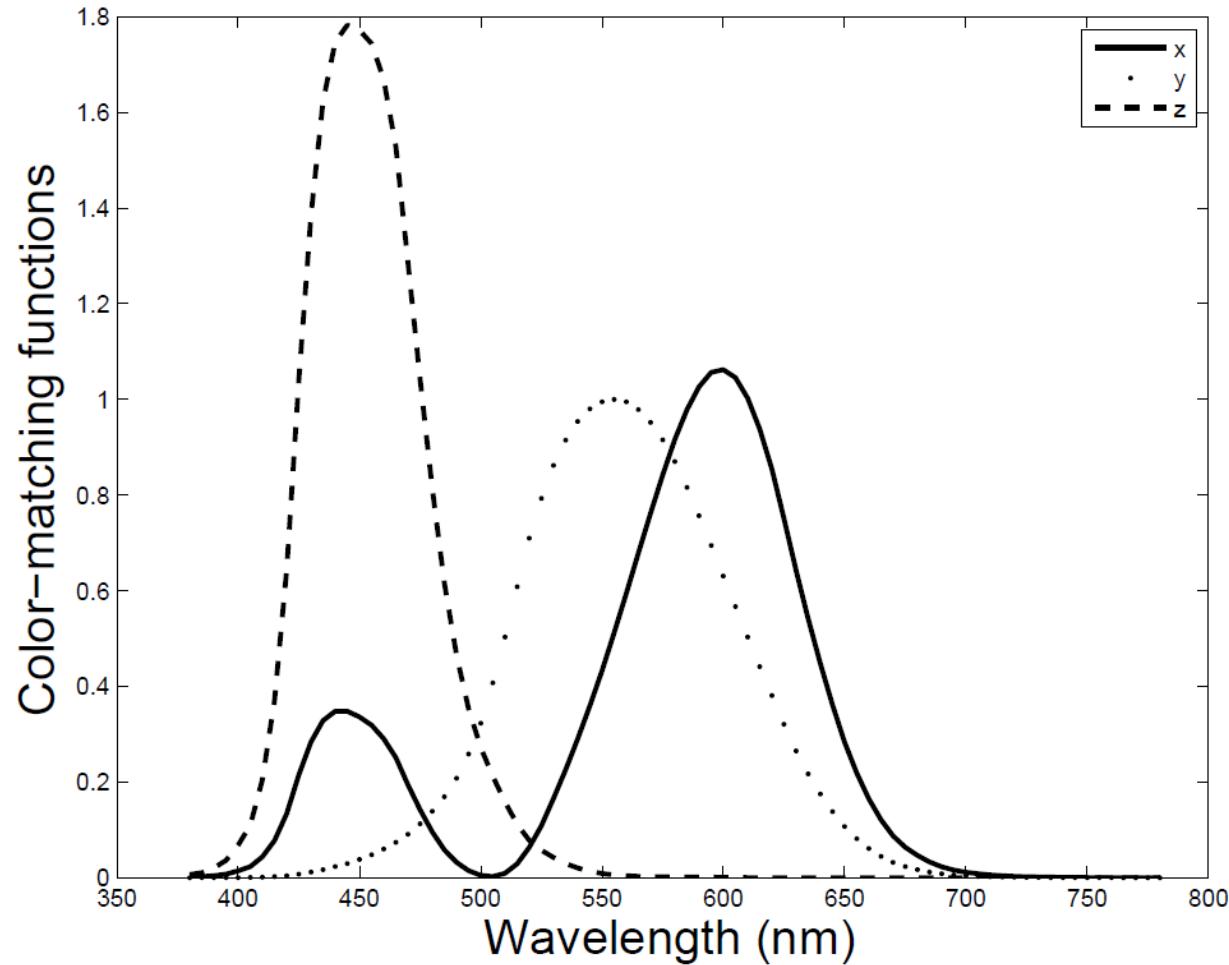


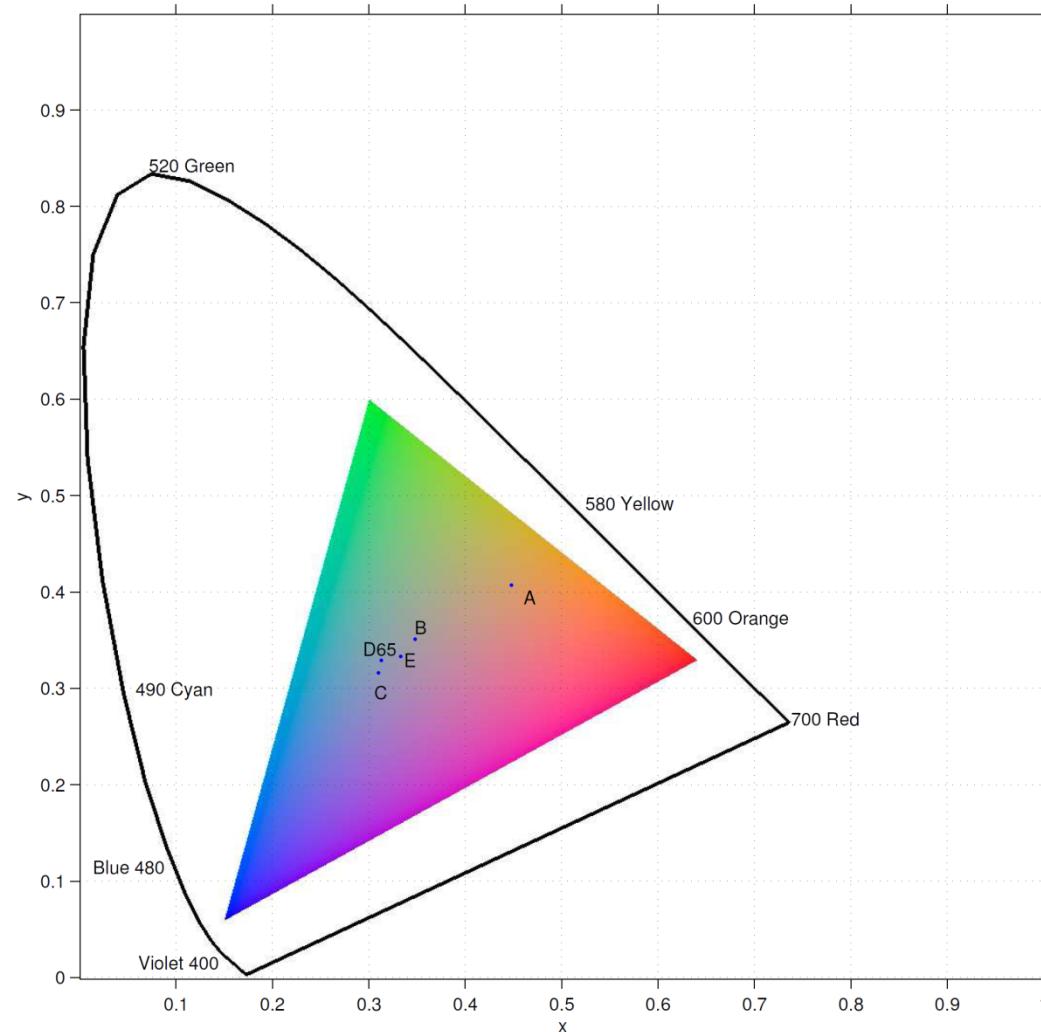
Figure 1.9 The  $\bar{x}$ ,  $\bar{y}$ , and  $\bar{z}$  color-matching functions.



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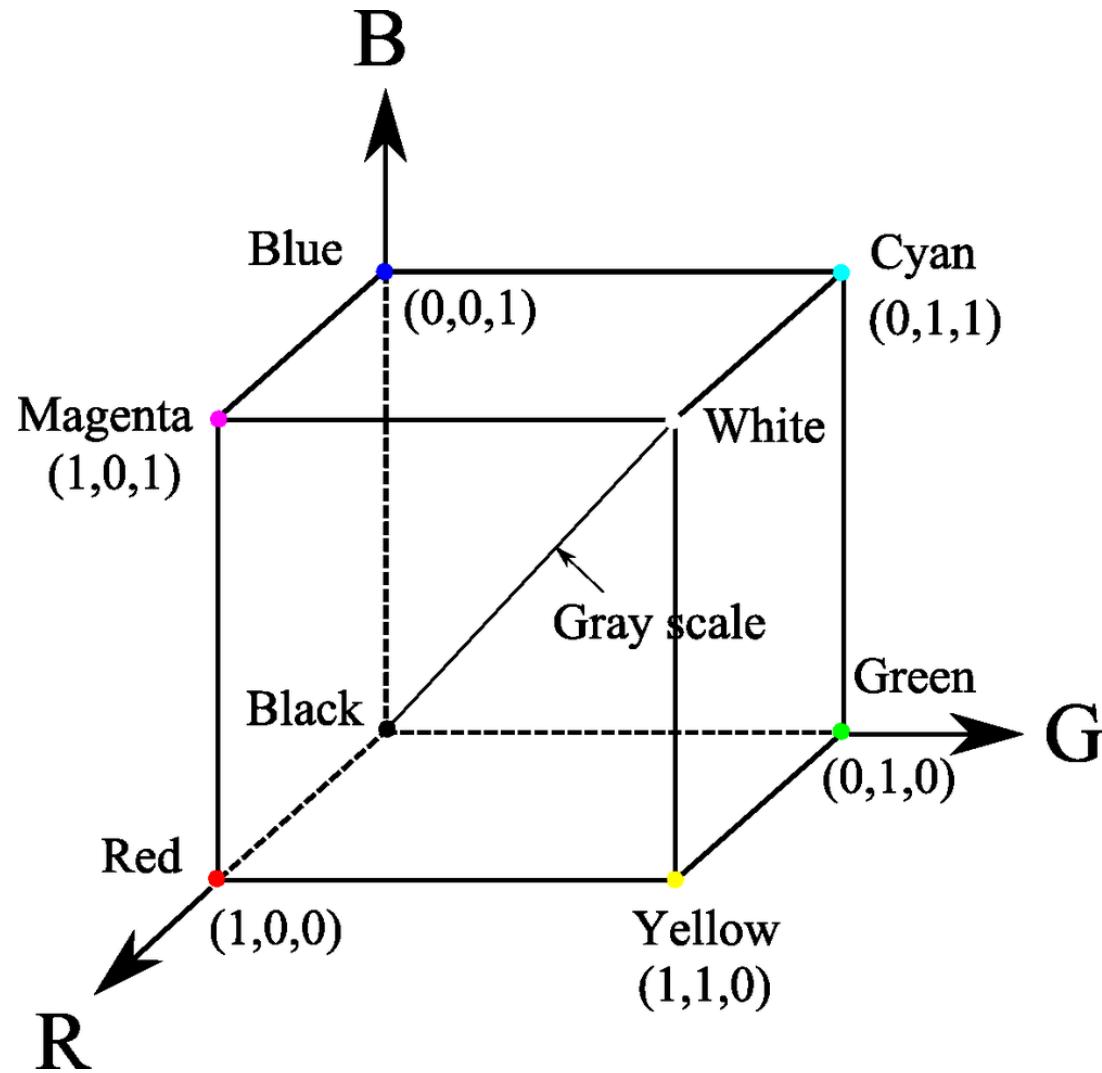


# CIE Chromaticity Diagram: Triangular Gamut of sRGB



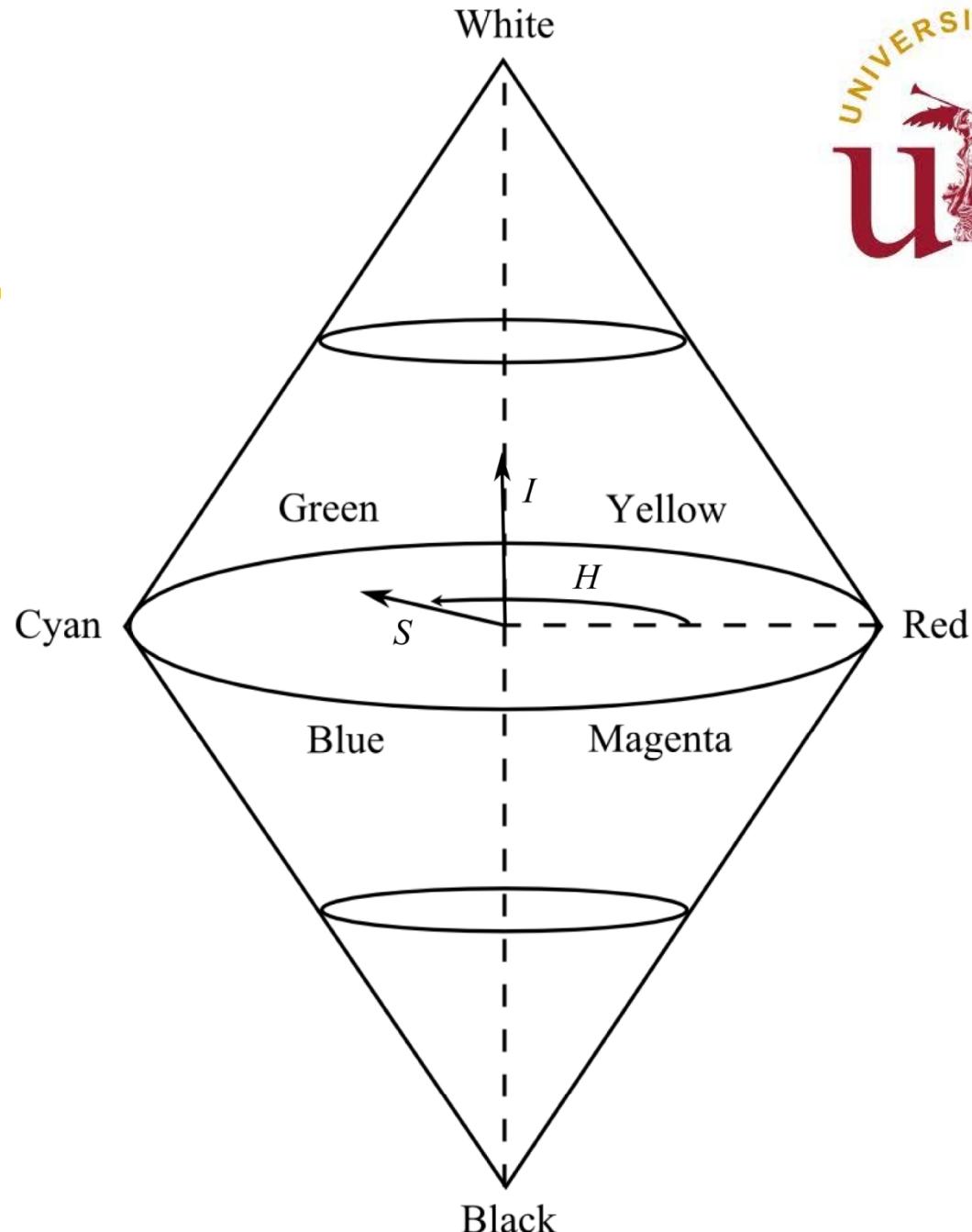


# The RGBW-CMYK Cube



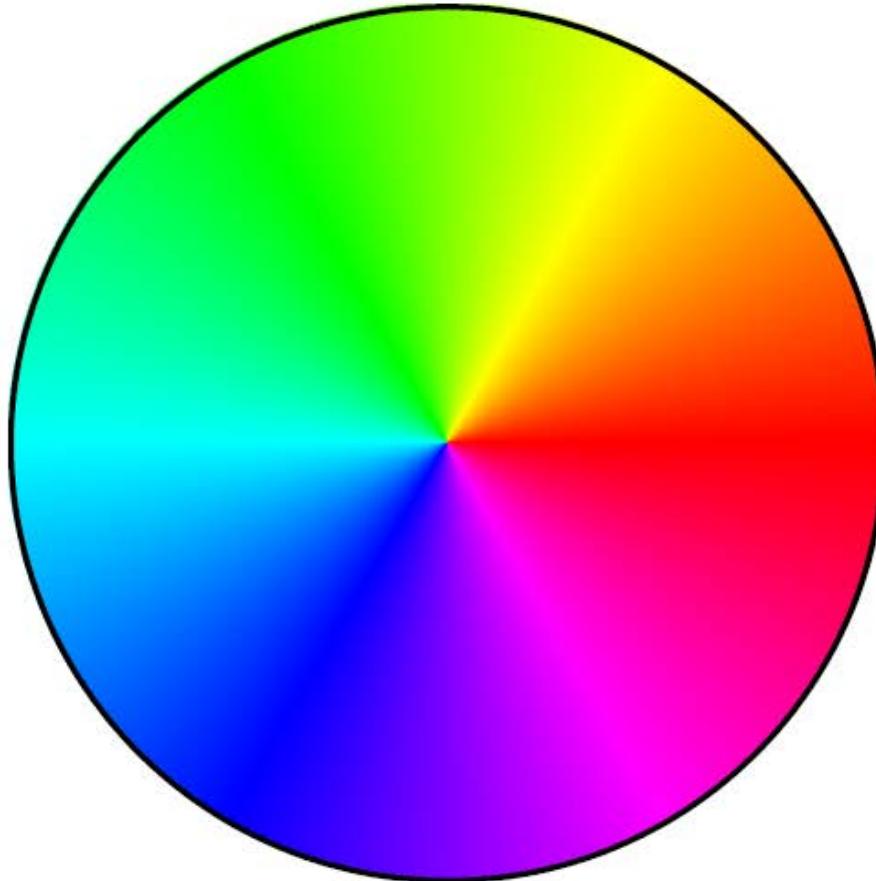


# Relationships between RGBW, HSI, and CMYK representations of color images

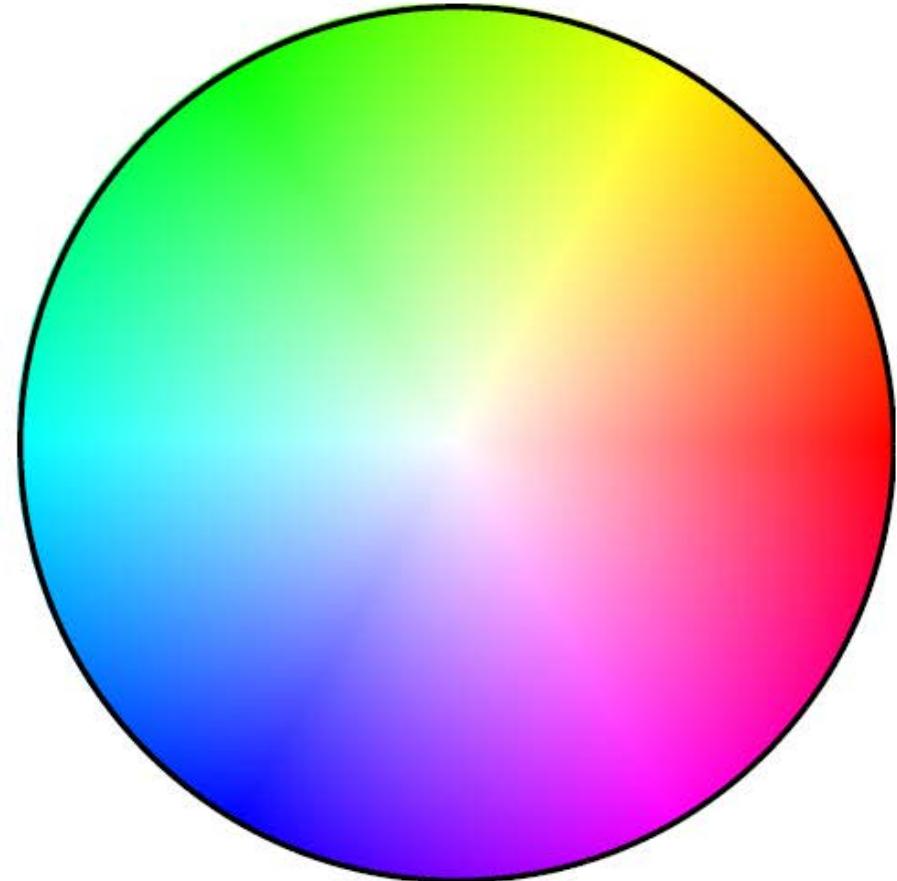




# Hue, Saturation, and Intensity



*Varying hue with constant  
saturation and intensity*



*Varying hue and saturation  
with constant intensity*



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# Representation of Color Images: RGB



*Original image*



*Red component*



*Green component*

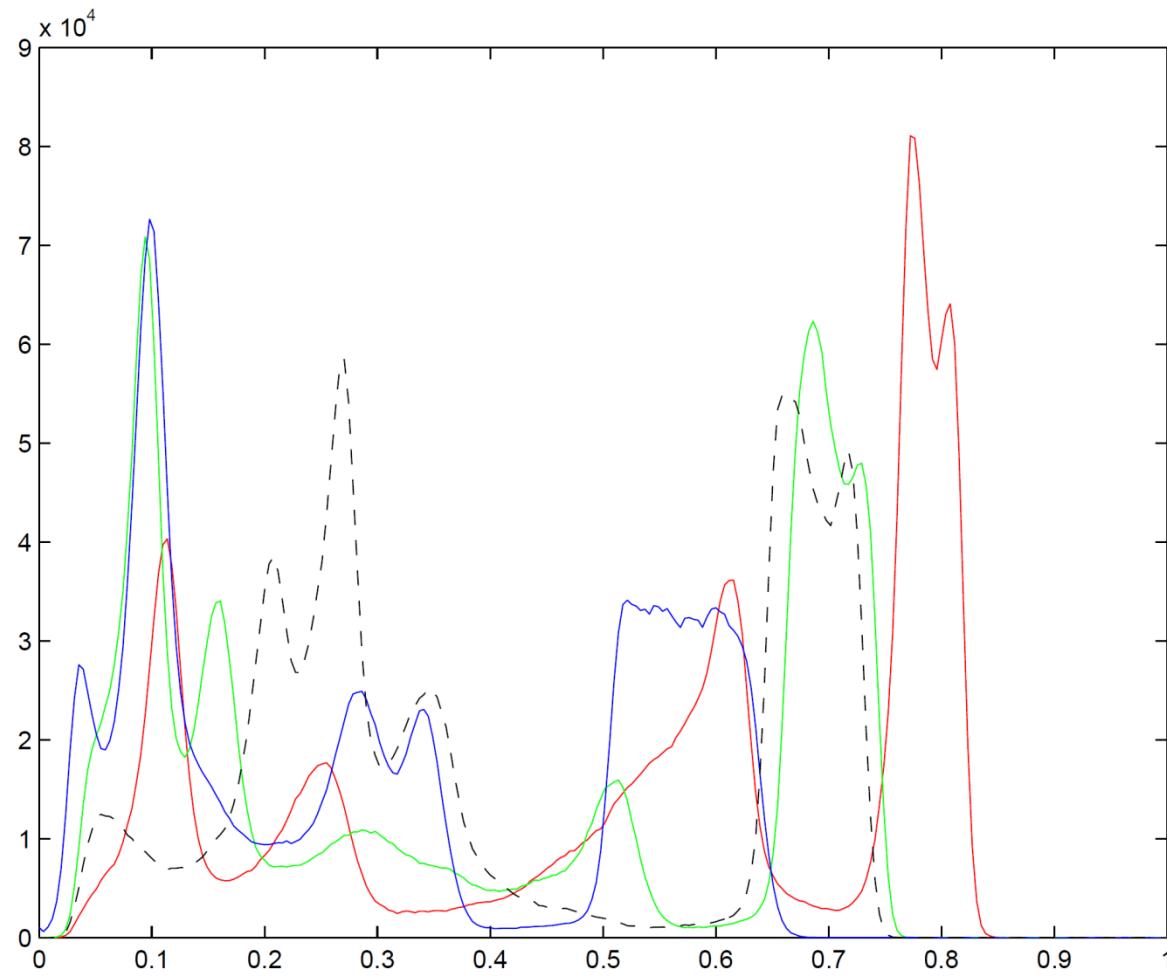


*Blue component*



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# Representation of Color Images: RGBV Histograms

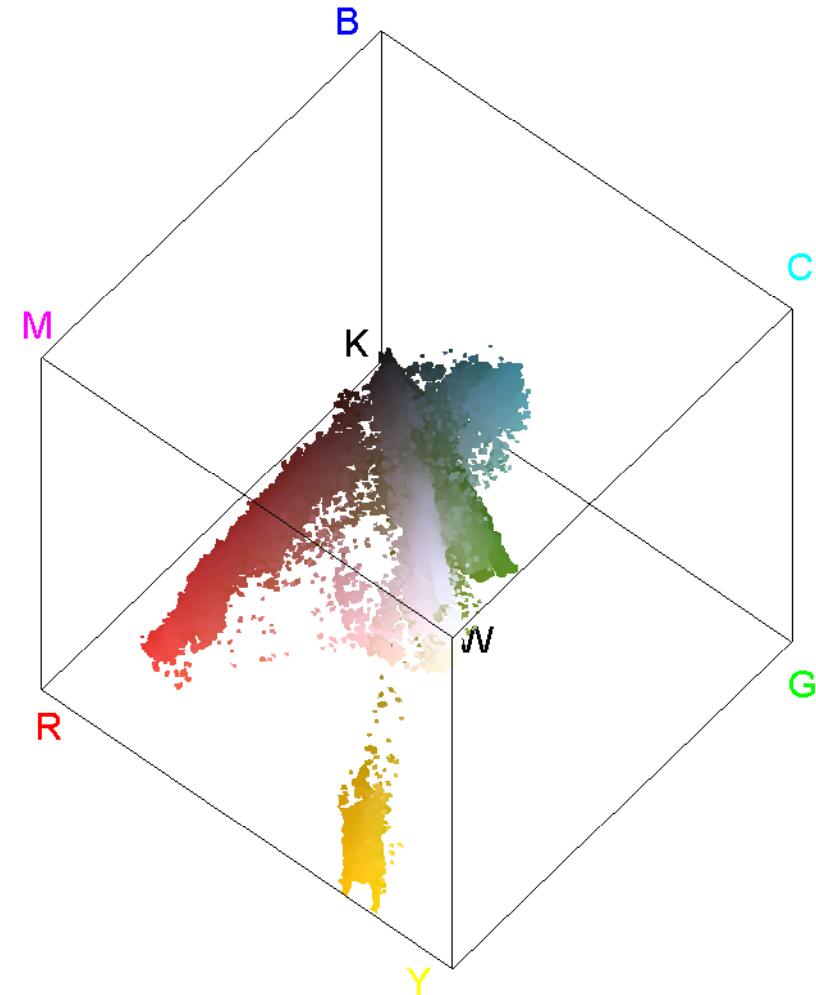




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# Representation of Color Images: RGB Histogram





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# Representation of Color Images: HSI



*Original image*



*Hue*



*Saturation*



*Intensity*



# Representation of Color Images: HSI



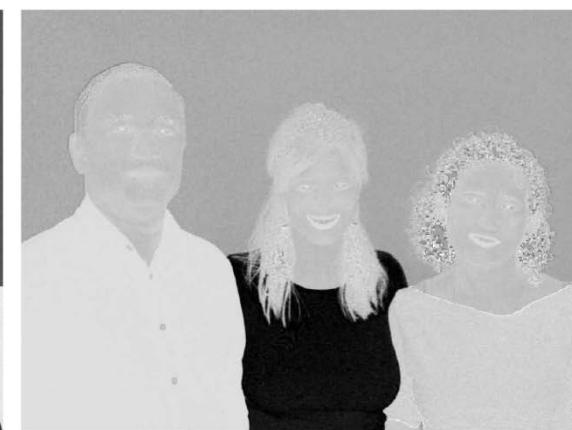
*Original image*



*Hue*



$\text{Sin}(\text{hue}/2)$  = distance from red



$\text{Sin}[(\text{hue}-120)/2]$  = distance from green



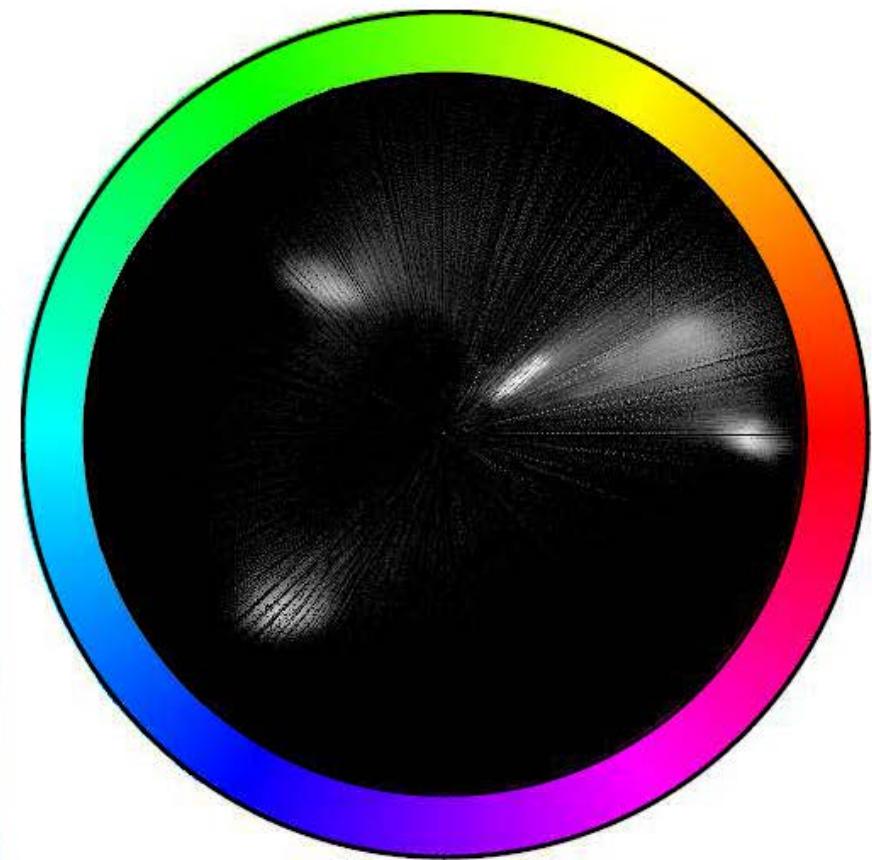
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# Representation of Color Images: HSI



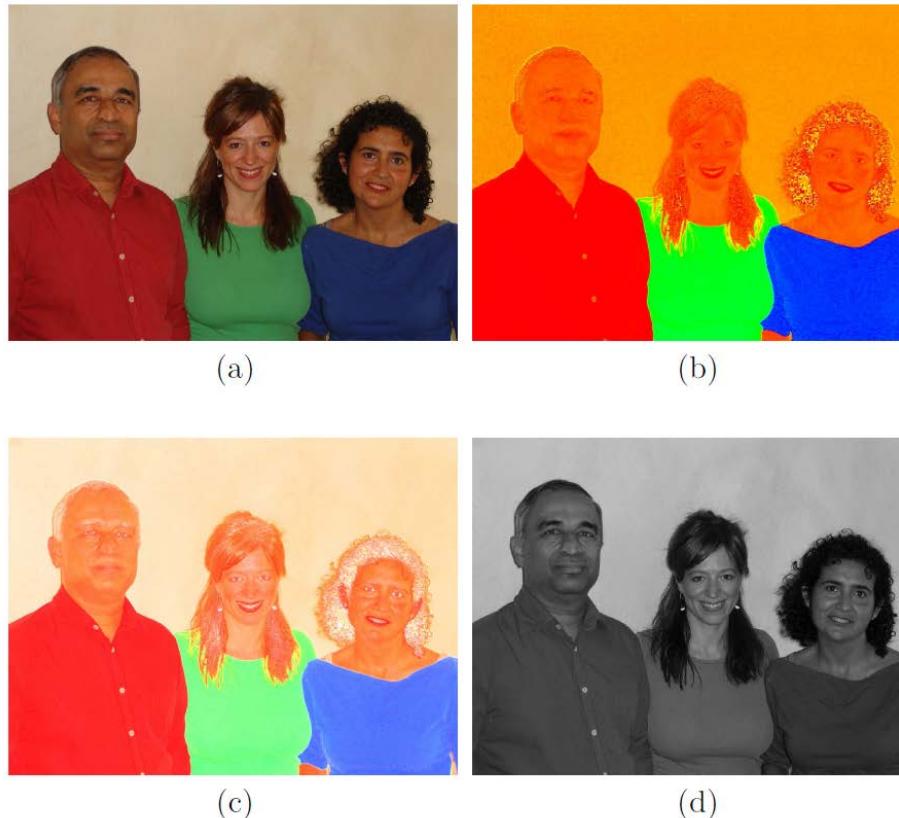
*Original image*



*Hue-saturation histogram*



# HSI: Roles of Hue Saturation and Intensity



**Figure 1.37** (a) An original color image. (b) Hue component with maximum saturation and intensity. (c) Isointensity rendition with the original hue and saturation, but intensity equal to unity for the entire image. This image gives the chrominance information. (d) Intensity component; this gives the luminance information. See also Figures 1.18 and 1.34.



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# Chromatic vs Achromatic Pixels



(a)



(b)



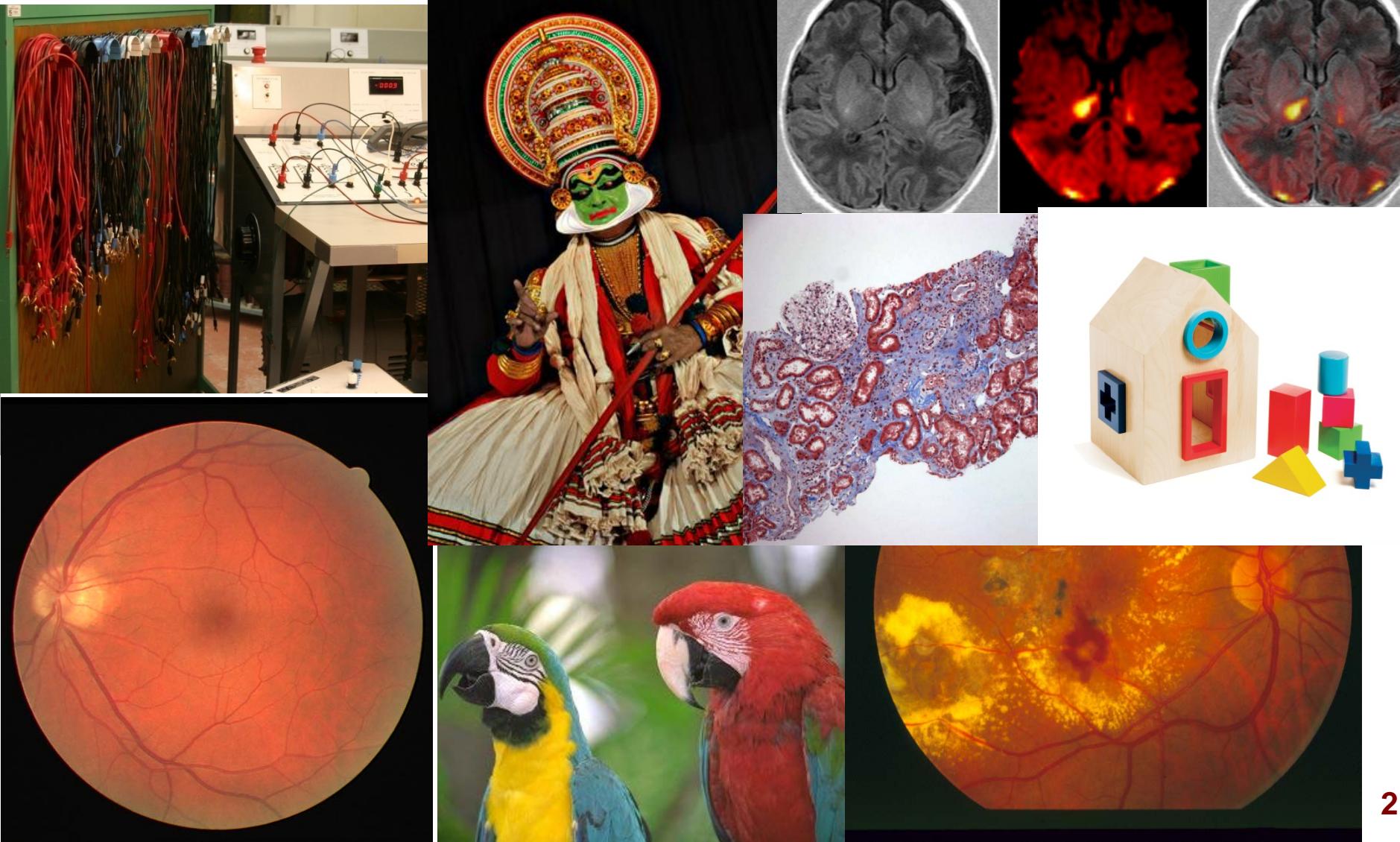
(c)



(d)

**Figure 1.39** (a) An original color image. (b) Dark or black achromatic pixels. (c) Bright or white achromatic pixels. (d) All achromatic pixels. In each case, pixels not selected have been assigned an arbitrary background color. See also Figure 1.36.

# Natural versus Pseudo Color





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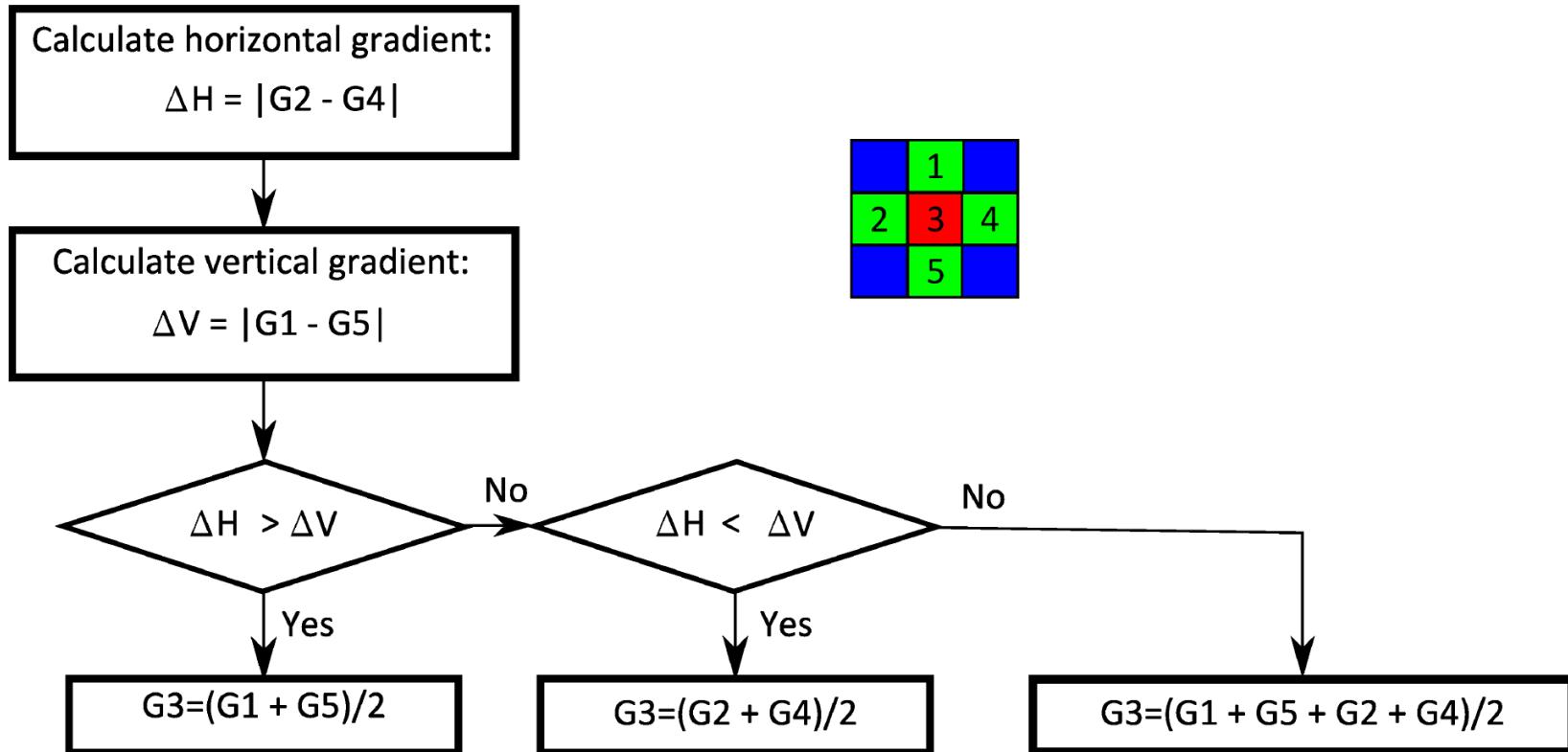
# Acquisition of Color Images



1. Sensor color filter array data
2. Dark current correction
3. White balance
4. Demosaicking
5. Color transformation to unrendered color space
6. Color transformation to rendered color space



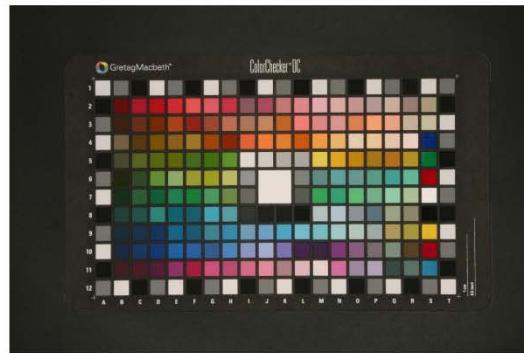
# Demosaicking by Interpolation



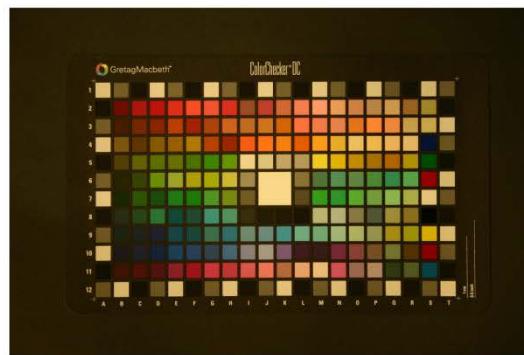
**Figure 2.4** Edge-directed interpolation: the green value of the central pixel labeled with the number 3 is interpolated from the green components of its four neighbors.  $G_n$  represents the green component of pixel  $n$  [169].



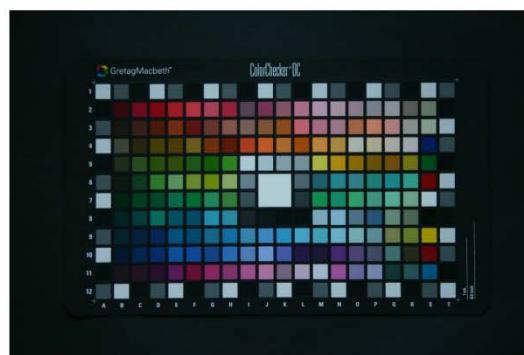
# The Need for Calibration of Color Images



(a)



(b)



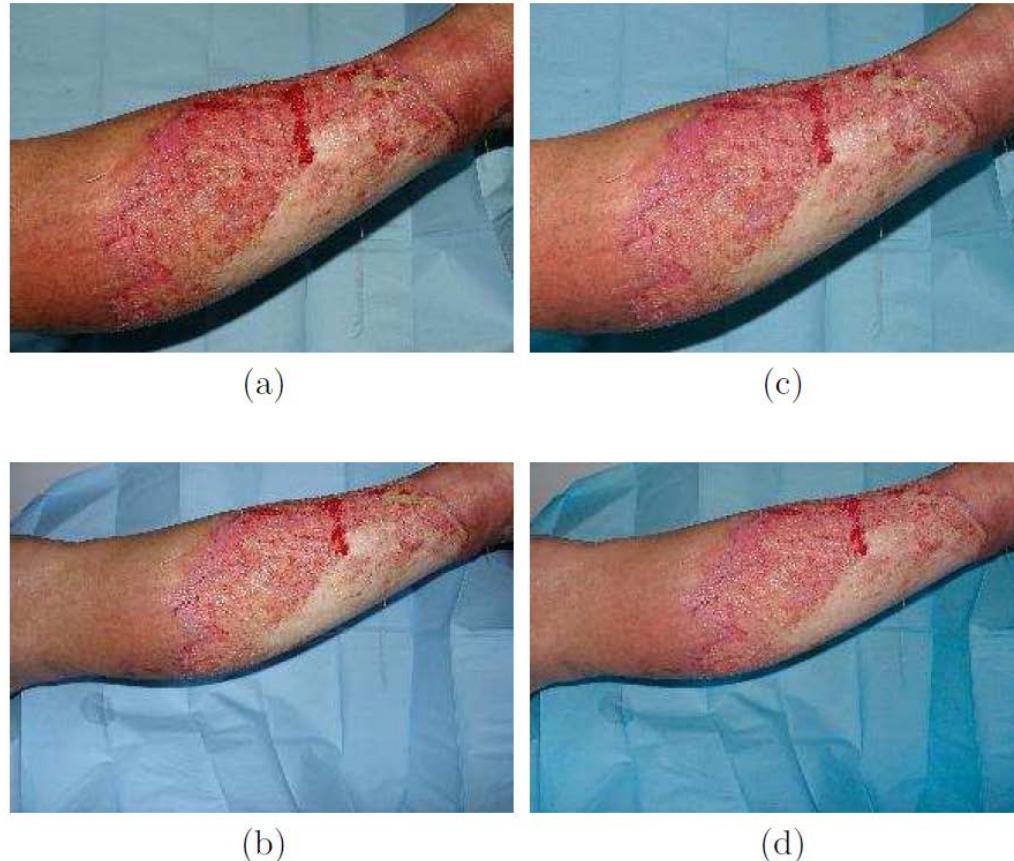
(c)

**Figure 2.34** Three images of the Macbeth Color Checker® chart DC (Gretag-Macbeth GmbH, Martinsried, Germany) obtained under different lighting conditions: (a) xenon flash, (b) fluorescent light, and (c) diffuse sunlight.



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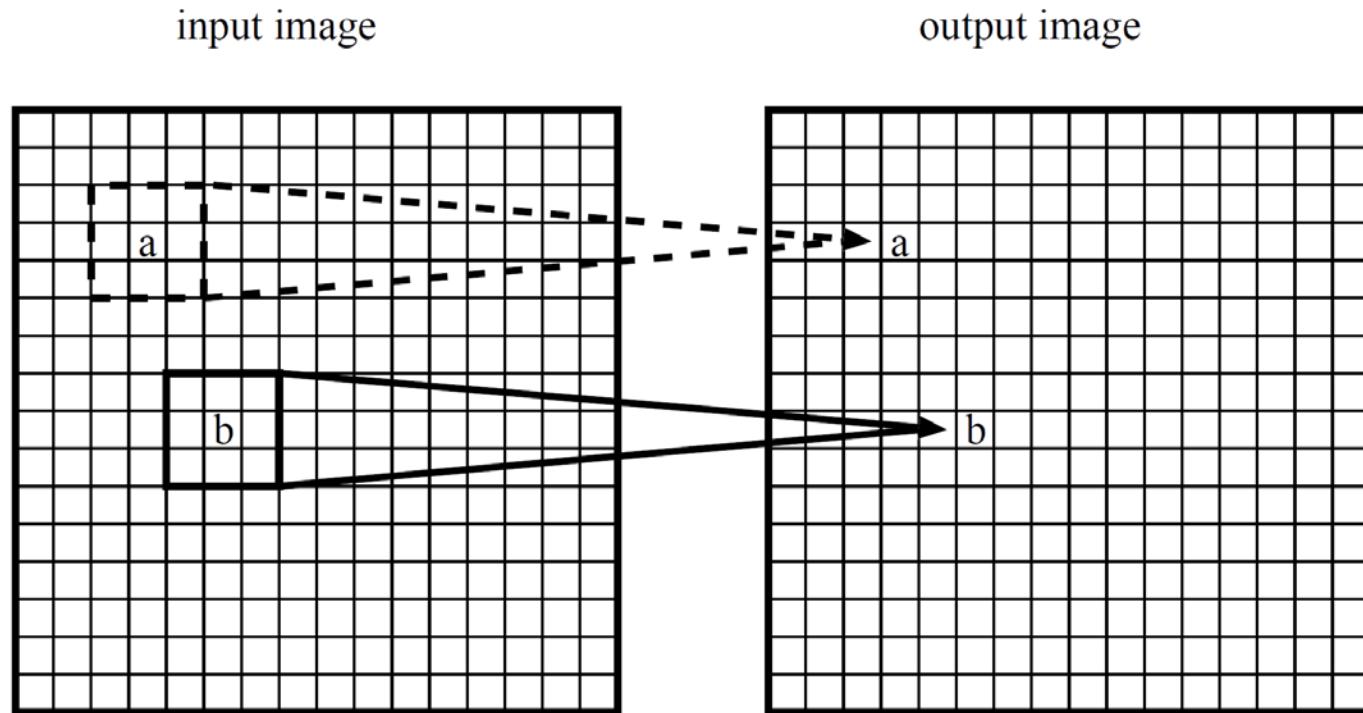
# Color Characterization



**Figure 2.36** Original digital photographic images of a burn wound taken using a xenon flash with (a) a Canon camera and (b) a Sony camera. (c)-(d) Characterized versions of the images in (a) and (b), respectively.



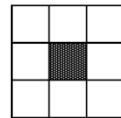
# Filtering to Remove Noise



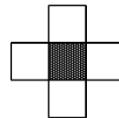
**Figure 3.1** Moving-window or moving-average filtering of an image. The size of the moving window in the illustration is  $3 \times 3$  pixels. Statistical measures or other values computed by using the pixels within the window in the input image are used to derive the output value. The moving window is shown for two pixel locations marked “a” and “b.”



# Neighborhood Shapes



(a) 3x3 square  
(8-connected)



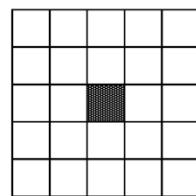
(b) 4-connected  
or integer  
distance 1



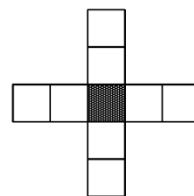
(c) 3x1 bar



(d) 1x3 bar



(e) 5x5 square



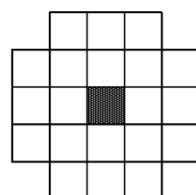
(f) cross



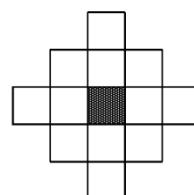
(g) 5x1 bar



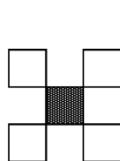
(h) 1x5 bar



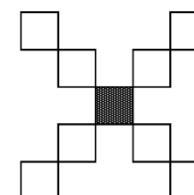
(i) circle



(j) integer  
distance 2



(k) X-1



(l) X-2



# Mean and Median Filtering



102	72	48
83	115	76 .
90	143	87

The rank-ordered pixels, arranged in increasing order, are as follows:

48 72 76 83 **87** 90 102 115 143.

$$(102 + 72 + 48 + 83 + 115 + 76 + 90 + 143 + 87)/9 = 90.67.$$

*Mean = 90.67*

*Median = 87*



# Ordering of Vectorial Data

*RGB pixel values in a 3x3 neighborhood of a color image:*

[252 170 146]	[200 80 57]	[247 158 119]
[226 138 86]	<span style="border: 2px solid red; padding: 2px;">[244 77 180]</span>	[235 155 78]
[224 116 82]	[203 96 75]	[236 114 100].



# Marginal Median: sort by R, G, B

[200	77	57]	
[203	80	75]	
[224	96	78]	
[226	114	82]	
[235	116	86]	: Median : MMF
[236	138	100]	
[244	155	119]	
[247	158	146]	
[252	170	180].	



# Reduced Ordering: Euclidean distance to mean

$$d_i^2 = (\mathbf{x}_i - \bar{\mathbf{x}})^T (\mathbf{x}_i - \bar{\mathbf{x}}) = \sum_{j=1}^P [\mathbf{x}_i(j) - \bar{\mathbf{x}}(j)]^2$$

[236 114 100] : 11 : Median : RDM

[224 116 82] : 22

[226 138 86] : 23

[235 155 78] : 41

[247 158 119] : 43

[203 96 75] : 47

[252 170 146] : 68

[200 80 57] : 69

[244 77 180] : 91.

$$\bar{\mathbf{x}}(j) = \frac{1}{K} \sum_{i=1}^K \mathbf{x}_i(j)$$

$$= [229.7 \ 122.7 \ 102.6]$$



# Vector Median and Vector Directional Filters

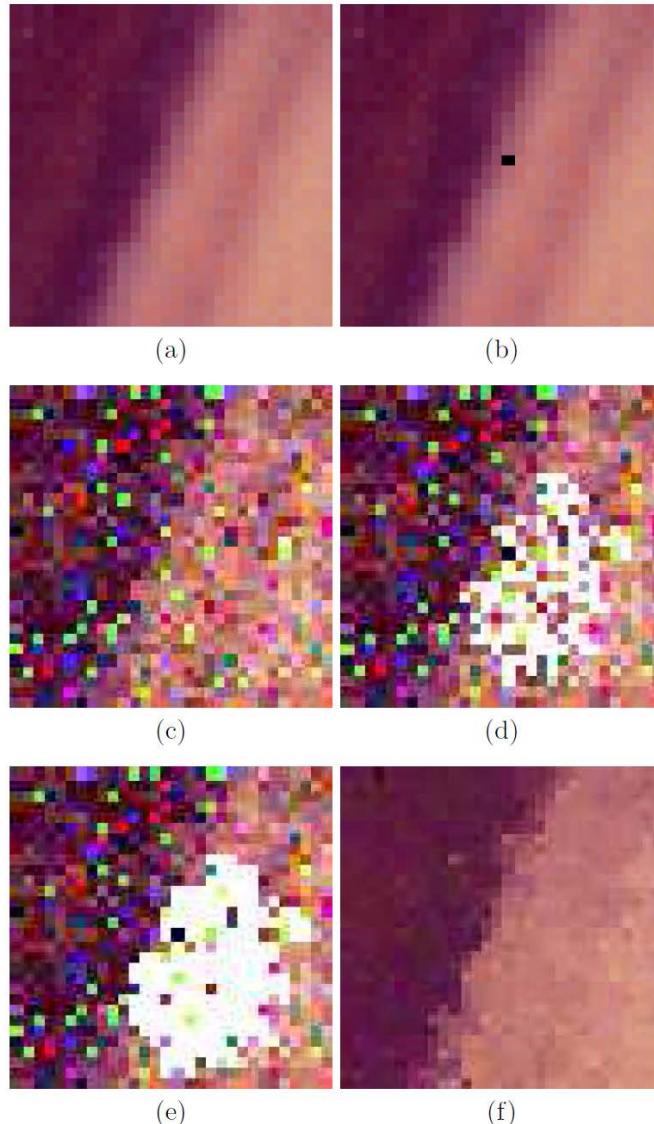
$$d_i = \sum_{k=1}^K d(\mathbf{x}_i, \mathbf{x}_k) \quad \text{sum of distances from each vector to all other vectors}$$

$$d(\mathbf{x}_i, \mathbf{x}_k) = \left[ \sum_{j=1}^P [\mathbf{x}_i(j) - \mathbf{x}_k(j)]^2 \right]^{\frac{1}{2}}$$

$$d_\theta(\mathbf{x}_i, \mathbf{x}_k) = \cos^{-1} \left[ \frac{\mathbf{x}_i^T \mathbf{x}_k}{\|\mathbf{x}_i\| \|\mathbf{x}_k\|} \right]$$



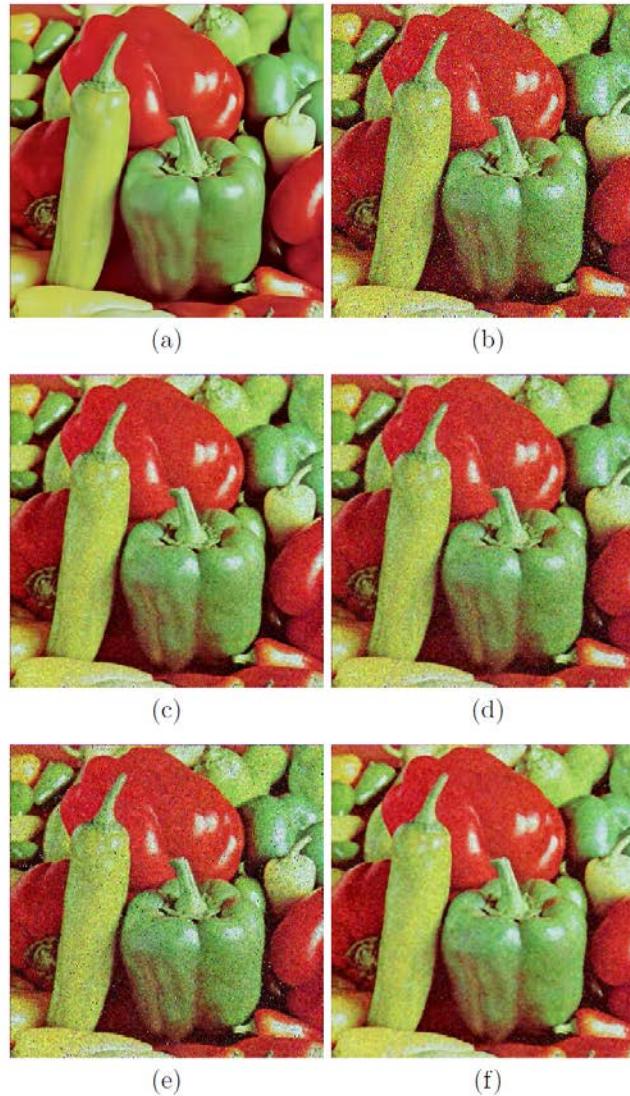
# Filtering using statistics derived using adaptive neighborhoods



**Figure 3.8** Illustration of the steps of adaptive-neighborhood region growing: (a) A  $30 \times 30$ -pixel wide portion of the “Lena” image. (b) Seed pixel shown in black. (c) The corresponding portion of a noisy image with additive Gaussian noise ( $\sigma_\eta = 30$ ) and 5% impulsive noise. (d) Region grown after the first step: seed pixel in black, retained pixels in white, background pixels in their true (noisy) colors. (e) Region after step two. (f) The same portion of the image after filtering.



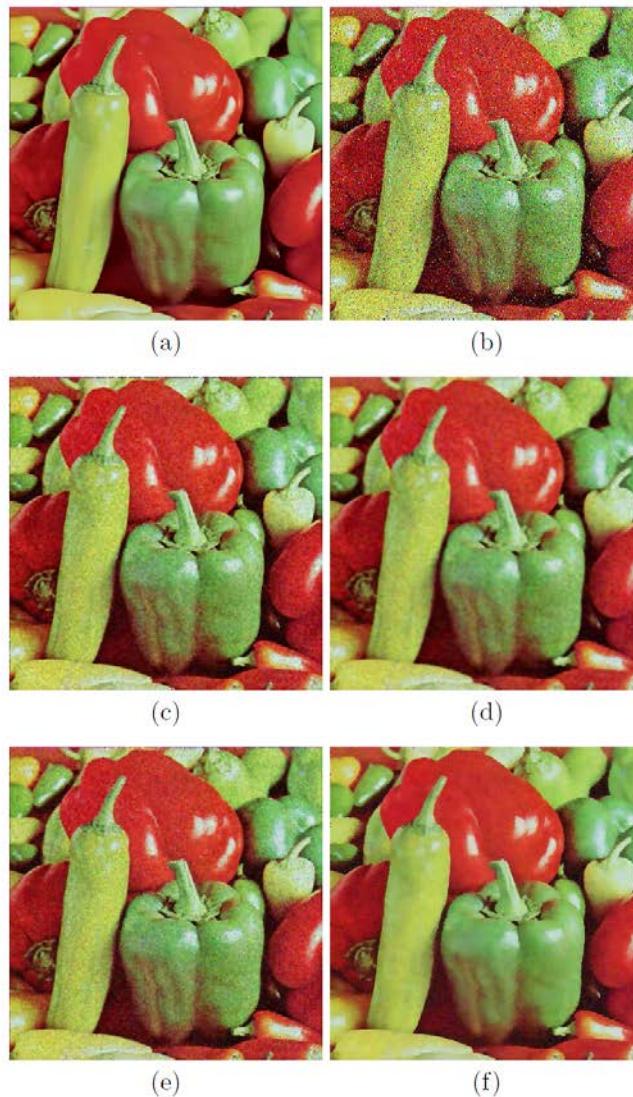
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**Figure 3.10** Original, noisy, and filtered versions of the  $512 \times 512$ -pixel, 24-bit “Peppers” image. (a) Original image. (b) Noisy image with Gaussian additive noise characterized by  $\sigma_n = 30$ ,  $\rho_{RG} = 0.5$ ,  $\rho_{GB} = 0.4$ , and  $\rho_{BR} = 0.2$ , and 5% impulsive noise. (c) Filtered with MMF. (d) Filtered with VMF. (e) Filtered with DDF. (f) Filtered with GVDF. Images courtesy of Dr. Mihai Ciuc, Laboratorul de Analiza și Prelucrarea Imaginilor, Universitatea Politehnica București, Bucharest, Romania [295].



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**Figure 3.12** Original, noisy, and filtered versions of the  $512 \times 512$ -pixel, 24-bit “Peppers” image. (a) Original. (b) Noisy, with Gaussian additive noise characterized by  $\sigma_\eta = 30$ ,  $\rho_{RG} = 0.5$ ,  $\rho_{GB} = 0.4$ , and  $\rho_{BR} = 0.2$ , and 5% impulsive noise. (c) Filtered with DW-MTMF. (d) Filtered with AMNFG2. (e) Filtered with AHMF. (f) Filtered with ANF. Images courtesy of Dr. Mihai Ciuc, Laboratorul de Analiza și Prelucrarea Imaginilor, Universitatea Politehnica București, Bucharest, Romania [295].



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# Enhancement of Color Images



Quite often, the enhancement required would be only in the intensity component:

Gamma correction,

Histogram equalization.

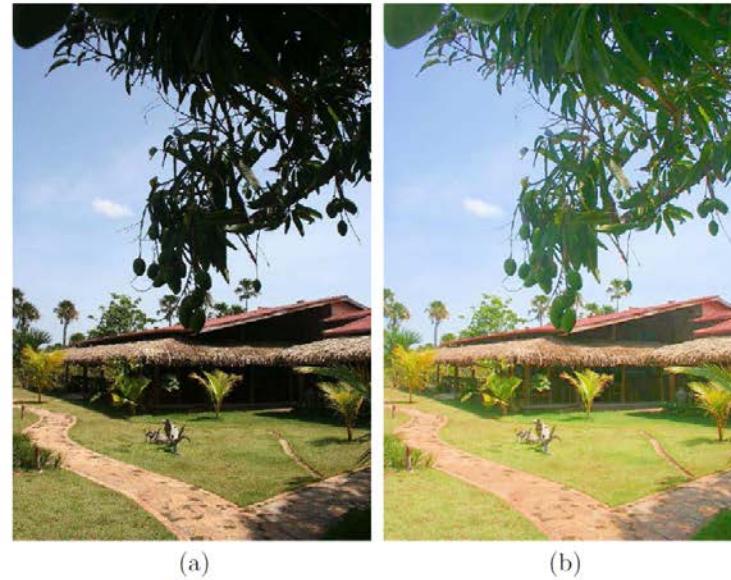
Sometimes, saturation may need to be increased.

Rarely would we want to alter the hue component.

Processing the RGB components individually is not usually recommended.



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(a)

(b)

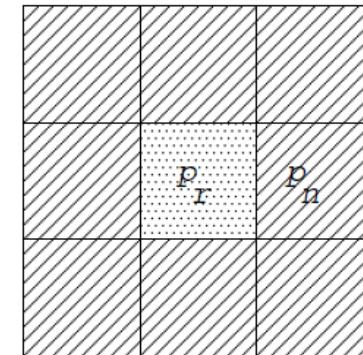
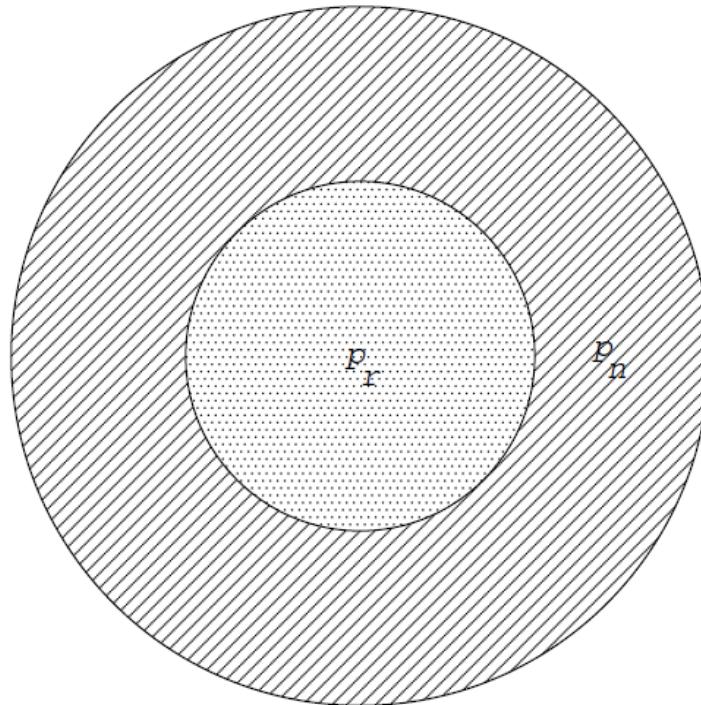
(c)

(d)

**Figure 4.4** Results of gamma correction applied to the components of a color image: (a) Original image. (b) Intensity enhanced with  $\gamma = 0.4$ . (c) Intensity and saturation enhanced with  $\gamma = 0.4$ . (d) All three *RGB* components enhanced individually with  $\gamma = 0.4$ .



# Enhancement of Contrast in Luminance and Color



$$c_{g1} = \frac{p_r - p_n}{p_n}$$

$$c_{g2} = \frac{p_r - p_n}{p_r + p_n}$$



# Enhancement of Contrast in Luminance and Color



$$c_L(m, n) = \frac{|L(m, n) - L_m|}{\Delta L_{\max}}$$

$$CD = [(L_1^* - L_2^*)^2 + (a_1^* - a_2^*)^2 + (b_1^* - b_2^*)^2]^{\frac{1}{2}}$$

$$cc(m, n) = \frac{CD_m}{CD_{\max}}$$

*m: mean over 5x5 region*  
*max: max over image*



# Enhancement of Contrast in Luminance and Color

$$c_E(m, n) = g_L(m, n) c_L(m, n) + g_C(m, n) c_C(m, n)$$

$$g_L(m, n) = \frac{\Delta c(m, n) - \Delta c_{\min}}{\Delta c_{\max} - \Delta c_{\min}}$$

$$g_C(m, n) = \frac{\Delta c_{\max} - \Delta c(m, n)}{\Delta c_{\max} - \Delta c_{\min}}$$

$$\Delta c(m, n) = c_L(m, n) - c_C(m, n)$$



# Enhancement of Contrast in Luminance and Color

$$L_E(m, n) = \begin{cases} L_m + c_E(m, n) \Delta L_{\max}, & \text{if } L(m, n) > L_m \\ L_m - c_E(m, n) \Delta L_{\max}, & \text{otherwise.} \end{cases}$$

$$k(m, n) = \frac{L_E(m, n)}{L(m, n)}$$

$$R_E(m, n) = k(m, n) R(m, n)$$

*Green and Blue channels also scaled as above [Liu & Yan]*



(a)



(b)



(c)

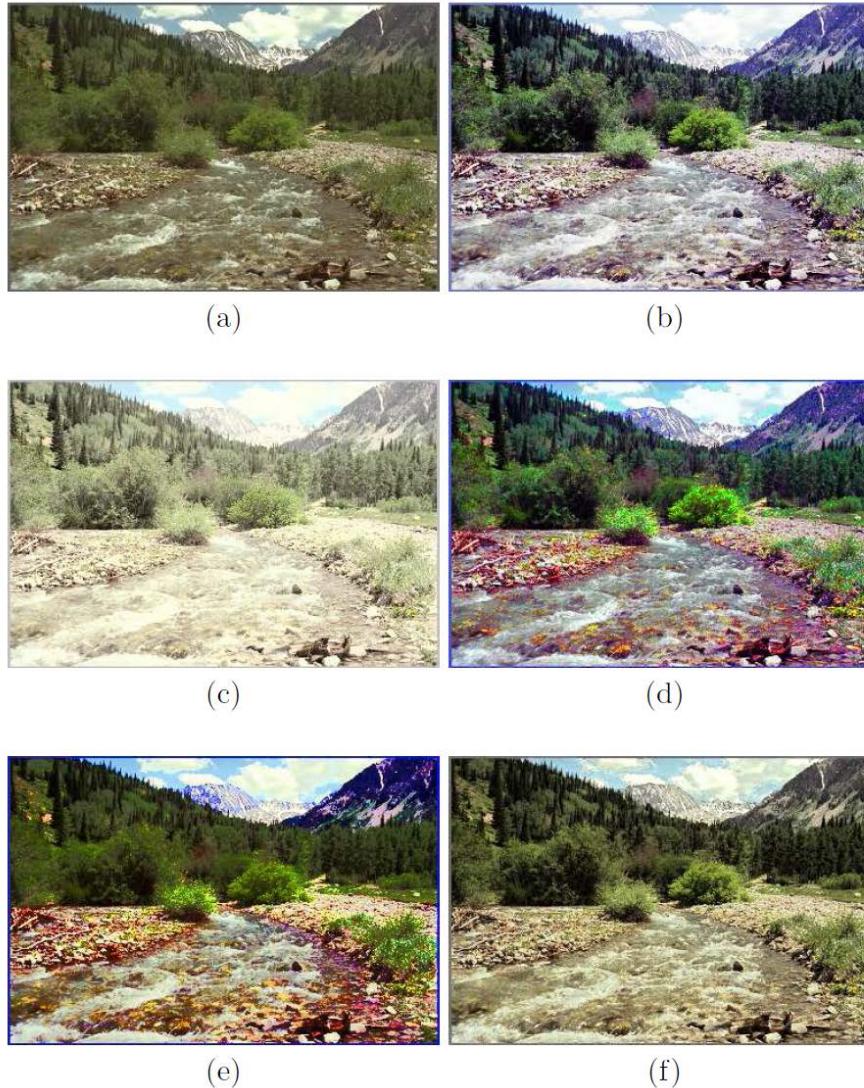


(d)

**Figure 4.20** Combined enhancement of luminance contrast and color contrast:  
(a) Original image. (b) Pictorial rendition of luminance contrast values. (c) Pictorial  
rendition of color contrast values. (d) Enhanced image.



## Color Histogram Equalization

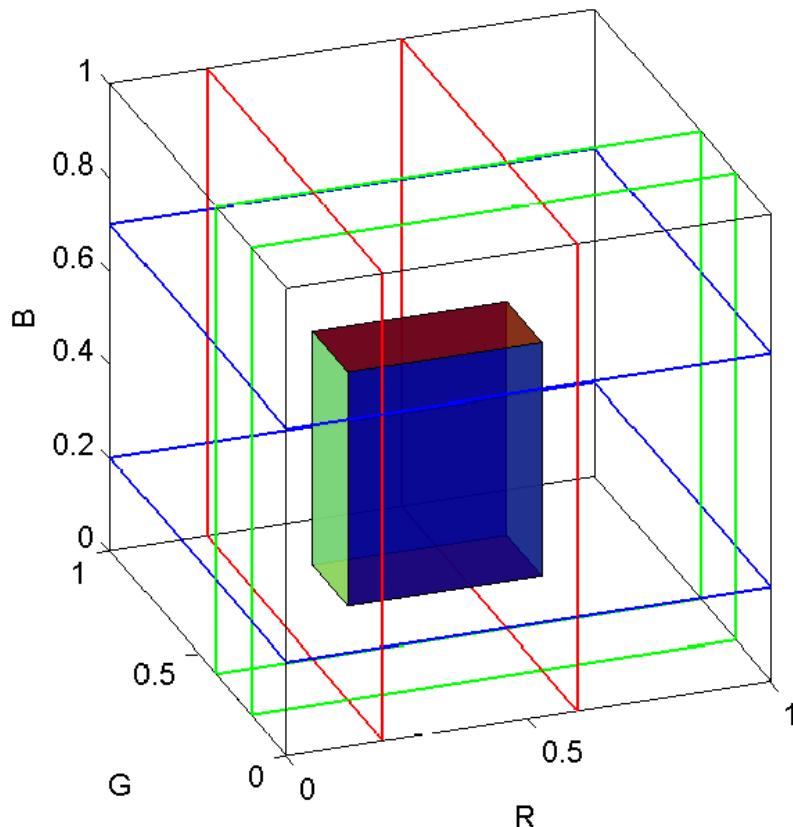


**Figure 4.31** Results of histogram equalization: (a) The original  $256 \times 384$ -pixel “13” image from the ftp site [ipl.rpi.edu](http://ipl.rpi.edu). (b) The image after histogram equalization of each channel independently. (c) Result of 3D histogram equalization. (d) Result of histogram decimation. (e) Result of histogram explosion. (f) Result of ANHE with  $N_{\max} = 100$ ,  $N_{\min} = 20$ ,  $T = 20$ , and  $\kappa = 3$ . Reproduced with permission from Buzuloiu et al. [325].

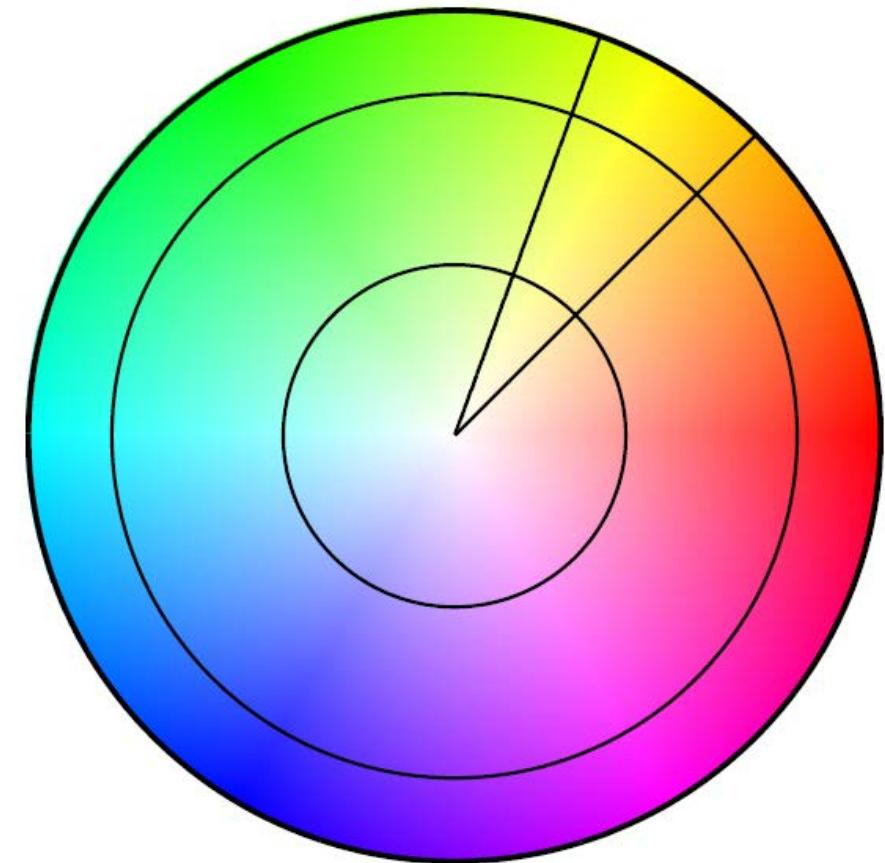


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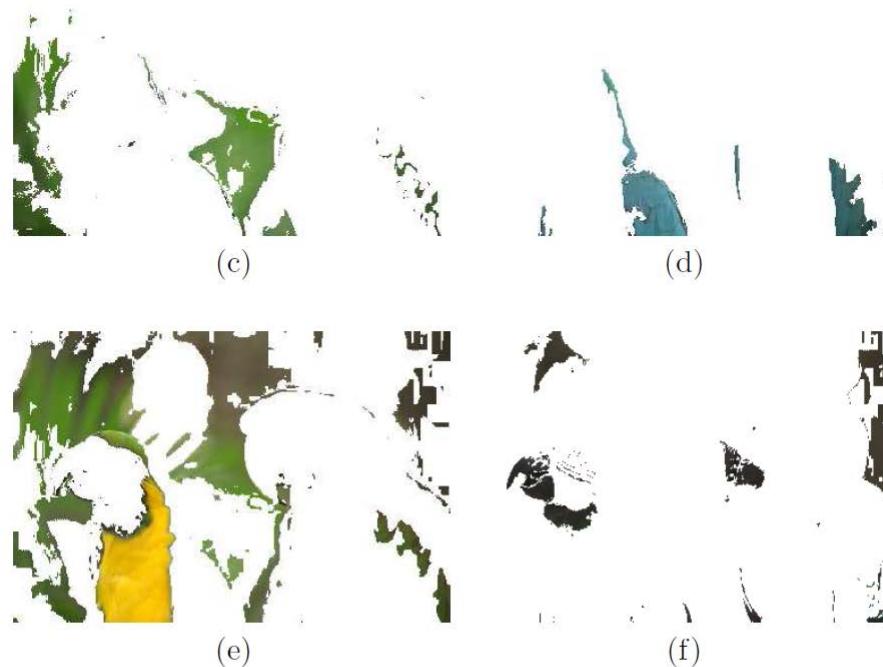
# Segmentation of Color Images



*Selecting ranges in RGB*



*Selecting ranges in HSI*



**Figure 5.6** (a) Original color image. Segmentation based upon hue angle and saturation: (b) segmented red component; (c) segmented green component; (d) segmented cyan component; (e) segmented yellow component; (f) segmented black component. The segmented blue and magenta components were nearly empty. See also Figures 1.36 and 1.43.

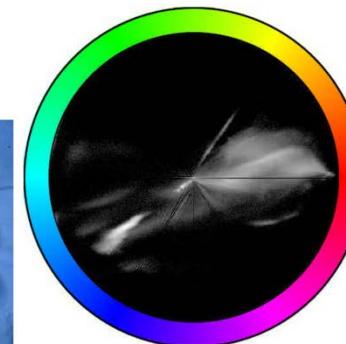


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# Segmentation of Images of Skin Ulcers



*Original image*



*Hue-saturation  
histogram*

*Red (granulation)*

$S > 0.4$  and  
 $H$   $300^\circ$  to  $0$  to  $30^\circ$



*Yellow (fibrin)*

$S > 0.2$  and  
 $H$   $30^\circ$  to  $90^\circ$

*Black (necrotic scar)*

$S < 0.2$  and  
 $I < 0.25 * \text{max}$



*Ulcer regions*



# Segmentation: *k*-means Algorithm

$X = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$  *color pixel dataset*

$\mathbf{x}_h \in \mathcal{R}^3$

$V = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$  *code book of centroids*

$\pi_i = \left\{ \mathbf{x} \in X \mid i = \arg \left[ \min_j \|\mathbf{x} - \mathbf{v}_j\|^2 \right] \right\}$

*set of pixels corresponding to  $v_i$  : for which  $v_i$  is nearest*



# Segmentation: $k$ -means Algorithm

Starting from the finite dataset  $X$ , iteratively move the  $k$  code vectors so as to minimize an error measure and recalculate the sets.

$$E(X) = \frac{1}{2n} \sum_{i=1}^k \sum_{\mathbf{x} \in \pi_i} \|\mathbf{x} - \mathbf{v}_i\|$$

$$\mathbf{v}_i = \frac{1}{|\pi_i|} \sum_{\mathbf{x} \in \pi_i} \mathbf{x}$$



(a)



(b)



(c)

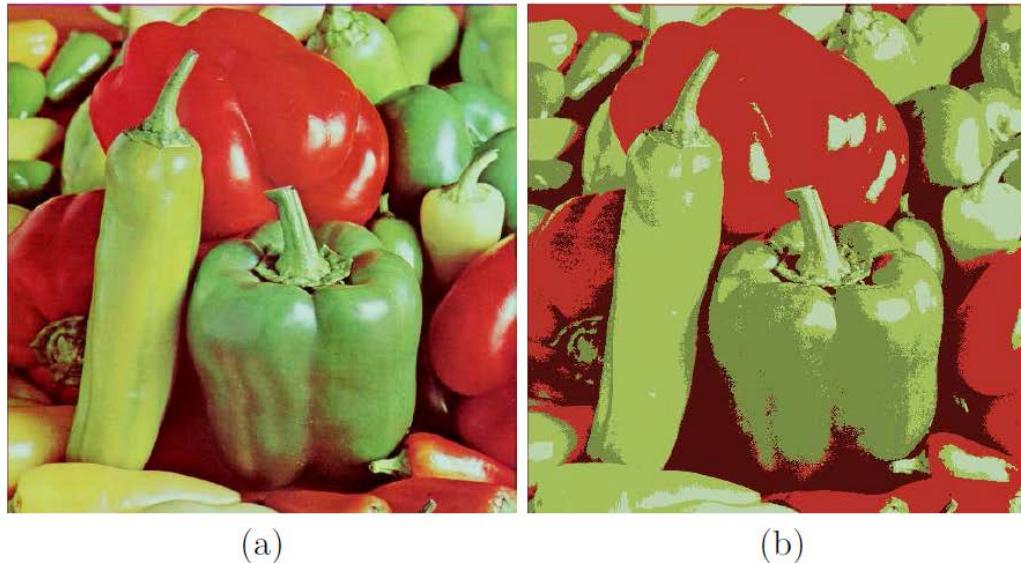


(d)

**Figure 5.7** (a) Original color image. Results of segmentation using the  $k$ -means clustering algorithm in three different color spaces: (b)  $sRGB$ , (c)  $HSV$ , and (d)  $L^*a^*b^*$ . In each case, the image has been segmented into six regions. The color assigned to each region is the final centroid of the color values in the corresponding region in the original image after application of the  $k$ -means algorithm.



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(a)



(b)



(c)



(d)

**Figure 5.8** (a) Original color image. Results of segmentation by application of the  $k$ -means algorithm in three different color spaces: (b)  $sRGB$ , (c)  $HSV$ , and (d)  $L^*a^*b^*$ .



# Color Deconvolution in Histopathology Images

$$\mathbf{P} = \begin{bmatrix} R & G & B \\ 0.18 & 0.20 & 0.08 \\ 0.01 & 0.13 & 0.01 \\ 0.10 & 0.21 & 0.29 \end{bmatrix} \quad \begin{array}{l} \leftarrow \text{hematoxylin} \\ \leftarrow \text{eosin} \\ \leftarrow \text{DAB.} \end{array}$$

$$m_{ij} = \frac{p_{ij}}{\left[ \sum_{j=1}^3 p_{ij}^2 \right]^{\frac{1}{2}}}$$

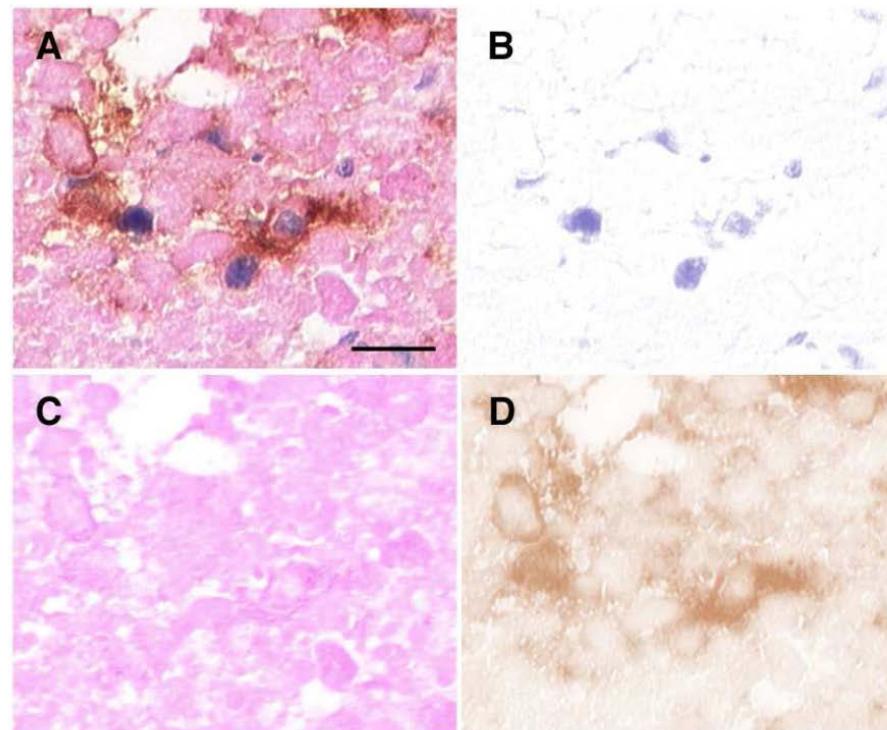
$$\mathbf{y} = \mathbf{CM}$$

$$\mathbf{C} = \mathbf{yM}^{-1}$$



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# Color Separation in Histopathology Images



**Figure 5.44** A. Breast biopsy specimen stained with a combination of hematoxylin (blue), eosin (magenta), and DAB (brown). The length of the bar in the image represents 20  $\mu\text{m}$ . The results of color separation or deconvolution: B. hematoxylin, C. eosin, and D. DAB. Reproduced with permission from Ruifrok AC and Johnston DA. Quantification of histochemical staining by color deconvolution. *Analytical and Quantitative Cytology and Histology*, 23:291–299, 2001. ©AQCH.

# Additional Topics

Edge detection in color

Region growing in color

Morphological image processing in color

Hyperspectral image processing

Analysis of texture in color

Coding and data compression of multispectral data

Analysis of burn wounds

Analysis of skin ulcers

Teledermatology

Telepathology

Aerial photogrammetry...



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# Thank You!



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