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Major factors in language evolution

- Efficient information transfer
- Learnability

Past research

Cognitive learning biases effect explanatory perturbations in language transmission (cf. Kirby et al 2007;2014)

But

We expect class of relevant transmission perturbations to be larger

(Iterated) Bayesian Learning

Learners consider the posterior probability of T given a data sequence d of (s, m) pairs

$$P(\tau \mid d) \propto P(\tau)$$
 $P(d \mid \tau)$

prior $\Pi_{\langle s,m \rangle \in d} P(m \mid s, \tau)$

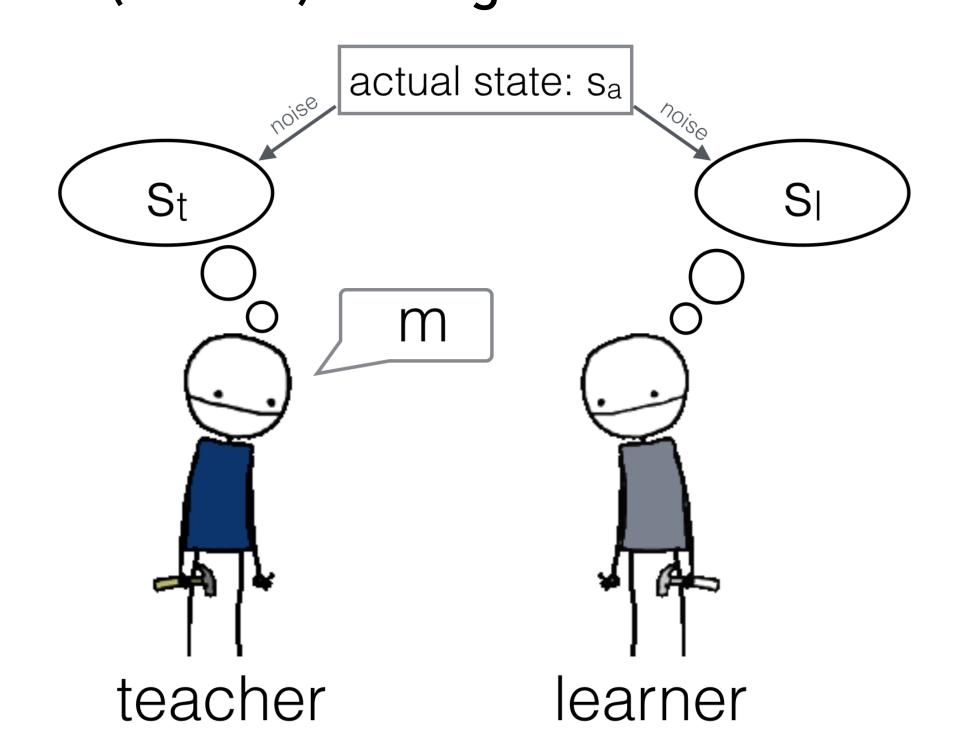
With a parametrized posterior:

$$F(\tau \mid d) \propto P(\tau \mid d)^l, \quad l \geq 1$$

The probability that a learner acquires type j when learning from type i is then:

$$P(\tau_j \to \tau_i) \propto \sum_{d \in D_k} P(d \mid \tau_j) F(\tau_i \mid d)$$

(Iterated) learning with state-noise



The probability that S_a is the actual state when the learner observes s₁ is

$$P_N(s_a \mid s_l) \propto P(s_a) P_N(s_l \mid s_a)$$

The probability that the teacher observes S_t when the learner observes S₁ is

$$P_N(s_t \mid s_l) = \sum_{s_a} P(s_a \mid s_l) P_N(s_t \mid s_a)$$

The probability that type t produces a perceived sequence d_l is

$$P_N(d_l \mid au) = \prod_{\langle s_l, m \rangle \in d_l} \sum_{s_t} P_N(s_t \mid s_l) P(m \mid s_t, au)$$

The probability that a learner acquires type j when learning from type i is then:

$$P_N(\tau_j \to \tau_i) \propto \sum_{d \in D_k} P_N(d_l \mid \tau_j) F(\tau_i \mid d)$$

Case study I: Vagueness

- Two messages; hundred states
- Probability of perception of actual state as perceived state:

$$P_N(\cdot \mid s_a) \sim N(s_a, \sigma, 0, 99)$$

- Types:
 - $\tau \in [0;99]$
- Linguistic behavior:

$$P(m_1 | s, \tau) = \delta_{s>\tau} = (1 - P(m_2 | s, \tau))$$

Case study II: Meaning deflation

- One message; hundred states
- Noise signature, behavior, and type space as in case study I
- We assume learners to take absence of observations into account:

$$P(\tau|d_l) \propto \text{Binom}(\text{successes} = k - |d_l|, \text{trials} = k,$$

$$\text{succ.prob} = \sum_{i=0}^{\tau-1} P(s=i) \prod_{s \in d_l} P(m|s,\tau)$$

Case study III: Scalar Expressions

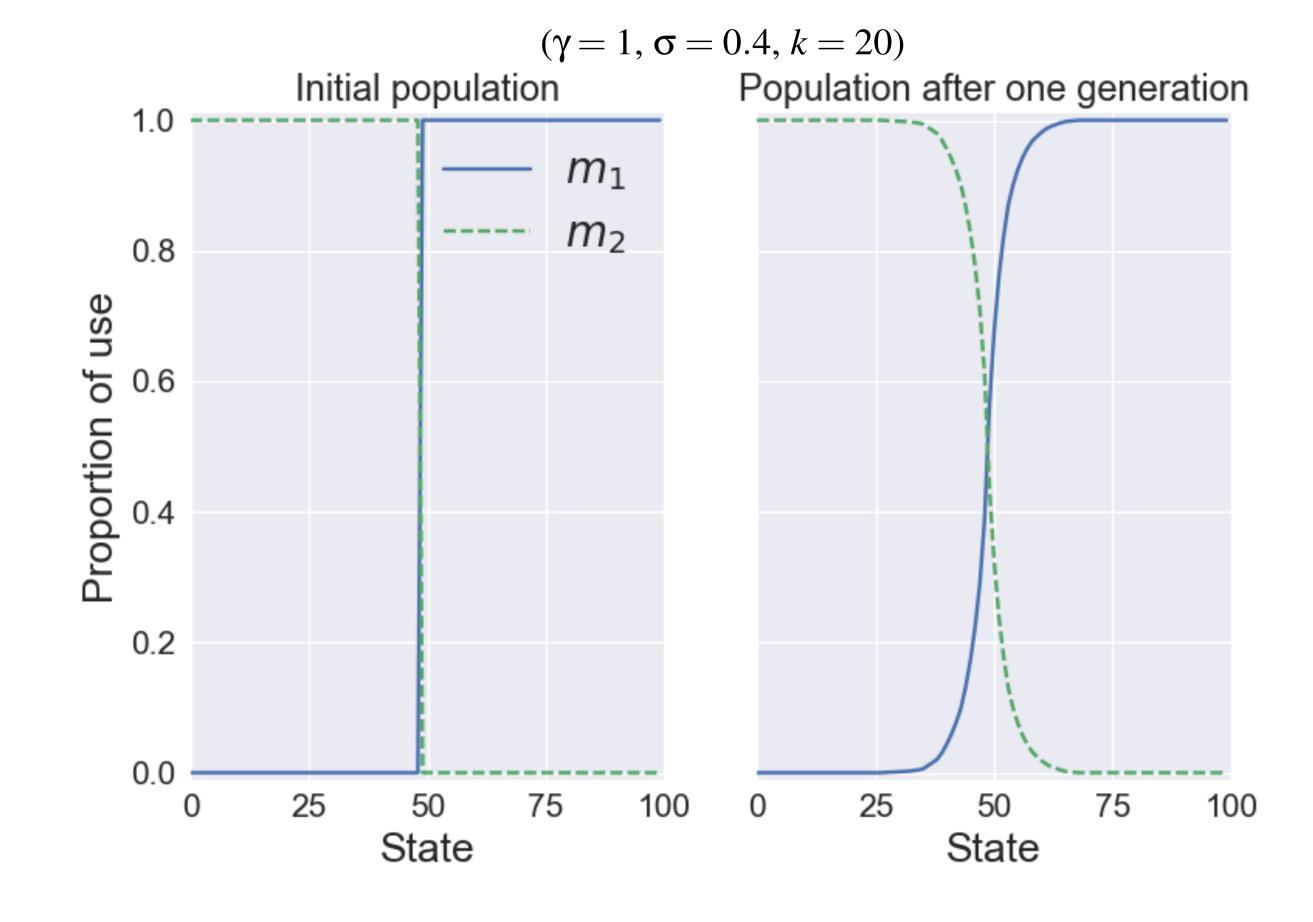
- Previous research:
- widespread adoption of non-upper bounded meaning in weak scalar expressions provided prior that favours them (Brochhagen et al. 2016)
- Target types:

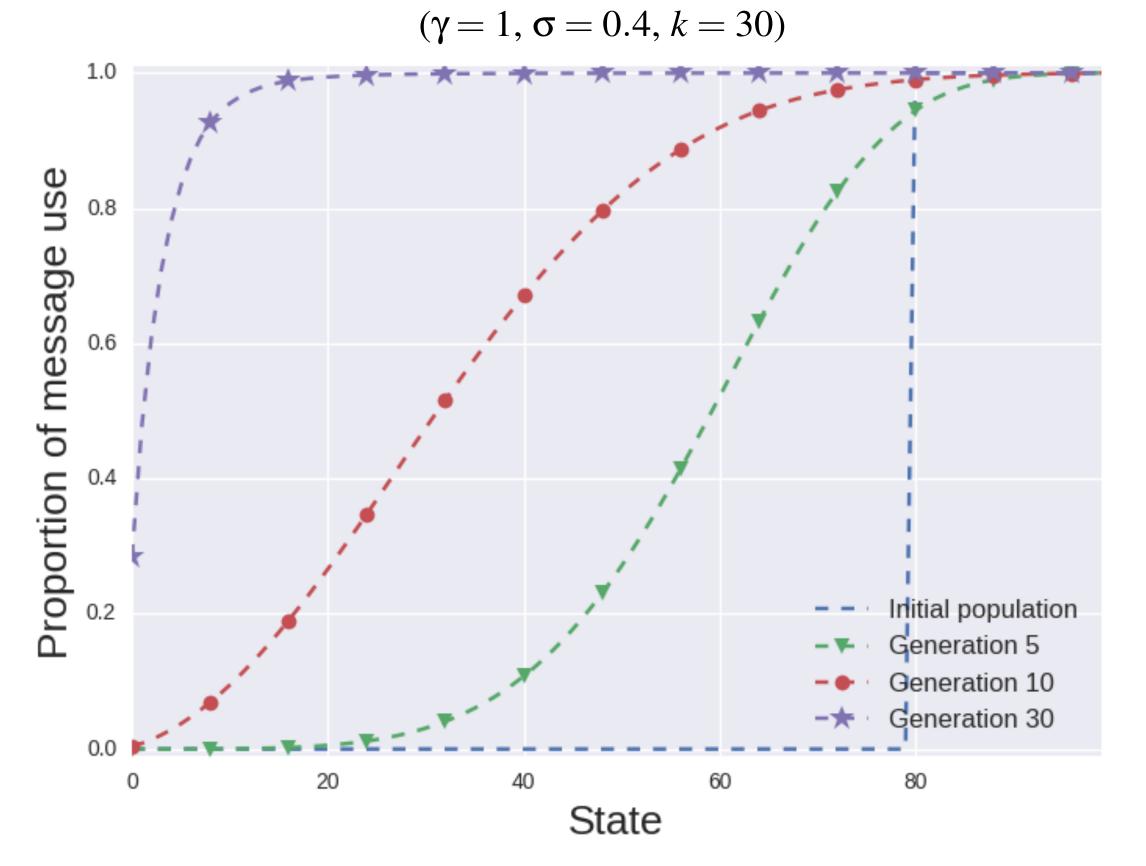
Linguistic behavior:

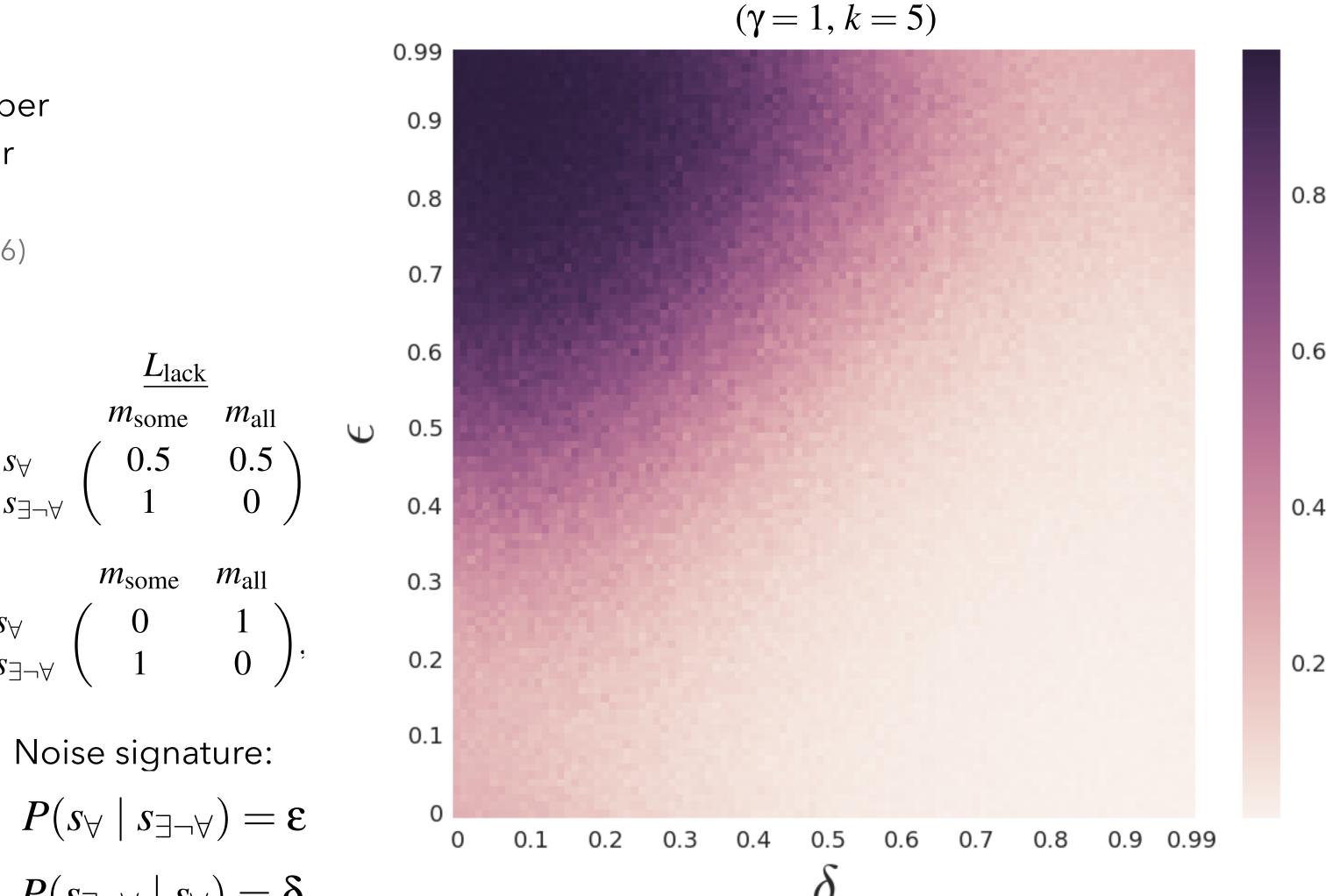
 $P(m \mid s, \tau = \langle lexicon, use \rangle)$

Noise signature:

 $P(s_{\exists \neg \forall} \mid s_{\forall}) = \delta$







Conclusions

- Systematic noise in agents' perception of world states can give rise to stochastic perturbations that may influence and explain language change
- Noisy perception may mimic effects of cognitive biases and offers a neutral alternative to the study of language evolution under functional competition or differential learnability (cf. Reali & Griffiths 2009)

References: Brochhagen et al. (2016) in Proceedings of CogSci • Kirby et al. (2007) in Proceedings of the National Academy of Sciences • Kirby et al. (2014) in Current Opinion in Neurobiology • Reali & Griffiths (2009) in Proceedings of the Royal Society B: Biological Sciences