Meeting N.1 (19/04 /2020)

Component present today = All

Due to government rules, not all the components of the team could meet in person. However, discussions on to-dos and different roles have been made via Discord. Todays meeting was the first one and the team started with the first tasks.

Juraška and Brodo were physically present and they worked on two different platforms.

Juraška focused on the L298N motor driver, with some difficulties because he tried to implement it not using simple functions such as digitalWrite and analogWrite.

On the other hand, Brodo only installed Ubuntu Mate and ROS on the RasPi.

Kochanek is now in charge of designing a chassis and a skeleton for the car which satisfy the requirements given by the professors.

Tuna has to research a functional water sensor for the raspberryPi. This sensor will be implemented in ROS.

Finally, Konevski will be in charge of developing a working steering system that works both on road and on water. Suggestion by the team have been discussed by the two team members and will be given to Konevski in the next meeting.

Trello has been already updated. The team decided to go with Discord instead of Slack since the all team can see updates in real time without the need to visit any website.

Today’s meeting was not as successful as the team wanted to be. unfortunately , not all the tasks have been completed. The tasks were decided for a three members meeting. However, that’s not a problem since there will be a meeting tomorrow after the lectures.