# HW2

### February 8, 2023

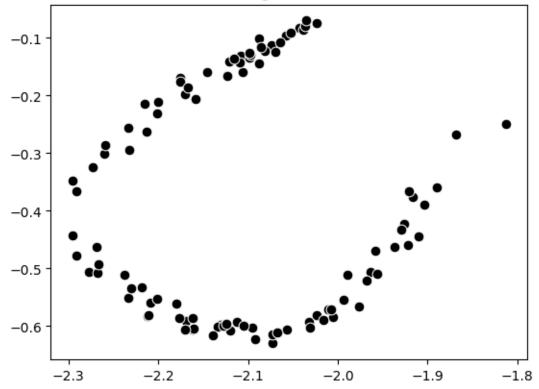
```
[]: import autograd.numpy as np from autograd.misc.flatten import flatten_func from autograd import grad import matplotlib.pyplot as plt
```

# 0.1 Problem 1 (13.4)

```
[]: # import data
X = np.loadtxt('universal_autoencoder_samples.csv', delimiter=',')

plt.scatter(X[0,:], X[1,:], c = 'k', s = 60, linewidth = 0.75, edgecolor = 'w')
plt.title("Original data")
plt.show()
```

## Original data

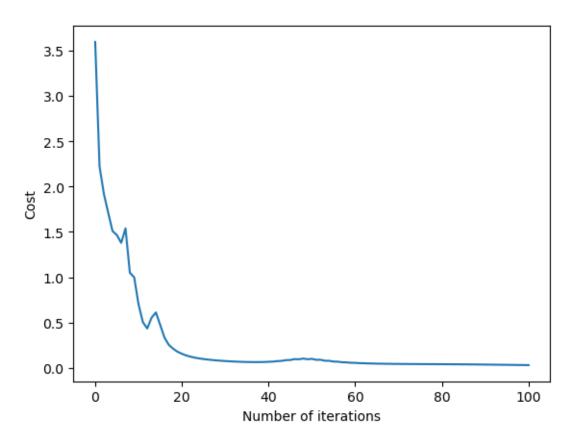


```
[]: x_mean = np.mean(X[0])
     x_std = np.std(X[0])
     y_{mean} = np.mean(X[1])
     y_std = np.std(X[1])
     X[0] = (X[0] - x_mean)/x_std
     X[1] = (X[1] - y_mean)/y_std
[]: activation = np.tanh
[]: def feature_transforms(a, w):
         for W in w:
             # compute inner-product with current layer weights
             a = W[0] + np.dot(a.T, W[1:])
             # pass through activation
             a = activation(a).T
         return a
[]: # neural network model
     def model(x, theta):
         # compute feature transformation
         f = feature_transforms(x, theta[0])
         # compute final linear combination
         a = theta[1][0] + np.dot(f.T, theta[1][1:])
         return a.T
[]: # create initial weights for a neural network model
     def network_initializer(layer_sizes, scale):
         # container for all tunable weights
         weights = []
         # create appropriately -sized initial weight matrix for each layer of \Box
      \rightarrownetwork
         for k in range(len(layer_sizes)-1):
             # get layer sizes for current weight matrix
             U_k = layer_sizes[k]
             U_k_plus_1 = layer_sizes[k+1]
```

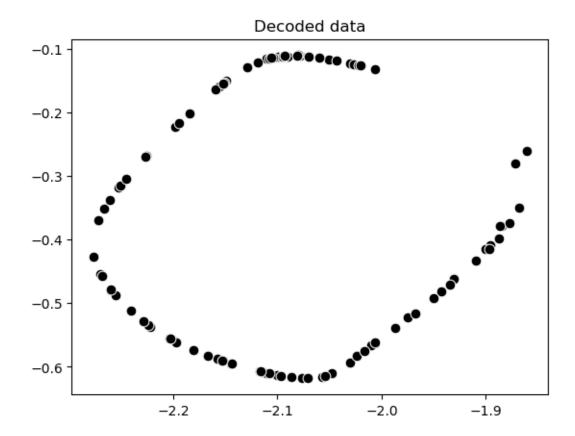
```
# make weight matrix
             weight = scale*np.random.randn(U_k+1, U_k_plus_1)
             weights.append(weight)
         # repackage weights so that theta_init[0] contains all
         # weight matrices internal to the network, and theta_init[1]
         # contains final linear combination weights
         theta_init = [weights[:-1], weights[-1]]
         return theta_init
[]: def least_squares_auto(w):
         w_e = w[0]
         w_d = w[1]
         decoded = model(model(X, w_e), w_d)
         return np.mean((decoded[0] - X[0])**2 + (decoded[1] - X[1])**2)
[]: def gradient_descent(g, alpha, max_its, w):
         weight_history = [w]
         cost_history = [g(w)]
         g_flat, unflatten, w = flatten_func(g, w)
         gradient = grad(g_flat)
         for k in range(max_its):
             grad_eval = gradient(w)
             w = w - alpha*grad_eval
             weight_history.append(unflatten(w))
             cost_history.append(g(unflatten(w)))
         return weight_history, cost_history
[]: layer_sizes = [2, 10, 10, 10, 2]
     theta_e = network_initializer(layer_sizes, .5)
     theta_d = network_initializer(layer_sizes, .5)
[]: alpha = 0.04
     num_iter = 100
     theta = [theta_e, theta_d]
     weight_history, cost_history = gradient_descent(least_squares_auto, alpha, u
      →num_iter, theta)
[]: plt.plot(cost_history)
     plt.xlabel("Number of iterations")
```

```
plt.ylabel("Cost")
```

### []: Text(0, 0.5, 'Cost')



```
decodedX = model(model(X, weight_history[num_iter][0]),
    weight_history[num_iter][1])
    decodedX[0] = (decodedX[0]*x_std) + x_mean
    decodedX[1] = (decodedX[1]*y_std) + y_mean
    plt.scatter(decodedX[0,:], decodedX[1,:], c = 'k', s = 60, linewidth = 0.75,
    edgecolor = 'w')
    plt.title("Decoded data")
    plt.show()
```



We can see from the scatterplot of the decoded data that our learned manifold closely resembles the original data

## 0.2 Problem 2 (13.8)

```
[]: # get MNIST data from online repository
    from sklearn.datasets import fetch_openml
    x, y = fetch_openml('mnist_784', version=1, return_X_y=True)

# convert string labels to integers
    y = np.array([int(v) for v in y])[:,np.newaxis]

print(np.shape(x))
    print(np.shape(y))

(70000, 784)
    (70000, 1)

[]: x = np.array(x.transpose())
    y = np.array(y.transpose())
    print(np.shape(x))
    print(np.shape(x))
```

```
(784, 70000)
    (1, 70000)
[]: selected_indices = np.random.choice(range(70000), size=50000, replace=False)
     x = x[:,selected_indices]
     y = y[:,selected_indices]
[]: print(np.shape(x))
     print(np.shape(y))
    (784, 50000)
    (1, 50000)
[]: def normalize(input):
         output = []
         for i in range(np.shape(input)[0]):
             if np.std(input[i]) != 0:
                 output.append((input[i] - np.mean(input[i]))/np.std(input[i]))
             else:
                 output.append(input[i] - np.mean(input[i]))
         return np.array(output)
[]: x = normalize(x)
[]: def activation(a):
         return np.maximum(0, a)
[]: layer_sizes = [784, 10, 10, 10, 10, 10]
     theta = network_initializer(layer_sizes, .1)
[]: def multi_softmax(w, indices):
         x_cur = x[:, indices]
         y_cur = y[:, indices]
         model_output = model(x_cur,w)
         return np.mean(np.log(np.sum(np.exp(model_output), axis=0)) - np.
      array([model output[int(y cur[0][i]), i] for i in range(len(y cur[0]))]))
[]: def gradient_descent_minibatch(g, alpha, max_its, w, batch_size):
         weight history = [w]
         cost_history = [g(w, range(np.shape(x)[1]))]
         g_flat, unflatten, w = flatten_func(g, w)
         gradient = grad(g_flat)
         for k in range(max_its):
             start_idx = 0
             while start_idx < np.shape(x)[1]:</pre>
```

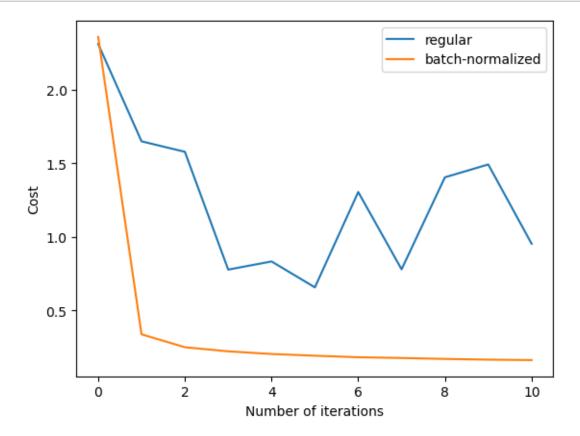
```
batch_inds = range(start_idx, start_idx+batch_size)
                 grad_eval = gradient(w, batch_inds)
                 w = w-alpha*grad_eval
                 start_idx += batch_size
             weight_history.append(unflatten(w))
             cost_history.append(g(unflatten(w), range(np.shape(x)[1])))
         return weight_history, cost_history
[]: alpha = 1
     num_iter = 10
     weight_history, cost_history = gradient_descent_minibatch(multi_softmax, alpha, __
      onum_iter, theta, 500)
[]: def feature_transforms2(a, w):
         for W in w:
             # compute inner-product with current layer weights
             a = W[0] + np.dot(a.T, W[1:])
             # pass through activation
             a = activation(a).T
             # normalize
             a = normalize(a)
         return a
[]: # neural network model
     def model2(x, theta):
         # compute feature transformation
         f = feature_transforms2(x, theta[0])
         # compute final linear combination
         a = theta[1][0] + np.dot(f.T, theta[1][1:])
         return a.T
[]: def multi_softmax2(w, indices):
         x_cur = x[:, indices]
         y_cur = y[:, indices]
         model_output = model2(x_cur,w)
```

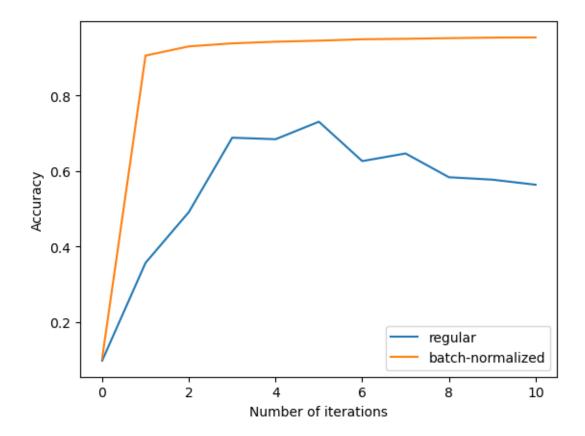
```
return np.mean(np.log(np.sum(np.exp(model_output), axis=0)) - np.

→array([model_output[int(y_cur[0][i]), i] for i in range(len(y_cur[0]))]))
```

```
[]: weight_history2, cost_history2 = gradient_descent_minibatch(multi_softmax2, ⊔ ⇔alpha, num_iter, theta, 500)
```

```
[]: plt.plot(cost_history, label="regular")
  plt.plot(cost_history2, label="batch-normalized")
  plt.xlabel("Number of iterations")
  plt.ylabel("Cost")
  plt.legend()
  plt.show()
```





The plots above look similar to the ones provided in the text

```
## Problem 3 (13.9)
```

```
[]: # load in dataset
    csvname = 'noisy_sin_sample.csv'
    data = np.loadtxt(csvname, delimiter = ',')
    x = data[:-1,:]
    y = data[-1:,:]
    print(np.shape(x))
    print(np.shape(y))

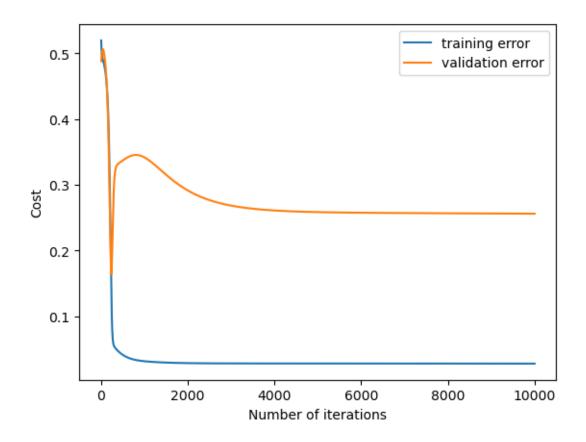
(1, 21)
    (1, 21)
(1, 21)

[]: x_mean = np.mean(x)
    x_std = np.std(x)
    x[0] = (x[0] - x_mean)/x_std

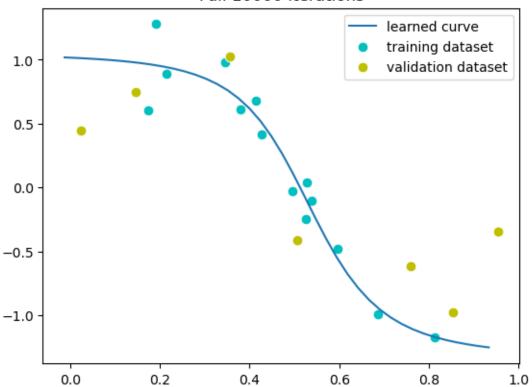
    x_orig = x
    y_orig = y
```

```
[]: train_indices = np.random.choice(range(21), size=14, replace=False)
     x_val = np.delete(x_orig, train_indices, axis=1)
     y_val = np.delete(y_orig, train_indices, axis=1)
     x = x_orig[:,train_indices]
     y = y_orig[:,train_indices]
     print(np.shape(x_orig))
     print(np.shape(y_orig))
     print(np.shape(x_val))
     print(np.shape(y_val))
     print(np.shape(x))
    print(np.shape(y))
    (1, 21)
    (1, 21)
    (1, 7)
    (1, 7)
    (1, 14)
    (1, 14)
[]: activation = np.tanh
[]: layer_sizes = [1, 10, 10, 10, 1]
     theta = network_initializer(layer_sizes, .1)
[]: def mse(w, x=x, y=y):
         model_output = model(x, w)
         return np.mean(np.square(y - model_output))
[]: def gradient_descent_val(g, alpha, max_its, w):
         weight_history = [w]
         cost_history = [g(w)]
         min_val_weights = w
         min_val_cost = g(w, x_val, y_val)
         min_val_iter = 0
         val_cost_history = [g(w, x_val, y_val)]
         g_flat, unflatten, w = flatten_func(g, w)
         gradient = grad(g_flat)
         for k in range(max_its):
             grad_eval = gradient(w)
             w = w - alpha*grad_eval
             weight_history.append(unflatten(w))
```

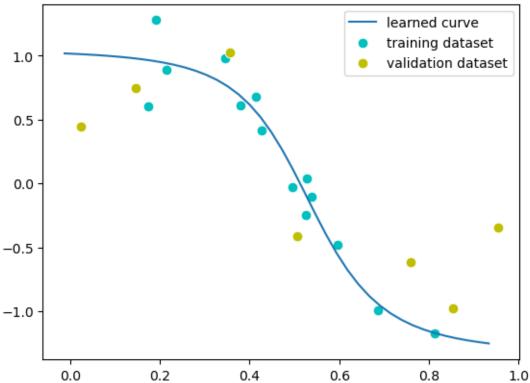
```
cost_history.append(g(unflatten(w)))
             cur_val_cost = g(unflatten(w), x_val, y_val)
             val_cost_history.append(cur_val_cost)
             if cur_val_cost < min_val_cost:</pre>
                 min_val_cost = cur_val_cost
                 min_val_weights = unflatten(w)
                 min_val_iter = k
         return weight_history, cost_history, min_val_weights, min_val_cost,_u
      →min_val_iter, val_cost_history
[]: alpha = .02
     num_iter = 10000
     weight_history, cost_history, min_val_weights, min_val_cost, min_val_iter, u
      aval_cost_history = gradient_descent_val(mse, alpha, num_iter, theta)
[]: print(min_val_iter)
    232
[]: plt.plot(cost_history, label="training error")
     plt.plot(val_cost_history, label="validation error")
    plt.legend()
     plt.xlabel("Number of iterations")
     plt.ylabel("Cost")
     plt.show()
```



#### Full 10000 iterations







The plots above look similar to the ones provided in the text

## 0.3 Problem 4 (13.10)

```
[]: # get MNIST data from online repository
    from sklearn.datasets import fetch_openml
    x, y = fetch_openml('mnist_784', version=1, return_X_y=True)

# convert string labels to integers
    y = np.array([int(v) for v in y])[:,np.newaxis]

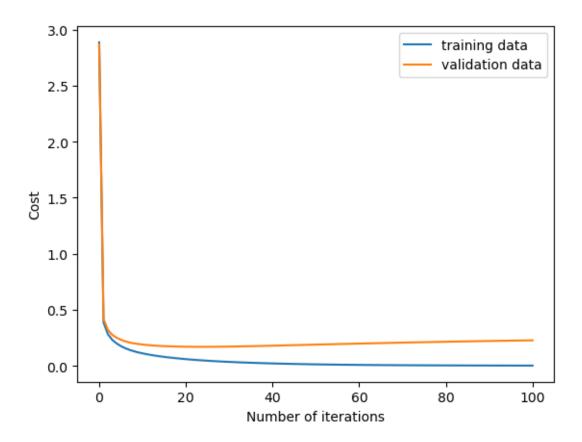
    print(np.shape(x))
    print(np.shape(y))

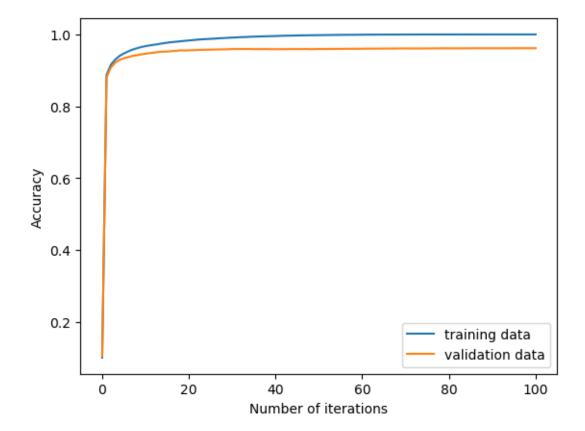
(70000, 784)
    (70000, 1)

[]: x = np.array(x.transpose())
    y = np.array(y.transpose())
    print(np.shape(x))
    print(np.shape(x))
    print(np.shape(y))
```

```
(784, 70000)
    (1, 70000)
[]: selected_indices = np.random.choice(range(70000), size=60000, replace=False)
     x = x[:,selected_indices]
     y = y[:,selected_indices]
[]: x=normalize(x)
[]: train_indices = np.random.choice(range(60000), size=50000, replace=False)
     val_indices = np.delete(range(60000), train_indices)
     print(np.shape(val_indices))
     print(np.shape(train_indices))
    (10000,)
    (50000,)
[]: def activation(a):
         return np.maximum(0, a)
[]: layer_sizes = [784, 100, 100, 10]
     theta = network_initializer(layer_sizes, .1)
[]: def gradient_descent_minibatch_val(g, alpha, max_its, w, batch_size):
         weight_history = [w]
         cost_history = [g(w, train_indices)]
         min_val_weights = w
         min_val_cost = g(w, val_indices)
         min_val_iter = 0
         val_cost_history = [g(w, val_indices)]
         g_flat, unflatten, w = flatten_func(g, w)
         gradient = grad(g_flat)
         for k in range(max_its):
             if k\%10 == 0:
                 print(k)
             start_idx = 0
             while start_idx < len(train_indices):</pre>
                 batch_inds = train_indices[range(start_idx, start_idx+batch_size)]
                 grad_eval = gradient(w, batch_inds)
                 w = w-alpha*grad_eval
                 start_idx += batch_size
```

```
weight_history.append(unflatten(w))
             cost_history.append(g(unflatten(w), train_indices))
             cur_val_cost = g(unflatten(w), val_indices)
             val_cost_history.append(cur_val_cost)
             if cur_val_cost < min_val_cost:</pre>
                 min_val_cost = cur_val_cost
                 min_val_weights = unflatten(w)
                 min_val_iter = k
         return weight_history, cost_history, min_val_weights, min_val_cost,_u
      →min_val_iter, val_cost_history
[]: alpha = .1
     num_iter = 100
     weight_history, cost_history, min_val_weights, min_val_cost, min_val_iter, __
      ⇒val_cost_history = gradient_descent_minibatch_val(multi_softmax, alpha, ulti_softmax)
      ⇒num_iter, theta, 500)
    0
    10
    20
    30
    40
    50
    60
    70
    80
    90
[]: plt.plot(cost_history, label="training data")
     plt.plot(val_cost_history, label="validation data")
     plt.legend()
     plt.xlabel("Number of iterations")
     plt.ylabel("Cost")
     plt.show()
```





We can see from the cost and accuracy plots above that we achieve similar results as in the text