

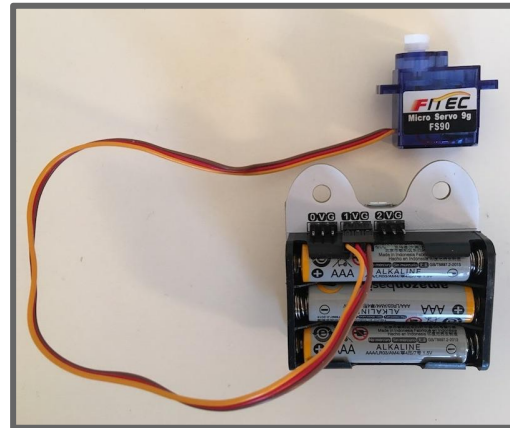
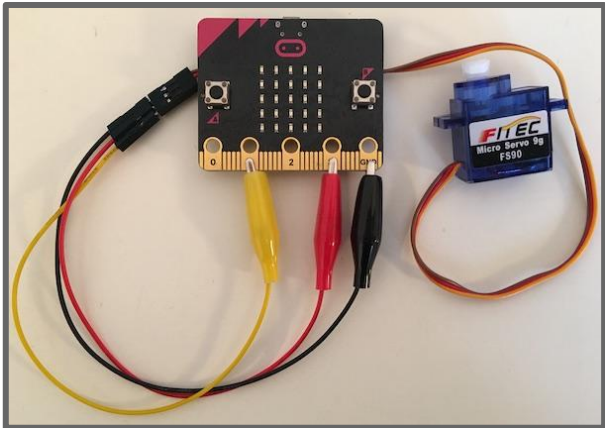


# micro:bit | Servos

Connect the micro:bit to MicroBlocks.



Connect a servo to pin 1 using either alligator clips or an extension board.



**NOTE:** The micro:bit needs extra power to run servos. Be sure to attach batteries or use an extension board that provides extra power.

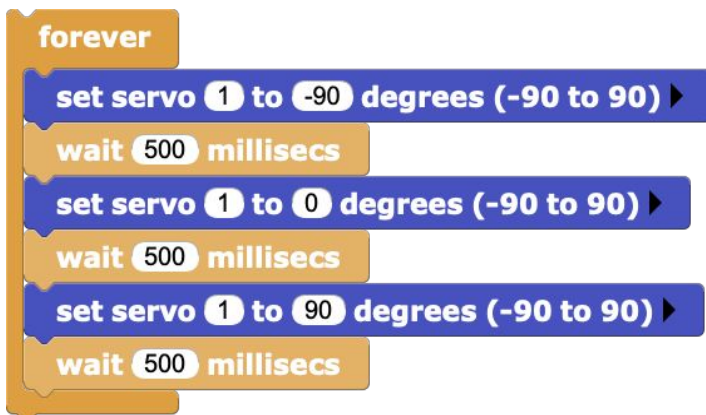
Add the Servo library:



**Servo**

## Position Servos

Position servos move to a specific angle and stay there. You control what angle they move to. Try this code to see your position servo move!



## Continuous Servos

Continuous servos spin continuously like a motor. You control their speed and direction. This code will make your continuous servo spin. What happens if you increase or decrease the speed?

