# **Documentation of ROS2** package: pack2

# **Description:**

P1 desc

# **Package Metadata**

## **Maintaner:**

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## License:

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Node: node2

Namespace: name/space2

#### Publishers

Name	Туре	Package	Path	Rate	QoS Profile
pub1	M1	interfaces	topic/path1	10.0	SYSTEM_DEFAULT

#### Clients

Name	Service Name	Туре	Package	Path	QoS Profile
c1	service1	Addtwo	interfaces	path	Custom

## Custom QoS Profile of Client **c1**

Parameter	Value
History	KEEP_ALL
Reliability	RELIABLE
Durability	SYSTEM_DEFAULT
Depth	0
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0

Parameter	Value
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

#### **Action Servers**

Name	Туре	Package
as2	Dec	interfaces

#### **Action Clients**

Name	Туре	Package
as1	Increase	interfaces