

# Documentation of ROS2 package: pack1

## **Description:**

The description is ....

---

# Package Metadata

**Maintaner:**

raf

**Email:**

rnm1816@gmail.com

**License:**

The license is ...

---

**Node: node1**  
**Namespace: None**

Parameters

Name	Type
p1	int32

Publishers

Name	Type	Package	Path	Rate	QoS
publy3	Header	std_msgs	topic/path3	12.0	10
publy2	ValueInt	interfaces	topic/path2	8.0	10

Servers

Name	Service Name	Type	Package	Path
Server1	add_two	Addtwo	interfaces	ser/vice/path1
Server3	set_bool	SetBool	std_srvs	ser/vice/path3

Action Servers

Name	Type	Package
action1	Increase	interfaces

---

**Node: node2**  
**Namespace: None**

Subscribers

Name	Type	Package	Path	QoS
suby2	ValueInt	interfaces	topic/path2	10

Clients

Name	Service Name	Type	Package	Path
Client1	add_two	Addtwo	interfaces	ser/vice/path1
Client3	set_bool	SetBool	std_srvs	ser/vice/path3

Action Clients

Name	Type	Package
action1	Increase	interfaces

---