

# Documentation of ROS2 package: launch\_robot

## **Description:**

This is a package, generated from Generos to contain the Deployment configuration of a Host. This package contains all the Launch Files that the user created in the model.

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## Package Metadata

**Maintaner:**

Generos

**Email:**

rnm1816@gmail.com

**License:**

Inherited from Repository

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# Host robot Info

Host spefication

Characteristic	Value
Architecture	x64
Operating System	Ubuntu_18
Hard Disk	20480.0
Memory	2048.0
ROS2 version	Eloquent_Elusr

Launch Files

Name	Nodes	Executables	Arguments
launch_robot	sonar   motor   controller	sonar_exec   motor_exec   controller_exec	