

Documentation of ROS2 package: Interfaces

Description:

This is a package, generated from Generos to contain all the Custom Interfaces, created by the user. This package contains all the Messages, Services and Actions that the user created in the model. This document present these interfaces.

Topic Messages

MSG: Distance

This is a Message to provide a timestamped range value from Sonar sensors

Distance Objects

Name	Type	Default	Package	Description
h	Header		std_msgs	Timestamp Header of the distance
range	float32		no	range from obstacle in meters

Service Messages

Action Messages