

# Documentation of ROS2 package: pack2

## Description:

None

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# Package Metadata

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## Node: node2

### Namespace: name/space2

#### Publishers

Name	Type	Package	Path	Rate	QoS Profile
pub1	M1	interfaces	topic/path/1	10.0	SYSTEM_DEFAULT

#### Clients

Name	Service Name	Type	Package	Path	QoS Profile
c1	service1	Addtwo	interfaces	path	Custom

#### Custom QoS Profile of Client **c1**

Parameter	Value
History	KEEP_ALL
Reliability	RELIABLE
Durability	SYSTEM_DEFAULT
Depth	0
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0

Parameter	Value
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

Action Servers

Name	Type	Package
as2	Dec	interfaces

Action Clients

Name	Type	Package
as1	Increase	interfaces

