

# Documentation of ROS2 package: pack2

## **Description:**

The description is ....

---

# Package Metadata

**Maintaner:**

raf

**Email:**

rnm1816@gmail.com

**License:**

The license is ...

---

**Node: node3**  
**Namespace: None**

Subscribers

Name	Type	Package	Path	QoS
suby3	Header	std_msgs	topic/path3	10

Clients

Name	Service Name	Type	Package	Path
Client2	str	SrFloatFloatString	interfaces	ser/vice/ path2

---