

# Documentation of ROS2 package: Interfaces

## Description:

This is a package, generated from Generos to contain all the Custom Interfaces, created by the user. This package contains all the Messages, Services and Actions that the user created in the model. This document present these interfaces.

---

---

## Topic Messages

### MSG: Velocities

This is a Message to provide a timestamped motion value for left and right motor

#### Velocities Objects

Name	Type	Default	Package	Description
h	Header		std_msgs	Timestamp Header of the velocities
left_rpm	float32	no		velocity of the left motor
right_rpm	float32	no		velocity of the right motor

---

---

## **Service Messages**

---

## **Action Messages**