

Documentation of ROS2 package: pack2

Description:

The description is

Package Metadata

Maintaner:

raf

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License:

The license is ...

Node: node3
Namespace: None

Subscribers

Name	Type	Package	Path	QoS
suby3	Header	std_msgs	topic/path3	10

Clients

Name	Service Name	Type	Package	Path
Client2	str	SrFloatFloatString	interfaces	ser/vice/ path2
