Documentation of ROS2 package: pack1

Description:

None

Package Metadata

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License:

Apache License 2.0

Node: sonar1 Namespace:

Publishers

Name	Туре	Package	Path	Rate	QoS Profile
toCpu1	Distance	interfaces	topic/path/s1	0.5	Custom

Custom QoS Profile of Publisher **toCpu1**

Parameter	Value
History	KEEP_LAST
Reliability	SYSTEM_DEFAULT
Durability	SYSTEM_DEFAULT
Depth	15
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0

Parameter	Value
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

Node: sonar2 Namespace:

Publishers

Name	Туре	Package	Path	Rate	QoS Profile
toCpu2	Distance	interfaces	topic/path/s2	0.5	Custom

Custom QoS Profile of Publisher **toCpu2**

Parameter	Value
History	KEEP_LAST
Reliability	SYSTEM_DEFAULT
Durability	SYSTEM_DEFAULT
Depth	15
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0

Parameter	Value
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

Node: cpu Namespace:

Publishers

Name	Type Package	Path R	ate QoS Profile
toActuators	Twist geometry_ms	topic/ sgs path/ 0. act	5 SYSTEM_DEFAULT

Subscribers

Name	Туре	Package	Path	QoS Profile
fromSonar1	Distance	interfaces	topic/path/s1	Custom
fromSonar2	Distance	interfaces	topic/path/s2	Custom

Custom QoS Profile of Subscriber fromSonar1

Parameter	Value
History	KEEP_LAST
Reliability	SYSTEM_DEFAULT
Durability	SYSTEM_DEFAULT
Depth	15
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0

Parameter	Value
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

Custom QoS Profile of Subscriber fromSonar2

Parameter	Value
History	KEEP_LAST
Reliability	SYSTEM_DEFAULT
Durability	SYSTEM_DEFAULT
Depth	15
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0

Parameter	Value
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False