

# Documentation of ROS2 package: pack1

## **Description:**

Package for a Server Client communication

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# Package Metadata

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**License:**

MIT

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**Node: node1**  
**Namespace:**

Servers

Name	Service Name	Type	Package	Path	QoS Profile
serv1	service1	SetBool	std_srvs	service/ path1	SYSTEM_DEFAULT

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**Node: node2**  
**Namespace:**

Clients

Name	Service Name	Type	Package	Path	QoS Profile
cli1	service1	SetBool	std_srvs	service/ path1	SYSTEM_DEFAULT

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