Documentation of ROS2 package: Interfaces

Description:

This is a package, generated from Generos to contain all the Custom Interfaces, created by the user. This package contains all the Msg, Srv and Action interfaces the user created in the model. This document present these interfaces.

Topic Messages

MSG: M1

M1 Objects

Name	Type	Default	Package	Description
a	int64		no	description...
b	bool	False	no	description333...
c	bool		no	descripssstion333...
h	Header		std_msgs	
s	string		no	description444...
y	float32		no	description222...

Service Messages

SRV: Addtwo

Addtwo Objects

Name	Type	Default	Package	Description
Request				
x	int32	0	no	first number
y	int32	0	no	second number
Response				
b	bool		no	descripssstion333...
h	Header		std_msgs	
z	int64		no	The sum of x+y

Action Messages

ACTION: Increase

Increase Objects

Name	Type	Default	Package	Description
Goal				
start	int32	0	no	start number
stop	int32	0	no	stop number
Result				
resus	bool		no	descripssstion333...
Feedback				
h	Header		std_msgs	
z	int64		no	The counter