

# Documentation of ROS2 package: pack2

## **Description:**

The description is ....

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# Package Metadata

**Maintaner:**

raf

**Email:**

rnm1816@gmail.com

**License:**

The license is ...

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**Node: node3**  
**Namespace: None**

Subscribers

Name	Type	Package	Path	QoS Profile
suby3	Header	std_msgs	topic/path3	SYSTEM_DEFAULT

Clients

Name	Service Name	Type	Package	Path	QoS Profile
Client2	str	SrFloatFloatString	interfaces	ser/ vice/ path2	SYSTEM_DEFAULT

