

# Documentation of ROS2 package: slam

## **Description:**

SLAM pre-existing package

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## Package Metadata

**Maintaner:**

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**License:**

Apache 2.0

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**Node: slamer**  
**Namespace:**

Publishers

Name	Type	Package	Path	Rate	QoS Profile
map	M1	interfaces	topic/map	10.0	SYSTEM_DEFAULT

Subscribers

Name	Type	Package	Path	QoS Profile
laser	M1	interfaces	topic/path1	SYSTEM_DEFAULT

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