

# Documentation of ROS2 package: pack1

## Description:

None

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## Package Metadata

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**License:**

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## Node: node1

### Namespace:

#### Parameters

Name	Type	Description
p1	INTEGER_ARRAY	

#### Subscribers

Name	Type	Package	Path	QoS Profile
sub1	M1	interfaces	topic/path/1	SYSTEM_DEFAULT

#### Servers

Name	Service Name	Type	Package	Path	QoS Profile
s1	service1	Addtwo	interfaces	path	Custom
s2	service2	SetBool	std_srvs	path2	Custom

#### Custom QoS Profile of Server **s1**

Parameter	Value
History	KEEP_ALL
Reliability	RELIABLE

Parameter	Value
Durability	SYSTEM_DEFAULT
Depth	0
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

#### Custom QoS Profile of Server **s2**

Parameter	Value
History	KEEP_ALL
Reliability	RELIABLE
Durability	SYSTEM_DEFAULT
Depth	0
Liveliness	SYSTEM_DEFAULT

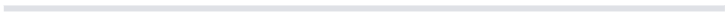
Parameter	Value
Deadline Sec	0
Deadline Nano Sec	0
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

Action Servers

Name	Type	Package
as1	Increase	interfaces

Action Clients

Name	Type	Package
as2	Dec	interfaces



## Node: node3

### Namespace: name/space3

#### Subscribers

Name	Type	Package	Path	QoS Profile
sub1	M1	interfaces	topic/path/1	SYSTEM_DEFAULT

#### Clients

Name	Service Name	Type	Package	Path	QoS Profile
c1	service1	Addtwo	interfaces	path	Custom

#### Custom QoS Profile of Client **c1**

Parameter	Value
History	KEEP_ALL
Reliability	RELIABLE
Durability	SYSTEM_DEFAULT
Depth	0
Liveliness	SYSTEM_DEFAULT
Deadline Sec	0
Deadline Nano Sec	0

Parameter	Value
Lifespan Sec	0
Lifespan Nano Sec	0
Liveliness Lease Duration Sec	0
Liveliness Lease Duration Nano Sec	0
Avoid ROS Namespace Conventions	False

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