

# Documentation of ROS2 package: pack1

## **Description:**

Package for a PubSub communication

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# Package Metadata

**Maintaner:**

bronzeRaf

**Email:**

rnm1816@gmail.com

**License:**

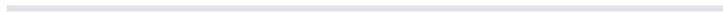
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**Node: node1**  
**Namespace:**

Publishers

Name	Type	Package	Path	Rate	QoS Profile
pub1	Header	std_msgs	topic/path1	10.0	SYSTEM_DEFAULT



**Node: node2**  
**Namespace:**

Subscribers

Name	Type	Package	Path	QoS Profile
sub1	Header	std_msgs	topic/path1	SYSTEM_DEFAULT

