```
// Author:
// Date:
// Date:
// Description: C code applic
// The program will read but
// and change the LED displa
// Button 1: Left
// Button 2: Not connected y
// Button 3: Shift LEDs righ
// LEDs 9-12: As display out
// + modify code
// + compile and link code:
// gcc -o buttonsAndLeds.
// execute code:
// hexecute code:
// sudo ./myApp
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             #include "gb_common.h"
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     void main (void)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             void setup_gpio()
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     // Set up the GPIO ports as needed
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          // Include Gertboard functions header
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     #include <stdio.h>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        GPIO_PULLCLK0 = 0x3800000;
short_wait();
GPIO_PULL = 0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                // However, a button press is detected as a LOW signal. // This means the RPi needs to pull up the input lines by default // to HIGH (to detect a button press as LOW).
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                GPIO_PULLCLK0 = 0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        // setting bits 25,24,23 below means that the GPIO_PULL is applied // to GPIO 25,24,23
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  short_wait();
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                GPIO_PULL = 2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             INP_GPIO(24);
INP_GPIO(23);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          Description: C code application to specification given for task 14 The program will read button input 1,2, and 3 from the <u>Gerthoard</u> and change the LED display accordingly (left, exit, right).
//output LEDS on B9-B12
printf ("GP22 in J2 --- B
printf ("GP21 in J2 --- B
printf ("GP18 in J2 --- B
printf ("GP17 in J2 --- B
printf ("\n");
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  INP_GPIO(25);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     // enable pull-up on GPIO 25,24,23: set pull to 2 (code for pull high)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             // For this test we are using 25, 24 and 23 as button input lines
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     // By default, the input lines are low.
                                                                                                                                                                                                                          printf ("GP25 in J2 --- B1
printf ("GP24 in J2 --- B2
printf ("GP23 in J2 --- B3
                                                                                                                                                                                                                                                                                                                                                                printf ("These are the connections for the LEDs test:\n"); printf ("First, we connect GPIO ports to Buffered I/O ports.\n"); printf ("\n");
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        LEDs 9-12: As display output
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Button 3: Shift LEDs right
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Button 2: Not connected yet
                                                                                                                                                                                                printf ("\n");
                                                                                                                                                                                                                                                                                                          // buttons on B1, B2, B3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  printf( "Hello World!\n\n" );
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        //a) inform the user how to wire up the gertboard ports
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             //display hello message
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  setup_gpio
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                gcc -a myApp buttonsAndLeds.a gb_common.a
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          gcc -c buttonsAndLeds.c
                             2 --- B9 in J3\n");
2 --- B10 in J3\n");
2 --- B11 in J3\n");
2 --- B12 in J3\n");
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                // 0011 1000 0000 0000 0000 0000 0000
                                                                                                                                                                                                                          13\n");
13\n");
13\n");
```

```
printf ("Jumpers in location B9-OUT, B10-OUT, B11-OUT, B12-OUT .\n");
printf ("Optional to indicate button press with LEDs: \n");
printf ("Jumpers in location B1-OUT, B2-OUT, B3-OUT. \n\n");
//tidy up IO ports
                                                                                                                                                                                                                                                            //d) Use infinite do-while loop
                                                                                                                                                                                                                                                                                                                           //c) Light up second LED ( = LED 10)
                                                                                                                                                                                                                                                                                                                                                                                         setup_gpio(); // as defined above
                                                                                                                                                                                                                                                                                                                                                                                                                            setup_io();
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         //b) Setup/initialise RPi and Gertboard ports for I/O
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       printf ("When ready hit enter.\n");
                                                                                                                                                                                                                                                                                                                                                                                                                                                              // Map the I/O sections
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           (void)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      //Jumpers to install:
                                                                                                                                                                                              //read button states for B1,
                                                           //If B2 is on, shift LED display to the right
                                                                                                                            //If B1 is on, shift LED display to the left
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           getchar();
                                                                                                                                                                                                                                                                                                                                                                                                                            // pre-defined in gb_common
                                                                                                                                                                                              B2,
                                                                                                                                                                                                 ВЗ
```

÷

ļ