

Submission Date: **23/Oct/2022 (no extensions)**

Submission Format: 1 file called <your-upi>.tgz containing the following:

- a.) A promela file, including the LTL formulas for Q1.
- b.) A python script encoding a working SMT formulation for Q2.
- c.) A pdf file/report explaining the results obtained from SPIN/SMT solvers for Q1 and Q2.

NOTE: Your code should be well commented

Q1.) This question relates to your understanding of model-checking LTL properties on concurrent processes.

Part-A

Model Petersons mutual exclusion algorithm as described below in Promela.

The basic idea behind Peterson's n -process mutual exclusion algorithm is that each process passes through $n-1$ stages before entering the critical section (cs). These stages are designed to block one process per stage so that after $n-1$ stages only one process will be eligible to enter the critical section (which we consider as stage n). The algorithm uses two integer arrays *step* and *pos* of sizes $n-1$ and n respectively: *pos* is an array of 1-writer multi-reader variables and *step* is an array of multi-writer multi-reader variables. The value at *step*[j] indicates the *latest* process at step j , and *pos*[i] indicates the latest stage that the process i is passing through. (Peterson uses Q for *pos*, and $TURN$ for *step*.) The array *pos* is initialized to 0. The process id's, *pids*, are assumed to be integers between 1 and n . The code segment for process i is given in Figure 1.

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Process i:

1. for j = 1 to n - 1 do
2. begin
3.  pos[i] := j;
4.  step[j] := i;
5.  wait until (∀k ≠ i, pos[k] < j)
               ∨ (step[j] ≠ i)
6. end;
7. cs.i;
8. pos[i] := 0;

```

Figure – 1

Part-B

Represent the following properties in LTL and verify them against at least 2 processes from above.

Property-1 (Safety property): Multiple processes cannot enter the critical section together.

Property-2 (Liveness property): If a process is waiting, eventually it will enter the critical section.

Property-3 (Liveness property): Any process not in the critical section will eventually enter the critical

section.

Q2.) This question relates to your understanding of using SMT solvers for hardware verification.

Majority voter is a protocol used in fault tolerant systems. Consider 3-processors A, B, and C, carrying out the same computation simultaneously. Any of these processors might suffer from transient faults during processing. In the majority voter protocol, an output Y is set depending upon the majority result produced from the processors. The truth table below describes the majority voter protocol:

| A | B | C | Y |
|---|---|---|---|
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

The boolean equation:

$$Y = (\neg A \wedge B \wedge C) \vee (A \wedge \neg B \wedge C) \vee (A \wedge B \wedge \neg C) \vee (A \wedge B \wedge C) \quad (1)$$

gives the functional description of the truth-table above. A hardware engineer states that he/she will implement the above circuit using the equation below:

$$Y' = (A \wedge B) \vee (B \wedge C) \vee (A \wedge C) \quad (2)$$

Prove using the SMT solver that Equations (1) and (2) are equivalent. If they are not, show why not?