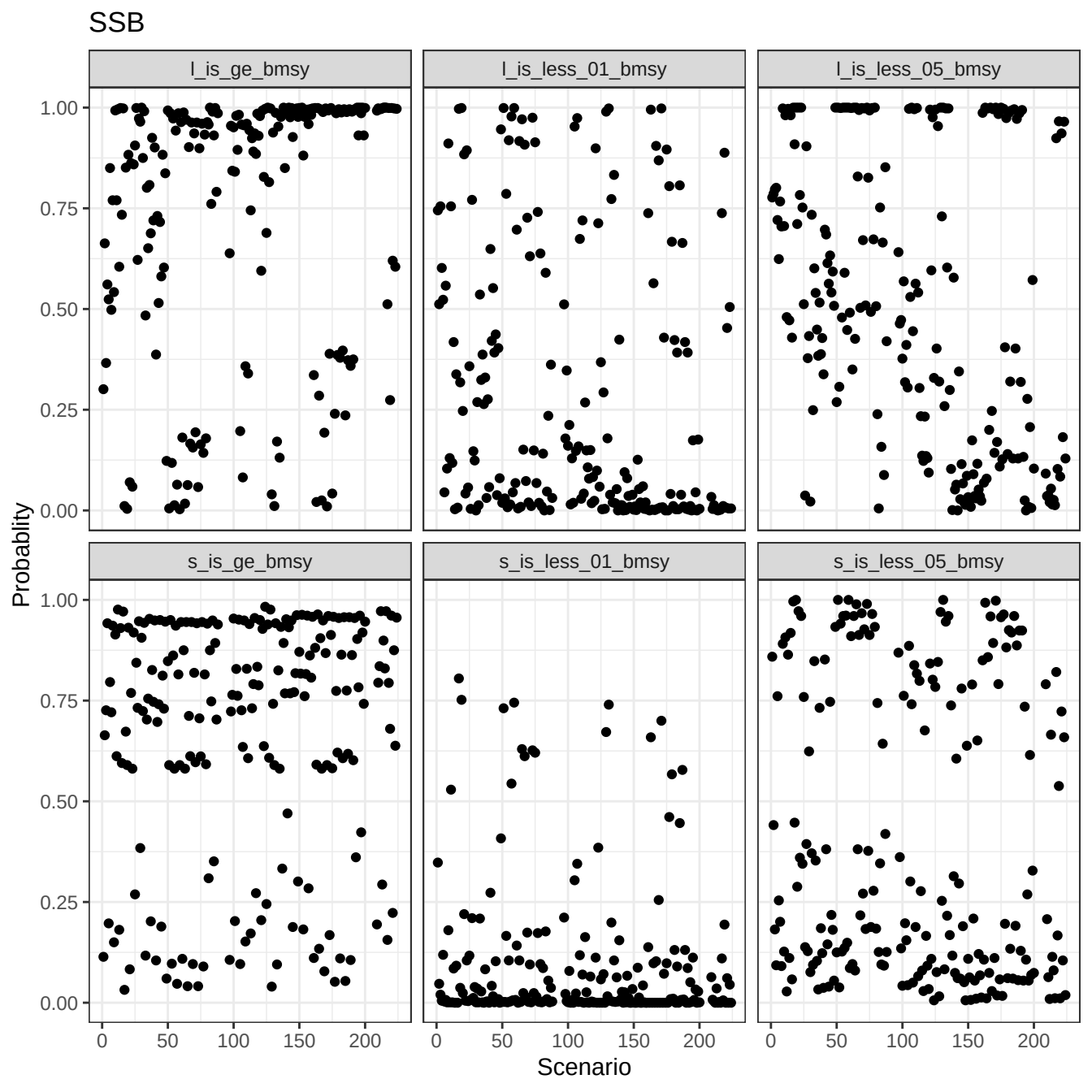
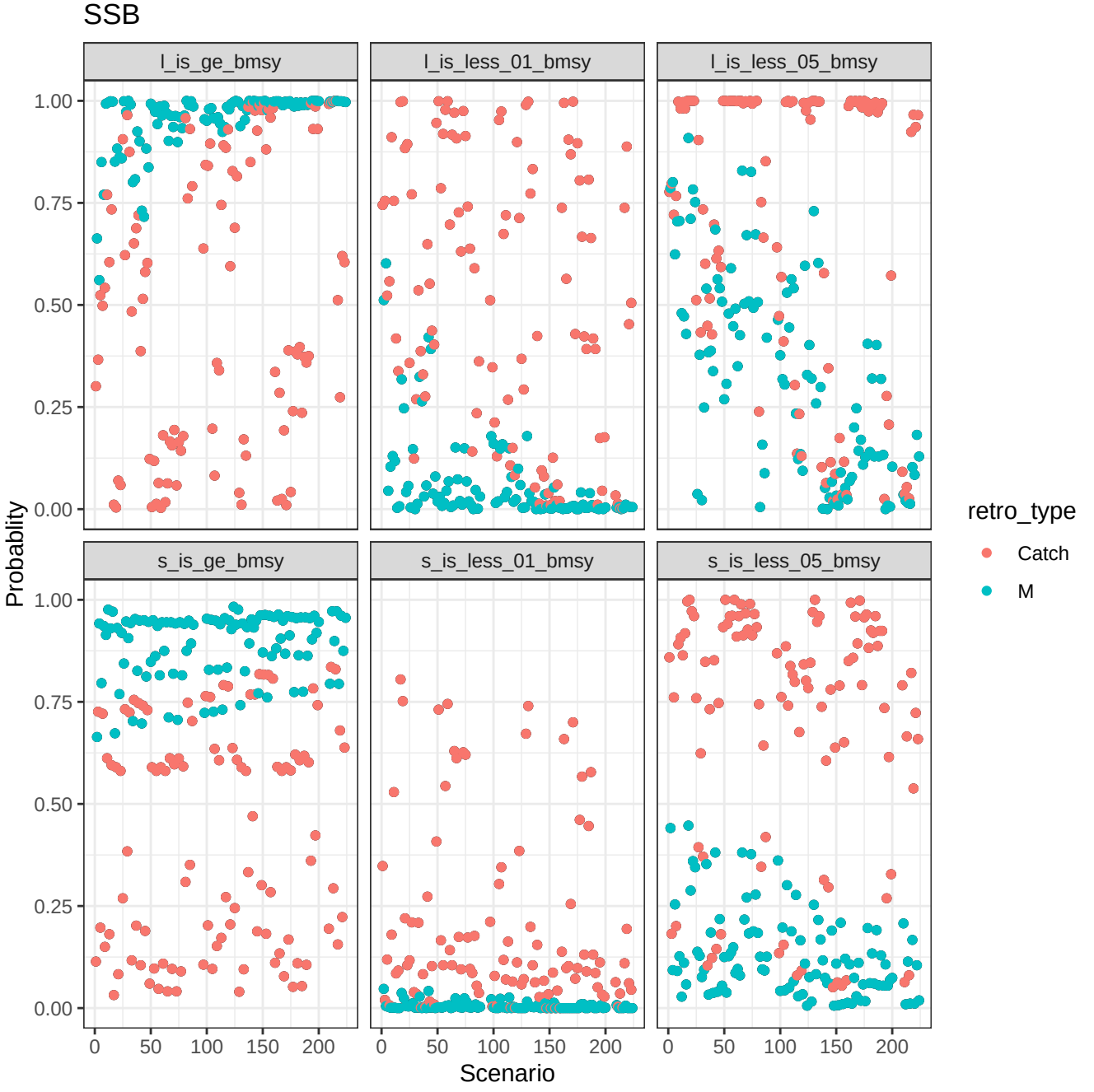
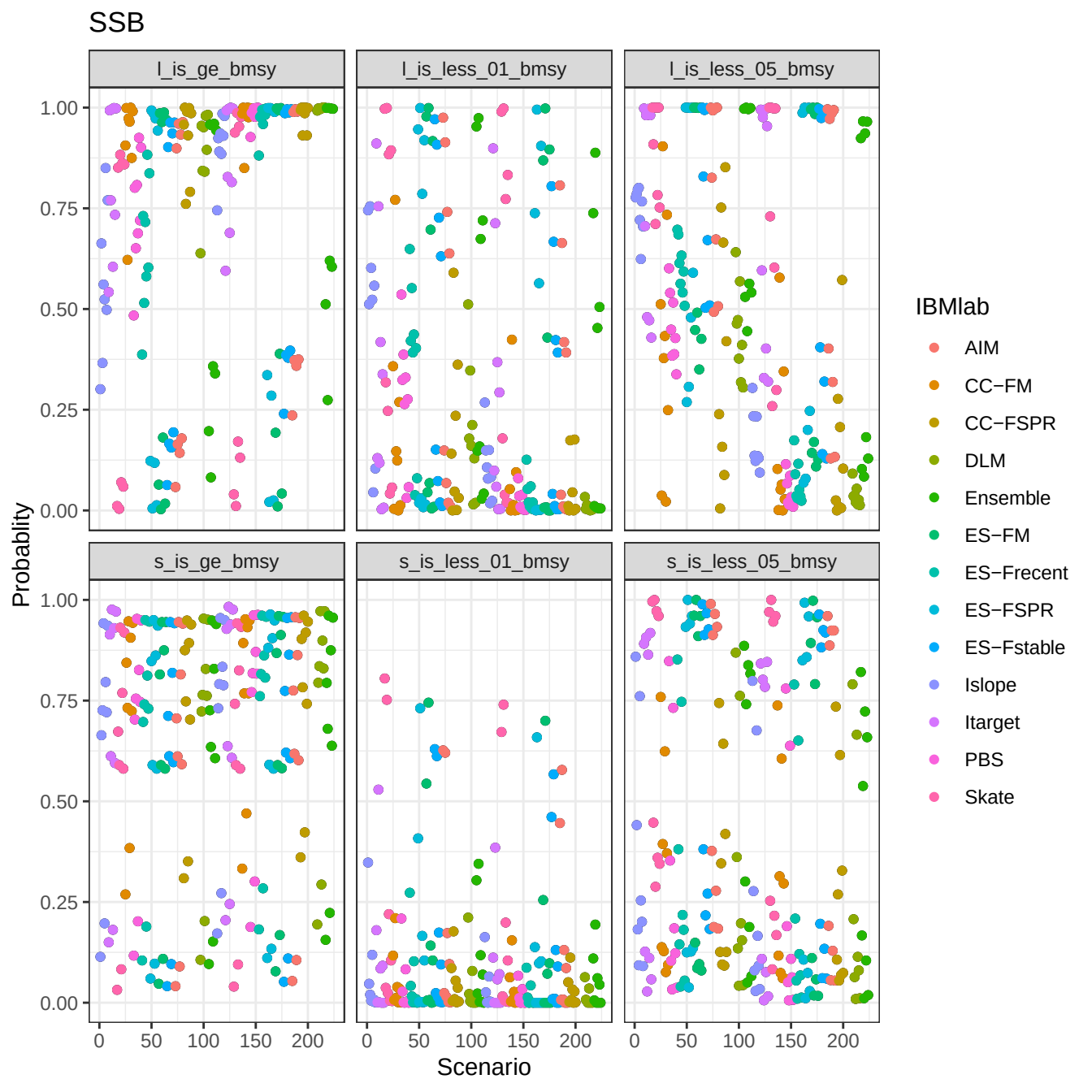
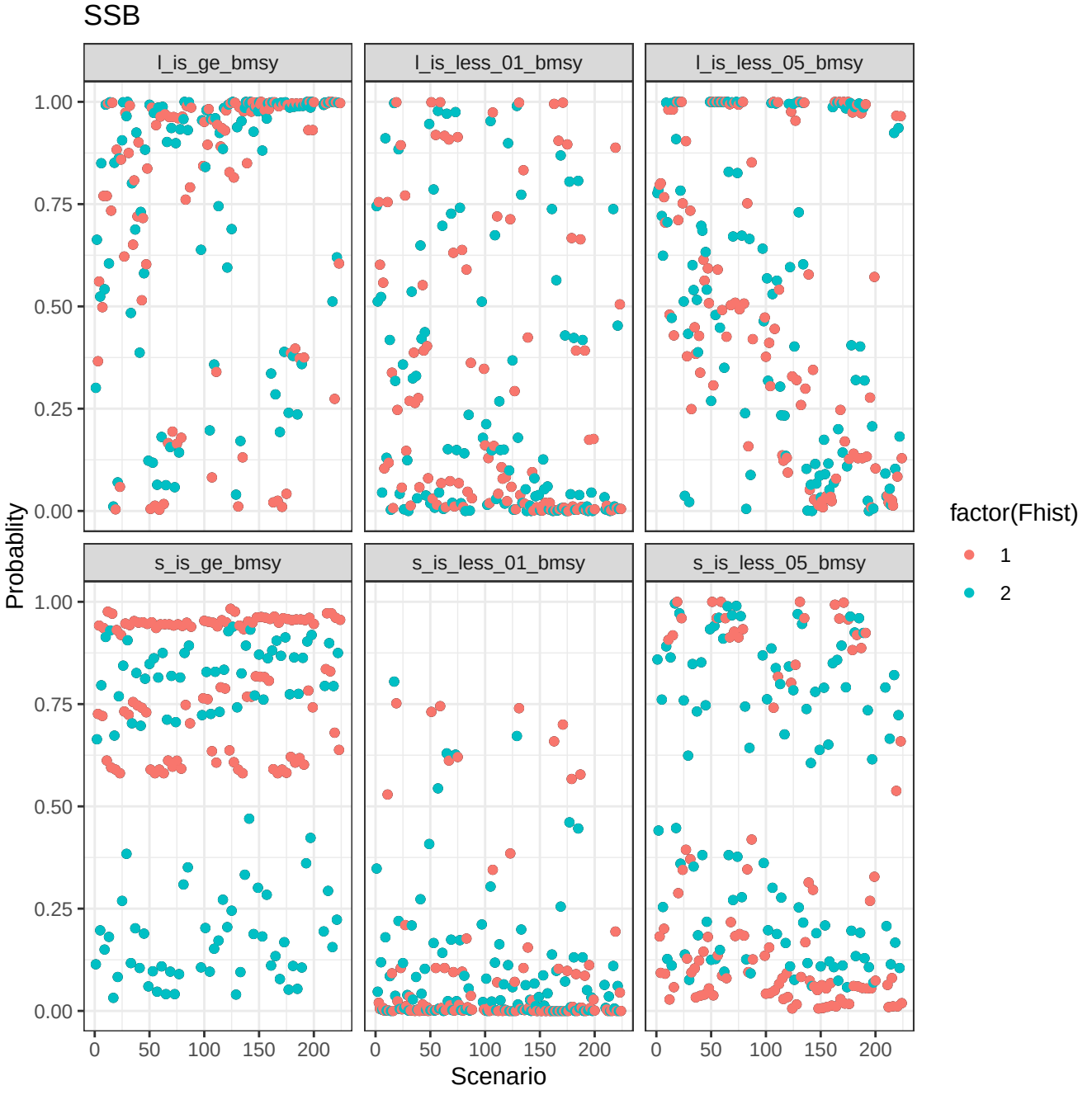
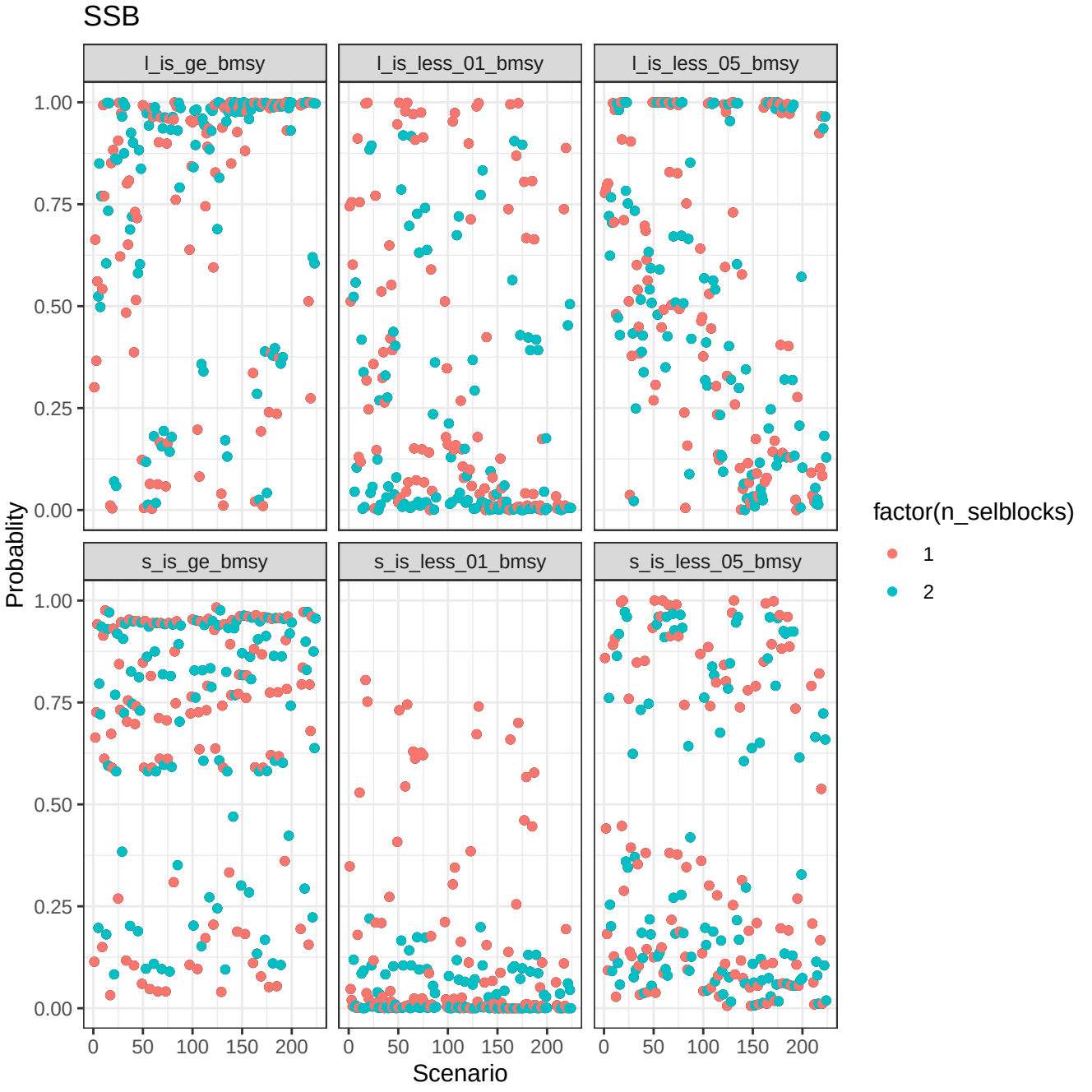
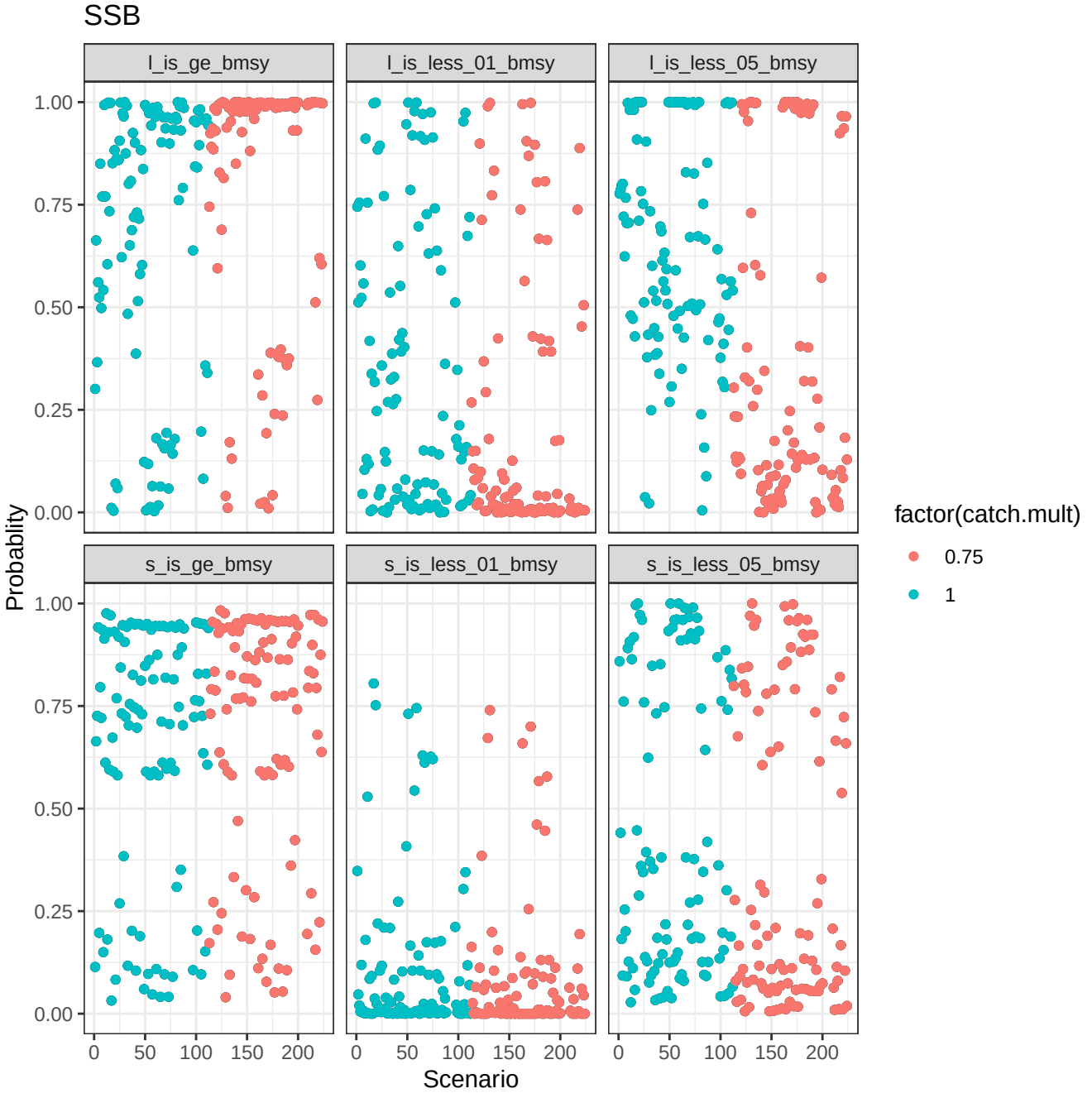

SSB
l_is_ge_bmsy
l_is_less_01_bmsy
l_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario

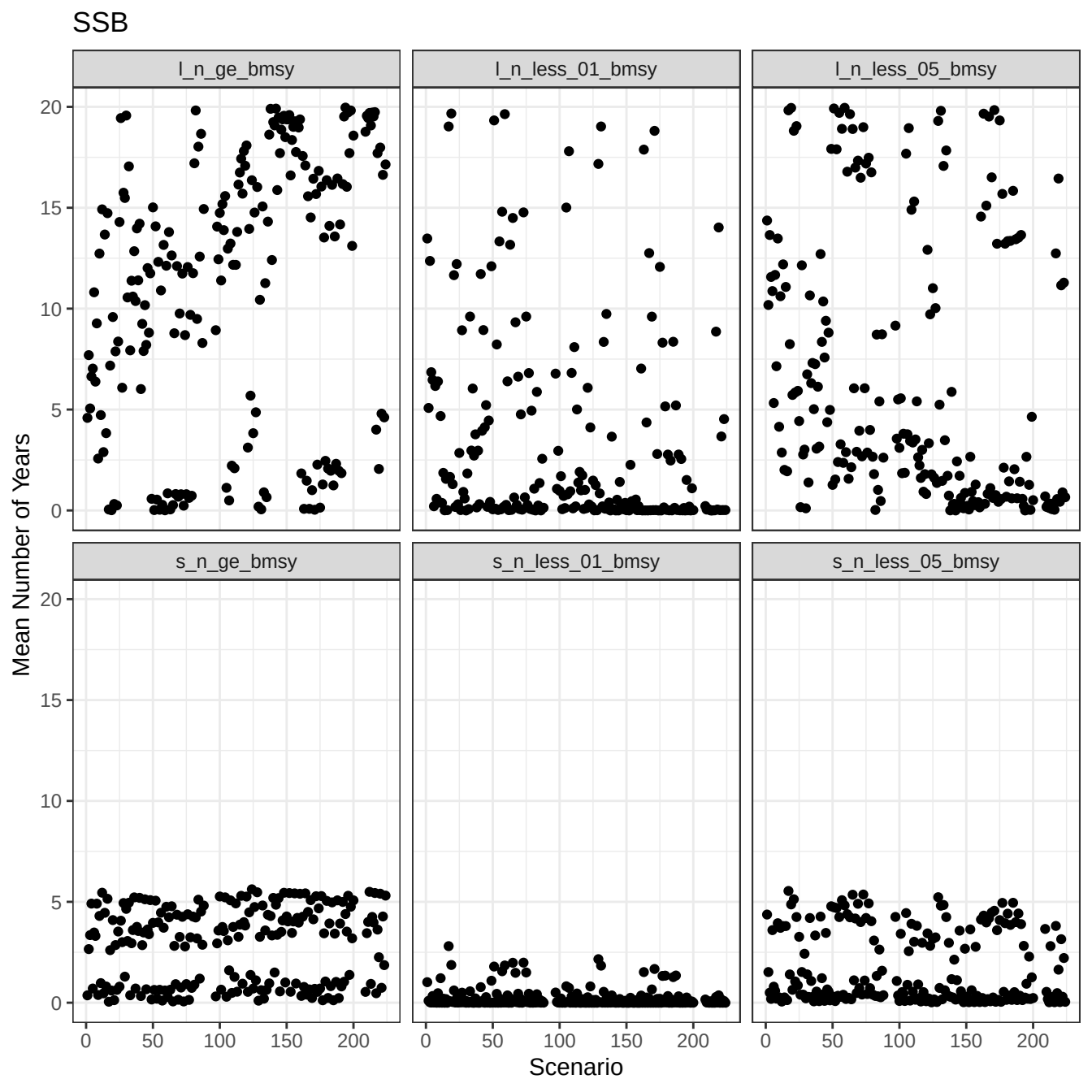

SSB
l_is_ge_bmsy
l_is_less_01_bmsy
l_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
retro_type
Catch
M

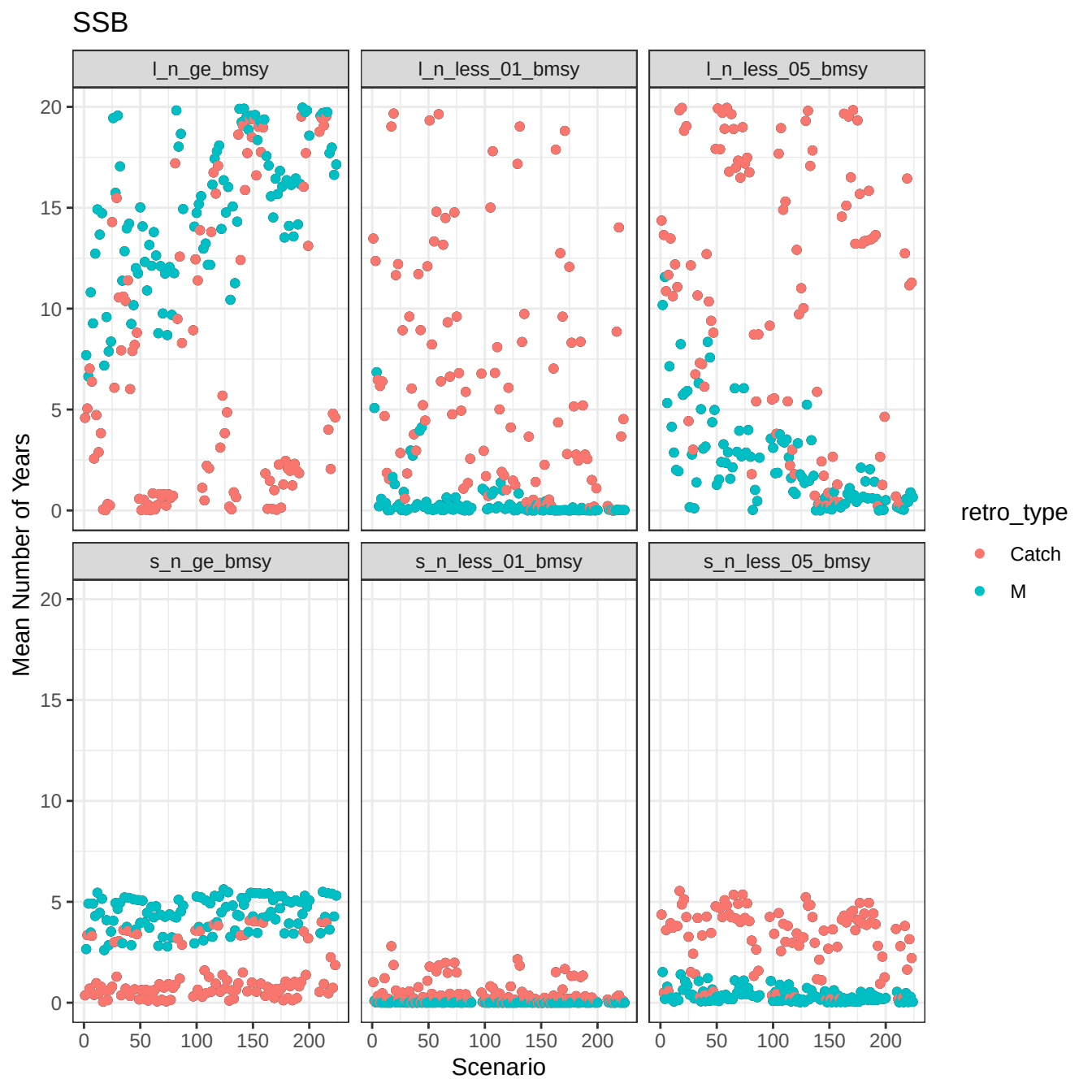

SSB
I_is_ge_bmsy
I_is_less_01_bmsy
I_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

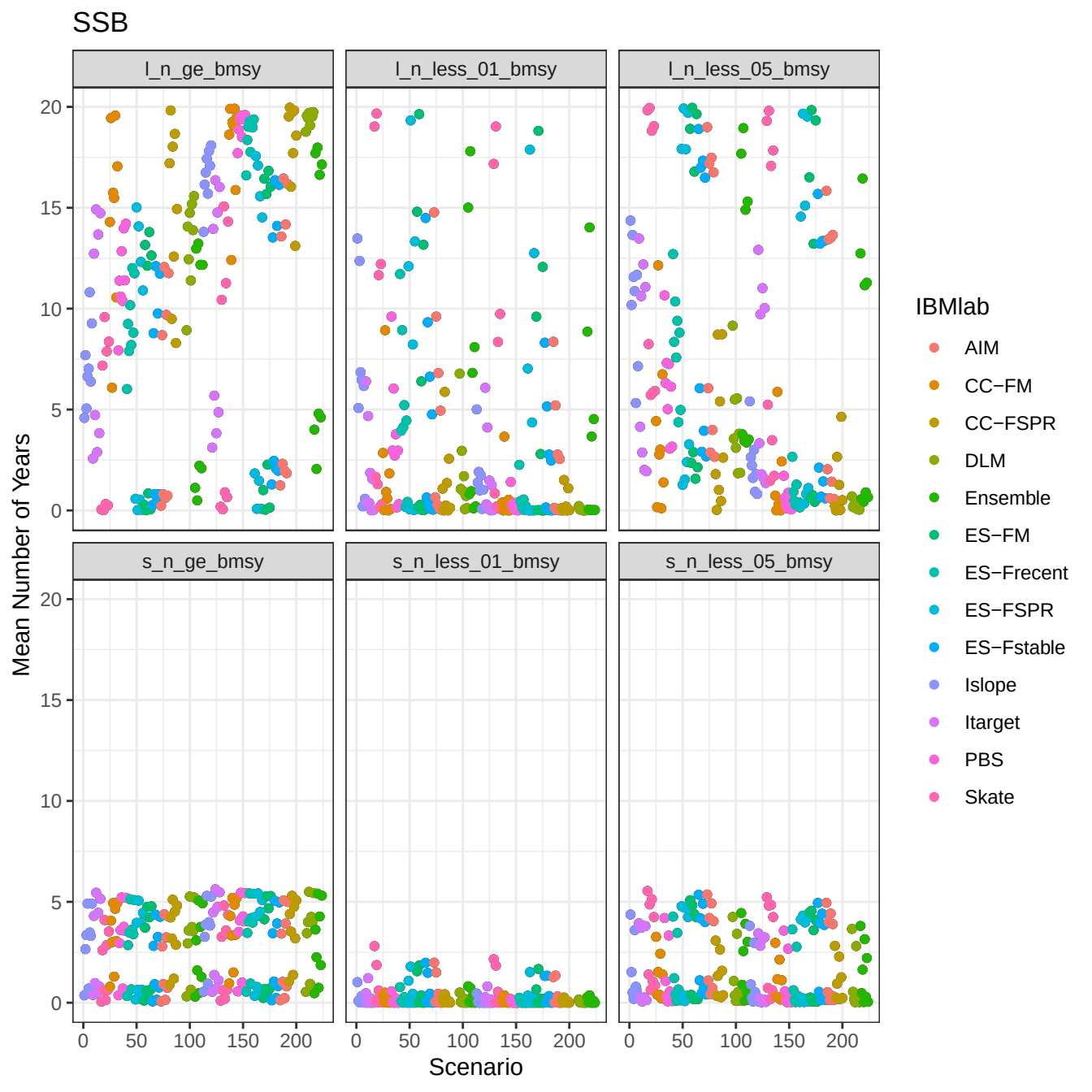

SSB
l_is_ge_bmsy
l_is_less_01_bmsy
l_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(Fhist)
1
2

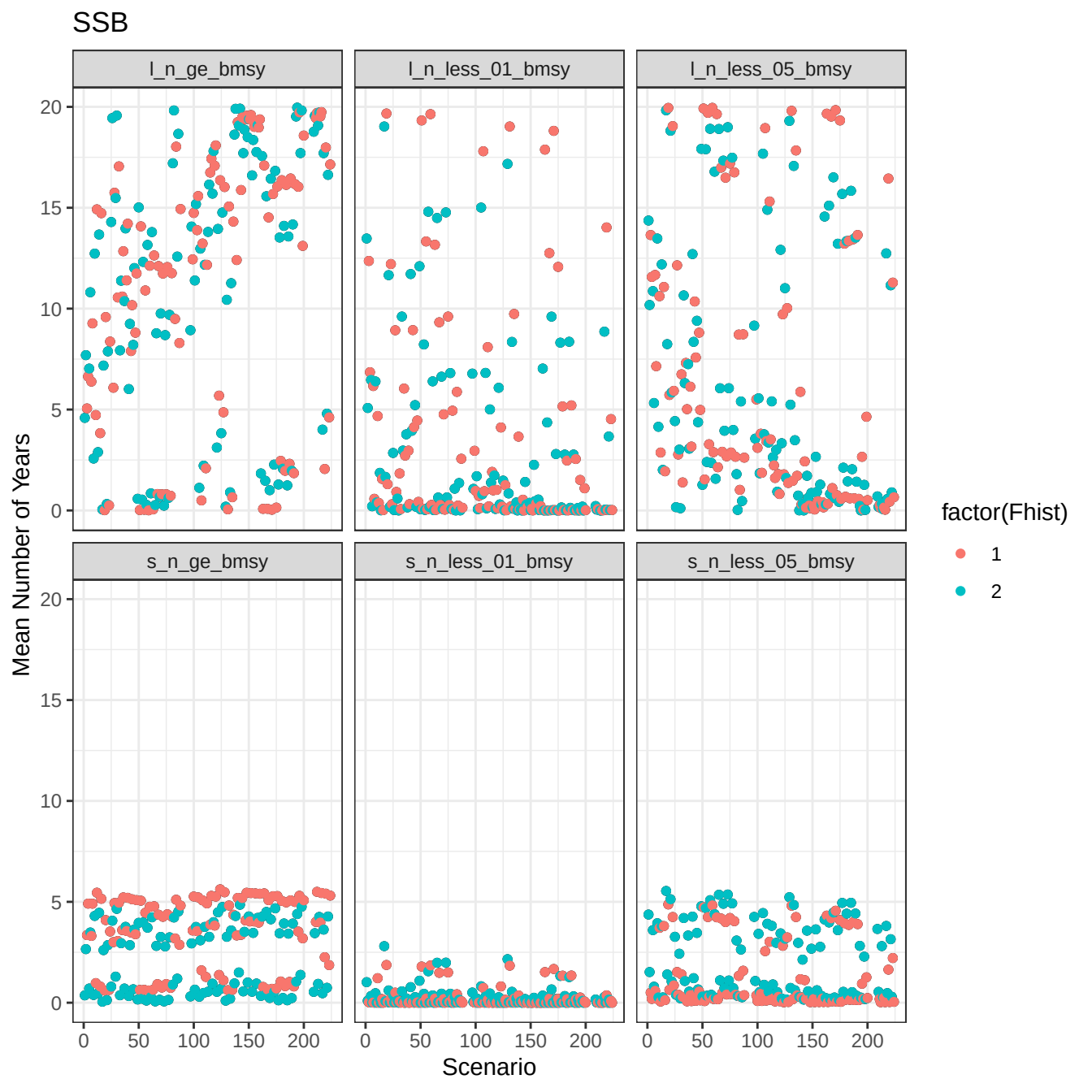

SSB
l_is_ge_bmsy
l_is_less_01_bmsy
l_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(n_selblocks)
1
2

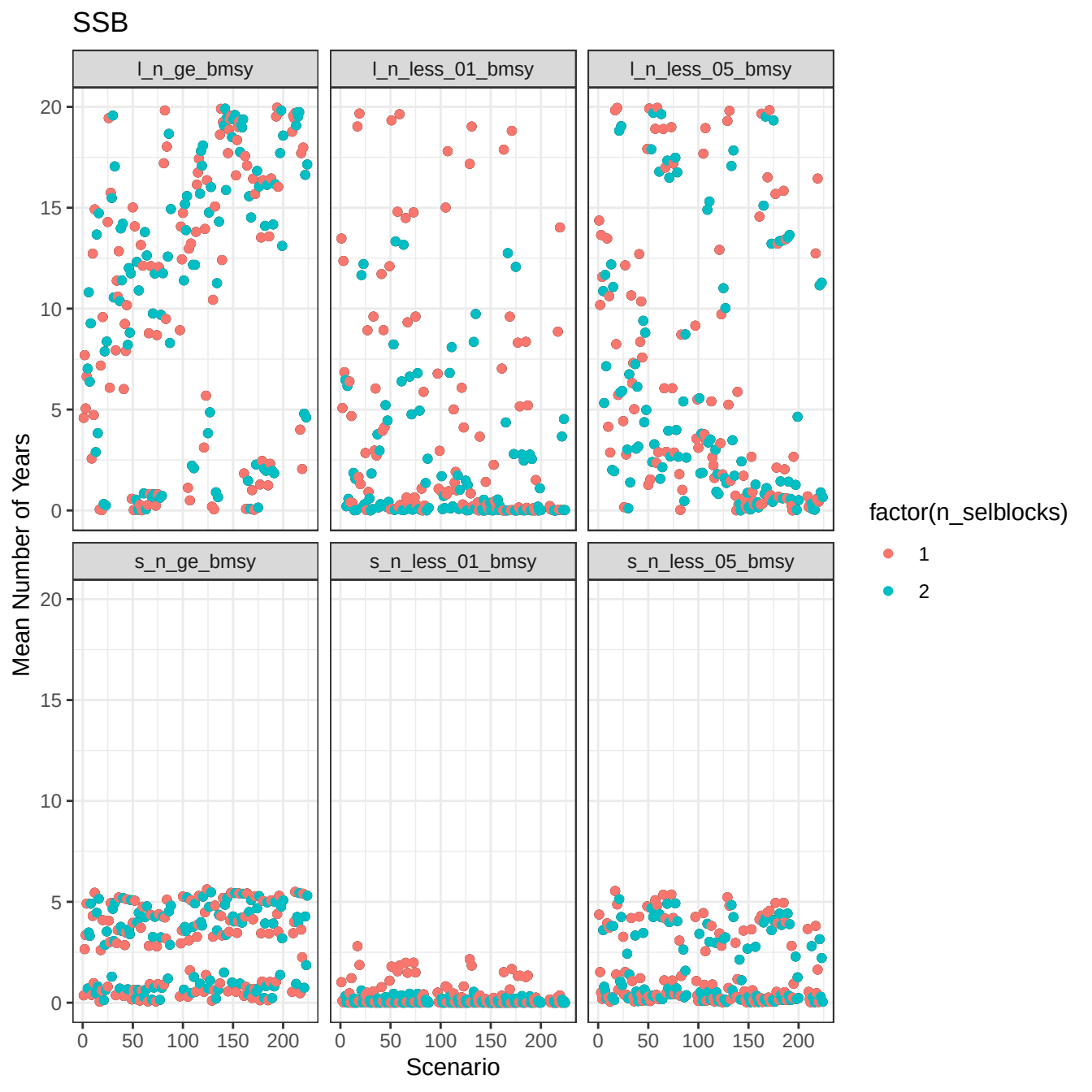

SSB
l_is_ge_bmsy
l_is_less_01_bmsy
l_is_less_05_bmsy
s_is_ge_bmsy
s_is_less_01_bmsy
s_is_less_05_bmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(catch.mult)
0.75
1

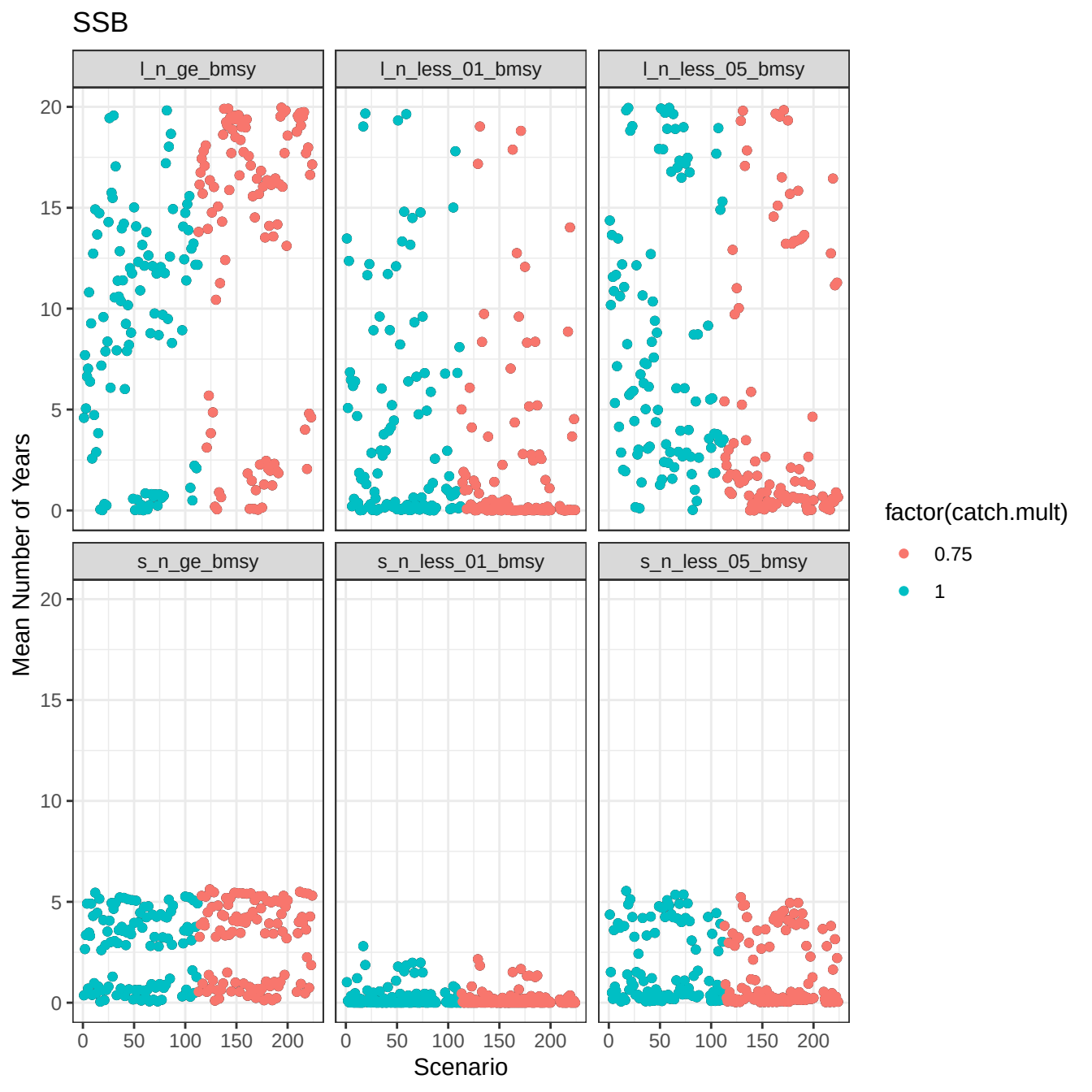

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
0
5
10
15
20
0
50
100
150
200

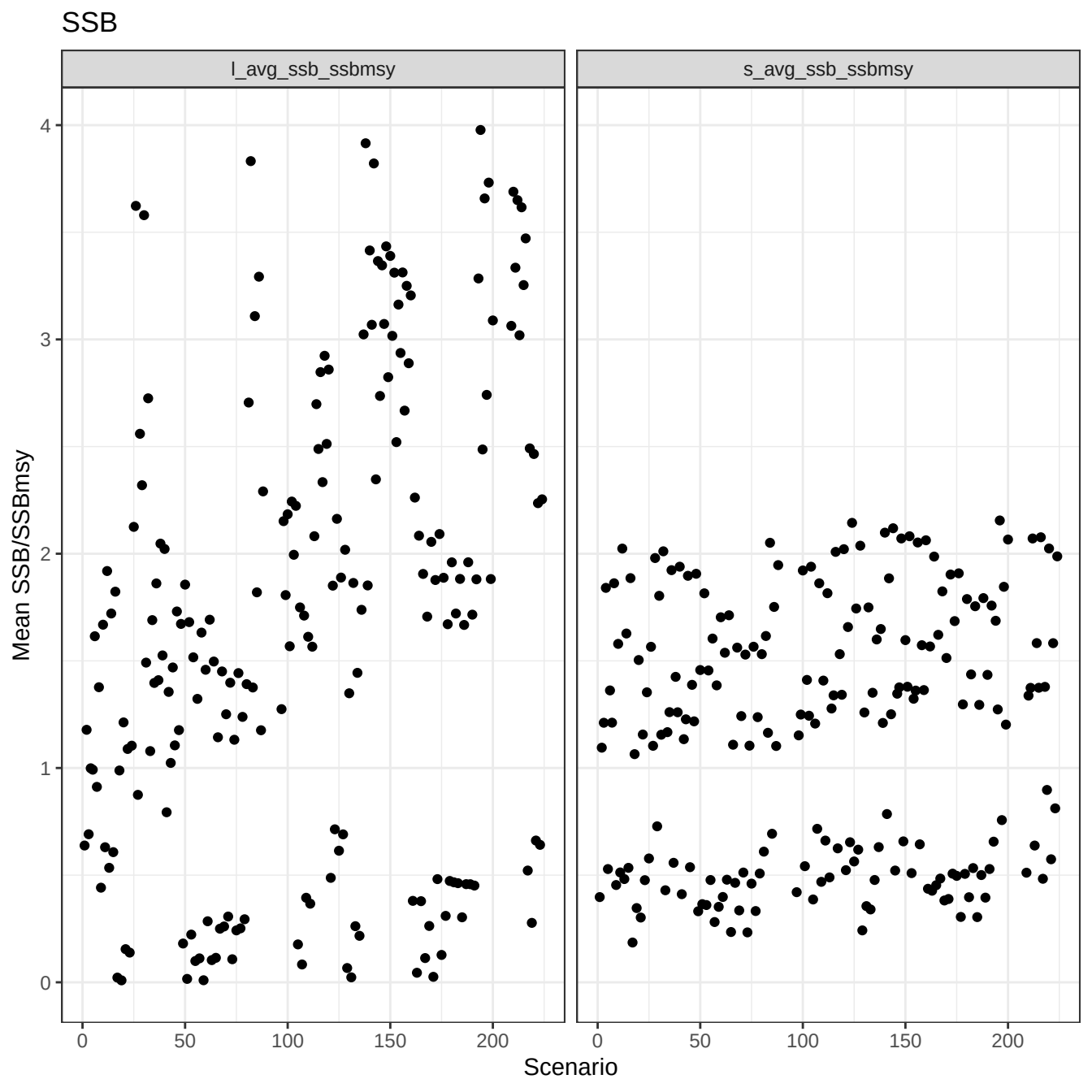

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
retro_type
Catch
M
0
5
10
15
20
0
50
100
150
200

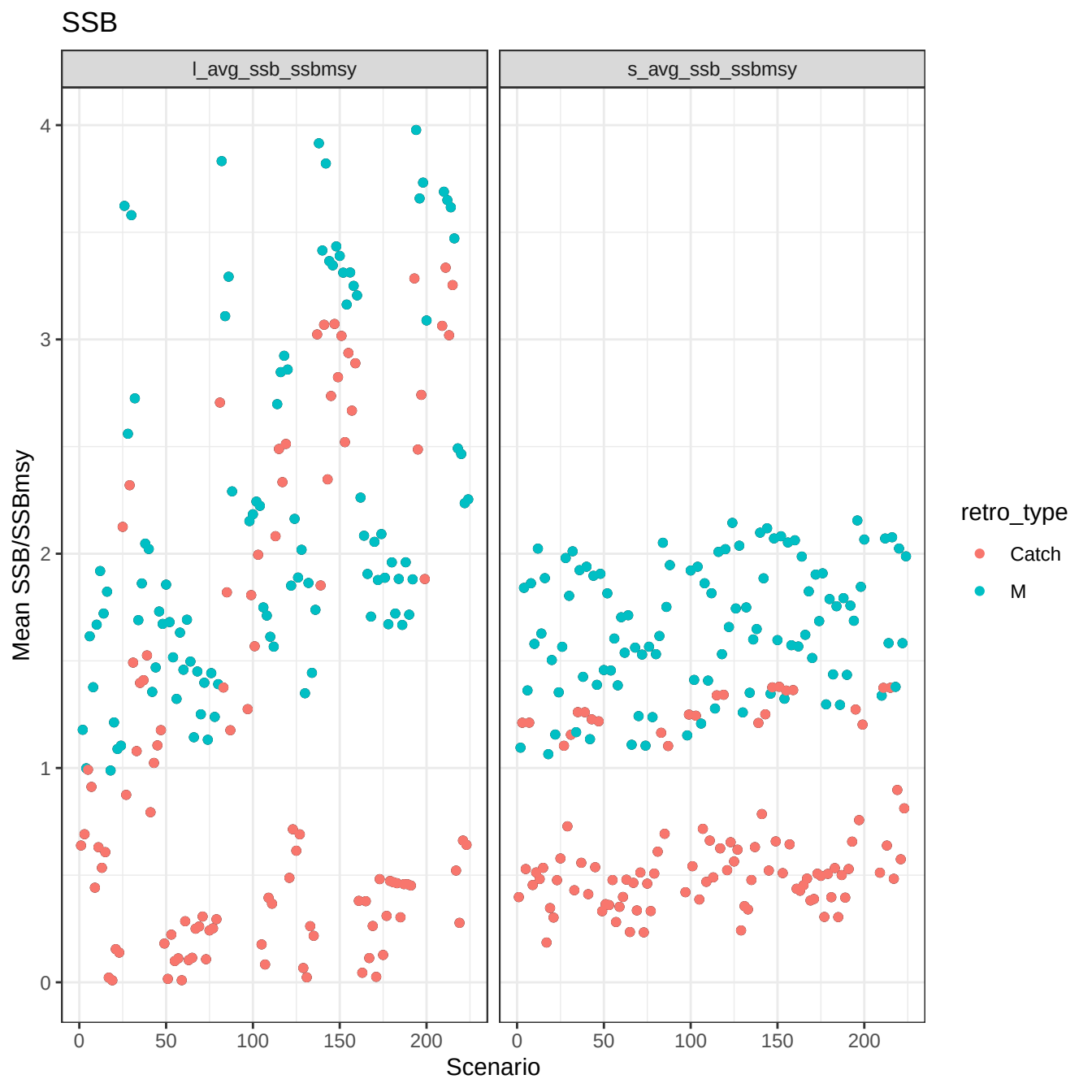

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
0
5
10
15
20
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

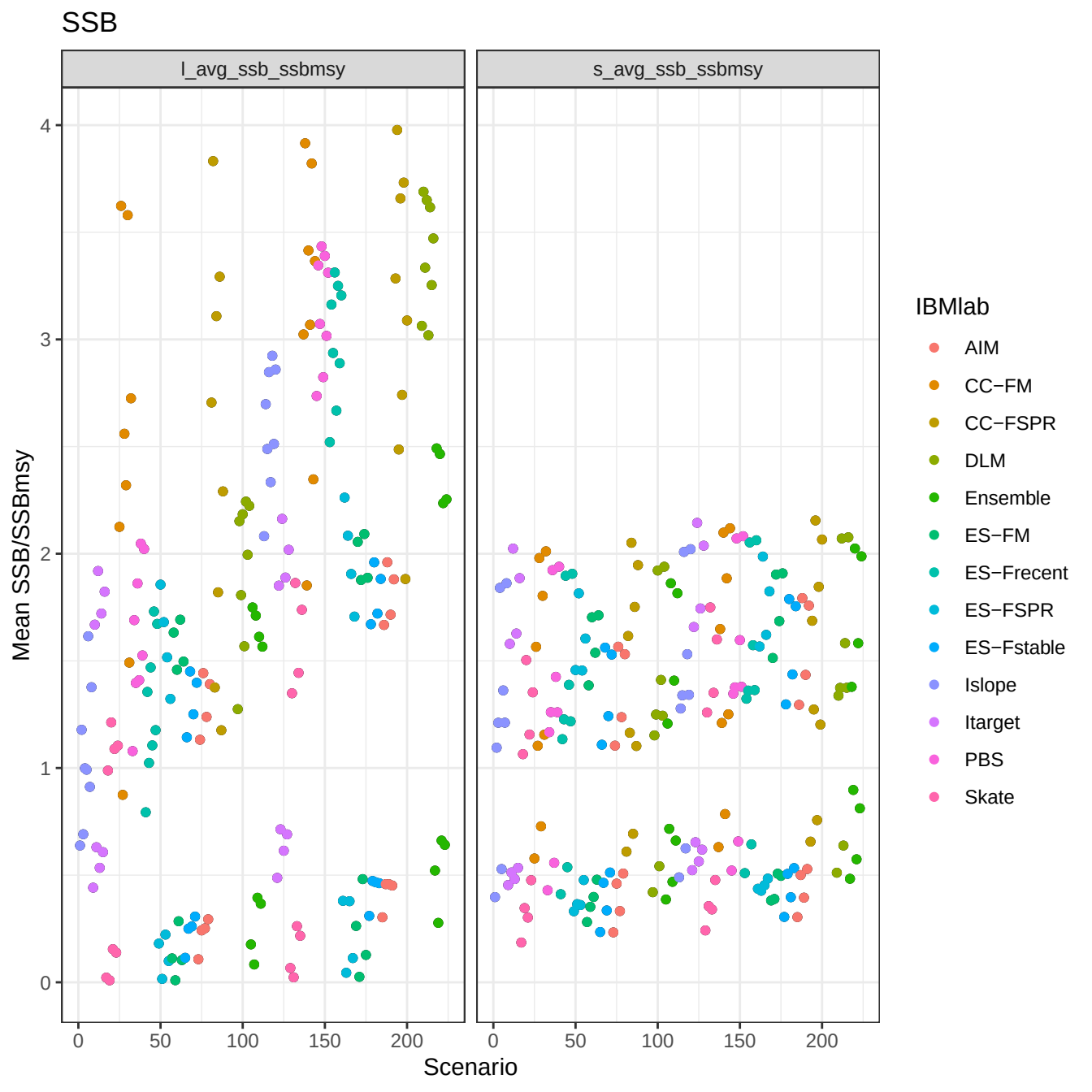

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
factor(Fhist)
1
2
0
5
10
15
20
0
50
100
150
200

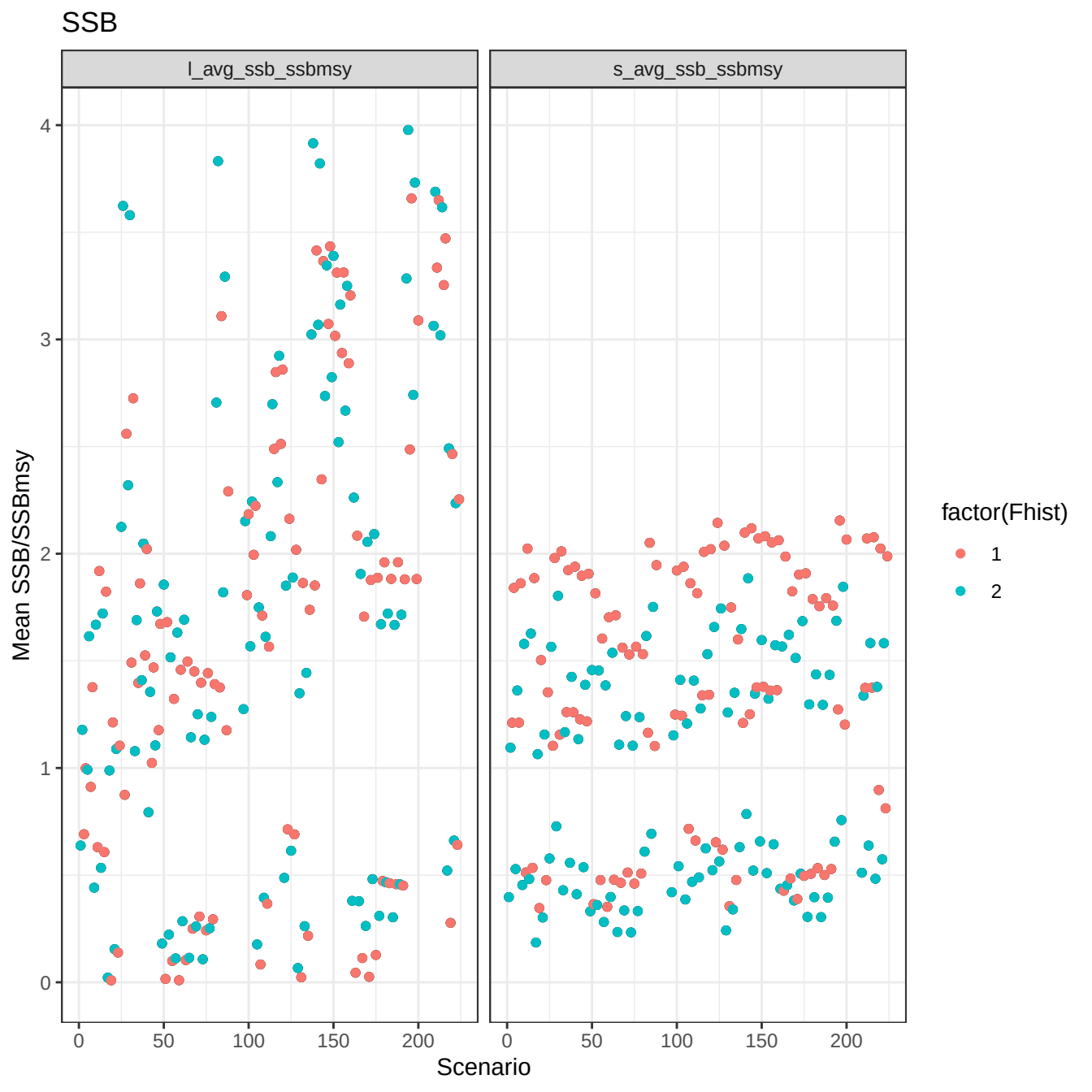

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
factor(n_selblocks)
1
2

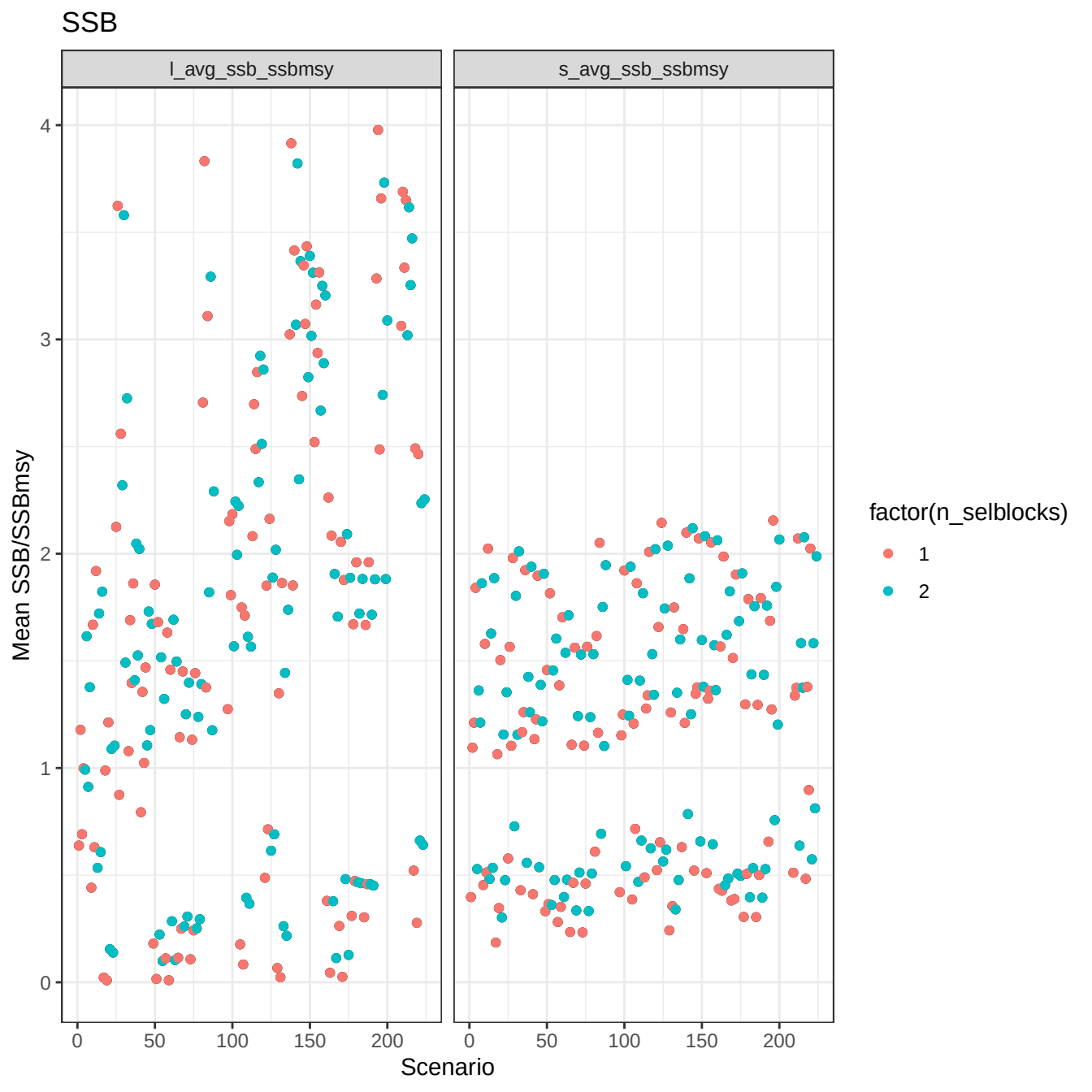

SSB
l_n_ge_bmsy
l_n_less_01_bmsy
l_n_less_05_bmsy
s_n_ge_bmsy
s_n_less_01_bmsy
s_n_less_05_bmsy
Mean Number of Years
Scenario
0
5
10
15
20
0
50
100
150
200
factor(catch.mult)
0.75
1

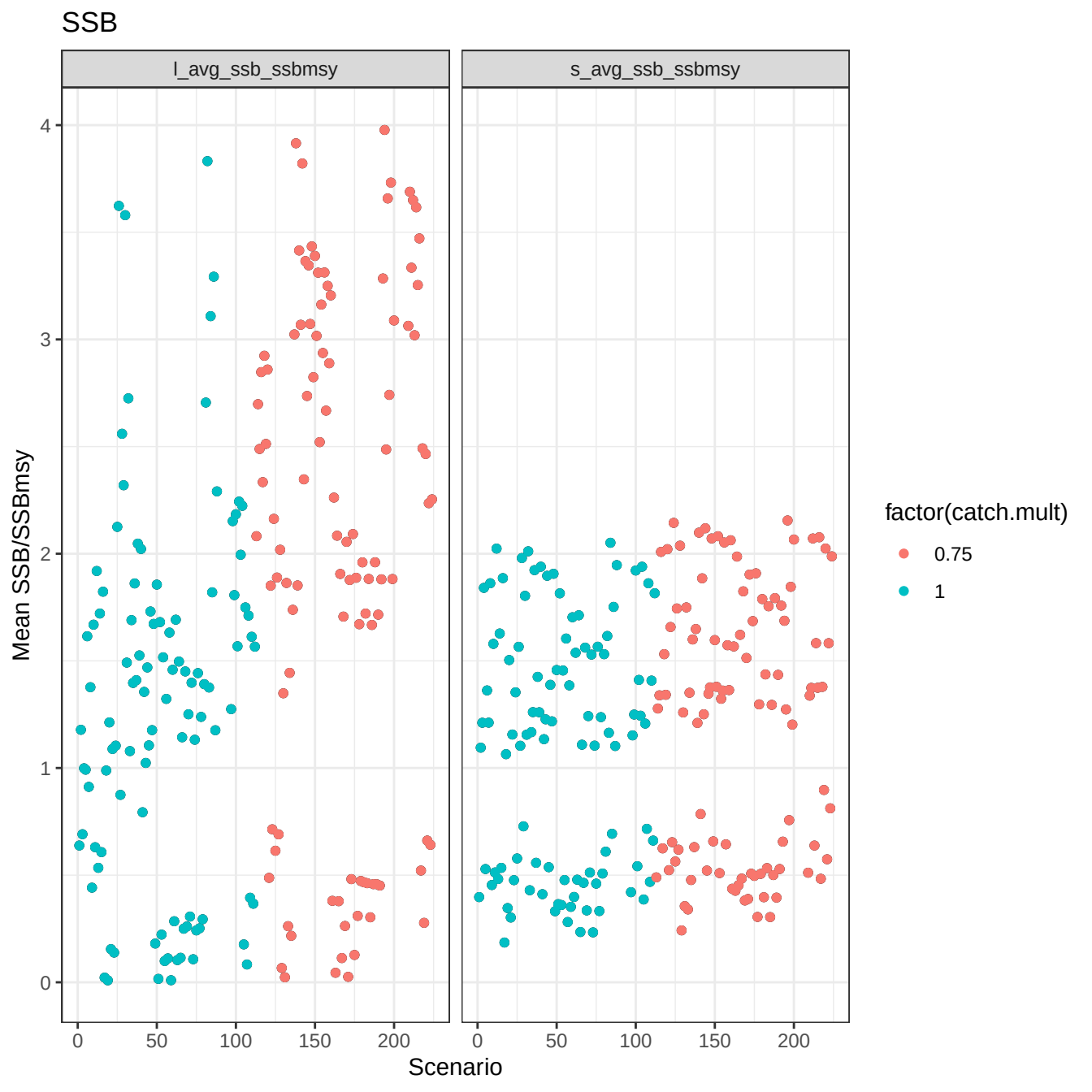

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
0
1
2
3
4
0
50
100
150
200
Scenario

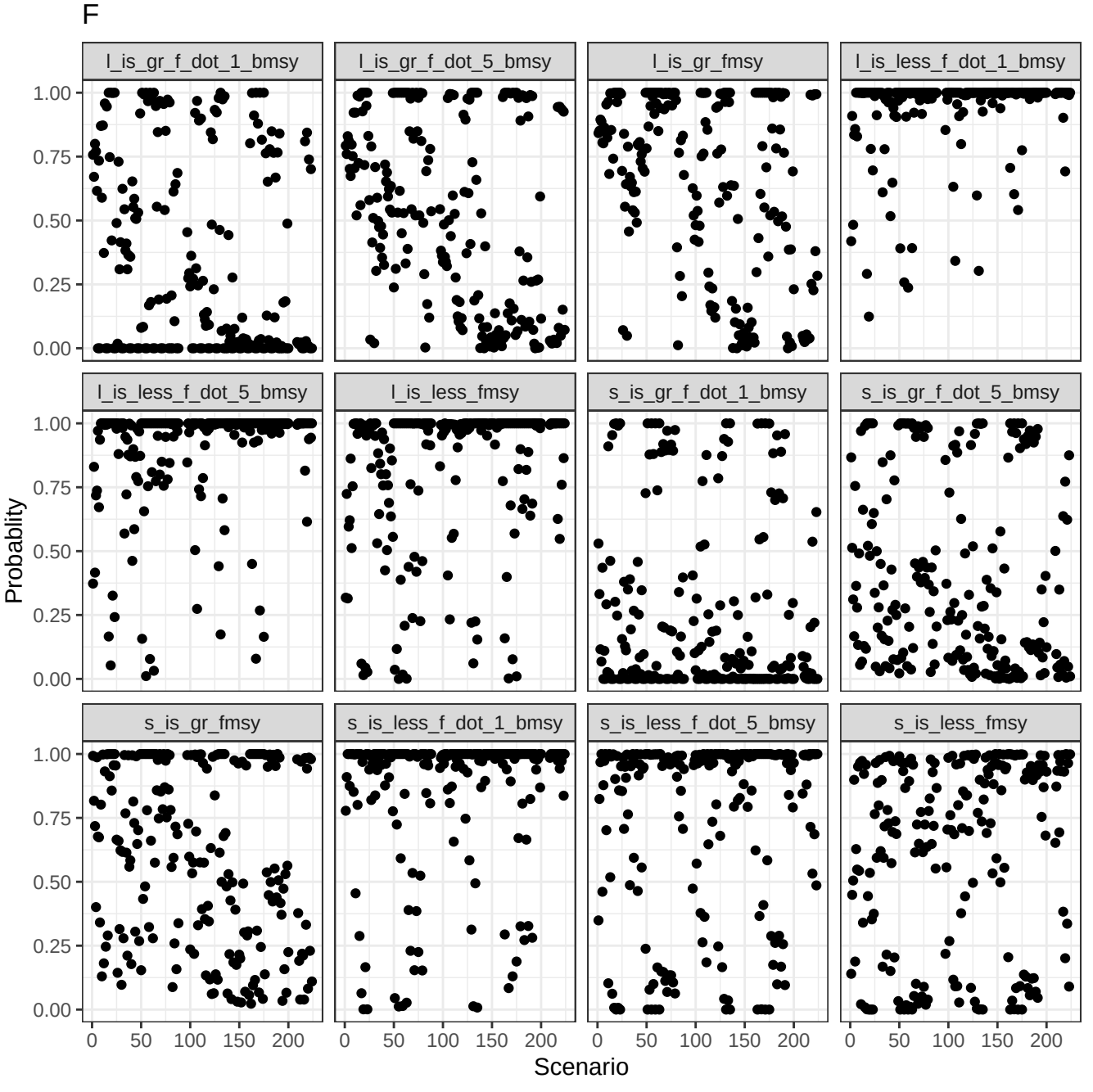

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
Scenario
retro_type
Catch
M
0
1
2
3
4
0
50
100
150
200

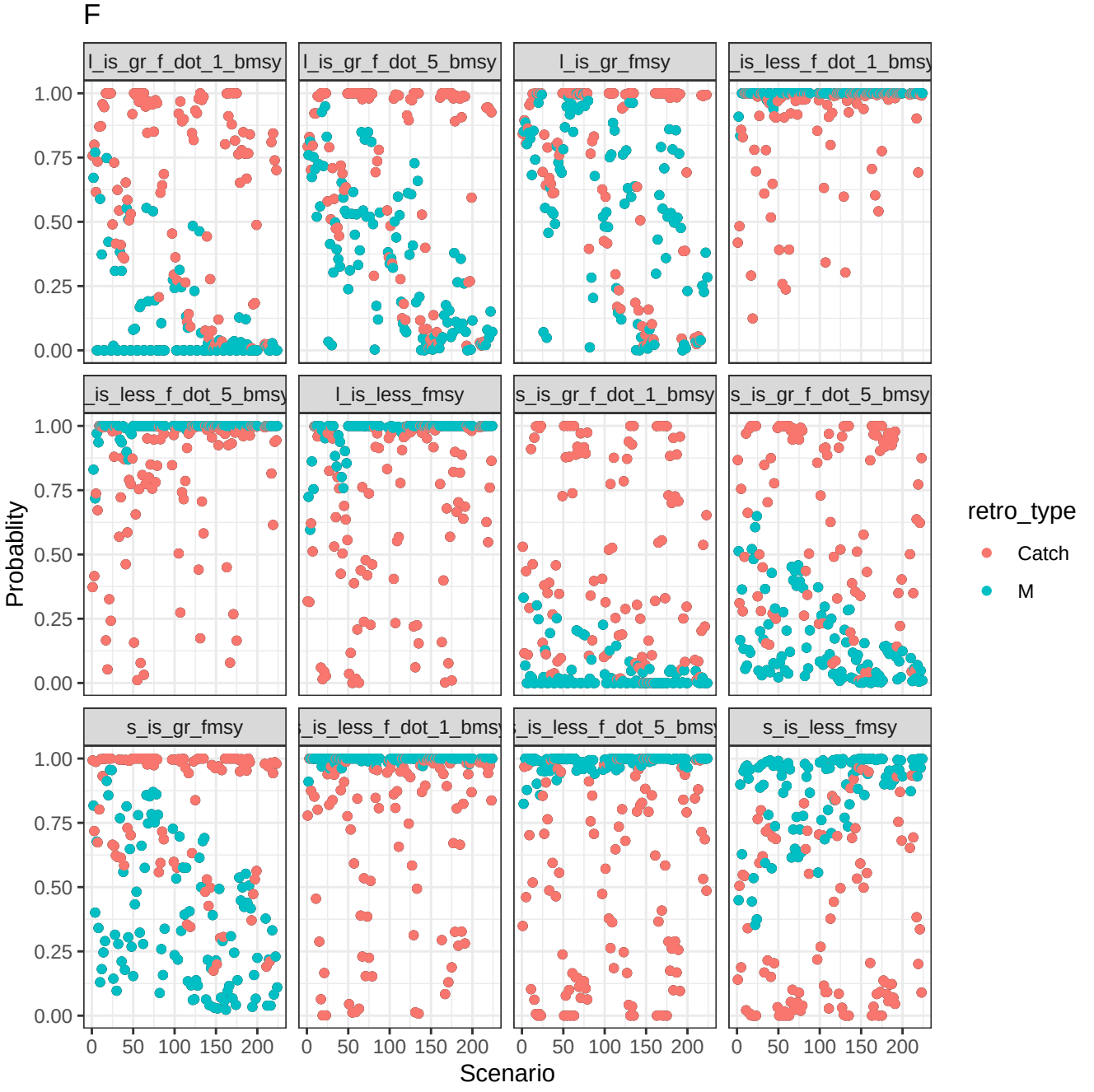

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
Scenario
0
1
2
3
4
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

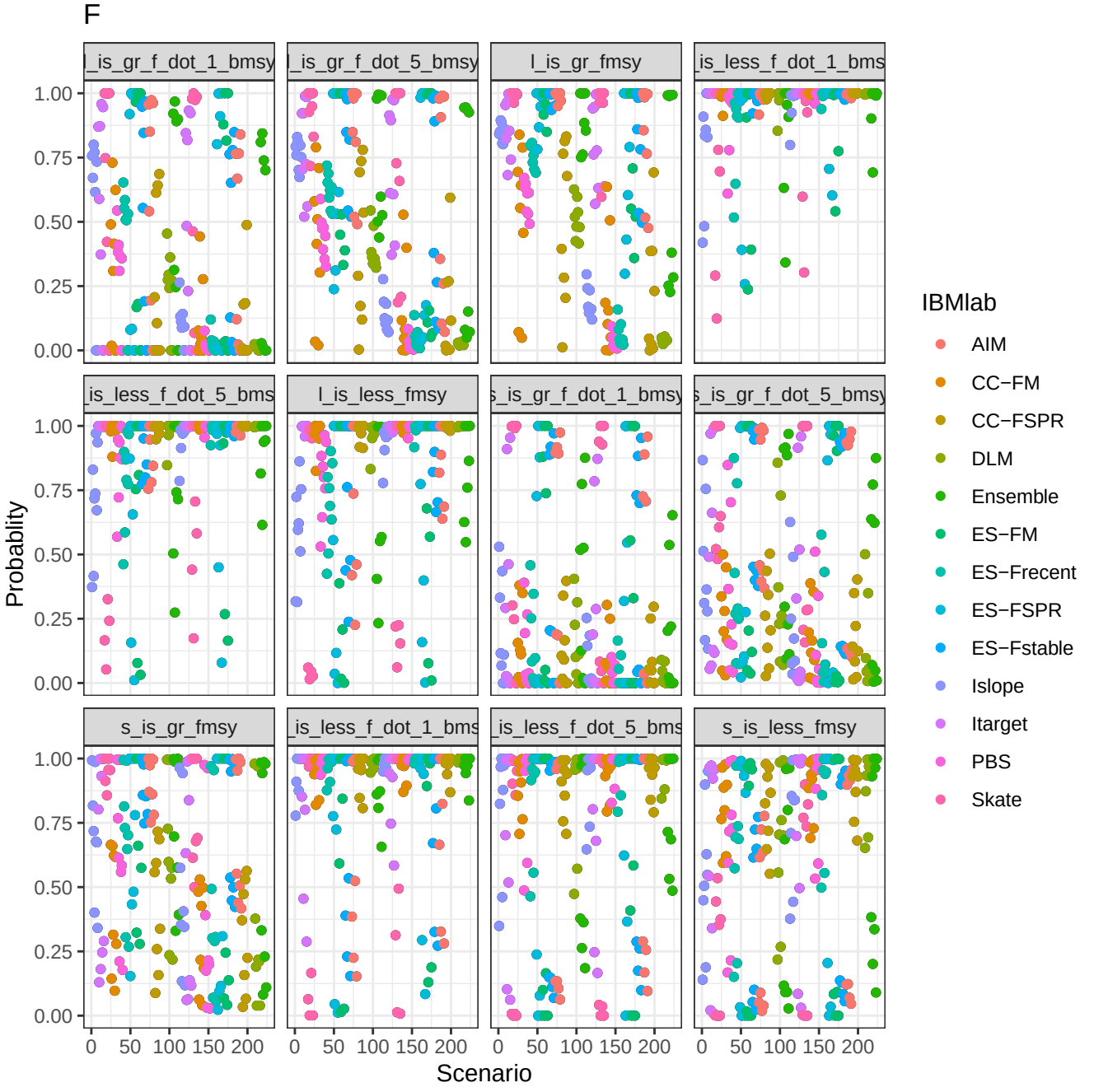

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
Scenario
factor(Fhist)
1
2
0
1
2
3
4
0
50
100
150
200

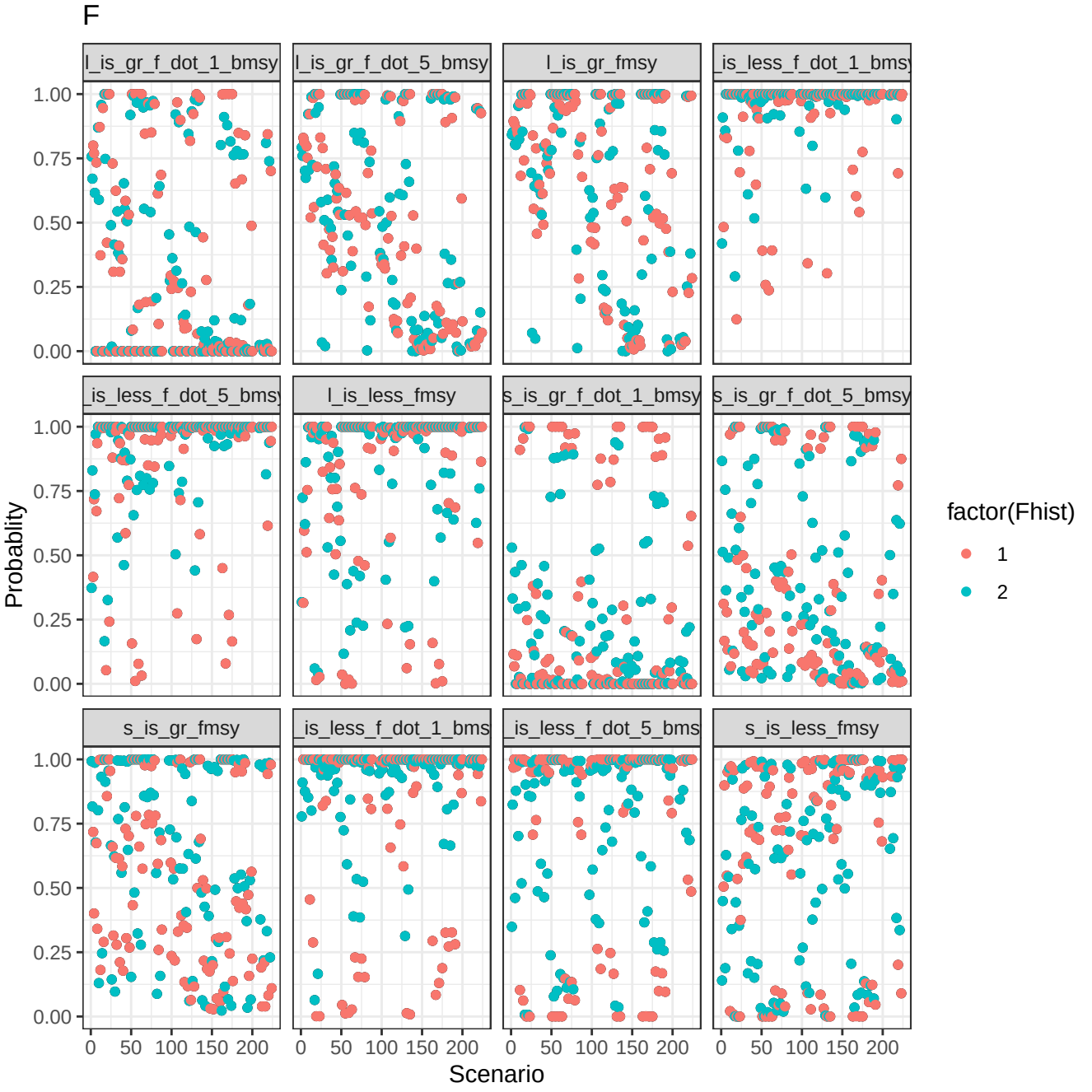

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
Scenario
factor(n_selblocks)
1
2
0
1
2
3
4
0
50
100
150
200

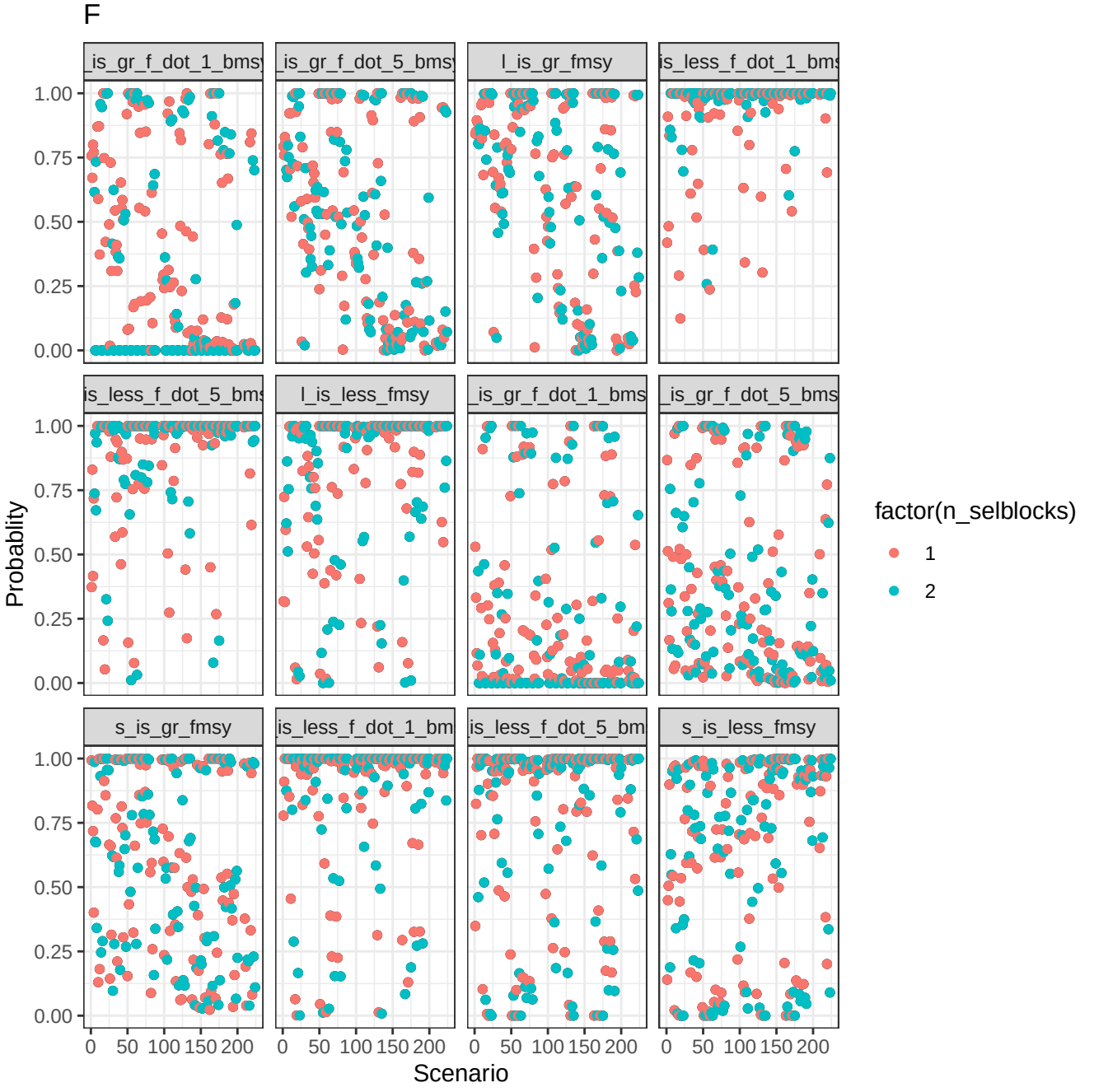

SSB
l_avg_ssb_ssbmsy
s_avg_ssb_ssbmsy
Mean SSB/SSBmsy
Scenario
factor(catch.mult)
0.75
1
0
1
2
3
4
0
50
100
150
200

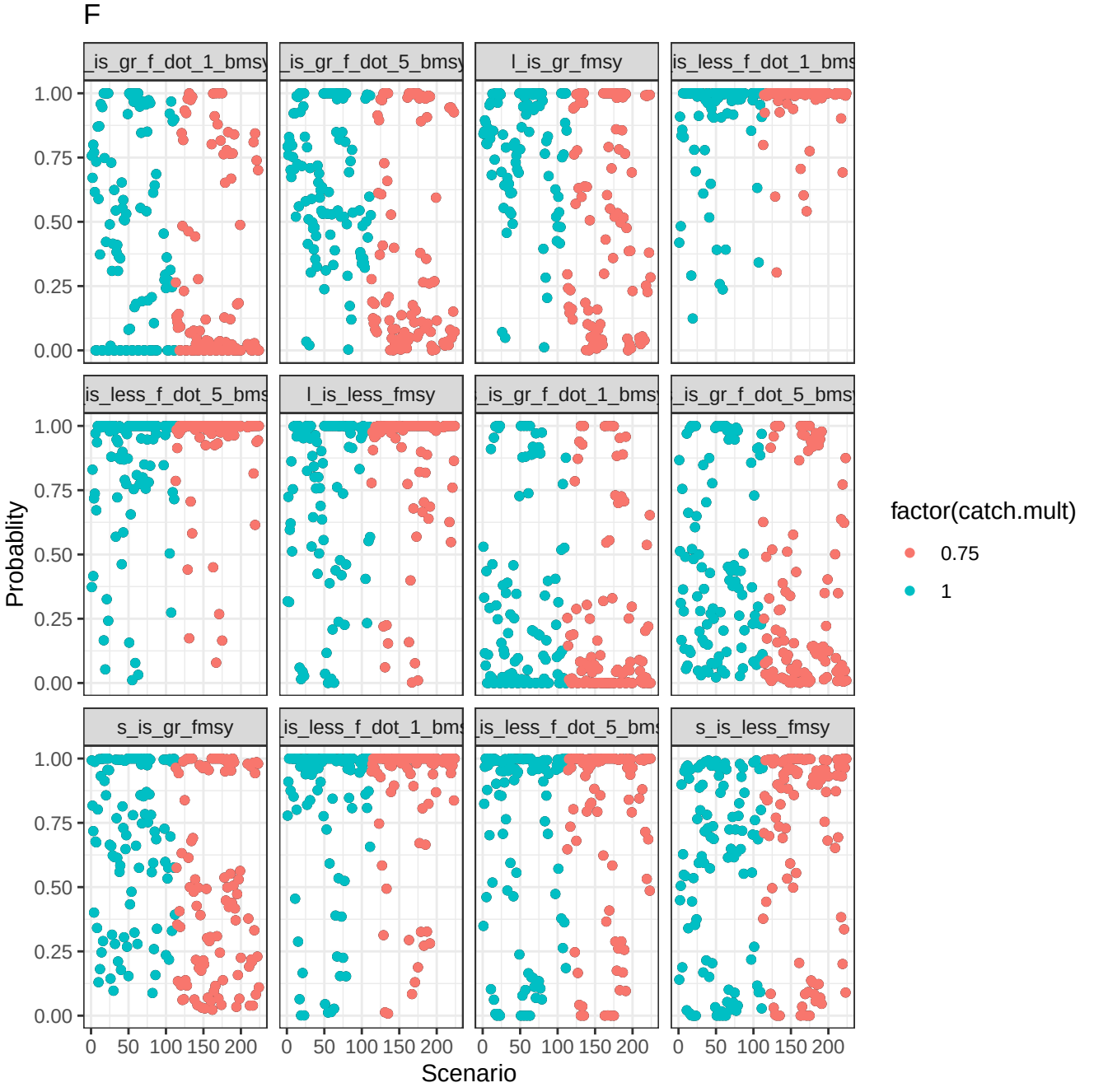

F
l_is_gr_f_dot_1_bmsy
l_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
l_is_less_f_dot_1_bmsy
l_is_less_f_dot_5_bmsy
l_is_less_fmsy
s_is_gr_f_dot_1_bmsy
s_is_gr_f_dot_5_bmsy
s_is_gr_fmsy
s_is_less_f_dot_1_bmsy
s_is_less_f_dot_5_bmsy
s_is_less_fmsy
Probablity
0.00
0.25
0.50
0.75
1.00
0
50
100
150
200
Scenario


F
l_is_gr_f_dot_1_bmsy
l_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
_is_less_f_dot_1_bmsy
_is_less_f_dot_5_bmsy
l_is_less_fmsy
s_is_gr_f_dot_1_bmsy
s_is_gr_f_dot_5_bmsy
s_is_gr_fmsy
_is_less_f_dot_1_bmsy
_is_less_f_dot_5_bmsy
s_is_less_fmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
retro_type
Catch
M

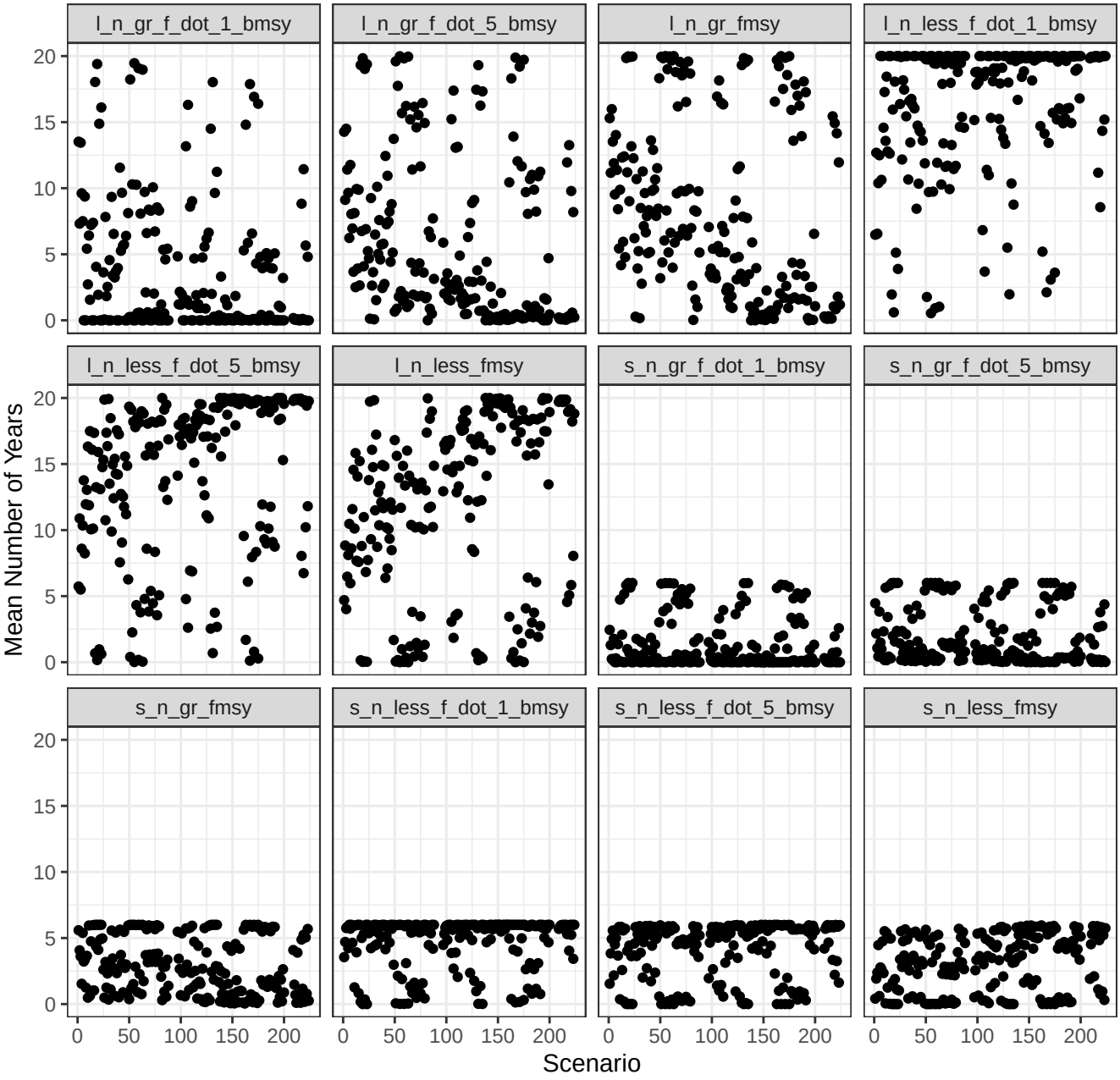

F
l_is_gr_f_dot_1_bmsy
l_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
_is_less_f_dot_1_bms
_is_less_f_dot_5_bms
l_is_less_fmsy
s_is_gr_f_dot_1_bmsy
s_is_gr_f_dot_5_bmsy
s_is_gr_fmsy
_is_less_f_dot_1_bms
_is_less_f_dot_5_bms
s_is_less_fmsy
Probablity
Scenario
0.00
0.25
0.50
0.75
1.00
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

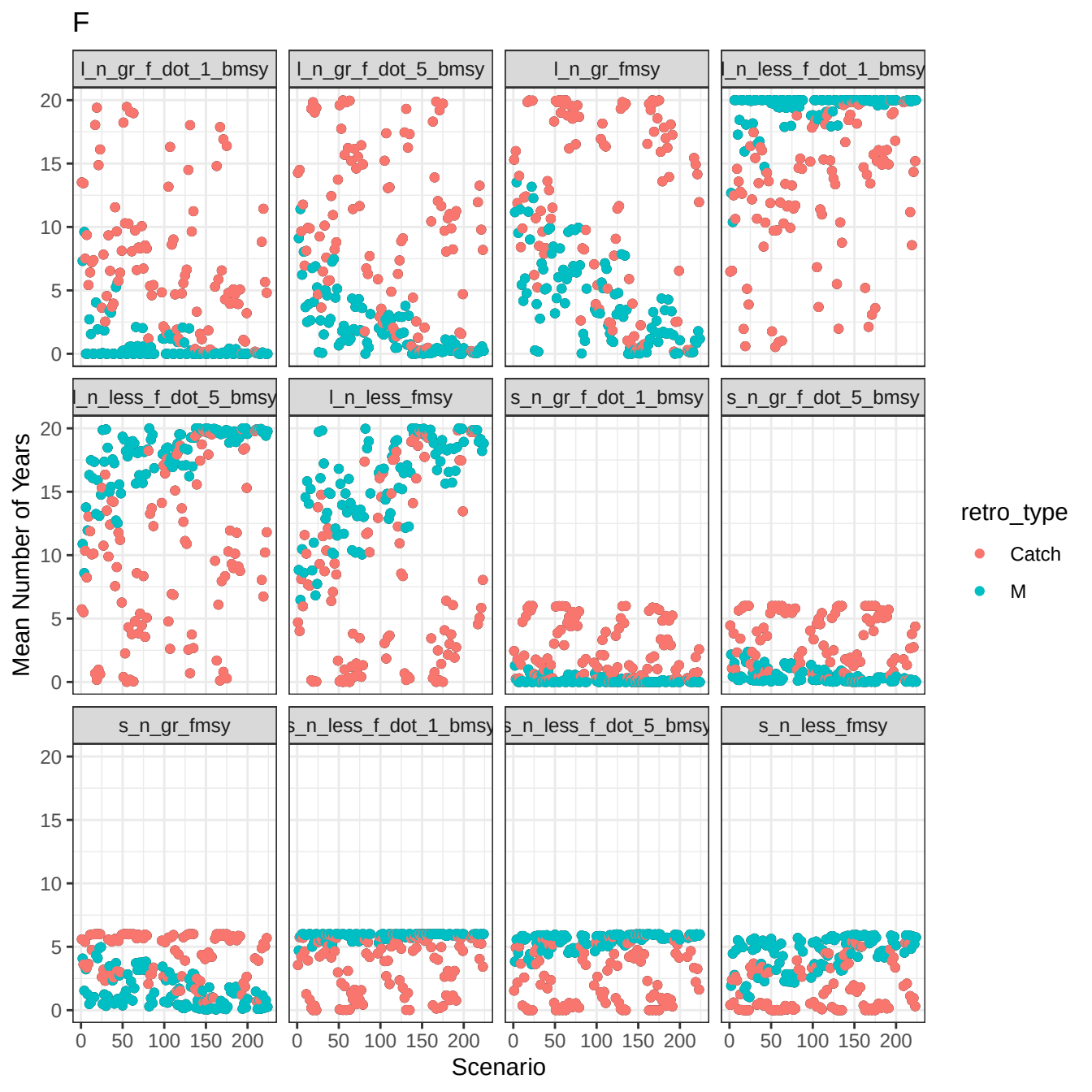

F
l_is_gr_f_dot_1_bmsy
l_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
_is_less_f_dot_1_bmsy
_is_less_f_dot_5_bmsy
l_is_less_fmsy
s_is_gr_f_dot_1_bmsy
s_is_gr_f_dot_5_bmsy
s_is_gr_fmsy
_is_less_f_dot_1_bms
_is_less_f_dot_5_bms
s_is_less_fmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(Fhist)
1
2

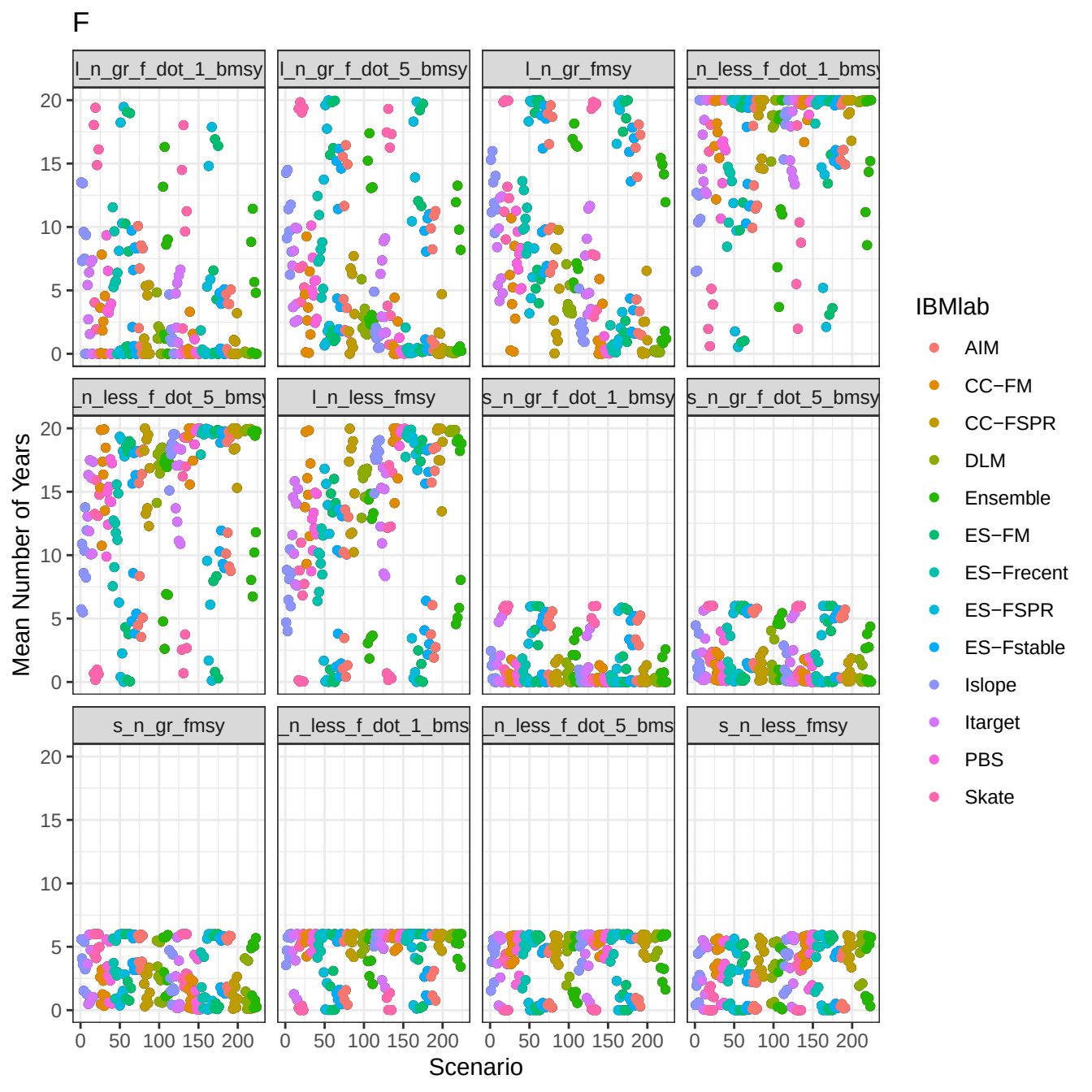

F
_is_gr_f_dot_1_bmsy
_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
is_less_f_dot_1_bms
is_less_f_dot_5_bms
l_is_less_fmsy
_is_gr_f_dot_1_bms
_is_gr_f_dot_5_bms
s_is_gr_fmsy
is_less_f_dot_1_bm
is_less_f_dot_5_bm
s_is_less_fmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(n_selblocks)
1
2

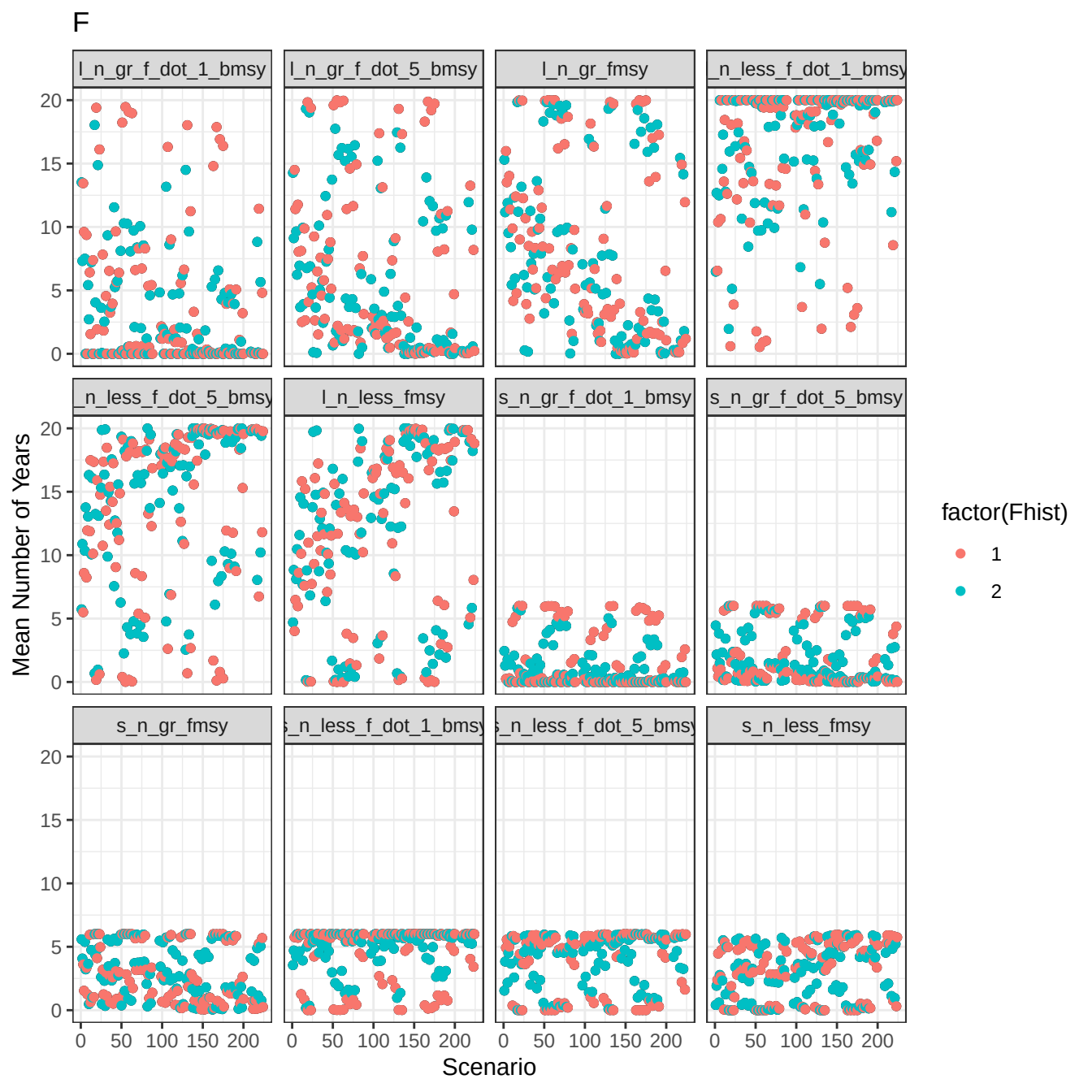

F
_is_gr_f_dot_1_bmsy
_is_gr_f_dot_5_bmsy
l_is_gr_fmsy
is_less_f_dot_1_bms
is_less_f_dot_5_bms
l_is_less_fmsy
_is_gr_f_dot_1_bms
_is_gr_f_dot_5_bms
s_is_gr_fmsy
is_less_f_dot_1_bms
is_less_f_dot_5_bms
s_is_less_fmsy
Probablity
1.00
0.75
0.50
0.25
0.00
0
50
100
150
200
Scenario
factor(catch.mult)
0.75
1

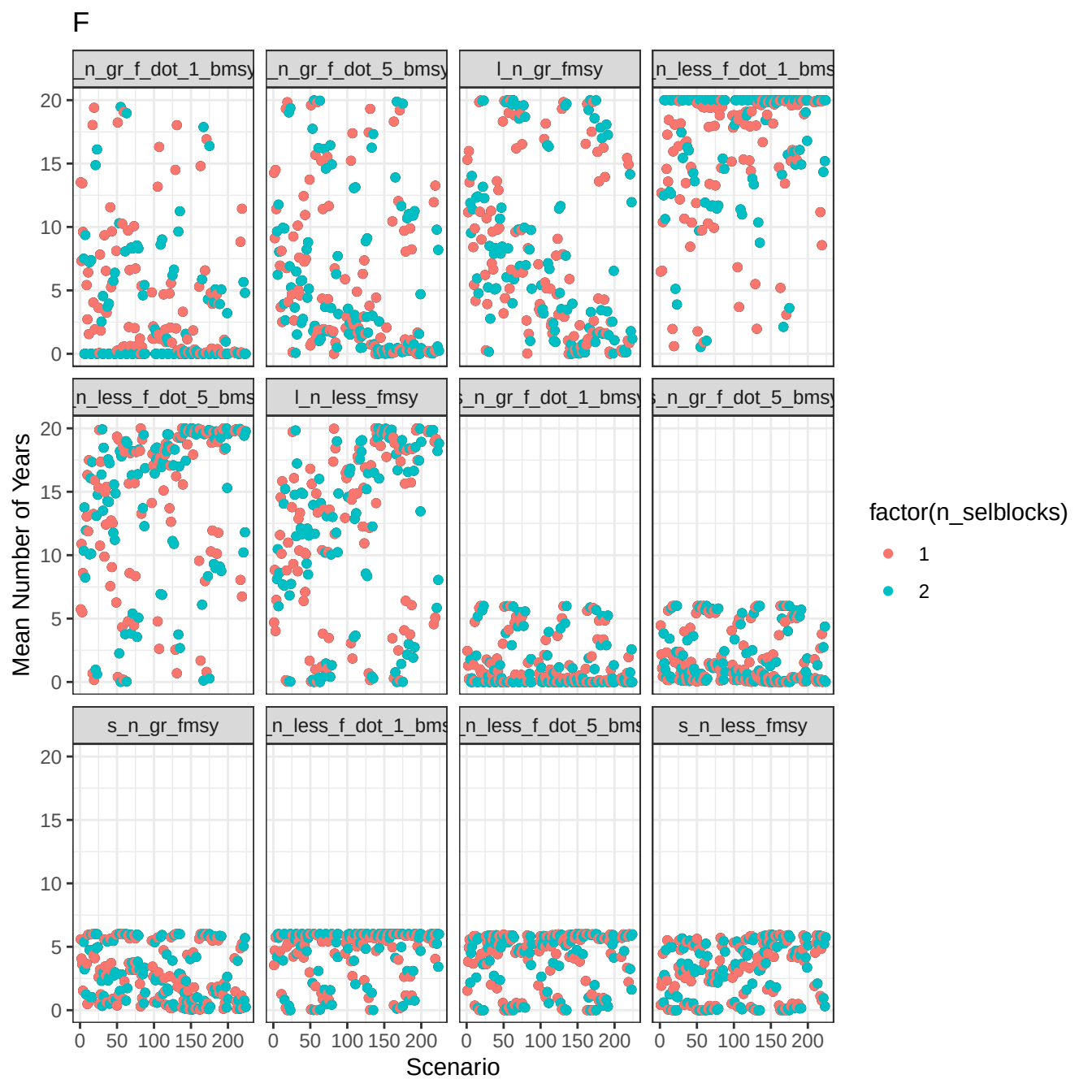
F

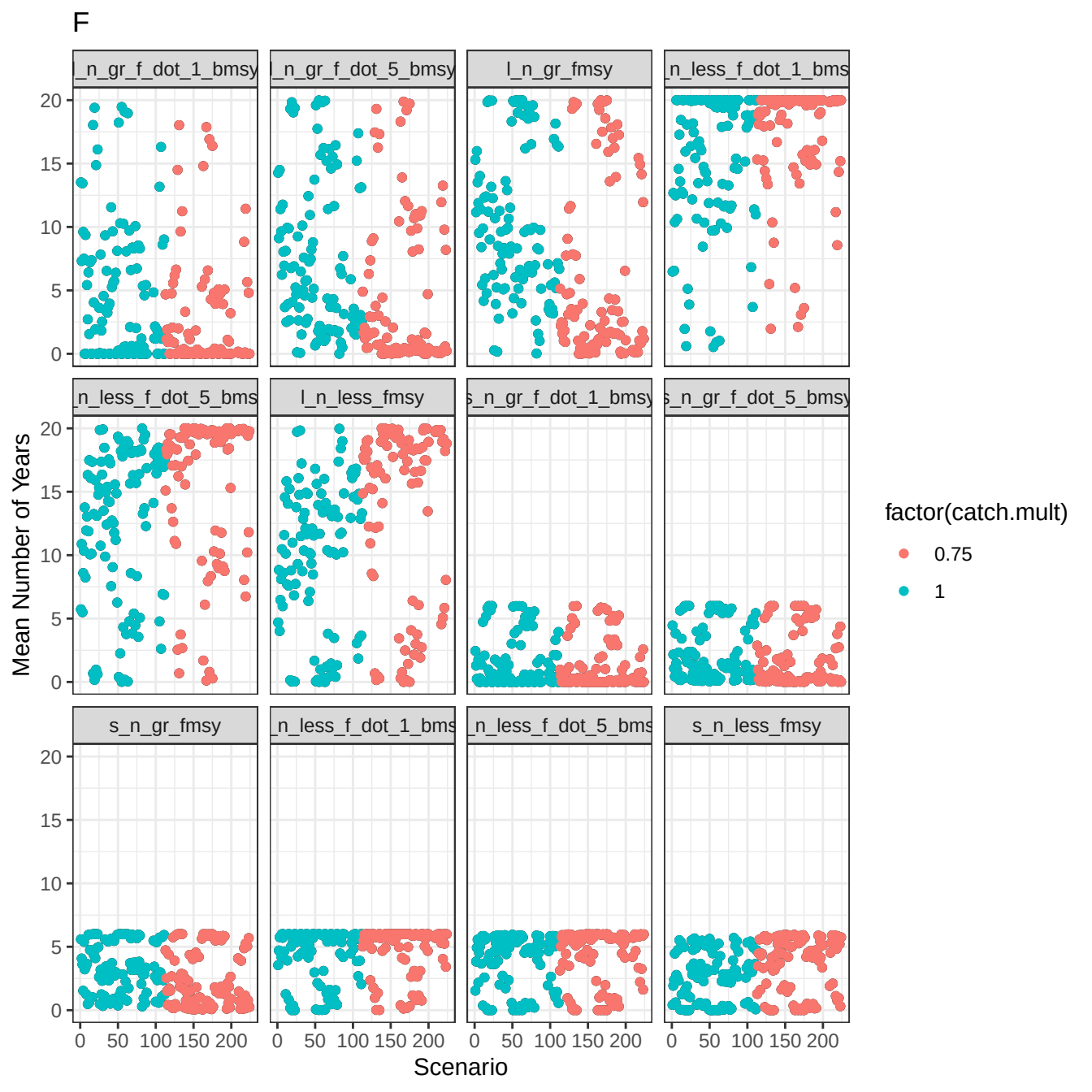

l_n_gr_f_dot_1_bmsy
l_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
l_n_less_f_dot_1_bmsy
l_n_less_f_dot_5_bmsy
l_n_less_fmsy
s_n_gr_f_dot_1_bmsy
s_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
s_n_less_f_dot_1_bmsy
s_n_less_f_dot_5_bmsy
s_n_less_fmsy
Mean Number of Years
0
5
10
15
20
0
50
100
150
200
Scenario


F
l_n_gr_f_dot_1_bmsy
l_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
l_n_less_f_dot_1_bmsy
l_n_less_f_dot_5_bmsy
l_n_less_fmsy
s_n_gr_f_dot_1_bmsy
s_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
s_n_less_f_dot_1_bmsy
s_n_less_f_dot_5_bmsy
s_n_less_fmsy
Mean Number of Years
Scenario
retro_type
Catch
M

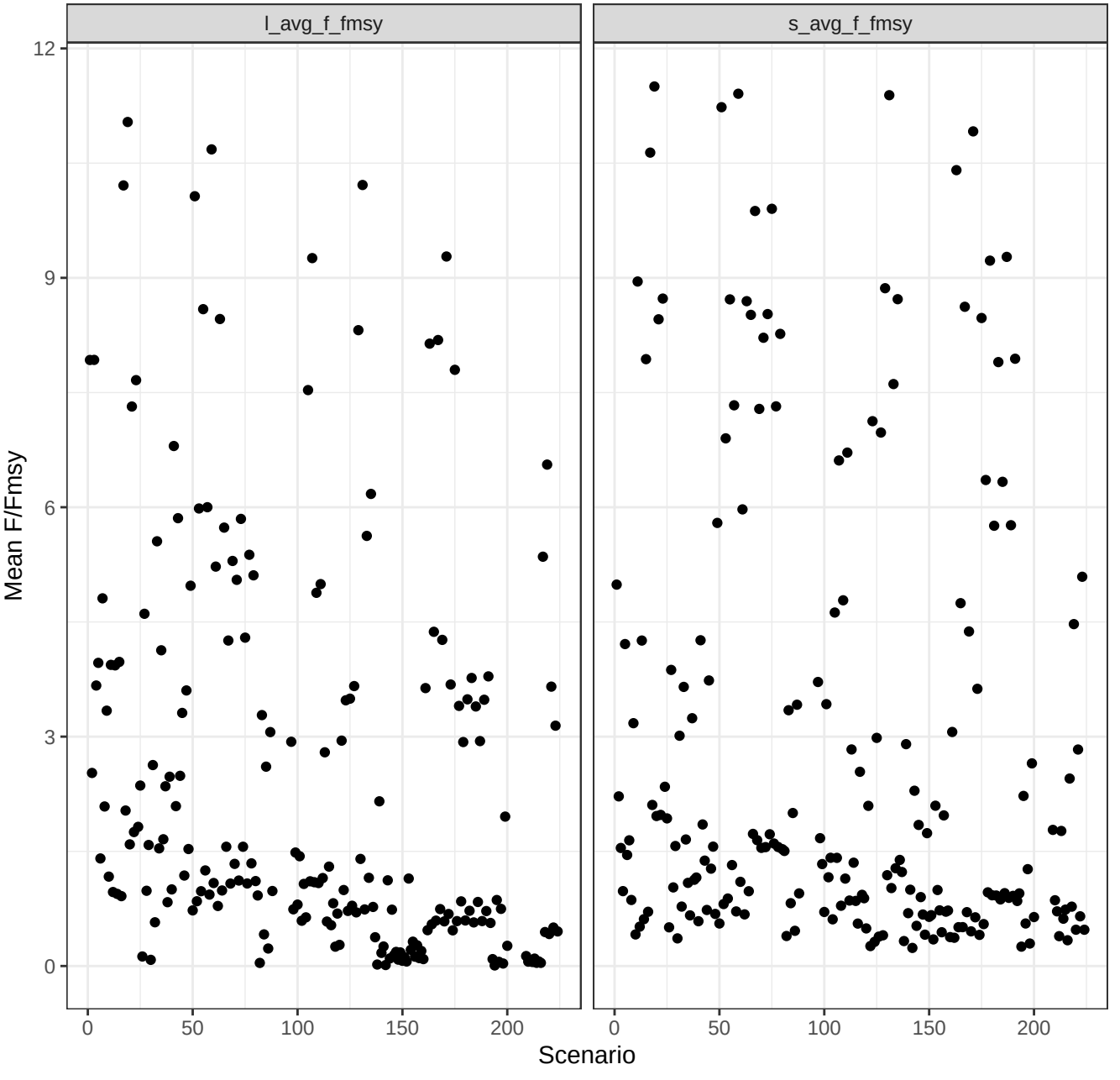

F
l_n_gr_f_dot_1_bmsy
l_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
_n_less_f_dot_1_bmsy
_n_less_f_dot_5_bmsy
l_n_less_fmsy
s_n_gr_f_dot_1_bmsy
s_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
_n_less_f_dot_1_bms
_n_less_f_dot_5_bms
s_n_less_fmsy
Mean Number of Years
Scenario
0
5
10
15
20
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

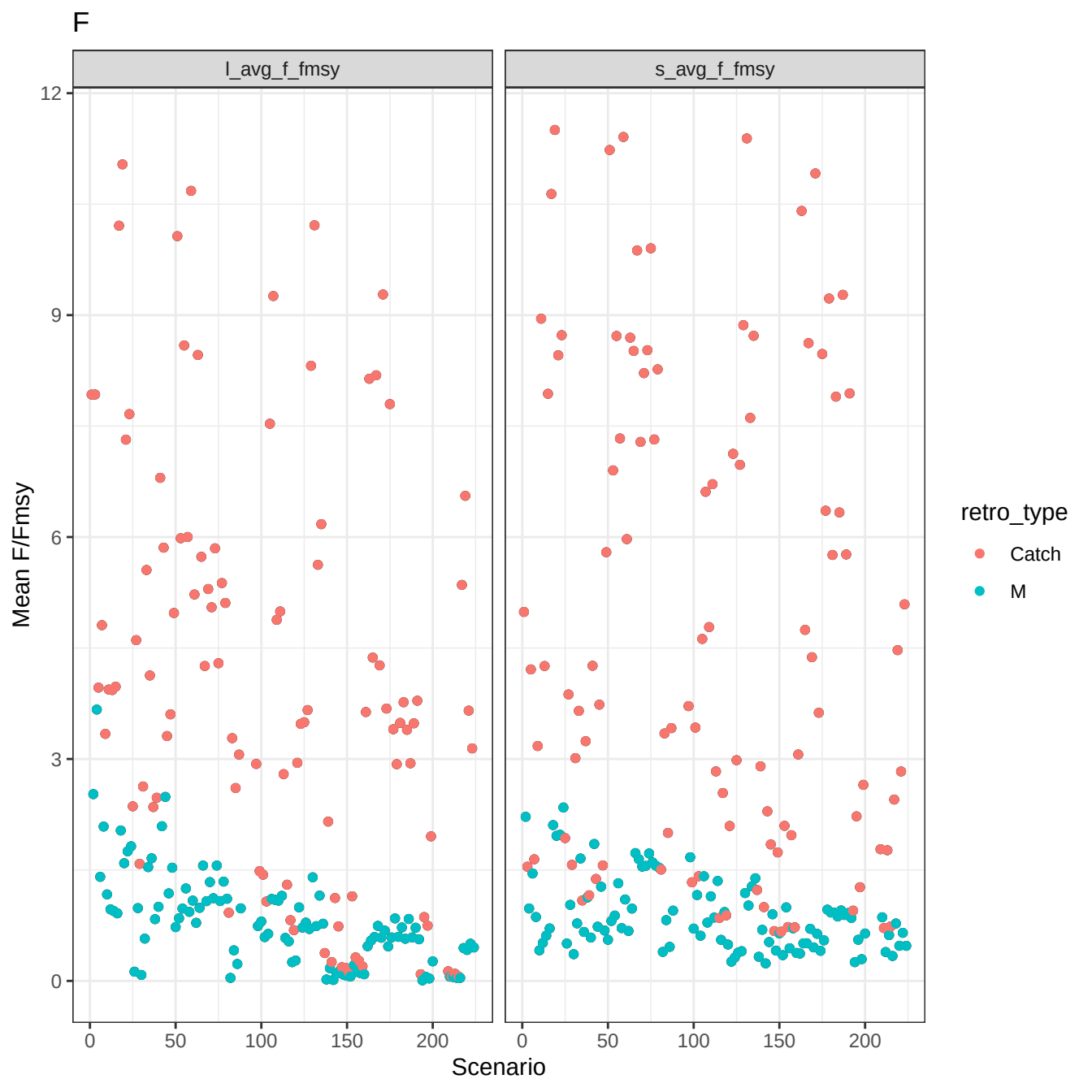

F
l_n_gr_f_dot_1_bmsy
l_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
_n_less_f_dot_1_bmsy
_n_less_f_dot_5_bmsy
l_n_less_fmsy
s_n_gr_f_dot_1_bmsy
s_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
s_n_less_f_dot_1_bmsy
s_n_less_f_dot_5_bmsy
s_n_less_fmsy
Mean Number of Years
Scenario
factor(Fhist)
1
2

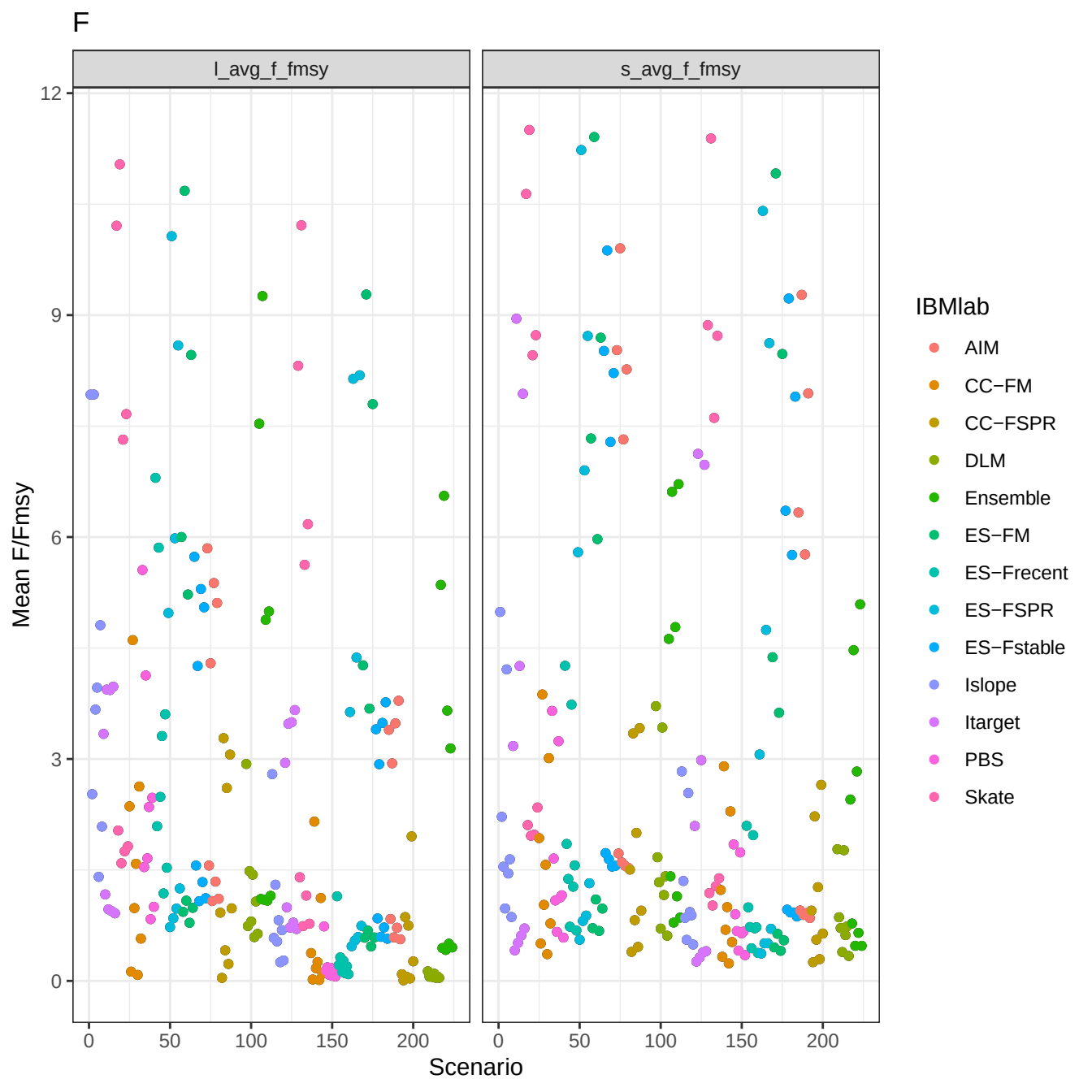

F
_n_gr_f_dot_1_bmsy
_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
n_less_f_dot_1_bms
n_less_f_dot_5_bms
l_n_less_fmsy
_n_gr_f_dot_1_bmsy
_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
_n_less_f_dot_1_bms
_n_less_f_dot_5_bms
s_n_less_fmsy
Mean Number of Years
Scenario
factor(n_selblocks)
1
2

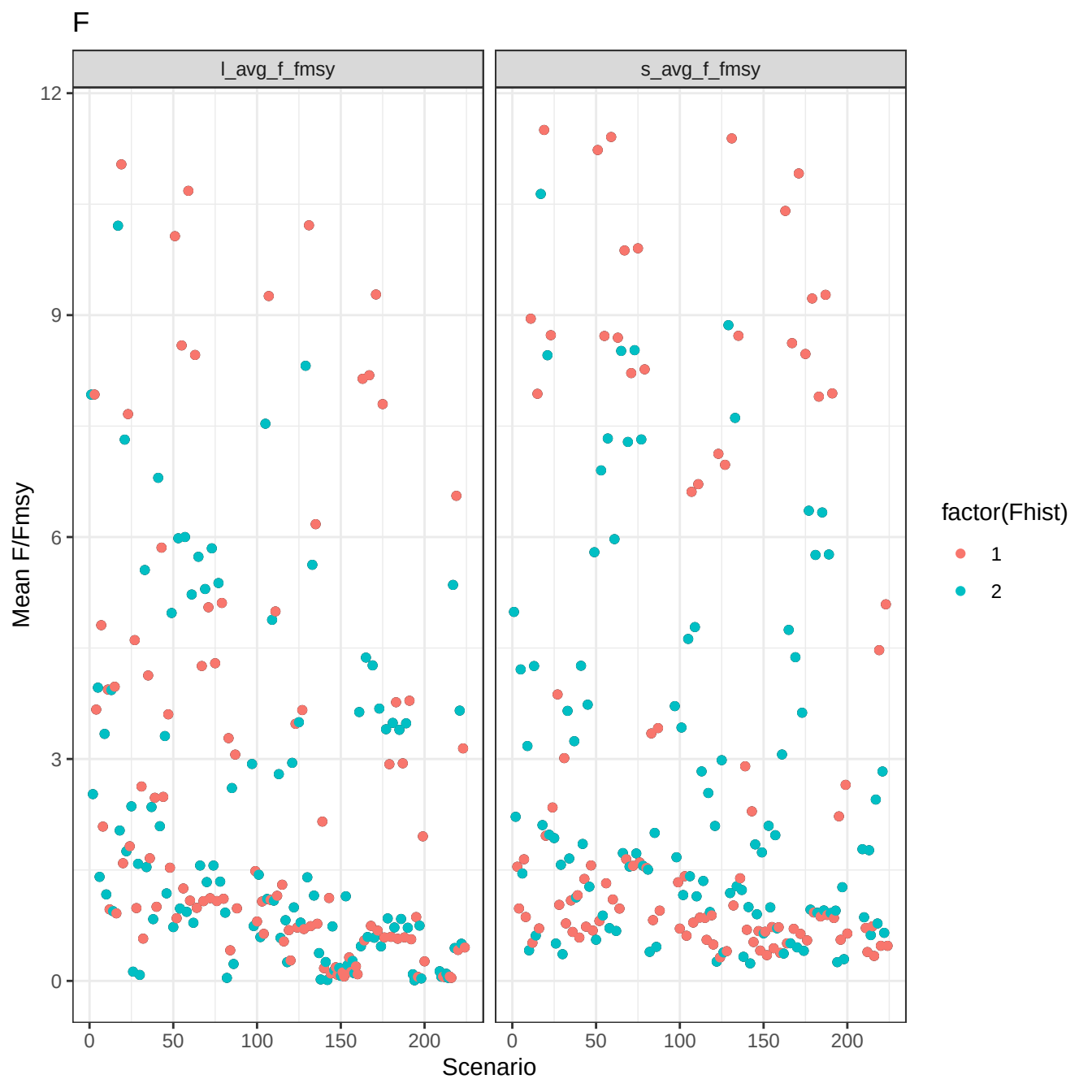

F
l_n_gr_f_dot_1_bmsy
l_n_gr_f_dot_5_bmsy
l_n_gr_fmsy
l_n_less_f_dot_1_bms
l_n_less_f_dot_5_bms
l_n_less_fmsy
s_n_gr_f_dot_1_bmsy
s_n_gr_f_dot_5_bmsy
s_n_gr_fmsy
l_n_less_f_dot_1_bms
l_n_less_f_dot_5_bms
s_n_less_fmsy
Mean Number of Years
Scenario
factor(catch.mult)
0.75
1

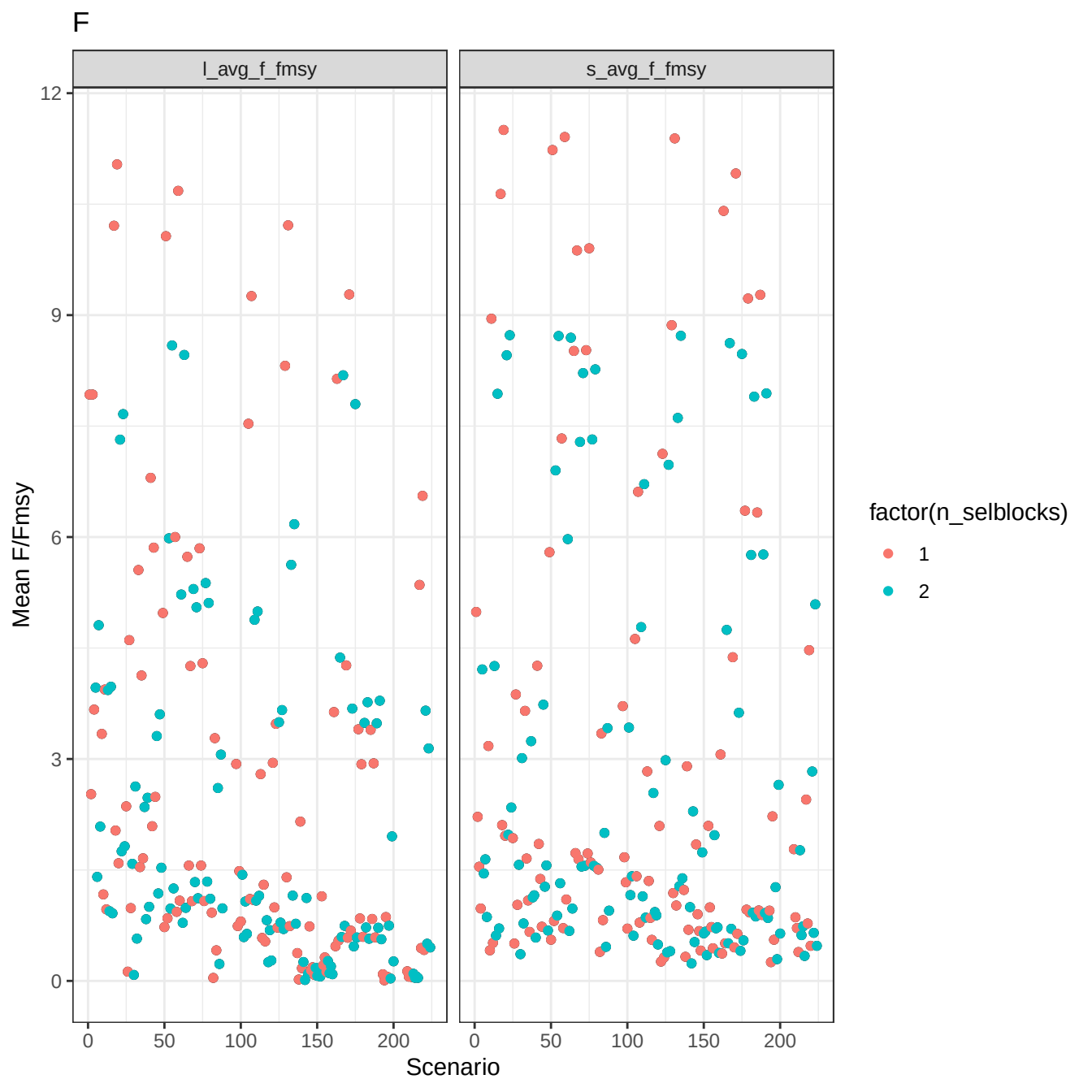
F

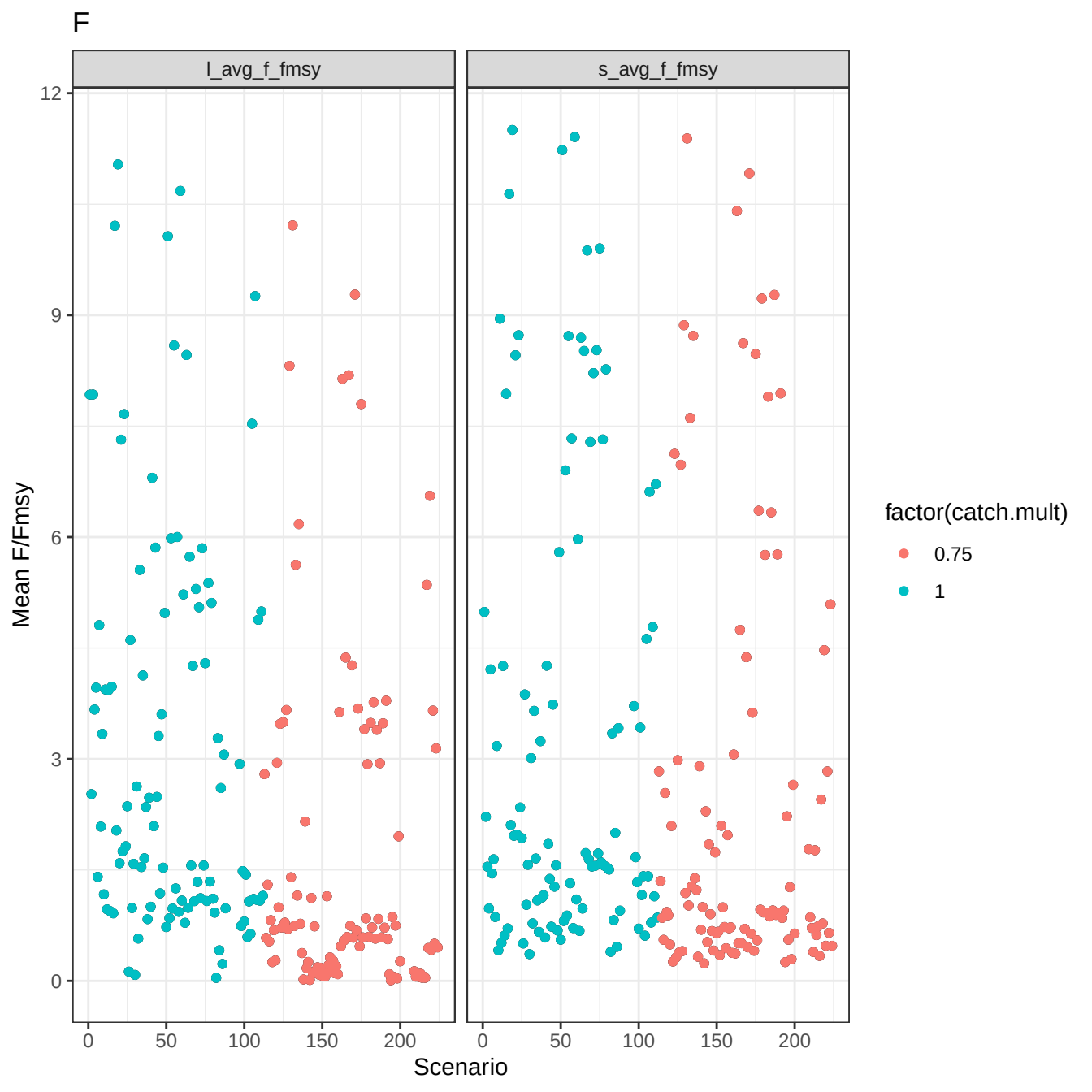

l_avg_f_fmsy
s_avg_f_fmsy
Mean F/Fmsy
12
9
6
3
0
0
50
100
150
200
Scenario

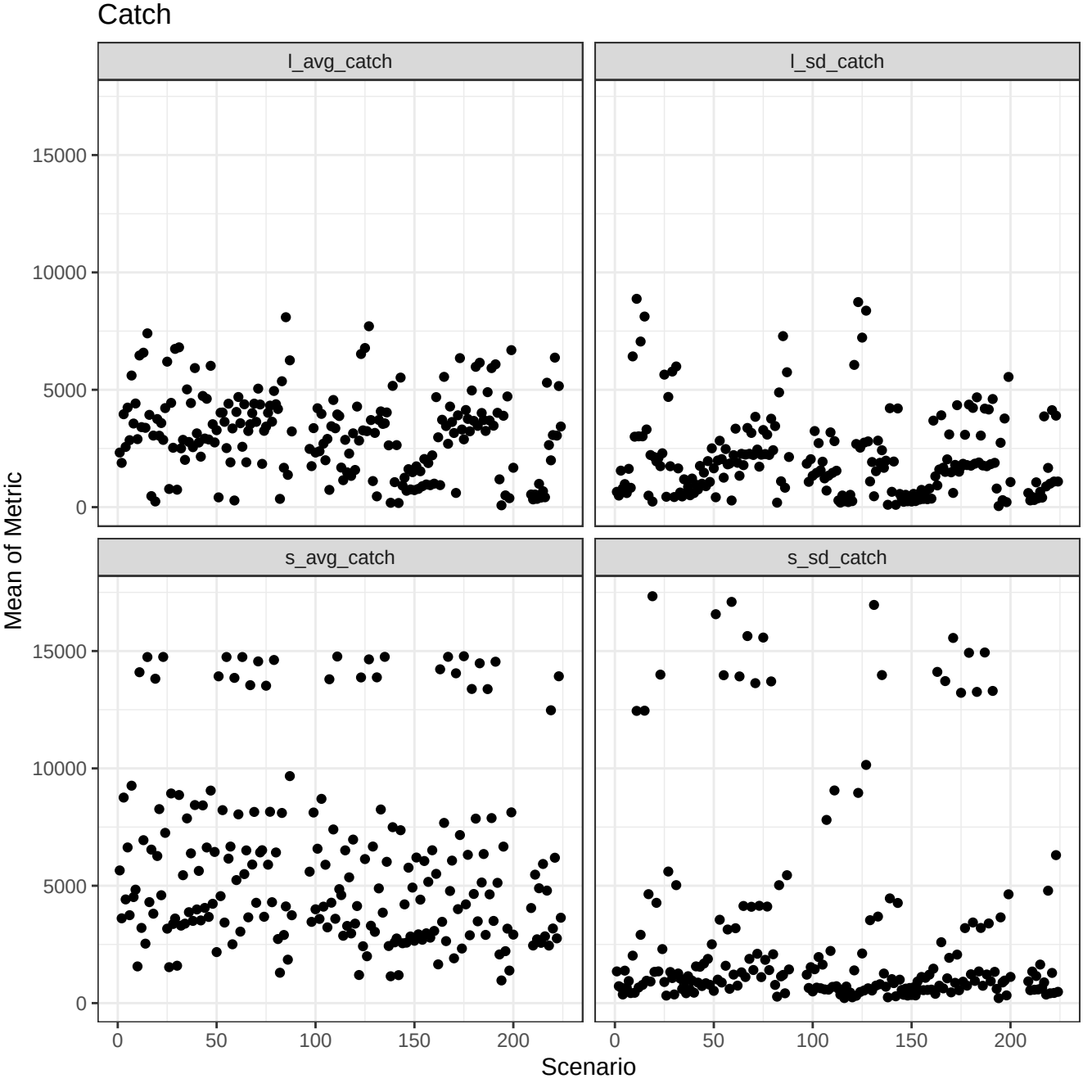

F
l_avg_f_fmsy
s_avg_f_fmsy
Mean F/Fmsy
12
9
6
3
0
0
50
100
150
200
Scenario
retro_type
Catch
M

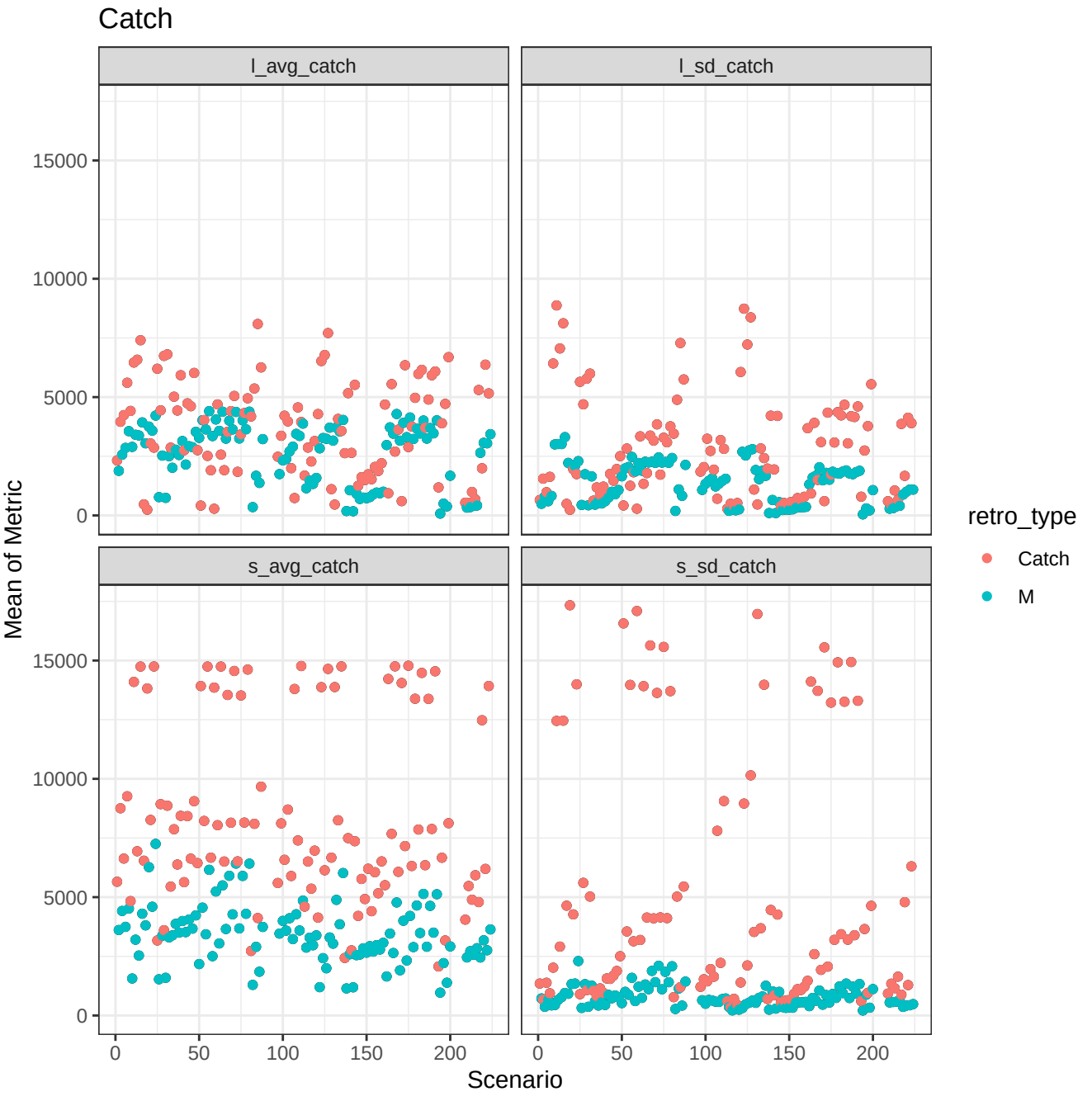

F
l_avg_f_fmsy
s_avg_f_fmsy
Mean F/Fmsy
12
9
6
3
0
0
50
100
150
200
Scenario
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

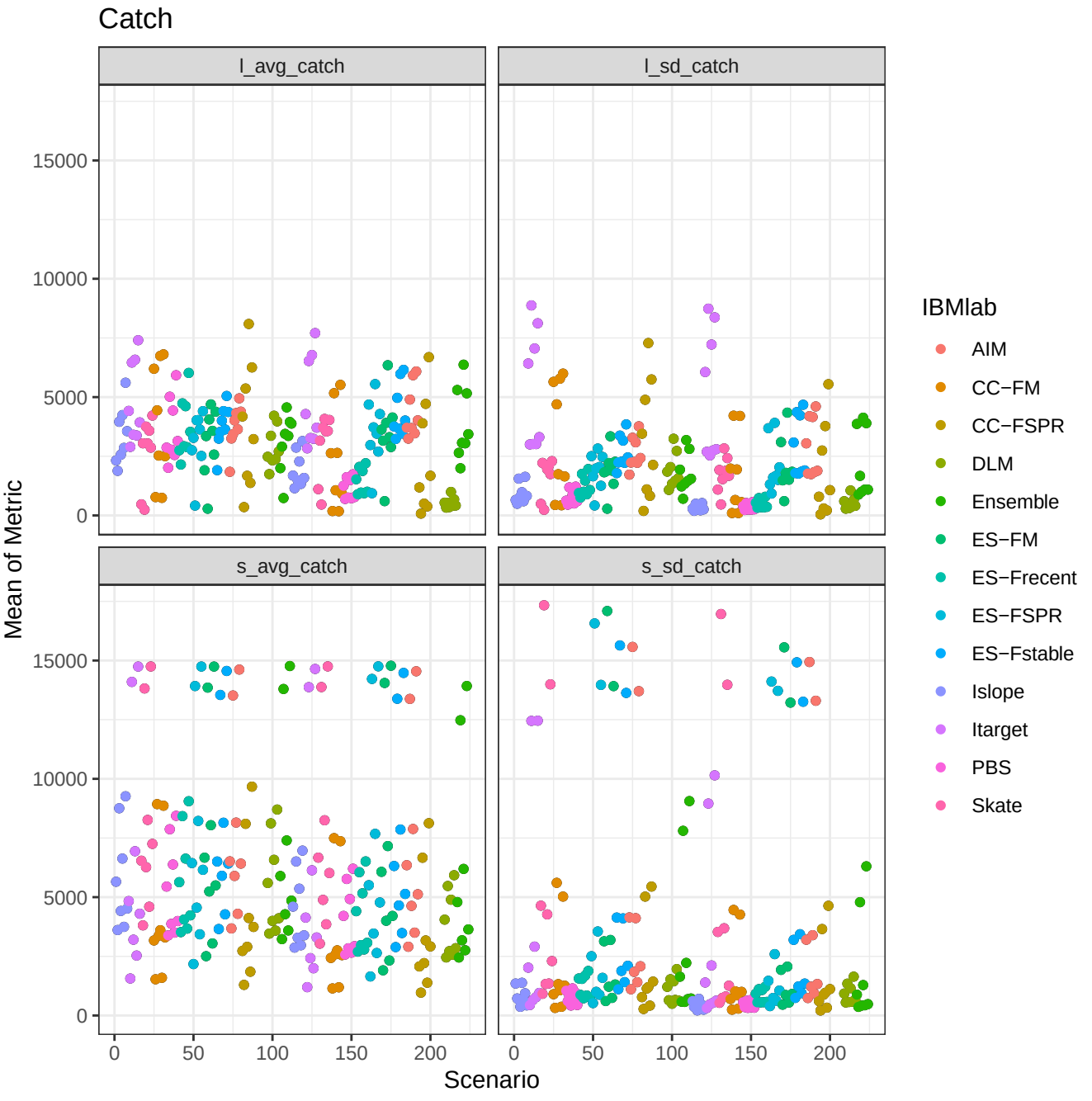

F
l_avg_f_fmsy
s_avg_f_fmsy
Mean F/Fmsy
Scenario
factor(Fhist)
1
2
0
3
6
9
12
0
50
100
150
200

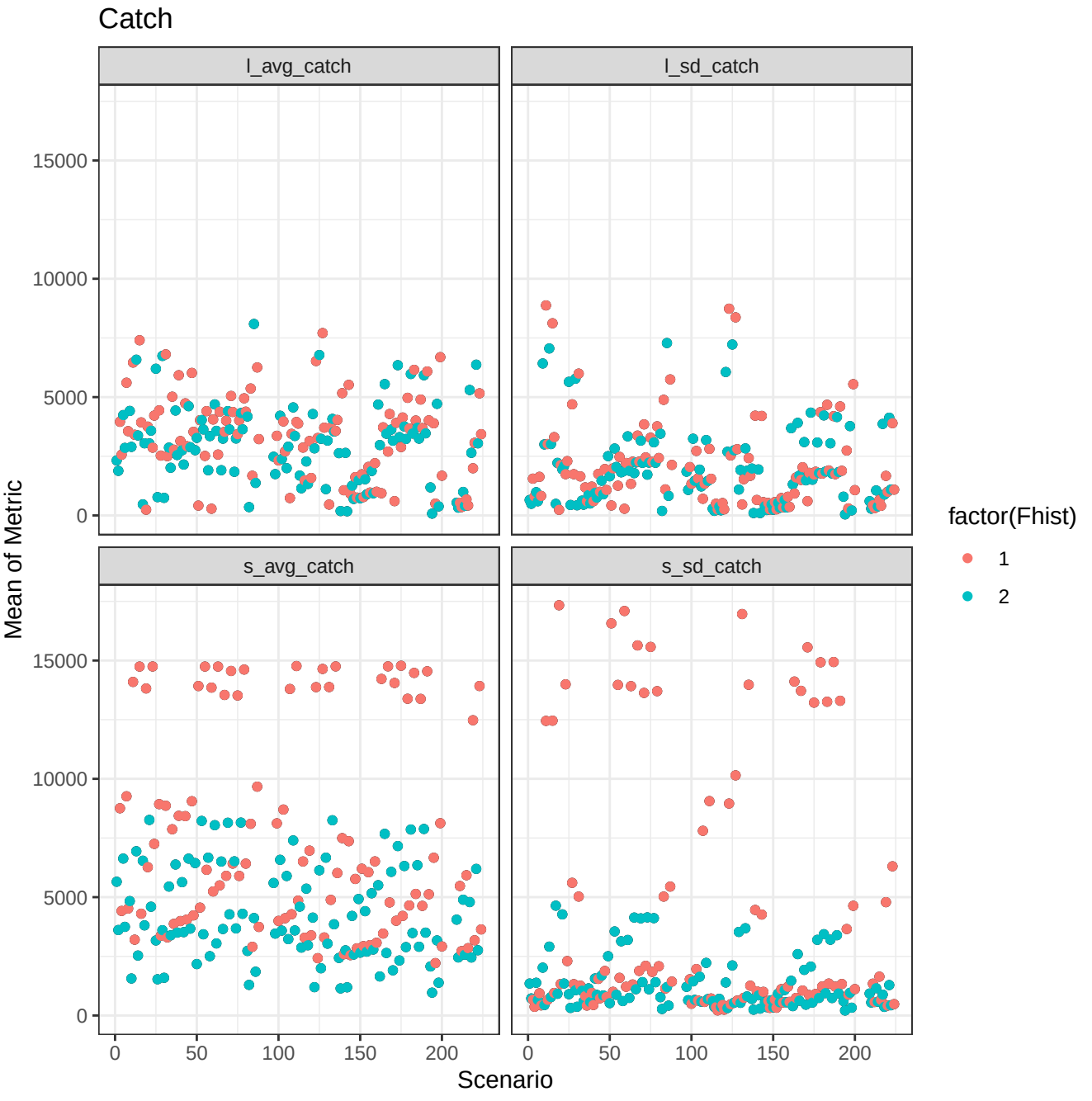

F
l_avg_f_fmsy
s_avg_f_fmsy
12
9
6
3
0
Mean F/Fmsy
0
50
100
150
200
Scenario
factor(n_selblocks)
1
2

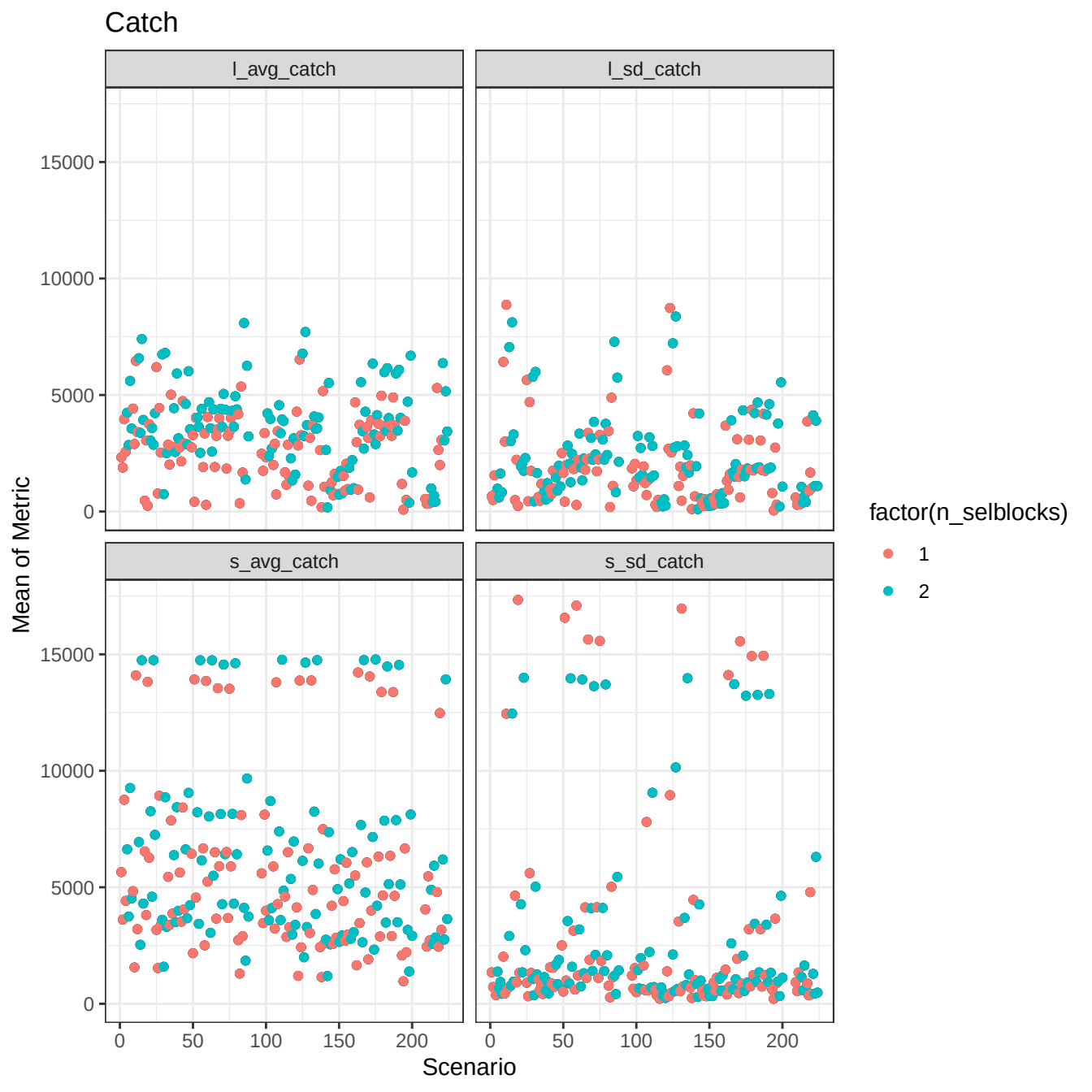

F
l_avg_f_fmsy
s_avg_f_fmsy
Mean F/Fmsy
12
9
6
3
0
0
50
100
150
200
Scenario
factor(catch.mult)
0.75
1

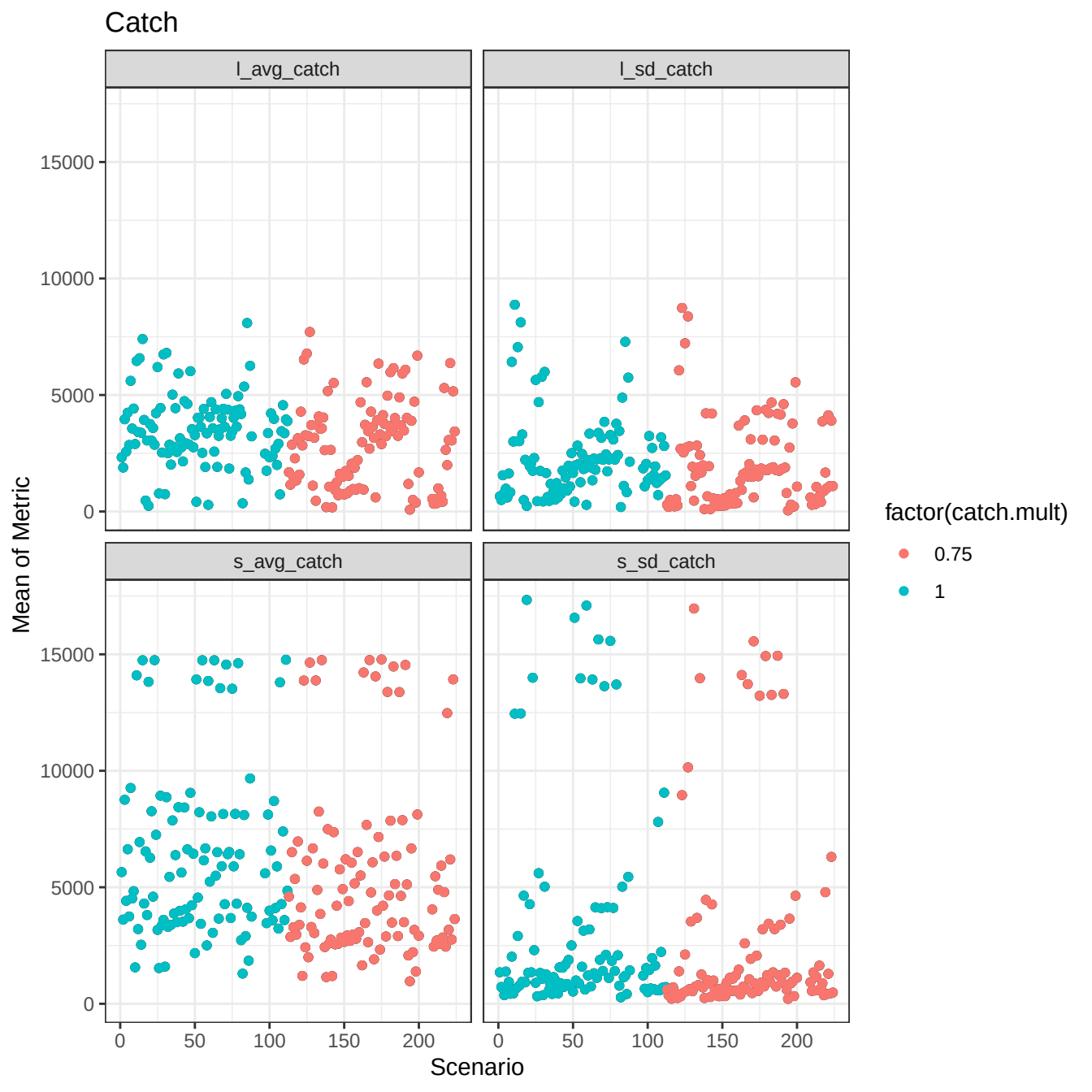

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
0
5000
10000
15000
0
50
100
150
200

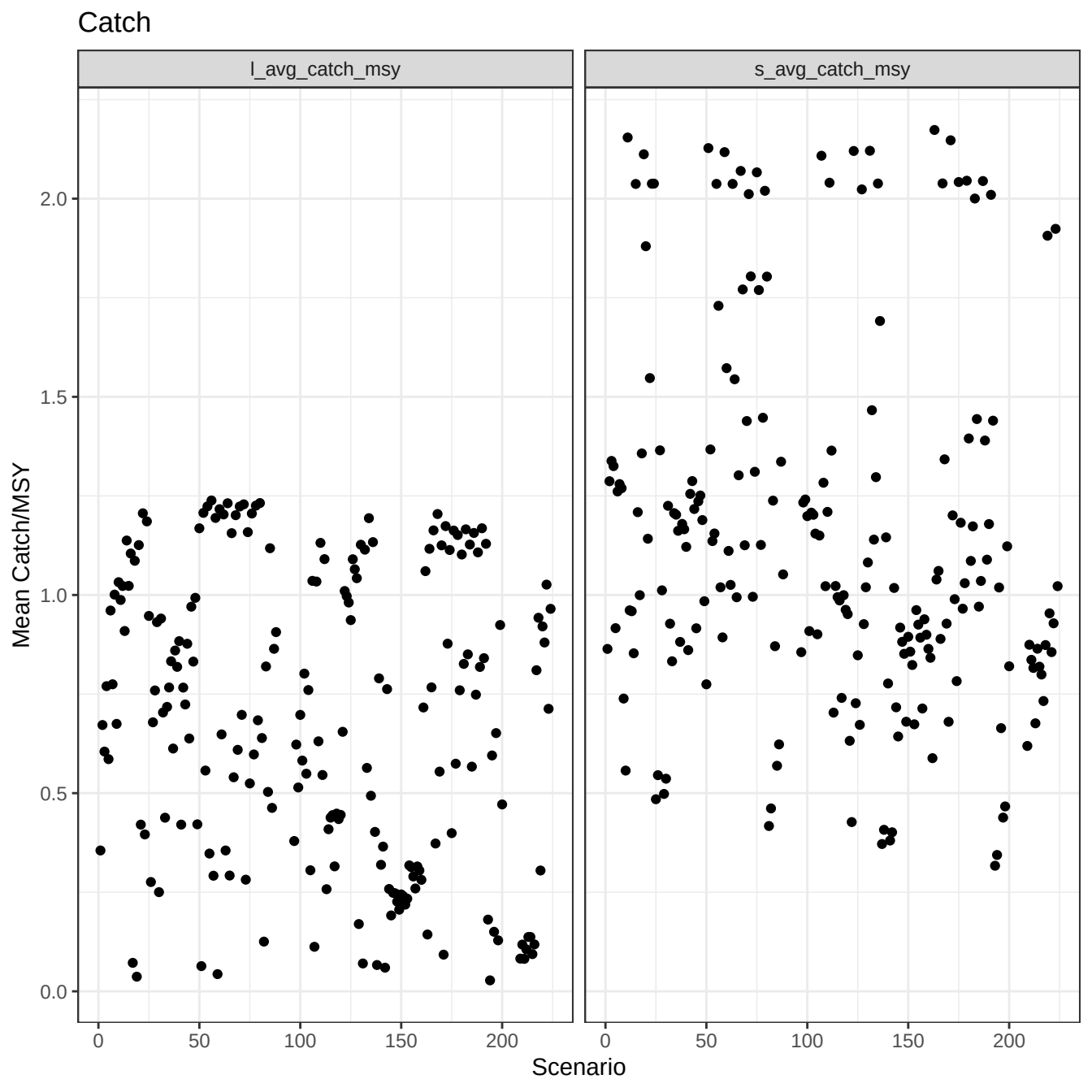

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
retro_type
Catch
M
0
5000
10000
15000
0
50
100
150
200

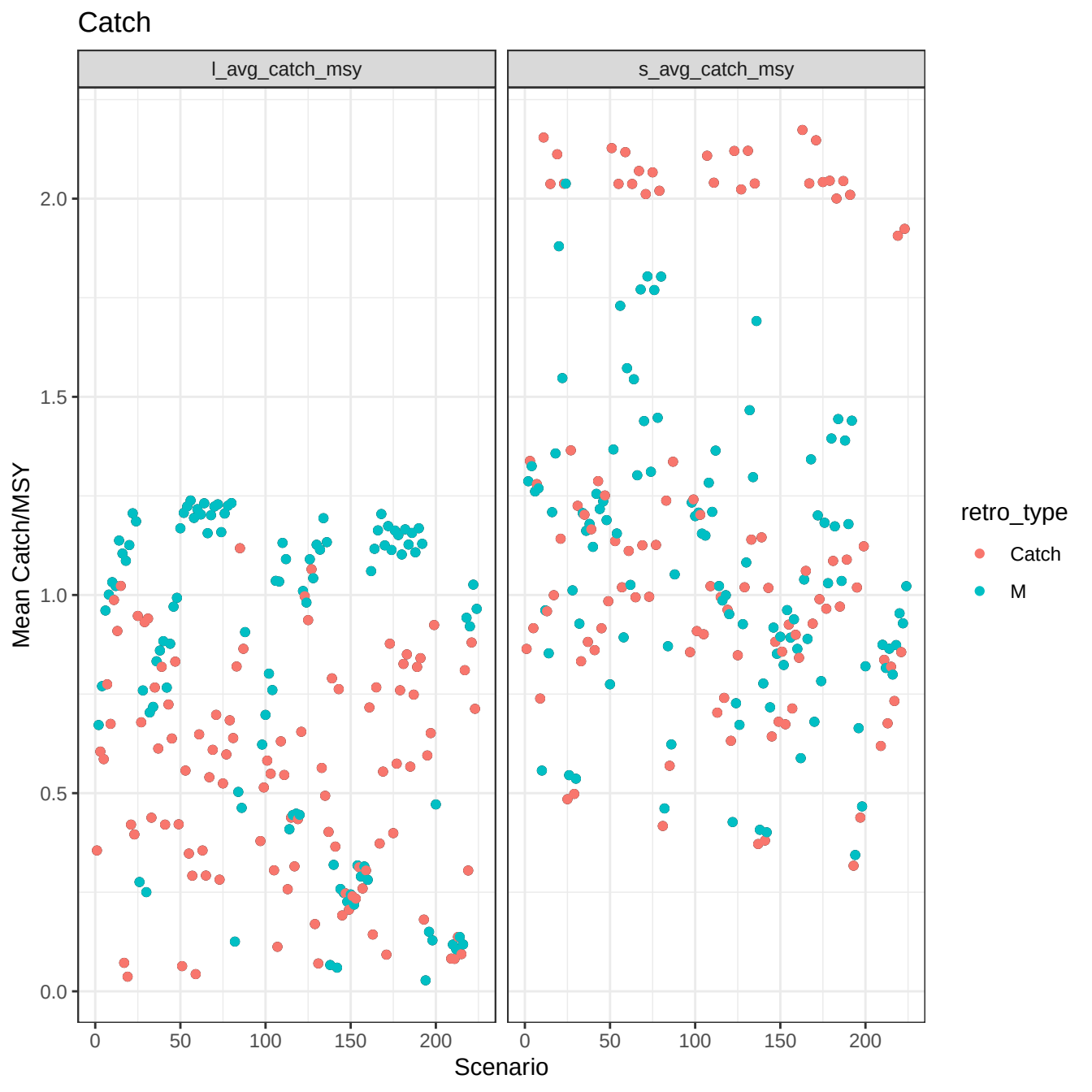

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
0
5000
10000
15000
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

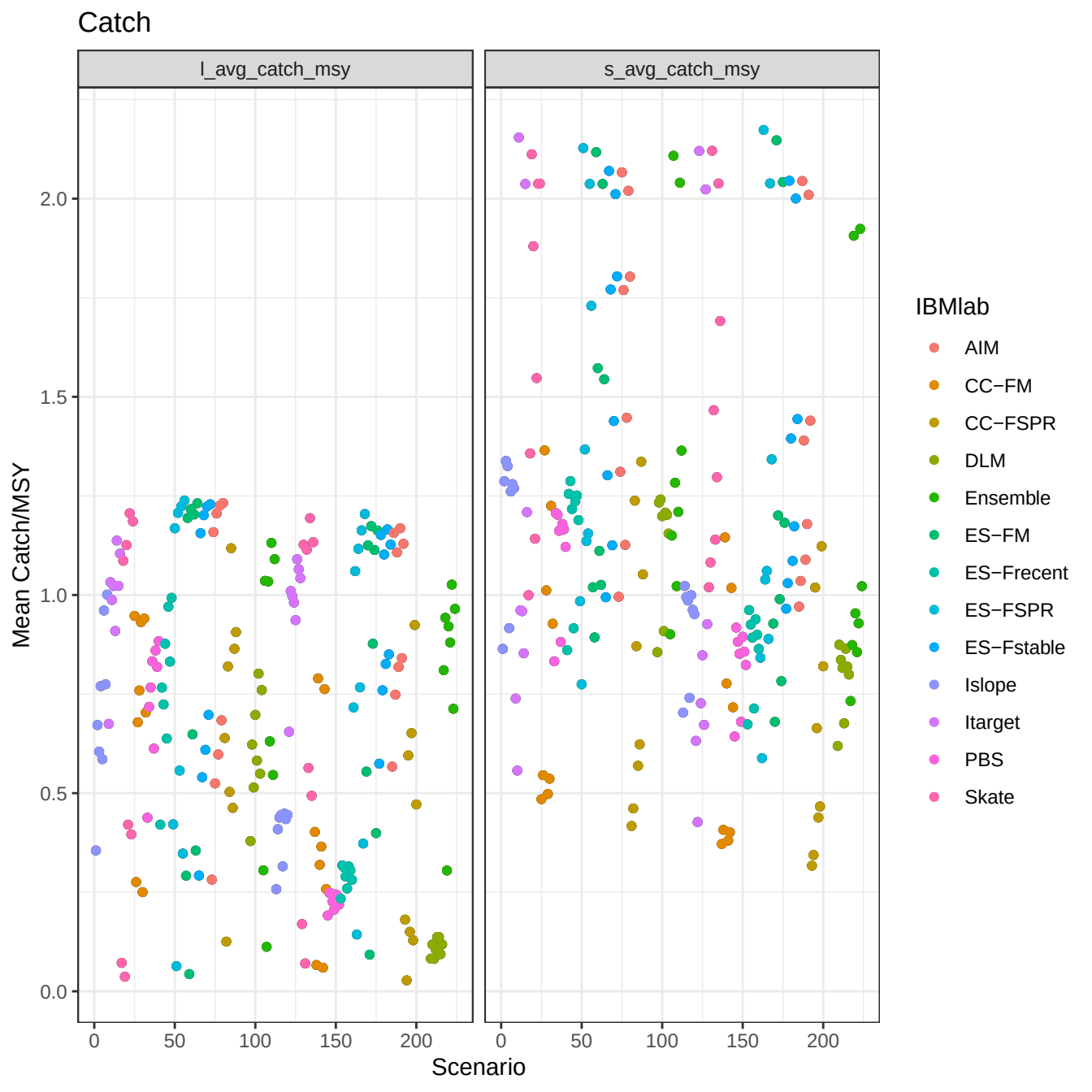

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
factor(Fhist)
1
2
0
5000
10000
15000
0
50
100
150
200

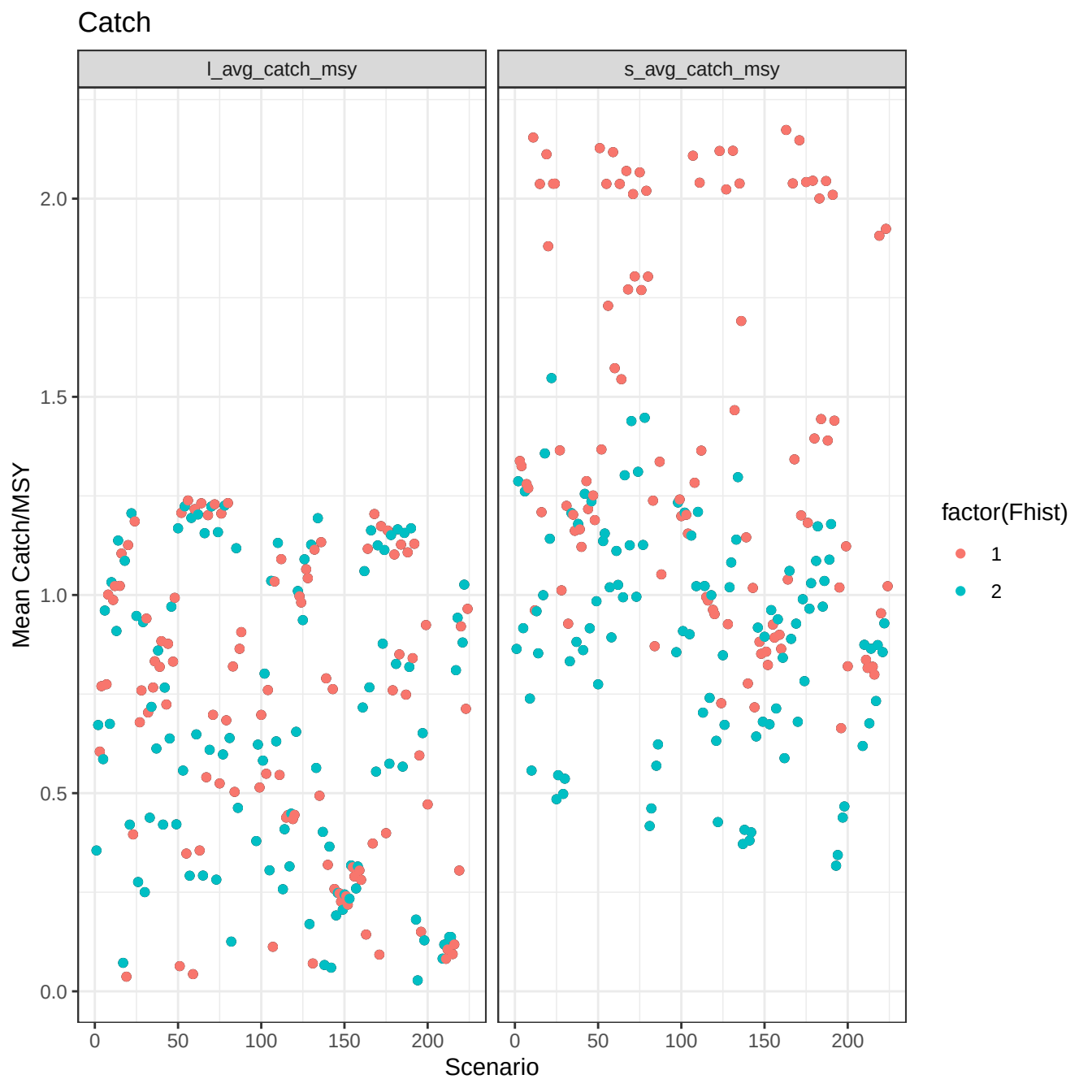

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
factor(n_selblocks)
1
2
0
5000
10000
15000
0
50
100
150
200

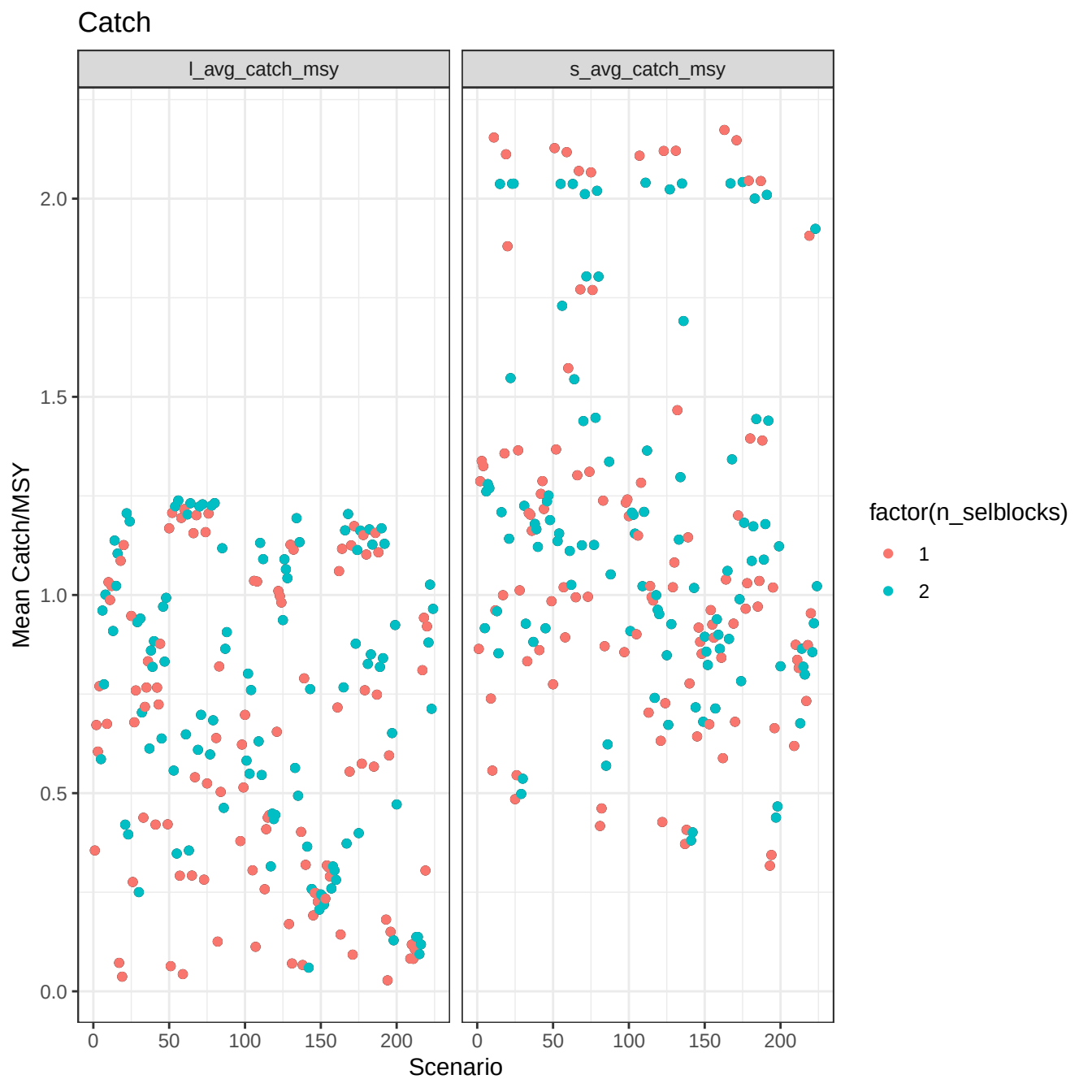

Catch
l_avg_catch
l_sd_catch
s_avg_catch
s_sd_catch
Mean of Metric
Scenario
0
5000
10000
15000
0
50
100
150
200
factor(catch.mult)
0.75
1

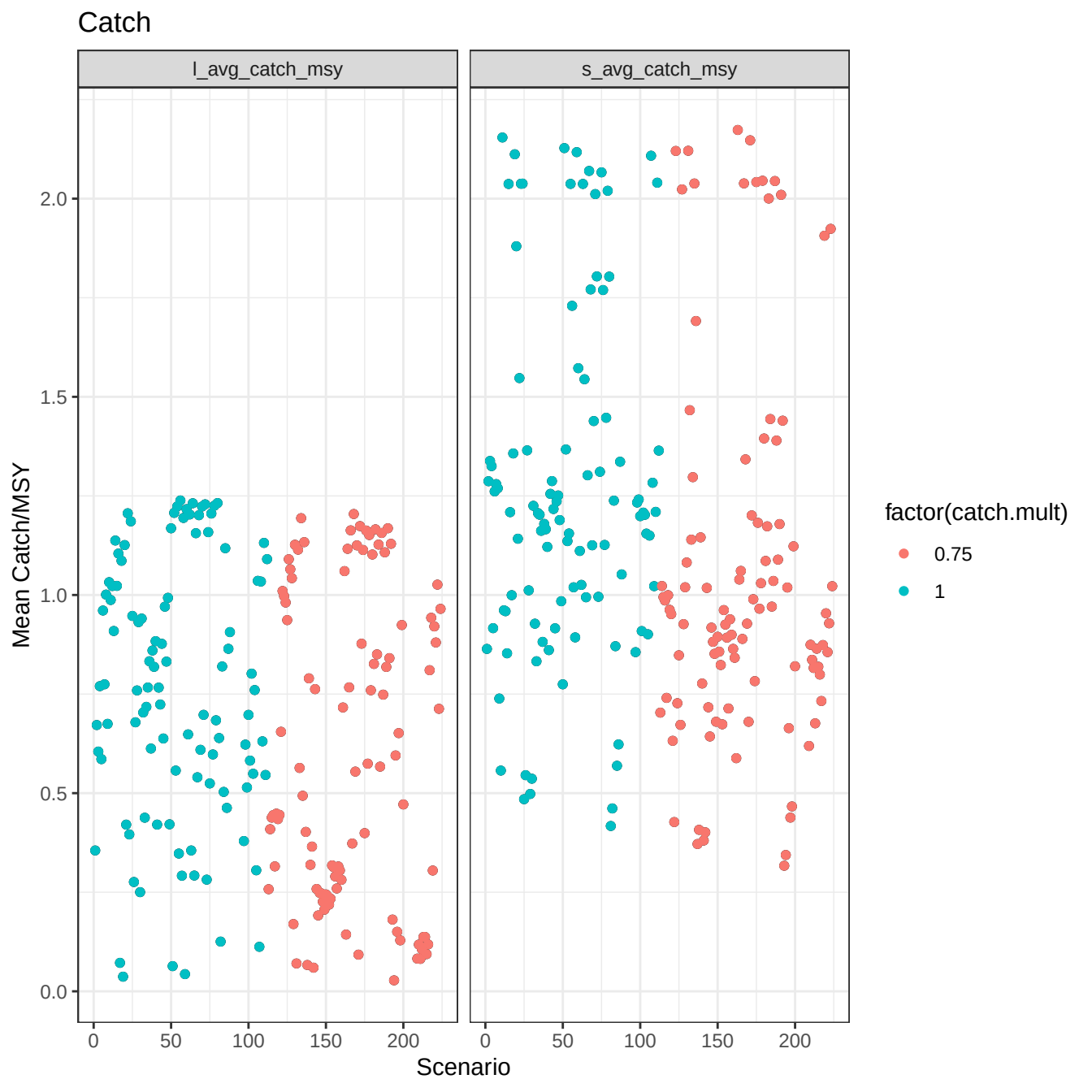

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario

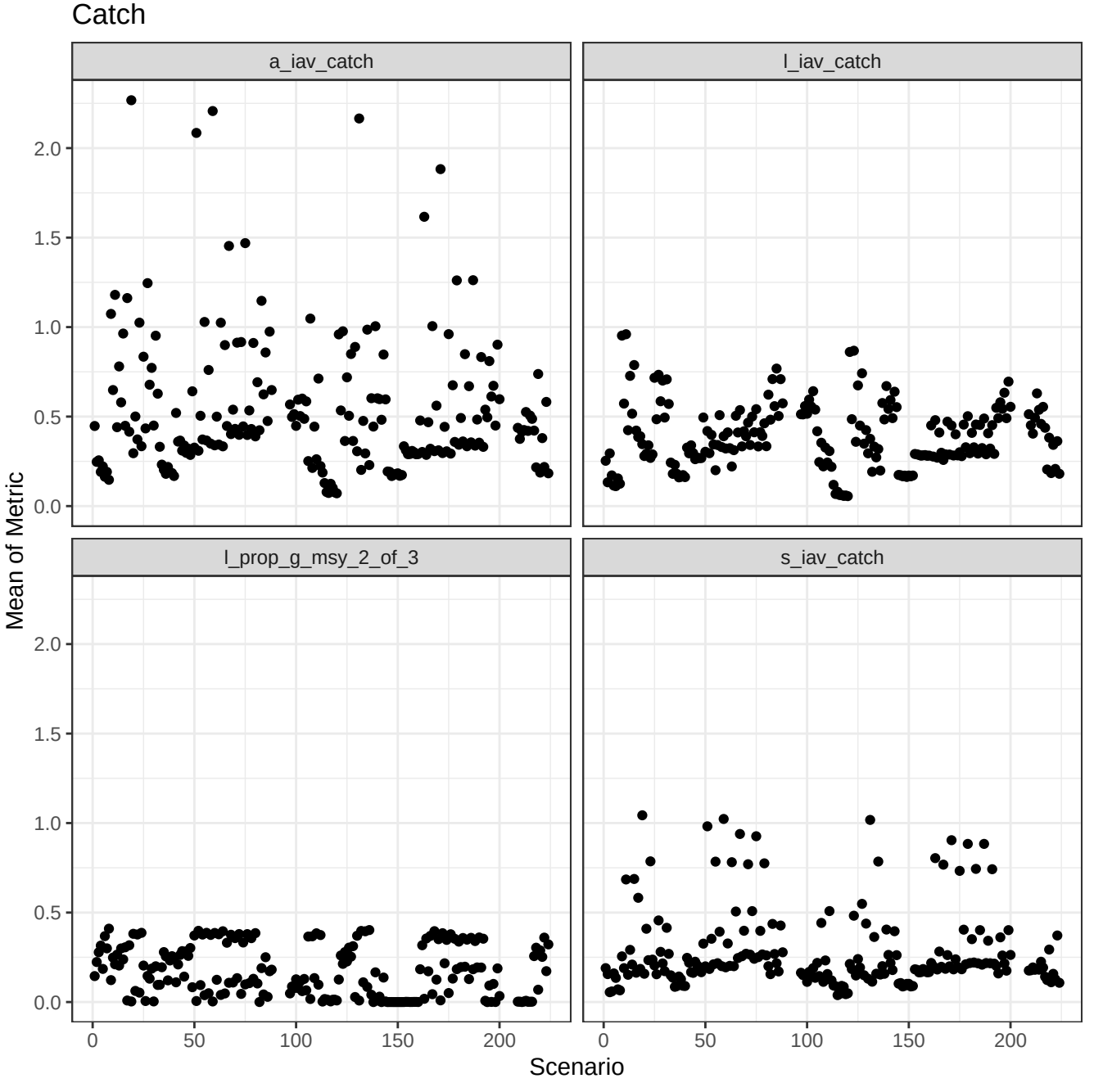

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario
retro_type
Catch
M

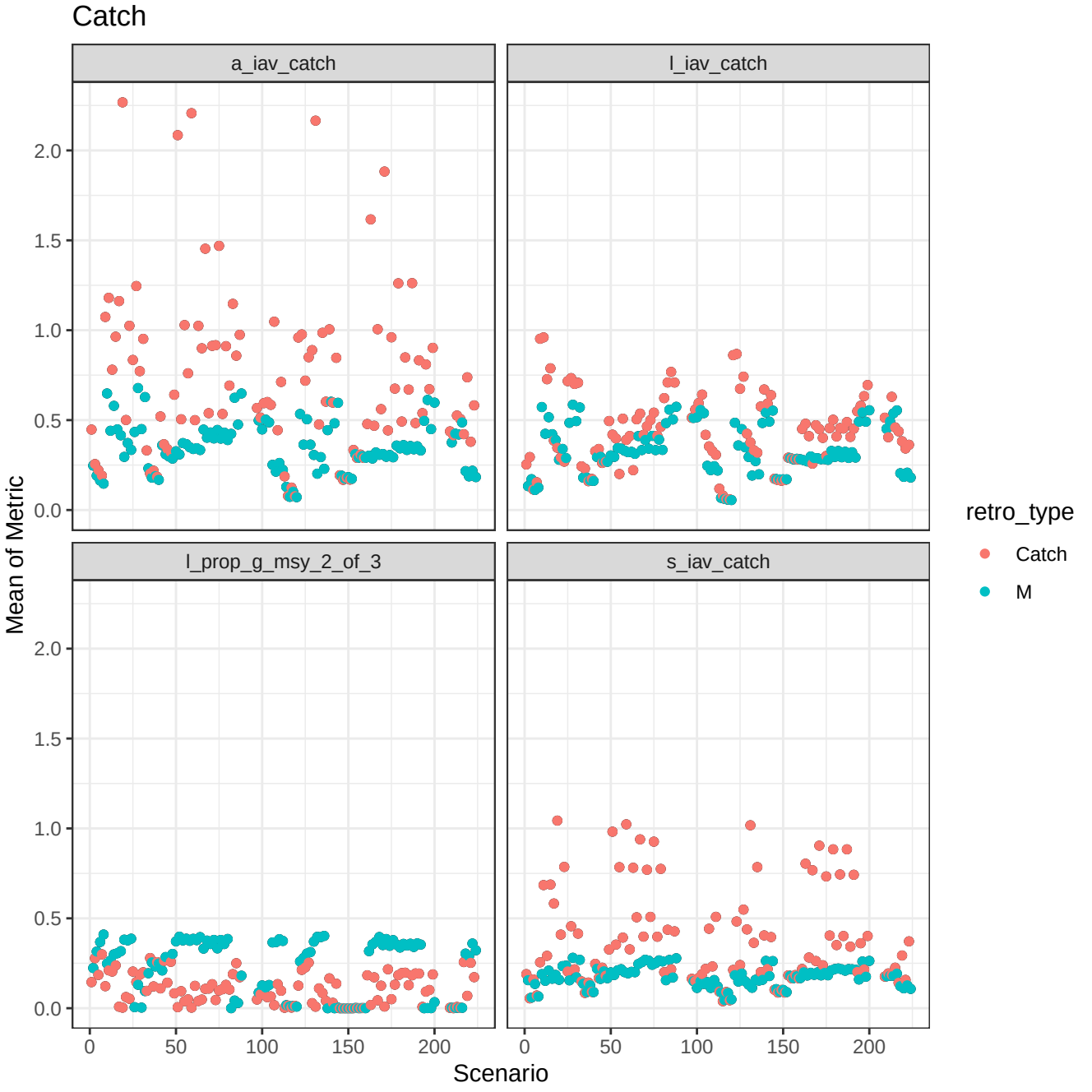

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate

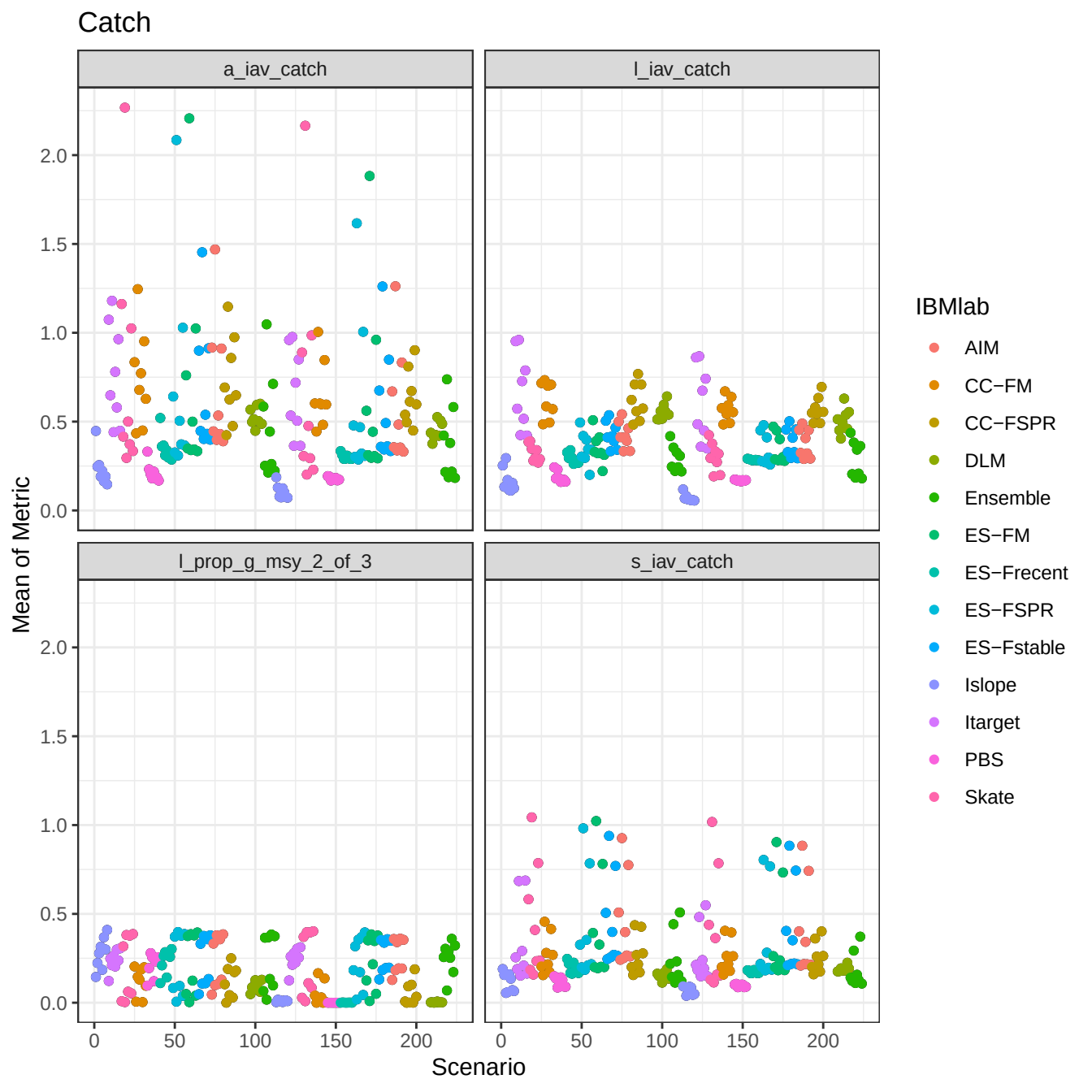

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario
factor(Fhist)
1
2

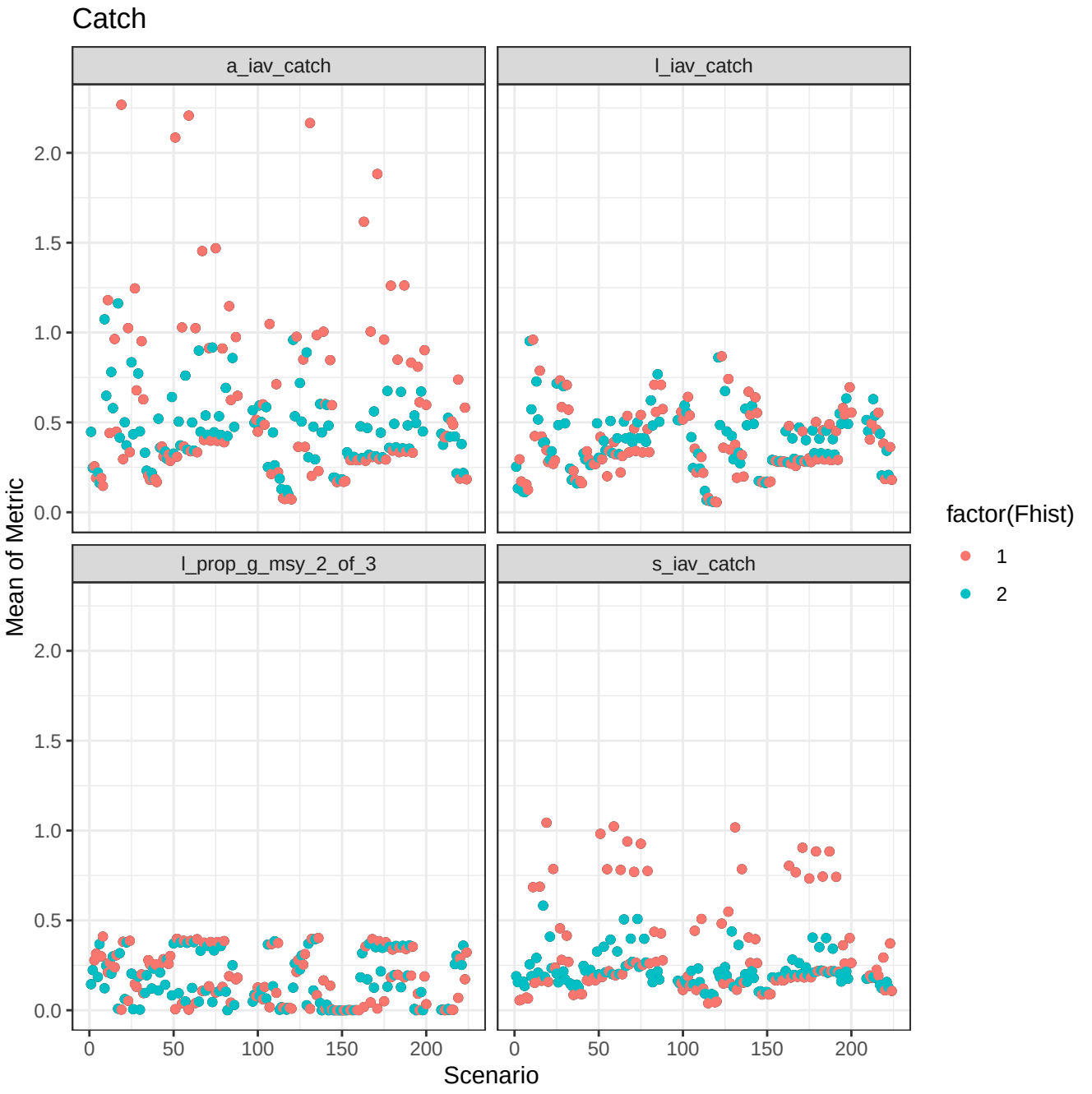

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario
factor(n_selblocks)
1
2

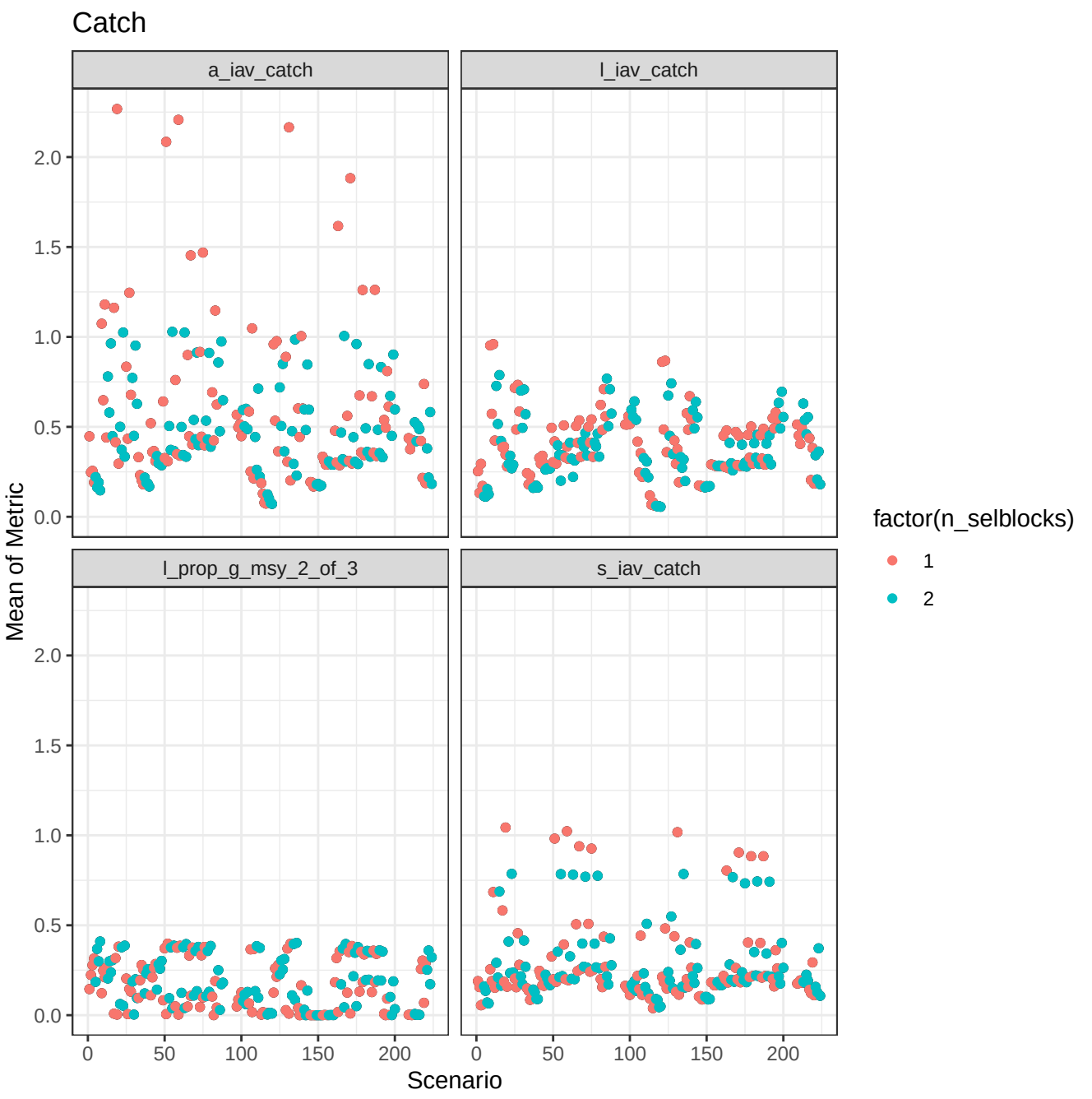

Catch
l_avg_catch_msy
s_avg_catch_msy
Mean Catch/MSY
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario
factor(catch.mult)
0.75
1

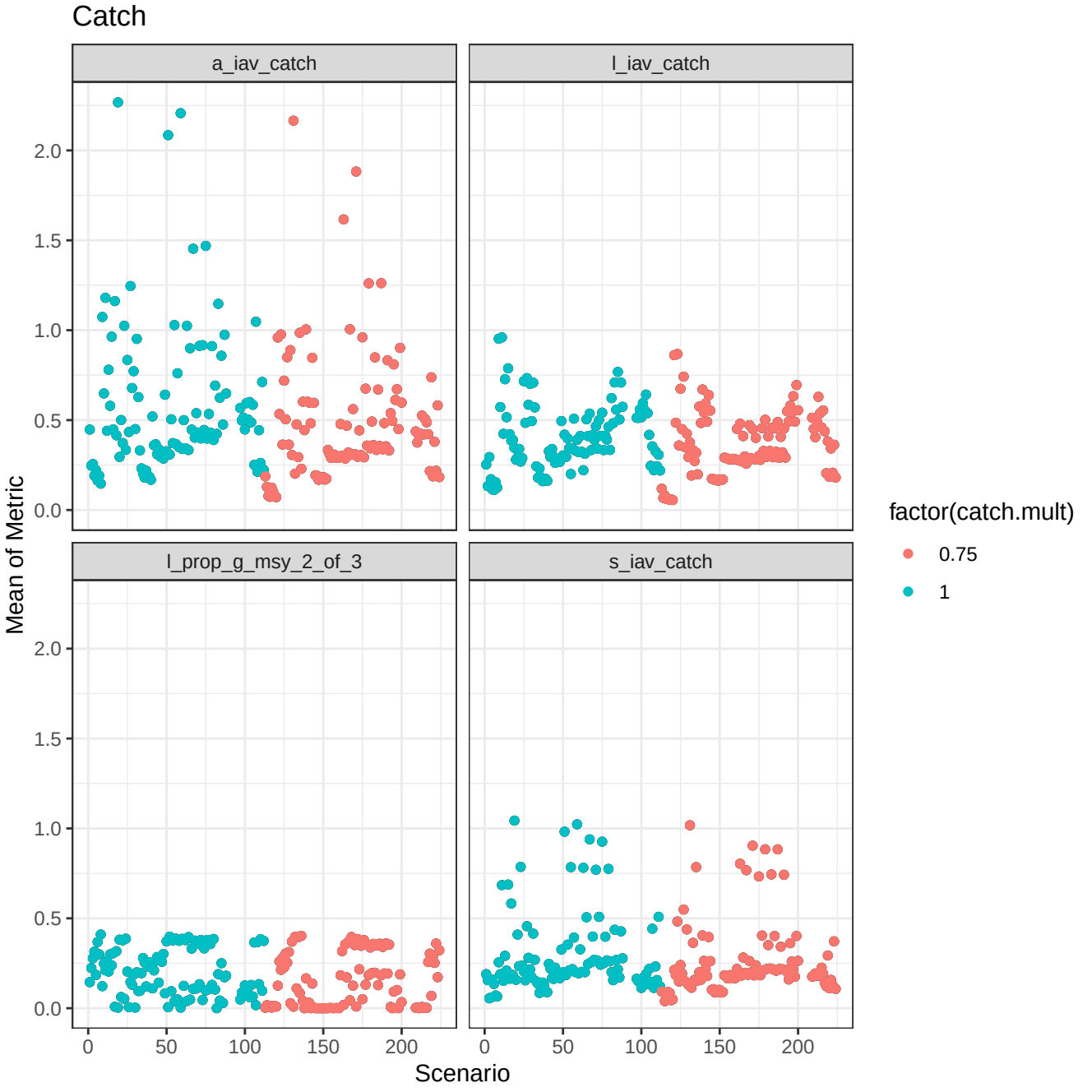

Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
Scenario


Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
Scenario
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
retro_type
Catch
M


Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
Scenario
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
IBMlab
AIM
CC−FM
CC−FSPR
DLM
Ensemble
ES−FM
ES−Frecent
ES−FSPR
ES−Fstable
Islope
Itarget
PBS
Skate


Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
Scenario
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
factor(Fhist)
1
2


Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
Scenario
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
factor(n_selblocks)
1
2


Catch
a_iav_catch
l_iav_catch
l_prop_g_msy_2_of_3
s_iav_catch
Mean of Metric
Scenario
0.0
0.5
1.0
1.5
2.0
0
50
100
150
200
factor(catch.mult)
0.75
1