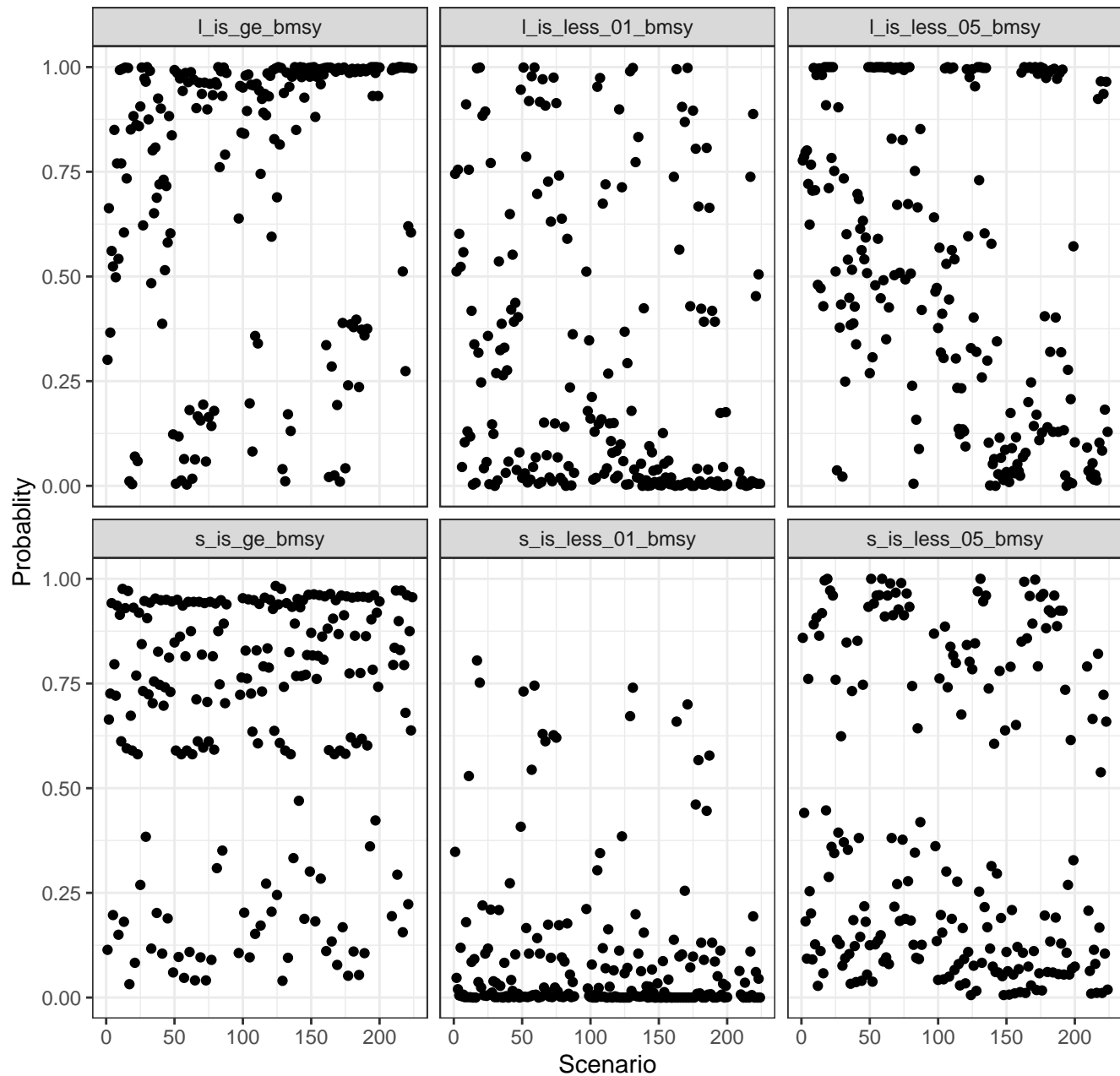
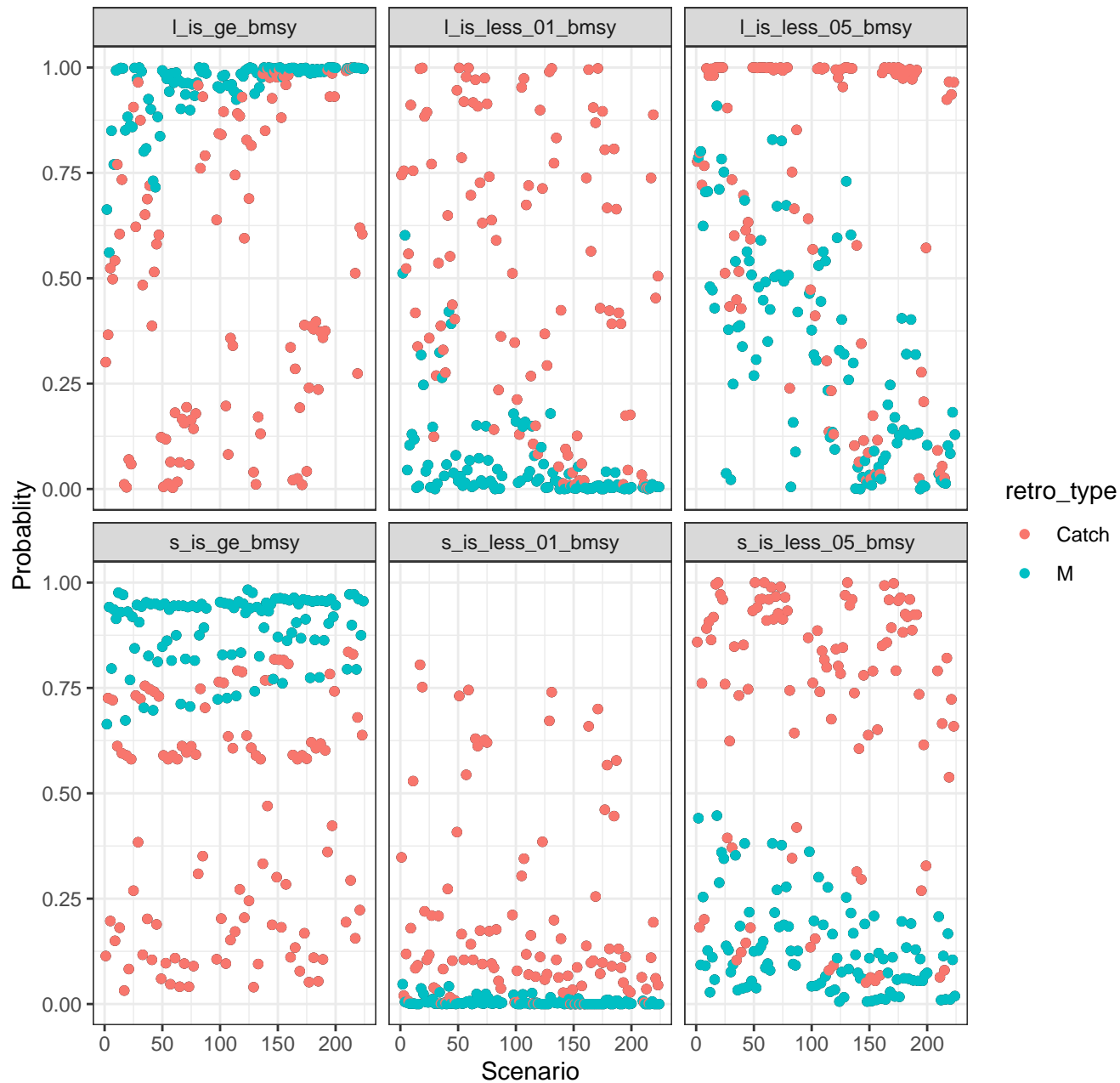


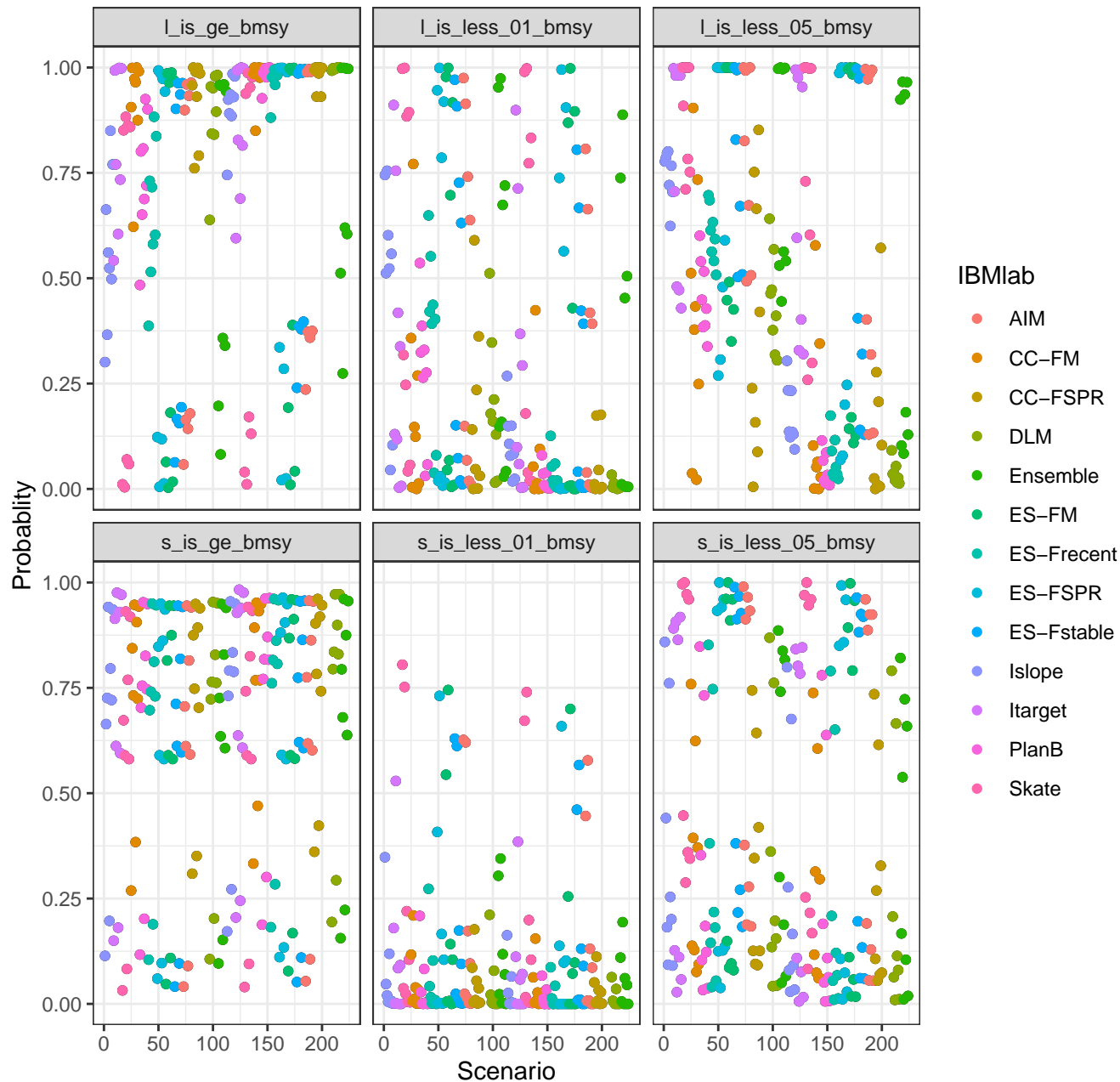
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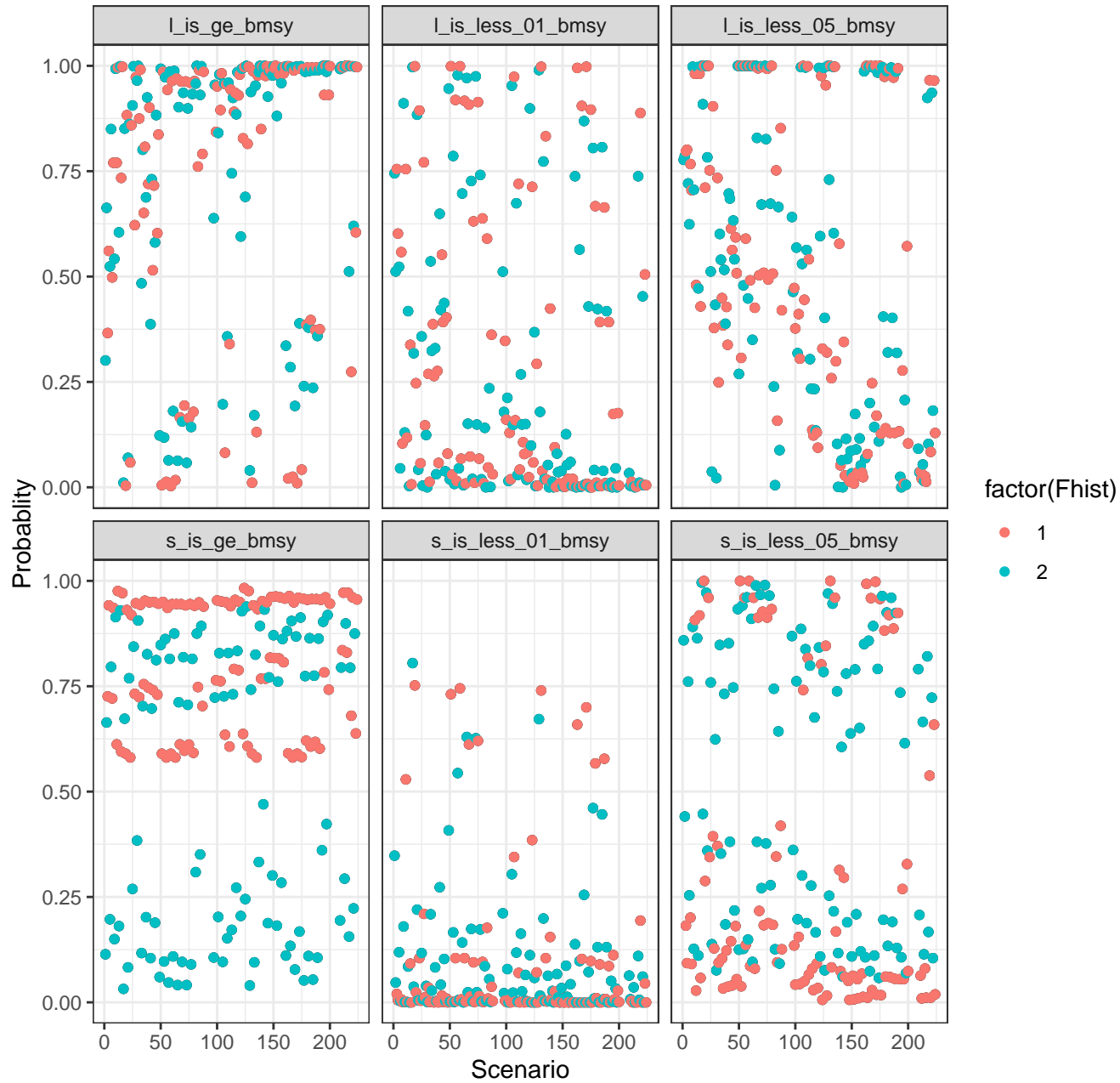
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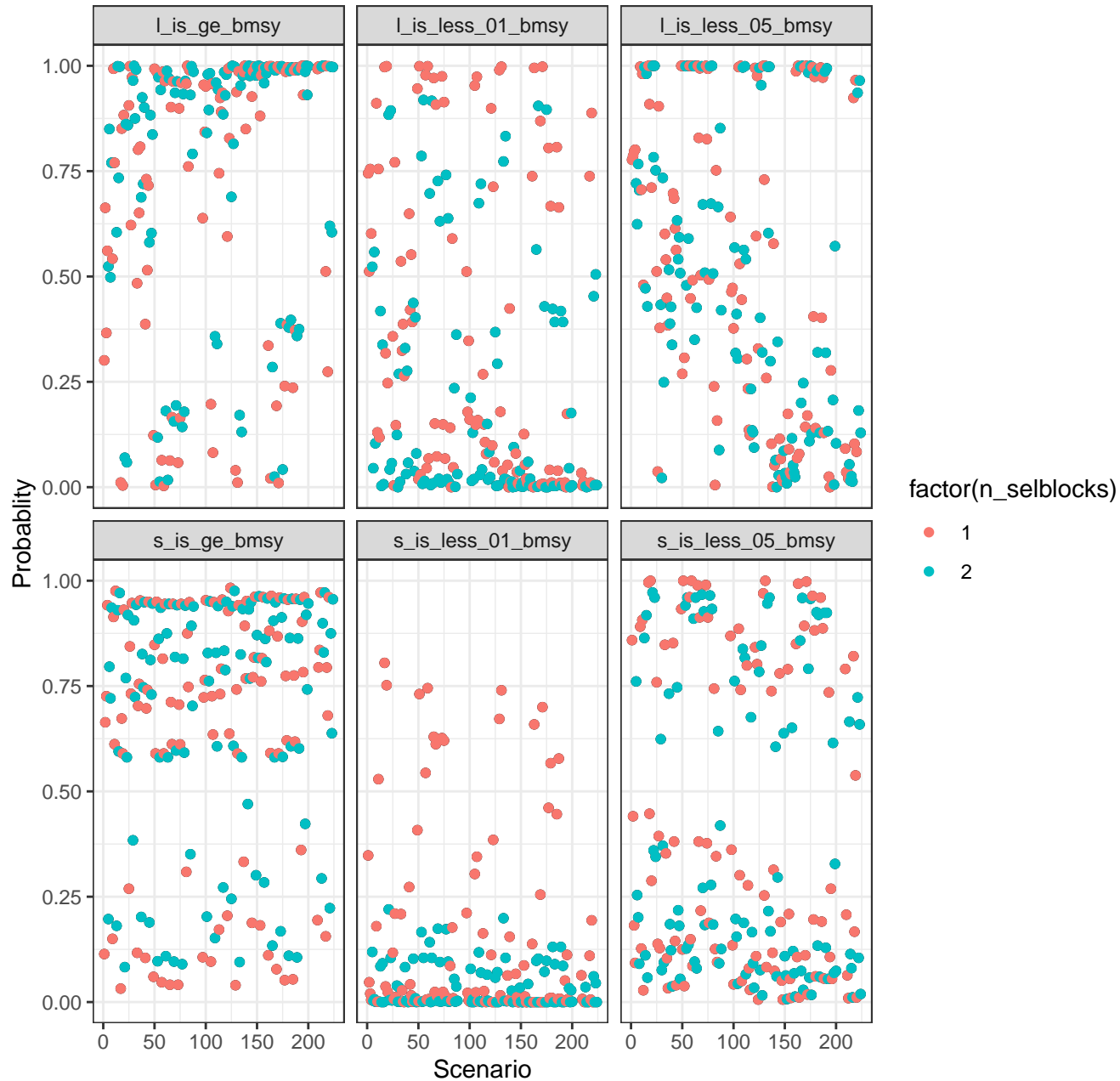
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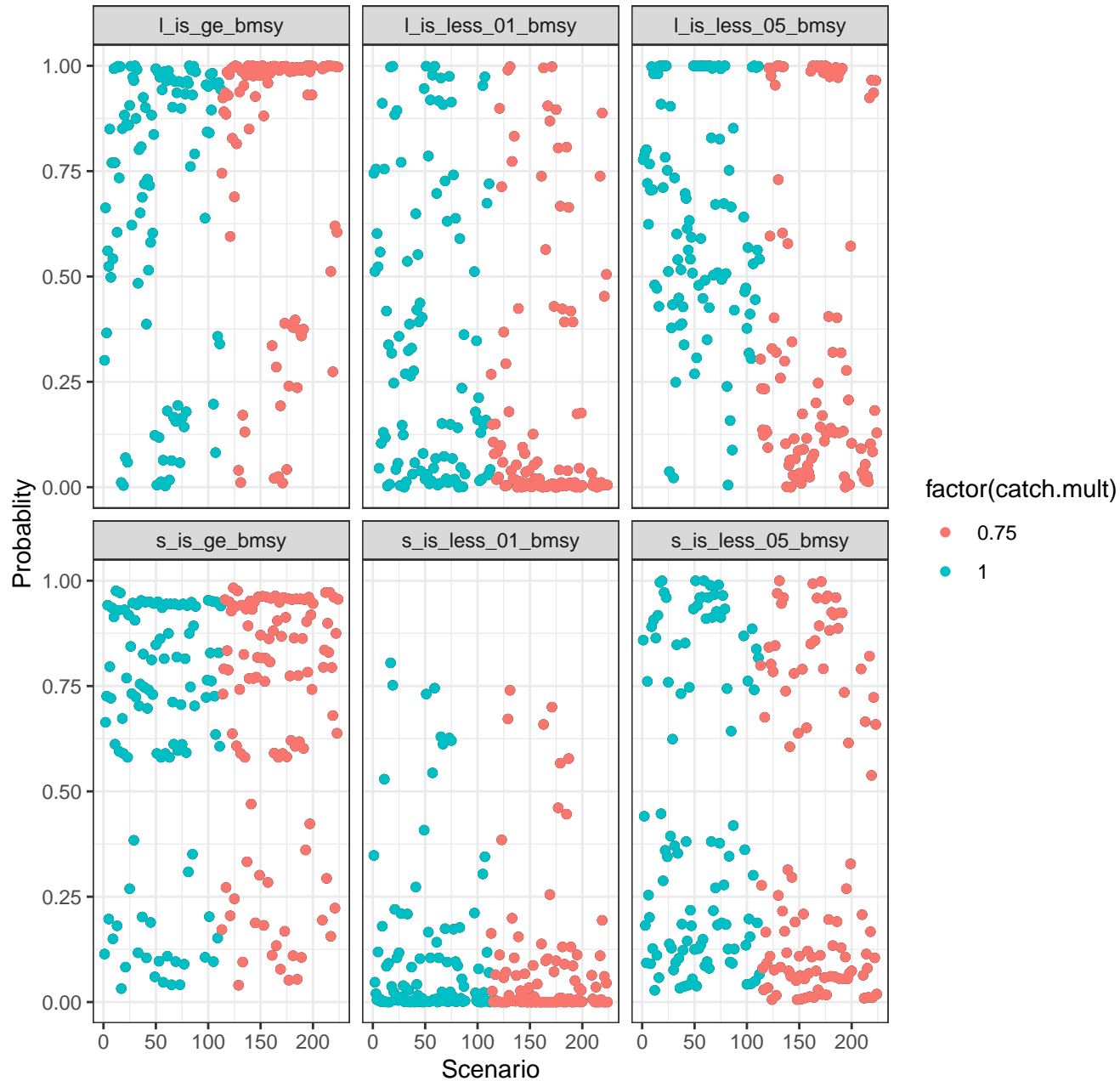
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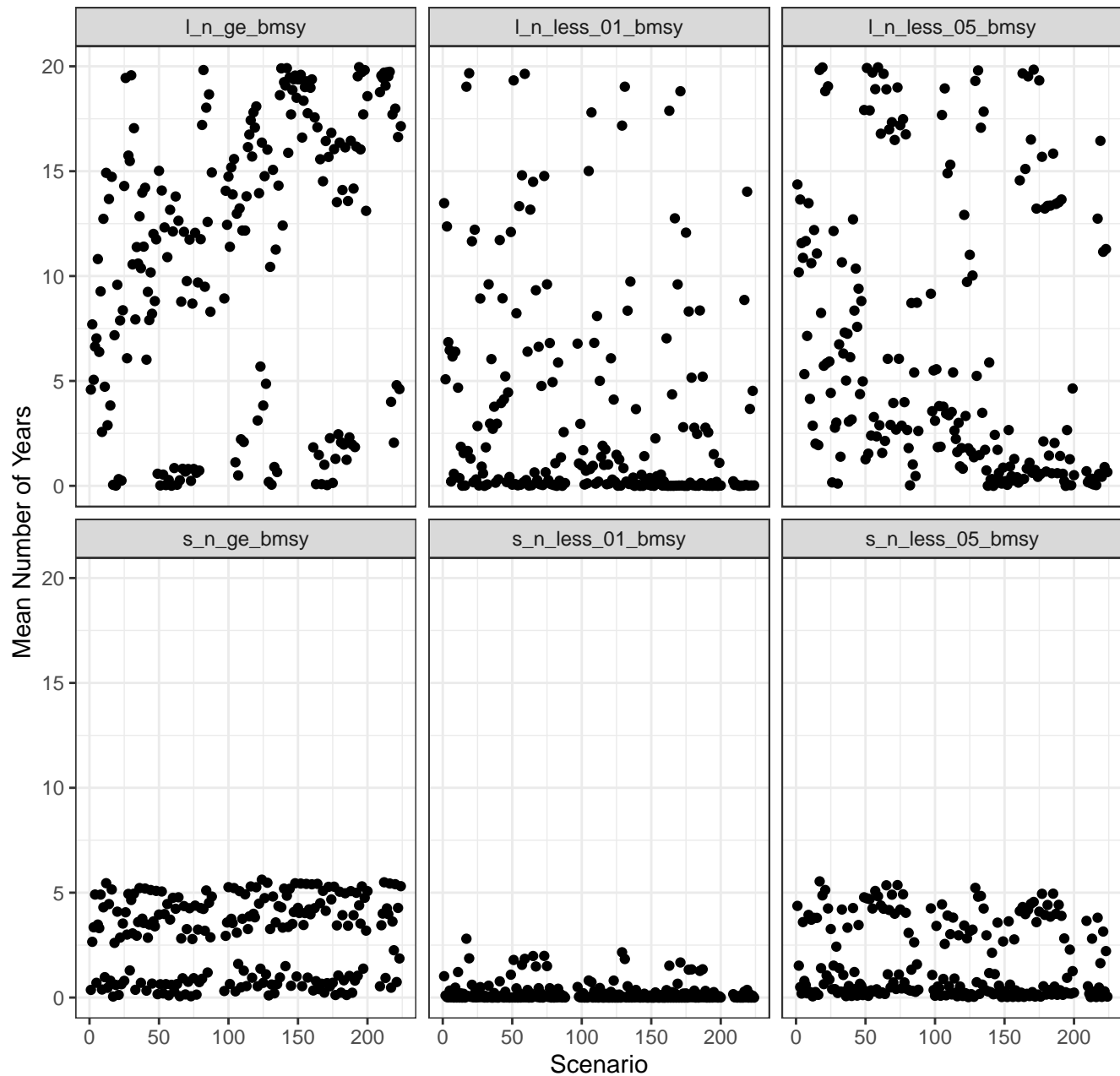
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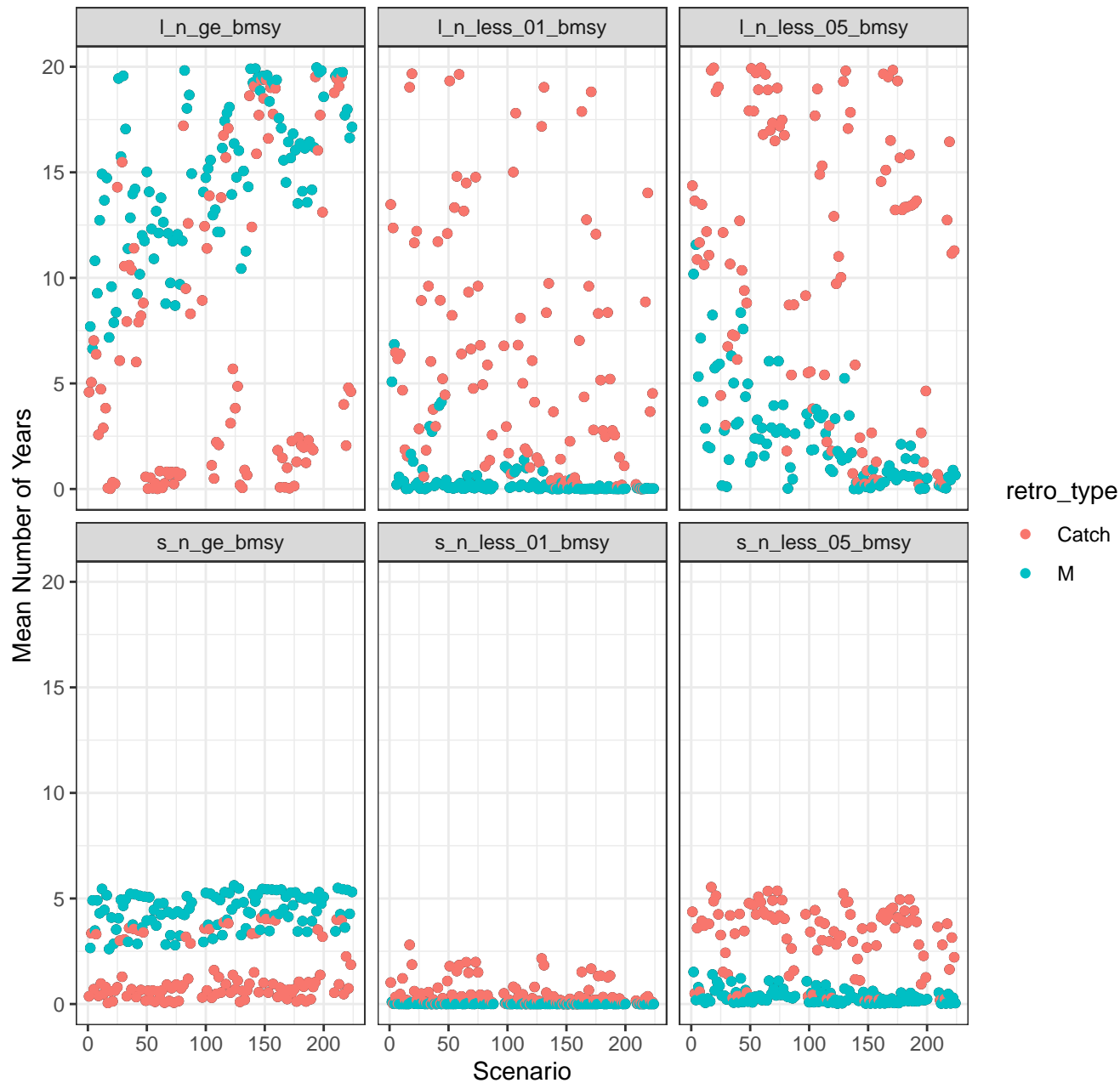
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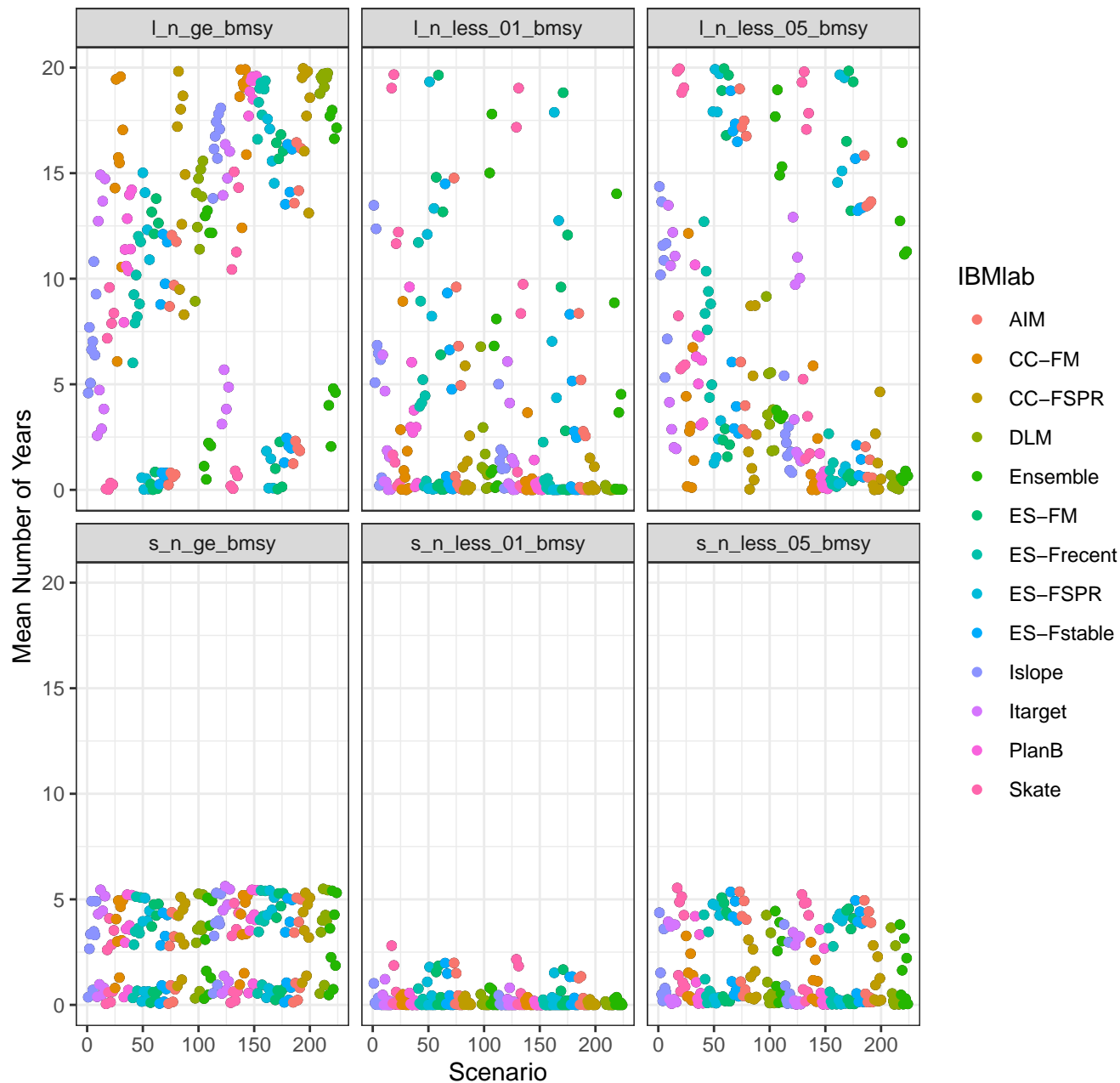
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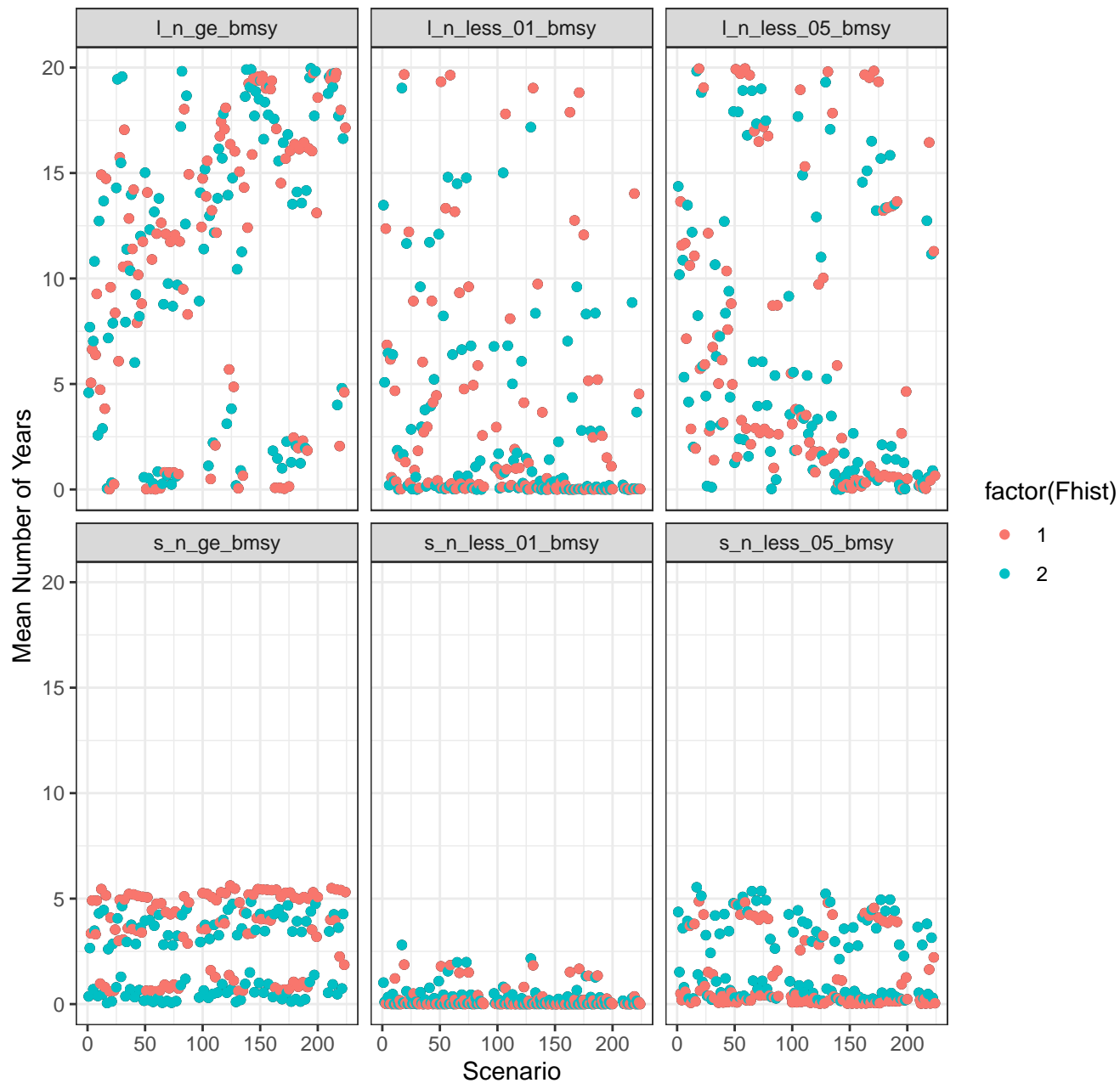
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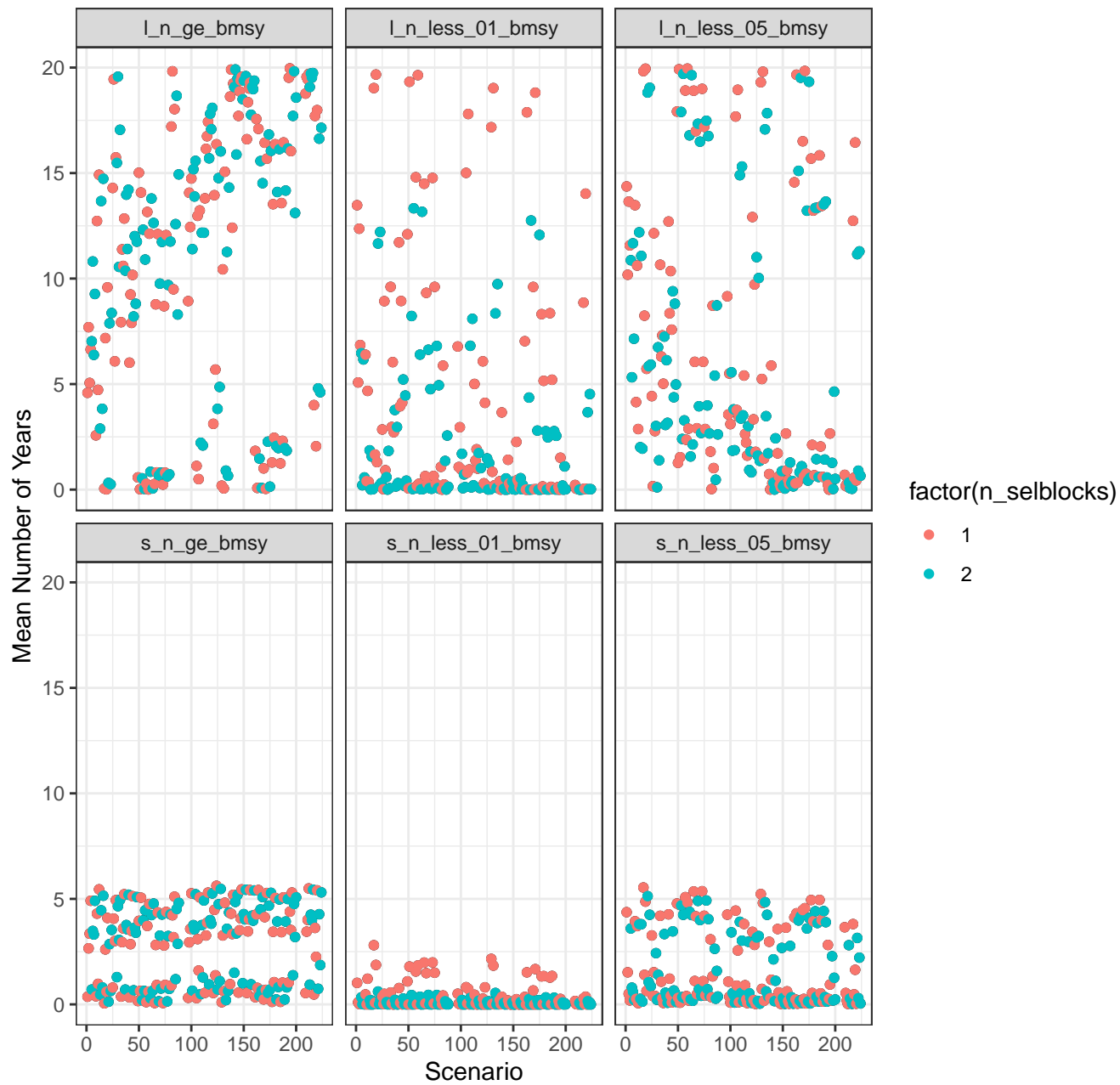
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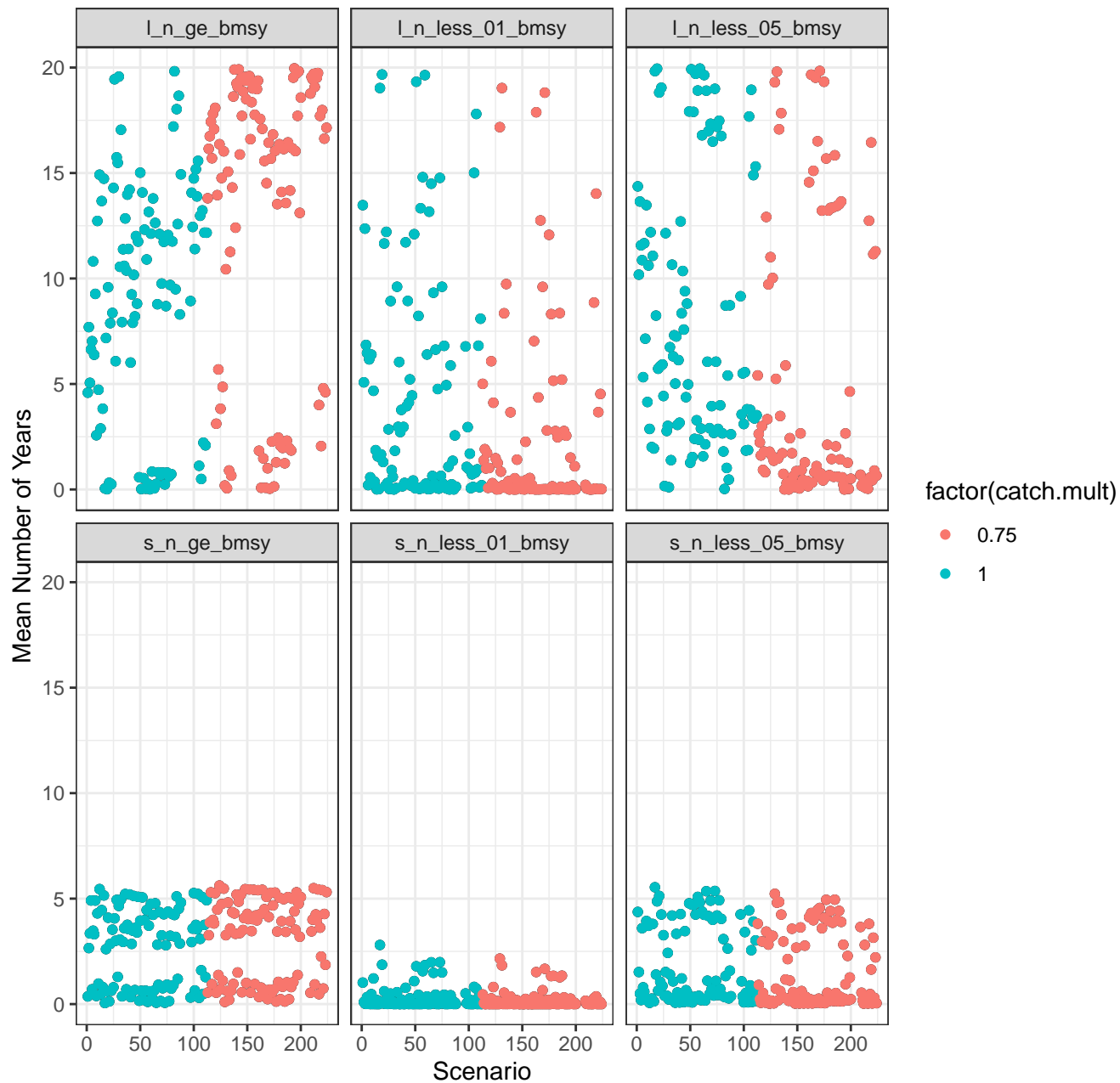
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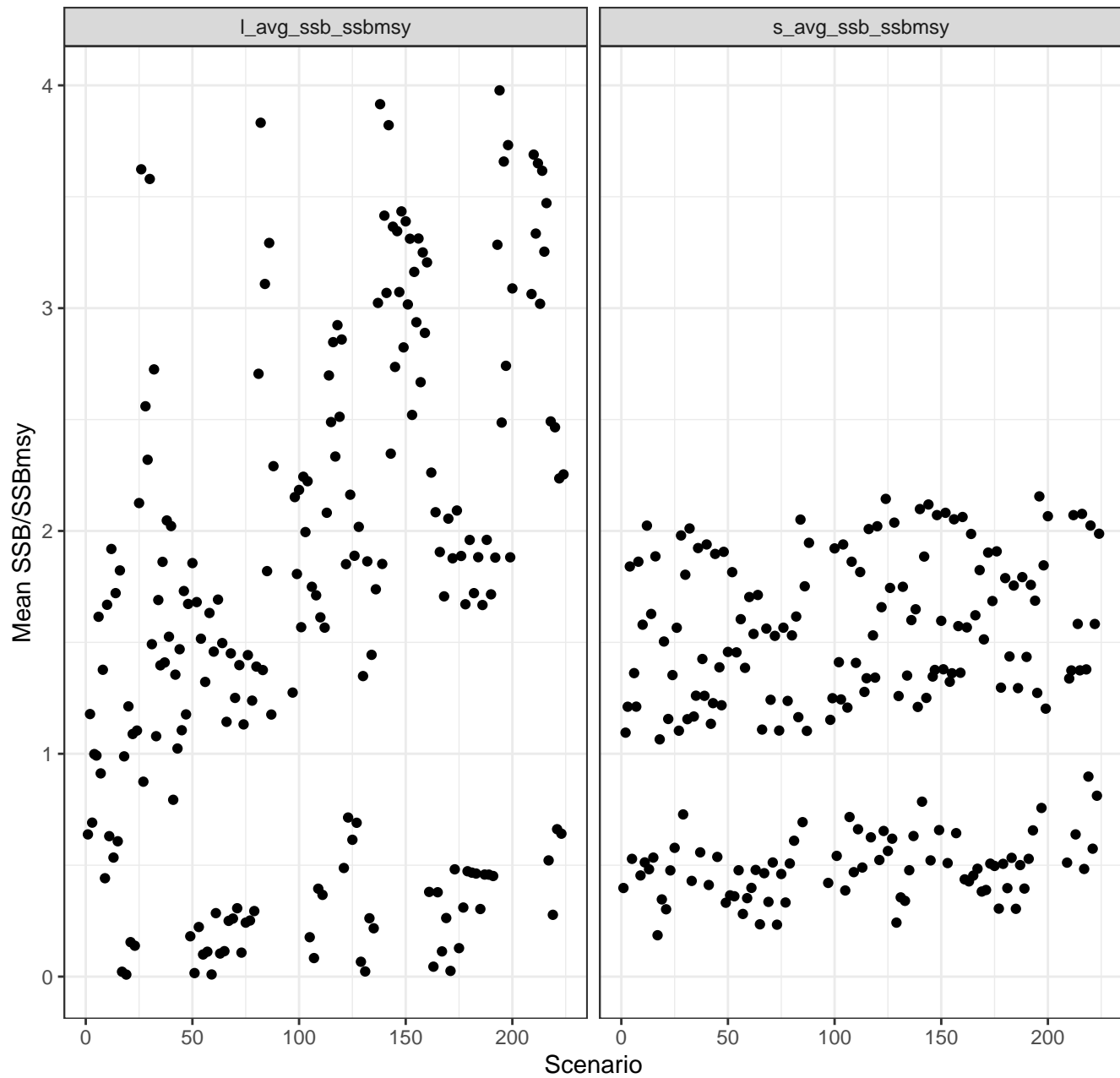
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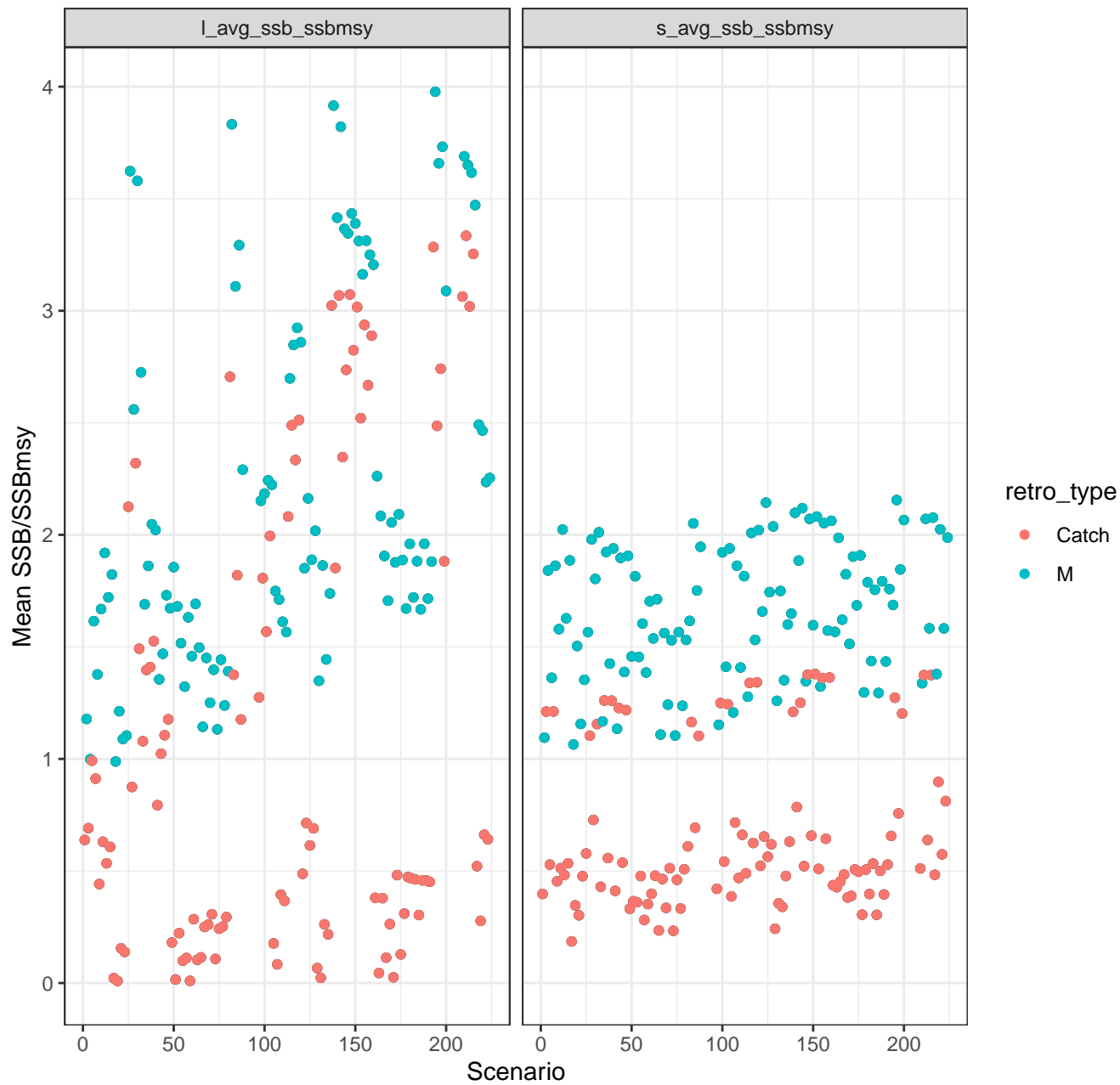
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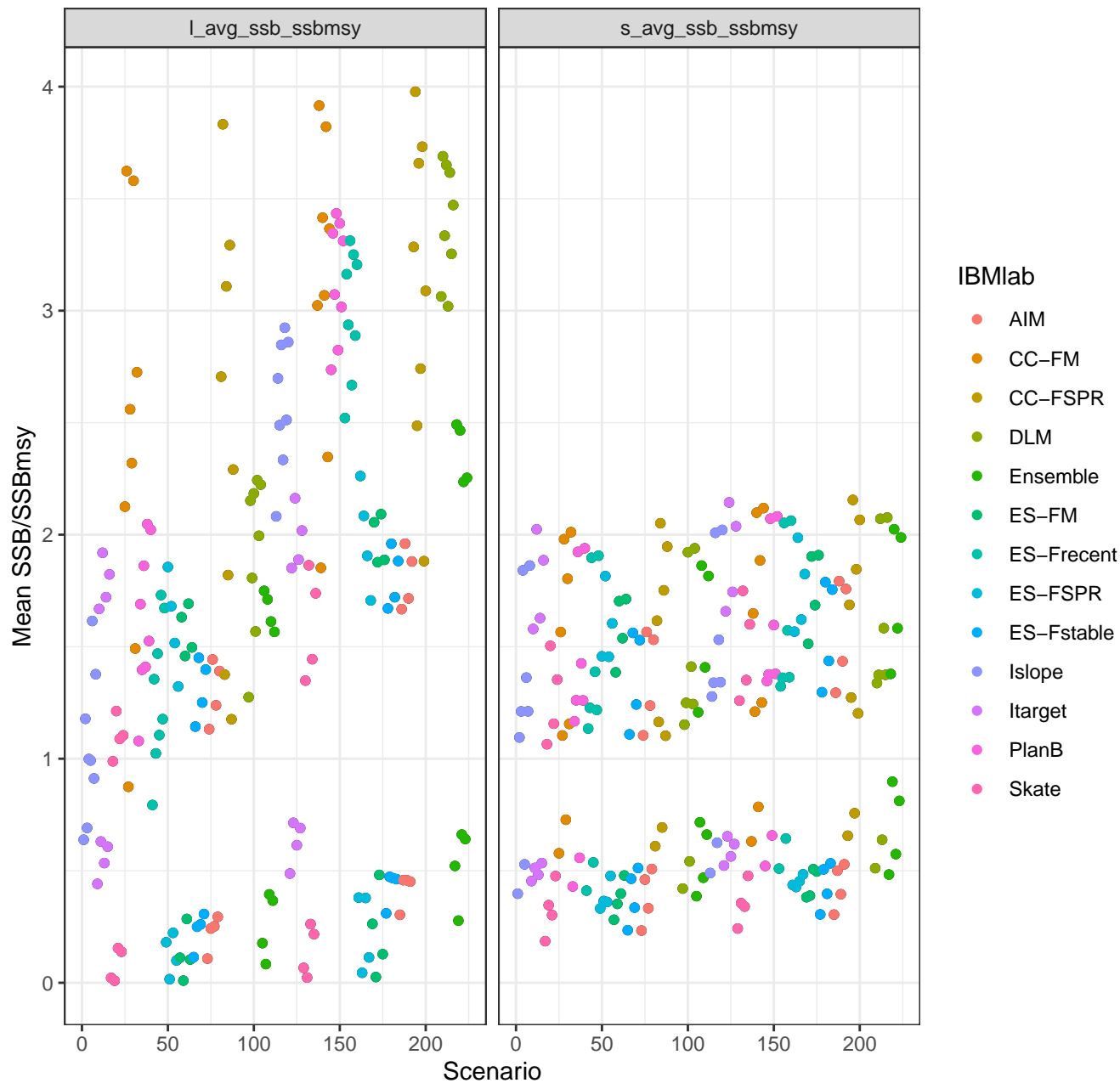
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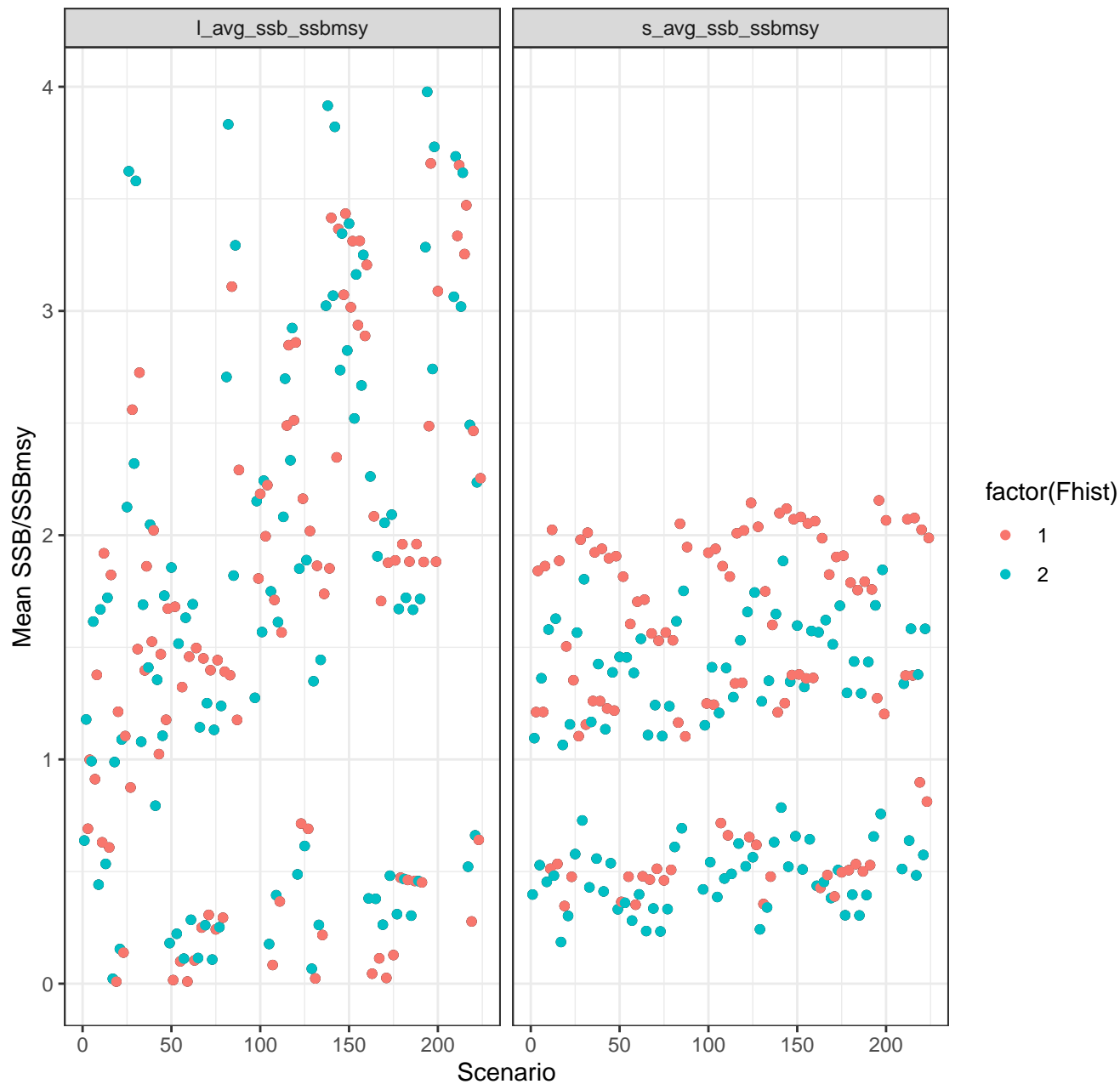
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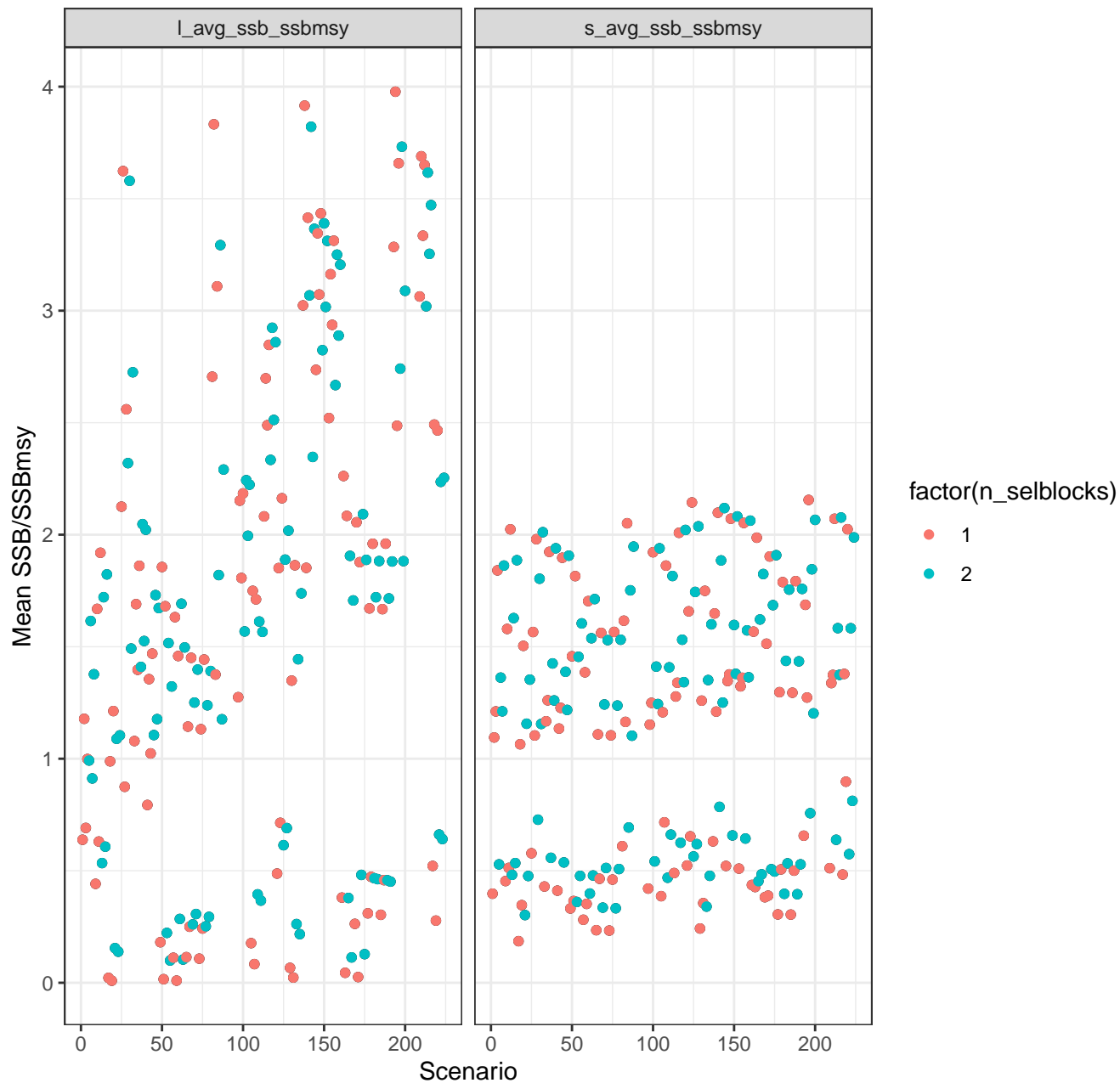
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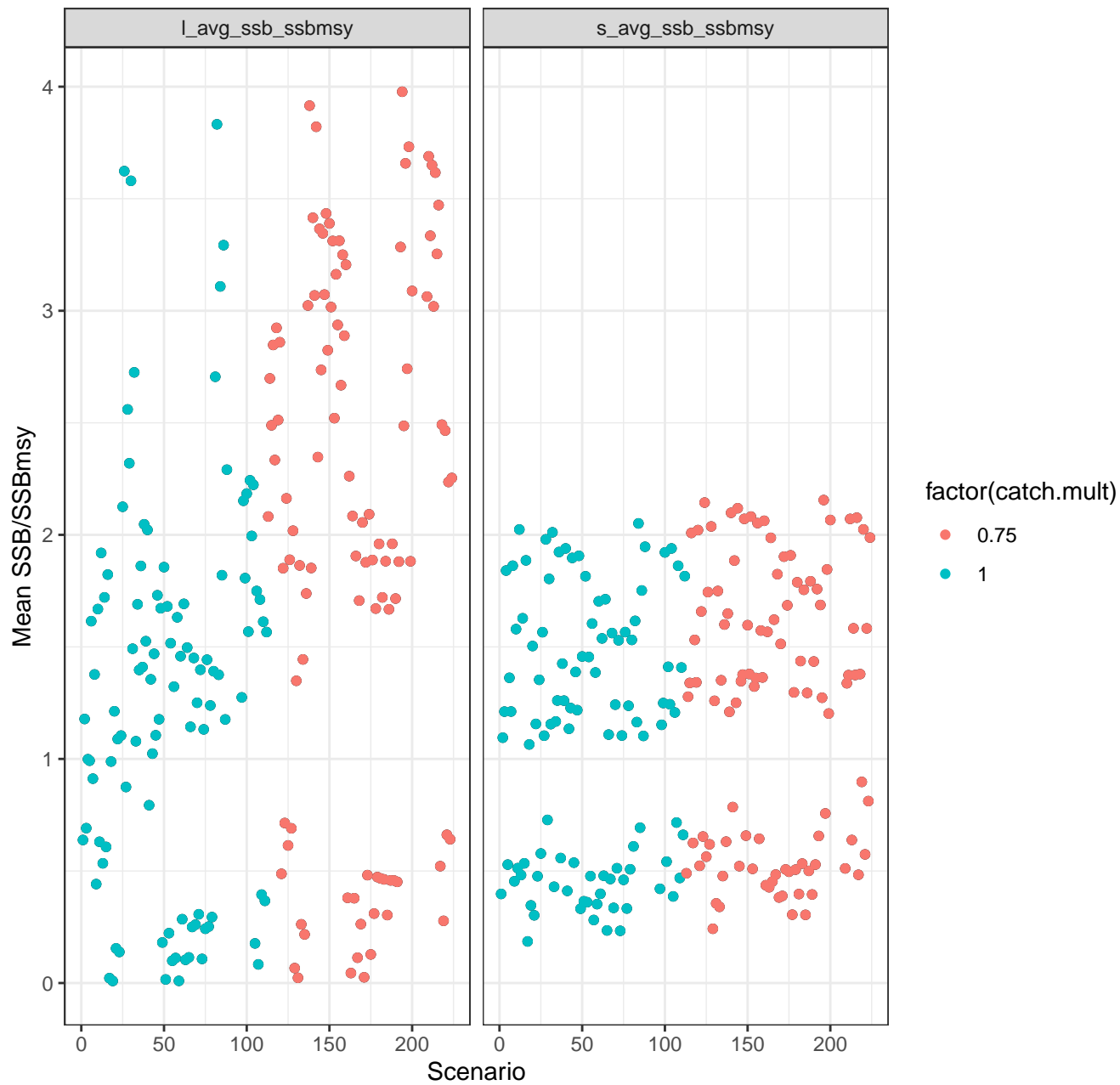
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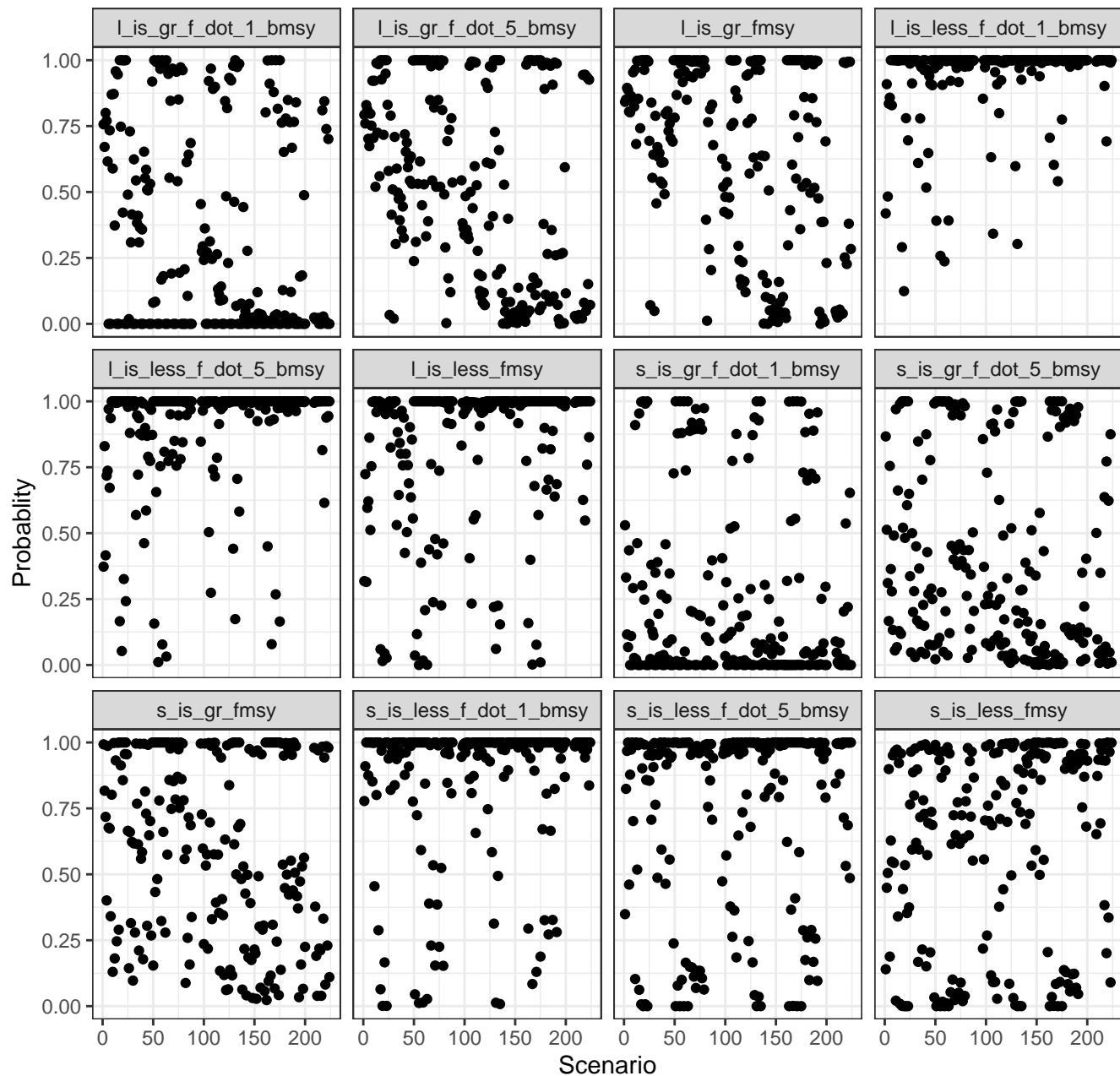
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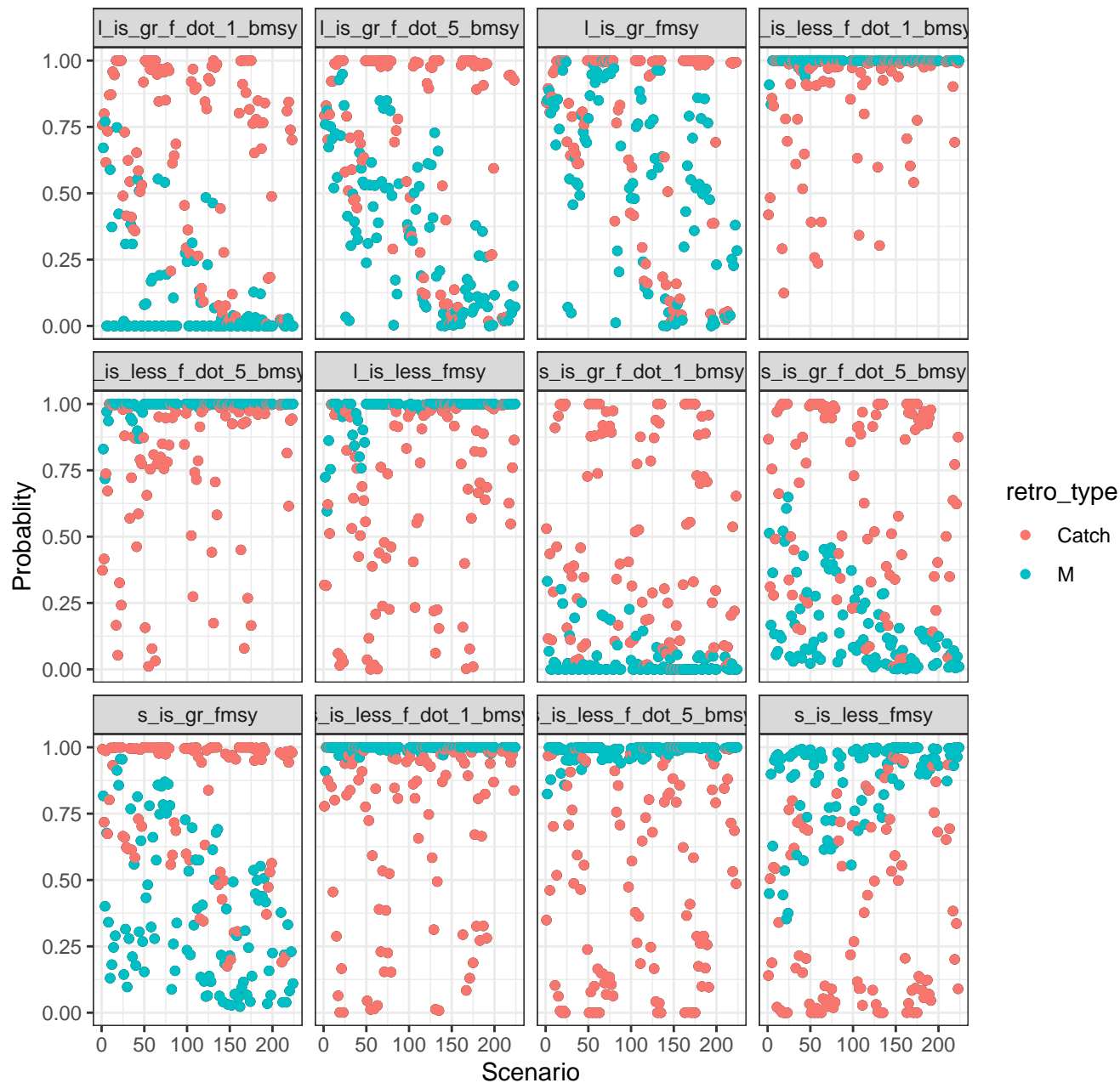
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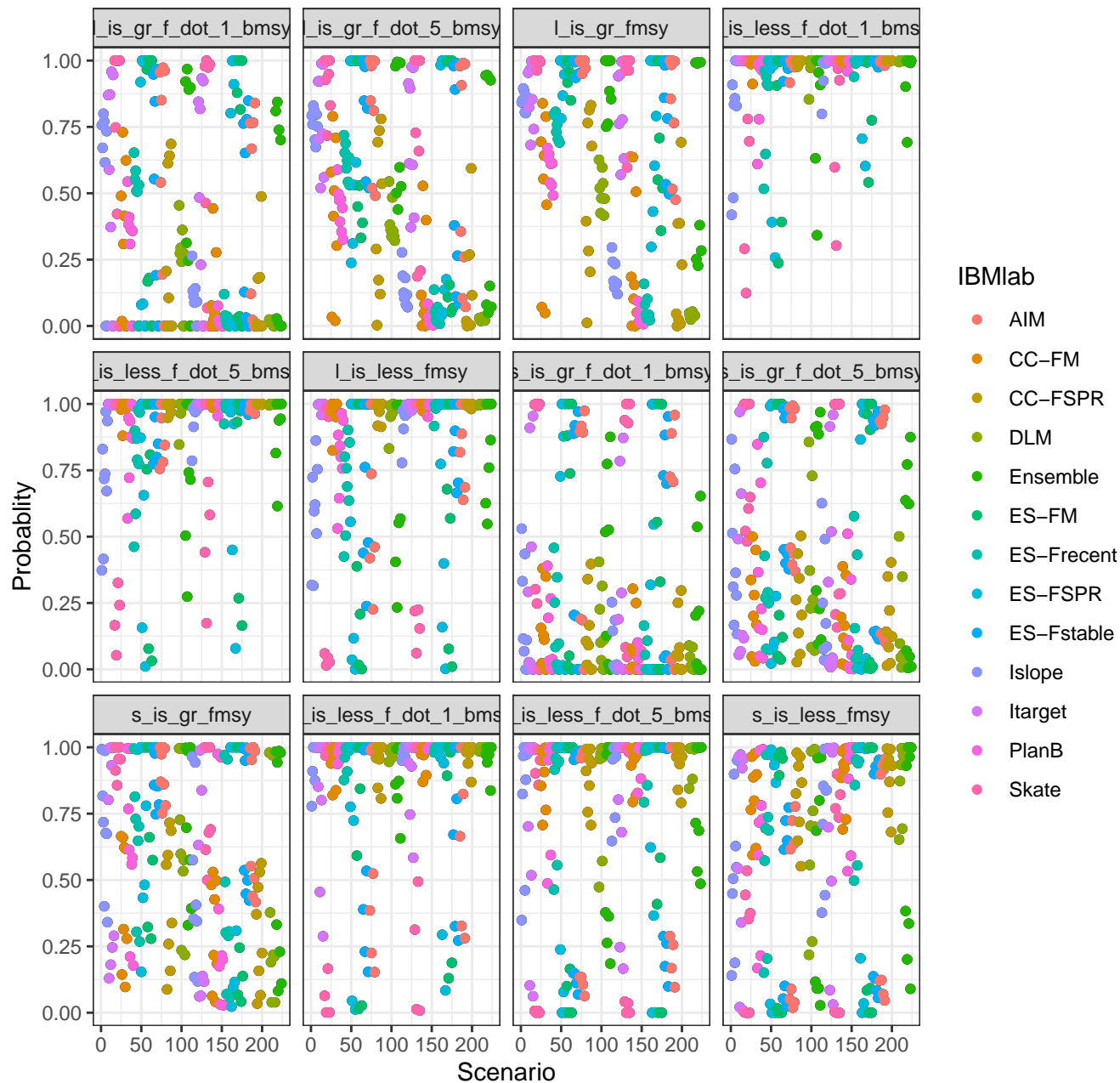
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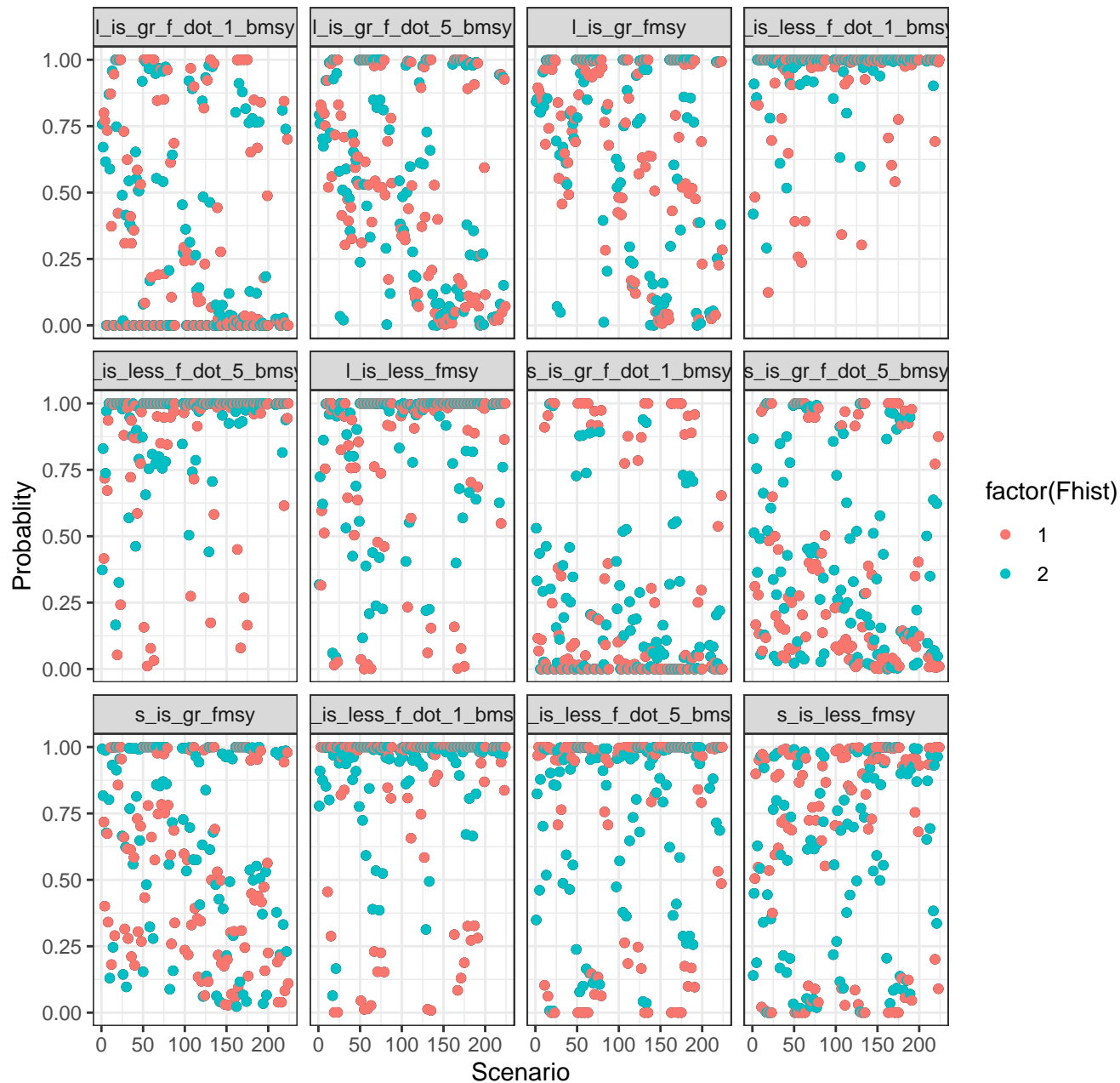
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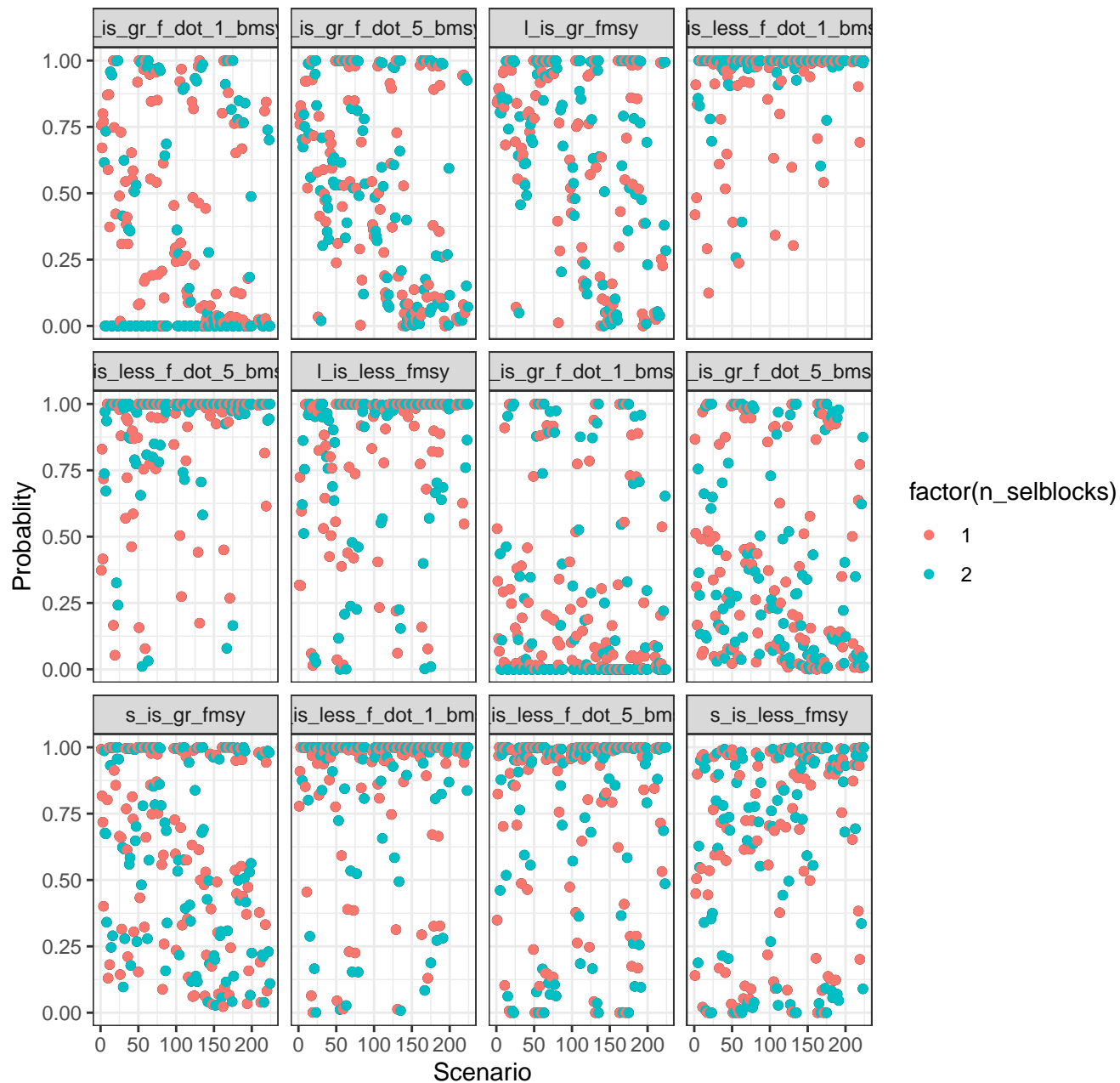
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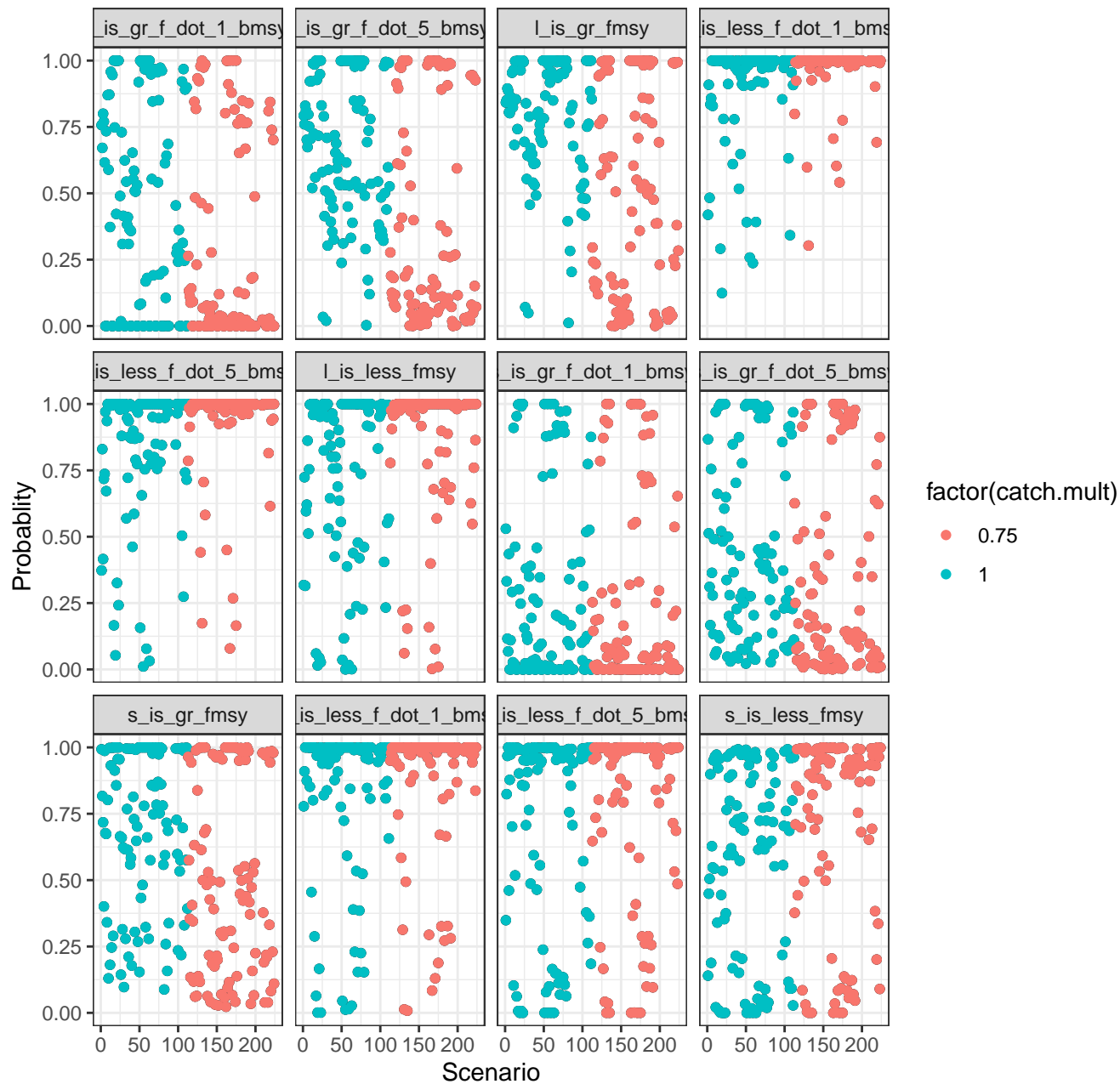
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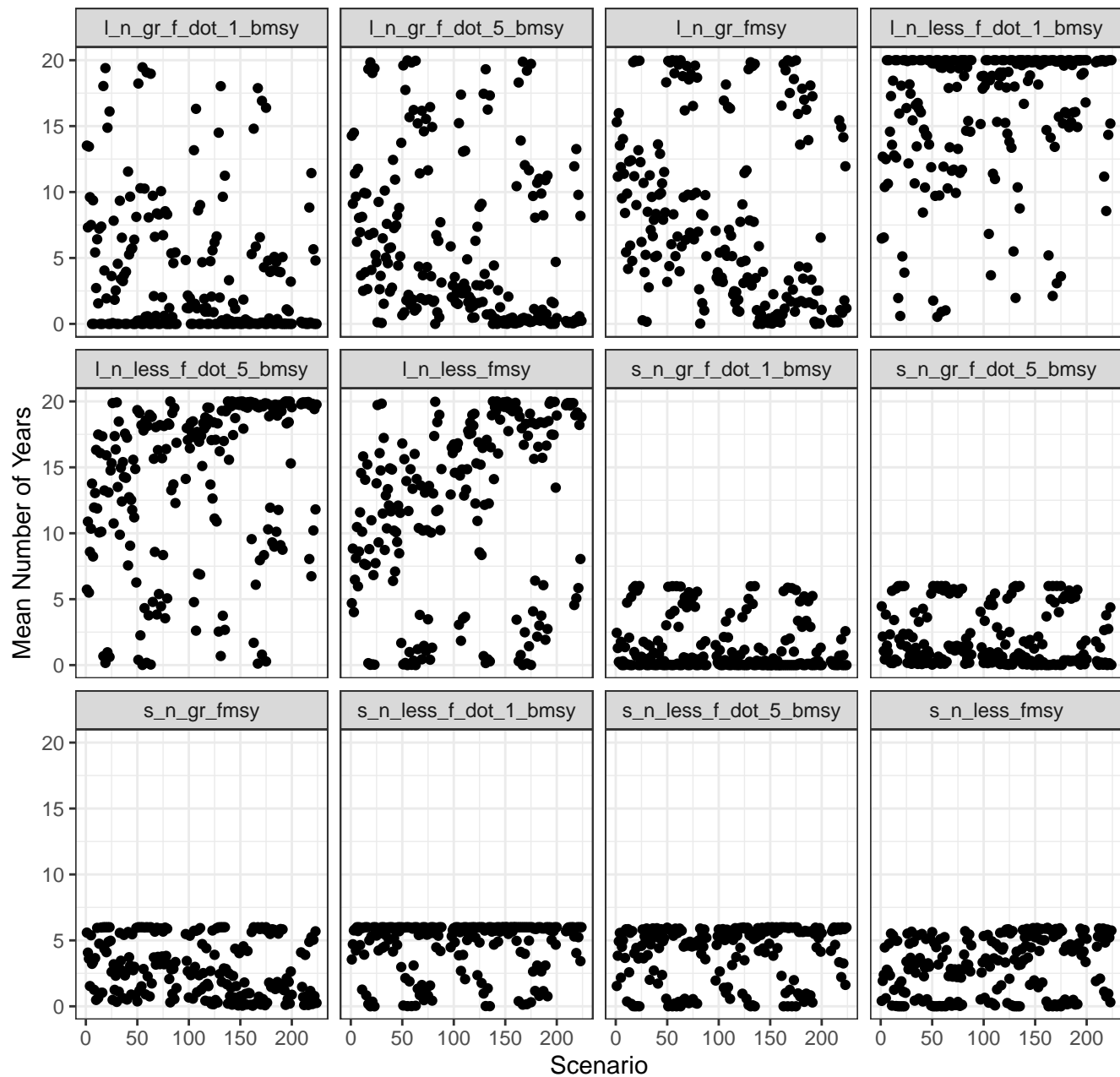
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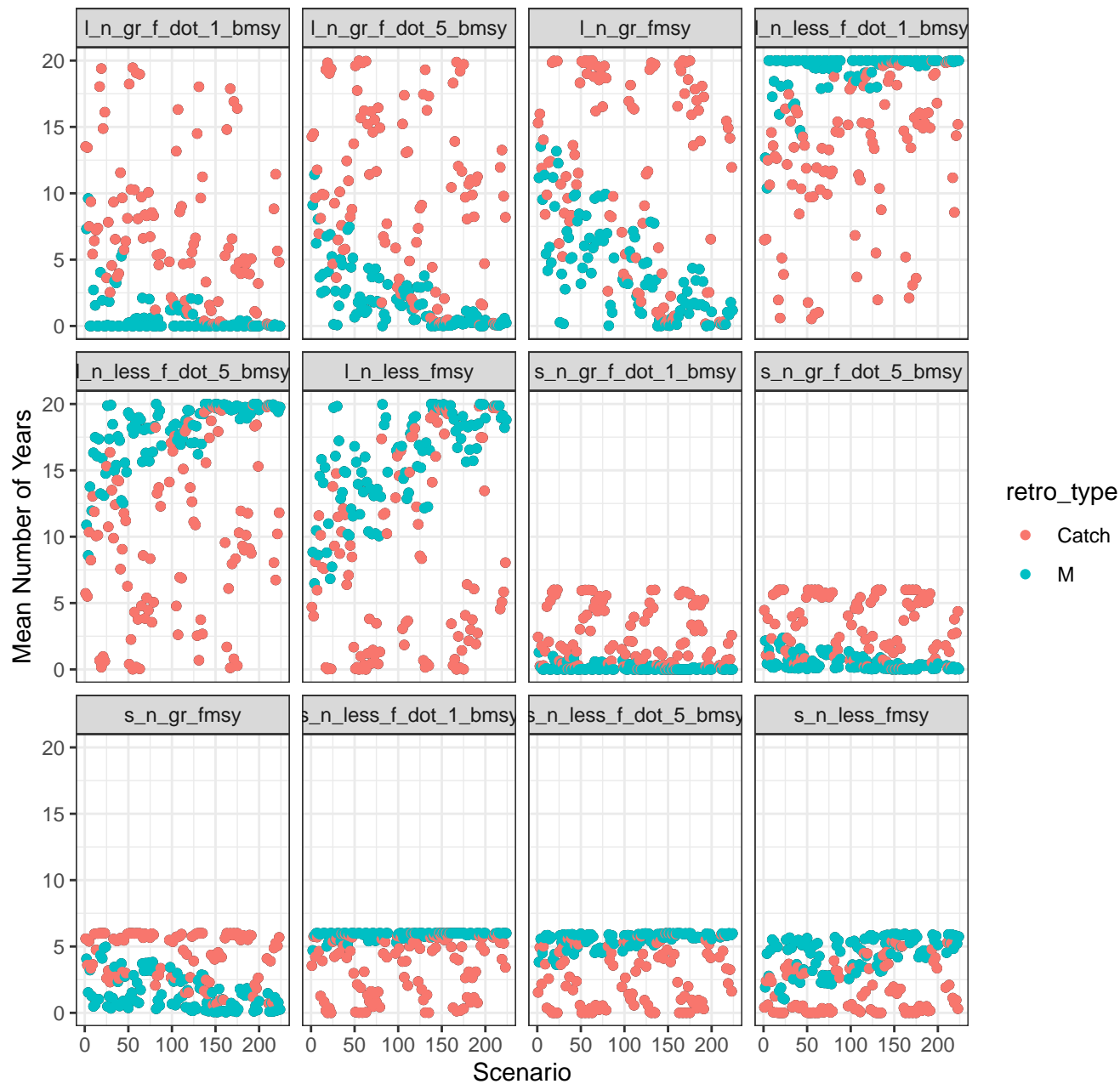
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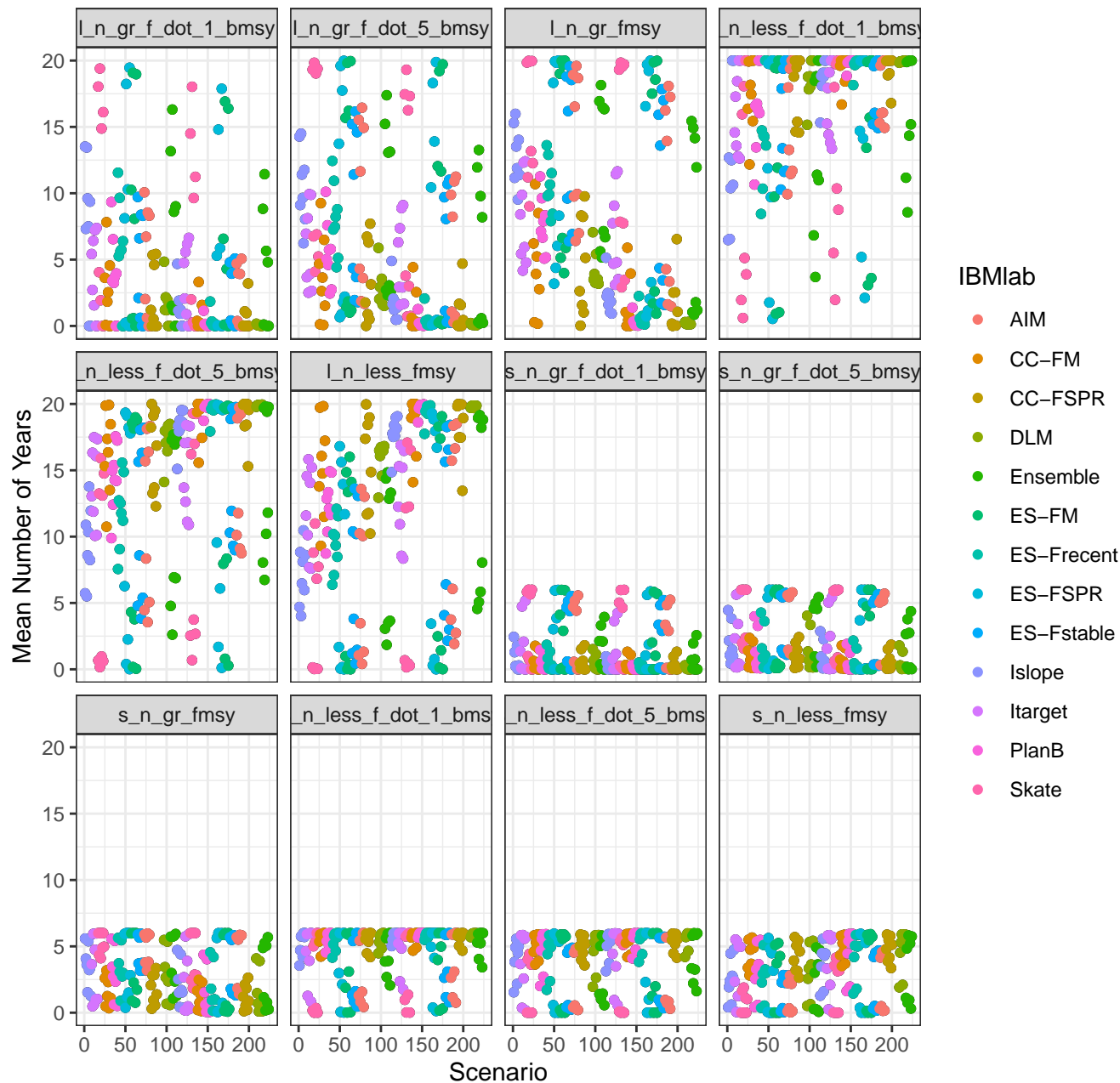
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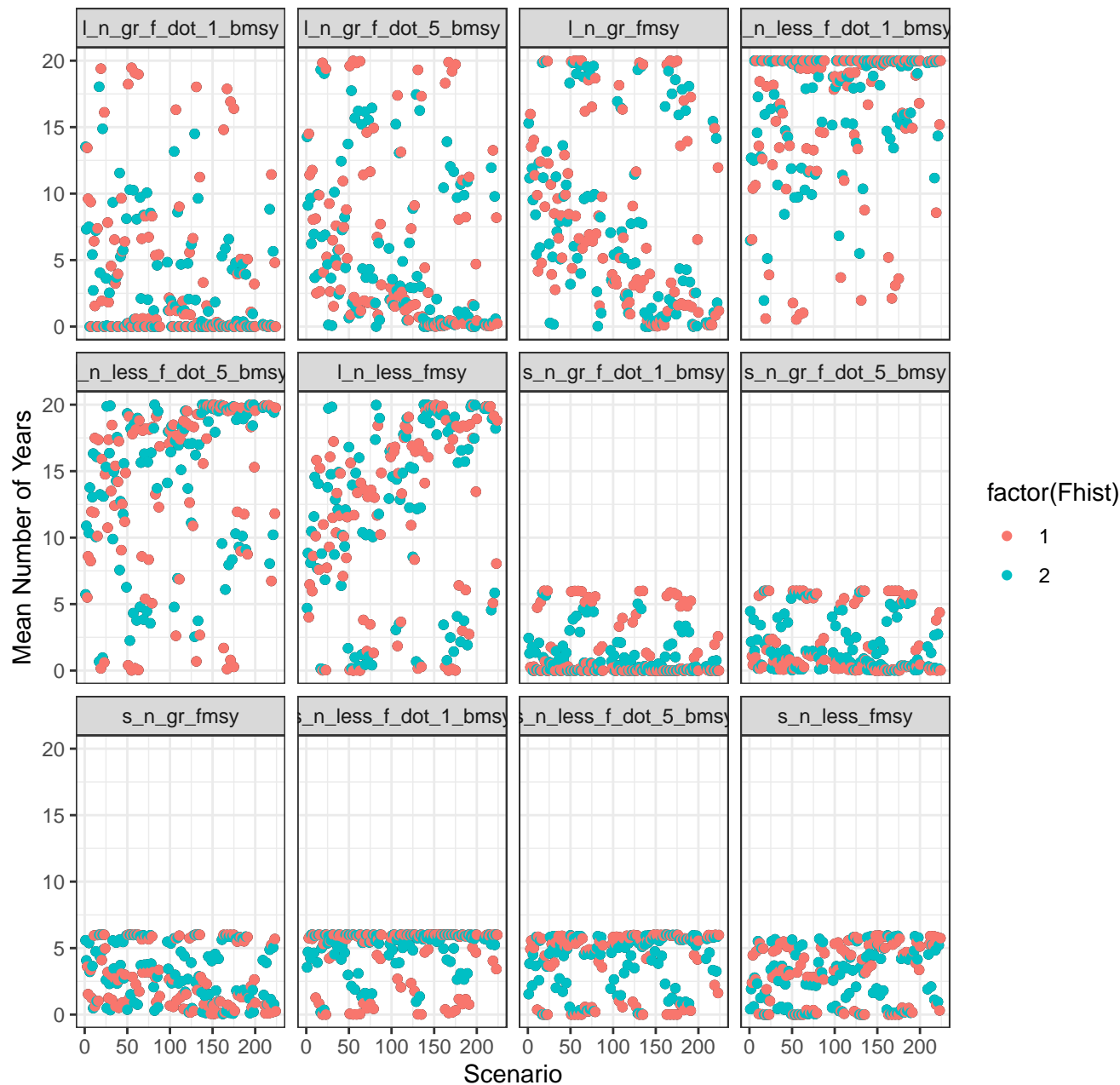
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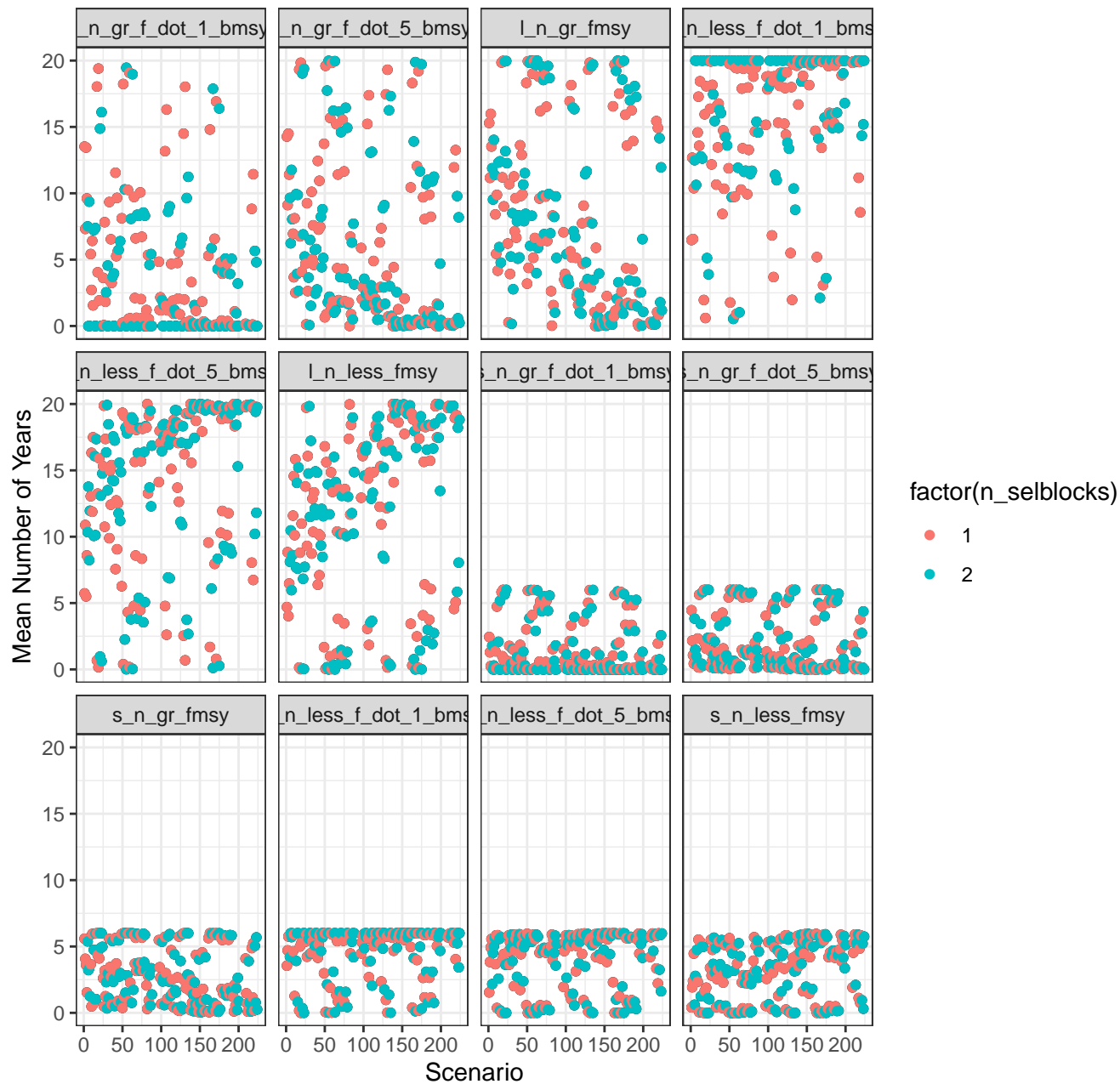
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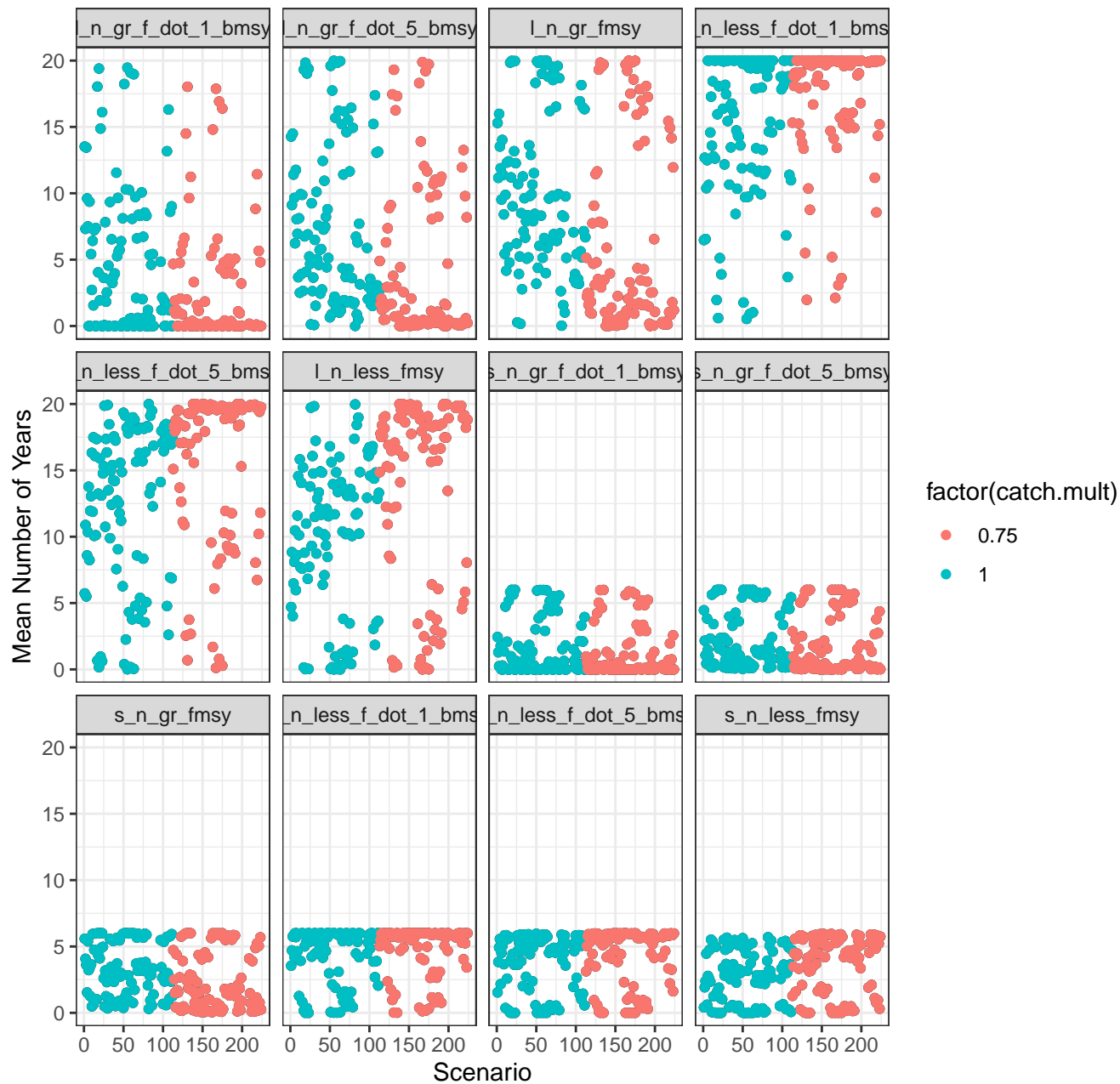
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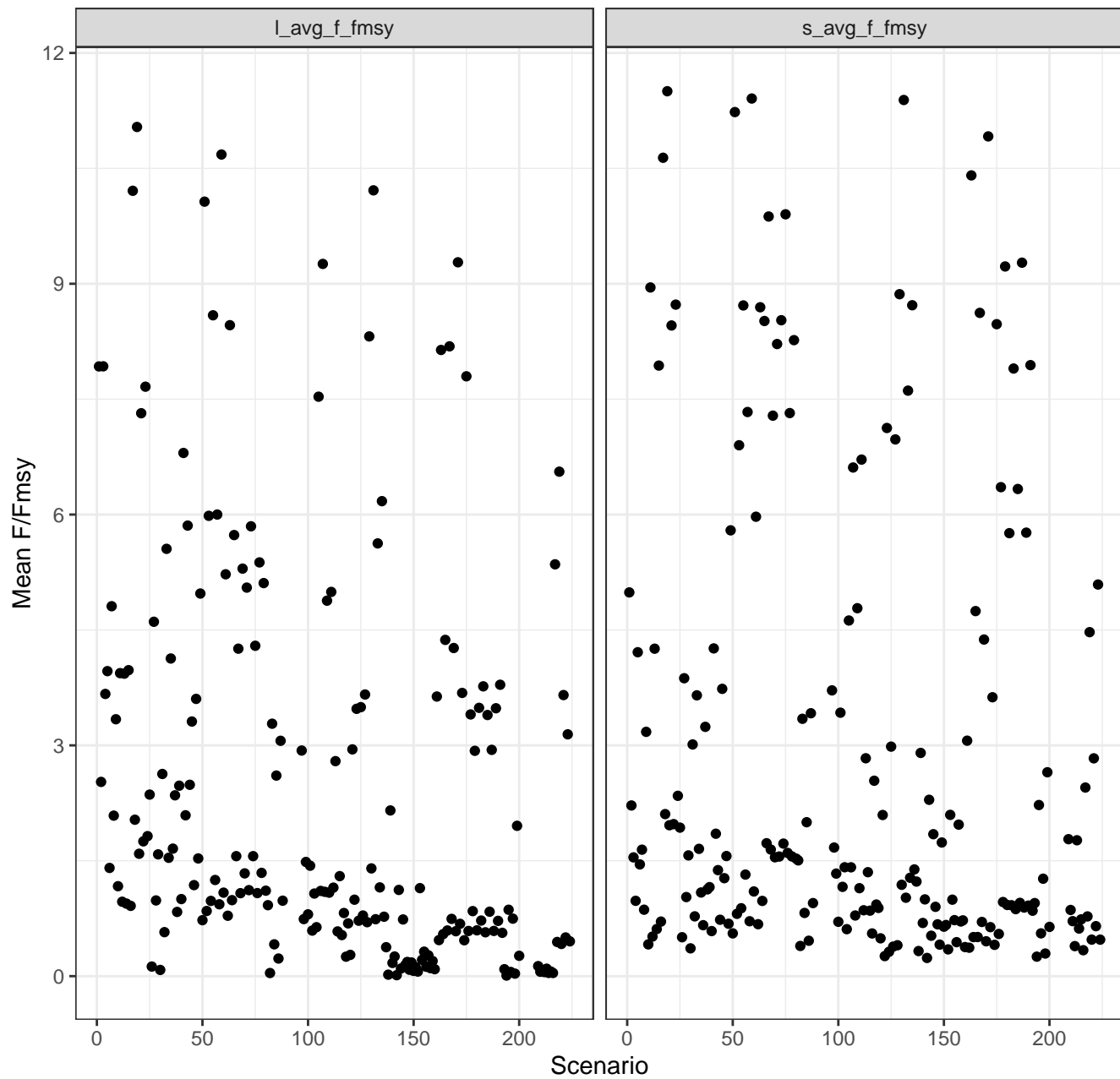
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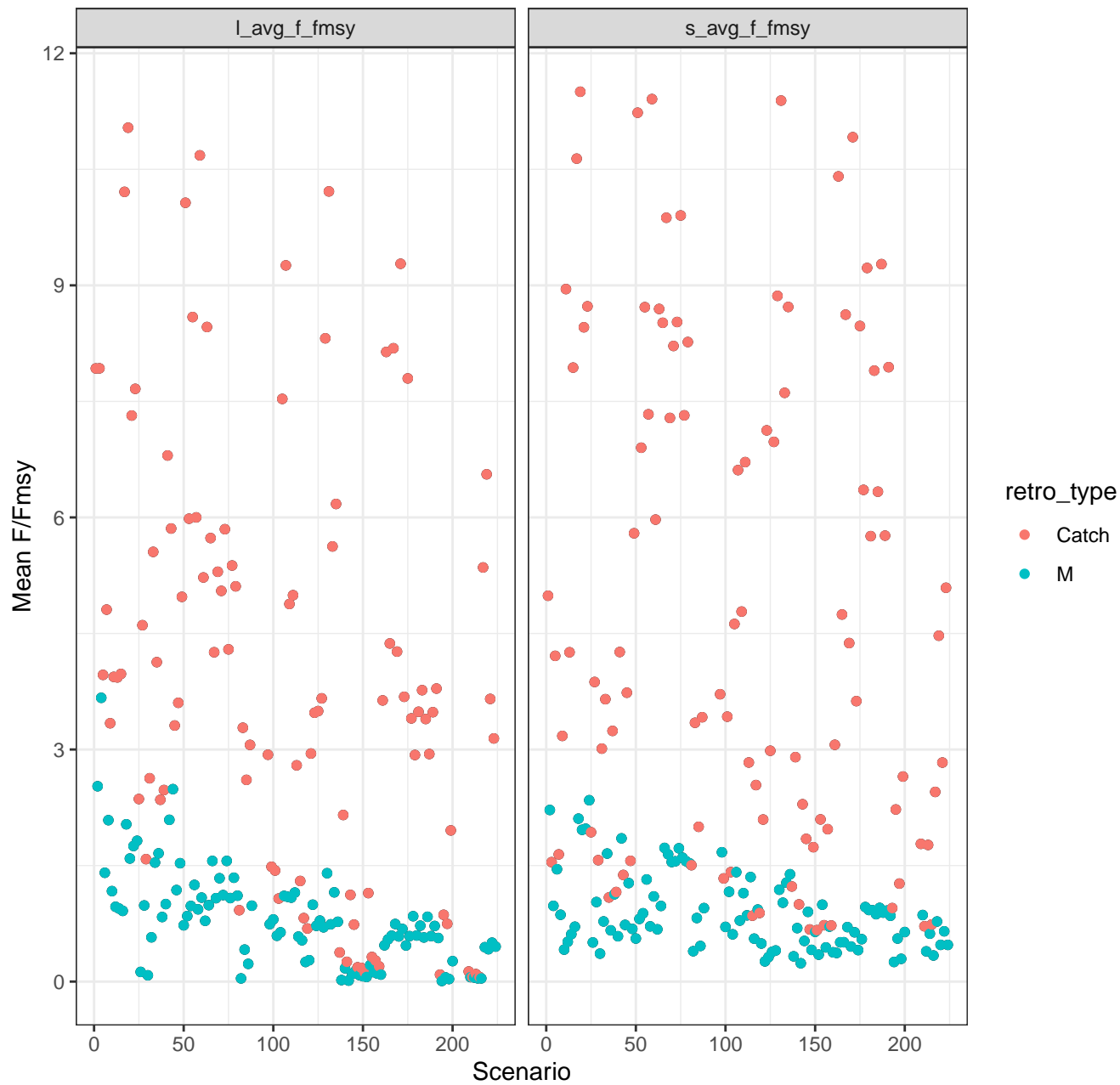
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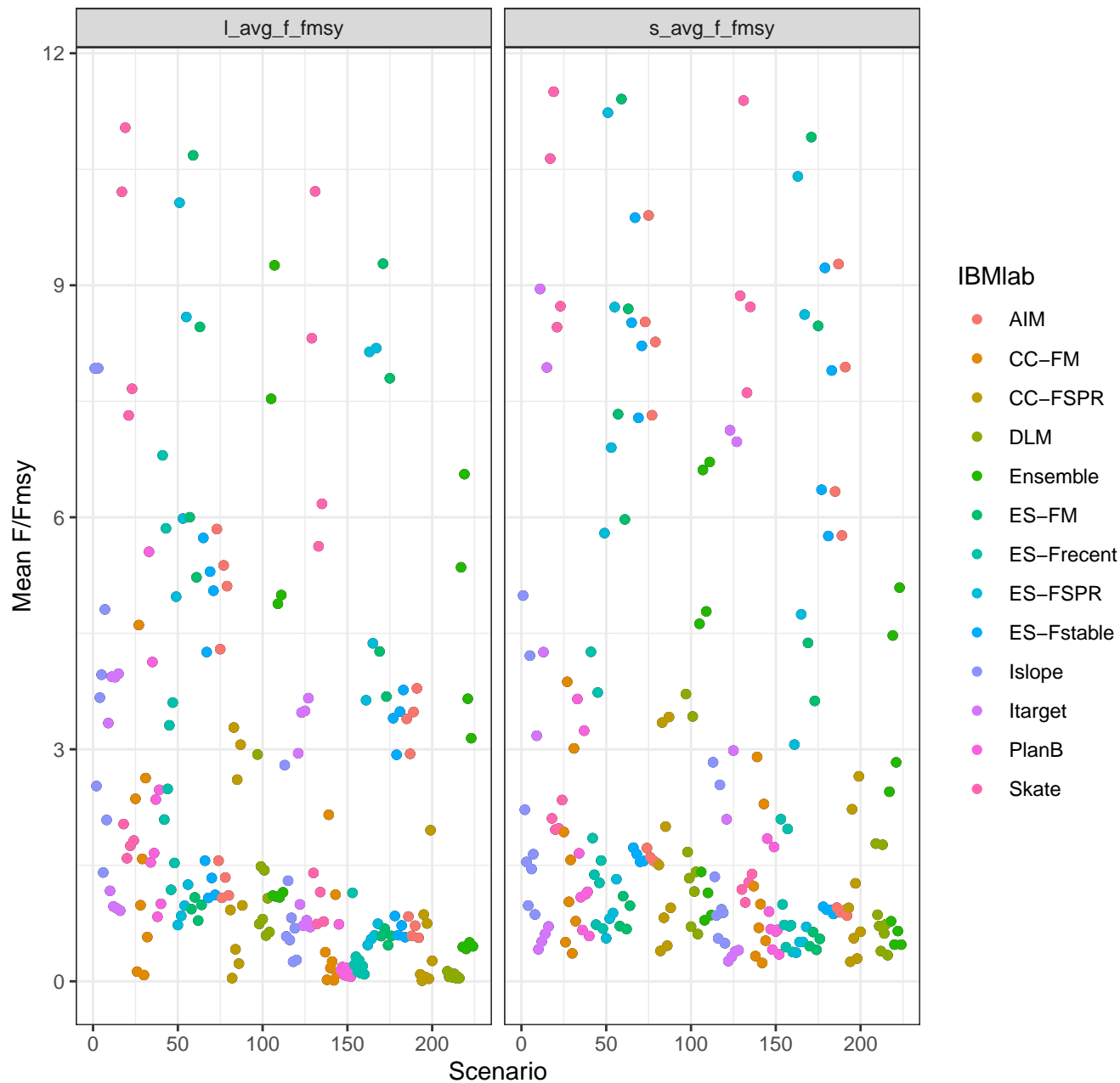
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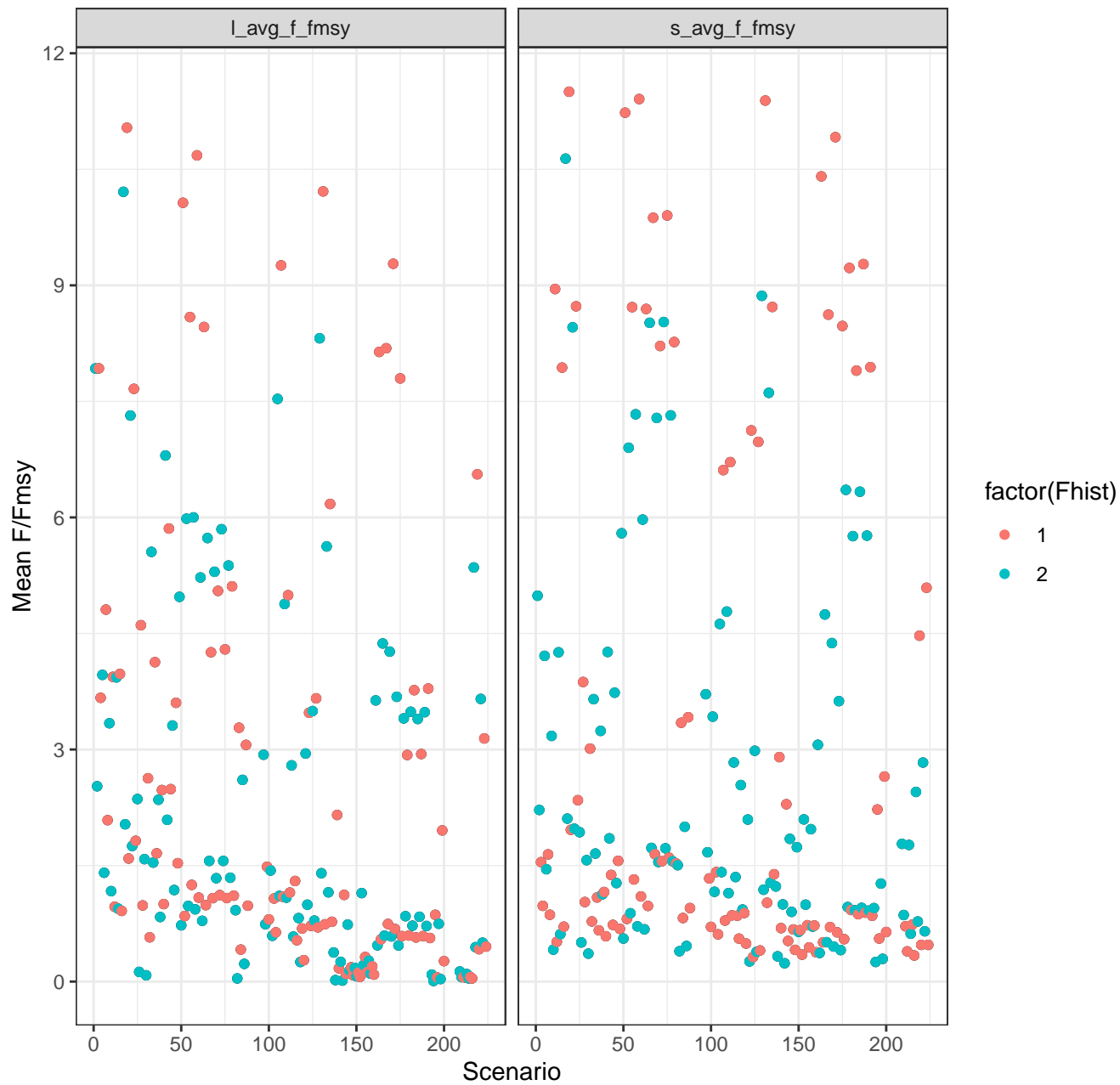
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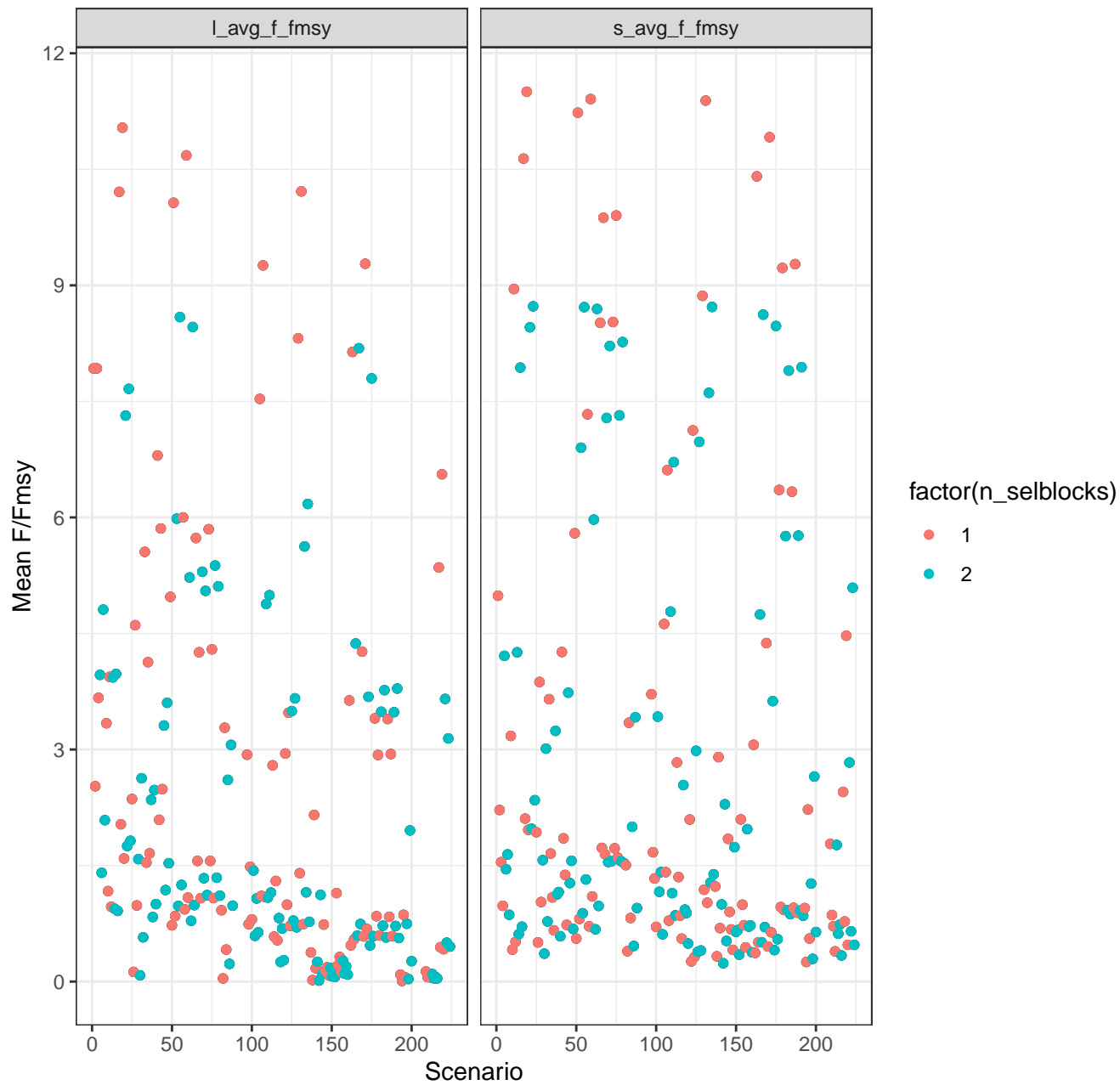
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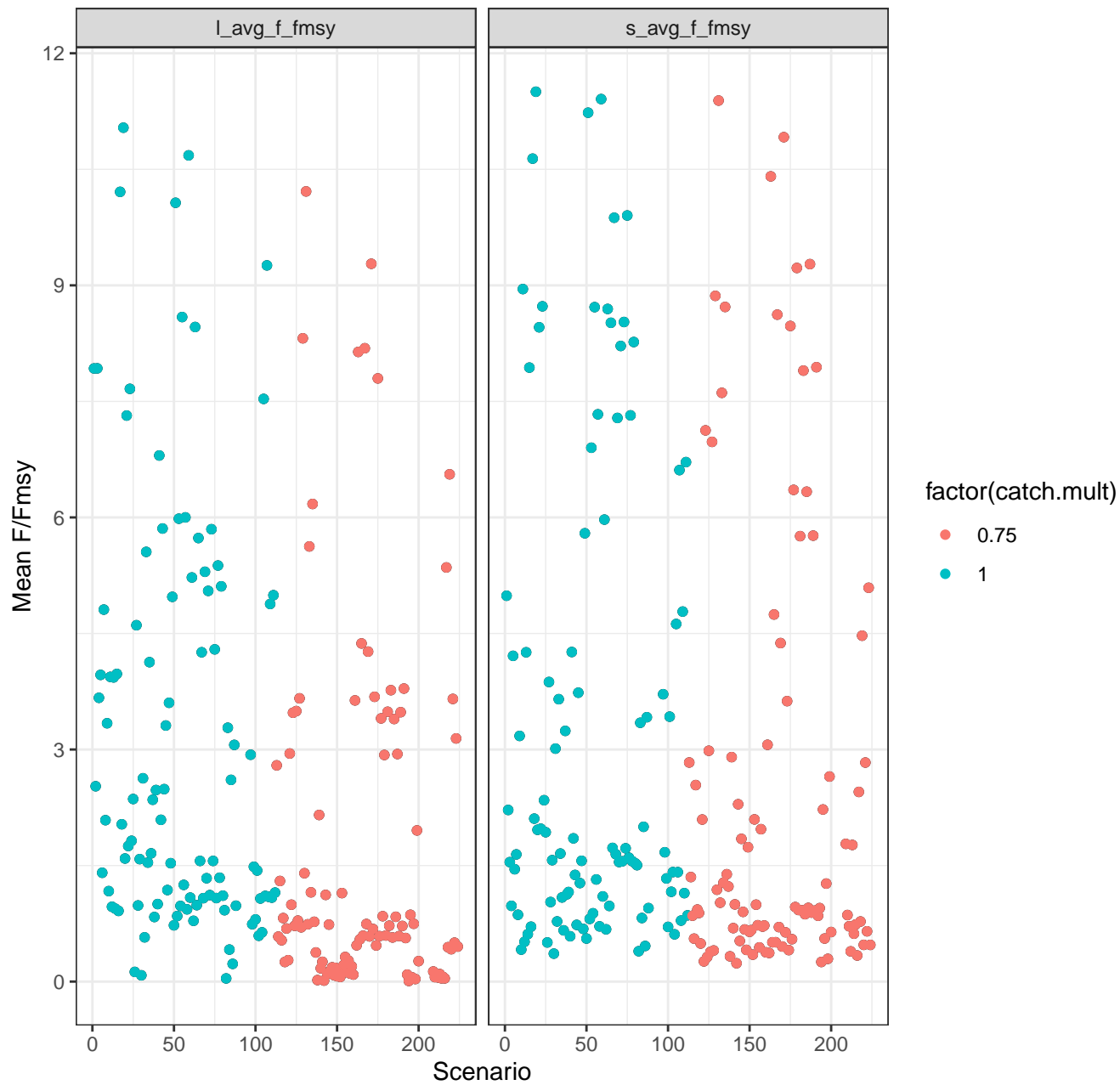
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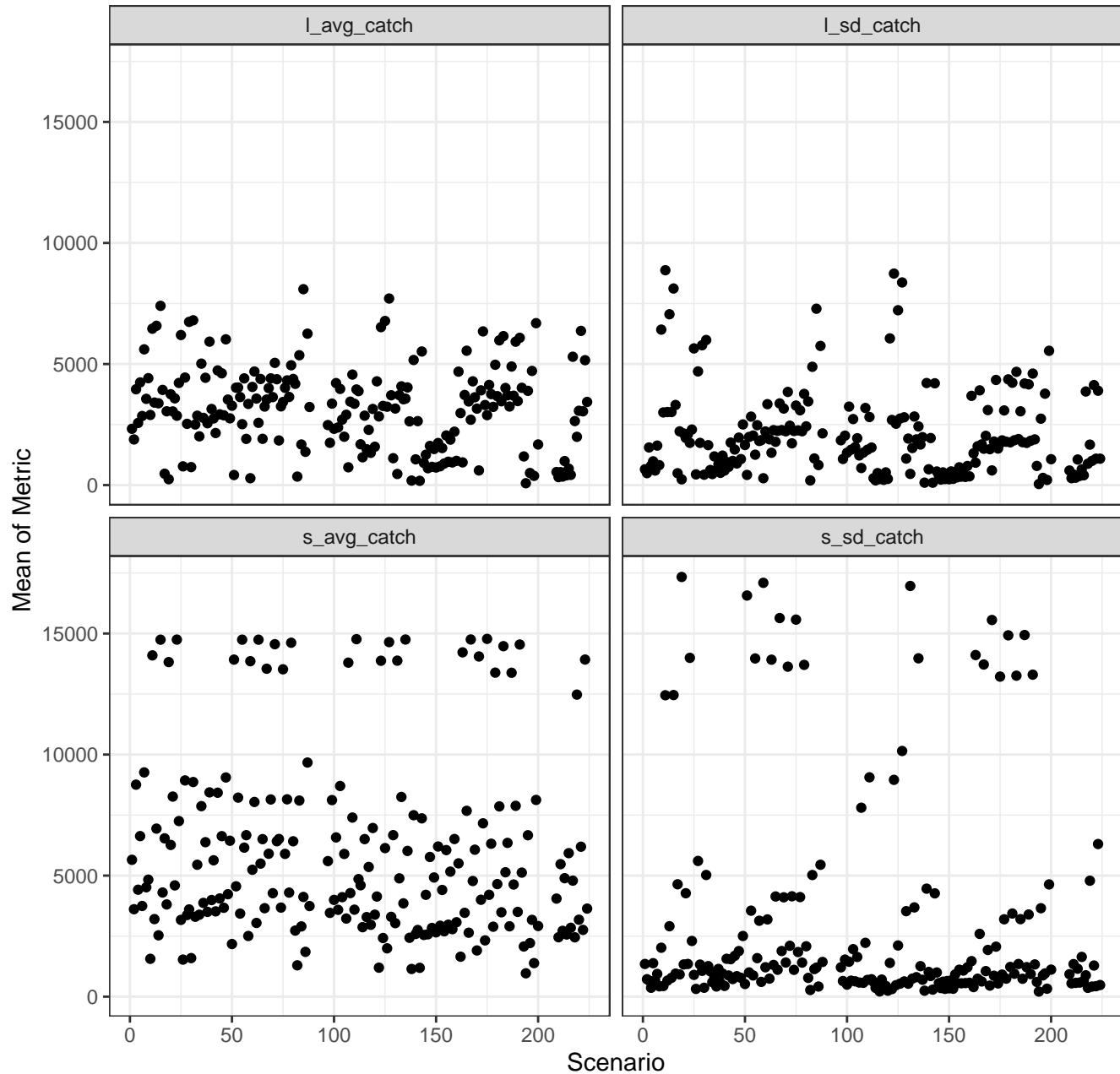
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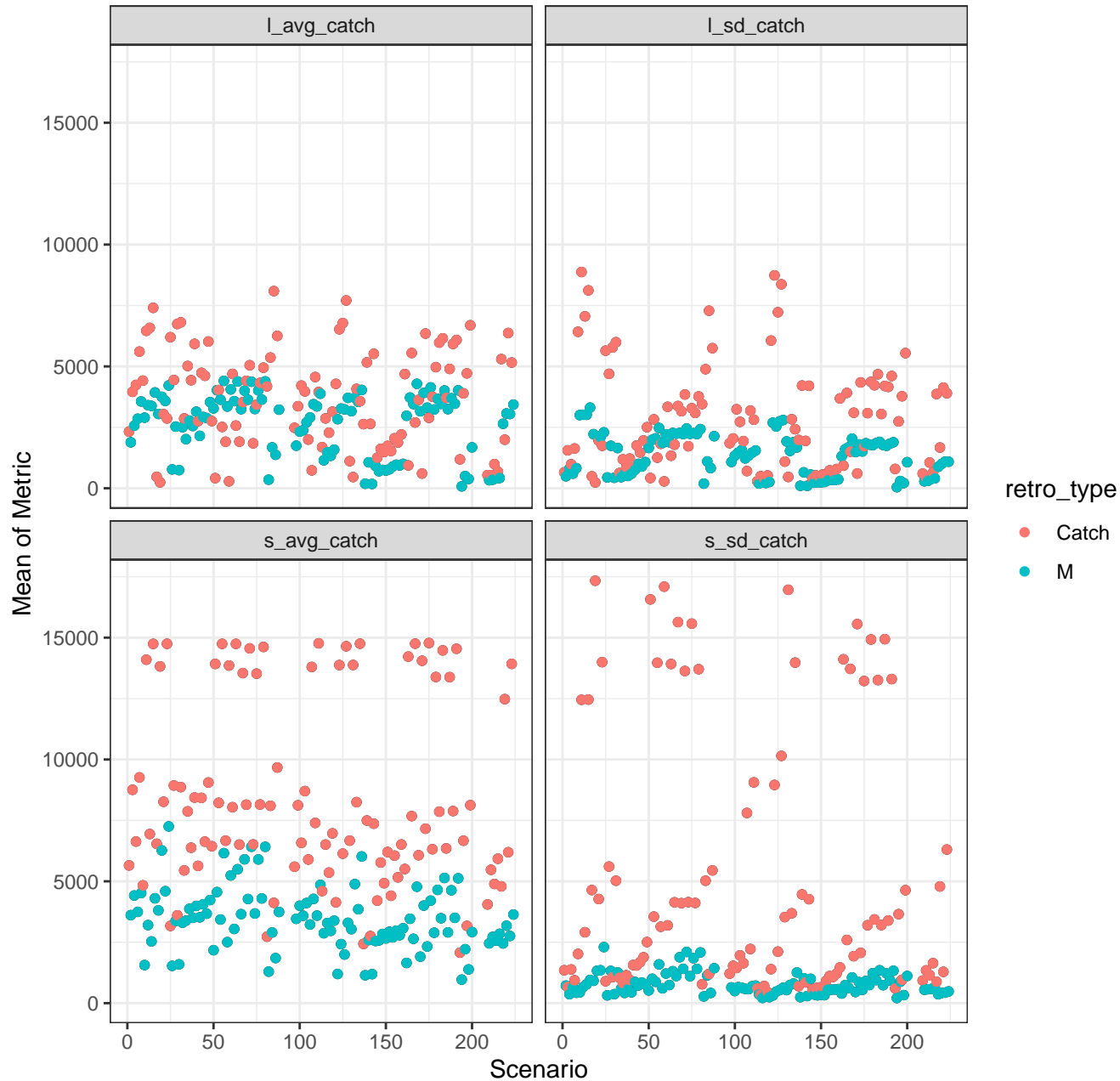
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Catch

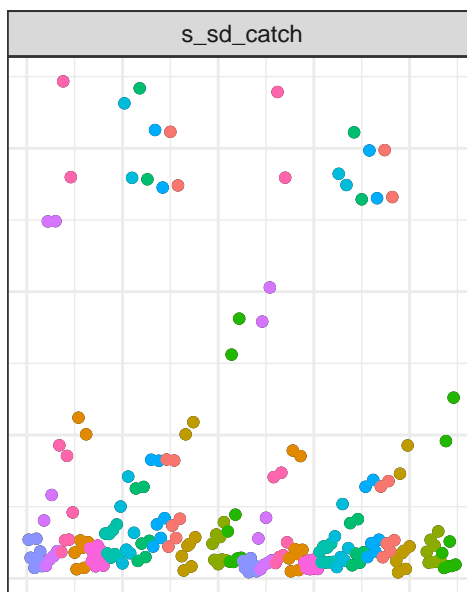
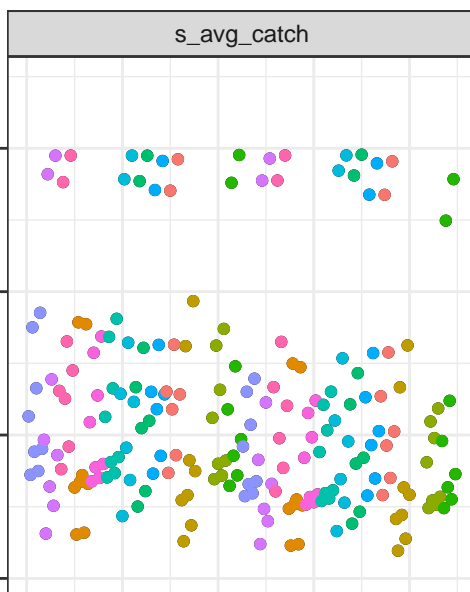
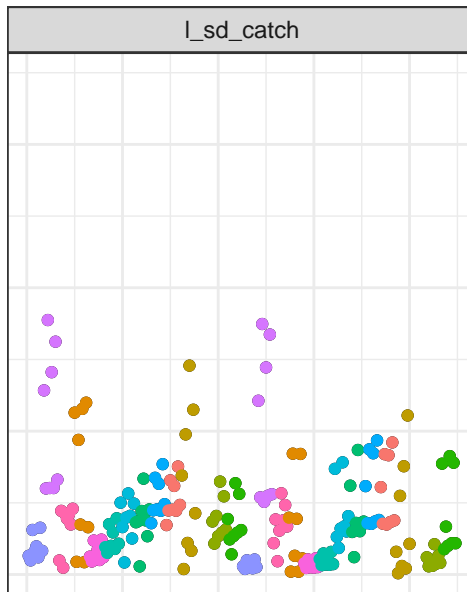
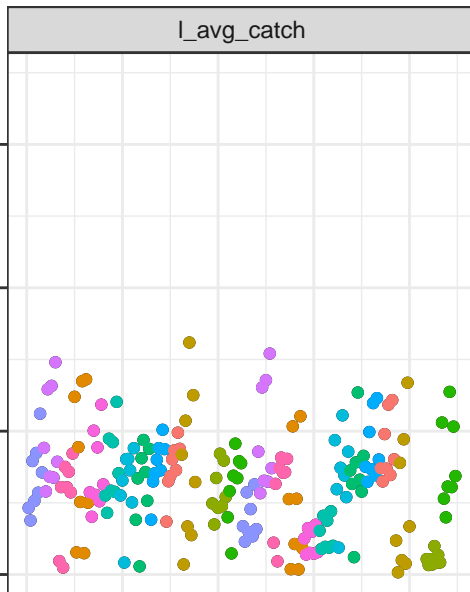


Catch



Catch

Mean of Metric

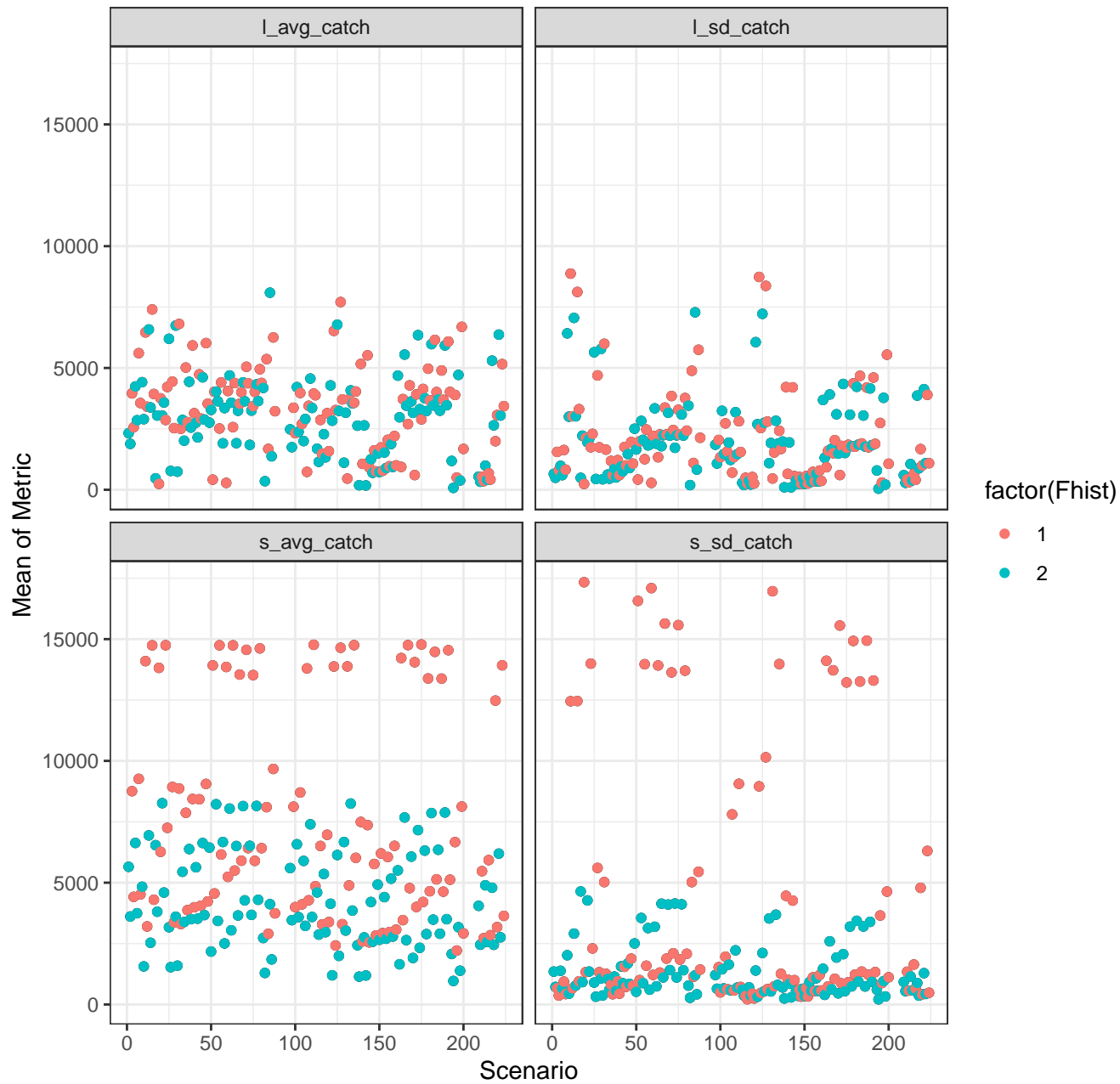


IBMlab

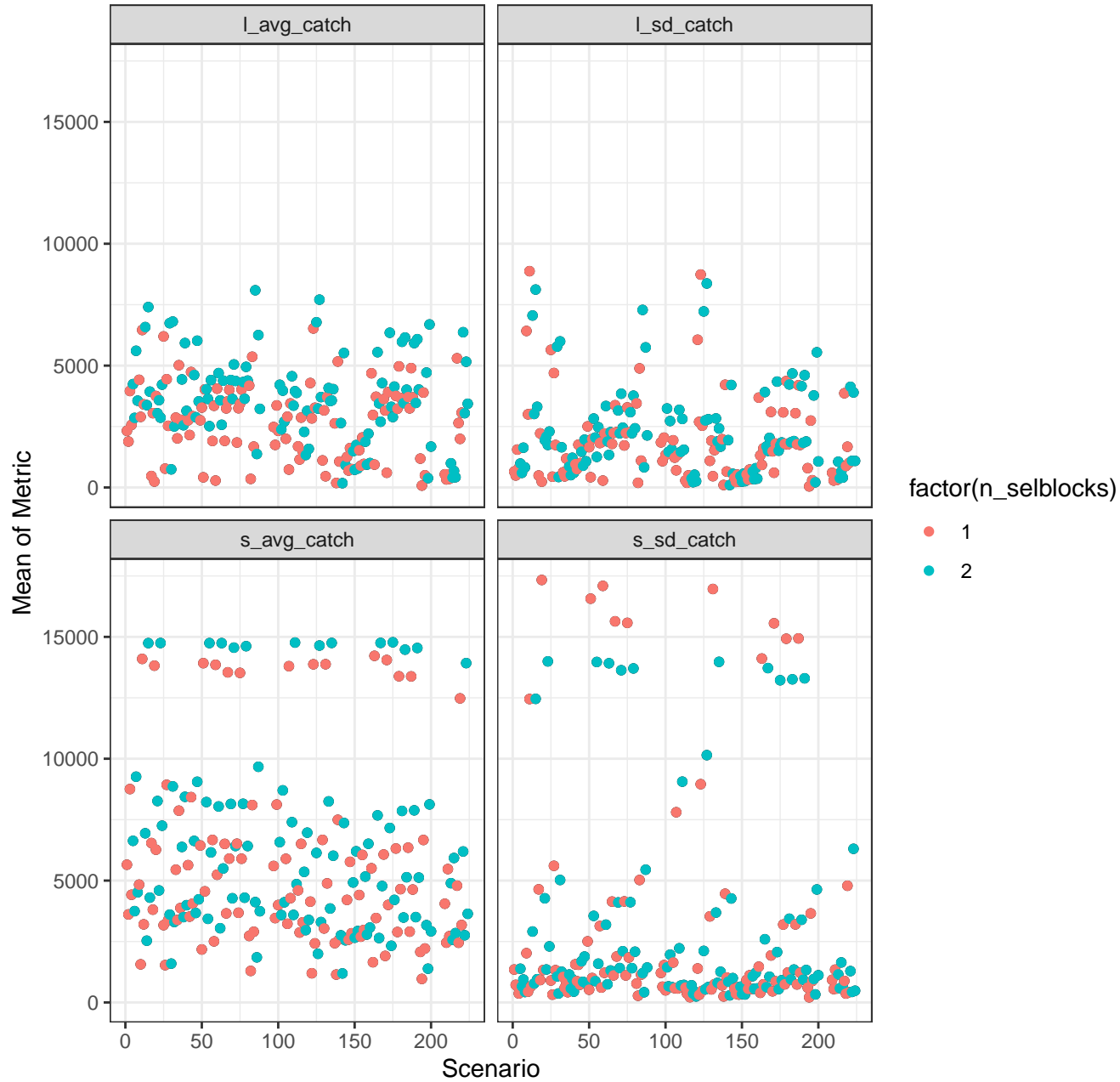
- AIM
- CC-FM
- CC-FSPR
- DLM
- Ensemble
- ES-FM
- ES-Frecent
- ES-FSPR
- ES-Fstable
- Islope
- Itarget
- PlanB
- Skate

Scenario

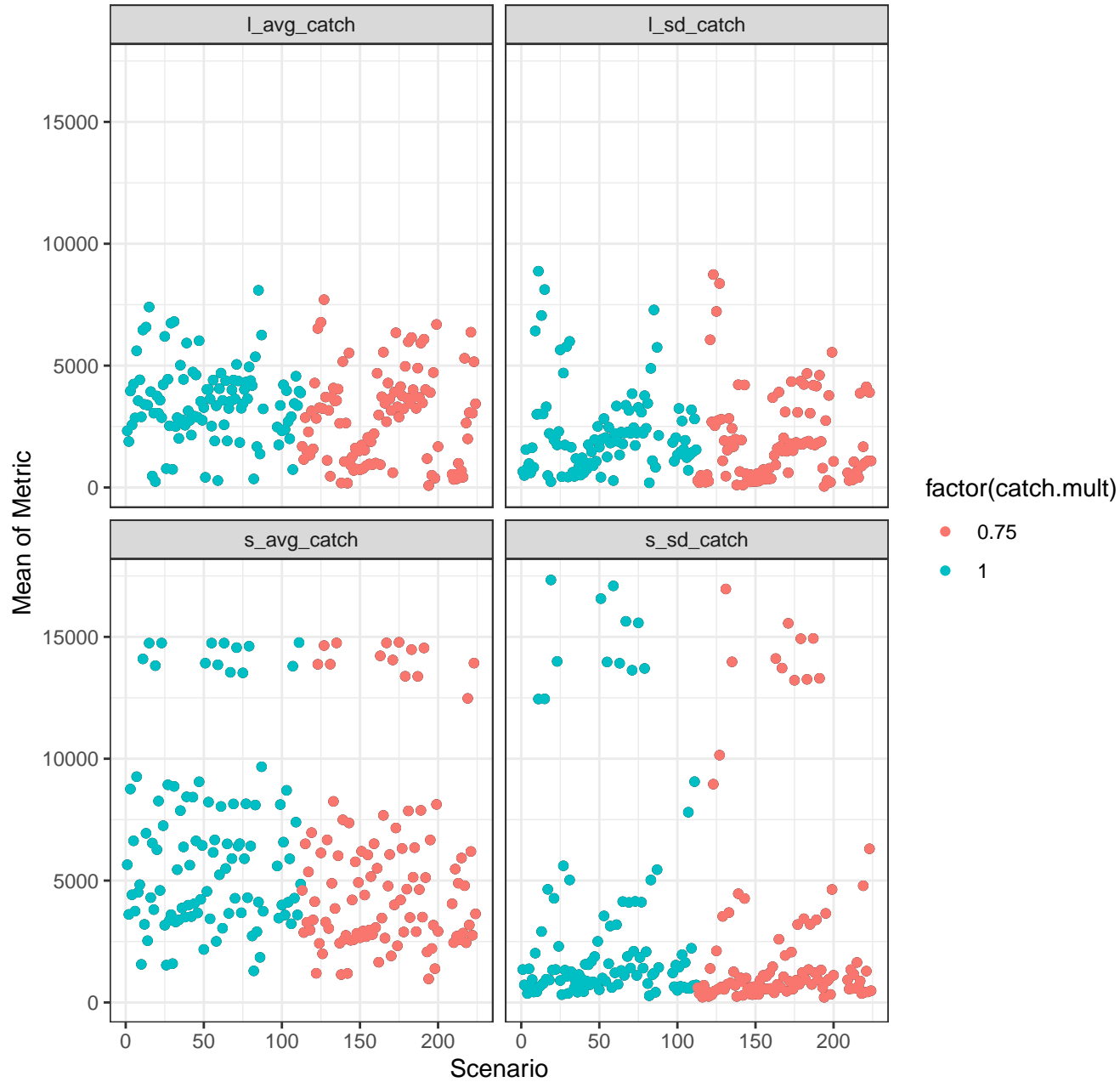
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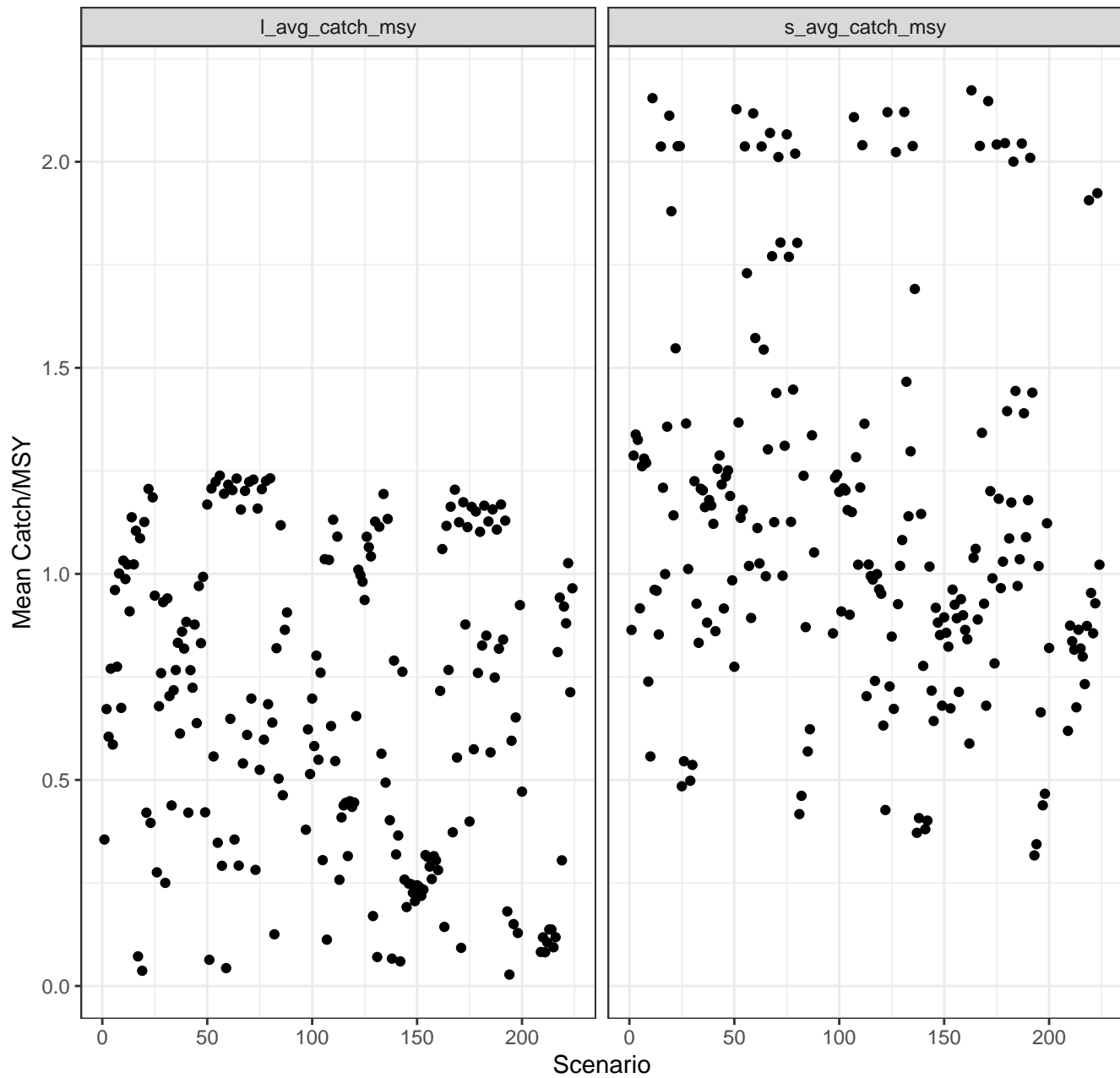
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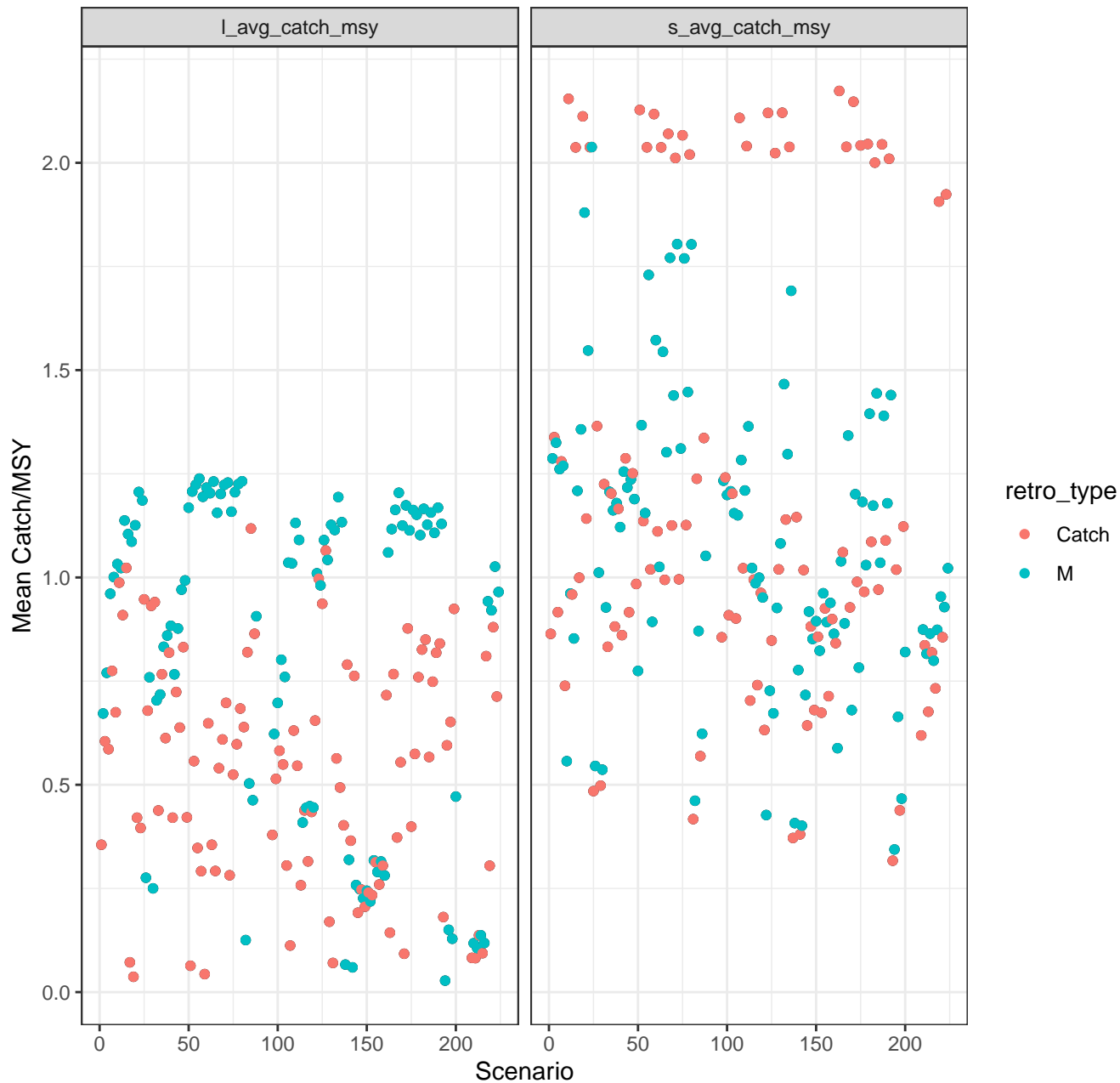
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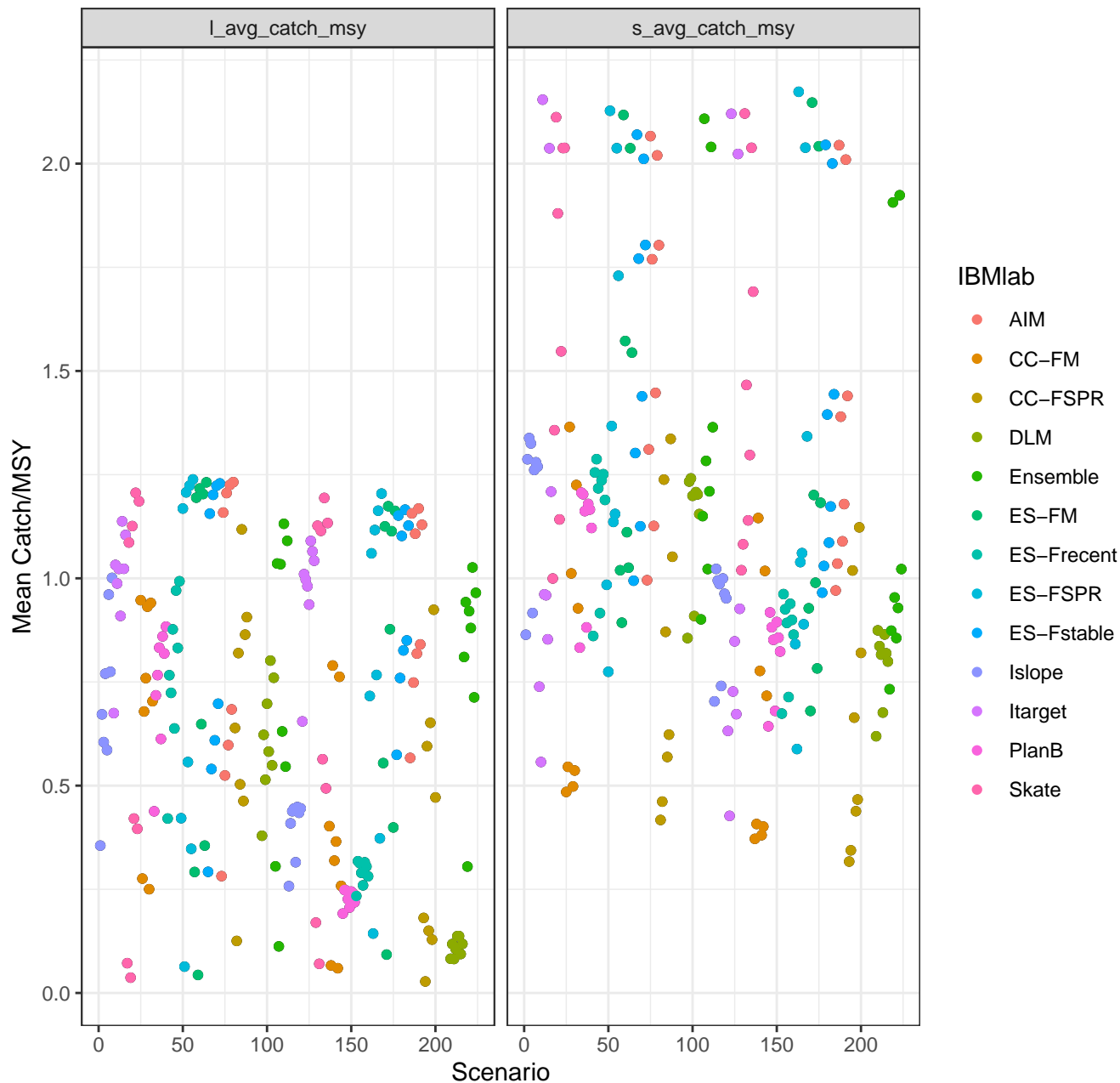
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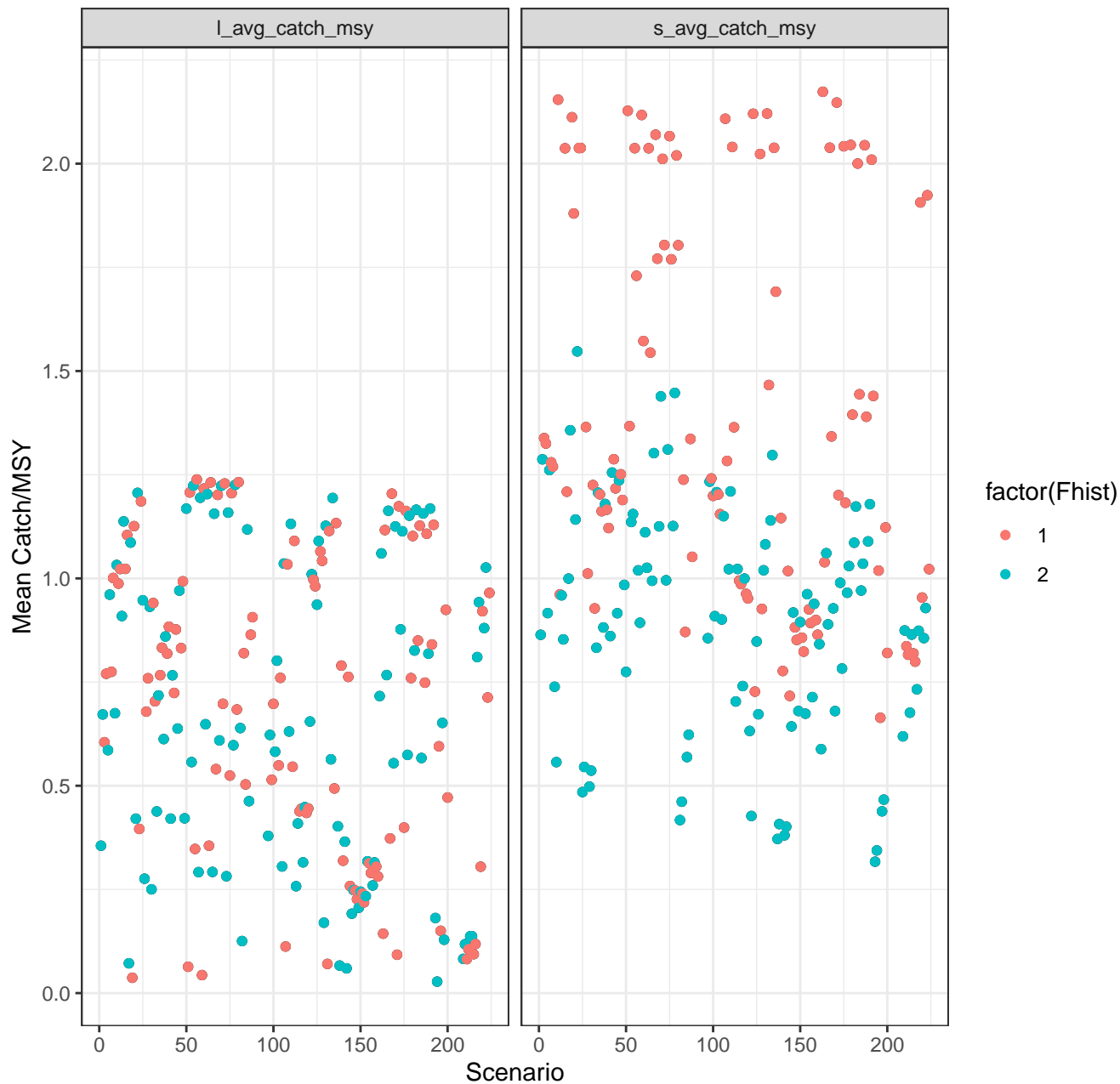
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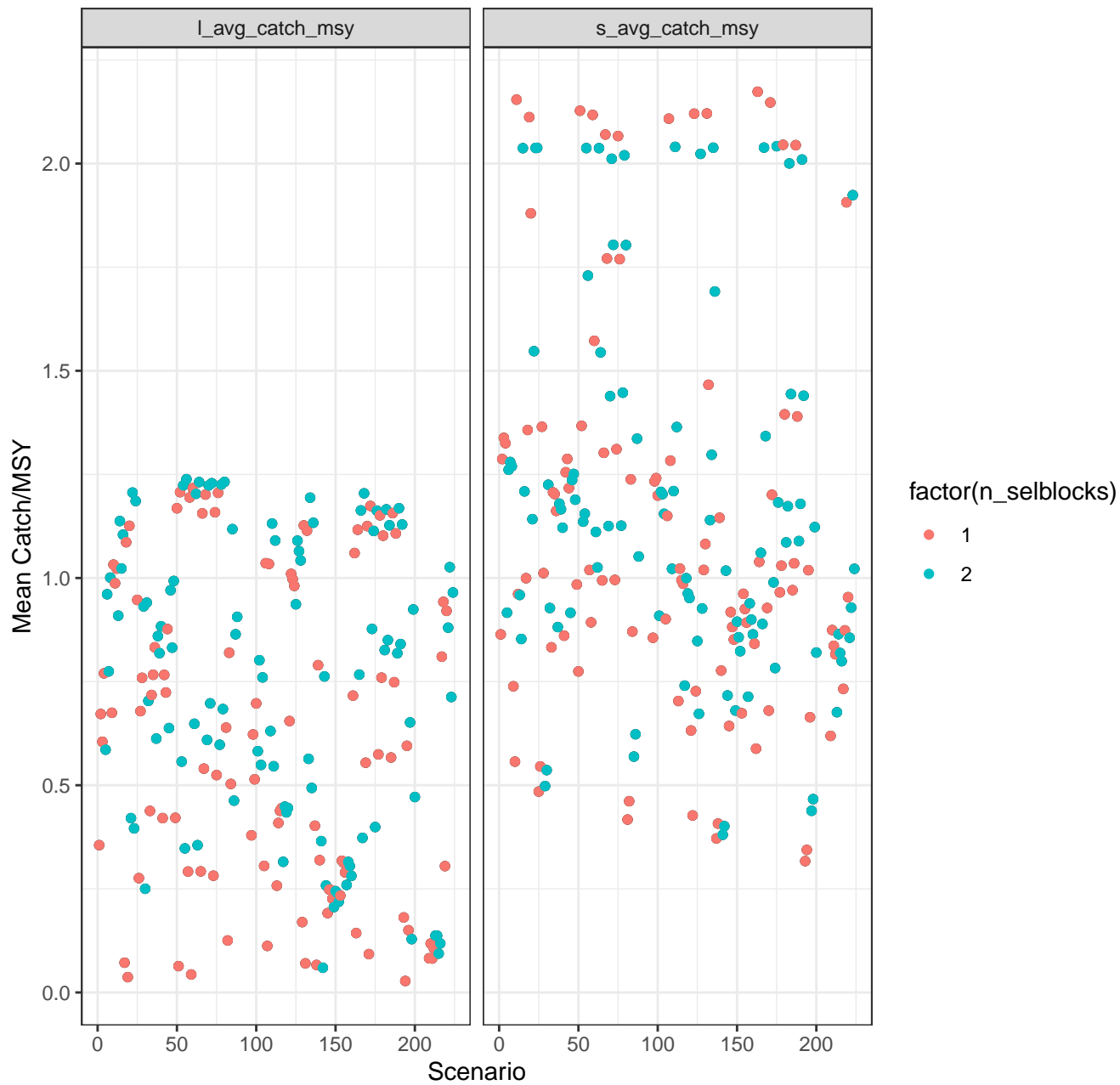
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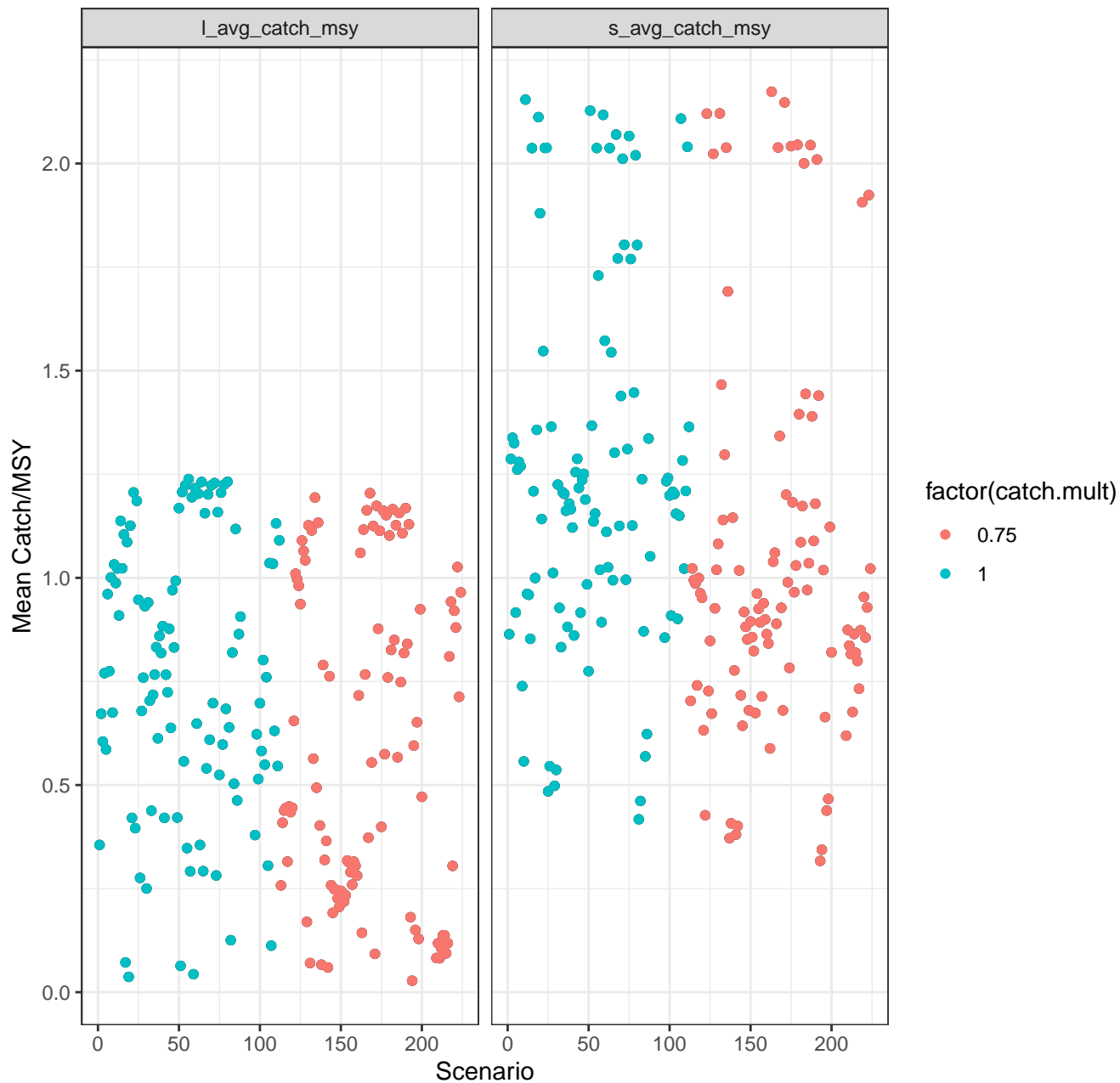
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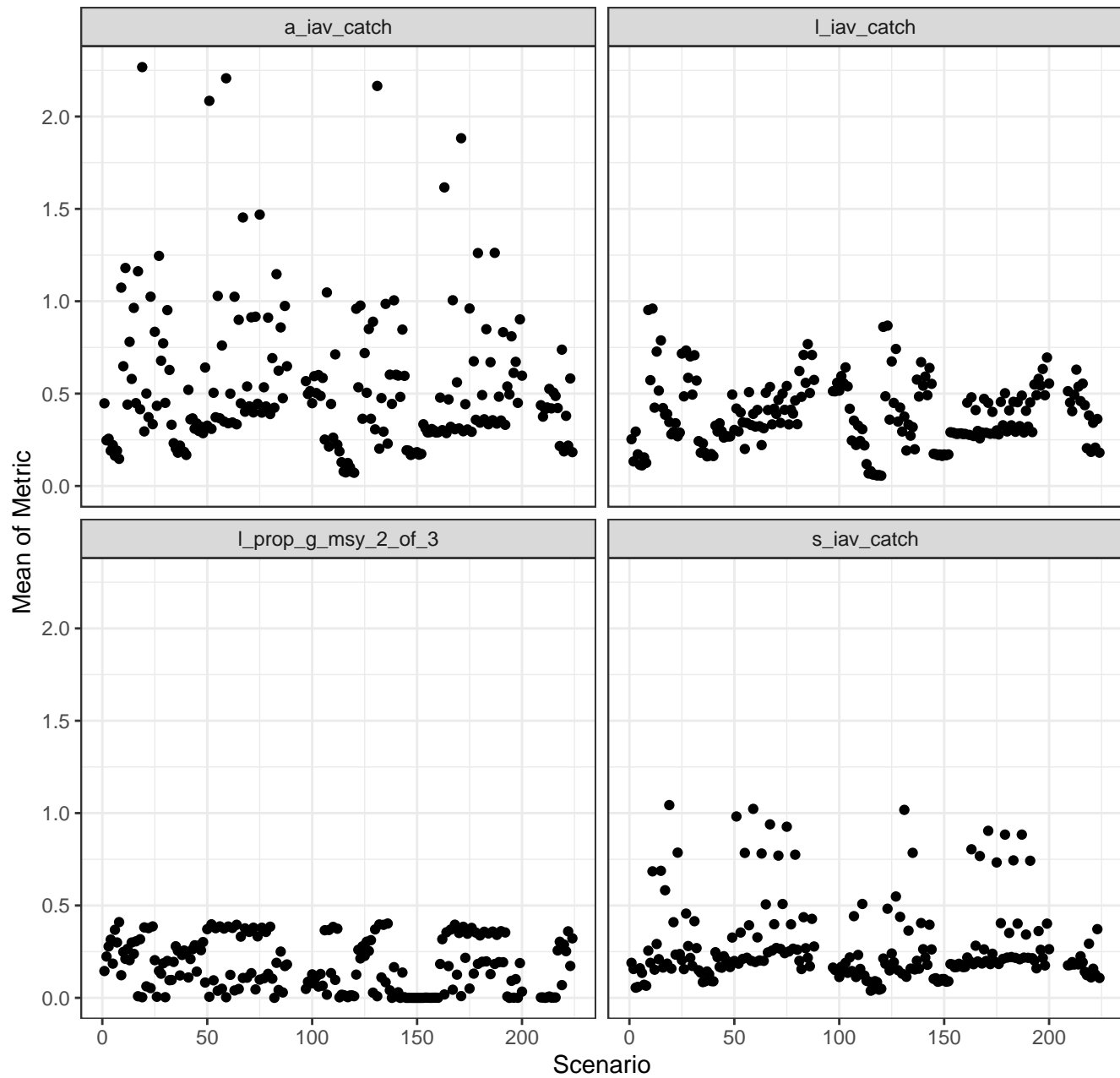
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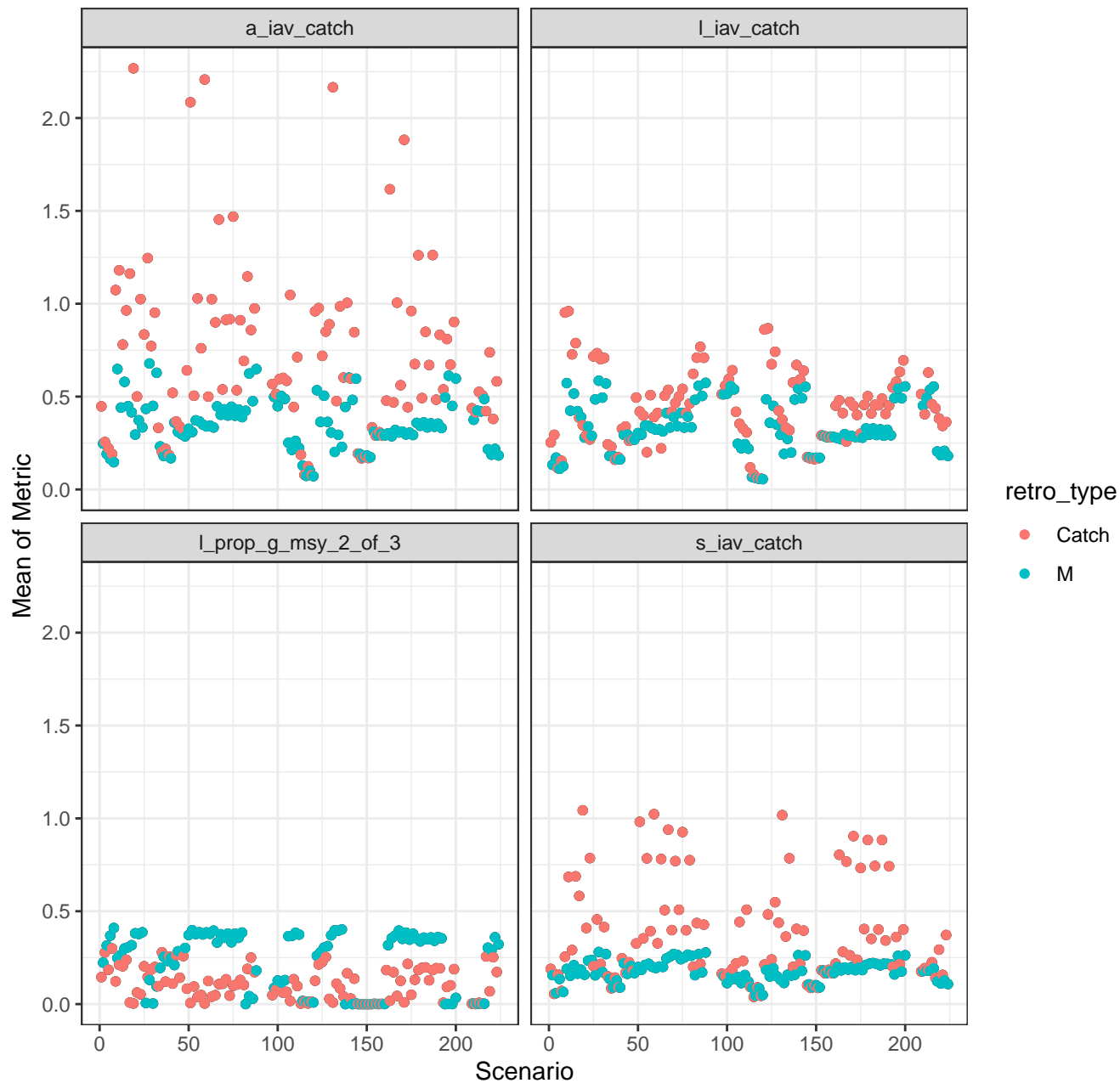
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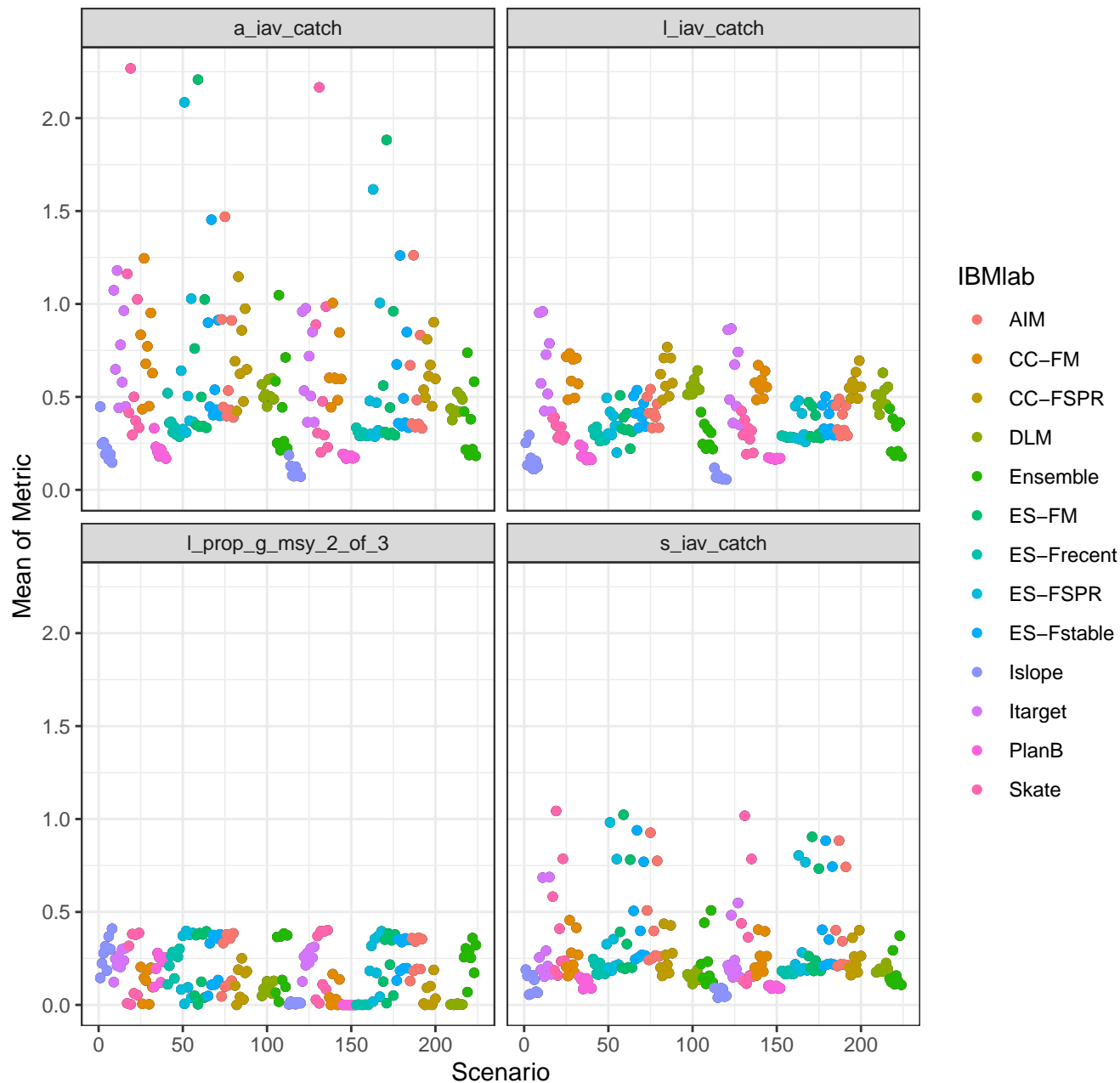
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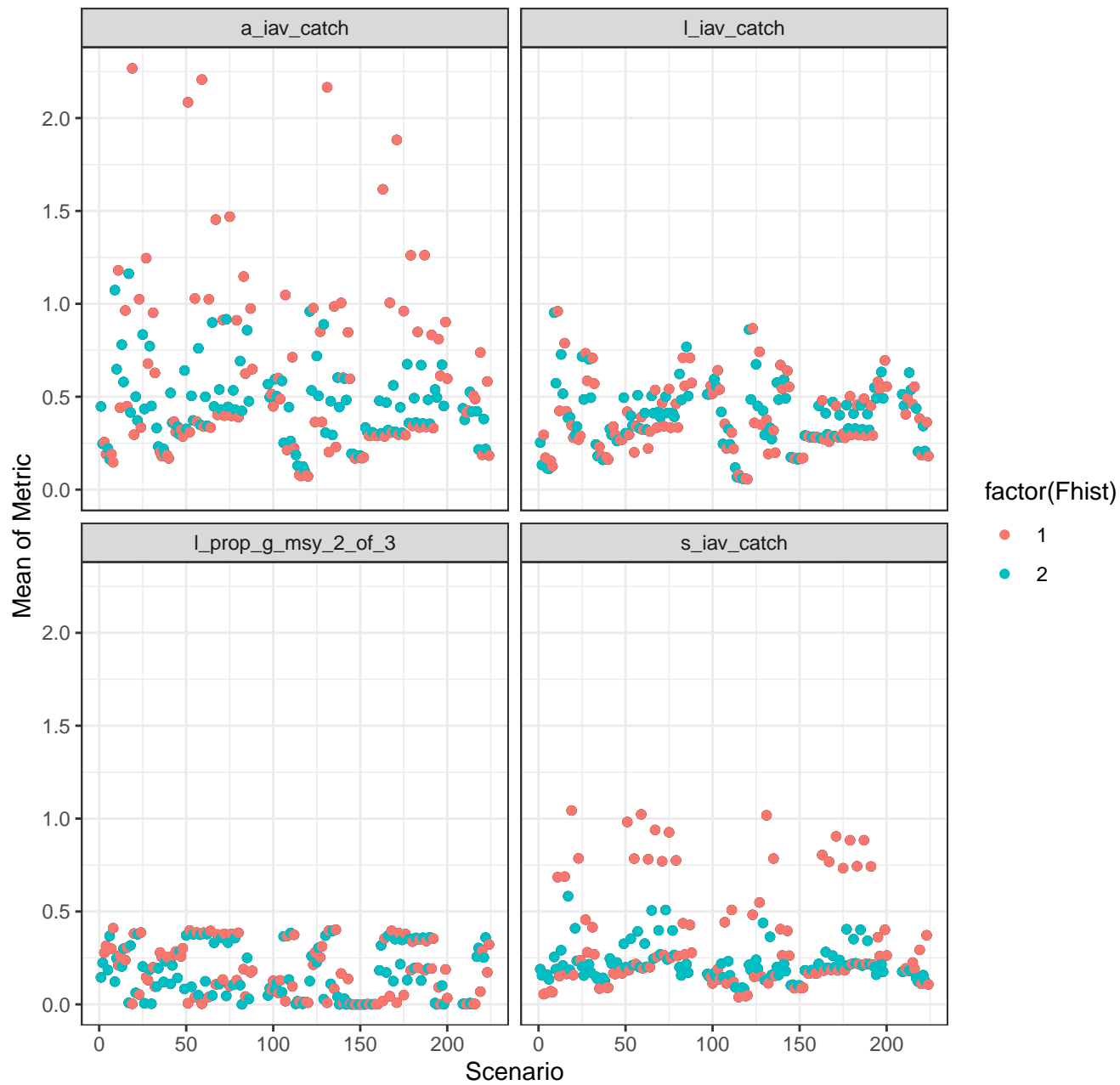
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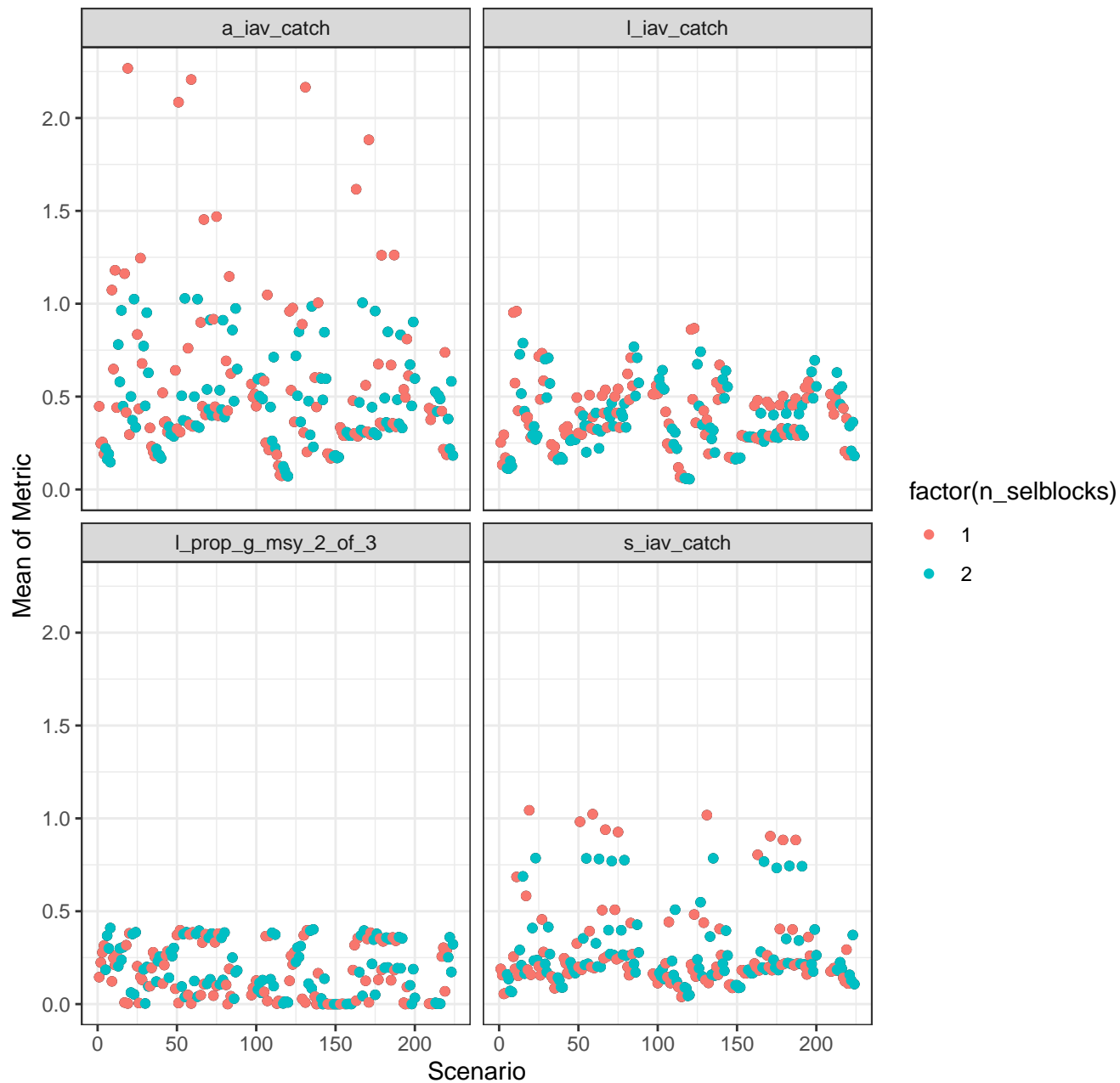
Catch



Catch



Catch



Catch

