

- Readings:

- Elliot & Timmermann Chp. 6
- James et al (ISLR) Chps. 5-6
- Chernick & LaBode Chp. 5
- Sheppard notes
- Hansen JBES, 2005

## Bootstrapping Time-Series Data

See: sheppard notes

AFE Week 1  
p. 26/42 (13)

(2)

- IID bootstrap is only appropriate for IID data
  - NB: may be okay for data not serially correlated
- Two strategies:
  - Parametric & IID bootstrap
    - If you have a model w/ IID residuals
    - Then you could bootstrap the residuals to generate new draws
    - "Historical filter": filter the new draws through the parametrically estimated model

EX: AR(1)

$$Y_t = \phi Y_{t-1} + \varepsilon_t$$

$$\hat{\varepsilon}_t = Y_t - \hat{\phi} Y_{t-1}$$

IID residuals



} obtain  $\hat{\phi}$  via OLS/MLE

- Nonparametric block bootstrap:

- Weak assumptions: basically that blocks can be sampled so that they are approximately IID

- Go to notebook for simulation of AR model

$$- \quad Y_t = 0.5 Y_{t-1} + \varepsilon_t \quad \text{s.t.} \quad \varepsilon_t \sim N(0, 1)$$

$$\phi \stackrel{a}{\sim} N(0, 1/n) \quad \text{via CLT}$$

- Q: Can we recover this value?

## Moving Block Bootstrap

- Samples blocks of  $m$  consecutive observations
- uses blocks which start at indices  $1, \dots, T-m+1$

### Algorithm

1. Initialize  $i=1$
2. Draw a uniform integer  $v_i$  on  $1, \dots, T-m+1$
3. Assign  $u_{(i-1)+j} = v_i + j-1$  for  $j=1, \dots, m$
4. Increment  $i$  and repeat 2-3 until  $i \geq T/m$
5. Trim  $u$  so that only the first  $T$  remain if  $T/m$  is not an integer

\* see sheppard's matlab code (which should be easily translated to Python)

## Circular Bootstrap

- simple extension of MBB which assumes the data live on a circular buffer so that  $Y_{T+1} = Y_1$ ,  $Y_{T+2} = Y_2$ , etc
- Has better finite sample properties since all data points get sampled with equal probability
- only step 2 changes in a very small way

## Algorithm

1. Initialize  $i=1$
2. Draw ~~from~~ a uniform integer  $v_i$  on  $1, \dots, T$
3. Assign  $u_{(i-1)+j} = v_i + j - 1$  for  $j=1, \dots, m$
4. Increment  $i$  and repeat 2-3 until  $i \geq T/m$
5. Trim  $u$  so that only the first  $T$  remains if  $T/m$  is not an integer

\* NB: See Matlab code

## Stationary Bootstrap (Politis & Romano 1992)

⑥

- Differs from MBB and CBB in that the block size is no longer fixed
- Chooses an average block size of  $m$  rather than an exact block size
- randomness in block size is worse when  $m$  is known, but helps if  $m$  may be suboptimal
- $m \sim \text{Exp}(\lambda)$

### Algorithm

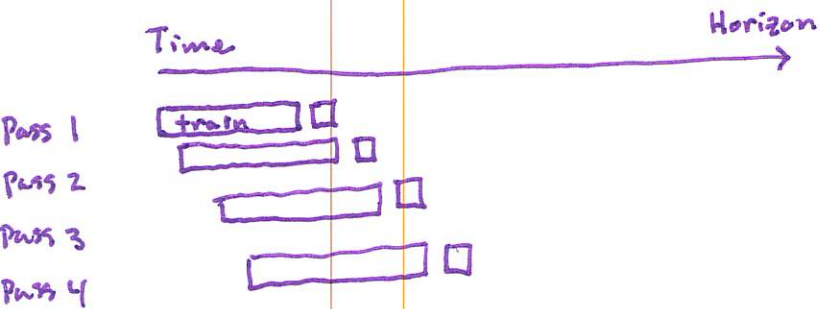
1. Draw uniform  $u_1$  on  $1, \dots, T$
2. For  $i=2, \dots, T$ 
  - a. Draw a uniform  $v$  on  $(0,1)$
  - b. if  $v \geq 1/m$  then  $u_i = u_{i-1} + 1$ 
    - i. if  $u_i > T$ , then  $u_i = u_i - T$
  - c. If  $v < 1/m$ , draw  $u_i$  uniform on  $1, \dots, T$

NB: See jupyter notebooks

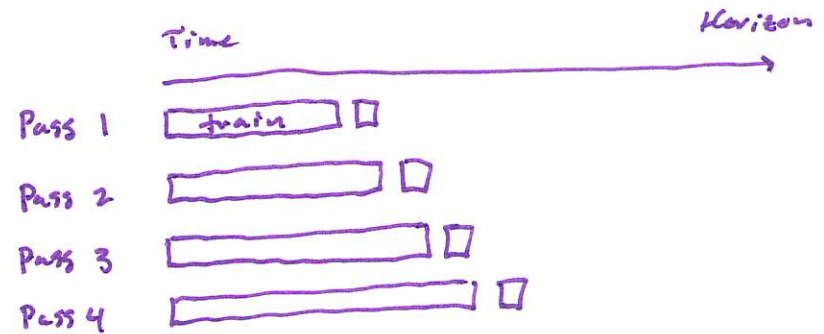
## Expanding Window Analysis

- Sliding/Moving Window vs. Expanding Window

### Sliding Window



### Expanding Window



NB: The window size in sliding window analysis and the training size in both introduce new "tuning parameters"



## 1-Step Ahead Returns Forecasts

- Recall that we are working w/ the Power Utility function for investors  $\gamma = (2, 5, 9)$  where

$$u(c) = \frac{c^{1-\gamma}}{1-\gamma}$$

- The input variable 'c' usually stands for consumption or wealth
- In this application we will use gross returns

$$1 + \gamma_{t+1} S_K(\chi_t, P_K)$$

Where

$$\chi_t = \left\{ \chi_{t-i} \right\}_{i=0}^R$$

where  $R$  is the length of the expanding window period

See  
STW p.  
1651  
for hints



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$$Y_{t+1} = \frac{P_{t+1} - P_t}{P_t} \quad \text{with } P_t = \overset{\text{level}}{\text{Price of asset at time } t}$$

$S_k(\cdot)$  is a "signal" function that converts a prediction into a market position. It takes two args:

1. Historical training data from  $t=1, \dots, R$
2.  $\beta_k$  from trained model  $k$

It produces one of the following values:

- 1 : long position (buy)
- 0 : hold position (do nothing)
- 1 : short position (sell)

- Hansen's SPA test looks for a model with lower loss than a benchmarks
- Convert utility to loss as :

$$L_k(y_{t+1}, S_k(x_t, \beta_k)) = -u[1 + y_{t+1} S_k(x_t, \beta_k)]$$

- For the benchmark use a long-only strategy

$$1 + y_{t+1} S_0(x_t, \cdot)$$

where  $S_0(x_t) = 1$  always