contvar_py

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0.1 Control Variate Sampling

```
[1]: import numpy as np
 [2]: def f(x):
          value = 1/(1+x)
          return value
 [3]: def g(x):
          value = 1 + x
          return value
 [4]: truth = 3.0 / 2.0
 [5]: truth
 [5]: 1.5
     0.1.1 The Naive Solution
[21]: n = 15_000
      u = np.random.uniform(size=n)
      x1 = f(u)
      x1.mean()
      x1.var()
      x1.std()
      se = x1.std() / np.sqrt(n)
[31]: np.round(np.mean(x1), 4)
[31]: np.float64(0.6934)
[23]: se
[23]: np.float64(0.0011406080903478744)
```

0.1.2 The Control Variate Solution

```
[24]: c = 0.4773
      y = g(u)
      x2 = f(u) + c * (g(u) - truth)
[30]: np.round(np.mean(x2), 4)
[30]: np.float64(0.6932)
[26]: se2 = x2.std() / np.sqrt(n)
[19]: se2
[19]: np.float64(0.0002006231759532942)
 []:
     0.2 Naive Monte Carlo in a BS World
 []: import time
      t1 = time.time()
 []: def VanillaCallPayoff(spot, strike):
          return np.maximum(spot - strike, 0.0)
 []: # The same old same old parameters
      S = 41.0
      K = 40.0
      r = 0.08
      v = 0.30
      q = 0.0
      T = 1.0
      M = 10000 # number of MC replications
     N = 252 # number of MC steps in a particular path
 [ ]: dt = T
      nudt = (r - q - 0.5 * v * v) * dt
      sigdt = v * np.sqrt(dt)
 []: spot_t = np.empty((N))
      call_t = np.empty(M)
      z = np.random.normal(size=(M,N))
      for i in range(M):
          spot_t[0] = S
```

```
for j in range(1,N):
             spot_t[j] = S * np.exp(nudt + sigdt * z[i,j])
         call_t[i] = VanillaCallPayoff(spot_t[-1], K)
[]: call_prc = np.exp(-r * T) * call_t.mean()
     t2 = time.time()
[]: call_prc
[]: 6.9288468728032111
[]: se = call_t.std() / np.sqrt(M)
[]:|se
[]: 0.10848490988044222
[]: print("The Naive Monte Carlo Price is: {0:.3f}".format(call_prc))
     print("The Naive Monte Carlo StdErr is: {0:.6f}".format(se))
     print("The total time take: {0}".format(t2-t1))
    The Naive Monte Carlo Price is: 6.929
    The Naive Monte Carlo StdErr is: 0.108485
    The total time take: 4.806628227233887
[]:
```

0.2.1 The Control Variate Approach in a BS World

z = np.random.normal(size=(M,N))

We will use the BS-Delta formula for our control variate. We can write the BS Delta function as follows:

```
[]: from scipy.stats import norm
[]: def BlackScholesDelta(spot, t, strike, expiry, volatility, rate, dividend):
    tau = expiry - t
    d1 = (np.log(spot/strike) + (rate - dividend + 0.5 * volatility **
    volatility) * tau) / (volatility * np.sqrt(tau))
    delta = np.exp(-dividend * tau) * norm.cdf(d1)
    return delta
[]: erddt = np.exp((r - q) * dt)
    beta = -1.0

spot_t = np.empty((N))
    call_t = np.empty(M)
    #cash_flow_t = np.zeros((engine.replications, ))
```

```
for i in range(M):
             \#spot_t = spot
             convar = 0.0
             #z = np.random.normal(size=int(engine.time_steps))
             spot_t[0] = S
             for j in range(1,N):
                 t = i * dt
                 delta = BlackScholesDelta(S, t, K, T, v, r, q)
                 spot_t[j] = spot_t[j-1] * np.exp(nudt + sigdt * z[i,j])
                 convar += delta * (spot_t[j] - spot_t[j-1]* erddt)
                 \#spot_t = spot_t
             call_t[i] = VanillaCallPayoff(spot_t[-1], K) + beta * convar
    /home/brough/anaconda3/lib/python3.5/site-packages/ipykernel/__main__.py:3:
    RuntimeWarning: divide by zero encountered in double_scalars
      app.launch_new_instance()
    /home/brough/anaconda3/lib/python3.5/site-packages/ipykernel/__main__.py:3:
    RuntimeWarning: invalid value encountered in sqrt
      app.launch_new_instance()
[]: disc = np.exp(-r * T)
     call_prc = disc * call_t.mean()
[]: call_prc
[]: nan
[]:
```