

Nearest State/County Finder:

Leveraging Geospatial Data for Efficient Query Processing

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Introduction

Geospatial Data:

- Geographic location
- Characteristics of natural or constructed features
- Boundaries on Earth

Dataset Source:

Utilizing the US Board on Geographic Names dataset, featuring extensive geographical reference points across the United States

Project Objective:

Develop a system that quickly and accurately finds the nearest state or county in the US based on given **geographic coordinates**

Project Challenge:

Processing a **vast dataset** to respond to queries in **real-time**

Key Tasks

Task 1 - Data Structure Implementation (KD-Tree)

- **Space-partitioning data structure**
- **Organizing points in a k-dimensional space**

Task 2 - Efficient Query Processing

- **User queries for coordinates**
- **leveraging the KD-Tree**
- **Determine the corresponding state and county**

Implementing KD-Tree for Data Loading

KD-Tree:

- Latitude
- Longitude

Code Snippet:

```
class KDTreeNode:
    def __init__(self, point, left=None, right=None):
        self.point = point # Point containing [latitude, longitude]
        self.left = left
        self.right = right
```

Handling User Queries:

- Accepting Queries
- Nearest Neighbor Search

Code Snippet:

```
// Utility function to calculate the distance between two points

double distance(const Point& p1, const Point& p2) {
    double x = (p2.lon - p1.lon) * std::cos((p1.lat + p2.lat) / 2);
    double y = p2.lat - p1.lat;
    return std::sqrt(x * x + y * y) * 6371; // Earth's radius in km
}
```

Distance Calculation Methodology

Equirectangular Approximation Formula:

- $x = (\lambda_2 - \lambda_1) \cdot \cos\left(\frac{\phi_1 + \phi_2}{2}\right)$
- $y = \phi_2 - \phi_1$
- $\text{Distance} = \sqrt{x^2 + y^2} \cdot R$

Implementation:

```
def equirectangular_distance(lat1, lon1, lat2, lon2):  
    R = 6371 # Earth's radius in km  
  
    x = (math.radians(lon2) - math.radians(lon1)) * math.cos(0.5 * (math.radians(lat1) +  
        math.radians(lat2)))  
  
    y = math.radians(lat2) - math.radians(lat1)  
  
    return math.sqrt(x*x + y*y) * R
```



THANK YOU

Q&A

