dot product cross product change of basis

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```
In [1]: %matplotlib inline
        from ipywidgets import interactive
        import matplotlib.pyplot as plt
        import numpy as np
        def unit_vector_xsys(theta, origin_reflection=False):
            v_hat_tip = np.array([np.cos(theta),np.sin(theta)])
            v_hat_tail = np.zeros(shape=(2,))
            if origin_reflection:
                v_hat_tail[0] = -v_hat_tip[0]
                v_hat_tail[1] = -v_hat_tip[1]
            v_xs = np.array([v_hat_tail[0], v_hat_tip[0]])
            v_ys = np.array([v_hat_tail[1], v_hat_tip[1]])
            return v_xs,v_ys
        def plot_unit_vector_dot(theta1=0, theta2=1, theta_ihat=0):
            # crete figure
            fig = plt.figure()
            ax = fig.add_subplot(1, 1, 1)
            # unit circle
            # create unit circle
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circ = plt.Circle((0, 0), radius=1, edgecolor='k', facecolor='None')
#
# i hat
ihat_xs, ihat_ys = unit_vector_xsys(theta_ihat, origin_reflection=True)
#
  j hat (orthogonal and ahead pi/2) [TMP]
theta_jhat = theta_ihat + np.pi/2
jhat_xs, jhat_ys = unit_vector_xsys(theta_jhat, origin_reflection=True)
# vector 1
v1_xs,v1_ys = unit_vector_xsys(theta1, origin_reflection=False)
# vector 1 i projection)
#
v1_proi_xs = np.array([ihat_xs[1]*v1_xs[1],0])
v1_proi_ys = np.zeros(shape=(2,))
# vector 1 j projection)
v1_proj_xs = np.zeros(shape=(2,))
v1_proj_ys = np.array([jhat_ys[1]*v1_ys[1],0])
# vector 2
v2_xs,v2_ys = unit_vector_xsys(theta2, origin_reflection=False)
# vector 2 counter part (+pi/2)
v2_counter_theta = theta2 +np.pi/2
v2_counter_xs,v2_counter_ys = unit_vector_xsys(v2_counter_theta, origin_reflection
#
# vector 2 counter j projection (vector 2 i projection)
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#
### catastrophic cancelation
\#counter\_proj\_j\_theta = np.dot(v2\_counter\_ys, jhat\_ys) \ \#np.cos(v2\_counter\_theta)
#counter_proj_xs, counter_proj_ys = unit_vector_xsys(counter_proj_j_theta, origin_
### catastrophic cancelation
counter_proj_xs = np.zeros(shape=(2,))
counter_proj_ys = np.array([0, jhat_ys[1]*v2_counter_ys[1]])
# vector 2 counter i projection (vector 2 j projection)
counter_proi_xs = np.array([ihat_xs[1]*v2_counter_xs[1],0])
counter_proi_ys = np.zeros(shape=(2,))
#
#
#
# Plot Things
# plot i hat
ax.plot(ihat_xs, ihat_ys, 'k--', linewidth=0.5)
# plot j hat
ax.plot(jhat_xs, jhat_ys, 'k--', linewidth=0.5)
# plot vector 1
\#ax.plot(v1\_xs, v1\_ys, c='b')
plt.quiver(v1_xs[0],v1_ys[0], v1_xs[1], v1_ys[1], color='b', scale=4)
# plot vector 1 projection onto i hat
ax.plot(v1_proi_xs, v1_proi_ys, 'b', linewidth=1)
# plot vector 1 projection onto j hat
ax.plot(v1_proj_xs, v1_proj_ys, 'b', linewidth=1)
# plot vector 2
\#ax.plot(v2\_xs, v2\_ys, c='r')
plt.quiver(v2_xs[0],v2_ys[0], v2_xs[1], v2_ys[1], color='r', scale=4)
```

```
# plot vector 2 counter part
            ax.plot(v2_counter_xs,v2_counter_ys, 'r--', linewidth=0.5, alpha=0.25)
            # # plot vector 2 counter part projection onto j hat
            ax.plot(counter_proj_xs, counter_proj_ys, c='r', linewidth=1)
            # # plot vector 2 counter part projection onto i hat
            ax.plot(counter_proi_xs, counter_proi_ys, c='r', linewidth=1)
            # plot circle
            ax.add_patch(circ)
            # plot origin
            ax.plot(0,0,marker='o', c='black')
            # Plot settings
            # set equal aspect
            ax.set_aspect('equal', 'datalim')
            # plot bounds
            plt.ylim(-2, 2)
            plt.xlim(-2, 2)
            # add grid
            plt.grid(False)
            # display
            plt.show()
        interactive_plot = interactive(plot_unit_vector_dot, theta1=(0.0, 2*np.pi, 0.25), theta1=(0.0, 2*np.pi, 0.25),
        output = interactive_plot.children[-1]
        output.layout.height = '350px'
        interactive_plot
interactive(children=(FloatSlider(value=0.0, description='theta1', max=6.283185307179586, step
```