

HIDDEN MARKOV MODELS

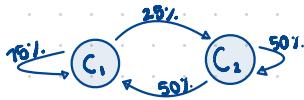
Example scenario:

Suppose Alice has 2 coins (C_1 and C_2) with different biases:

hidden states: which coin Alice flips i.e. $C_1, C_1, C_2, C_1, C_2, C_2$

observations: the resulting heads/tails i.e. T, H, T, T, T, T

there are also different probabilities of transitioning from 1 hidden state (coin) to another:



Suppose we only see the observations. Given a long enough sequence of observations, we can use statistical algorithms & techniques to infer the underlying sequence of hidden states.

► HMMs have powerful applications in genomics i.e. the hidden states can be various genes or genetic structures that we can infer from the observed sequence of bases

Markov Chains

S = set of states

A = state transition probability matrix

ex: Providence Weather

$S = \{\text{sunny, rainy}\}$

		state 2	
		sunny	rainy
state 1	sunny	0.7	0.3
	rainy	0.5	0.5

→ i.e. $P[\text{sunny} \rightarrow \text{rainy transition}] = 0.3$
 $P[\text{rainy} \rightarrow \text{sunny transition}] = 0.5$

Hidden Markov Models: have an added component of different states having different observation/emission probabilities

S = set of states ; V = set of possible observation symbols

A = probability transition matrix $\rightarrow a_{i,j} = P[q_{t+1} = s_j | q_t = s_i]$ (probability of state $t+1$ being s_j given state t is s_i)

B = emission probability matrix $\rightarrow b_{j,k} = \text{probability of emitting symbol } k \text{ when in state } j$

π = initial state probability distribution

Alice's coin flip example:

$$\begin{aligned} S &= \{C_1, C_2\} \\ V &= \{H, T\} \\ A &= \begin{matrix} C_1 & C_2 \\ \begin{bmatrix} 0.7 & 0.25 \\ 0.5 & 0.5 \end{bmatrix} \end{matrix} \end{aligned}$$

$$B = \begin{matrix} H & T \\ \begin{bmatrix} 0.3 & 0.7 \\ 0.1 & 0.9 \end{bmatrix} \end{matrix}$$

$$\pi = [0.5, 0.5]$$

Alice is equally likely to start by flipping Coin 1 or 2

Fundamental Computational HMM Problems

Problem 1: The evaluation problem

input: HMM defined by $\lambda = \{A, B, \pi\}$ and an observation sequence $O = o_1, o_2, o_3, \dots, o_T$

output: the probability of observing the sequence O given the HMM λ : $P(O|\lambda)$

Problem 2: The decoding problem

input: HMM defined by $\lambda = \{A, B, \pi\}$ and an observation sequence $O = o_1, o_2, o_3, \dots, o_T$

output: the most likely sequence of states $Q = q_1, q_2, \dots, q_T$ given the observation sequence O . The solution can be found using the Viterbi Algorithm

Problem 3: The Learning Problem

input: observation sequence O

output: find the most likely HMM defined by $\lambda = \{A, B, \pi\}$ given O

Solution to problem 1 ex: observations: a a b c c c $\Rightarrow |O| = 6$

if we have N states, there are N^6 possible sequences of states underlying the observation sequence O

Let's define a few fundamental probabilities:

$P[\text{observing } O \text{ given a sequence of states } Q]$: $P(O|Q) = P(o_1|q_1) P(o_2|q_2) \dots P(o_T|q_T)$

$$= b_{q_1}(o_1) b_{q_2}(o_2) \dots b_{q_T}(o_T)$$

$P[\text{having a particular sequence of states } Q]$: $P(Q) = \pi_{q_1} \alpha_{q_1 q_2} \alpha_{q_2 q_3} \dots \alpha_{q_{T-1} q_T}$

Joint probability of O and Q : $P(O, Q) = P(O|Q) \cdot P(Q)$

To be continued...