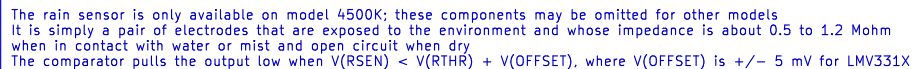
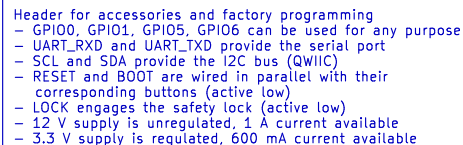
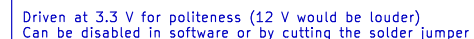


- Input must be 9 to 16 V
- Circuit protection
 - Internal: 4 A polyfuse and TVS
 - External: 5 A fuse recommended



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Sheet: /

File: minuet.kicad_sch

Title: Minuet Fan Controller

Size: A4	Date: 2025-06
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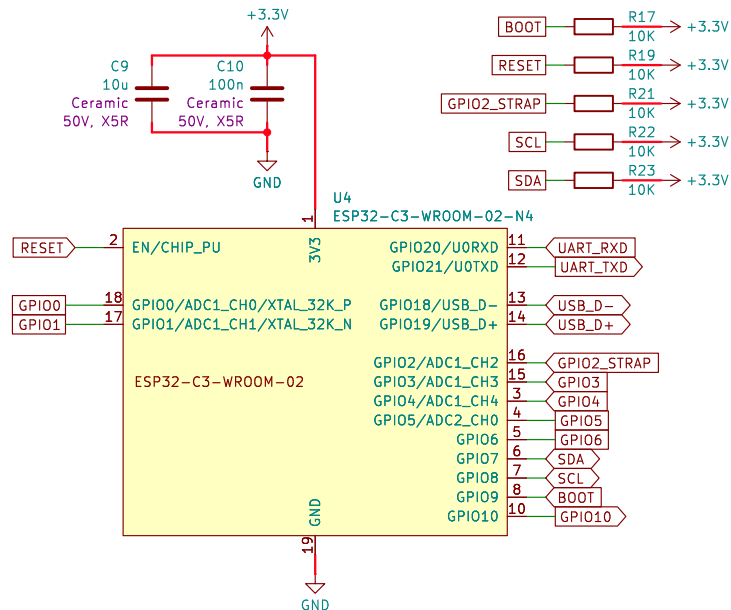
KiCad E.D.A. 8.0.8

Rev: v3.0

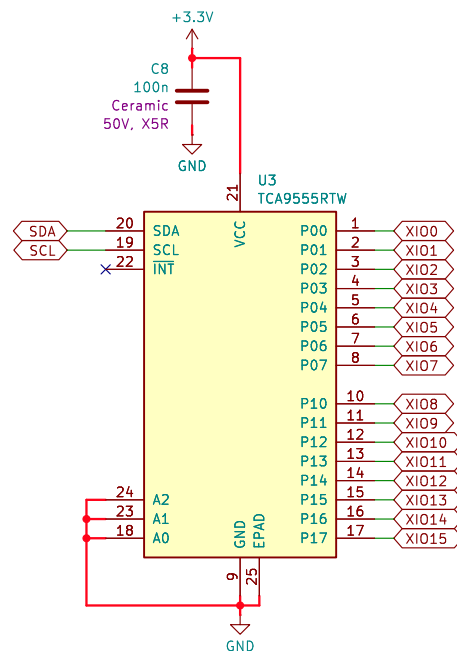
Id: 1/5

ESP32-C3 strapping pins

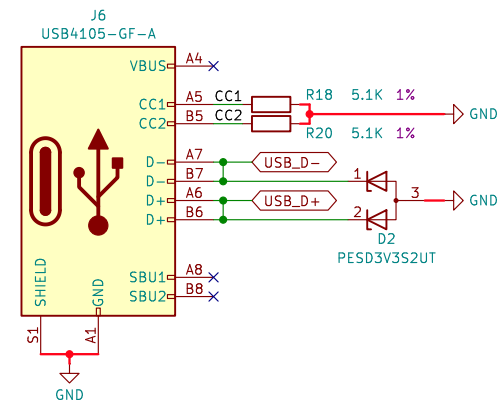
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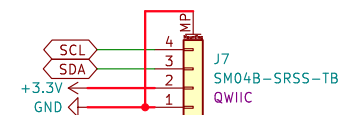
XIO pins have internal 100 K pull-ups, configured as inputs at reset, cannot be set to Hi-Z, 50 mA push-pull output, 5 V tolerant



ESP32-C3 only supports full-speed data rate (11 Mbps)



- A great place to plug in off-the-shelf accessories
- Host has pull-ups so accessories don't need their own
- 3.3 V supply is regulated, 600 mA current available



Hold BOOT, press/release RESET, then release BOOT to enter the bootloader for firmware updates



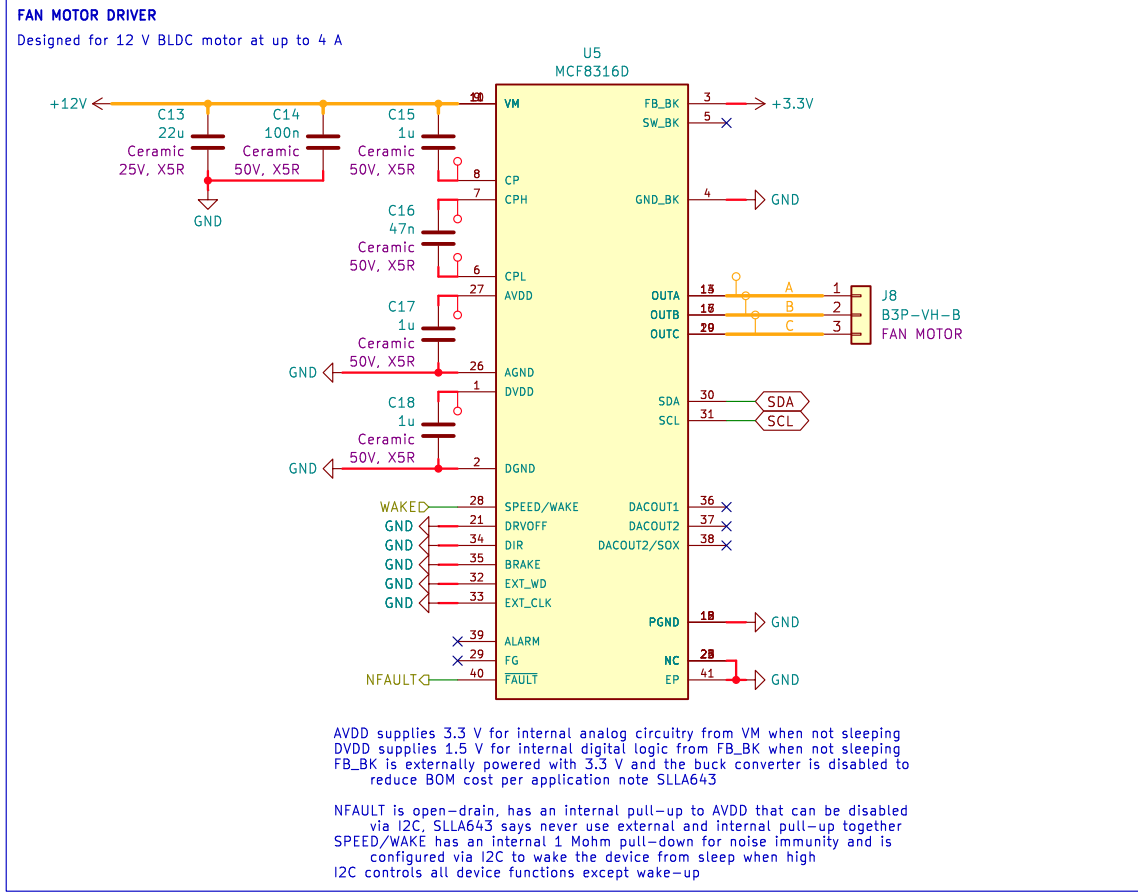
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Title: Minuet Core

Title: Minuet Core

Id: 2/5

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Sheet: /fan/
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Title: Minuet Fan Motor Driver

Size: A4
KiCad E.D.A. 8.0.8

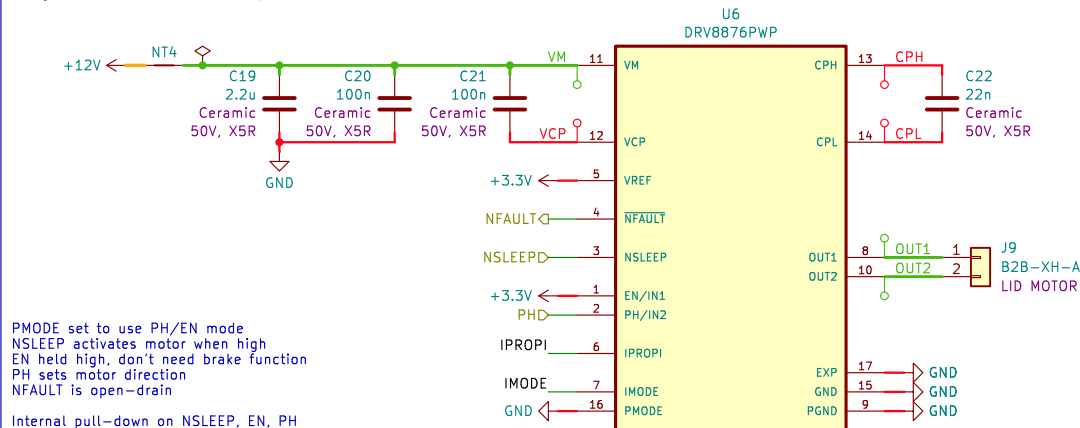
Date:

Rev:

Id: 3/5

LID MOTOR DRIVER

Designed for 12 V DC motor at up to 2 A

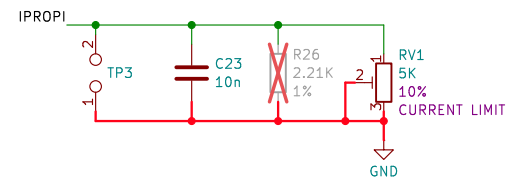


CURRENT LIMIT

Increasing resistance of the setpoint decreases the current limit



Current limit mode 3
When Itrip or Iocp exceeded (motor stall), brake motor, latch outputs off, and assert NFAULT until inputs change



Set overcurrent protection trip current
 $I_{trip} (A) = 1000 * V_{ref} (V) / R_{ipropi} (\Omega)$
Given $V_{ref} = 3.3 V$, $R_{ipropi} = 2.21 K$, $I_{trip} = 1.5 A$

Must be set high enough to allow the motor to overcome the torque demands of the lid mechanism and ideally should be low enough to detect stall at end of travel. Add a capacitor if there are glitches.

Sheet: /lid/

File: lid.kicad_sch

Title: Minuet Lid Motor Driver

Size: A4

Date:

KiCad E.D.A. 8.0.8

Rev:

Id: 4/5

