```
import numpy as np
  from matplotlib import pyplot as plt
   from scipy.integrate import solve_bvp
   # set up the right hand side of the ODE, with the parameter
   # tf (the final time rescaled)
   def chemo_finite_time(t,y,p):
       alpha = 1
       tf=p[0]
       return np.vstack((tf*alpha*y[0] + tf*0.5*y[1], -tf*alpha*y←
10
            [1]))
11
   # set up the endpoint conditions. The final one is H(tf) = 2a(\leftarrow)
^{12}
   def bc_new(ya,yb,p):
13
       x0 = 2
14
       a = 1
15
       alpha = 1
16
       m = 2
17
       tf = p[0]
       return np.array([ya[0]-x0, yb[1]+m, alpha*yb[0]*yb[1]+.25*yb↔
19
            [1]**2-2*a*(tf-1)])
20
   # construct the solution using solve_bvp. We use an initial \hookleftarrow
   # of tf=1 as that is the value we are forcing the solution to be\!\!\leftarrow
        close to.
   t=np.linspace(0,1,10)
23
   y = np.zeros((2, t.size))
   res = solve_bvp(chemo_finite_time, bc_new, t, y, p=[1])
26
   # plot the results and print out the optimal final time t_f
27
   t_plot = np.linspace(0, 1, 100)
28
   x_plot = res.sol(t_plot)[0]
29
   p_plot = res.sol(t_plot)[1]
plt.plot(t_plot, x_plot)
   plt.plot(t_plot, -.5*p_plot)
   plt.legend(['cancer cells','chemo concentration'])
  print('t_f = '+str(res.p[0]))
```

Algorithm 21.2: Algorithm for computing the solution of the Chemotherapy problem in Example 21.3.2 for specific values of the relevant parameters.