

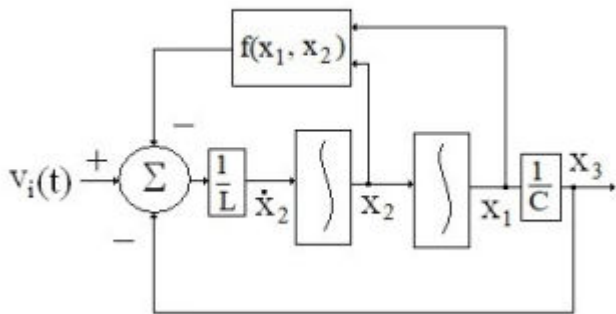
## Circuitos Electricos II

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### Soluciones propuestas para los ejercicios del taller 11

#### Sistema



$$\alpha_1(x_1) = \frac{\pi/2}{1 + e^{-k_1 x_1}}; \quad \alpha_2(x_2) = \frac{\pi/2}{1 + e^{-k_2 x_2}}$$

$$\begin{aligned} f(x_1, x_2) = & a_1 [\cos \alpha_1(x_1) \cos \alpha_2(x_2)]^2 \\ & + a_2 [\cos \alpha_1(x_1) \sin \alpha_2(x_2)]^2 \\ & + a_3 [\sin \alpha_1(x_1) \cos \alpha_2(x_2)]^2 \\ & + a_4 [\sin \alpha_1(x_1) \sin \alpha_2(x_2)]^2 \end{aligned}$$

#### Simulacion con valores iniciales

$$\omega = 5.0 \text{ rad/s}$$

$$a_1 = -0.2, \quad a_2 = 0.2, \quad a_3 = -0.5, \quad a_4 = 0.5$$

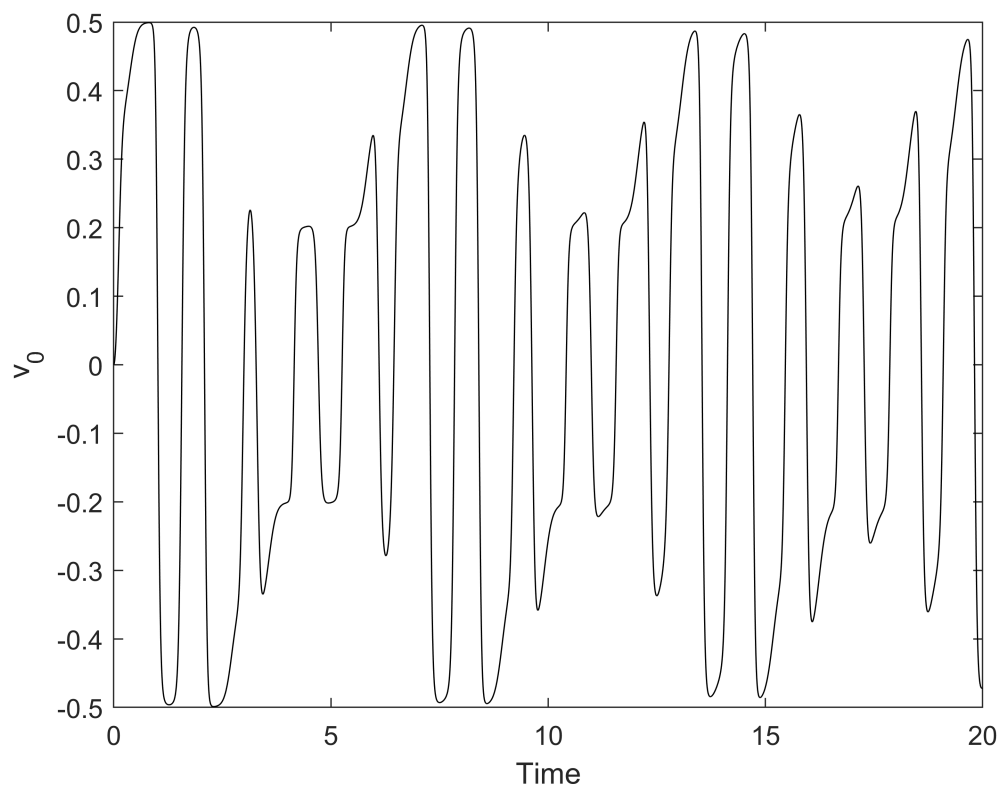
$$k_1 = 2.0, \quad k_2 = 2.0$$

```
w = 5;  
A=10;  
a1=-0.2;  
a2=0.2;  
a3=-0.5;  
a4=0.5;  
k1=2;  
k2=2;
```

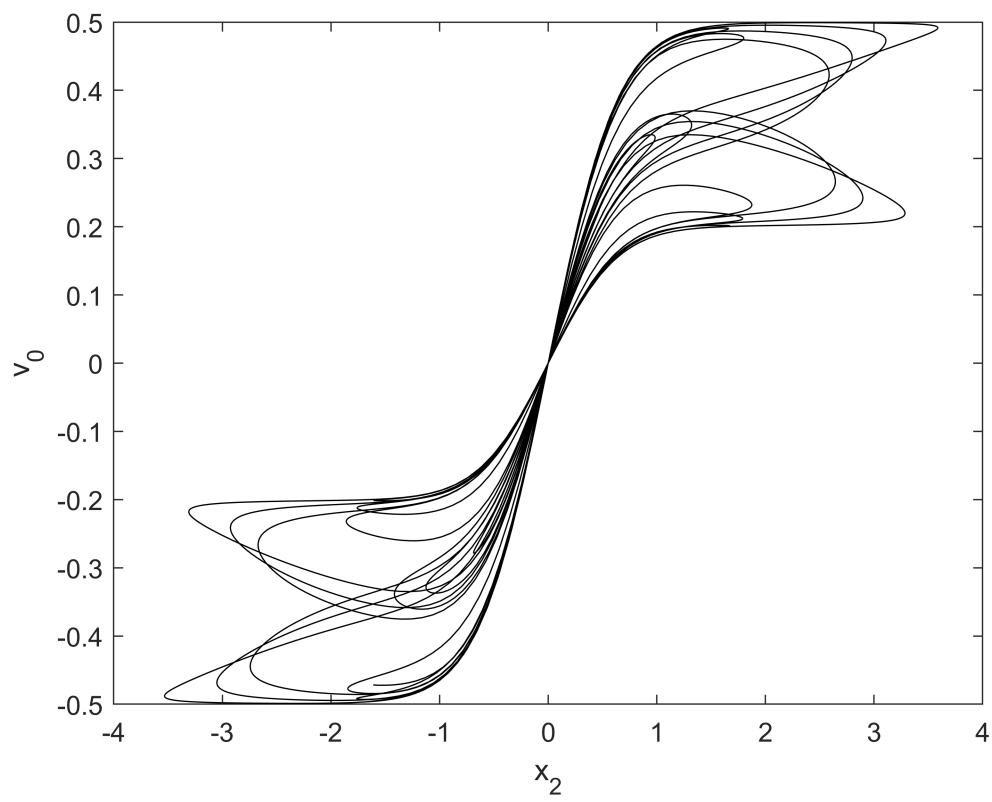
```
L = 1;  
C = 1;
```

```
xy=out.f_xy.Data;  
t=out.f_xy.Time;  
x2=out.x2.Data;  
x1=out.x1.Data;
```

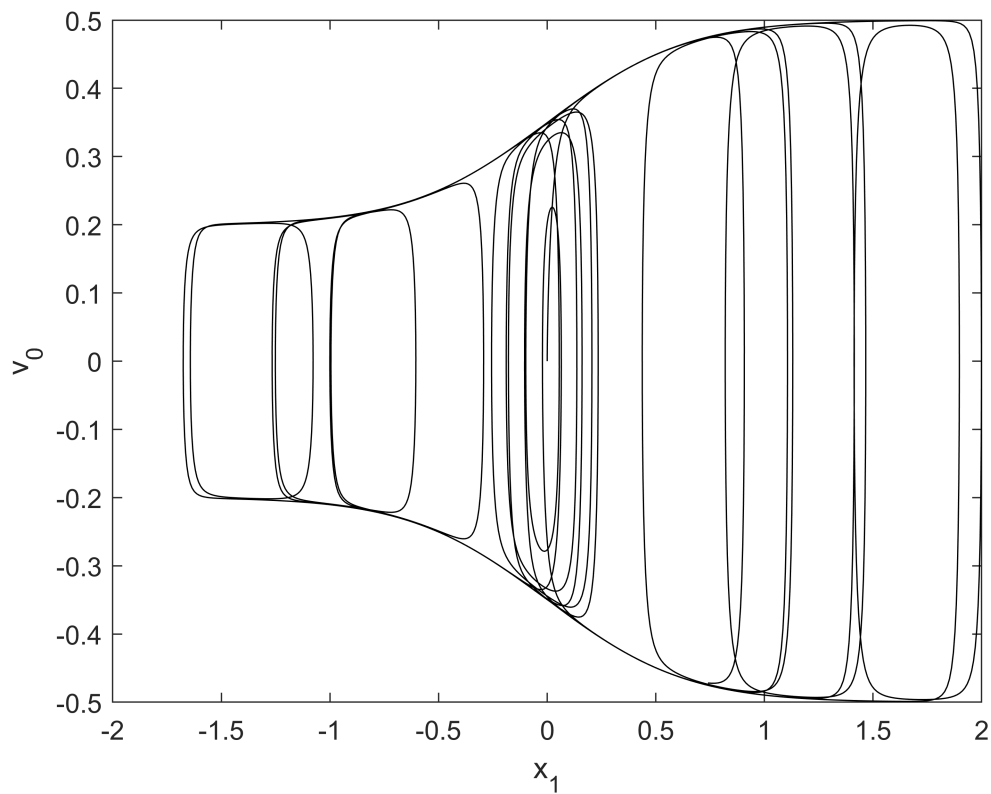
```
figure  
plot(t,xy,'k')  
xlabel('Time')  
ylabel('v_0')
```



```
figure
plot(x2,xy,'k')
xlabel('x_2')
ylabel('v_0')
```



```
figure
plot(x1,xy,'k')
xlabel('x_1')
ylabel('v_0')
```



## Simuilacion con valores de alfas cambiados

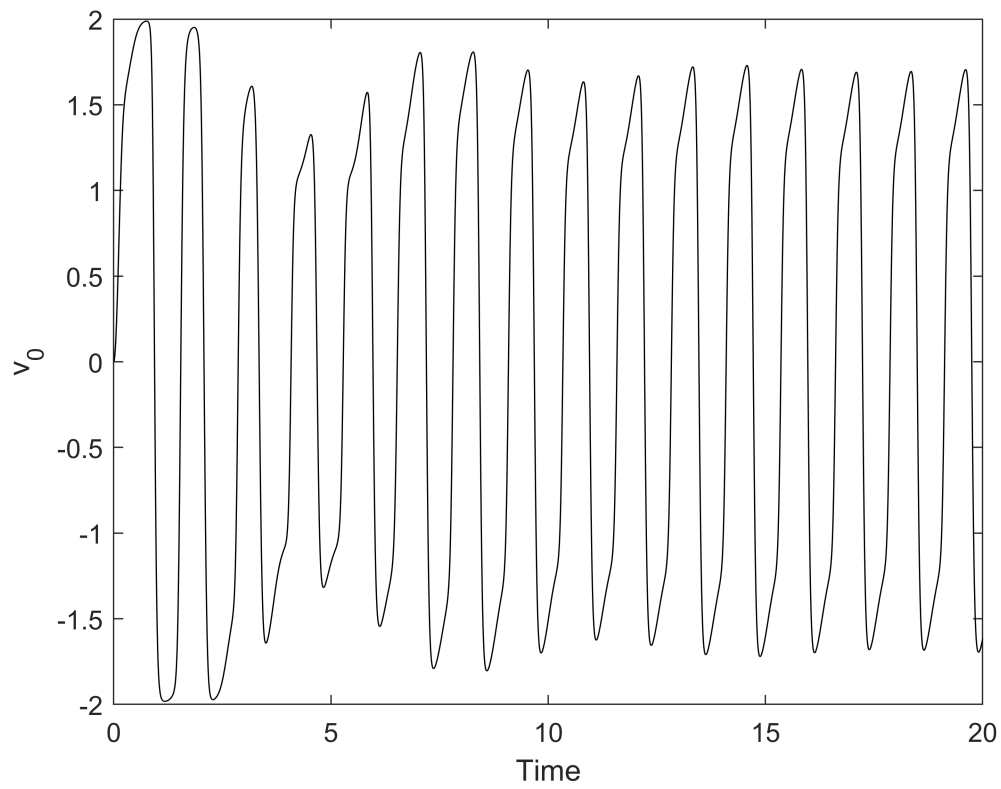
$$\begin{aligned} \omega &= 5.0 \text{ rad/s} \\ a_1 &= -1.0, \quad a_2 = 1.0, \quad a_3 = -2.0, \quad a_4 = 2.0 \\ k_1 &= 2.0, \quad k_2 = 2.0 \end{aligned}$$

```
w = 5;
A=10;
a1=-1;
a2=1;
a3=-2;
a4=2;
k1=2;
k2=2;
```

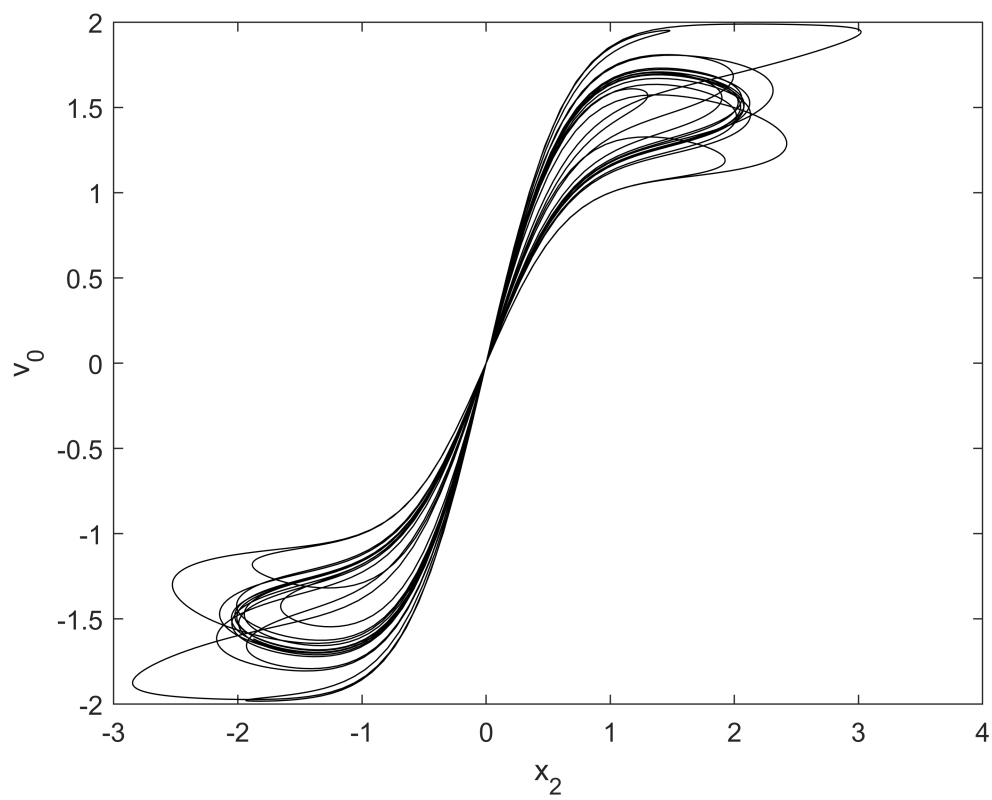
```
xy=out.f_xy.Data;
t=out.f_xy.Time;
x2=out.x2.Data;
x1=out.x1.Data;

figure
plot(t,xy,'k')
xlabel('Time')
```

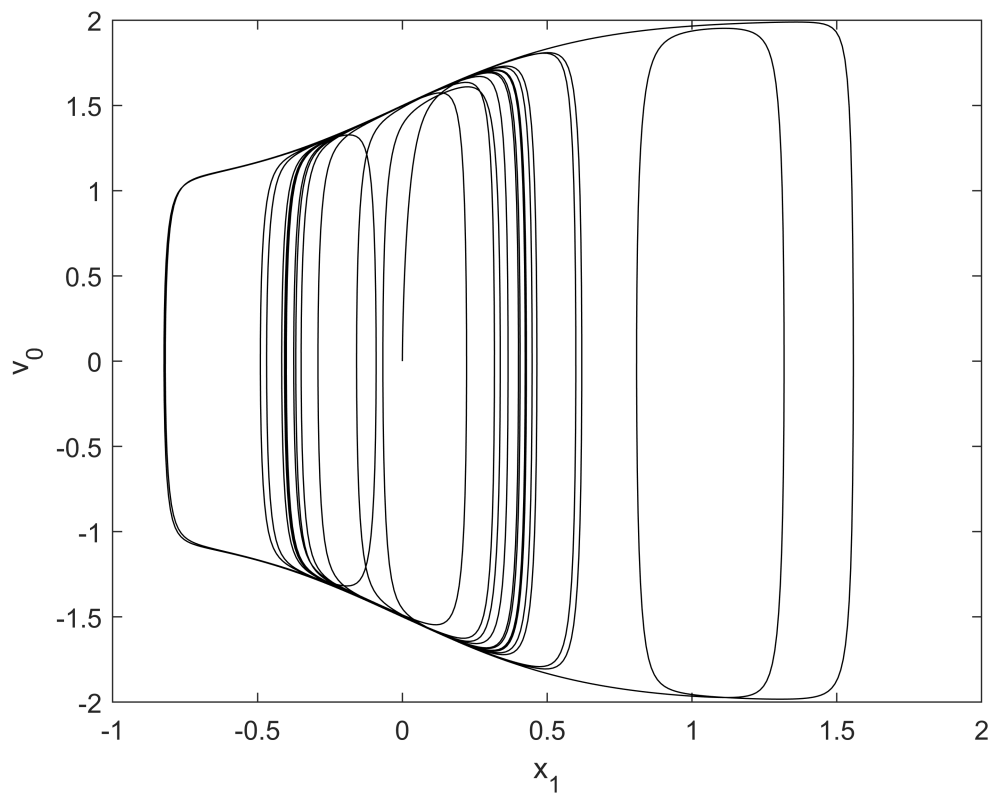
```
ylabel('v_0')
```



```
figure
plot(x2,xy,'k')
xlabel('x_2')
ylabel('v_0')
```



```
figure
plot(x1,xy,'k')
xlabel('x_1')
ylabel('v_0')
```



## Simulacion con valor de frecuencia cambiados

$$\omega = 10.0 \text{ rad/s}$$

$$a_1 = -0.2, \quad a_2 = 0.2, \quad a_3 = -0.5, \quad a_4 = 0.5$$

$$k_1 = 2.0, \quad k_2 = 2.0$$

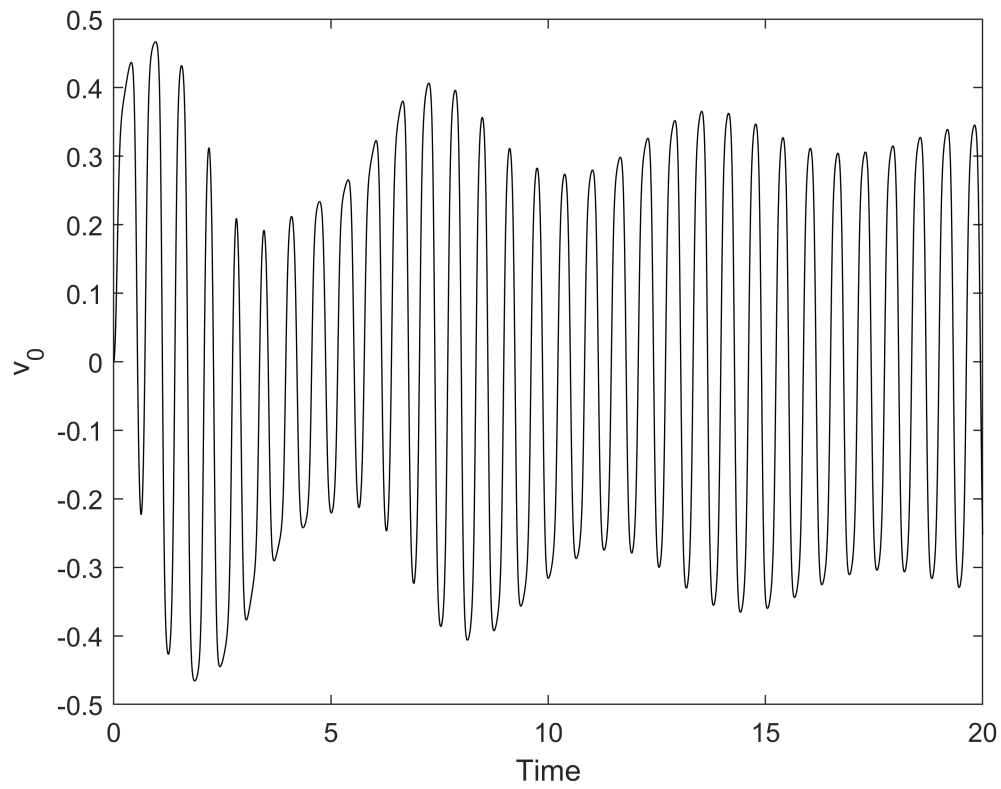
```
w = 10;
A=10;
a1=-0.2;
a2=0.2;
a3=-0.5;
a4=0.5;
k1=2;
k2=2;
```

```
xy=out.f_xy.Data;
t=out.f_xy.Time;
x2=out.x2.Data;
x1=out.x1.Data;
```

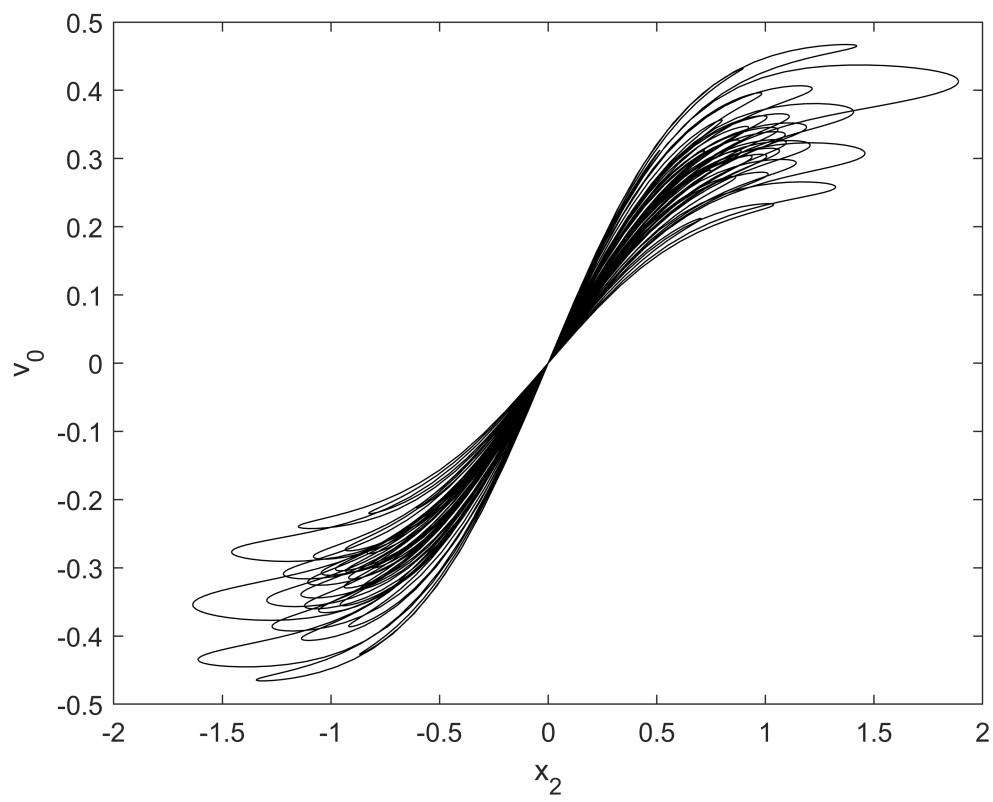
```
figure
plot(t,xy,'k')
xlabel('Time')
```



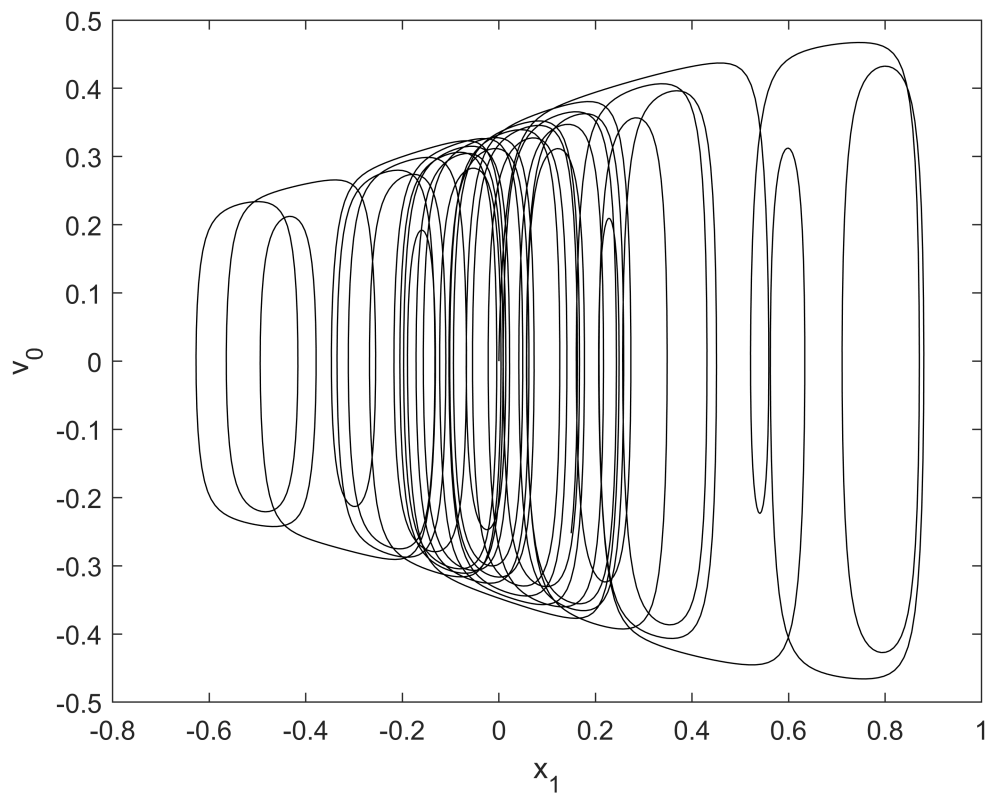
```
ylabel('v_0')
```



```
figure
plot(x2,xy,'k')
xlabel('x_2')
ylabel('v_0')
```



```
figure
plot(x1,xy,'k')
xlabel('x_1')
ylabel('v_0')
```



## Simulacion con valores de alfas trucados

$$\omega = 5.0 \text{ rad/s}$$

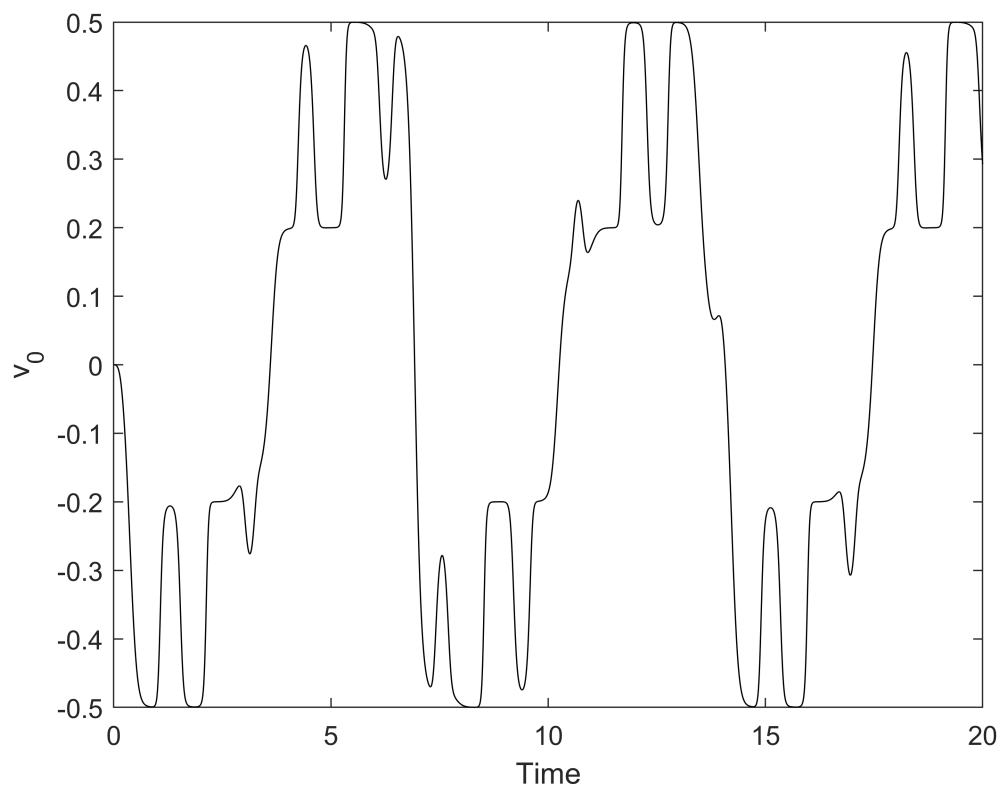
$$a_1 = 0.2, \quad a_2 = 0.5, \quad a_3 = -0.2, \quad a_4 = -0.5$$

$$k_1 = 2.0, \quad k_2 = 2.0$$

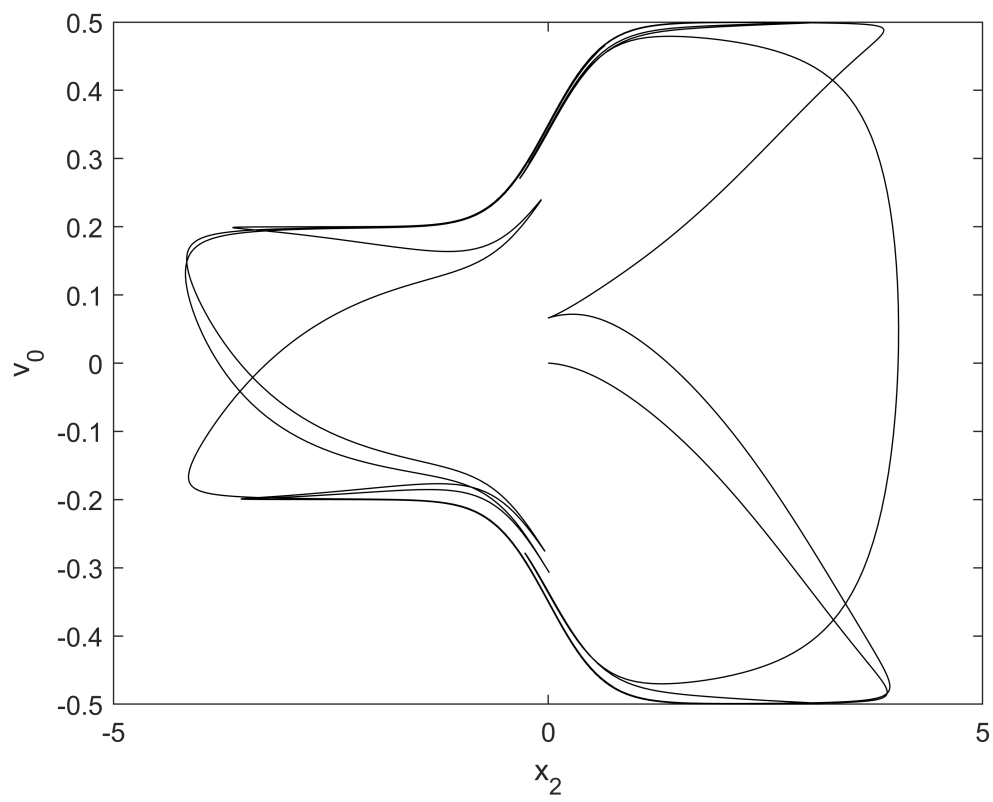
```
w = 5;
A=10;
a1=0.2;
a2=0.5;
a3=-0.2;
a4=-0.5;
k1=2;
k2=2;
```

```
xy=out.f_xy.Data;
t=out.f_xy.Time;
x2=out.x2.Data;
x1=out.x1.Data;
```

```
figure
plot(t,xy,'k')
xlabel('Time')
ylabel('v_0')
```



```
figure
plot(x2,xy,'k')
xlabel('x_2')
ylabel('v_0')
```



```
figure
plot(x1,xy,'k')
xlabel('x_1')
ylabel('v_0')
```

