

RosHandler

- nh
- linear
- angular
- l_scale
- a_scale
- sonarPoints
- current_linear_velocity
- current_angular_velocity
- last_dt
- last_joy_time
- vel_pub
- sonar_sub
- joy_sub
- ram_pub
- ram_timer

- + RosHandler()
- + getSonarPoints()
- + getLinearVelocity()
- + getAngularVelocity()
- + getLastDeltaTime()
- joyCallback()
- sonarPointReceiver()
- getMemoryUsageKB()
- publishMemoryUsage()