

Programming Familiarization Part 2
ROS Familiarization (ROS message/comms protocols)

Part 4: 5%

Questions:

1. Briefly explain how services in ROS work. A few lines will suffice.

A pair of message of request and reply is called service in ROS. Client calls the service to a ROS node that offers a service by sending the request message and awaiting the reply.

2. Include a ROS node graph of your nodes. This can be automatically generated using rqt (http://wiki.ros.org/rqt_graph). This graph needs to include all the nodes and topics.

3. Do you think the assignment was helpful for you to get started in ROS? If not, how would you improve it?

4. Was the assignment difficulty manageable?