

Machine Learning

Lecture 2 - Machine Learning Fundamentals

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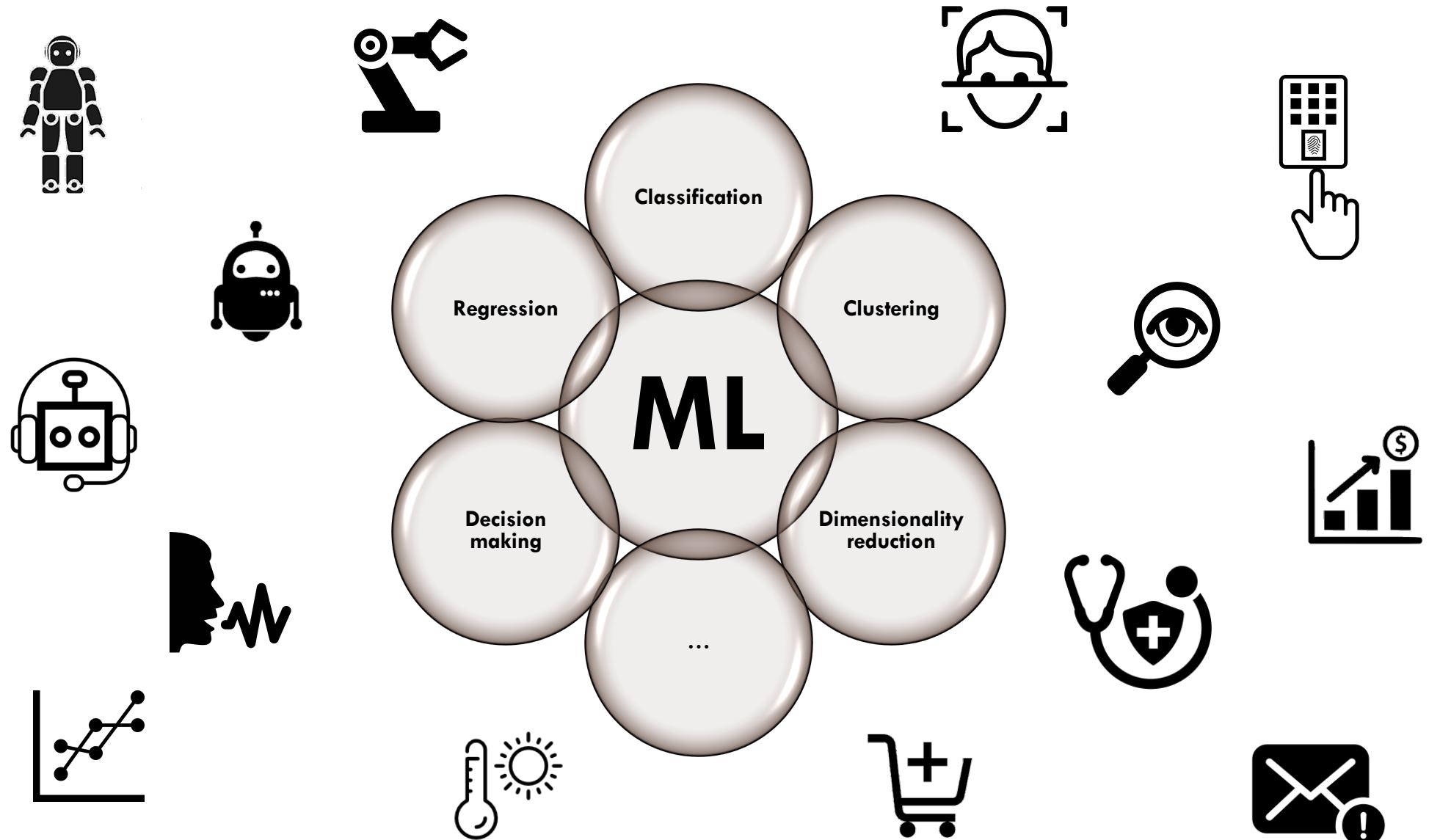


- ML typical tasks:
 - Regression
 - Clustering
 - Classification
 - Dimensionality reduction
 - Decision making
- Model training, performance and evaluation basic concepts:
 - Generalization
 - Underfitting
 - Overfitting
 - Data splitting
 - Cross-validation
 - Training early stopping
 - Data normalization

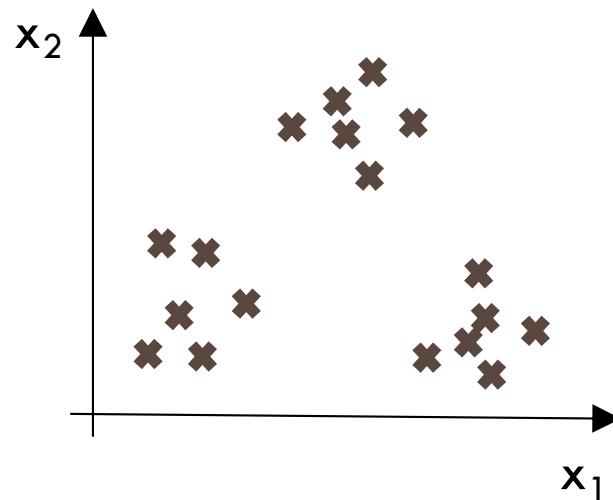


ML Typical Tasks

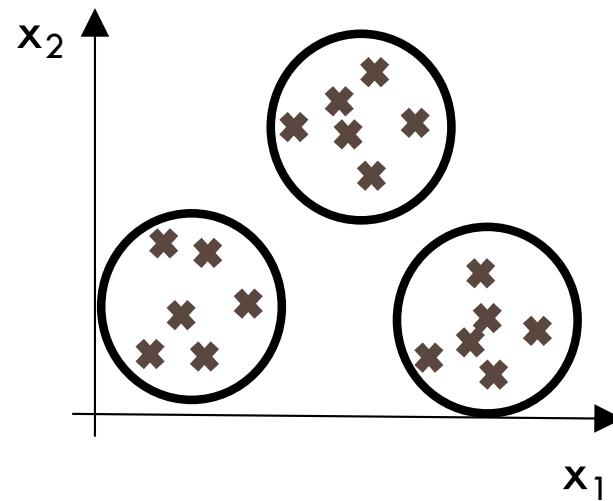




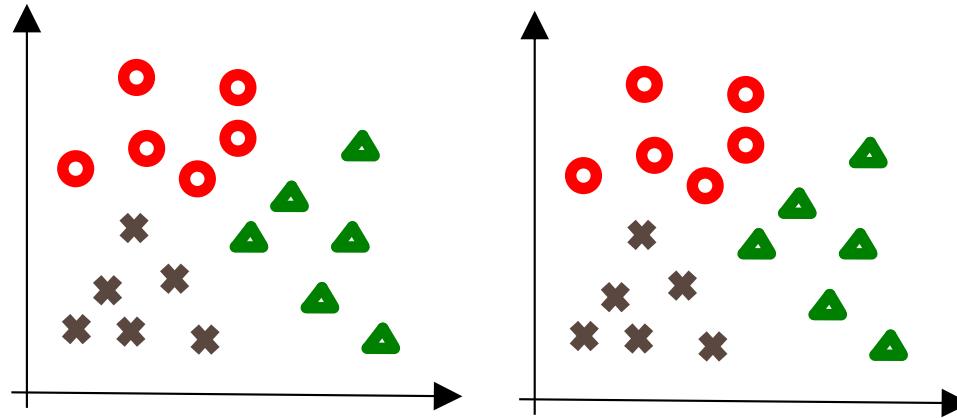
- Given some (typically unlabeled) data points, the goal is to group these points in such a way that points in the same group (or cluster) can be, **in some sense, more similar to each other** than points in other groups
- Common measures: distance between cluster members, density of clusters, statistical distribution...



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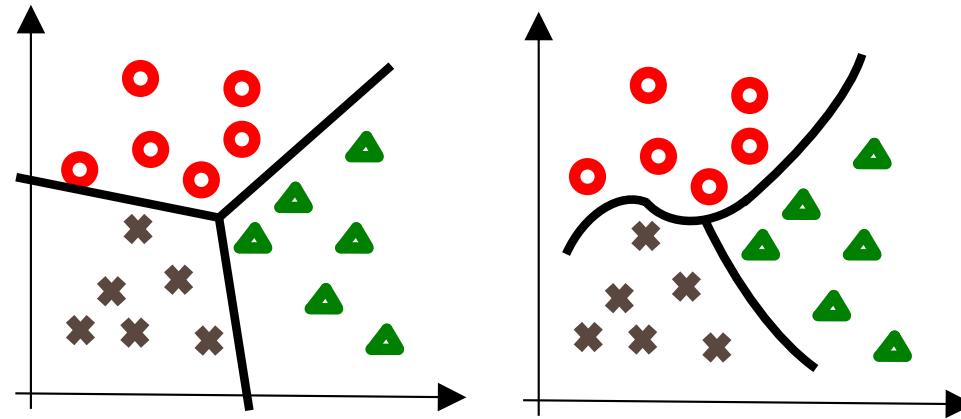


- Given a set of input data points and the classes they belong (labels), the goal is **to identify to which class a new observation belongs**



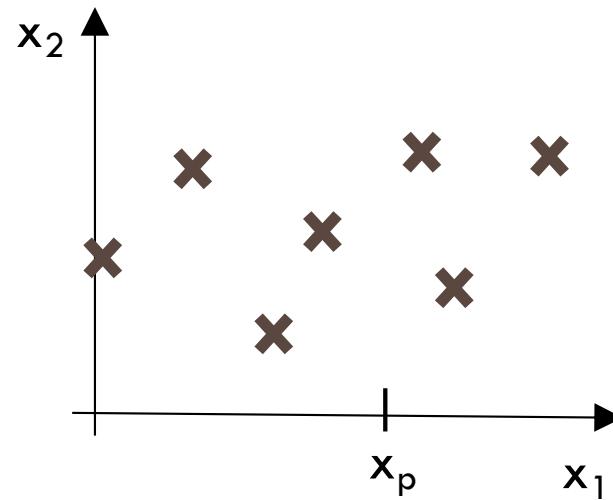
- Most of the classification methods look to establish **decision boundaries** to separate the different classes

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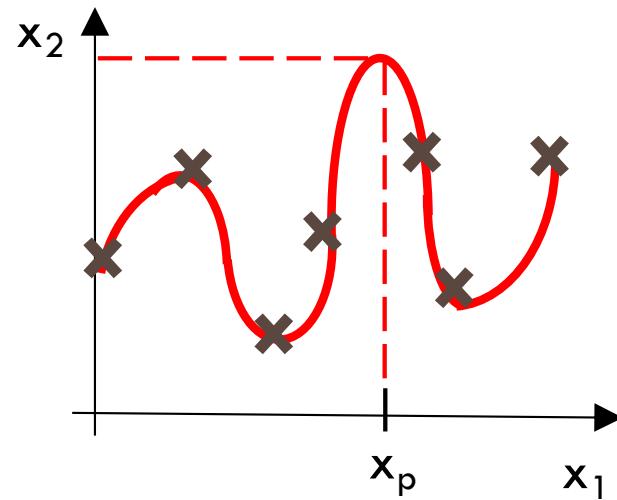


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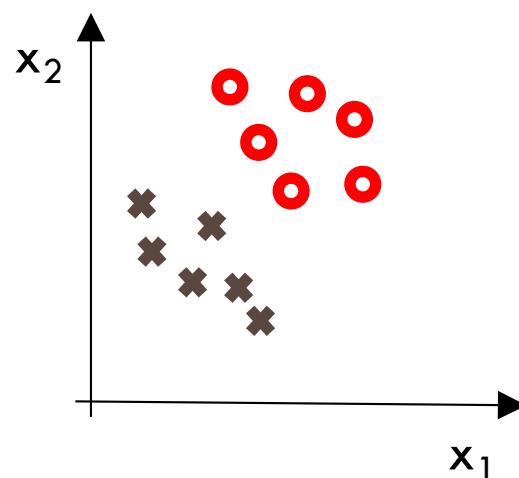
- Given some data points, the goal is to learn a **mathematical model** capable to fit data with a **curve**, so that the curve passes as close as possible to all of the data points
- This approach allows to **predict** the output for points that were not part of the original data



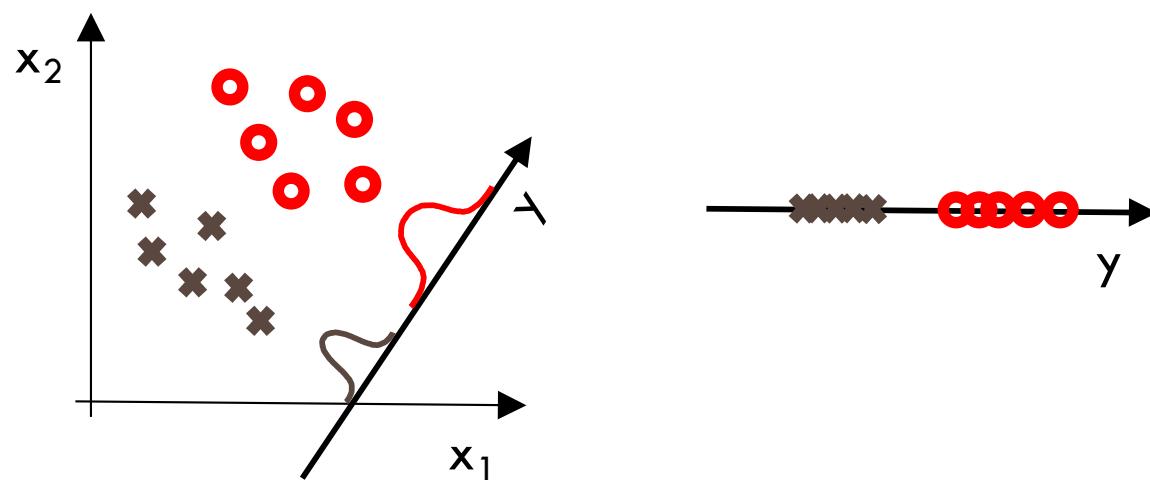
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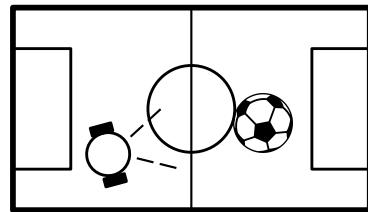
- Given a set of data points in a high number of dimensions (features or attributes), the goal is **to reduce the number of dimensions under consideration**
- Benefits: lower data volume, less computing required, shorter analysis time...



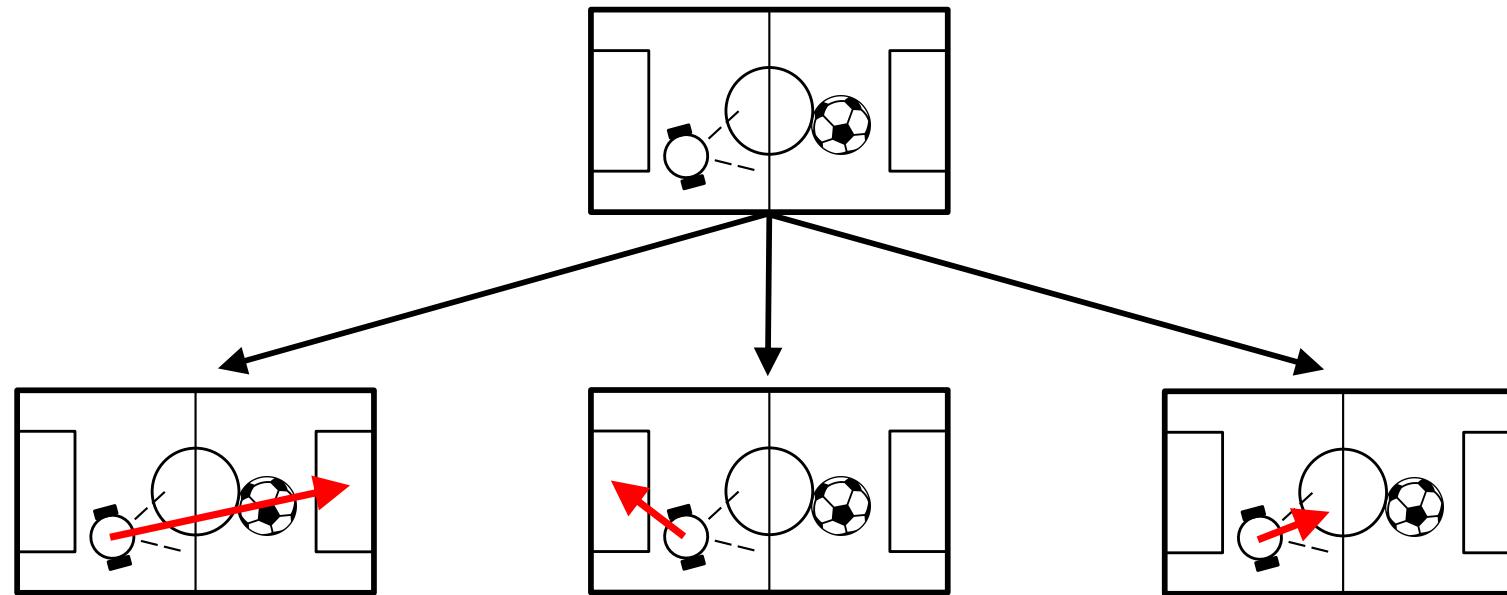
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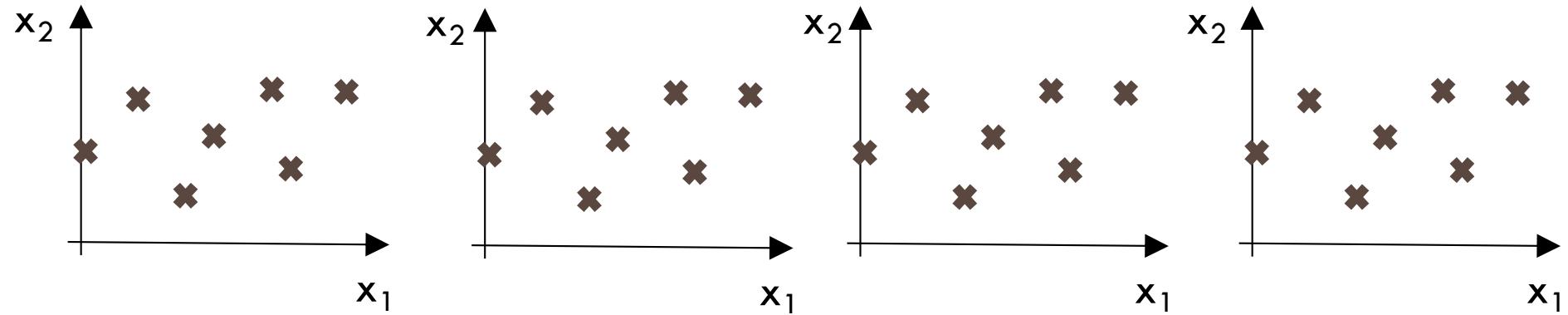




Fundamental concepts

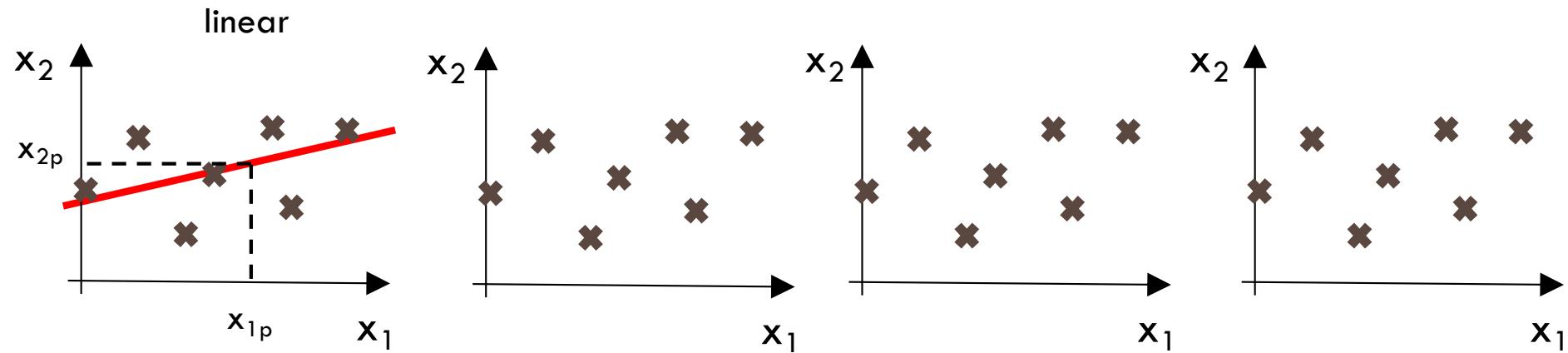


- Which function best describes the data?



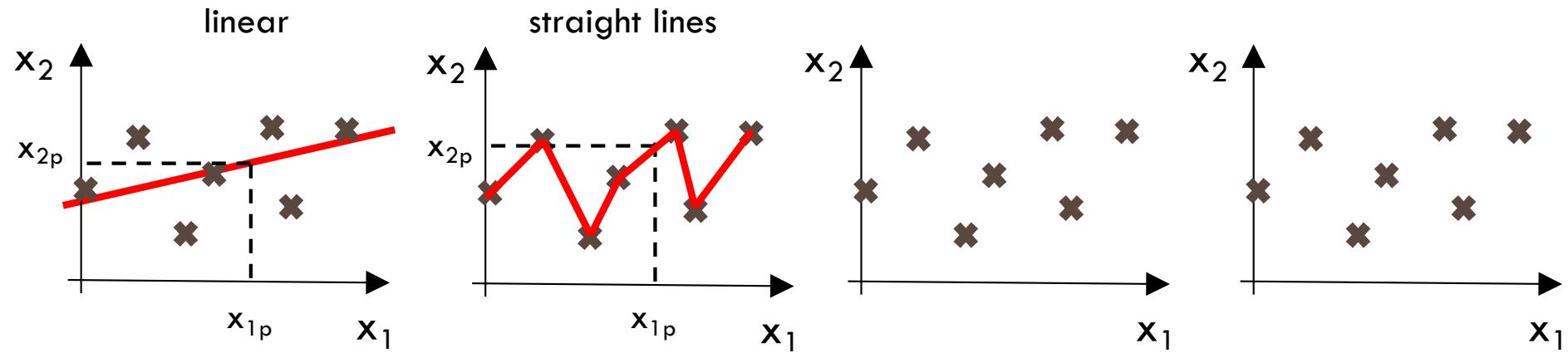
- In learning process, we are concerned with:
 1. Learning functions/models/concepts that will give us the correct outputs for the data present in the training set
 2. Learning functions/concepts/models that can **generalize** to instances similar, but not identical, to those in the training set
- **Generalization:** capacity to correctly predict values for unseen data

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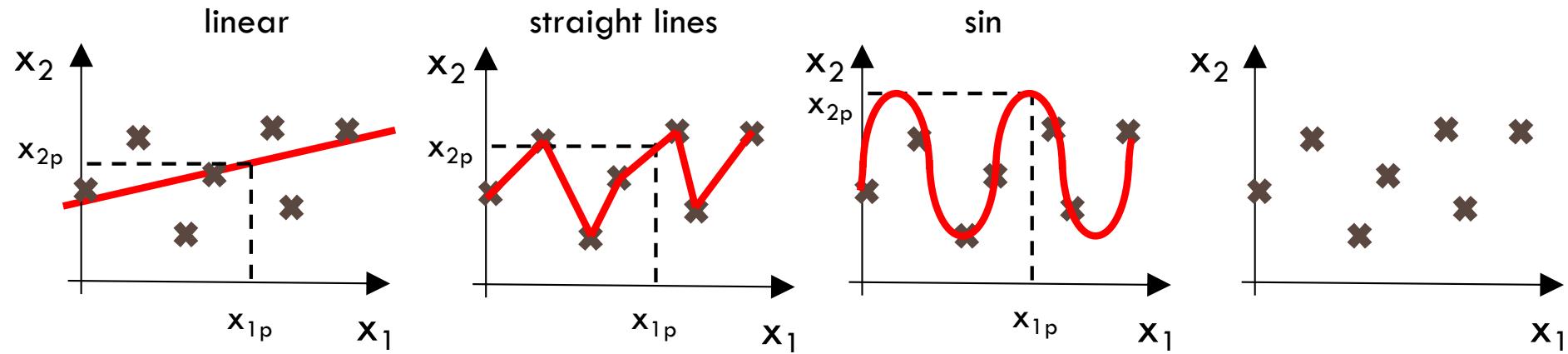
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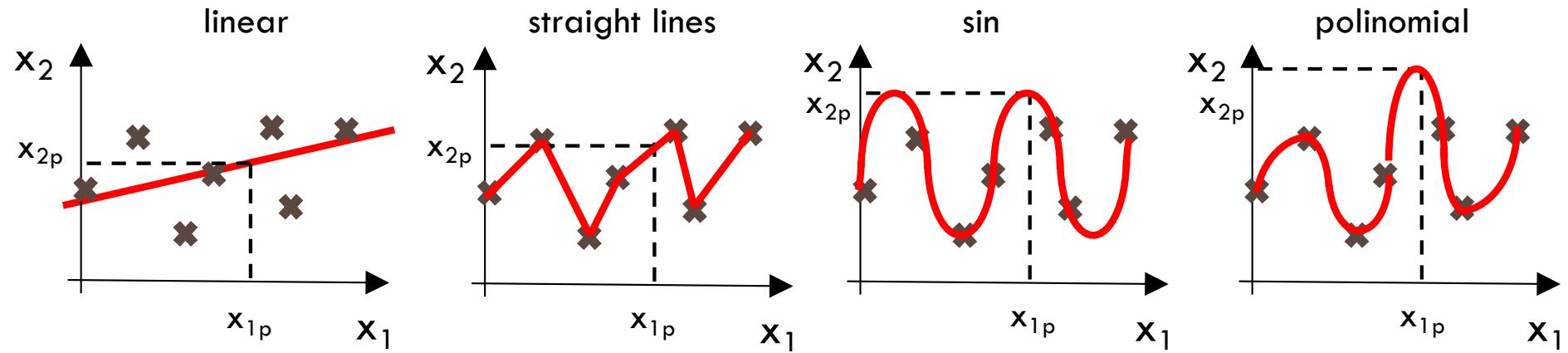
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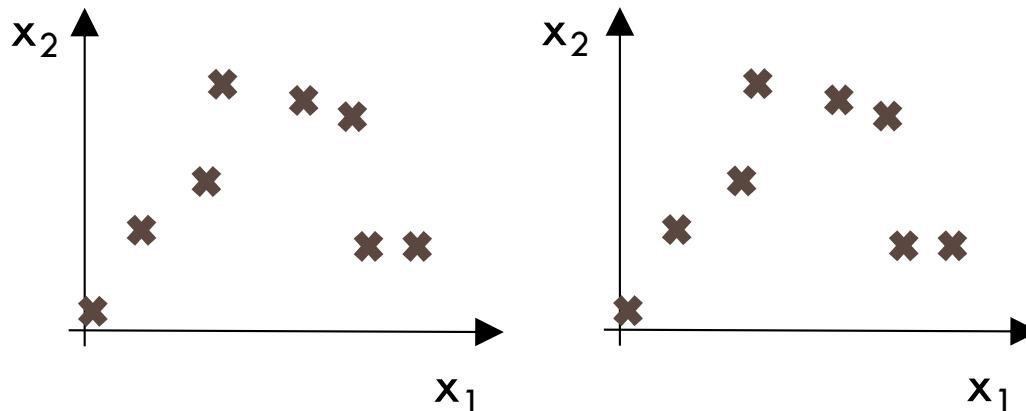
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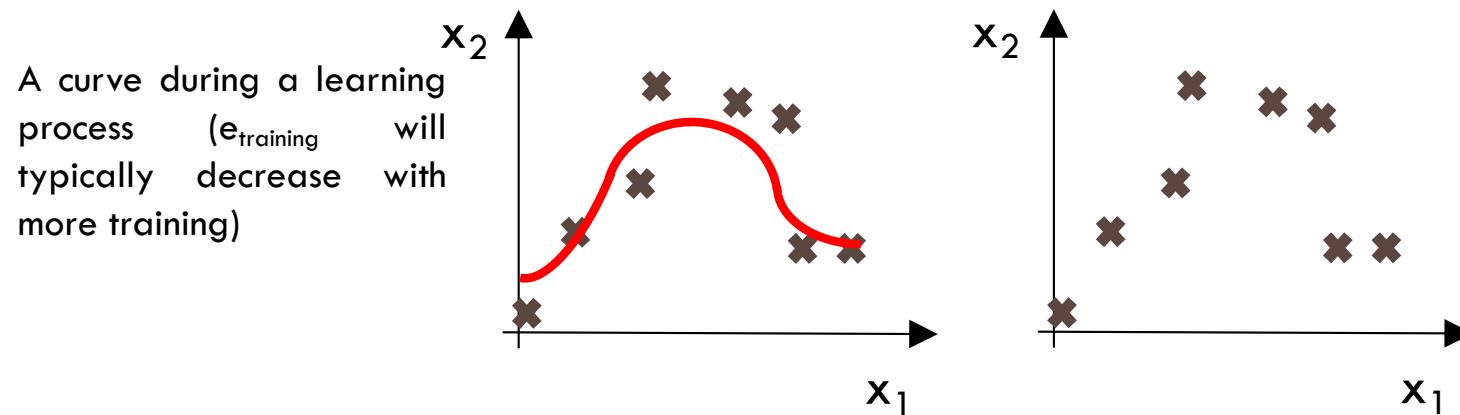


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- Occurs when a model is **not capable** of adequately represent the training data ($\uparrow e_{\text{training}}$) nor generalize to new data
- It typically occurs due to:
 1. The system was **not trained enough**
 2. The model is **not complex enough** to adequately represent the data, even with more training

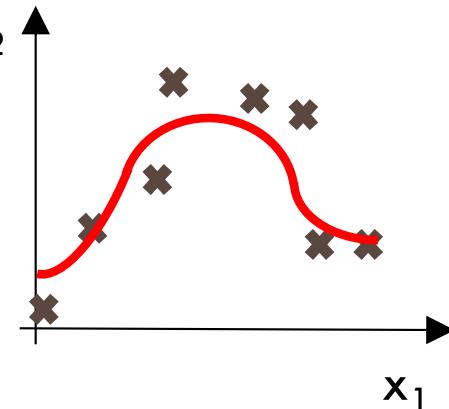


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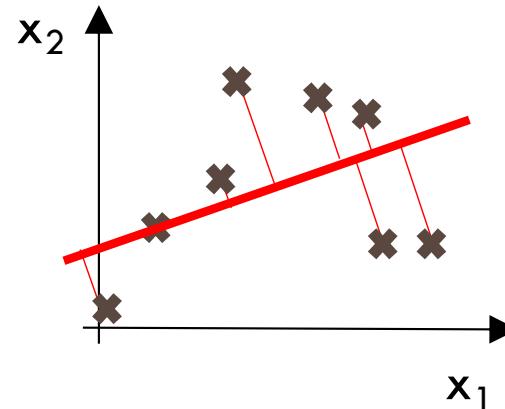


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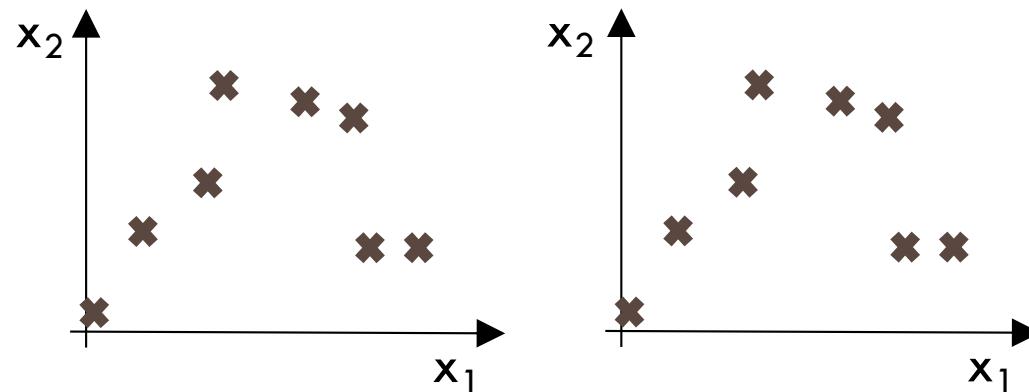
A curve during a learning process (e_{training} will typically decrease with more training)



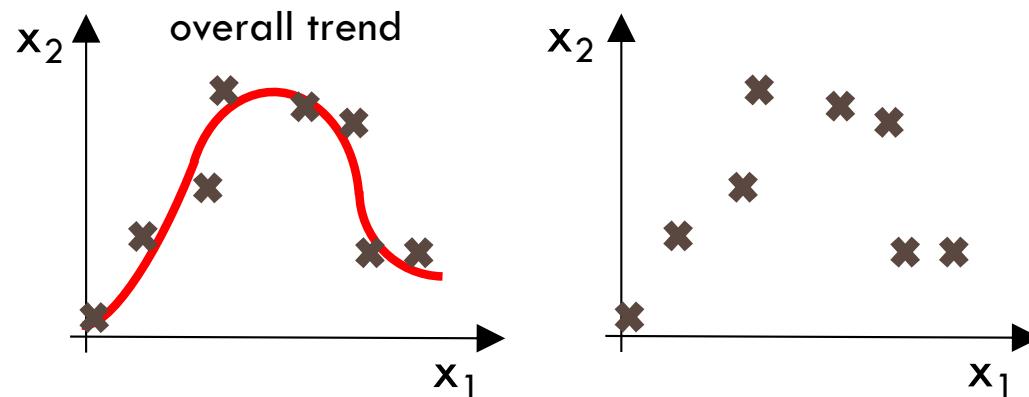
A first order model that may not be suitable for representing the data (e_{training} typically will not decrease with more training)



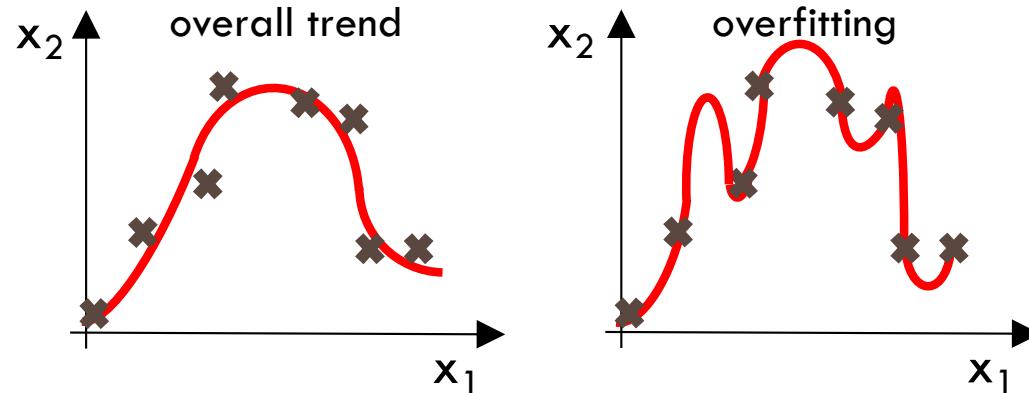
- In well trained systems, typically curves will tend to fit the overall trend of the data ($e_{\text{training}} > 0$)
- If the system is **trained for too long**, it tends to learn the noise and inaccuracies of the data. Models that are more complex than necessary will be learned, generating lower training errors (eventually $e_{\text{training}} = 0$), but reducing the performance of the system with new data ($\uparrow e_{\text{generalization}}$). This situation is called **overfitting**.



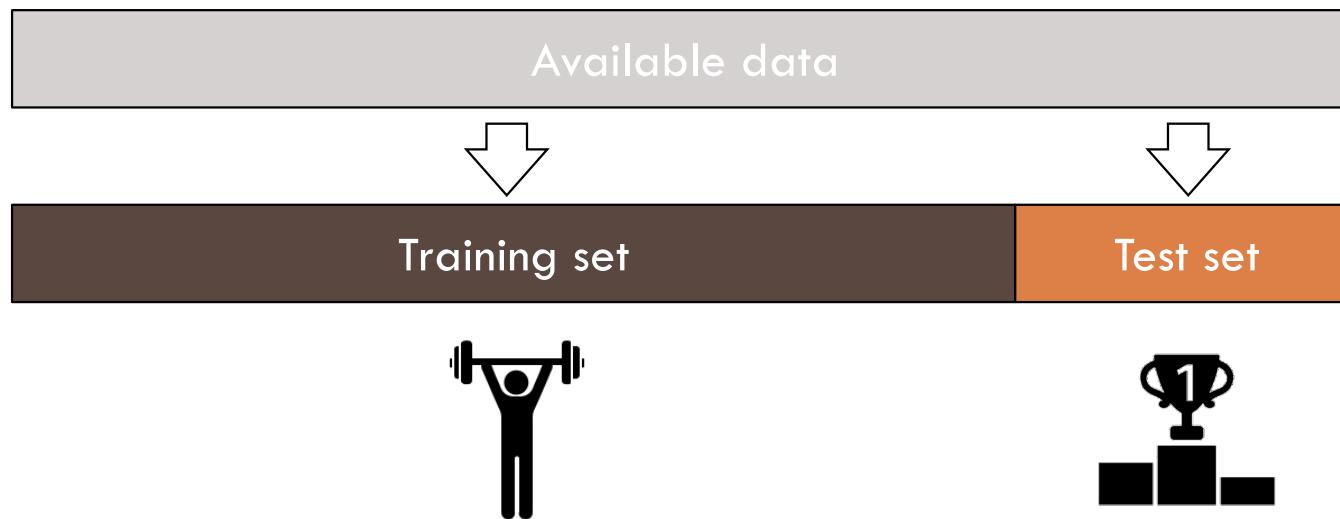
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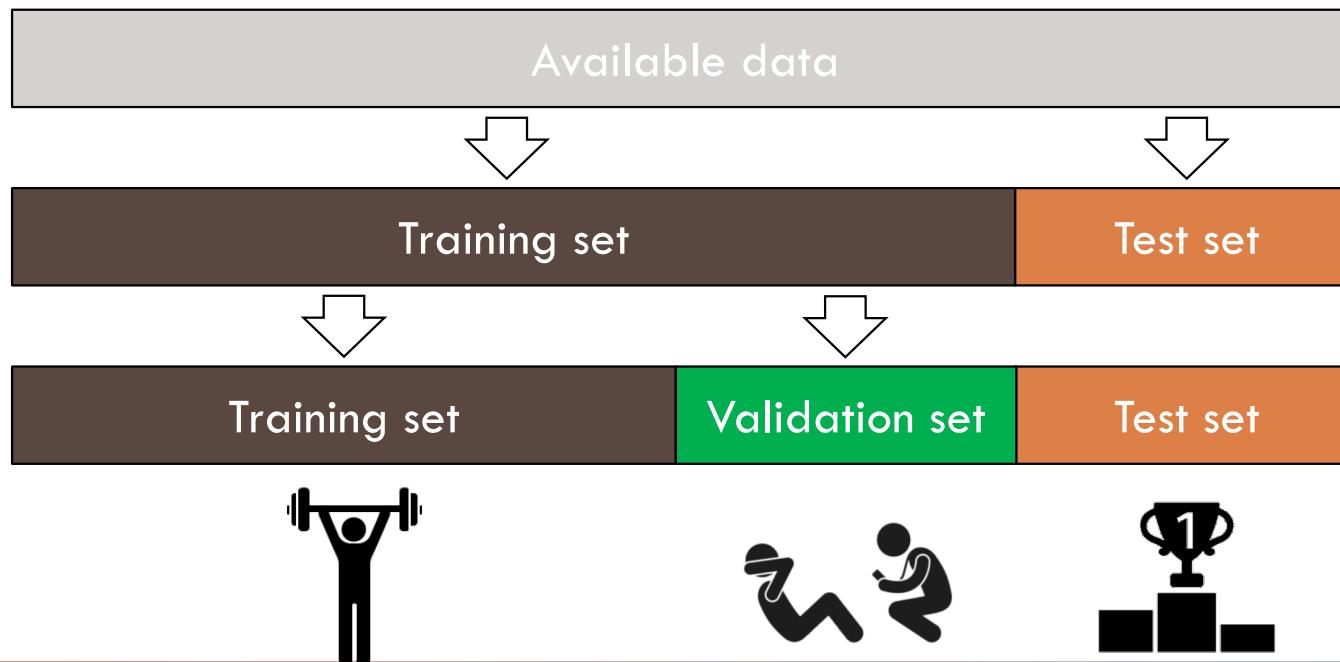
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- A common strategy in learning systems is to split the data set in two subsets:
 - **Training set:** data used to train system (adjust the free parameters of the model)
 - **Test set:** data used to evaluate system (learned model). This data should never be used until the end of training!

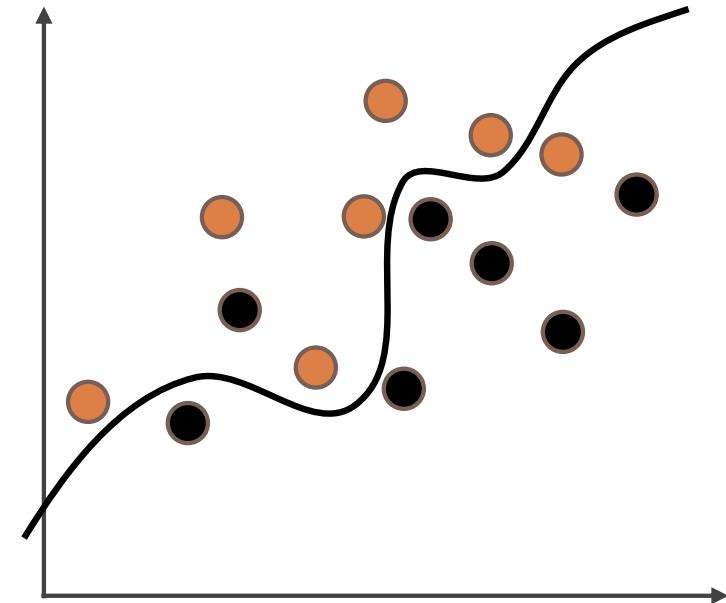
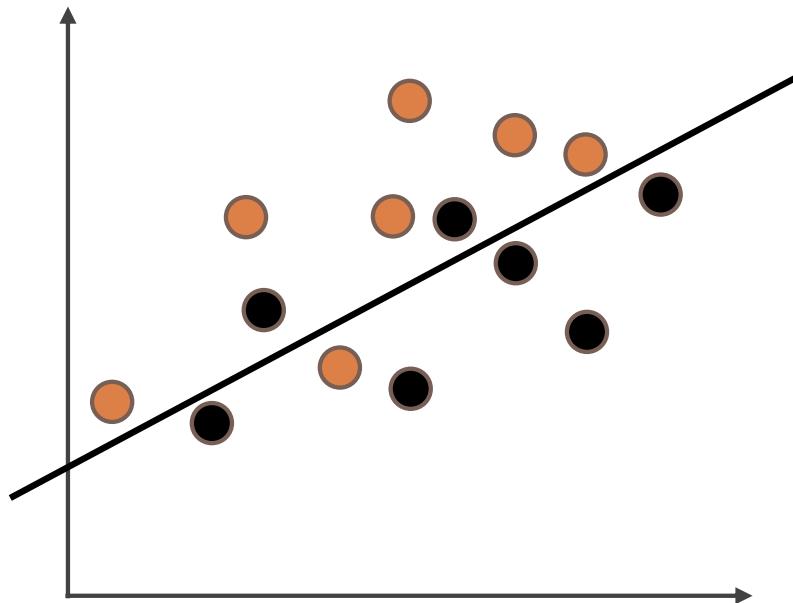


- Strategy to estimate **how good is the model generalization** in the training phase and eventually to **stop training**
- **Validation set:** data set (not used in training phase) that will be eventually used to evaluate training
- A suitable **proportion** between sets must be defined. Usual practical values are: 50:25:25 or 60:20:20 (if you have plenty of data) until 90:5:5 (few data)



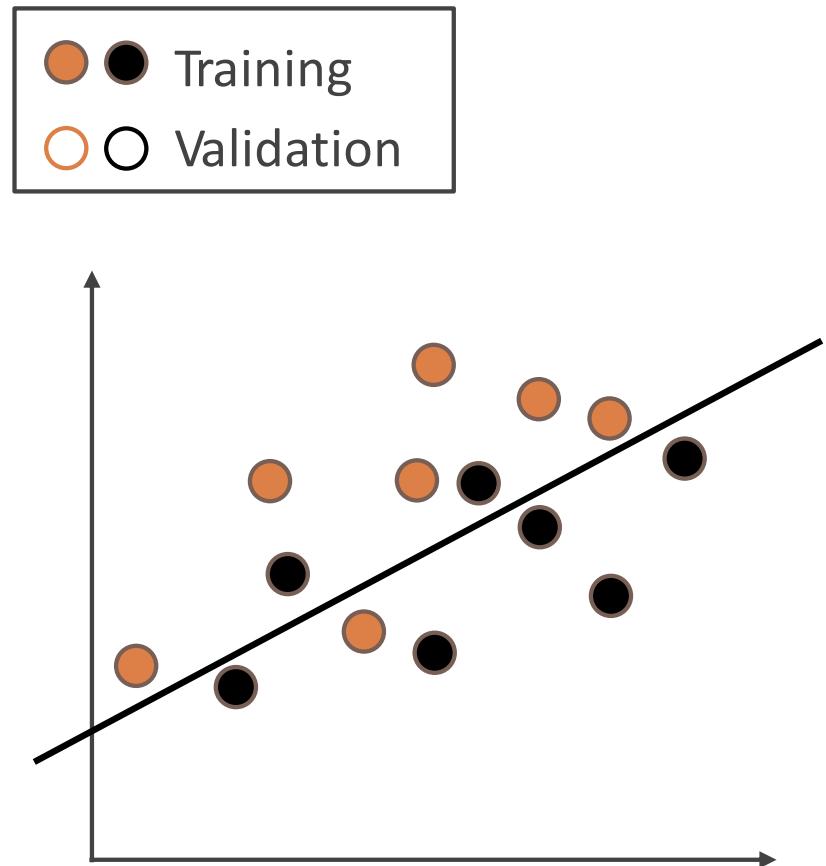
•••• Which model is better?

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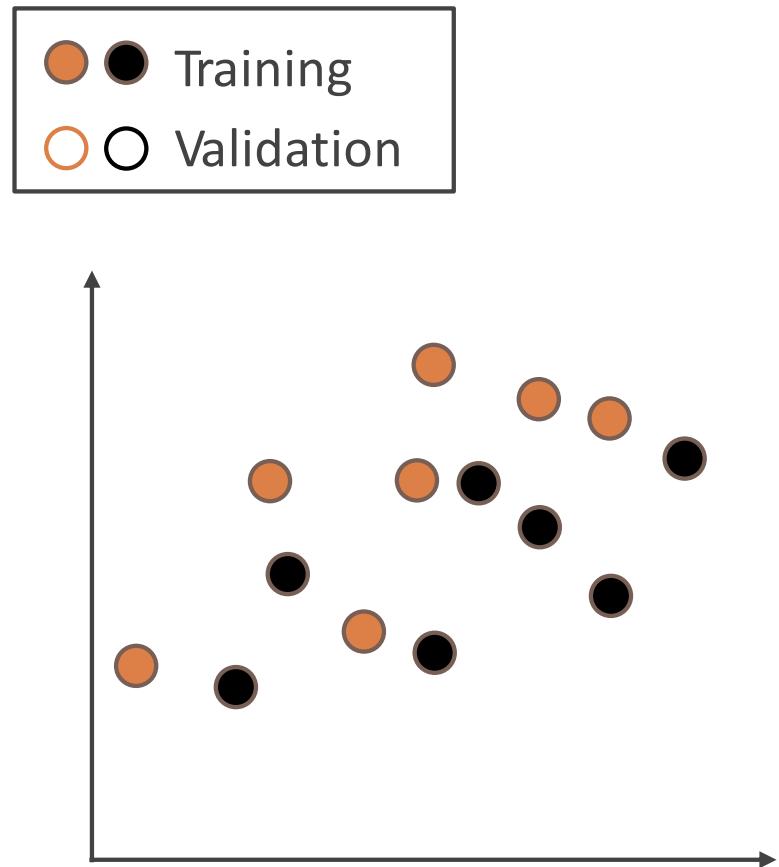
••••• Why validating?

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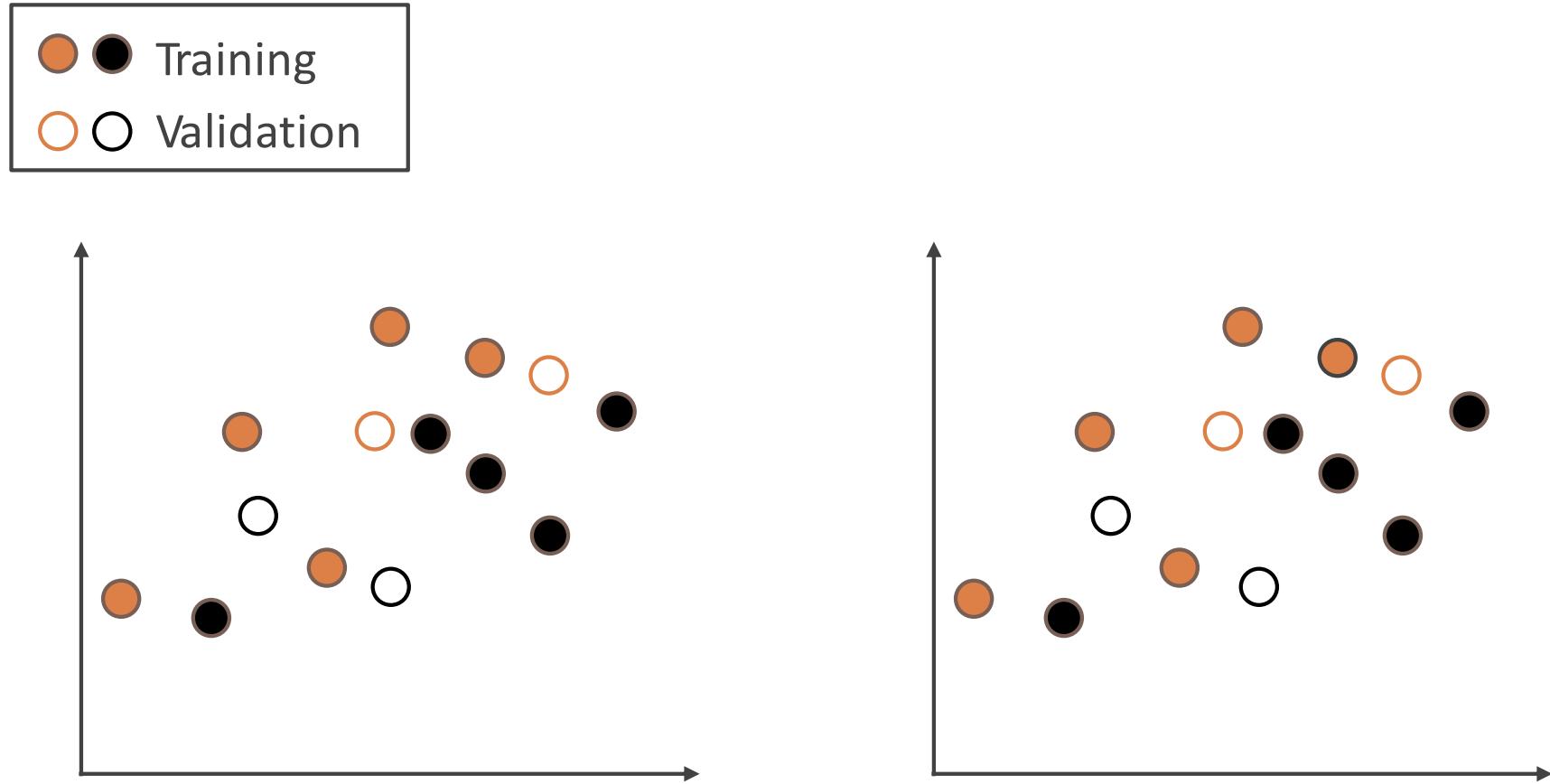
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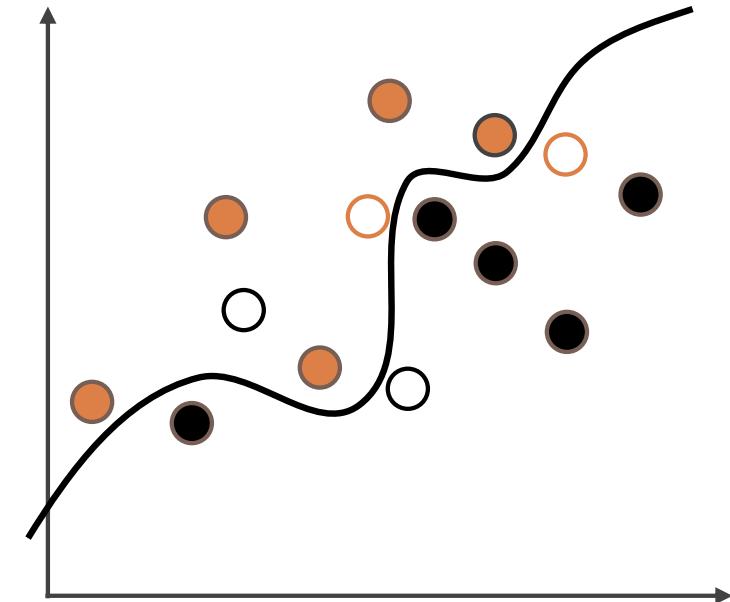
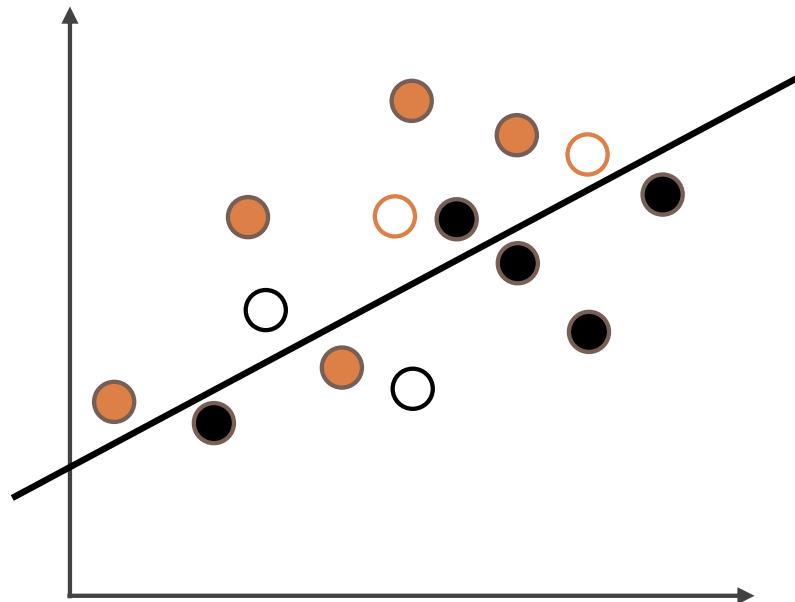
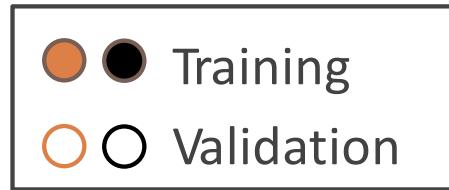
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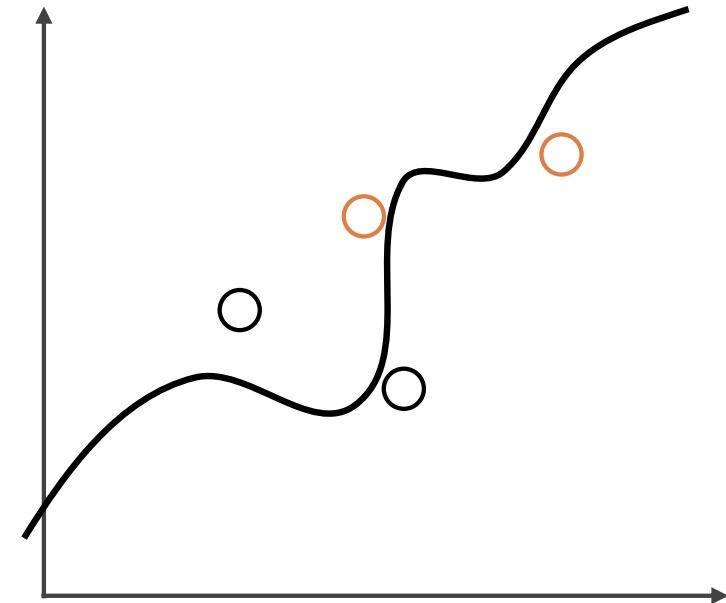
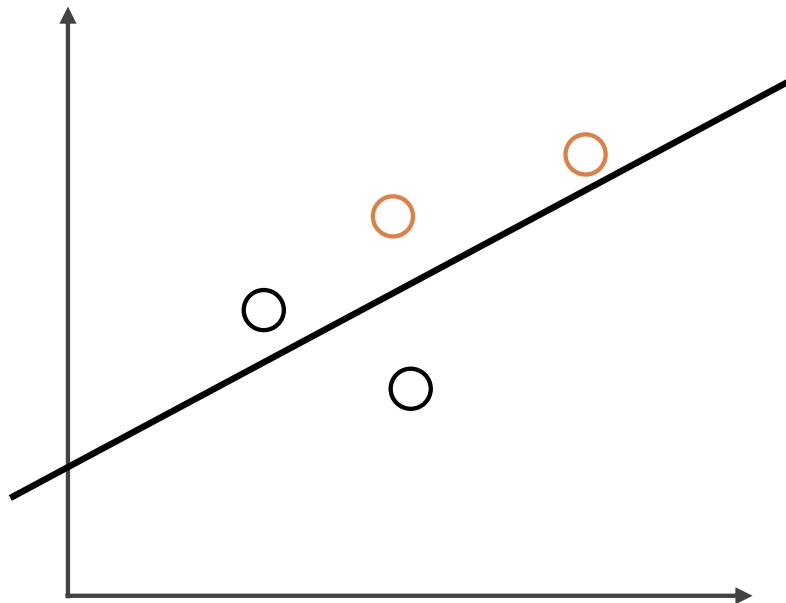
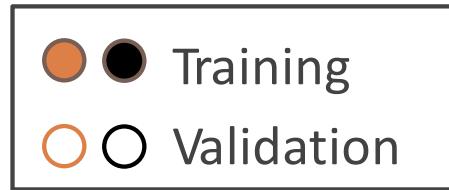
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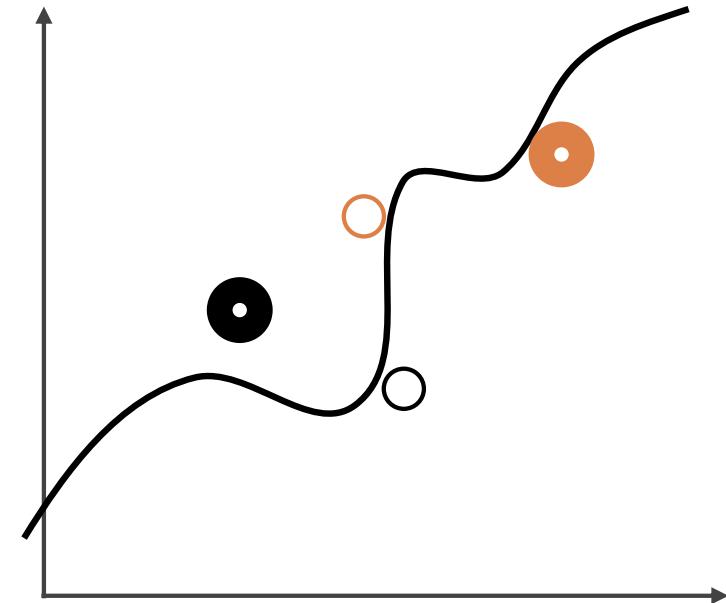
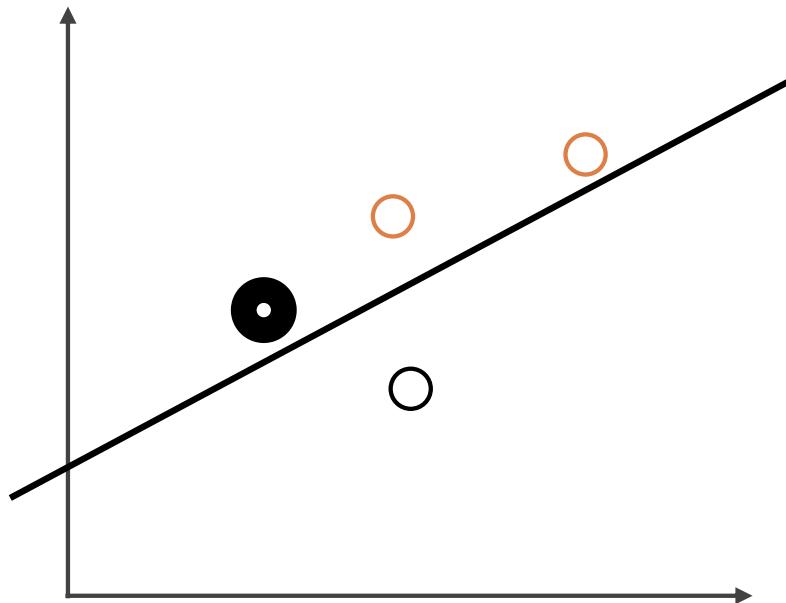
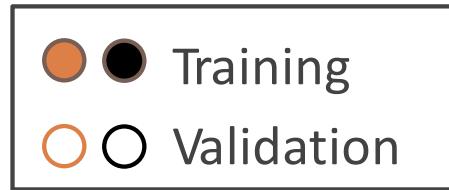
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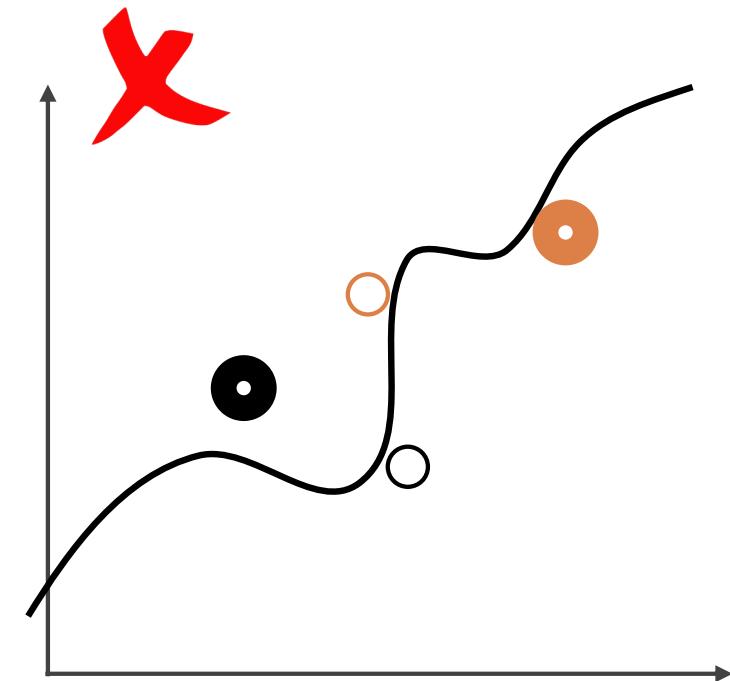
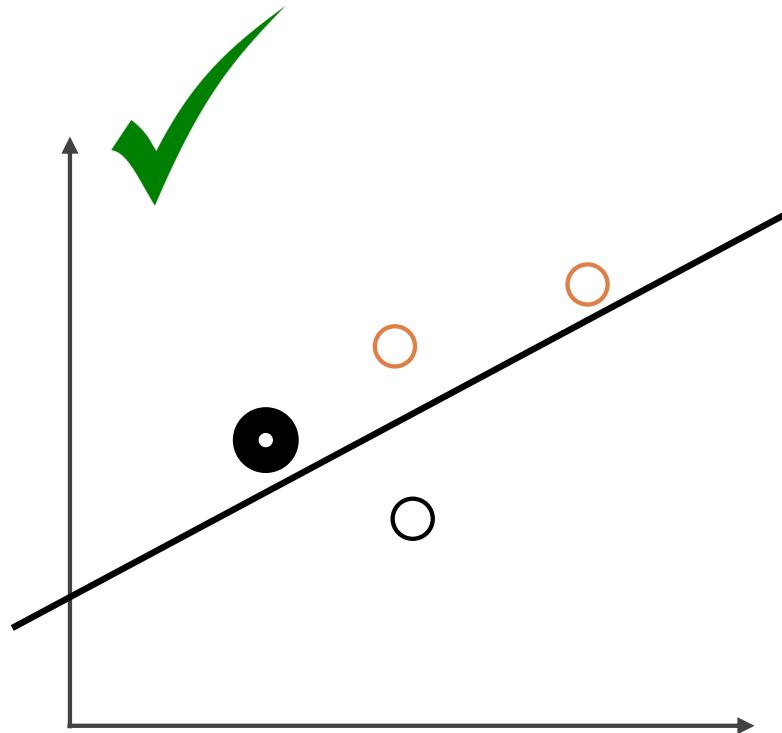
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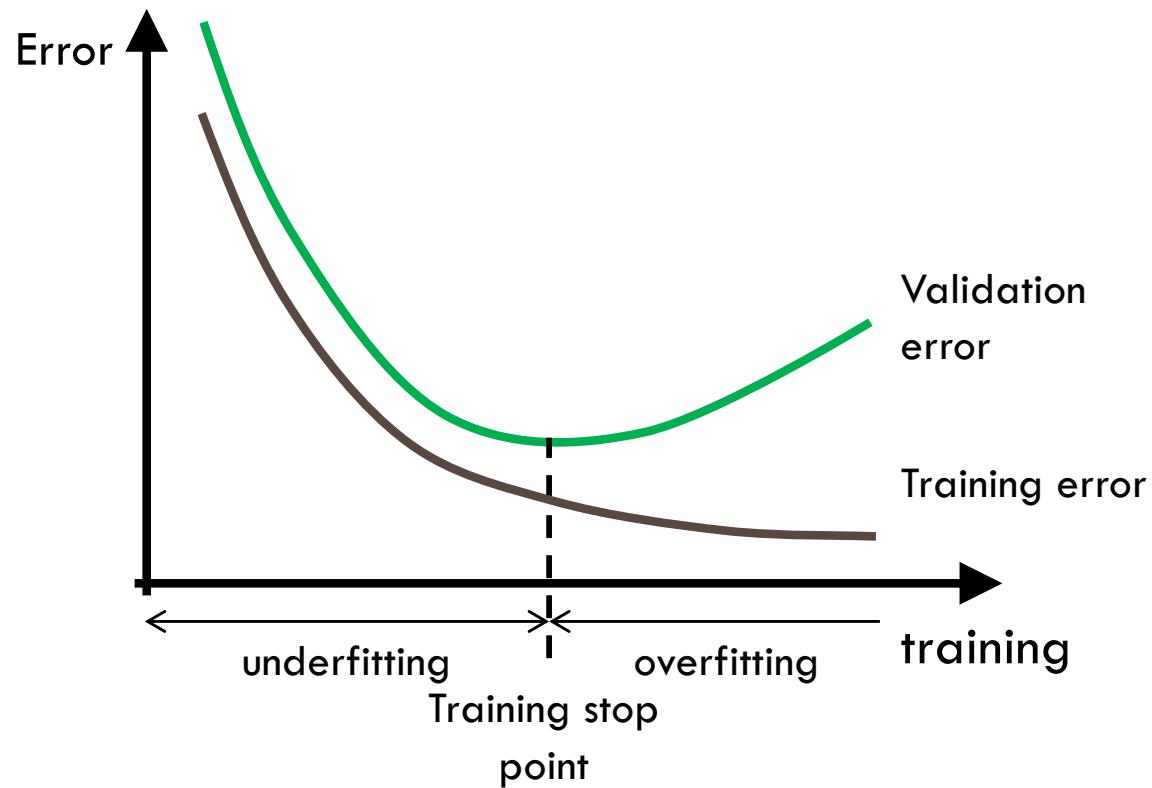


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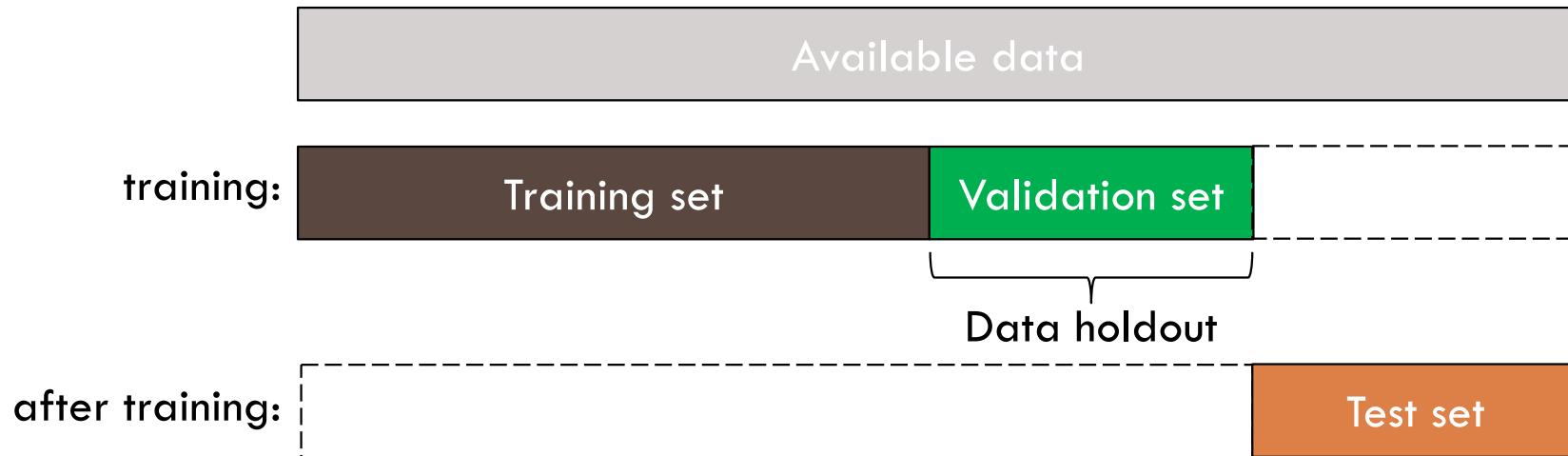
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- In training, the early-stopping must occur to avoid *underfitting* and *overfitting*



□ Holdout method:



□ Remarks:

- Less data available to training
- If training and validation sets have different data distribution, results can be distorted

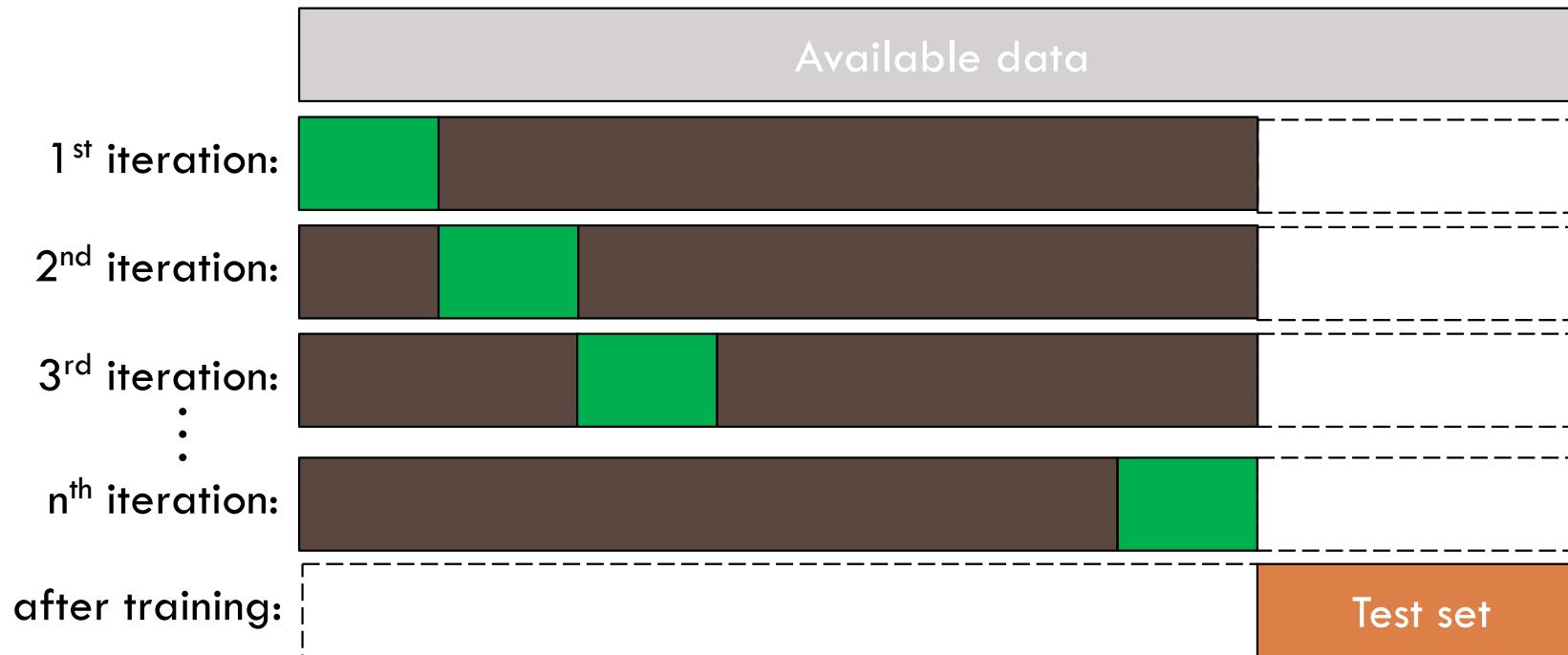
□ Repeated holdout method:



□ Remark:

- If some examples are selected more (or less) than others for the training or validation sets, results can be distorted

□ K-Fold:



□ Remarks:

- This strategy has a more structured way to divide the available data between training and validation sets
- Very common approach in practice

$$CV_{(K)} = \sum_{k=1}^K \frac{n_k}{n} \text{Error}_k$$

□ Leave-one-out:

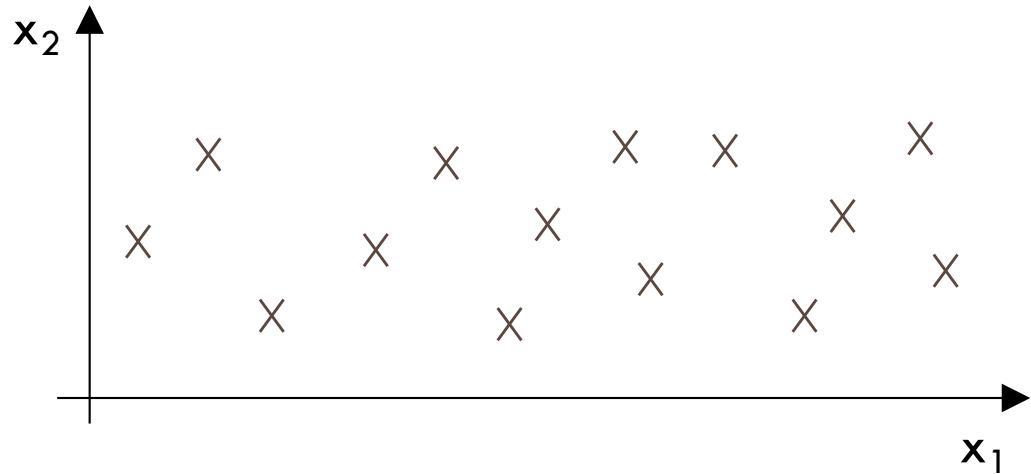
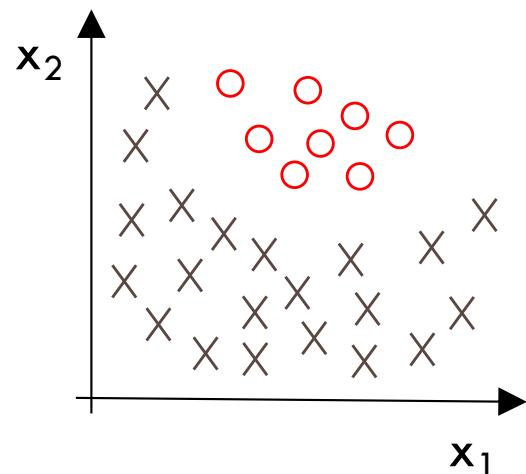


□ Remarks:

- Particular case of K-Fold with just one sample at the validation set

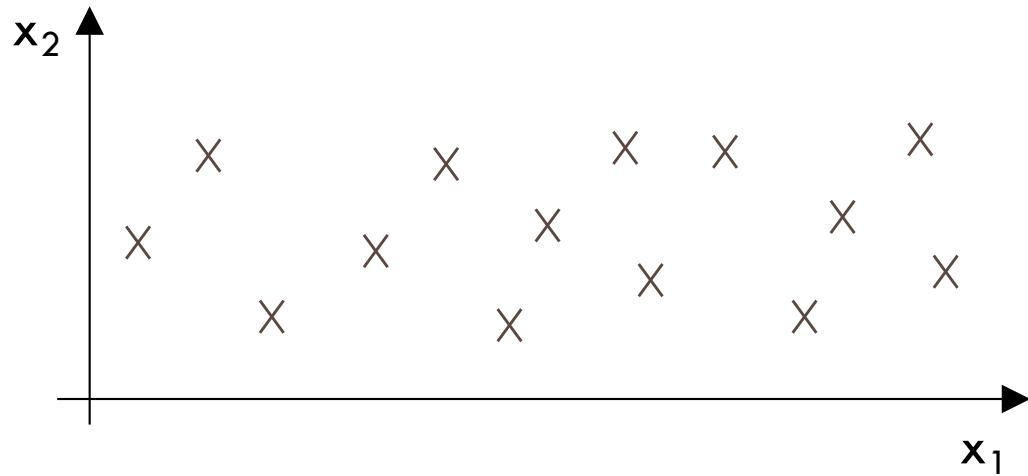
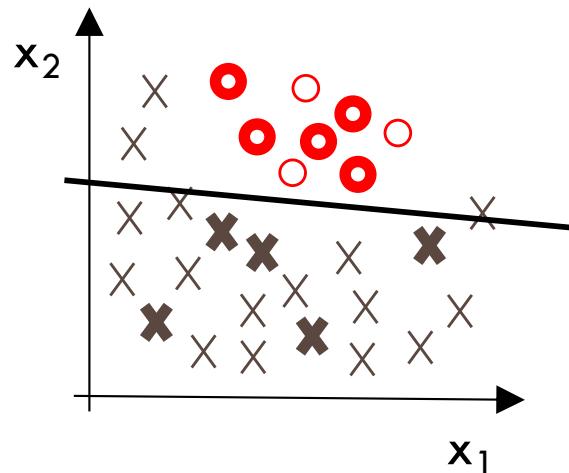
- ☐ Ideally, sampling in all datasets (training, validation and test) must have the **same data distribution than the total available data**. Particularly:

1. Sets must preserve the same relation of the number of samples from each class present in original data
2. Sets must contain samples spread over all regions of the domain



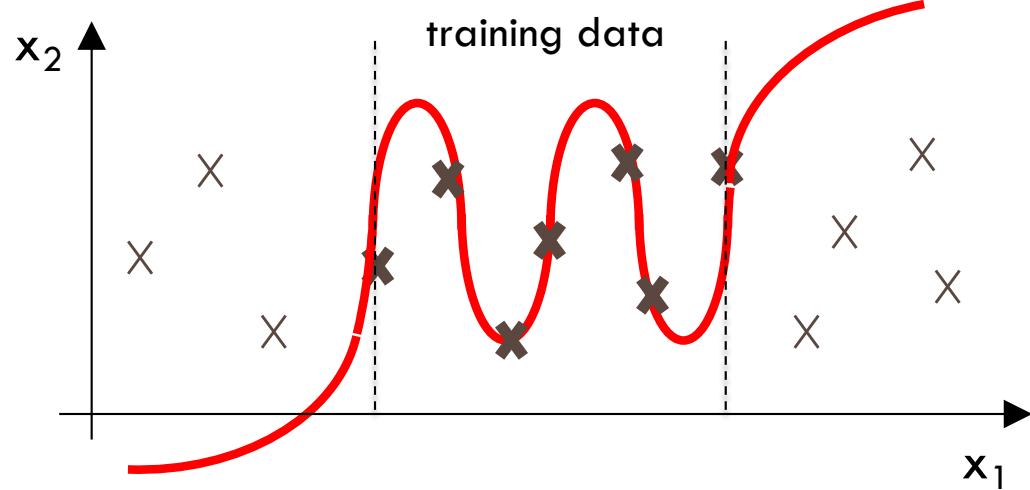
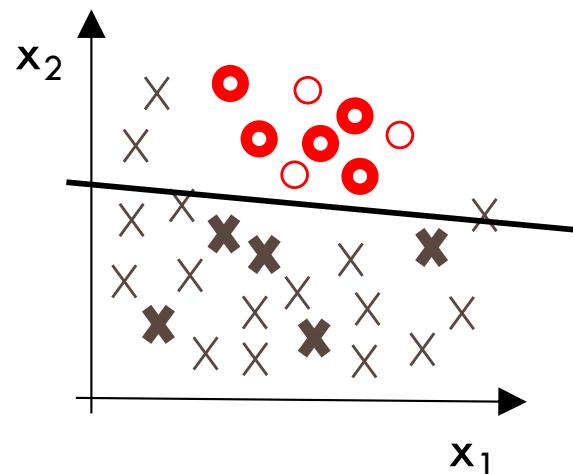
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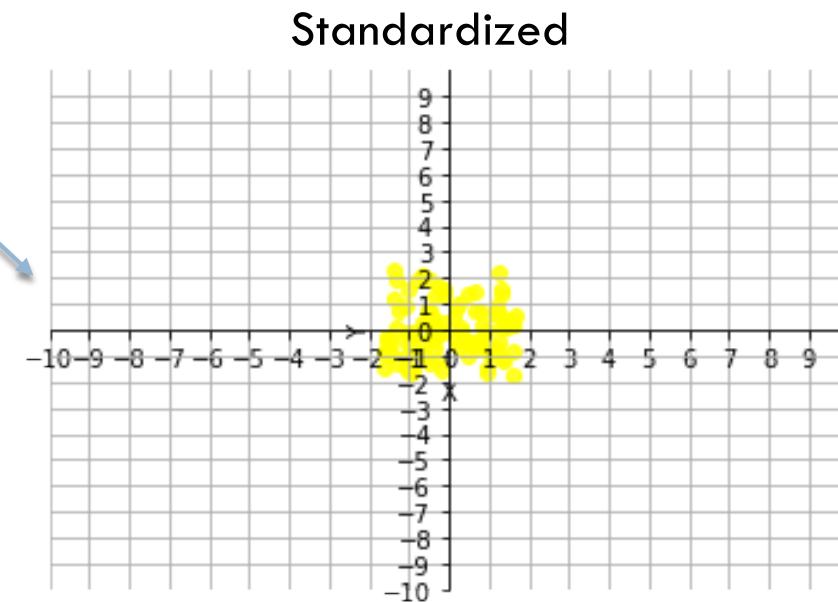
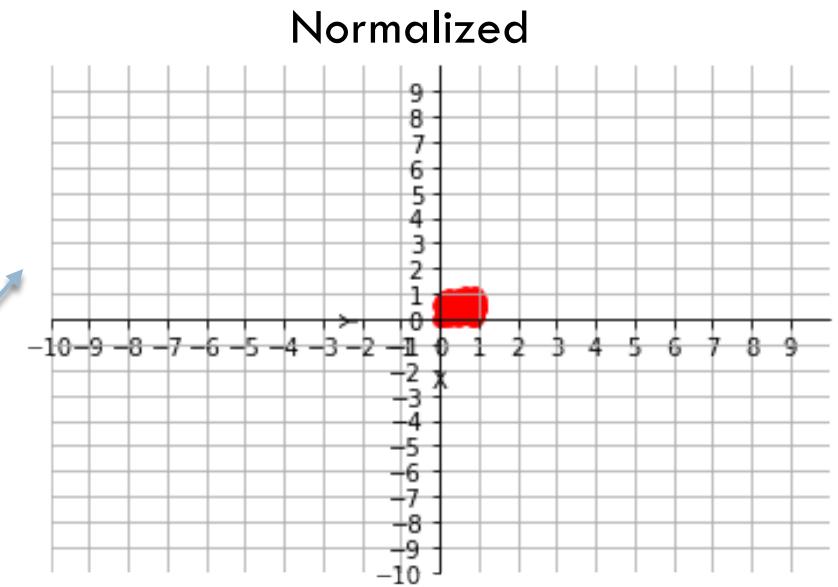
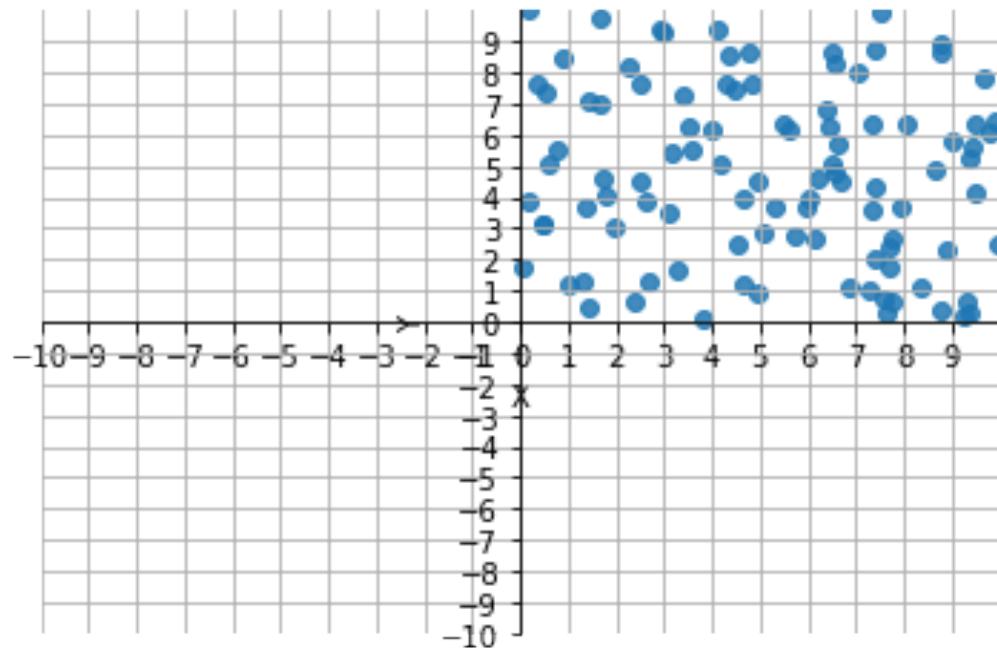
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- **Feature scaling** is a method used to normalize the range of independent variables or features of data
 - It is also known as data **normalization** and is generally performed during the data preprocessing step
 - In **normalization**, the range of your data changes. Normalization means adjusting values measured on different scales to a common scale
 - typically, between [0,1] or [-1,1]
 - In **standardization** the shape of the distribution of your data changes
 - typically means rescaling data to have a mean of 0 and a standard deviation of 1 (unit variance)
- Why use these pre-processing steps?
 - the range of values of raw data varies widely
 - some machine learning algorithms will not work properly without normalization
 - For example, methods that calculate the distance between two points using the Euclidean distance
 - If one of the features has a broad range of values, the distance will be governed by this particular feature

●●●● Feature scaling

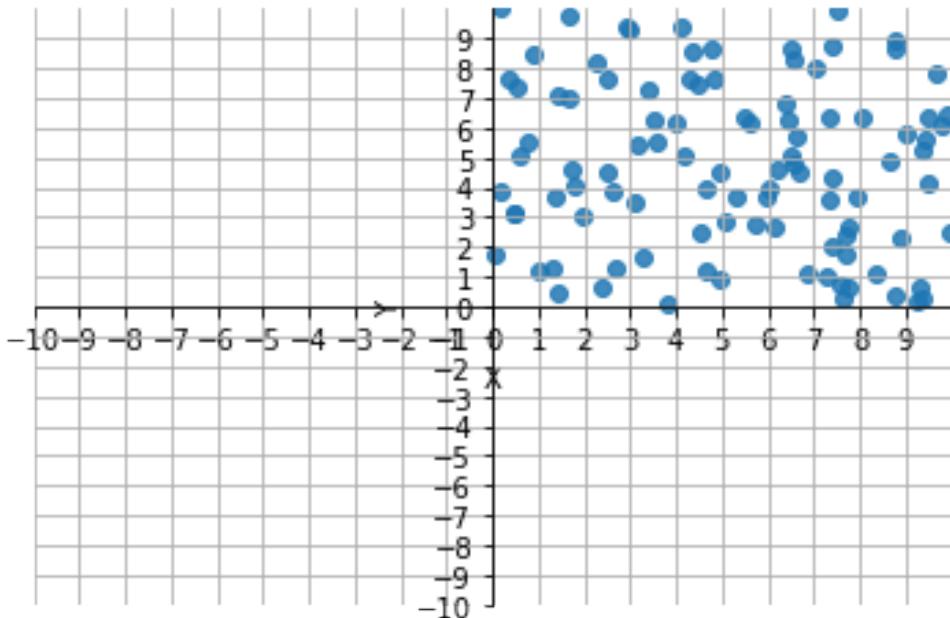
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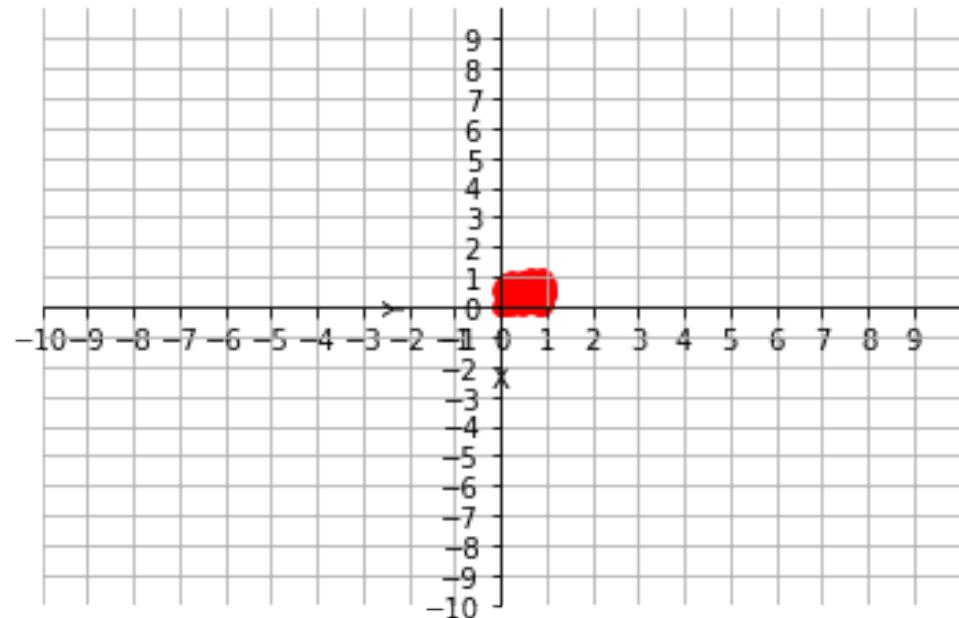
Types

□ Min-Max Scaler (MinMaxScaler)

- Transform features by scaling each feature to a given range



mean: [4.64091733 4.71477069]
std: [2.92323848 2.93324495]
min: [0.02917744 0.07193049]
max: [9.97337705 9.99855761]

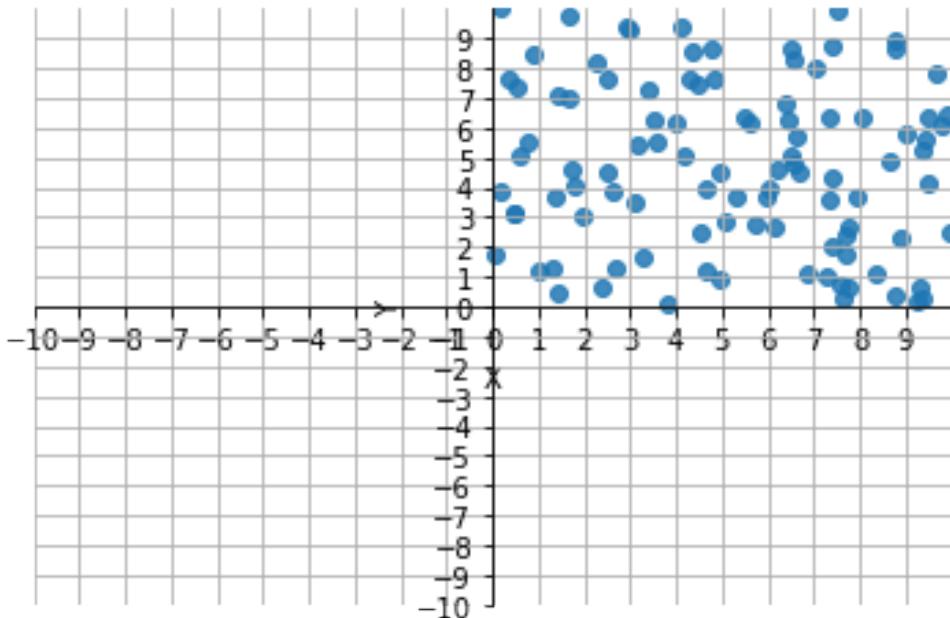


mean: [0.52228216 0.50308238]
std: [0.30594303 0.26681954]
min: [0. 0.]
max: [1. 1.]

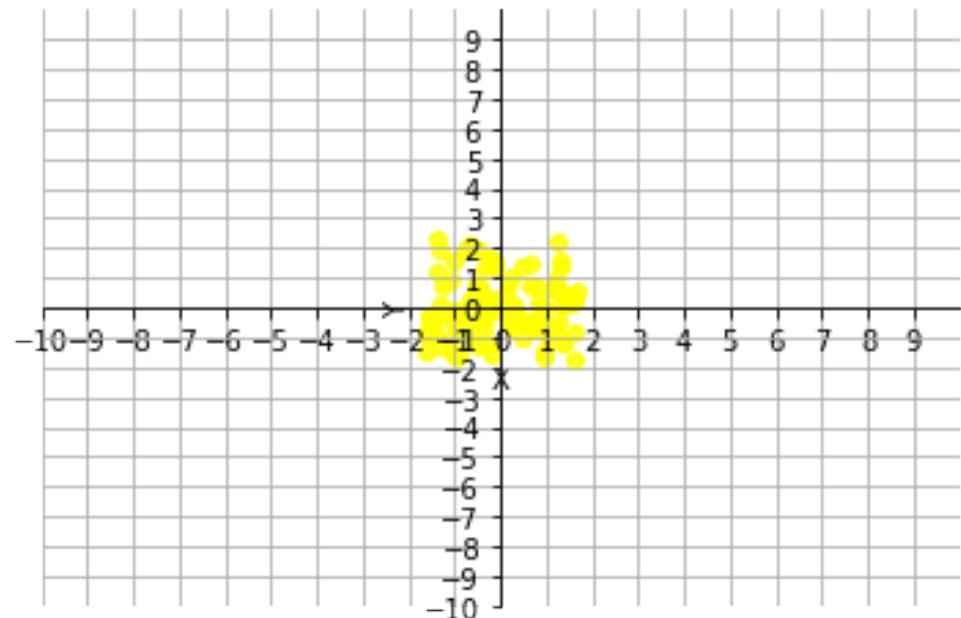
Types

□ Standard Scaler (StandardScaler)

- Standardize features by removing the mean and scaling to unit variance



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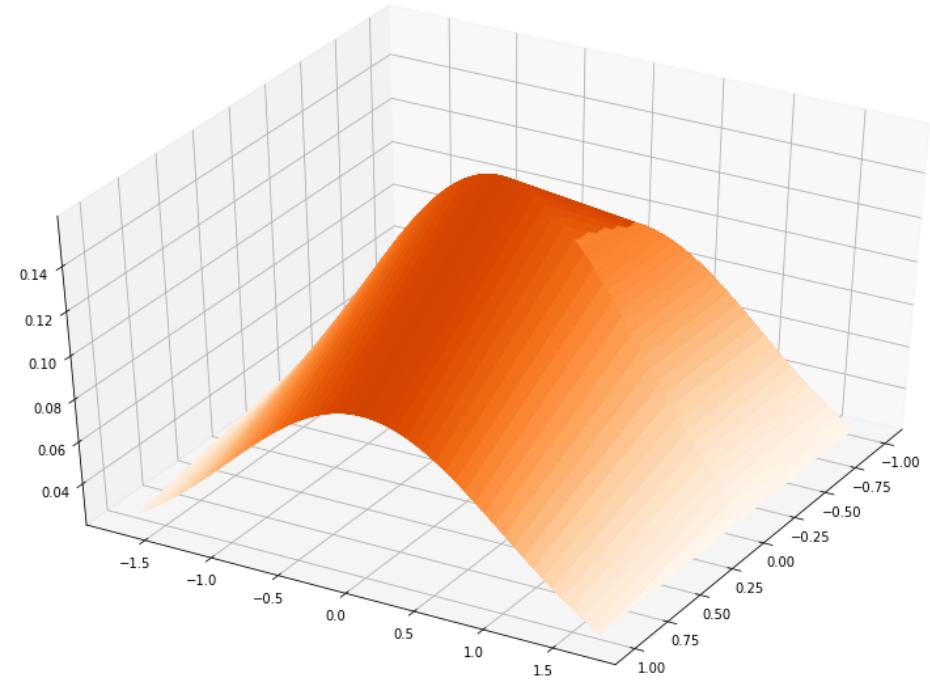
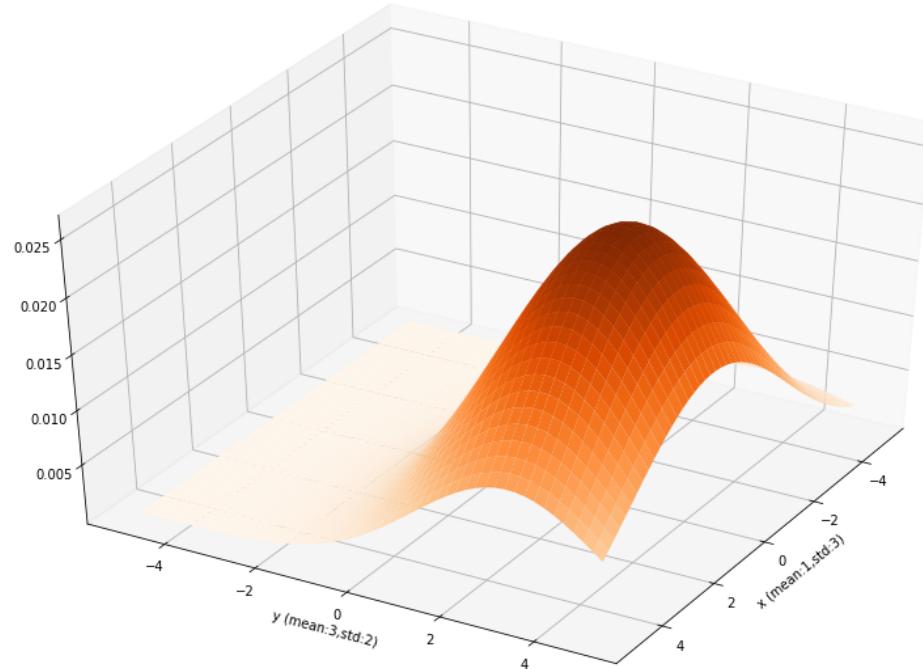


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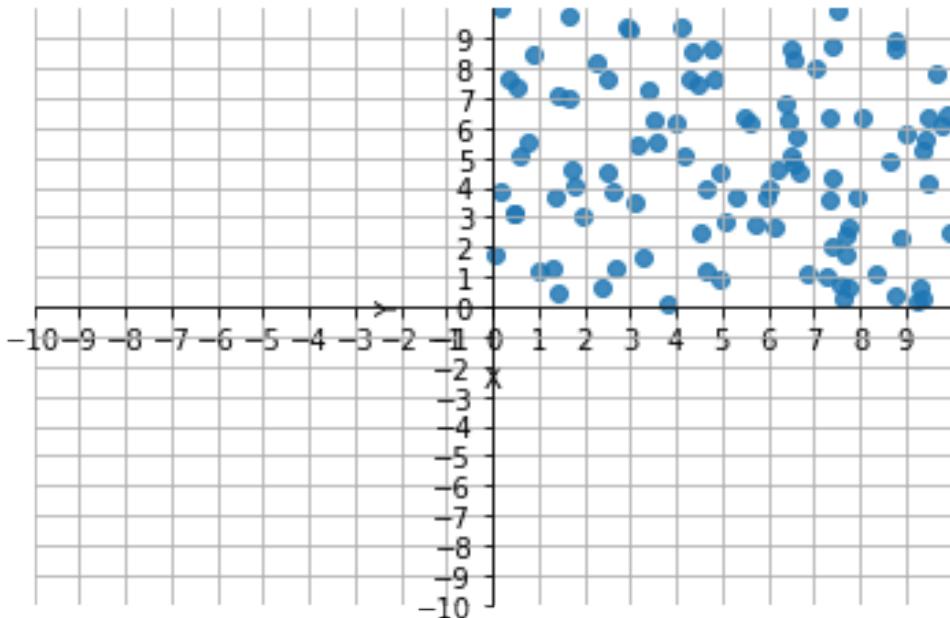
- Standardize features by removing the mean and scaling to unit variance



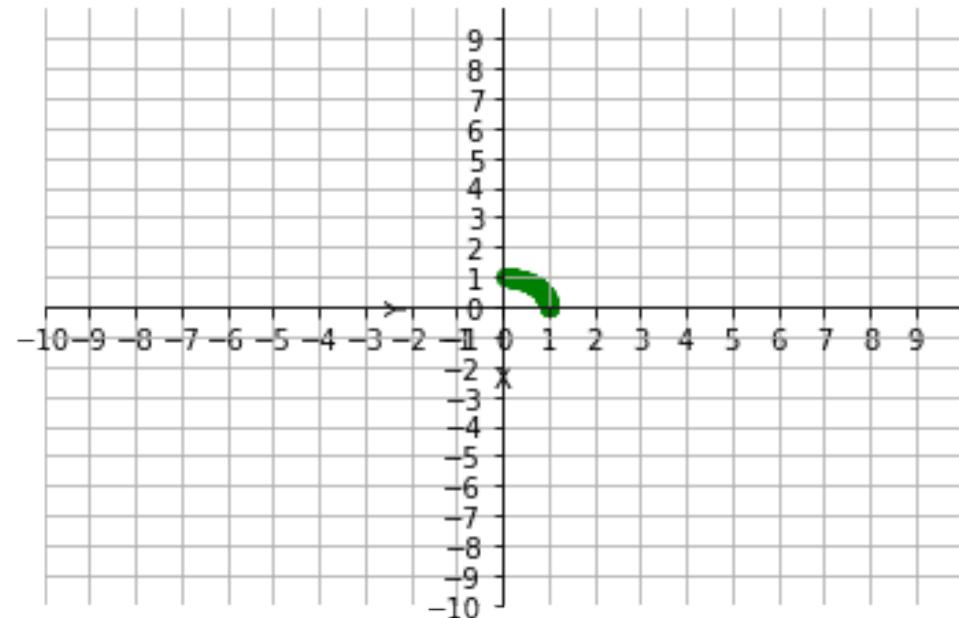
Types

□ Unit Vector Scaler (Normalizer)

- Normalize samples individually to unit norm.



mean: [5.24874418 4.65066746]
std: [3.03272127 3.02536061]
min: [0.01605648 0.07731266]
max: [9.93963622 9.76344994]

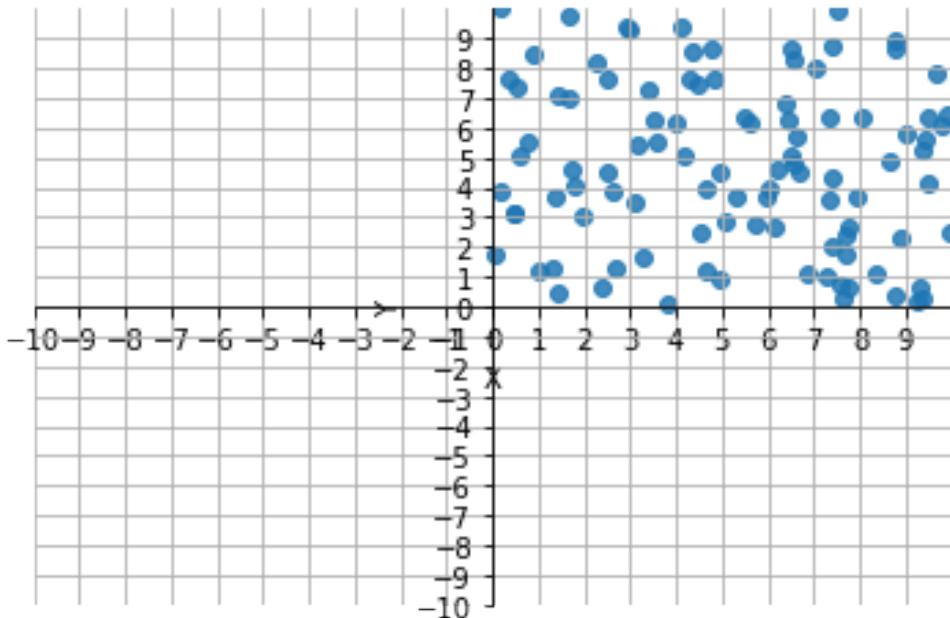


mean: [0.67938241 0.59354895]
std: [0.30042037 0.3096559]
min: [0.00180982 0.05084794]
max: [0.99870641 0.99999836]

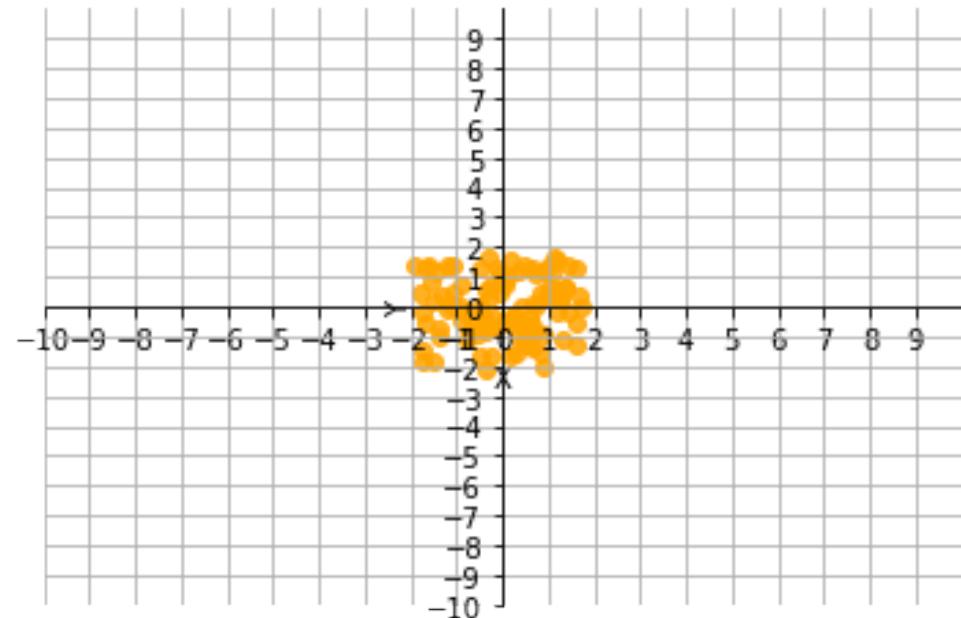
Types

□ Power Transformer Scaler (PowerTransformer)

- Apply a power transform featurewise to make data more Gaussian-like.



mean: [5.00643671 5.14637406]
 std: [2.7285058 2.73460667]
 min: [0.07036322 0.0115435]
 max: [9.99080893 9.87448843]

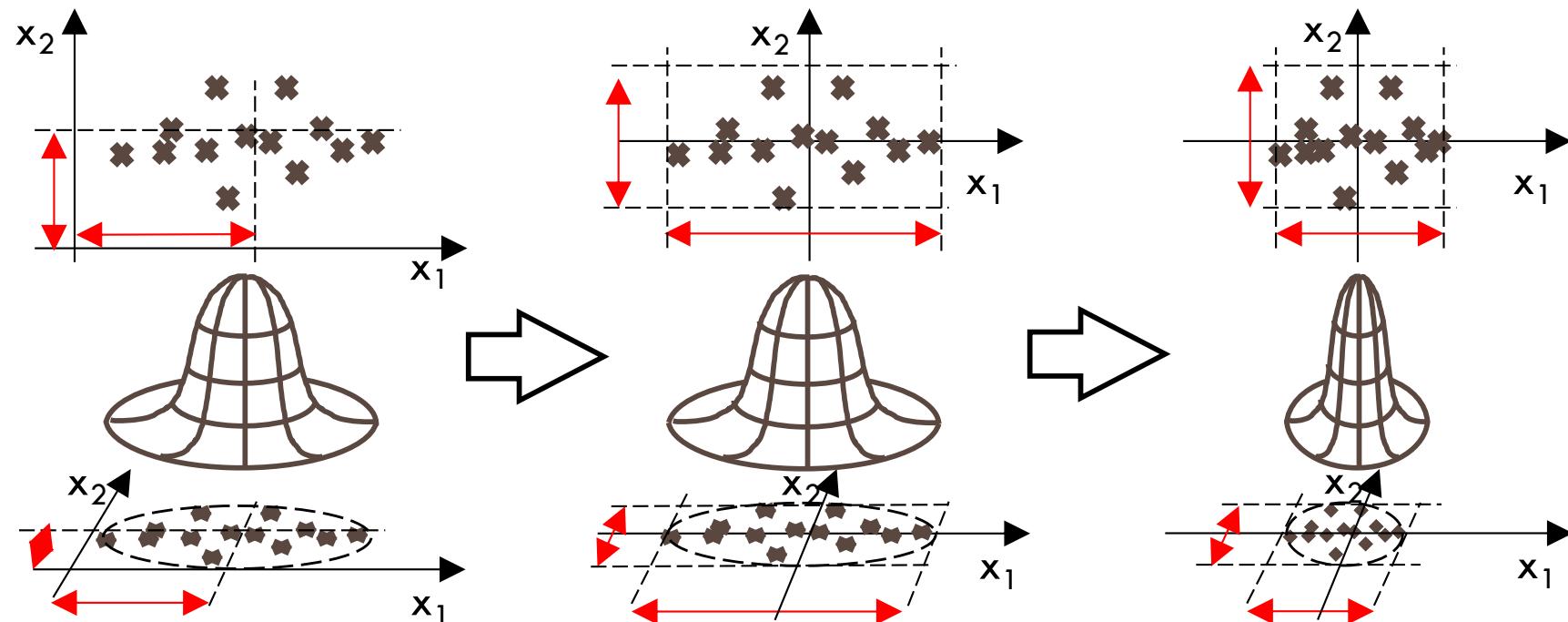


mean: [-2.44249065e-17 - 7.73617281e-16] std: [1. 1.]
 min: [-1.92383512 -2.07521871]
 max: [1.74245717 1.63357549]

● ● ● ● ● Input data normalization

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- Adjust of measured values (probability distribution):



Zero mean adjustment:

$$\mu_d = \frac{1}{n} \sum_{i=1}^n x_{id}$$

$$x_{id} := x_{id} - \mu_d$$

Variance normalization:

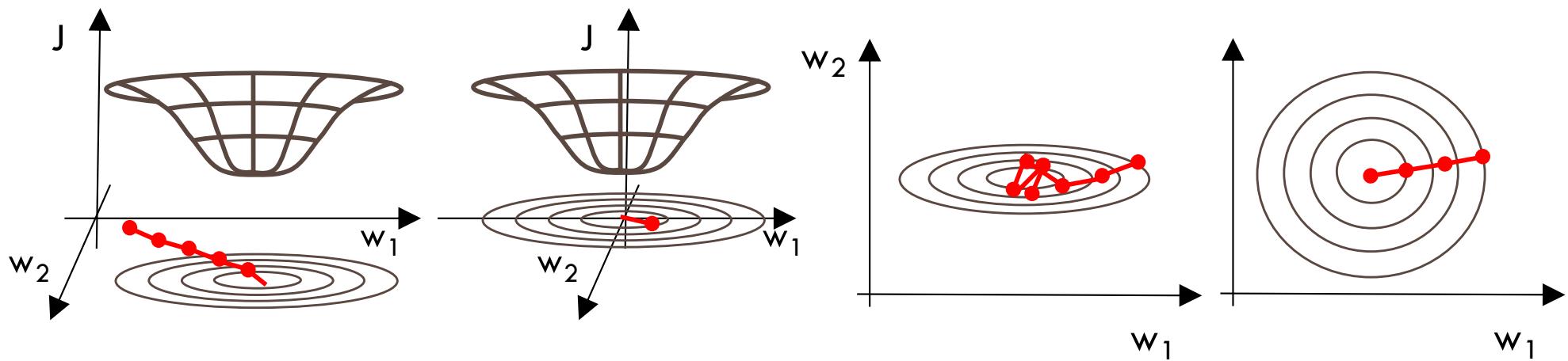
$$\sigma_d^2 = \frac{1}{n} \sum_{i=1}^n (x_{id} - \mu_d)^2$$

$$x_{id} := \frac{x_{id}}{\sigma_d^2}$$

•••• Why normalize input data?

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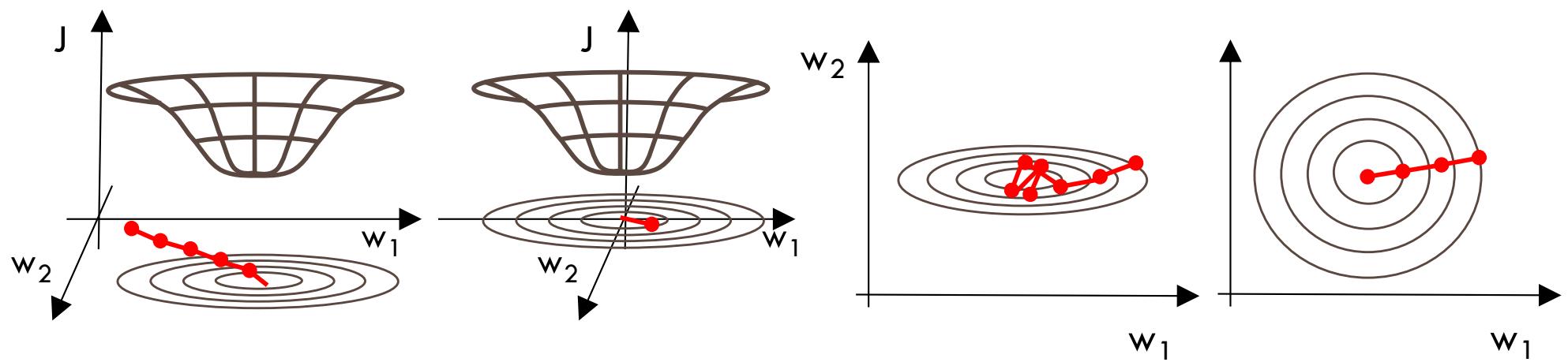
- Input data distribution has implications in the **shape of the cost function** used in some learning processes. Although most of the learning algorithms are able to learn over unnormalized data:
 - If data distribution has **zero mean**, it will probably require less learning steps to tune variables in models
 - In a **symmetrical cost function**, the step size (learning rate) tends to be more effective to find the center of the function



•••• Why normalize input data?

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- Input data distribution has implications in the **shape of the cost function** used in some learning processes. Although most of the learning algorithms are able to learn over unnormalized data:
 - If data distribution has **zero mean**, it will probably require less learning steps to tune variables in models
 - In a **symmetrical cost function**, the step size (learning rate) tends to be more effective to find the center of the function



Lecture 2

□ Activities

- Quis 2
 - Fundamental of ML
- Reading:
 - Python for ML

Lecture 2

- MARSLAND, S. Machine Learning: an algorithm perspective. CRC Press, 2nd edition, 2015.
- ALPAYDIN, E. Introduction to Machine Learning. MIT Press, 3rd edition, 2014.
- SILVA, I. N.; SPATTI, D. H.; FLAUZINO, R. A. Redes Neurais Artificiais para engenharia e ciências aplicadas. Curso prático. Artliber Editora, 2010.
- SUTTON, R. S.; BARTO, A. G. Reinforcement learning: an introduction. MIT Press, Cambridge, MA, 2nd edition in progress, 2017.

This material is part of the Machine Learning Course
By Esther Colombini and Alexandre Simões

