Title

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References

[1] Z. Fu, J. Pan, E. Spyrakos-Papastavridis, X. Chen, and M. Li, "A Dual Quaternion-Based Approach for Coordinate Calibration of Dual Robots in Collaborative Motion,", 2020. DOI: 10.1109/LRA.2020.2988407.

[2] A. Khan, G. Aragon-Camarasa, L. Sun, and J. P. Siebert, "On the calibration of active binocular and RGBD vision systems for dual-arm robots,", 2016. DOI: 10.1109/ROBIO.2016.7866616.

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[1] Z. Fu, J. Pan, E. Spyrakos-Papastavridis, X. Chen, and M. Li, "A Dual Quaternion-Based Approach for Coordinate Calibration of Dual Robots in Collaborative Motion,", 2020. DOI: 10.1109/LRA.2020.2988407.

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