HG+ - Precise hollow shaft solution

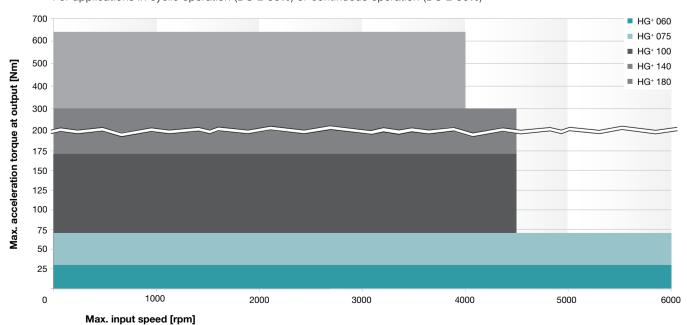


The successor to our versatile hypoid gearhead with hollow shaft on one/both sides.

With the HG⁺, low torsional backlash and high torsional rigidity assure maximum positioning accuracy of your drives and precision of your machines – even during highly dynamic operation.

Quick size selection

HG⁺ **MF** (example for i = 5) For applications in cyclic operation (DC \leq 60%) or continuous operation (DC \geq 60%)



light-angle gearheads

Versions and Applications

Features	HG⁺ MF version page 250
Power density	••
Positioning accuracy (e.g clamped drives)	••
Highly dynamic applications	••

Product features

Ratios c)		3 – 100						
Torsional backlash	Standard	≤ 4						
[arcmin] c)	Reduced	-						
Output type*								
Smooth output shaft, r	rear side	•						
Keywayed output shaf	ft, rear side	•						
Hollow shaft interface Connected via shrink dis		•						
Hollow shaft interface, Connected via shrink dis		•						
Closed cover, rear side	Э	•						
nput type								
Motor mounted version	n	•						
Туре								
ATEX a)		•						
Food-grade lubrication	ղ ^{a) b)}	•						
Corrosion resistant a) b)	1	•						
Accessories								
Coupling		•						
Shrink disc		•						
torqXis sensor flange		•						
Intermediate plate for co	poling connection	•						
a) Power reduction: techni	ical data available u	non request b) Please contact WITTENSTEIN alpha c) In relation to reference sizes						

a) Power reduction: technical data available upon request b) Please contact WITTENSTEIN alpha c) In relation to reference sizes

You can find order information for the relevant type of output on page 424.



HG+060 MF 1/2-stage

							1-stage)						2-st	tage				
Ratio ^{a)}			i		3	4	5	7	10	12	16	20	25	28	35	40	50	70	100
Max. acceleration torque			T _{2B}	Nm	30	30	30	25	20	30	30	30	30	30	30	30	30	25	20
(max. 1000 cycles per hour)			* 2B	in.lb	266	266	266	221	177	266	266	266	266	266	266	266	266	221	177
Nominal output torque			T _{2N}	Nm · ··	22	22	22	20	15	22	22	22	22	22	22	22	22	20	15
(with n _{1N})				in.lb Nm	195 40	195 50	195 50	177 45	133 40	195 50	195 50	195 50	195 50	195 50	195 50	195 50	195 50	177 45	133 40
Emergency stop torque (permitted 1000 times during the service life of	the gea	rhead)	T _{2Not}	in.lb	354	443	443	398	354	443	443	443	443	443	443	443	443	398	354
Nominal input speed (with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	2500	2700	3000	3000	3000	4400	4400	4400	4400	4400	4400	4400	4800	5500	5500
Max. continuous speed (with 20% T _{2N} and 20°C ambient temperature)		n _{1Ncym}	rpm	3000	3500	4000	3500	3500	5000	5000	5000	5000	5000	5000	5000	5000	5500	5500
Max. input speed			n _{1Max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Mean no load running torque		d)	T ₀₁₂	Nm	1.3	1.2	1.1	1.3	1.2	0.2	0.2	0.2	0.2	0.2	0.2	0.1	0.1	0.1	0.1
(with n,=3000 rpm and 20°C gearhead temper	erature)		012	in.lb	11.5	10.6	9.7	11.5	10.6	1.8	1.8	1.8	1.8	1.8	1.8	0.9	0.9	0.9	0.9
Max. torsional backlash		-	j_t	arcmin		П		Г				≤ 5		1		1			
Torsional rigidity			C ₁₂₁	Nm/ arcmin	2.2	2.3	2.4	2.2	1.9	2.3	2.3	2.3	2.3	2.3	2.3	2.3	2.4	2.2	1.9
				in.lb/ arcmin	19	20	21	19	17	20	20	2400	20	20	20	20	21	19	17
Max. axial force e)			F _{2AMax}	lb,		540 540													
May redial fares e)			_	N		2700													
Max. radial force e)			F _{2RMax}	lb _f		608 251													
Max. tilting moment			M _{2KMax}	Nm in.lb								251 2220							
Efficiency at full load			η	%			96					94							
Service life (For calculation, see the Chapter "Information"	1")		L	h								> 20000)						
Weight incl. standard adapter p	late		m	kg lb _m			2.9 6.4					3.2 7.1							
Operating noise (with n,=3000 rpm no load)			L _{PA}	dB(A)								≤ 64							
				°C								+90							
Max. permitted housing temper	ature			F								194							
Ambient temperature				°C								0 to +40							
,				F							3	32 to 10	4						
Lubrication											Lubr	icated fo	or life						
Paint					Blue RAL 5002														
Direction of rotation										Motor a	nd gearh	nead op	posite d	irections	3				
Protection class												IP 65							
Moment of inertia	В	11	J,	kgcm ²	_	_	_	_		0.09	0.09	0.07	0.07	0.06	0.06	0.06	0.06	0.06	0.06
(relates to the drive)	Ĺ	-	-1	10 ⁻³ in.lb.s ²						0.08	0.08	0.07	0.06	0.06	0.06	0.05	0.05	0.05	0.05
Clamping hub diameter [mm]	С	14	J_1	kgcm ² 10 ⁻³ in.lb.s ²	0.52	0.44	0.40	0.36	0.34	0.20	0.20	0.19	0.19	0.18	0.18	0.17	0.17	0.17	0.17
				kgcm ²	0.46	0.39	0.35	0.32	0.30	0.18	0.18	0.17	0.16	0.16	0.16	0.15	0.15	0.15	0.15
	Е	19	$J_{\scriptscriptstyle 1}$	10 ⁻³ in.lb.s ²	0.77	0.70	0.66	0.63	0.62	-	-	-	_	-	-	-	-	-	-

Please contact us for information on the best configuration for S1 conditions of use (continuous operation).

All technical data for front output side applies.

Technical data for rearward output versions, see page 428.

^{a)} Other ratios available on request

^{b)} Higher speeds are possible if the nominal torque is reduced

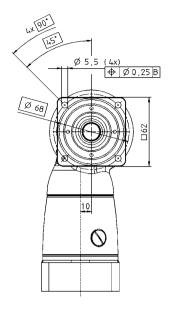
c) For higher ambient temperatures, please reduce input speed

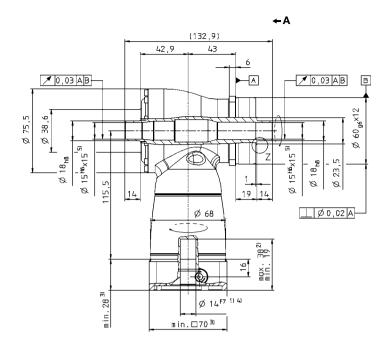
d Idling torques decrease during operation

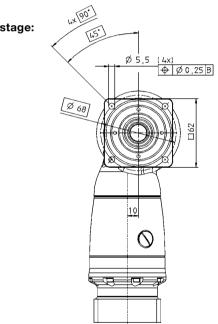
e) Refers to center of the output shaft or flange

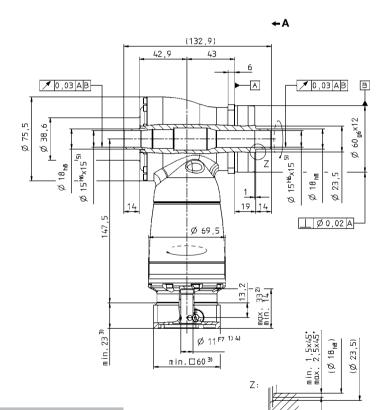




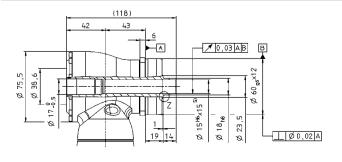








Alternatives: Single output shaft



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ±1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.
- 5) Tolerance h6 for mounted shaft.
- CAD data is available under www.wittenstein-alpha.com

HG+075 MF 1/2-stage

							1-stage	•						2-st	tage				
Ratio ^{a)}			i		3	4	5	7	10	12	16	20	25	28	35	40	50	70	100
Max. acceleration torque			T _{2B}	Nm	70	70	70	60	50	70	70	70	70	70	70	70	70	60	50
(max. 1000 cycles per hour)			· 2B	in.lb	620	620	620	531	443	620	620	620	620	620	620	620	620	531	443
Nominal output torque			T _{2N}	Nm 	50	50	50	45	40	50	50	50	50	50	50	50	50	45	40
(with n_m)				in.lb Nm	443 95	443 115	443 115	398 110	354 100	443 115	443 115	443 115	443 115	443 115	443 115	443 115	443 115	398 110	354 100
Emergency stop torque (permitted 1000 times during the service life of t	the gea	rhead)	T _{2Not}	in.lb	841	1018	1018	974	885	1018	1018	1018	1018	1018	1018	1018	1018	974	885
Nominal input speed (with T_{2N} and 20°C ambient temperature) b), c)			n _{1N}	rpm	2300	2500	2800	2800	2800	3500	3500	3500	3500	3500	3500	3500	3800	4500	4500
Max. continuous speed (with 20?% T _{2N} and 20°C ambient temperature	re)		n _{1Ncym}	rpm	3000	3500	4000	3500	3500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500
Max. input speed			n _{1Max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Mean no load running torque		al)	T ₀₁₂	Nm	2.2	1.9	1.7	2.2	2.0	0.3	0.3	0.2	0.2	0.2	0.2	0.1	0.1	0.1	0.1
(with n ₁ =3000 rpm and 20°C gearhead tempe	erature)		012	in.lb	19	17	15	19	18	2.7	2.7	1.8	1.8	1.8	1.8	0.9	0.9	0.9	0.9
Max. torsional backlash		-	j_t	arcmin	≤ 4														
Torsional rigidity			C _{t21}	Nm/ arcmin															6.5
				in.lb/ arcmin	47	52	60	58	57	52	52	52 3400	52	52	52	52	59	58	58
Max. axial force ^{e)}			F _{2AMax}	lb,	3400 765														
NA			_	N	4000														
Max. radial force el			F _{2RMax}	lb _f	900														
Max. tilting moment			M _{2KMax}	Nm	437 3867														
-			ZKIVIAX	in.lb							-	3867			-	-		-	-
Efficiency at full load			η	%			96					94							
Service life (For calculation, see the Chapter "Information	ı")		L	h								> 20000)						
Weight incl. standard adapter pl	late		m	kg lb _m			4.8 10.6					5.1 11.3							
Operating noise (with n,=3000 rpm no load)			L _{PA}	dB(A)								≤ 66							
NACO promotita di bassatina damana	_4			°C								+90							
Max. permitted housing tempera	ature			F								194							
Ambient temperature				°C								0 to +40							
				F								32 to 10	4						
Lubrication					Lubricated for life														
Paint				Blue RAL 5002															
Direction of rotation									ı	Motor a	nd gearh	nead op	posite d	irections	8				
Protection class												IP 65							
Moment of inertia	С	14	J,	kgcm ²	_	_		_	_	0.28	0.27	0.23	0.23	0.20	0.20	0.18	0.18	0.18	0.18
(relates to the drive)			J ₁	10 ⁻³ in.lb.s ²		_				0.25	0.24	0.21	0.20	0.18	0.18	0.16	0.16	0.16	0.16
Clamping hub diameter [mm]	Е	19	J_{1}	kgcm ²	1.46	1.19	1.06	0.95	0.90	0.73	0.71	0.68	0.67	0.63	0.62	0.63	0.63	0.63	0.63
	_			10°3 in.lb.s²	1.29 2.86	1.05 2.60	0.94 2.47	0.84 2.36	0.79 2.31	0.64	0.63	0.60	0.59	0.55	0.55	0.56	0.55	0.55	0.55
	1	28	J_{i}	kgcm ²	2.00	2.00	2.41	2.30	2.31			1		i		1		1	

Please contact us for information on the best configuration for S1 conditions of use (continuous operation).

All technical data for front output side applies.

Technical data for rearward output versions, see page 428.

^{a)} Other ratios available on request

b) Higher speeds are possible if the nominal torque is reduced

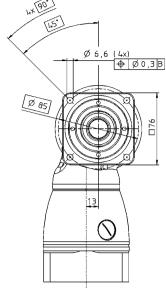
c) For higher ambient temperatures, please reduce input speed

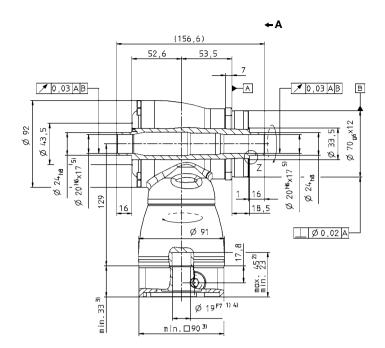
d Idling torques decrease during operation

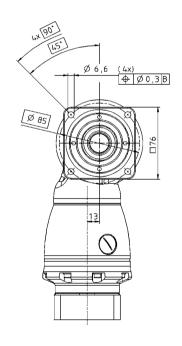
e) Refers to center of the output shaft or flange

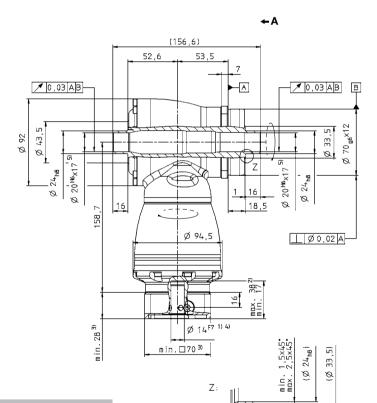




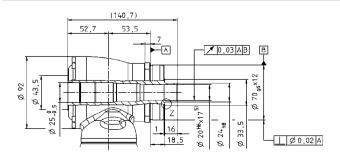








Alternatives: Single output shaft



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ±1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.
- 5) Tolerance h6 for mounted shaft.
- CAD data is available under www.wittenstein-alpha.com

HG+ 100 MF 1/2-stage

							1-stage	•						2-st	tage				
Ratio ^{a)}			i		3	4	5	7	10	12	16	20	25	28	35	40	50	70	100
Max. acceleration torque (max. 1000 cycles per hour)			T _{2B}	Nm in.lb	170 1505	170 1505	170 1505	145 1283	125 1106	170 1505	170 1505	170 1505	170 1505	170 1505	170 1505	170 1505	170 1505	145 1283	125 1106
Nominal output torque (with n_n)			T _{2N}	Nm in.lb	100 885	100 885	100 885	90 797	80 708	100 885	100 885	100 885	100 885	100 885	100 885	100 885	100 885	90 797	80 708
Emergency stop torque (permitted 1000 times during the service life of	the gea	rhead)	T _{2Not}	Nm in.lb	220 1947	260 2301	260 2301	255 2257	250 2213	260 2301	260	260 2301	260 2301	260 2301	260 2301	260 2301	260 2301	255 2257	250 2213
Nominal input speed (with T_{2N} and 20°C ambient temperature) b), c)		n _{1N}	rpm	2200	2400	2700	2500	2500	3100	3100	3100	3100	3100	3100	3100	3500	4200	4200
Max. continuous speed (with 20% T _{2W} and 20°C ambient temperature			n _{1Ncym}	rpm	3000	3400	3800	3400	3400	4000	4000	4000	4000	4000	4000	4000	4000	4200	4200
Max. input speed			n _{1Max}	rpm	4500	00 4500 4500 4500 4500 4500 4500 4500 4						4500	4500	4500	4500	4500			
Mean no load running torque (with n,=3000 rpm and 20°C gearhead temp	erature) ^{d)}	T ₀₁₂	Nm in.lb	4.2	3.3	2.5	3.9	3.1	0.7 6.2	0.7 6.2	0.6 5.3	0.4	0.4	0.3	0.2	0.2	0.2	0.2
Max. torsional backlash			j_t	arcmin	- 01	3/ 29 22 35 27 6.2 6.2 5.3 3.5 3.5 2.7 1.8 1.8 1.8 1.8 ≤ 4							1.0						
Torsional rigidity			C ₁₂₁	Nm/ arcmin	10.7 95	12.1 107	14.0 124	14.2 126	14.4	12.1 107	12.1	12.1 107	12.1 107	12.1 107	12.1	12.1	14.0 124	14.2 126	14.4
Max. axial force e)			F _{2AMax}	N lb,								5700					121		
Max. radial force ⁹⁾			F _{2RMax}	N Ib,								6300							
Max. tilting moment			M _{2KMax}	Nm in.lb								833							
Efficiency at full load			η	%			96					94							
Service life (For calculation, see the Chapter "Information	n")		L _n	h								> 20000)						
Weight incl. standard adapter p	late		m	kg lb _m			9.3					9.5							
Operating noise (with n,=3000 rpm no load)			L _{PA}	dB(A)								≤ 66							
Max. permitted housing temper	ature			°C							-	+90				-		-	
Ambient temperature				°C								194 0 to +40							
Lubrication		-		F								32 to 104							
Paint											Blu	e RAL 5	002						
Direction of rotation		-			Motor and gearhead opposite directions														
Protection class	-											IP 65							
Moment of inertia	Е	19	J,	kgcm ²	-	_	-	_	-	1.02	0.97	0.86	0.84	0.75	0.74	0.69	0.69	0.68	0.68
(relates to the drive) Clamping hub diameter [mm]	G	24	J,	kgcm ²		-	_	_	_	0.91 2.59	0.86 2.54	0.76 2.42	2.40	0.66 2.31	2.30	2.26	2.25	2.25	0.60 2.25
	Н	28	J,	tgcm ²	4.64	3.80	3.34	2.98	2.79	2.29	2.25	2.14	2.13	2.05	2.04	2.00	1.99	1.99	1.99
	K	38	J,	tgcm ²	4.10	3.36	2.95	2.64 10.2	10.0	_	_	_	_	_	_	_	_	_	_
			_ ′	10 ⁻³ in.lb.s ²	10.4	9.73	9.34	9.04	8.88										

^{a)} Other ratios available on request

 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

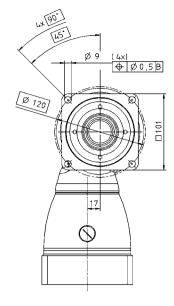
c) For higher ambient temperatures, please reduce input speed

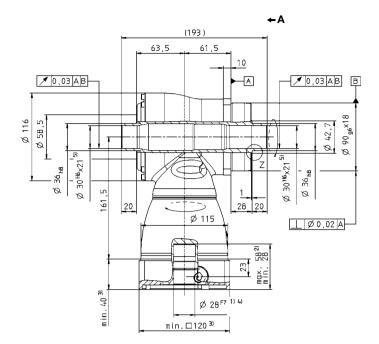
d Idling torques decrease during operation

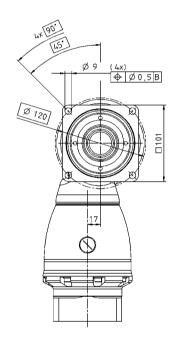
e) Refers to center of the output shaft or flange

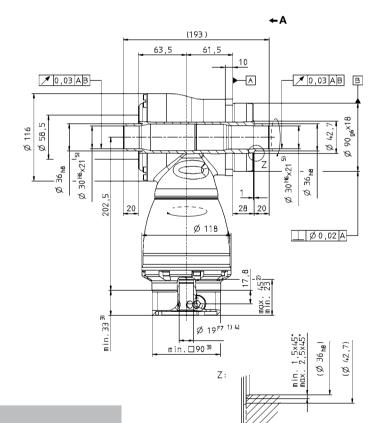




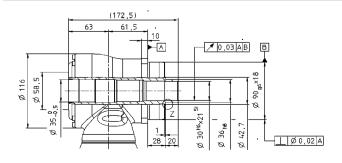








Alternatives: Single output shaft



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ±1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.
- 5) Tolerance h6 for mounted shaft.
- CAD data is available under www.wittenstein-alpha.com

HG+ 140 MF 1/2-stage

							1-stage)						2-st	tage				
Ratio ^{a)}			i		3	4	5	7	10	12	16	20	25	28	35	40	50	70	100
Max. acceleration torque (max. 1000 cycles per hour)			T _{2B}	Nm in.lb	300 2655	300 2655	300 2655	250 2213	210 1859	300 2655	300 2655	300 2655	300 2655	300 2655	300 2655	300 2655	300 2655	250 2213	210 1859
Nominal output torque			T _{2N}	Nm in.lb	190	190	190	175	160	190	190	190	190	190	190	190	190	175	160
Emergency stop torque (permitted 1000 times during the service life of t	h a a a a a	(bood	T _{2Not}	Nm	400	1682 500	1682 500	1549 450	1416 400	1682 500	1682 500	1682 500	1682 500	1682 500	1682 500	1682 500	1682 500	1549 450	1416 400
Nominal input speed (with T _{2W} and 20°C ambient temperature) ^{b), c)}	ne gear	neau)	n _{1N}	in.lb rpm	1900	2000	2200	3983 2000	3540 2000	2900	2900	2900	2900	2900	2900	2900	3200	3983 3200	3540
Max. continuous speed (with 20% T _{2N} and 20°C ambient temperature)			n _{1Ncym}	rpm	2500	2800	3100	2800	2800	4000	4000	4000	4000	4000	4000	4000	4200	4200	4200
Max. input speed			n _{1Max}	rpm	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500	4500
Mean no load running torque (with n,=3000 rpm and 20°C gearhead tempe	rature)	d)	T ₀₁₂	Nm in.lb	7.7 68	5.7 50	5.0 44	8.3 73	6.1 54	1.5 13.3	1.0	0.8 7.1	0.6 5.3	0.6 5.3	0.4 3.5	0.4 3.5	0.3	0.3 2.7	0.3
Max. torsional backlash			j_t	arcmin				1				≤ 4							
Torsional rigidity			C ₁₂₁	Nm/ arcmin	32	36	41	39	38	36	36	36	36	36	36	36	41	39	38
Max. axial force ^{e)}			F _{2AMax}	in.lb/ arcmin	287	321	360	346	337	319	319	9900 9900	319	319	319	319	363	345	336
Max. radial force ^{e)}			F _{2RMax}	lb _f								9500							
Max. tilting moment			M _{2KMax}	lb _f Nm								2138 1692							
				in.lb								14974							
Efficiency at full load Service life			η	%			96					94							
(For calculation, see the Chapter "Information	")		L _h	h								> 20000)						
Weight incl. standardadapter pla	ite		m	kg lb _m			22.6 50					24 53							
Operating noise (with n_1 =3000 rpm no load)			L_{PA}	dB(A)								≤ 68							
Max. permitted housing tempera	ature			°C F								+90 194							
Ambient temperature				°C F								0 to +40							
Lubrication												icated fo							
Paint											Blu	e RAL 5	002	-					
Direction of rotation					Motor and gearhead opposite directions														
Protection class												IP 65							
Moment of inertia (relates to the drive)	G	24	J_1	kgcm ²	-	_	-	_	_	4.20	3.84	3.27	3.16 2.80	2.78	2.73	2.48	2.45	2.43	2.42
(relates to the crive) Clamping hub diameter [mm]	K	38	J,	kgcm ²	25.0	19.1	16.3	14.1	12.8	3.71	3.40	10.2	10.1	9.69	9.64	9.39	9.37	9.34	9.33
			•	10 ⁻³ in.lb.s ²	22.1	16.9	14.4	12.4	11.3	9.83	9.51	9.01	8.92	8.58	8.53	8.31	8.29	8.27	8.26

Please contact us for information on the best configuration for S1 conditions of use (continuous operation).

All technical data for front output side applies.

Technical data for rearward output versions, see page 428.

a) Other ratios available on request

b) Higher speeds are possible if the nominal torque is reduced

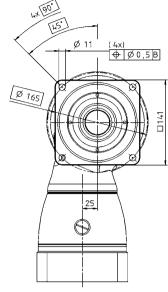
 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

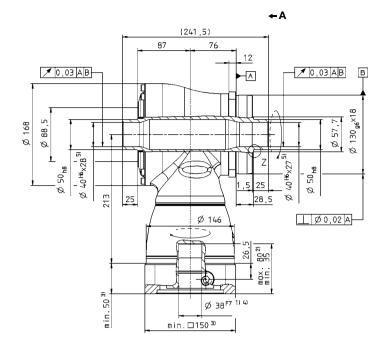
d) Idling torques decrease during operation

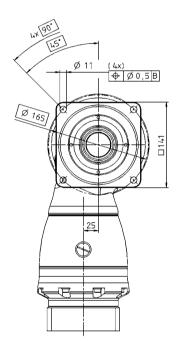
e) Refers to center of the output shaft or flange

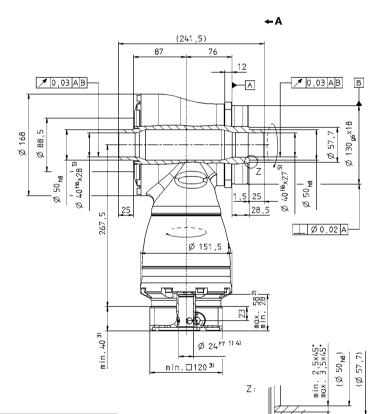




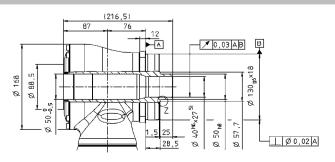








Alternatives: Single output shaft



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ±1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.
- 5) Tolerance h6 for mounted shaft.
- CAD data is available under www.wittenstein-alpha.com

HG+ 180 MF 1/2-stage

							1-stage	•						2-st	tage				
Ratio ^{a)}			i		3	4	5	7	10	12	16	20	25	28	35	40	50	70	100
Max. acceleration torque (max. 1000 cycles per hour)			T _{2B}	Nm in.lb	640 5664	640 5664	640 5664	550 4868	470 4160	640 5664	640 5664	640 5664	640 5664	640 5664	640 5664	640 5664	640 5664	550 4868	470 4160
Nominal output torque			T _{2N}	Nm in.lb	400	400	400	380	360 3186	400	400	400	400	400	400	400	400	380	360 3186
Emergency stop torque (permitted 1000 times during the service life of t	he gea	head)	T _{2Not}	Nm in.lb	900	1050	1050	970 8585	900	1050 9293	1050	1050	1050	1050	1050	1050	1050	970 8585	900
Nominal input speed (with T _{2W} and 20°C ambient temperature) ^{b), c)}	no goa	ricad)	n _{1N}	rpm	1600	1800	2000	1800	1800	2700	2700	2700	2700	2700	2700	2700	2900	3200	3400
Max. continuous speed (with 20% T _{2N} and 20°C ambient temperature))		n _{1Ncym}	rpm	2000	2400	2800	2500	2500	3500	3500	3500	3500	3500	3500	3500	3500	3800	3800
Max. input speed			n _{1Max}	rpm	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000	4000
Mean no load running torque (with n,=3000 rpm and 20°C gearhead tempe	erature)	d)	T ₀₁₂	Nm in.lb	16.0 142	13.0 115	11.0 97	16.5 146	14.0 124	3.3 29.2	2.5	2.0 17.7	1.8	1.4 12.4	1.3	1.0	1.0	1.0 8.9	1.0
Max. torsional backlash			j_t	arcmin				-				≤ 4							
Torsional rigidity			C ₁₂₁	Nm/ arcmin	71 633	80 711	91 803	89 791	88 780	80 708	80 708	80 708	80 708	80 708	80 708	80 708	91 805	89 788	88 779
Max. axial force ^{e)}			F _{2AMax}	N lb,	000	711	003	751	700	700	700	14200	700	700	700	700	003	700	113
Max. radial force e)			F _{2RMax}	N								14700							
Max. tilting moment			M _{2KMax}	lb _f Nm								3308 3213							
Efficiency at full load			η	in.lb			96					28435 94							
Service life (For calculation, see the Chapter "Information	")		L _h	h		,						> 20000)	,					
Weight incl. standardadapter pla			m	kg lb _m			45.4 100					47 104							
Operating noise (with n,=3000 rpm no load)			L _{PA}	dB(A)			100					≤ 68							
Max. permitted housing tempera	ature			°C								+90			-	-			
Ambient temperature				°C								194 0 to +40							
Lubrication				F								32 to 10- icated fo							
Paint											Blu	e RAL 5	002						
Direction of rotation										Motor a	nd gearh			irections	 S				
Protection class												IP 65							
Moment of inertia	K	38	J_1	kgcm ²		_	_	_		15.3	13.9	12.3	12.0	10.9	10.7	10.1	10.0	9.95	9.91
(relates to the drive) Clamping hub diameter [mm]		48		10 ⁻³ in.lb.s ² kgcm ²	73.3	51.6	42.1	34.0	29.7	13.5 30.0	12.3 28.7	10.9 27.0	10.6 26.7	9.65 25.6	9.48 25.4	8.96 24.8	8.88 24.7	8.80 24.7	8.77 24.6
	M	40	$J_{_1}$	10 ⁻³ in.lb.s ²	64.9	45.6	37.3	30.1	26.3	26.6	25.4	23.9	23.6	22.7	22.5	22.0	21.9	21.8	21.8

Please contact us for information on the best configuration for S1 conditions of use (continuous operation).

All technical data for front output side applies.

Technical data for rearward output versions, see page 428.

a) Other ratios available on request

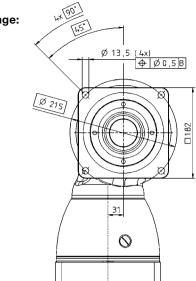
b) Higher speeds are possible if the nominal torque is reduced

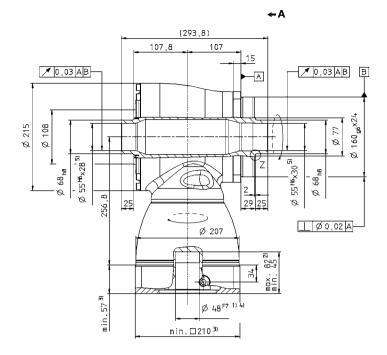
c) For higher ambient temperatures, please reduce input speed

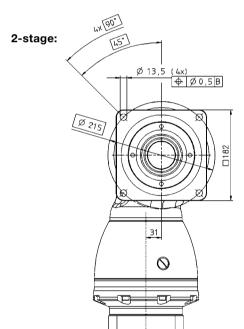
d Idling torques decrease during operation

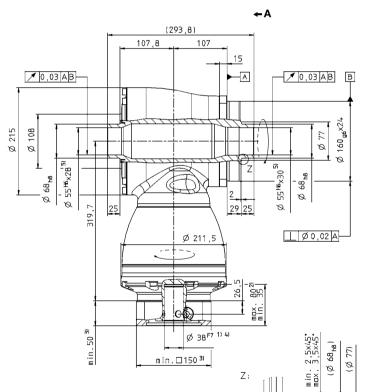
e) Refers to center of the output shaft or flange



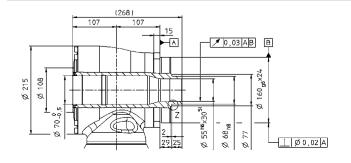








Alternatives: Single output shaft



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ±1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.
- 5) Tolerance h6 for mounted shaft.
- CAD data is available under www.wittenstein-alpha.com

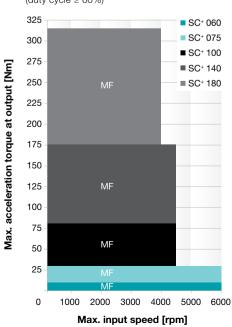
SC+/SPC+/TPC+ - High performance with low ratios



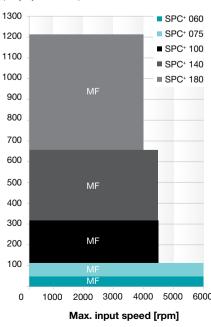
Low backlash right-angle gearheads with output shaft or output flange. This gearhead series is used in dynamic applications with low transmission ratios and demanding requirements with regard to precision, torque, and efficiency.

Quick size selection

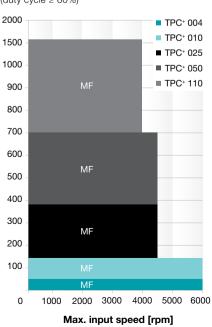
SC+MF (example for i = 1) For applications in cyclic operation (duty cycle \leq 60 %) or continuous operation (duty cycle \geq 60%)



SPC+MF (example for i=5) For applications in cyclic operation (duty cycle $\leq 60\%$) or continuous operation (duty cycle $\geq 60\%$)



TPC+MF (example for i=5) For applications in cyclic operation (duty cycle \leq 60%) or continuous operation (duty cycle \geq 60%)



Right-angle gearheads

Versions and their uses

Features	SC+ MF version Catalog page 262	SPC ⁺ MF version Catalog page 272	TPC⁺ MF version Catalog page 282
Power density	•••	•••	•••
Positioning accuracy (e.g clamped drives)	••	•••	•••
Highly dynamic applications	••	••	••
High output speeds	•••	••	••

Product features

Ratios c)		1 - 2	4 - 20	4 - 20
Backlash	Standard	≤ 4	≤ 4	≤ 4
[arcmin] ©	Reduced	-	≤ 2	≤ 2
Output type				
Smooth output shaft		•	•	
Keywayed output shaf	t	•	•	
Output shaft with invol	ute toothing		•	
Mounted shaft			•	
Output flange				•
System output with pir	nion			•
Input type				
Motor attachment vers	ion	•	•	•
Model				
Food-grade lubrication) a) b)	•	•	•
Accessories				
Coupling		•	•	•
Rack		•	•	•
Pinion		•	•	•
Shrink disk			•	

a) Power reduction: Technical data available upon request b) Please contact WITTENSTEIN alpha c) Based on reference sizes



SC+ 060 MF 1-stage

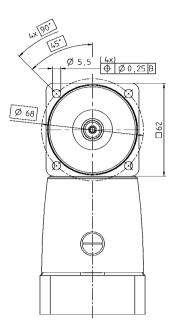
					1-st	tage						
Ratio ^{a)}			i		1	2						
Max. acceleration torque			_	Nm	10	10						
(max. 1000 cycles per hour)			$T_{_{2B}}$	in.lb	89	89						
Nominal output torque			_	Nm	7	7						
(with n _{1s})			T_{2N}	in.lb	62	62						
Emergency stop tourque			T _{2Not}	Nm	25	25						
(permitted 1000 times during the service life of the gearher	ad)		* 2Not	in.lb	221	221						
Nominal input speed (with T_{2N} and 20°C ambient temperature) $^{\rm bl,c)}$			n _{1N}	rpm	5000	5500						
Max. input speed			n _{1max}	rpm	6000	6000						
Average no-load running torque			T	Nm	0.5	0.3						
(with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	4.4	2.7						
Max. torsional backlash			\dot{J}_t	arcmin	≤	5						
Torsional rigidity			C ₁₂₁	Nm/ arcmin	0.4	0.6						
Torsional rigidity			U _{t21}	in.lb/ arcmin	3.5	5.3						
Max. axial force			F _{2AMax}	N	50	00						
			* 2AMax	lb _f	113							
Max. radial force	radial force		F _{2RMax}	N	950 214							
			ID _f		71							
Max. tilting moment	tilting moment		M _{2KMax} Nm in.lb		628							
Efficiency at full load			η	% w	97							
Service life (For calculation, see the Chapter "Information")			L _n	h	> 20	0000						
(For Calculation, See the Chapter Information)				ka		.9						
Weight incl. standard adapter plate			m	kg lb _m		.2						
Operating noise				IID _m	-							
(with n ₁ = 3000 rpm without load)			L_{PA}	dB(A)	≤	66						
				°C	+9	90						
Max. permitted housing temperature				F	19	94						
A male is not to make a mark out				°C	0 to	+40						
Ambient temperature				F	32 to	104						
Lubrication					Lubricate	ed for life						
Paint					no p	paint						
ounting position					aı	ny						
irection of rotation					Motor and gearhe	ead same direction						
Protection class					IP	65						
				kgcm ²	0.66	0.42						
	С	14	$J_{_{1}}$	10 ⁻³ in.lb.s ²	0.58	0.42						
(relates to the drive)	+			kgcm ²	0.99	0.75						
Clamping hub diameter [mm]	E	19	J_{1}	10 ⁻³ in.lb.s ²	0.88	0.66						

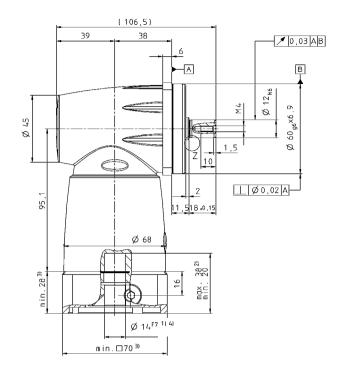
a) Other ratios available on request

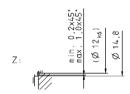
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

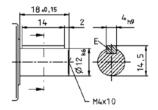






Alternatives: Output shaft variants

Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html

Motor mounting according to operating manual

SC+ 075 MF 1-stage

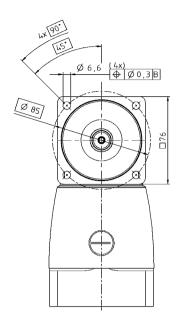
					1-st	tage					
Ratio ^{a)}			i		1	2					
Max. acceleration torque			_	Nm	30	30					
(max. 1000 cycles per hour)			T _{2B}	in.lb	266	266					
Nominal output torque			T _{2N}	Nm	20	20					
(with n _{1N})			* 2N	in.lb	177	177					
Emergency stop tourque			T _{2Not}	Nm	48	62					
(permitted 1000 times during the service life of the gearher	ead)		2/101	in.lb	425	549					
Nominal input speed (with T _{2N} and 20°C ambient temperature) b), c)			n _{1N}	rpm	2600	4000					
Max. input speed			n _{1max}	rpm	6000	6000					
Average no-load running torque			T ₀₁₂	Nm	0.9	0.3					
(with n ₁ =3000 rpm and 20°C gearhead temperature)			012	in.lb	8.0	2.7					
Max. torsional backlash			j_t	arcmin	≤	4					
Torsional rigidity			C ₁₂₁	Nm/ arcmin	1.0	1.5					
Torona rigidity			t ₂₁	in.lb/ arcmin	8.9	13.3					
Max. axial force			F _{2AMax}	N		00					
	. radial force		ZAIVIAX	lb _f		58					
Max. radial force	radial force		F _{2RMax}	N 	1300						
			Nm		293 131						
Max. tilting moment	. tilting moment		M _{2KMax} Nm in.lb		1159						
Efficiency at full load	-		η %			17					
Service life (For calculation, see the Chapter "Information")	ice life		L _h	h	> 20	0000					
(or calculation, see the enapter mornater.)				kg	3	.6					
Weight incl. standard adapter plate			m	lb _m		.0					
Operating noise (with n ₁ = 3000 rpm without load)			L _{PA}	dB(A)	≤	68					
				°C	+9	90					
Max. permitted housing temperature				F		94					
A mala in and the management				°C	0 to	+40					
Ambient temperature				F	32 to	104					
Lubrication					Lubricate	ed for life					
Paint					uo t	paint					
Mounting position				al	ny						
Direction of rotation					Motor and gearhe	ead same direction					
Protection class				IP	65						
				kgcm ²	1.99	1.19					
Moment of inertia (relates to the drive)	Е	19	$J_{_1}$	10 ⁻³ in.lb.s ²	1.76	1.05					
		00	,	kgcm ²	3.43	2.63					
Clamping hub diameter [mm]	Н	28	$J_{_{1}}$	10 ⁻³ in.lb.s ²	3.04	2.33					

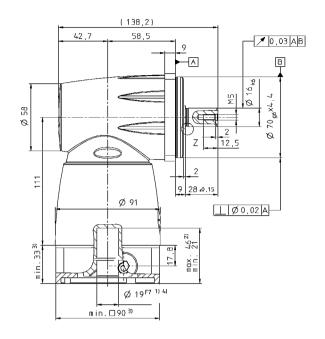
a) Other ratios available on request

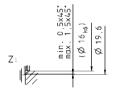
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

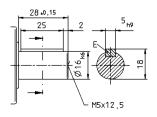






Alternatives: Output shaft variants

Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html

Motor mounting according to operating manual

SC+ 100 MF 1-stage

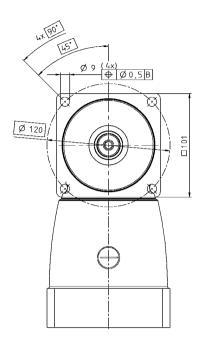
				1-st	tage						
Ratio ^{a)}		i		1	2						
Max. acceleration torque		1_	Nm	81	81						
(max. 1000 cycles per hour)		T _{2B}	in.lb	717	717						
Nominal output torque		7	Nm	50	50						
(with n _{1N})		T _{2N}	in.lb	443	443						
Emergency stop tourque		T _{2Not}	Nm	135	200						
(permitted 1000 times during the service life of the gearhead	d)	2Not	in.lb	1195	1770						
Nominal input speed (with T_{2N} and 20°C ambient temperature) ^{b), c)}		n _{1N}	rpm	2500	2800						
Max. input speed		n _{1max}	rpm	4500	4500						
Average no-load running torque		7	Nm	2.5	1.5						
(with n ₁ =3000 rpm and 20°C gearhead temperature)		T ₀₁₂	in.lb	22.1	13.3						
Max. torsional backlash		j_t	arcmin		4						
Torsional rigidity		C _{t21}	Nm/ arcmin	2.9	4.6						
Torsional rigidity		U _{t21}	in.lb/ arcmin	25.7	40.7						
Max. axial force		F _{2AMax}	N	1900							
Wax. axiai 10100		2AMax	lb _f	4:	28						
Max. radial force		F _{2RMax}	N	3800							
		ZHIVIAX	lb _f	855							
Max. tilting moment		M _{2KMax}	Nm	439							
		Zitivida	in.lb	3885							
Efficiency at full load		η	%	g	77						
Service life (For calculation, see the Chapter "Information")		L _h	h	> 20	0000						
Weight incl. standard adapter plate		m	kg	7	.0						
weight incl. standard adapter plate			lb _m	15	5.5						
Operating noise		LPA	dB(A)	<	68						
(with n ₁ = 3000 rpm without load)		-PA									
Max. permitted housing temperature			°C		90						
			F		94						
Ambient temperature			°C		+40						
			F	32 to	o 104						
Lubrication				Lubricate	ed for life						
Paint				no p	paint						
ounting position				a	ny						
rection of rotation				Motor and gearhe	ead same direction						
Protection class				IP	65						
			kgcm ²	7.1	4.8						
Moment of inertia (relates to the drive)	H 28	J_1	10 ⁻³ in.lb.s ²	6.28	4.25						
			kgcm ²	14.2	11.9						
Clamping hub diameter [mm]	K 3	$\mathbf{B} \mid \mathbf{J}_{\scriptscriptstyle 1}$	10 ⁻³ in.lb.s ²	12.57	10.53						

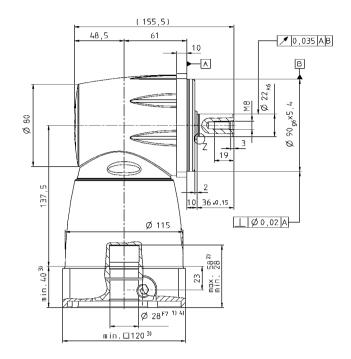
a) Other ratios available on request

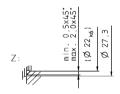
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

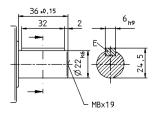






Alternatives: Output shaft variants

Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html

SC+ 140 MF 1-stage

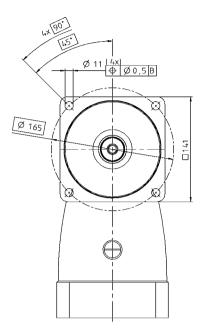
			1-st	age
Ratio ^{a)}	i		1	2
Max. acceleration torque	1_	Nm	175	175
(max. 1000 cycles per hour)	T _{2B}	in.lb	1549	1549
Nominal output torque		Nm	110	110
(with n _{IN})	T _{2N}	in.lb	974	974
Emergency stop tourque	T _{2Not}	Nm	240	310
(permitted 1000 times during the service life of the gearhead)	2Not	in.lb	2124	2744
Nominal input speed (with T_{2N} and 20° C ambient temperature) ^{b), c)}	n _{1N}	rpm	1600	2100
Max. input speed	n _{1max}	rpm	4500	4500
Average no-load running torque		Nm	4.0	1.7
(with n ₁ =3000 rpm and 20°C gearhead temperature)	T ₀₁₂	in.lb	35.4	15.0
Max. torsional backlash	j_t	arcmin	≤	4
Torsional rigidity	C ₁₂₁	Nm/ arcmin	6.4	9.1
Torsional rigidity	U ₁₂₁	in.lb/ arcmin	56.6	80.5
Max. axial force	F _{2AMax}	N	30	00
IVIAA. AXIAI IOICE	2AMax	lb _f	6	75
Max. radial force	F _{2RMax}	N		00
	2RMax	lb _f		50
Max. tilting moment	M _{2KMax}	Nm		57
	2KMax	in.lb	84	69
Efficiency at full load	η	%	9	7
Service life (For calculation, see the Chapter "Information")	L	h	> 20	0000
Weight incl. standard adapter plate	m	kg	14	1.7
Weight incl. Standard adapter plate	"	lb _m	32	2.5
Operating noise	L _{PA}	dB(A)	_	70
(with n ₁ = 3000 rpm without load)	₽A			
Max. permitted housing temperature		°C		90
,		F		94
Ambient temperature		°C		+40
•		F	32 to	0 104
Lubrication			Lubricate	ed for life
Paint			no p	paint
Mounting position			aı	ny
Direction of rotation			Motor and gearhe	ad same direction
Protection class			IP	65
Moment of inertia (relates to the drive)		kgcm²	41.3	21.3
(relates to the drive) K 3 Clamping hub diameter [mm]	8 J ₁	10 ⁻³ in.lb.s ²	36.55	18.85

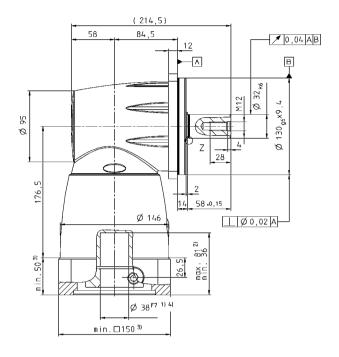
a) Other ratios available on request

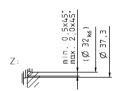
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

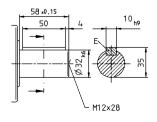






Alternatives: Output shaft variants

Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html

Motor mounting according to operating manual

SC+ 180 MF 1-stage

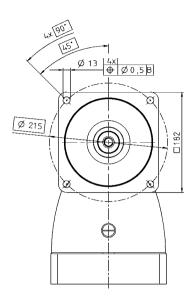
			1-st	age
Ratio ^{a)}	i		1	2
Max. acceleration torque		Nm	315	315
(max. 1000 cycles per hour)	T _{2B}	in.lb	2788	2788
Nominal output torque	7	Nm	200	200
(with n _{1N})	T _{2N}	in.lb	1770	1770
Emergency stop tourque	T _{2Not}	Nm	390	685
(permitted 1000 times during the service life of the gearhead)	2Not	in.lb	3452	6062
Nominal input speed (with $T_{_{2N}}$ and 20°C ambient temperature) $^{\mathrm{bl},\;\mathrm{c})}$	n _{1N}	rpm	1200	1500
Max. input speed	n _{1max}	rpm	4000	4000
Average no-load running torque	7	Nm	9.5	5.5
(with n ₁ =3000 rpm and 20°C gearhead temperature)	T ₀₁₂	in.lb	84.1	48.7
Max. torsional backlash	j_t	arcmin	≤	3
Torsional rigidity	C ₁₂₁	Nm/ arcmin	13	22
Torsional rigidity	U ₁₂₁	in.lb/ arcmin	115.1	194.7
Max. axial force	F _{2AMax}	N		00
	2AMax	lb _f		113
Max. radial force	F _{2RMax}	N		00
	Zi iiiida	lb _f		25
Max. tilting moment	M _{2KMax}	Nm		10
		in.lb	10:	904
Efficiency at full load	η	%	9	7
Service life (For calculation, see the Chapter "Information")	L	h	> 20	0000
Weight incl. standard adapter plate	m	kg	31	.4
Troight mon standard adaptor plate		lb _m	69	9.4
Operating noise	L _{PA}	dB(A)	≤	70
(with $n_1 = 3000 \text{ rpm}$ without load)	PA			
Max. permitted housing temperature		°C		90
		°C		94
Ambient temperature	-	F		+40
		Г	32 to	, 10 4
Lubrication			Lubricate	ed for life
Paint			no p	paint
Mounting position			aı	ny
Direction of rotation			Motor and gearhe	ad same direction
Protection class			IP	65
Moment of inertia (relates to the drive)		kgcm ²	99.5	46.7
(relates to the drive) M Clamping hub diameter [mm]	18 J,	10 ⁻³ in.lb.s ²	88.06	41.33

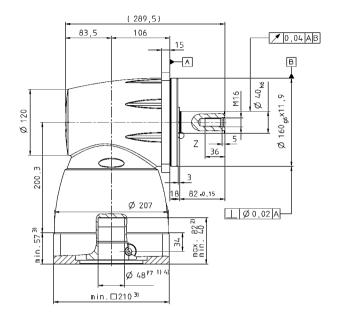
a) Other ratios available on request

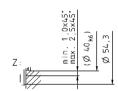
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

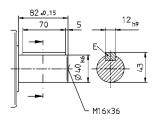






Alternatives: Output shaft variants

Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html

Motor mounting according to operating manual

SPC+ 060 MF 2-stage

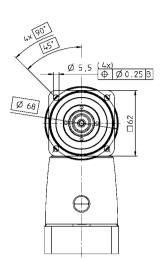
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			<i>T</i>	Nm	40	42	42	40	42	42	32
(max. 1000 cycles per hour)			T _{2B}	in.lb	354	372	372	354	372	372	283
Nominal output torque			T _{2N}	Nm	26	26	26	26	26	26	17
(with n _{1N})			* 2N	in.lb	230	230	230	230	230	230	150
Emergency stop tourque (permitted 1000 times during the service life of the gearhous)	ead)		T _{2Not}	Nm in.lb	100 885	100 885	100 885	100 885	100 885	100 885	80 708
Nominal input speed (with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	3000	3000	3200	3400	3400	3600	3600
Max. input speed			n _{1max}	rpm	6000	6000	6000	6000	6000	6000	6000
Average no-load running torque			T	Nm	1.2	1.1	0.9	0.6	0.6	0.5	0.4
(with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	11	10	8	5	5	4	4
Max. torsional backlash			\dot{J}_t	arcmin			Stand	ard ≤ 5 / Reduc	ed ≤ 3		
Toroional vigidity			_	Nm/ arcmin	2.4	2.7	3.1	2.7	3.0	3.2	3.3
Torsional rigidity			C ₁₂₁	in.lb/ arcmin	21	24	27	24	27	28	29
Max. axial force			F _{2AMax}	N				2400	,		,
IVIAX. AXIAI IOIOC			2AMax	lb _f				540			
Max. radial force			F _{2RMax}	N				2800			
			2RMax	lb _f			-	630			
Max. tilting moment			M _{2KMax}	Nm in.lb				152 1345.2			
Efficiency at full load			η	%				95			
Service life (For calculation, see the Chapter "Information")			L _h	h				> 20000			
, , ,				kg				3.1			
Weight incl. standard adapter plate			m	lb _m				6.851			
Operating noise (with n₁ = 3000 rpm without load)			L _{PA}	dB(A)				≤ 68			
Max permitted bousing temperature				°C				+90			
Max. permitted housing temperature				F				194			
Ambient temperature				°C				0 to +40			
				F				32 to 104			
Lubrication							L	ubricated for lit	e 		
Paint								Blue RAL 5002			
Mounting position								any			
Direction of rotation							Motor and	l gearhead sam	e direction		
Protection class								IP 65			
				kgcm ²	0.72	0.7	0.66	0.44	0.43	0.43	0.43
Moment of inertia (relates to the drive)	С	14	J_{1}	10 ⁻³ in.lb.s ²	0.64	0.62	0.58	0.39	0.38	0.38	0.38
(romas to the drive)				kgcm ²	1.05	1.03	0.99	0.77	0.76	0.76	0.75
Clamping hub diameter [mm]	Е	19	$J_{\scriptscriptstyle 1}$	10 ⁻³ in.lb.s ²	0.93	0.91	0.88	0.68	0.67	0.67	0.66

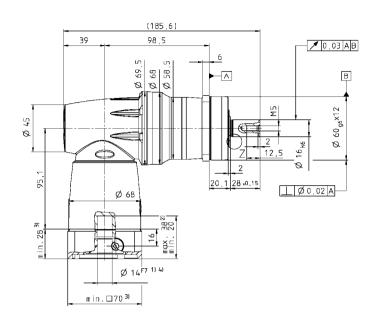
a) Other ratios available on request

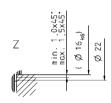
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

o For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

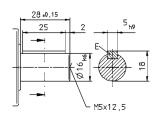




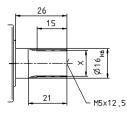


Alternatives: Output shaft variants

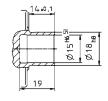
Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



Involute gearing DIN 5480 in mm X = W 16 x 0,8 x 30 x 18 x 6m, DIN 5480



Shaft mounted Mounted via shrink disc



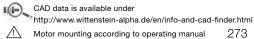
See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under



SPC+ 075 MF 2-stage

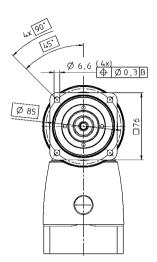
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			<i>T</i>	Nm	110	110	110	110	110	110	95
(max. 1000 cycles per hour)			T _{2B}	in.lb	974	974	974	974	974	974	841
Nominal output torque			T_{2N}	Nm	75	75	75	75	75	75	52
(with n _{IN})			* 2N	in.lb	664	664	664	664	664	664	460
Emergency stop tourque			T _{2Not}	Nm	195	245	250	250	250	250	200
(permitted 1000 times during the service life of the gearh	ead)		21101	in.lb	1726	2168	2213	2213	2213	2213	1770
Nominal input speed (with T _{2N} and 20°C ambient temperature) b), c)			n _{1N}	rpm	2200	2200	2400	2650	2650	2800	2800
Max. input speed			n _{1max}	rpm	6000	6000	6000	6000	6000	6000	6000
Average no-load running torque			T ₀₁₂	Nm	2.3	2.0	1.7	1.0	0.9	0.7	0.6
(with n ₁ =3000 rpm and 20°C gearhead temperature)			012	in.lb	20	18	15	9	8	6	5
Max. torsional backlash			\dot{J}_t	arcmin			Stand	ard ≤ 4 / Reduc	ced ≤ 2		
Torsional rigidity			C	Nm/ arcmin	6.6	7.5	8.6	7.6	8.3	9.1	9.5
Torsional rigidity			C _{t21}	in.lb/ arcmin	58	66	76	67	73	81	84
Max. axial force			F _{2AMax}	N		,		3350			
			* 2AMax	lb _f				753.75			
Max. radial force			F _{2RMax}	N				4200			
			ZHIVIAX	lb _f				945			
Max. tilting moment			M _{2KMax}	Nm in.lb				236			
Efficiency at full load			η	In.ib %				95			
Service life								00000			
(For calculation, see the Chapter "Information")			L _h	h				> 20000			
Weight incl. standard adapter plate			m	kg				5.9			
voight mon standard ddaptor plato				lb _m				13.039			
Operating noise			L _{PA}	dB(A)				≤ 68			
(with n ₁ = 3000 rpm without load)			-PA								
Max. permitted housing temperature				°C				+90			
·				F				194			
Ambient temperature		-		°C F				0 to +40			
				г				32 to 104			
Lubrication							l	ubricated for li	fe		
Paint								Blue RAL 5002	!		
Mounting position								any			
Direction of rotation							Motor and	d gearhead sam	e direction		
Protection class								IP 65			
				kgcm ²	2.23	2.15	1.99	1.25	1.23	1.21	1.2
Moment of inertia	Е	19	J_{1}	10 ⁻³ in.lb.s ²	1.97	1.90	1.76	1.11	1.23	1.07	1.06
(relates to the drive)				kgcm²	3.66	3.59	3.43	2.68	2.67	2.65	2.64
Clamping hub diameter [mm]	Н	28	J_{1}	10 ⁻³ in.lb.s ²	3.24	3.18	3.04	2.37	2.36	2.35	2.34

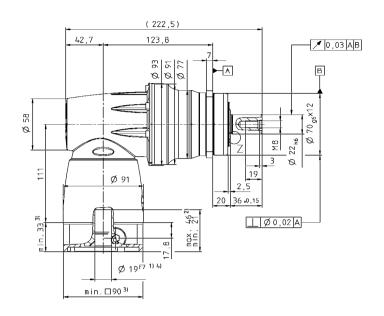
a) Other ratios available on request

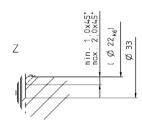
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

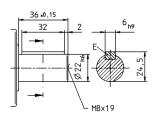




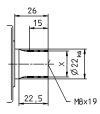


Alternatives: Output shaft variants

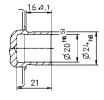
Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



Involute gearing DIN 5480 in mm X = W 16 x 0,8 x 30 x 18 x 6m, DIN 5480



Shaft mounted Mounted via shrink disc



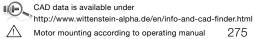
See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under



SPC+ 100 MF 2-stage

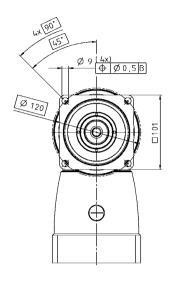
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			<i>T</i>	Nm	315	315	315	315	315	315	235
(max. 1000 cycles per hour)			$T_{_{2B}}$	in.lb	2788	2788	2788	2788	2788	2788	2080
Nominal output torque			T _{2N}	Nm	180	175	170	180	175	170	120
(with n _{1N})			1 2N	in.lb	1593	1549	1505	1593	1549	1505	1062
Emergency stop tourque			T _{2Not}	Nm	540	625	625	625	625	625	500
permitted 1000 times during the service life of the gearh	ead)		* 2Not	in.lb	4779	5531	5531	5531	5531	5531	4425
Nominal input speed with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	2000	2000	2200	2300	2300	2400	2400
Max. input speed			n _{1max}	rpm	4500	4500	4500	4500	4500	4500	4500
Average no-load running torque			T	Nm	5.2	4.9	4.1	2.9	2.7	2.3	2.2
with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	46	43	36	26	24	20	19
Max. torsional backlash			j_t	arcmin			Stand	ard ≤ 4 / Reduc	ced ≤ 2		
Toroional visidity			_	Nm/ arcmin	20.0	23.0	26.0	24.0	26.0	28.0	30.0
Torsional rigidity			C _{t21}	in.lb/ arcmin	177	204	230	212	230	248	266
Max. axial force			_	N				5650			
viax. axiai iorce			F _{2AMax}	lb _f				1271.25			
Max. radial force			F _{2RMax}	N				6600			
viax. radial force			2RMax	lb _f				1485	_		_
Max. tilting moment			M _{2KMax}	Nm				487			
			2KMax	in.lb				4309.95			
Efficiency at full load			η	%				95			
Service life (For calculation, see the Chapter "Information")			L,	h				> 20000			
Meight inclusional adoptor plate			m	kg				11.7			
Weight incl. standard adapter plate			m	lb _m				25.857			
Operating noise (with n ₁ = 3000 rpm without load)			L _{PA}	dB(A)				≤ 68			
				°C				+90			
Max. permitted housing temperature		Ì		F				194			
A				°C				0 to +40			
Ambient temperature				F				32 to 104			
Lubrication							l	ubricated for li	fe		
Paint								Blue RAL 5002	2		
Mounting position								any			
Direction of rotation							Motor and	d gearhead sam	ne direction		
Protection class								IP 65			
				kacm²	8	7.6	7	5	4.9	4.0	4.0
Moment of inertia	Н	28	$J_{_1}$	kgcm ²	7.08	7.6 6.73		4.43	4.9	4.9	4.8
(relates to the drive)	+			kgcm ²	15	14.7	6.20	12.1	12	11.9	11.9
Clamping hub diameter [mm]	K	38	$J_{_{1}}$	10 ⁻³ in.lb.s ²	13.28	13.01	12.48	10.71	10.62	10.53	10.53

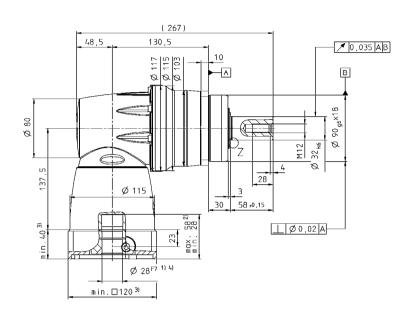
a) Other ratios available on request

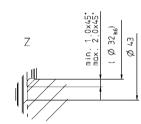
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

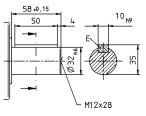




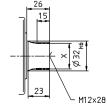


Alternatives: Output shaft variants

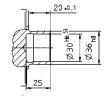
Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



Involute gearing DIN 5480 in mm X = W 16 x 0,8 x 30 x 18 x 6m, DIN 5480



Shaft mounted Mounted via shrink disc



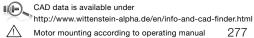
See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under



 $\mathsf{SPC}^{\scriptscriptstyle{\downarrow}}$

SPC+ 140 MF 2-stage

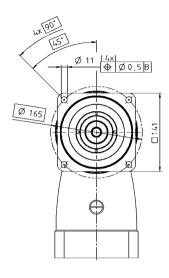
							2-stage			
Ratio ^{a)}		i		4	5	7	8	10	14	20
Max. acceleration torque		_	Nm	660	660	660	660	660	660	530
max. 1000 cycles per hour)		T _{2B}	in.lb	5841	5841	5841	5841	5841	5841	4691
Nominal output torque		_	Nm	360	360	360	360	360	360	220
with n _{IN})		T _{2N}	in.lb	3186	3186	3186	3186	3186	3186	1947
Emergency stop tourque		T _{2Not}	Nm	960	1200	1250	1250	1250	1250	1000
permitted 1000 times during the service life of the gearhead)		2Not	in.lb	8496	10620	11063	11063	11063	11063	8850
Nominal input speed with T _{2N} and 20°C ambient temperature) ^{b), c)}		n _{1N}	rpm	1300	1300	1400	1500	1500	1600	1600
Max. input speed		n _{1max}	rpm	4500	4500	4500	4500	4500	4500	4500
Average no-load running torque		_	Nm	9.8	8.7	7.4	4.6	4.0	3.4	2.9
with n ₁ =3000 rpm and 20°C gearhead temperature)		T ₀₁₂	in.lb	87	77	65	41	35	30	26
Max. torsional backlash		j_t	arcmin			Stand	ard ≤ 4 / Reduc	ed ≤ 2		
Foreignal rigidity		_	Nm/ arcmin	37.0	41.0	46.0	41.0	45.0	48.0	51.0
Forsional rigidity		C _{t21}	in.lb/ arcmin	327	363	407	363	398	425	451
Max. axial force		F _{2AMax}	N				9870			
viax. dalai 10100		2AMax	lb _f				2220.75			
Max. radial force		F _{2RMax}	N				9900			
	_	ZHIVIAX	lb _f				2227.5			
Max. tilting moment		M _{2KMax}	Nm in.lb				952 8425.2	,		
Efficiency at full load		η	%				95			
Service life For calculation, see the Chapter "Information")		L,	h			-	> 20000	-		
			kg				24.7			
Weight incl. standard adapter plate		m	lb _m				54.587			
Operating noise		L _{PA}	dB(A)				≤ 70			
with n ₁ = 3000 rpm without load)		PA								
Max. permitted housing temperature							+90			
			F				194			
Ambient temperature			°C F				0 to +40			
			۲				32 to 104			
Lubrication						L	ubricated for lit	fe		
Paint							Blue RAL 5002	!		
Mounting position						·	any	·	·	
Direction of rotation						Motor and	l gearhead sam	e direction		
Protection class							IP 65			
Moment of inertia	38	J,	kgcm²	30.6	29.7	27.9	18.9	18.7	18.5	18.4
relates to the drive)										

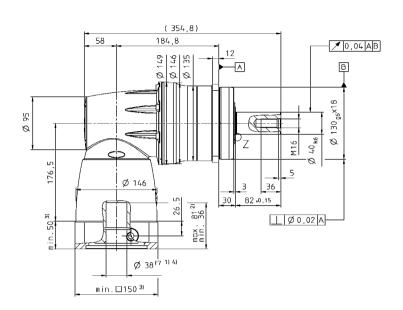
a) Other ratios available on request

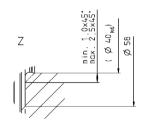
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

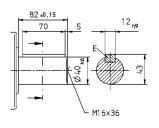




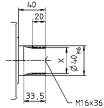


Alternatives: Output shaft variants

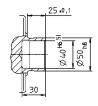
Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



Involute gearing DIN 5480 in mm X = W 16 x 0,8 x 30 x 18 x 6m, DIN 5480



Shaft mounted Mounted via shrink disc



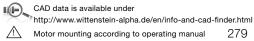
See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under



 $\mathsf{SPC}^{\scriptscriptstyle{\downarrow}}$

SPC+ 180 MF 2-stage

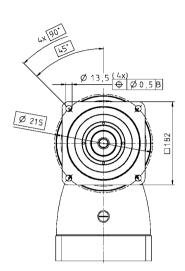
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque		-	_	Nm	1210	1210	1210	1210	1210	1210	970
(max. 1000 cycles per hour)			T _{2B}	in.lb	10709	10709	10709	10709	10709	10709	8585
Nominal output torque			T _{2N}	Nm	750	750	750	750	750	750	750
(with n _n)		-	* 2N	in.lb	6638	6638	6638	6638	6638	6638	6638
Emergency stop tourque (permitted 1000 times during the service life of the gear	and)		T _{2Not}	Nm	1560	1955	2735	2750	2750	2750	2200
Nominal input speed	nead)			in.lb	13806	17302	24205	24338	24338	24338	19470
(with T _{2N} and 20°C ambient temperature) b), c)			n _{1N}	rpm	1000	1000	1100	1200	1200	1300	1300
Max. input speed			n _{1max}	rpm	4000	4000	4000	4000	4000	4000	4000
Average no-load running torque			_	Nm	20.5	18.5	16.5	11.0	10.0	9.0	8.0
with n _i =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	181	164	146	97	89	80	71
Max. torsional backlash			j_t	arcmin			Stand	ard ≤ 4 / Reduc	ed ≤ 2		
Torsional rigidity			C ₁₂₁	Nm/ arcmin	104.0	122.0	143.0	130.0	144.0	157.0	166.0
Torsional rigidity			U _{t21}	in.lb/ arcmin	920	1080	1266	1151	1274	1389	1469
Max. axial force			F _{2AMax}	N				14150			-
			2AMax	lb _f				3183.75			
Max. radial force			F _{2RMax}	N				15400 3465			
				lb _f Nm				1600			
Max. tilting moment			M _{2KMax}	in.lb				14160	,	,	
Efficiency at full load			η	%				95			
Service life For calculation, see the Chapter "Information")			L _h	h				> 20000			
Materials to all about aloud a dambar aloud				kg				54.7			
Weight incl. standard adapter plate			m	lb _m				120.887			
Operating noise			L _{PA}	dB(A)				≤ 70			
with n ₁ = 3000 rpm without load)				°C				+90			
Max. permitted housing temperature				F				+90 194			
				°C				0 to +40			
Ambient temperature				F				32 to 104			
Lubrication							L	ubricated for lit	fe		
Paint								Blue RAL 5002	!		-
Mounting position								any	,	,	
Direction of rotation							Motor and	l gearhead sam	e direction		
Protection class								IP 65			
Moment of inertia				kgcm²	109.5	105	94.7	49.2	48.1	46.9	46.2
(relates to the drive)	M	48	$J_{_{1}}$	10 ⁻³ in.lb.s ²	96.91	92.93	83.81	43.54	42.57	41.51	40.89
Clamping hub diameter [mm]					50.51	32.30	00.01	-0.54	72.01	71.51	40.03

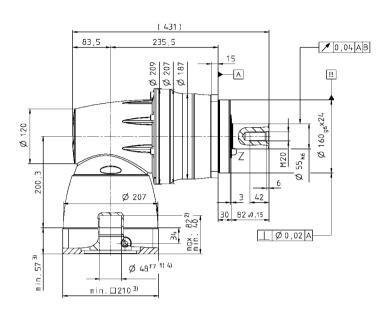
a) Other ratios available on request

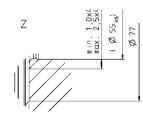
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange

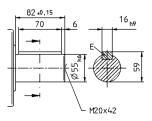




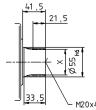


Alternatives: Output shaft variants

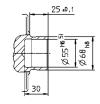
Keywayed output shaft in mm E = key as per DIN 6885, sheet 1, form A



Involute gearing DIN 5480 in mm X = W 16 x 0,8 x 30 x 18 x 6m, DIN 5480



Shaft mounted Mounted via shrink disc



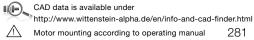
See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions $\pm 1 \text{ mm}$

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under



 $\mathsf{SPC}^{\scriptscriptstyle{\downarrow}}$

TPC+ 004 MF 2-stage

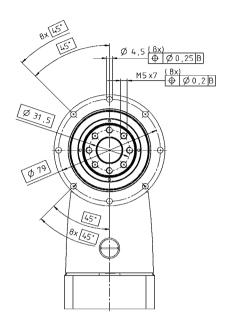
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			_	Nm	40	50	55	40	50	55	35
(max. 1000 cycles per hour)			T_{2B}	in.lb	354	443	487	354	443	487	310
Nominal output torque			т	Nm	28	28	28	28	28	28	18
with n,,)			T _{2N}	in.lb	248	248	248	248	248	248	159
Emergency stop tourque			T _{2Not}	Nm	100	100	100	100	100	100	100
permitted 1000 times during the service life of the gearh	ead)		2Not	in.lb	885	885	885	885	885	885	885
Nominal input speed with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	2900	2900	3100	3400	3400	3600	3600
Max. input speed			n _{1max}	rpm	6000	6000	6000	6000	6000	6000	6000
Average no-load running torque			-	Nm	1.5	1.3	1.1	0.8	0.7	0.6	0.5
with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	13	12	10	7	6	5	4
Max. torsional backlash		,	İt	arcmin			Stand	ard ≤ 5 / Reduc	ed ≤ 3		
Parantaria di Mantalita.				Nm/ arcmin	4.8	6.2	7.6	6.1	7.4	8.5	7.3
Forsional rigidity			C _{t21}	in.lb/ arcmin	42	55	67	54	65	75	65
Tialina vialialia.			^	Nm/ arcmin				-			•
ilting rigidity		- 1	C_{2K}	in.lb/ arcmin				-			
Max. axial force			F _{2AMax}	N				1630.0			
nax. axiai iorce			2AMax	lb _f				366.8			
Max. tilting moment			M _{2KMax}	Nm		,		110.0			
			2KMax	in.lb				973.5			
Efficiency at full load			η	%				95.0			
Service life For calculation, see the Chapter "Information")			L _h	h				> 20000			
Majalat in all atomatous a stantau alata				kg				2.6			
Neight incl. standard adapter plate			m	lb _m				5.7			
Operating noise			ı	dB(A)				≤ 68			
with n ₁ = 3000 rpm without load)			L _{PA}	UD(A)							
Max. permitted housing temperature				°C				+90			
,				F				194			
Ambient temperature		_		°C				0 to +40			
		_		F				32 to 104			
Lubrication							L	ubricated for lit	e e		
Paint Paint								Blue RAL 5002			
Mounting position								any			
Direction of rotation							Motor and	gearhead sam	e direction		
Protection class								IP 65			
		\dashv		kgcm ²	0.72	0.7	0.66	0.44	0.43	0.43	0.43
Moment of inertia	С	14	$J_{_{1}}$	10 ⁻³ in.lb.s ²	0.64	0.62	0.58	0.39	0.38	0.38	0.38
relates to the drive)		\dashv		kgcm ²	1.05	1.03	0.99	0.77	0.76	0.76	0.75
Clamping hub diameter [mm]	E	19	$J_{_{1}}$	10 ⁻³ in.lb.s ²	0.93	0.91	0.88	0.68	0.67	0.67	0.66

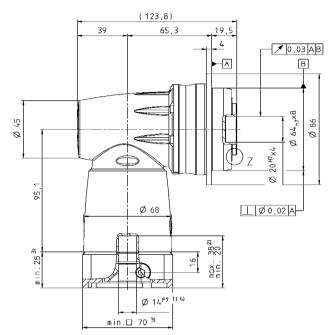
a) Other ratios available on request

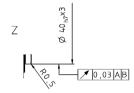
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange







See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ± 1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html Motor mounting according to operating manual

TPC+ 010 MF 2-stage

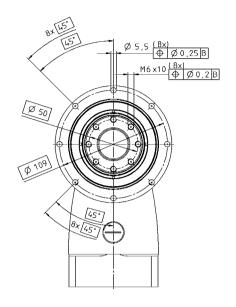
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			T _{2B}	Nm	120	143	143	120	143	143	105
(max. 1000 cycles per hour)			* 2B	in.lb	1062	1266	1266	1062	1266	1266	929
Nominal output torque			T _{2N}	Nm	75	75	75	75	75	75	60
(with n _{1N})			* 2N	in.lb	664	664	664	664	664	664	531
Emergency stop tourque (permitted 1000 times during the service life of the gearhous)	ead)		T _{2Not}	Nm in.lb	195 1726	245 2168	250 2213	250 2213	250 2213	250 2213	250 2213
Nominal input speed (with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	2100	2100	2300	2650	2650	2800	2800
Max. input speed			n _{1max}	rpm	6000	6000	6000	6000	6000	6000	6000
Average no-load running torque			_	Nm	2.5	2.2	1.9	1.1	1.0	0.8	0.7
(with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	22	19	17	10	9	7	6
Max. torsional backlash			j_t	arcmin			Stand	ard ≤ 4 / Reduc	ced ≤ 2		
Tourism of statether.				Nm/ arcmin	12.0	16.0	20.0	16.0	20.0	23.0	21.0
Torsional rigidity			C _{t21}	in.lb/ arcmin	106	142	177	142	177	204	186
Tilting rigidity			_	Nm/ arcmin				225			
Titting rigidity			C _{2K}	in.lb/ arcmin				1991			
Max. axial force			F _{2AMax}	N				2150			
Wax. axial 10100			* 2AMax	lb _f				484			
Max. tilting moment			M _{2KMax}	Nm in.lb				270 2390			
Efficiency at full load			η	%				95			
Service life (For calculation, see the Chapter "Information")			L _n	h				> 20000			
(For Calculation, See the Orlapier Information)				kg				6			
Weight incl. standard adapter plate			m	lb _m				13			
Operating noise (with n ₁ = 3000 rpm without load)			L _{PA}	dB(A)				≤ 68			
May paymitted bauging tampayatura				°C				+90			
Max. permitted housing temperature				F				194			
Ambient temperature				°C				0 to +40			
				F				32 to 104			
Lubrication							L	ubricated for li	fe		
Paint								Blue RAL 5002	!		
Mounting position								any			
Direction of rotation							Motor and	d gearhead sam	e direction		
Protection class								IP 65			
				kgcm ²	2.41	2.27	1.99	1.29	1.26	122	1.21
Moment of inertia (relates to the drive)	Е	19	$J_{_{1}}$	10 ⁻³ in.lb.s ²	2.13	2.01	1.76	1.14	1.12	107.97	1.07
		-	,	kgcm ²	3.85	3.71	3.43	2.73	2.7	2.66	2.64
Clamping hub diameter [mm]	Н	28	J_{1}	10 ⁻³ in.lb.s ²	3.41	3.28	3.04	2.42	2.39	2.35	2.34

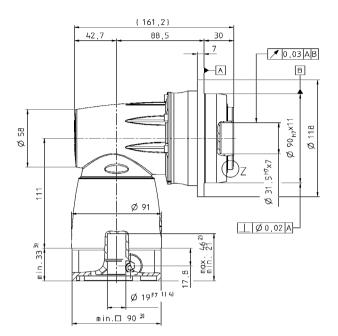
a) Other ratios available on request

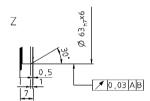
b) Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange







See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ± 1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html Motor mounting according to operating manual

TPC+ 025 MF 2-stage

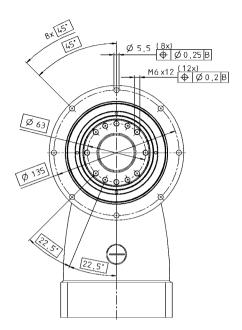
								2-stage			
Ratio ^{a)}			i		4	5	7	8	10	14	20
Max. acceleration torque			_	Nm	320	380	330	320	380	330	265
(max. 1000 cycles per hour)			T _{2B}	in.lb	2832	3363	2921	2832	3363	2921	2345
Nominal output torque			_	Nm	170	170	170	170	170	170	120
(with n _{1N})			T _{2N}	in.lb	1505	1505	1505	1505	1505	1505	1062
Emergency stop tourque			T	Nm	540	625	625	625	625	625	625
(permitted 1000 times during the service life of the gear	nead)		T _{2Not}	in.lb	4779	5531	5531	5531	5531	5531	5531
Nominal input speed with T _{2N} and 20°C ambient temperature) ^{b), c)}			n _{1N}	rpm	1900	1900	2100	2300	2300	2400	2400
Max. input speed			n _{1max}	rpm	4500	4500	4500	4500	4500	4500	4500
Average no-load running torque			_	Nm	5.8	5.2	4.5	3.2	2.9	2.5	2.2
with n ₁ =3000 rpm and 20°C gearhead temperature)			T ₀₁₂	in.lb	51	46	40	28	26	22	19
Max. torsional backlash			j_t	arcmin			Stand	ard ≤ 4 / Reduc	ed ≤ 2		
Tavaianal visisliku			_	Nm/ arcmin	33.0	43.0	53.0	45.0	56.0	61.0	57.0
Forsional rigidity			C _{t21}	in.lb/ arcmin	292	381	469	398	496	540	504
Filting rigidity			_	Nm/ arcmin				550			
Titing rigidity			C _{2K}	in.lb/ arcmin				4868			
Max. axial force			F	N				4150			
VIAX. UXIAI 10100			F _{2AMax}	lb _f				934		_	
Max. tilting moment			M _{2KMax}	Nm				440			
-			2KMax	in.lb				3894			
Efficiency at full load			η	%				95			
Service life For calculation, see the Chapter "Information")			L _n	h				> 20000			
Weight incl. standard adapter plate			m	kg				11			
Weight incl. standard adapter plate			m	lb _m				23			
Operating noise			L _{PA}	dB(A)				≤ 68			
(with n ₁ = 3000 rpm without load)			►PA	GD(r)							
Max. permitted housing temperature				°C				+90			
, and a second composition				F				194			
Ambient temperature				°C				0 to +40			
- p				F				32 to 104			
Lubrication							l	ubricated for lit	fe		
Paint								Blue RAL 5002	!		
Mounting position								any			
Direction of rotation							Motor and	d gearhead sam	e direction		
Protection class								IP 65			
				kgcm ²	8.3	7.9	7	5.1	5	4.9	4.8
Moment of inertia (relates to the drive)	Н	28	J_1	10 ⁻³ in.lb.s ²	7.35	6.99	6.20	4.51	4.43	4.34	4.25
			l .	kgcm ²	15.4	14.9	14.1	12.2	12.1	12	11.9
Clamping hub diameter [mm]	K	38	J_1	10 ⁻³ in.lb.s ²	13.63	13.19	12.48	10.80	10.71	10.62	10.53

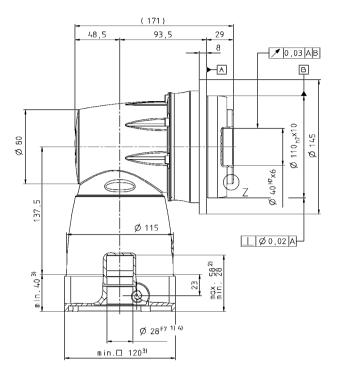
a) Other ratios available on request

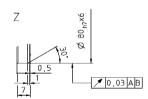
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange







See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ± 1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html Motor mounting according to operating manual

TPC+ 050 MF 2-stage

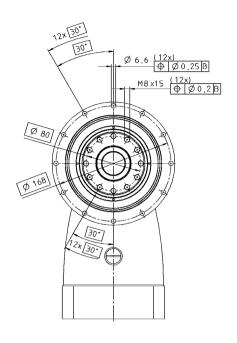
						2-stage			
Ratio ^{a)}	i		4	5	7	8	10	14	20
Max. acceleration torque		Nm	700	700	700	700	700	700	540
(max. 1000 cycles per hour)	T _{2B}	in.lb	6195	6195	6195	6195	6195	6195	4779
Nominal output torque	_	Nm	370	370	370	370	370	370	240
(with n _{1N})	T _{2N}	in.lb	3275	3275	3275	3275	3275	3275	2124
Emergency stop tourque	_T	Nm	960	1200	1250	1250	1250	1250	1250
permitted 1000 times during the service life of the gearhead)	T _{2Not}	in.lb	8496	10620	11063	11063	11063	11063	11063
Nominal input speed with T _{2N} and 20°C ambient temperature) ^{b), c)}	n _{1N}	rpm	1200	1200	1300	1500	1500	1600	1600
Max. input speed	n _{1max}	rpm	4500	4500	4500	4500	4500	4500	4500
Average no-load running torque	-	Nm	12.0	10.5	8.8	5.7	5.0	4.1	3.4
with n ₁ =3000 rpm and 20°C gearhead temperature)	T ₀₁₂	in.lb	106	93	78	50	44	36	30
Max. torsional backlash	j_t	arcmin			Stand	ard ≤ 4 / Reduc	ed ≤ 2		,
		Nm/ arcmin	73.0	93.0	111.0	93.0	113.0	124.0	111.0
Forsional rigidity	C ₁₂₁	in.lb/ arcmin	646	823	982	823	1000	1097	982
Filain a vini alia.		Nm/ arcmin				560			
ilting rigidity	C _{2K}	in.lb/ arcmin				4956			
Max. axial force	_	N				6130			
viax. axiai loice	F _{2AMax}	lb _f				1379			
Max. tilting moment	14	Nm				1335			
viax. titting moment	M _{2KM}	in.lb				11815			
Efficiency at full load	η	%				95			
Service life For calculation, see the Chapter "Information")	L	h				> 20000			
Maintain at the standard advance of the		kg				22			
Weight incl. standard adapter plate	m	lb _m				48			
Operating noise	,					< 70			
with n ₁ = 3000 rpm without load)	L _{PA}	dB(A)				≤ 70			
Max. permitted housing temperature		°C				+90			
vian. politilited housing temperature		F				194			
Ambient temperature		°C				0 to +40			
		F				32 to 104			
ubrication					L	ubricated for lit	fe		
Paint						Blue RAL 5002			
Mounting position						any			
Direction of rotation					Motor and	gearhead sam	e direction		
Protection class						IP 65			
Moment of inertia (relates to the drive)		kgcm ²	32.3	30.8	27.90	19.4	19.00	18.7	18.50
Clamping hub diameter [mm]	38 J ₁	10 ⁻³ in.lb.s ²	28.59	27.26	24.69	17.17	16.82	16.55	16.37

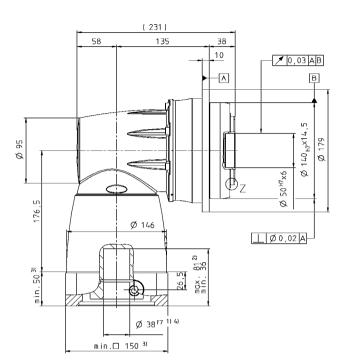
a) Other ratios available on request

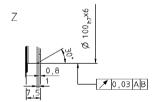
 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

 $^{^{\}mbox{\tiny c)}}$ For higher ambient temperatures, please reduce input speed

d Refers to center of the output shaft or flange







See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

Non-tolerated dimensions ± 1 mm

- 1) Check motor shaft fit.
- 2) Min./Max. permissible motor shaft length. Longer motor shafts are adaptable, please contact us.
- 3) The dimensions depend on the motor.
- 4) Smaller motor shaft diameter is compensated by a bushing with a minimum thickness of 1 mm.



CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html Motor mounting according to operating manual

TPC+ 110 MF 2-stage

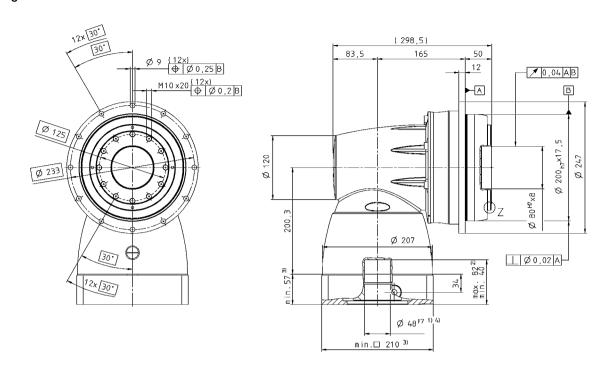
							2-stage			
Ratio ^{a)}	i			4	5	7	8	10	14	20
Max. acceleration torque	-		Nm	1260	1575	1600	1260	1575	1600	1400
(max. 1000 cycles per hour)	T 20	В	in.lb	11151	13939	14160	11151	13939	14160	12390
Nominal output torque	T ₂		Nm	700	750	750	700	750	750	750
(with n _{1N})	2	N	in.lb	6195	6638	6638	6195	6638	6638	6638
Emergency stop tourque (permitted 1000 times during the service life of the gearhead)	T 2	Not	Nm in.lb	1560 13806	1955 17302	2735 24205	2750 24338	2750 24338	2750 24338	2750 24338
Nominal input speed (with T_{2N} and $20^{\circ}C$ ambient temperature) (b), c)	n ₁₁	N	rpm	900	900	1000	1200	1200	1300	1300
Max. input speed	n,,	max	rpm	4000	4000	4000	4000	4000	4000	4000
Average no-load running torque			Nm	25.0	22.0	19.0	13.5	12.0	10.0	9.0
(with n ₁ =3000 rpm and 20°C gearhead temperature)	To	12	in.lb	221	195	168	119	106	89	80
Max. torsional backlash	j_t		arcmin			Stand	ard ≤ 4 / Reduc	ed ≤ 2		
Torsional rigidity	C_{t}		Nm/ arcmin	181.0	242.0	324.0	278.0	345.0	407.0	390.0
Torsional rigidity		21	in.lb/ arcmin	1602	2142	2867	2460	3053	3602	3452
Filting rigidity	C		Nm/ arcmin				1452			
		2K	in.lb/ arcmin				12850			
Max. axial force	$ F_2 $	AMax	N				10050			
			lb _f Nm				2261 3280			
Max. tilting moment	M	2KMax	in.lb				29028			
Efficiency at full load	η		%				95			
Service life For calculation, see the Chapter "Information")	L		h				> 20000			
Weight incl. standard adapter plate	m		kg				51			
			lb _m				112			
Operating noise (with n, = 3000 rpm without load)	L	И	dB(A)				≤ 70			
May permitted housing temperature			°C				+90			
Max. permitted housing temperature			F				194			
Ambient temperature			°C				0 to +40			
			F				32 to 104			
Lubrication						L	ubricated for lit	fe		
Paint							Blue RAL 5002			
Mounting position							any			
Direction of rotation						Motor and	l gearhead sam	e direction		
Protection class							IP 65			
Moment of inertia			kgcm²	121.2	112.6	94.7	52.1	50	47.9	46.7
(valetes to the drive)	48 J,									

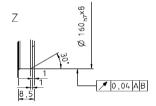
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 $^{^{\}mbox{\scriptsize b)}}$ Higher speeds are possible if the nominal torque is reduced

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See technical data sheet for available clamping hub diameters (mass moment of inertia). Dimensions available on request.

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CAD data is available under http://www.wittenstein-alpha.de/en/info-and-cad-finder.html Motor mounting according to operating manual