

Reliable <u>High Torque</u> safety clutches for heavy load applications









Always in use

EAS®-HT safety clutches for heavy load applications prolong the availability of your production systems.

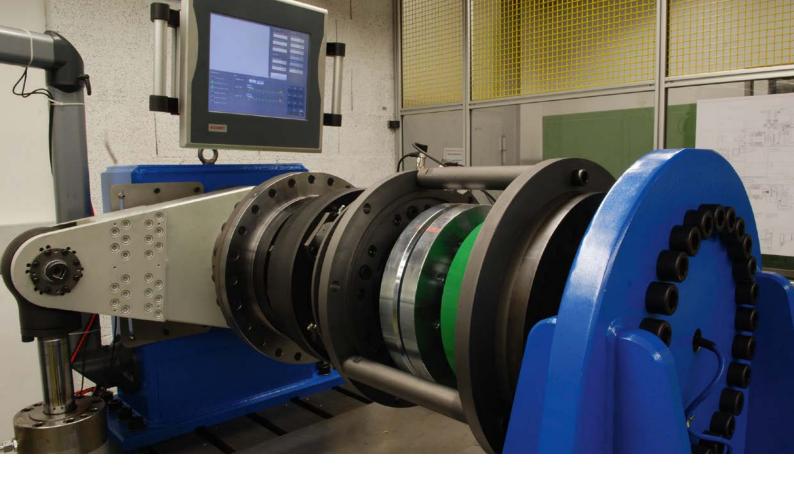
They increase your profit, prevent damage caused by overload and save costs.

EAS®-HT safety clutches

the reliable, non-destructive overload protection

- Disengaging
- Steplessly adjustable
- Precise
- Compact
- Robust





Tested safety

For more than 40 years, we have been dimensioning, developing and manufacturing safety clutches for heavy load applications.

You can rely on the tested reliability and safety of our heavy load clutch.

Experts, not experiments

as safety does not allow for compromises



EAS®-HT short bearing-supported hub



Torque: 4 to 40 kNm

Sizes 7 to 10 Type 4050._0400

- Direct attachment of the drive element on the bearing-supported, output-side clutch flange.
- The bearing is able to absorb high additional forces in axial and radial directions.

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EAS®-HT lastic



Torque: 4 to 40 kNm

Sizes 7 to 10 Type 4053._0400

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

Page 8

EAS®-HT flange design



Torque: 7.5 to 440 kNm

Sizes 0 to 6 Type 4060.71400

- Compact, ready-to-install module
- Can easily be integrated into the drive line

Page 10

EAS®-HT Toothed coupling



Torque: 7.5 to 440 kNm

Sizes 0 to 6 Type 4061.71400

- Double shaft design
- Toothed coupling with crowned teeth cutting
- Robust and temperature-resistant
- High misalignment compensation capability

Page 12

EAS®-HT backlash-free



Torque: 7.5 to 140 kNm

Sizes 0 to 4 Type 4062.71400

- Double shaft design with a torsionally rigid, backlash-free disk pack coupling
- High torsional rigidity
- Backlash-free torque transmission
- Maintenance-free

Page 14

EAS®-HT lastic bolt



Torque: 40 to 260 kNm

Sizes 3 to 5 Type 4063.70400

- Double shaft design with a flexible, positive locking coupling
- Absorbs impact-type loads

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EAS®-HT Options

Customer-specific designs Low temperature design Alternative shaft connections ATEX

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EAS®-elements

- Standard
- Reinforced



- Torque limiting or force limiting elements
- Installation into two flanges located towards one another
- Integration into existing constructions possible

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Technical Explanations

General
Pre-selection
Misalignment compensation capability

Page 23

Additional branch-optimised EAS® safety clutches

High-speed clutches EAS®-HSE



Torque: 100 to 8.400 Nm

Sizes 02 to 0 Type 404_ . _04_ _ Reliable overload protection at high speeds

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-HSC/ EAS®-HSE.

Extruder clutches EAS®-dutytorque



Torque: 70 to 17.000 Nm

Sizes 2 to 9 Type 4043. _1400 Protect extruder screws

from expensive damage caused by overload

For more information as well as detailed Technical Data and Dimensions, please see our product catalogue EAS®-dutytorque.

Rustproof design



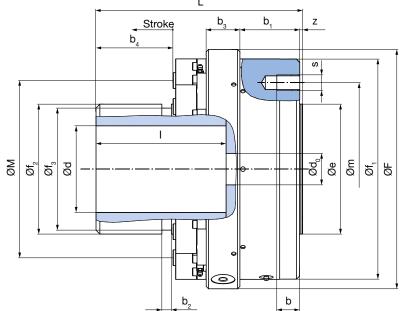


Corrosion-protected safety clutches for environmental and waste water technology

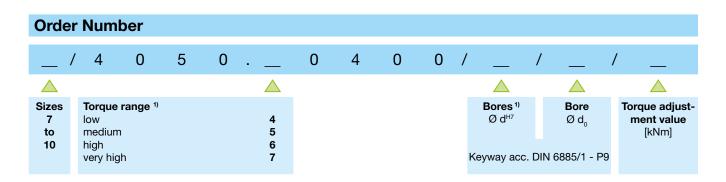


Short bearing-supported hub

Type 4050._0400 Sizes 7 to 10







Example: Order Number 8 / 4050.60400 / 90 / 35 / 84050.60400 / 90 / 35 / 8

1) Position of the keyway to the tapped hole "s" in the thrust piece is not defined. Defined position available on request.

Technical Dat	_				Siz	zes	
lecillical Dat	a 			7	8	9	10
	Type 4050. 4 0400	$M_{\scriptscriptstyle G}$	[kNm]	1.3 - 2.6	1.6 - 3.2	4 - 8	5 - 10
	Number of	EAS®-el	ements	2	2	2	2
	Type 4050. 5 0400	$M_{\scriptscriptstyle G}$	[kNm]	2 - 4	3.2 - 6.4	6 - 12	10 - 20
Limit torques for overload	Number of	EAS®-elements		3	4	3	4
ioi overioau	Type 4050. 6 0400	$M_{\scriptscriptstyle G}$	[kNm]	2.6 - 5.2	4.8 - 9.6	8 - 16	15 - 30
	Number of	Number of EAS®-elements			6	4	6
	Type 4050. 7 0400	$M_{\scriptscriptstyle G}$	[kNm]	4 - 8	6.5 - 13	12 - 24	20 - 40
	Number of	EAS®-el	ements	6	8	6	8
Sizes EAS®-elements		0	0	1	1		
Maximum speed	Maximum speed n _{max}		[rpm]	3000	3000 2800		2200
Bolt stroke on ov	erload		[mm]	6	6	8	8

Max. permitted forces on the flange con-				Sizes					
nection			7	8	9	10			
Radial forces	Tupo 4050 0400	F _R	[kN]	15	20	30	40		
Axial forces	Type 40500400 F _A [kN]			10	15	20	30		

Mass moments of inertia and weights			Sizes					
			7	8	9	10		
EAS®-hub-side	Type 40500400	J	[kgm²]	0.18	0.38	1.05	2.37	
Flange side	Type 40500400	J	[kgm²]	0.17	0.38	1.3	2.65	
Weight at d _{max}	Type 40500400		[kg]	47	76	145	232	

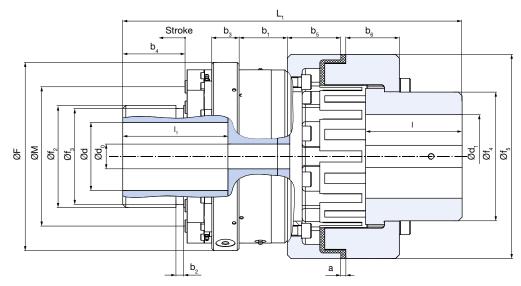
Bores [mm]		Sizes						
		7	8	9	10			
EAS®-hub-side	d _{max}	90 ^{H7}	110 ^{H7}	135 ^{H7}	160 ^{H7}			
Flange side	d _{0 max}	30	40	48	58			

Dimensions		Siz	es	
[mm]	7	8	9	10
b	25	30	35	35
b ₁	66	78	94	110
b_2	12.5	12.5	15	15
b ₃	44	44	56	56
b ₄	70.5	100.5	119.3	159.3
e _{h7}	147	165	242	276
F	260	304	380	450
f ₁	237.5	279.5	359.5	417.5
$\mathbf{f_2}$	120	165	190	245
f ₃	110	155	180	230
L	228	270	330	387
I	140	170	210	250
M	180	225	270	340
m	190	220	285	325
S	8xM16	8xM20	8xM24	12xM24
z	4	4	5	6

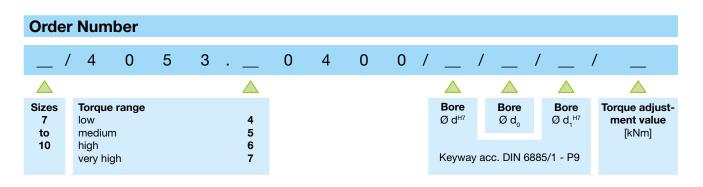
We reserve the right to make dimensional and constructional alterations.



Type 4053._0400
Sizes 7 to 10







Example: Order Number 8 / 4053.60400 / 90 / 35 /115 / 8

Technical Data			Sizes					
rechnical Data	d 				7	8	9	10
	Type 4053. 4	0400	M_{G}	[kNm]	1.3 - 2.6	1.6 - 3.2	4 - 8	5 - 10
	Nu	ımber of	EAS®-e	lements	2	2	2	2
	Type 4053. 5	0400	\mathbf{M}_{G}	[kNm]	2 - 4	3.2 - 6.4	6 - 12	10 - 20
Limit torques for overload	Nu	ımber of	EAS®-e	lements	3	4	3	4
Tor overload	Type 4053. 6 0400	0400	M_{G}	[kNm]	2.6 - 5.2	4.8 - 9.6	8 - 16	15 - 30
	Nu	ımber of	EAS®-e	lements	4	6	4	6
	Type 4053. 7	0400	M_{G}	[kNm]	4 - 8	6.5 - 13	12 - 24	20 - 40
	Nι	Number of EAS®-elements			6	8	6	8
Sizes EAS®-eleme	ents				0	0	1	1
Maximum speed			n _{max}	[rpm]	2250	2000	1500	1400
Bolt stroke on ove	erload			[mm]	6	6	8	8
	Permitted	axial	ΔK_{a}	[mm]	±2.5	±2.5	±2.5	±2.5
Flexible	misalign-	radial	ΔK	[mm]	0.3	0.3	0.3	0.3
shaft coupling	ments 1)	angular	ΔK _w	[mm]	0.3	0.3	0.3	0.3
Nominal and max	imum torque	s,	T _{KN}	[kNm]	5.8	9.9	20.5	28
flexible coupling	·		T _{K max}	[kNm]	8.3	14.5	27	66

Mass moments of inertia and weights				Sizes					
			7	8	9	10			
Mass moments	of EAS®-hub-side	J	[kgm²]	0.18	0.38	1.05	2.37		
inertia Flexible side		J	[kgm²]	0.57	1.62	5.0	10.7		
Weight at d _{max}		[kg]	85	154	282	464			

Bores [mm]		Sizes					
		7	8	9	10		
EAS®-hub-side	d _{max}	90 ^{H7}	110 ^{H7}	135 ^{H7}	160 ^{H7}		
Bearing flange	d _{o max}	30	40	48	58		
Flexible side	d _{1 max}	115 ^{H7}	135 ^{H7}	180 ^{H7}	200 ^{H7}		

Dimensions	Sizes			
[mm]	7	8	9	10
а	5.5	8	8	8
b ₁	66	78	94	110
b_2	12.5	12.5	15	15
b ₃	44	44	56	56
b ₄	70.5	100.5	119.3	159.3
b ₅	76	86.5	102	108
b ₆	76	86.5	102	108
F	260	304	380	450
$\mathbf{f_2}$	120	165	190	245
f ₃	110	155	180	230
f ₄	164	208	275	289
f ₅	265	330	415	480
L,	469.5	548.5	668	754
I	137	156	196	220
l _t	140	170	210	250
М	180	225	270	340

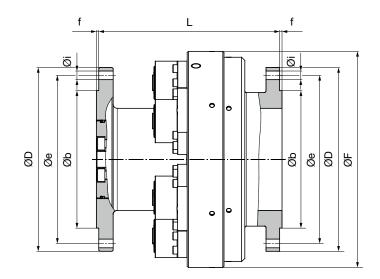
We reserve the right to make dimensional and constructional alterations.

1) The values refer to 1500 rpm.

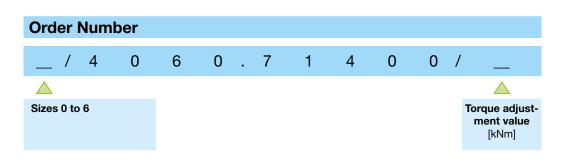


flange design

Type 4060.71400 Sizes 0 to 6







Example: Order number 5/ 4060.71400 / 200



Technical Data			Sizes							
recriffical Data	Technical Data			1	2	3	4	5	6	
Limit torques for overload	M_{G}	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140	125 - 250	220 - 440	
Number of EAS®-elements			6	8	6	8	12	10	10	
Sizes EAS®-elements			0	0	1	1	1	2	2 1)	
Maximum speed	n _{max}	[rpm]	2000	1750	1500	1250	1000	900	750	
Bolt stroke on overload		[mm]	6	6	8	8	8	12	12	

Mass moments of inertia and weights			Sizes							
			0	1	2	3	4	5	6	
EAS®-element-side	J	[kgm²]	0.25	0.5	1.16	2.71	5.51	16.29	27.87	
EAS®-pressure flange side	J	[kgm²]	0.19	0.37	0.96	2.05	4.22	10.29	19.3	
Weight at d _{max}		[kg]	56	77	142	212	303	627	814	

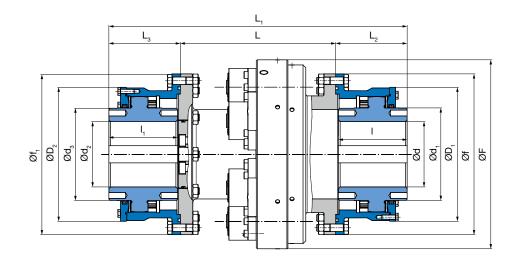
Dimensions				Sizes			
[mm]	0	1	2	3	4	5	6
b _{h7}	175	230	255	310	340	460	540
е	214	269	306	360	400	531	618
D	234	292	330	390	430	567	660
F	275	320	380	455	545	640	740
f	3	3	4	4	5	6	6
i	11	13	13	17	17	21	25
L	226	243	298	312	328	476	485

We reserve the right to make dimensional and constructional alterations.

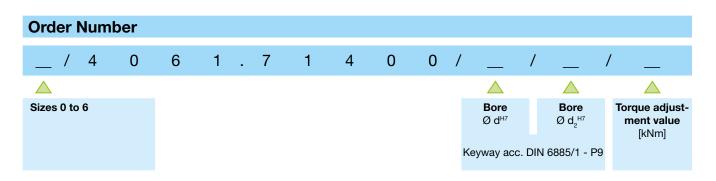


Toothed coupling

Type 4061.71400 Sizes 0 to 6







Example: Order number 4 / 4061.71400 / 180 / 200 / 90

Tooknied D	oto							Sizes			
Technical Data					0	1	2	3	4	5	6
Limit torques f	or overload		M _G	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140	125 - 250	220 - 440
Number of EAS	®-elements				6	8	6	8	12	10	10
Sizes EAS®-eler	ments				0	0	1	1	1	2	2 1)
Maximum spee	ed		n _{max}	[rpm]	2000	1750	1500	1250	1000	900	750
Bolt stroke on	overload			[mm]	6	6	8	8	8	12	12
T	Permitted	axial	ΔK_{a}	[mm]	±2	±3	±3	±3	±3	±4	±4
Toothed cou- pling	misalign-	radial	ΔK_r	[mm]	7.5	8.6	10.2	11.7	12.4	18.4	20.6
pinig	ments 1) 2)	angular	ΔK_{w}	[mm]	1.25	1.25	1.25	1.25	1.25	1.25	1.25
Nominal and maximum torques, T _{KN} [kNm]		12.5	25	40	63	100	250	400			
curved-tooth o	oupling		T _{K max}	[kNm]	25	50	80	12.6	200	500	800

The values refer to 1500 rpm.
 Per joint

Mass moments of inertia and weights		Sizes							
		0	1	2	3	4	5	6	
EAS®-pressure flange side	J	[kgm ²]	0.27	0.65	1.48	3.33	6.43	19.17	39.74
EAS®-element side	J	[kgm²]	0.34	0.78	1.69	3.99	7.72	25.18	48.3
Weight at d _{max} / d _{2max}		[kg]	83	132	220	345	488	1053	1523

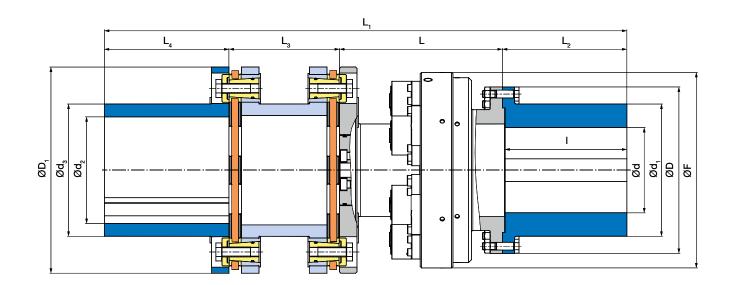
Bores [mm]			Sizes							
		0	1	2	3	4	5	6		
EAS®-pressure flange side	d _{max}	95	130	150	185	210	285	340		
EAS®-element side	d _{2 max}	95	130	150	185	210	285	340		

We reserve the right to make dimensional and constructional alterations.

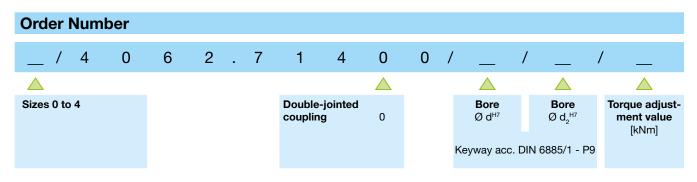
Dimensions				Sizes			
[mm]	0	1	2	3	4	5	6
d ₁	135	185	210	255	290	400	480
d_3	135	185	210	255	290	400	480
D ₁	195	251	288	337	375	502	584
$D_{\!\scriptscriptstyle 2}$	195	251	288	337	375	502	584
F	275	320	380	455	545	640	740
f	234	292	330	390	430	567	660
f ₁	234	292	330	390	430	567	660
L	226	242.5	298	312	328	476	485
L,	434	502.5	588	685	740	1012	1125
$L_{\scriptscriptstyle 2}$	104	130	145	186.5	206	268	320
L ₃	104	130	145	186.5	206	268	320
1	100	125	140	180	200	260	310
Ļ	100	125	140	180	200	260	310

backlash-free

Type 4062.71400 Sizes 0 to 4







Example: Order number 4 / 4062.71400 / 180 / 200 / 90

Tooksisel Det	·_						Sizes		
Technical Dat	ieciiiicai Data					1	2	3	4
Limit torques for	overload		$M_{\rm G}$	[kNm]	7.5 - 15	12.5 - 25	20 - 40	37.5 - 75	70 - 140
Number of EAS®-	elements				6	8	6	8	12
Sizes EAS®-eleme	Sizes EAS®-elements				0	0	1	1	1
Maximum speed			n _{max}	[rpm]	2000	1750	1500	1250	1000
Bolt stroke on ov	verload			[mm]	6	6	8	8	8
T	Permitted	axial	ΔK_{a}	[mm]	1.6	1.7	2.1	2.3	2.3
Torsionally rigid shaft coupling	misalign-	radial	ΔK_r	[mm]	1.0	1.0	1.1	1.3	1.4
ments 1) angular		ΔK_{w}	[°]	0.4	0.4	0.4	0.4	0.4	
Nominal and maximum torques, T _{KN} [kNm]		[kNm]	22	33	50	73	110		
torsionally rigid a	all-steel cou	pling	T _{K max}	[kNm]	44	66	100	146	220

¹⁾ The values refer to 1500 rpm.

Mass moments of inertia and weights			Sizes					
			0	1	2	3	4	
Mass moments	of Hub side	J	[kgm²]	0.35	0.76	1.58	3.68	6.56
inertia	torsionally rigid side	J	[kgm ²]	0.86	1.73	3.5	7.1	13.95
Weight at d _{max}			[kg]	132	195	308	468	665

Poros [mm]			Sizes						
Bores [mm]		0	1	2	3	4			
Hub-side	d _{max}	140	170	180	220	240			
Torsionally rigid side	d _{2 max}	140	160	180	210	240			

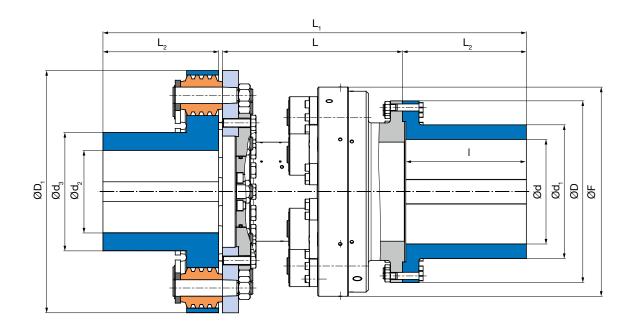
Dimensions			Sizes		
[mm]	0	1	2	3	4
d ₁	186	230	243	300	321
$d_{_3}$	186	215	243	279	321
D	234	292	330	390	430
D ₁	290	332	378	431	492
F	275	320	380	455	545
L	229	245.5	302	316	330
L,	735	811.5	934	1054.5	1173
$L_{_2}$	175	200	225	265	310
L_3	155.6	166	182	208.4	223
L ₄	175	200	225	265	310
l l	171	195	219	260	302

We reserve the right to make dimensional and constructional alterations.

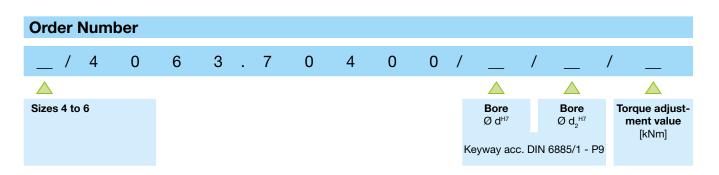
lastic bolt

Type 4063.70400

Sizes 4 to 6







Example: Order number 4 / 4063.70400 / 270 / 180 / 90

Technical Do	4~					Sizes	
Technical Da	Technical Data				4	5	6
Limit torques for	r overload		$M_{\rm G}$	[kNm]	40 - 80	72.5 - 145	130 - 260
Number of EAS®-	elements				12	10	10
Sizes EAS®-elem	ents				1	2	2
Maximum speed	i		n _{max}	[rpm]	1000	900	750
Bolt stroke on o	verload			[mm]	8	12	12
Plantin.	Permitted	axial	ΔK_{a}	[mm]	±4	±4	±4
Flexible shaft coupling	misalign-	radial	ΔK_r	[mm]	1.5	1.5	1.5
ments 1) angular		ΔK_{w}	[mm]	4.6	5.3	6.4	
Nominal and ma	Nominal and maximum torques,		T _{KN}	[kNm]	48	100	160
flexible coupling			T _{K max}	[kNm]	96	200	320

Mass moments of inertia and weights			Sizes				
			4	5	6		
Mass moments of	Hub side	J	[kgm ²]	6.6	20.02	39.63	
inertia	Flexible side	J	[kgm ²]	22.35	55.18	110.68	
Weight at d _{max}			[kg]	706	1407	1956	

Porce [mm]		Size					
Bores [mm]		4	5	6			
Hub-side	d _{max}	240	300	340			
Flexible side	d _{2 max}	225	250	320			

Dimensions		Sizes	
[mm]	4	5	6
d ₁	321	420	500
d ₃	320	360	450
D	430	567	660
D ₁	660	760	920
F	545	640	740
L	375	533	543
L,	946	1201	1231
L ₂	310	350	370
L_3	250	300	300
I	302	342	362

We reserve the right to make dimensional and constructional alterations.

¹⁾ The values refer to 1500 rpm.

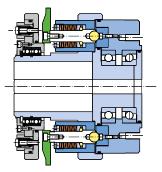
EAS®-HT Options

For the EAS®-HT clutches, designs specially created according to customer requests and different variants are also available.

EAS®-HT clutches can be combined with additional attachment parts.

We are happy to advise you on the dimensioning and configuration of your optimum design.

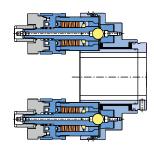
EAS®-HT with automatic re-engagement



After overload occurrence, the EAS®-HT safety clutch is disengaged. It is possible to engage the EAS®-HT safety clutch via remote control by means of automatic re-engagement. Re-engagement can be carried out pneumatically, hydraulically, electromechanically or mechanically.



EAS®-HT with mechanical disengagement

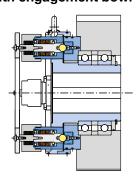


Mechanical disengagement device for the EAS®-elements.

The EAS $^{\otimes}$ -elements can be disengaged individually mechanically.



EAS®-HT with engagement bowl

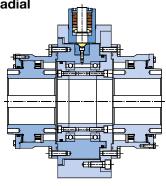


Engagement without aids.

Automatic engagement device for low operating speeds. Direct overload query possible through switching disk.



EAS®-HT radial



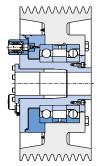
EAS®-HT radial for small construction space length values and low to medium operating speed values.





EAS®-HT Options

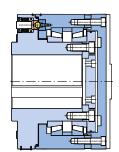
EAS®-HT with integrated drive elements



EAS®-HT, integrated attachment of sprocket and toothed wheels, V-belt disks etc.



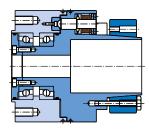
EAS®-HT for roller gears



Highest torques at lowest diameters. The alternative to hydraulic clamping sets and shear pins in rolling mills.



Frictionally-locking shaft-hub connection



Frictionally-locking shaft-hub connections:

- Shrink disk (see Fig.)
- External shrink disk
- Oil press fit

EAS®-HT low temperature design



Reliable overload protection in case of very low temperatures to -48 °C.

(Please contact the manufacturer separately for this).



ATEX design



EAS®-HT safety clutches are also available in ATEX design according to the directive 94/9 EC (ATEX 95).

(Please contact the manufacturer separately for this).



EAS®-element

Application

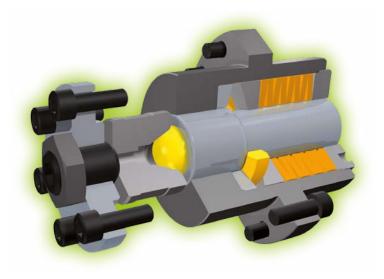
- ☐ EAS®-elements for installation in two bearing-supported flanges facing each other or for integration into existing constructions
- ☐ As EAS®-HT safety clutch component
- ☐ For customer-specific constructions

Applications

- □ Conveyor belts
- □ Crushers
- □ Rolling mills
- ☐ Underground mining / mining
- □ Raw material extraction

Advantages/Benefits

- $\hfill\Box$ Safe overload protection
- ☐ Can be used flexibly and in modular form
- ☐ Maximum performance density
- ☐ Release forces adjustable
- □ Easy and quick engagement
- ☐ Large number of disengagement procedures





Rustproof design available on request

Function:

Positive locking transmission of circumferential force and axial force. In case of overload, the EAS®-elements separate the input and output mechanically, so that the system can slow down freely. Manual re-engagement of the individual elements (automatic reengagement available on request).



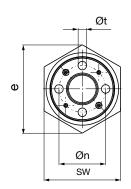
The catalogue contains basic information on pre-selection and dimensioning.

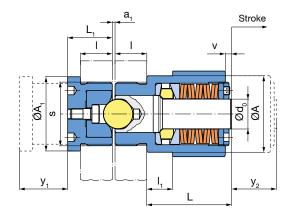
For detailed information on selection, dimensioning, installation, initial operation and maintenance, please see the Installation and Operational Instructions.



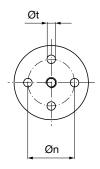
EAS®-element

Standard

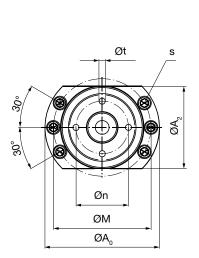


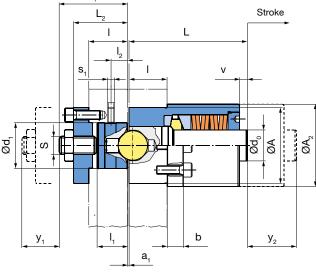


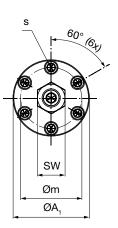
Type 440._04.0 Sizes 02 to 01



Type 440._04.0 Sizes 0 to 2

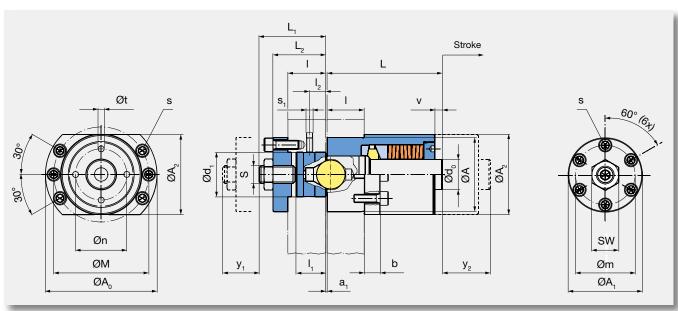






Reinforced

Type 441.604.0 Sizes 0 to 2



EAS®-element

Technical Data				Sizes				
				02	01	0	1	2
Circumferential	Type 440.404.0 (Low torque range)	F _{u min}	[kN]	0.22	1	1.8	5	4
		F _{u max}	[kN]	0.54	2	5	10	11
	Type 440.504.0 (Medium torque range)	F _{u min}	[kN]	0.5	1.25	3.75	7.5	10
		F _{u max}	[kN]	1.4	2.5	7.5	15	30
force	Type 440.604.0 (High torque range)	F _{u min}	[kN]	1.2	2.5	7.5	15	30
		F _{u max}	[kN]	2.5	5	15	30	60
	Type 441.604.0 Reinforced design	F _{u min}	[kN]	-	-	19	38	75
		F _{u max}	[kN]	-	-	38	75	150
Axial force	Type 440.404.0 (Low torque range)	F _{ax min}	[kN]	0.2	0.9	1.62	4.5	3.6
		F _{ax max}	[kN]	0.48	1.8	4.5	9	9.9
	Type 440.504.0 (Medium torque range)	F _{ax min}	[kN]	0.45	1.12	3.37	6.75	9
		F _{ax max}	[kN]	1.26	2.25	6.75	13.5	27
	Type 440.604.0 (High torque range)	F _{ax min}	[kN]	1.08	2.25	6.75	13.5	27
		F _{ax max}	[kN]	2.25	4.5	13.5	27	54
	Type 441.604.0 Reinforced design	F _{ax min}	[kN]	-	-	10	20	40
		F _{ax max}	[kN]	-	-	20	40	80
Bolt stroke on overload [mm]		[mm]	2.5	4	6	8	12	
Weights [kg]		[kg]	0.25	0.6	1.75	4.1	11.3	

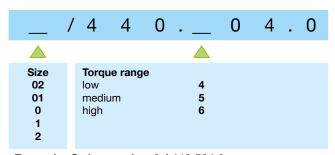
Dimensions			Sizes		
[mm]	02	01	0	1	2
A H8	28	38	55	75	100
A _o	-	-	85	110	150
A ₁	28	35	55	75	100
\mathbf{A}_{2}	-	-	55	75	108
a ₁	1.0	1.5	2	2	3
b	-	-	12	15	20
d _o	10	14	20	30	40.6
d _{1 h7} H8	-	-	30	40	60
е	31.2	41.6	-	-	-
L	28	40	73	96	160
L,	15	21	52	65	80
$L_{\scriptscriptstyle 2}$	-	-	42	51	70
I	12	15	30	40	50

Dimensions			Cinas				
[mm]	Sizes						
Limin	02	01	0	1	2		
I ₁	7	10	22	30	40		
	-	-	12	17	22		
М	-	-	72	95	128		
m	-	-	44	60	80		
n	17	22	31	48	69		
S	-	-	M12	M20	M24		
s	M24x1 1)	M30x1,5 ²⁾	M6 ³⁾	M8 ⁴⁾	M12 ⁵⁾		
S ₁	-	-	M5	M6	M8		
sw	27	36	19	30	36		
t	3	4	5	6	8		
v	2	3	3	4	15		
У ₁ ⁶⁾	12	15	8	10	10		
y ₂ ⁶⁾	16	21	38	50	65		

We reserve the right to make dimensional and constructional alterations.

EAS®-element Standard

Order Number



Example: Order number 0 / 440.504.0

- 1) Tightening torque $M_A = 40 \text{ Nm}$ 2) Tightening torque $M_A = 60 \text{ Nm}$
- 3) Fixing screw DIN EN ISO 4762 10.9 $M_{\Delta} = 9 \text{ Nm}$

EAS®-element Reinforced

Order Number

1 . 6 0 4.0 / 4 4

Size

0

1

2

Example: Order number 0 / 441.604.0

- 4) Fixing screw DIN EN ISO 4762 10.9 $\rm M_A$ = 19 Nm 5) Fixing screw DIN EN ISO 4762 10.9 $\rm MM_A$ = 76 Nm
- 6) y_1 and y_2 are extension dimensions

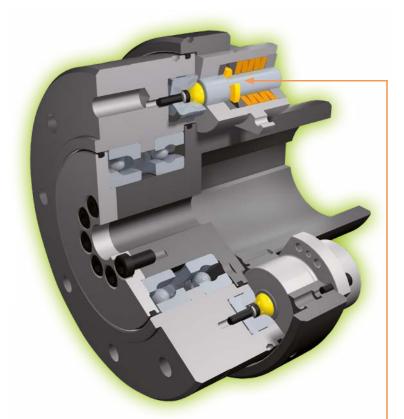


Characteristics

- ☐ Positive locking torque transmission acc. to the ball-detent principle
- ☐ Adjustable torque
- □ Separates disengagingly
- ☐ Easy repeat operation start-up
- ☐ Robust
- ☐ Long service lifetime



Rustproof design available on request



Design

All clutch parts are made of steel. EAS®-HT safety clutch basic components have a zinc-phosphated surface which provides a basic corrosion protection for further surface treatments.

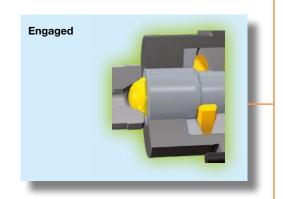
Clutch types 4050, 4060 are also suitable for oil-running.

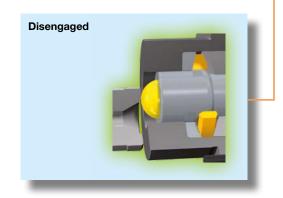
The limit torque for overload on the clutch can be adjusted by changing the cup spring pre-tension of each overload element.

The EAS®-HT safety clutches can be set to the required limit torque for overload at the place of manufacture. Subsequent torque changes can be carried out using the Adjustment Diagram included in the delivery (see respective Installation and Operational Instructions).

Operating principle of the EAS®-HT safety clutch Overload elements

- ☐ If the proportional circumferential force on the individual elements proves too large, the resulting axial force causes an axial movement of the bolt via the ball/calotte system and therefore the disconnection of the torque transmission.
- ☐ The maximum circumferential force is individually determined through the adjusting nut and *mayr*®-cup springs. The transmittable torque is determined in this way.
- Due to the axial stroke of the bolt (ball carrier), the control segments move radially outwards, thereby disconnecting the components axially.
- ☐ Re-engagement of the balls through a bolt stroke in the direction of the calotte takes place either manually or via a mayr® re-engagement device (pneumatic, hydraulic, electromechanical or mechanical).







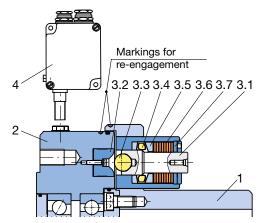


Fig. 2: EAS®-element clutch disengaged

Processes for torque switch-off on overload:

On overload, the hub part 1 and the output flange 2 begin to turn against each other. The bolts 3.1 in the overload elements are pressed via the control segments 3.4 against the force of the cup springs 3.6 from the thrust washers 3.2. The control segments 3.4 travel radially outwards over the bolt 3.1 switching edge and hold the bolts 3.1 in a disengaged position (see Fig. 2). The positive locking connection of the hub part 1 and the output flange 2 is nullified. The originally coupled masses can slow down freely. The drive is switched off electrically via speed monitoring device 4.

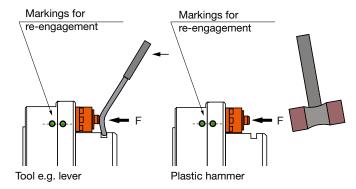


Fig. 3

Re-engagement:

Turn the hub part 1 and the output flange 2 into the correct angular position to one another (re-engagement position can be recognized via the marking bores on the clutch outer diameter, Fig. 3). By applying axial pressure on the bolt end, bolts 3.1 are brought back to their engaged position. The clutch is ready for operation when all clutch overload elements are engaged.

Maintenance

The EAS®-HT safety clutches do not require special maintenance work. They are largely protected against dust and humidity, they have an initial grease filling and are therefore mainly maintenance-free.

EAS®-elements Please find a detailed description in the respective Installation and Operational Instructions (go to www.mayr.com). Special maintenance work may be necessary, however, if the device is subject to large amounts of dirt or dust or is operating in extreme ambient conditions.

In this case, please contact the manufacturer.

Mounting onto the shaft:

In a standard delivery, the EAS®-HT safety clutches are delivered with a finish bore and a keyway acc. DIN 6885/1 P9. The clutch can be secured axially onto the shaft e.g. using a washer and a screw, screwed into the shaft threaded centre hole.

Optionally, we deliver a frictionally-locking shaft-hub connection (see EAS $^\circ$ -HT options, page 19).

Pre-selection of the clutch

Drive lines in heavy engineering are robust and designed for operation in adverse conditions. In contrast to systems with servomotor-driven drives, the torque course and the system behaviour often cannot be determined precisely.

Frequently, only the drive power of the motor and the permitted max. torque of the gear output are known.

Using tried-and-tested operating factors, clutch sizes suitable for the application can be pre-selected.

Pre-selection

$$T_{N} = \frac{9550 \times P}{n}$$
 [Nm]

$$T_{G} \approx T_{N} \times K_{B}$$
 [Nm]

Names:					
T _N	[Nm]	Nominal torque of the motor			
T_{G}	[Nm]	Pre-selected release torque on the overload clutch			
Р	[KW]	Input power motor			
n	[rpm]	Speed			
K _B	[-]	Service factor			

Service factors:					
2.5 - 3	medium impacts	machines / miving systems / conveyor heits /			
3 - 5	high impacts	Shredding machines / centrifuges / crushers / roll trains / construction machines / mining machines / etc.			

In normal operation, the EAS®-HT transmits the set overload torque via positive locking. All torques for normal operation, including torque peaks, must be transmitted safely and must not cause the safety clutch to respond.

Often, the actual complex of loads (impacts) during operation (e.g. for shredding machines / mixers) are not known and can only be measured in the system with great effort.

Using software specially developed for the purpose, it is possible to simulate the behaviour in case of collisions of such drive lines. The prerequisite is that all specifications are known:

- Mass moments of inertia
- ☐ Rigidities of all overload elements, including the overload clutch
- ☐ Parameters of the motor and the control circuit



Particularly in case of load-side vibration generation (e.g. piston compressors / shredding machines / etc.) or alternating torques **please contact us** to select a reliable, tried and tested overload protection for your production systems.

Here, the overload clutch is combined with suitable clutches, depending on the application:

- □ Elastomer coupling
- ☐ Shaft Couplings
- ☐ Curved-tooth coupling

Profit from our many years of market and application experience in different branches.



Misalignment compensation capability of the different shaft misalignment compensation couplings

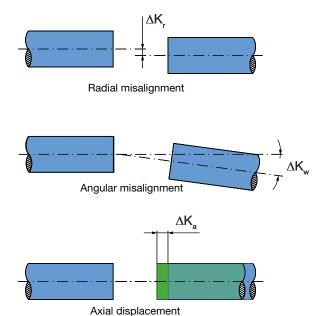


Fig. 4

Shaft Misalignment

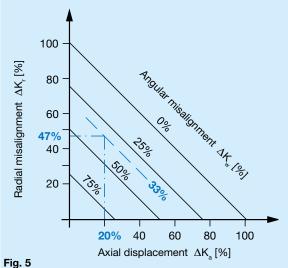
Misalignments between shafts occur due to manufacturing and assembly tolerances, bearing backlash and temperature influences.

This can cause axial, radial and angular shaft misalignment.

The shaft misalignment compensation coupling of the EAS-HT safety clutch can compensate for misalignments.

The misalignment possibilities of the shaft misalignment compensation coupling are general guideline values (see table "Technical Data").

In the application, the aim is to produce as precise a shaft alignment as possible, so that the bearing loads are reduced to a minimum.



If more than one kind of misalignment takes place simultaneously, they influence each other. The permitted misalignment values are dependent on one another. The sum total of the actual misalignments - in percent of the maximum value - must not exceed 100 %.

Example:

EAS®-HT lastic, Size 8 Type 4053.00400.0

- ☐ Axial displacement occurrence: $\Delta K_a = 0.5$ mm; equals **20** % of the permitted maximum value $\Delta K_a = 2.5 \text{ mm}$
- ☐ Angular misalignment occurrence: $\Delta K_{w} = 0.1$ mm, equals 33 % of the permitted maximum value $\Delta K_w = 0.3 \text{ mm}$
- ☐ Radial displacement occurrence: $\Delta K_{w} = 0.14$ mm, equals 47 % of the permitted maximum value $\Delta K_{w} = 0.3 \text{ mm}$

Product Summary

Safety Clutches/Overload Clutches

■ EAS®-Compact®/EAS®-NC

Positive locking and completely backlash-free torque limiting clutches

EAS®-smartic®

Cost-effective torque limiting clutches, quick installation

EAS®-element clutch/EAS®-elements

Load-disconnecting protection against high torques

EAS®-axial

Exact limitation of tensile and compressive forces

■ EAS®-Sp/EAS®-Sm/EAS®-Zr

Load-disconnecting torque limiting clutches with switching function

ROBA®-slip hubs

Load-holding, frictionally locked torque limiting clutches

ROBA®-contitorque

Magnetic continuous slip clutches

■ EAS®-HSC/EAS®-HSE

High-speed safety clutches for high-speed applications

Shaft Couplings

smartflex®/primeflex®

Perfect precision couplings for servo and stepping motors

■ ROBA®-ES

Backlash-free and damping for vibration-sensitive drives

ROBA®-DS/ROBA®-D

Backlash-free, torsionally rigid all-steel couplings

■ ROBA®-DSM

Cost-effective torque-measuring couplings



Electromagnetic Brakes/Clutches

■ ROBA-stop[®] standard

Multifunctional all-round safety brakes

■ ROBA-stop®-M motor brakes

Robust, cost-effective motor brakes

ROBA-stop®-S

Water-proof, robust monoblock brakes

ROBA-stop®-Z/ROBA-stop®-silenzio®

Doubly safe elevator brakes

ROBA®-diskstop®

Compact, very quiet disk brakes

□ ROBA®-topstop®

Brake systems for gravity loaded axes

ROBA®-linearstop

Backlash-free brake systems for linear motor axes

ROBA®-guidestop

Backlash-free holding brake for profiled rail guides

ROBATIC®/ROBA®-quick/ROBA®-takt

Electromagnetic clutches and brakes, clutch brake units

DC Drives

tendo®-PM

Permanent magnet-excited DC motors









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You can find the complete address for the representative responsible for your area under www.mayr.com in the internet.