

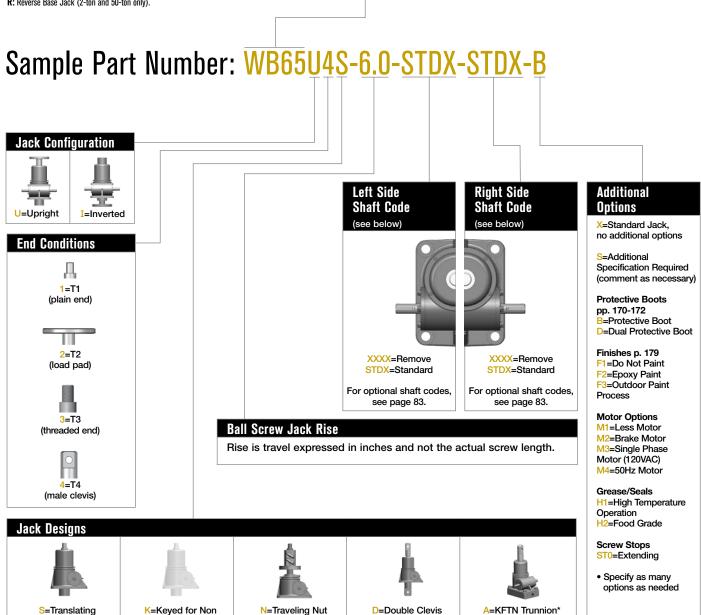
BALL SCREW JACKS ORDERING INFORMATION

Instructions: Select a model number from this chart.

1-Ton Standard	2-Ton Standard	2-Ton Reverse Base Standard	5-Ton Standard	10-Ton Standard	10-Ton Heavy Duty	20-Ton Standard	30-Ton Standard	50-Ton Standard
WBL51 WBL201	WB62 WB122 WB242	RWB62 RWB122 RWB242	WB65 WB125 WB245	WBL810 WBL2410	WB810 WB2410	WB820 WB2420	WB1130 WB3230	WB1150 WB3250
1-Ton Heavy Duty	2-Ton High Lead	2-Ton Reverse Base High Lead	5-Ton High Lead	10-Ton Standard High Lead	10-Ton Heavy Duty High Lead			50-Ton Reverse Base
WB51 WB201	HWB62 HWB122 HWB242	RHWB62 RHWB122 RHWB242	HWB65 HWB125 HWB245	HWBL810 HWBL2410	HWB810 HWB2410			RWB1150 RWB3250

Important Note: *Not self-locking, may lower under load. Brake motors or external locking systems are required.

- H: indicates High lead (2-ton, 5-ton and 10-ton only).
- R: Reverse Base Jack (2-ton and 50-ton only).



^{*}Standard trunnion mounts available on 2-ton through 20-ton jacks. (See page 173)

Rotation**

T=Trunnion'

^{**}Keyed for non-rotation is not a standard option. Contact Joyce/Dayton with your requirements.

BALL SCREW JACKS SHAFT CODES

Instructions: Select the appropriate shaft codes for both right and left hand shafts. One shaft code must be specified for each side of the jack.

Screw Stops (p. 10) and Boots (pp. 170-172)

Screw stops are optional on ball screw jacks. When specified the closed height of the jack and the protection tube length may be increased.

When boots are added to ball screw jacks, the closed height of the jack may be increased.

Geared Potentiometers (p. 176)

POTA=0-10V (IP65)

POTB=4-20MA (IP65)

POTC=0-10V w/2 switches*

POTD=4-20MA w/2 switches*

*Optional IP65 rating available.



Encoders and Electronic Limit Switches

ENCX=Encoder (p. 178)

ELS2=2 Position Electronic Switch

ELS4=4 Position Electronic Switch

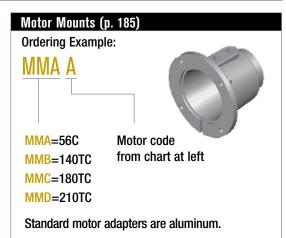
ELS6=6 Position Electronic Switch



Motors for Systems and Direct Drive (p. 185)

- All standard motors are 3-phase, 208-230/460 VAC or 230/460 VAC. Other motor options are available. Specify the appropriate motor size from the chart on the right.
- Refer to the "Additional Options" chart on the preceding page as needed.
- Brake motors (M2) are required for ball screw jacks.
- If the motor frequency will be varied to provide a "soft" start, an inverter duty brake motor may be required.

Motors	
Size	Code
1/4 HP	K
1/3 HP	Α
1/2 HP	В
3/4 HP	С
1 HP	D
1-1/2 HP	Е
2 HP	F
3 HP	L
5 HP	G
7-1/2 HP	Н
10 HP	I
15 HP	J



Mechanical Limit Switches (pp. 174-175)

Ordering Example: LA13

Models	
Model	Code
LS7-402	LI
LS8-402	LA
LS8-404	LB
LS9-502	LC
LS9-503	LD
LS9-504	LE
LS9-505	LF
LS9-506	LG
LS9-507	LH

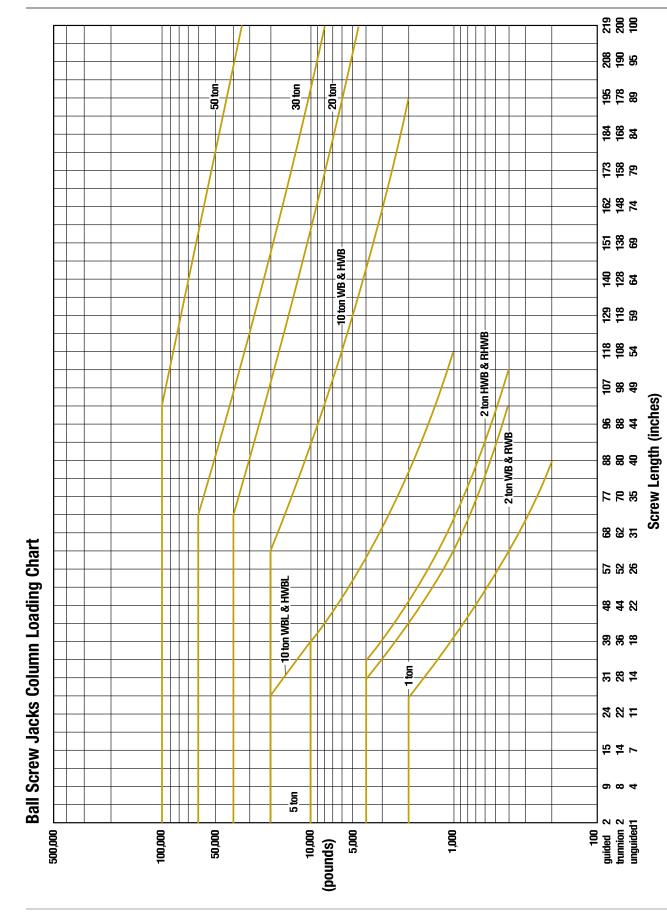
Number of DPDT Switches (see p. 175)

NOTE: Will always be 0 for LS7 models

Available	e Positions	6						
	1 2*		3 4		5	6*	6* 7	
Left Side Shaft Options								
Right Side Shaft Options								

- 2, 5, 10, 15, and 20 Ton ball screw jacks are available with positions #1, #3, and #5.
- 30-ton and 50-ton ball screw jacks are available with positions #1, #4, #7 and #8.
- *These positions are not standard. Contact Joyce/Dayton with your requirements.

BALL SCREW JACKS COLUMN LOADING



This chart includes a 2:1 Factor-of-Safety based on the Euler-Johnson equation for column loading (Oberg, Erik et al: Machinery's Handbook, 24th Edition. c. 1992 Industrial Press Inc.)
The horizontal portion of each line represents the jack's maximum dynamic capacity. Under static conditions, these lines can be exceeded. Please contact factory for assistance.

BALL SCREW JACKS SPECIFICATIONS

Model	Capacity	Screw Diameter (Inches)	Thread Pitch/Lead	Worm Gear Ratio	Worm Shaft Turns for 1" Travel	Torque	Starting Torque (Inch Lbs.)	Operating Torque (Inch Lbs.)	Efficiency Rating % Approx	Screw Torque (Inch Lbs.)	Worm Holding Torque	Ball Nut Life at Rated Load (Inch Screw Travel x 1000)	Basic Jack Weight (Lbs.)	Jack Weight per Inch Travel (Lbs.)
WBL51				5:1	25	3	.014W*	.012W* @ 500 RPM	51.7	.035W*	.006W*	100		(2.50.)
WBL201	4 4	0.44	0.2	20:1	100		.005W*	.004W* @ 500 RPM	38.5		.002W*	108		0.05
WB51	1 ton	3/4		5:1	25	3	.014W*	.012W* @ 500 RPM	51.7	.035W	.006W*	050	8	0.25
WB201				20:1	100		.005W*	.004W* @ 500 RPM	38.5		.002W*	858		
(R)WB62				6:1	24		.015W*	.013W* @ 500 RPM	52.1	.044W*	.007W*			0.4
(R)WB122			0.25	12:1	48		.009W*	.007W* @ 500 RPM	47.2		.004W*	642		
(R)WB242				24:1	96		.006W*	.004W* @ 500 RPM	39.3		.002W*			
(R)HWB62	2 ton	1		6:1	6	4	.064W*	.051W* @ 500 RPM	52.1		.033W*		18	
(R)HWB122			1.0	12:1	12	-	.039W*	.028W* @ 500 RPM	47.2	.177W*	.020W*	190		
(R)HWB242				24:1	24		.028W*	.017W* @ 500 RPM	39.3		.014W*			
WB65		1 1/2 -	0.474	6:1	12.66		.030W*	.025W* @ 300 RPM	51.1	.084W*	.013W*	1015	42	0.7
WB125				12:1	25.33		.019W*	.014W* @ 300 RPM	45.7		.007W*			
WB245				24:1	50.66		.013W*	.008W* @ 300 RPM	37.2		.004W*			
HWB65	5 ton		1.0	6:1	6	10	.065W*	.052W* @ 300 RPM	51.1	0.177W*	.033W*	512		
HWB125				12:1	12		.041W*	.029W* @ 300 RPM	45.7		.020W*			
HWB245				24:1	24		.029W*	.018W* @ 300 RPM	37.2		.014W*			
WBL810				8:1	16.88	20	.022W*	.019W* @ 200 RPM	50.7	.084W*	.010W*			0.9
WBL2410		1 1/2	0.474	24:1	50.66		.010W*	.008W* @ 200 RPM	40.3		.004W*	127	- 58	
HWBL810	10 ton		1.0	8:1	8		.047W*	.039W* @ 200 RPM	50.7		.024W*			
HWBL2410				24:1	24		.024W*	.016W* @ 200 RPM	40.3		.012W*	64		
WB810		2	0.5	8:1	16		.023W*	.019W* @ 200 RPM	50.7	.088W*	.009W*		62	1.4
WB2410				24:1	48		.011W*	.008W* @ 200 RPM	40.3		.003W*	729		
HWB810	10 ton			8:1	8	20	.047W*	.039W* @ 200 RPM	50.7	.177W*	.018W*			
HWB2410			1.0	24:1	24		.023W*	.016W* @ 200 RPM	40.3		.006W*	1423		
WB820		2 1/4 0.5	8:1	16		.024W*	.020W* @ 200 RPM	47.4		.009W*				
WB2420	20 ton		0.5	24:1	48	40	.012W*	.009W* @ 200 RPM	35	.088W*	.003W*	121	105	2.6
WB1130	30 ton 3	_		11:1	16.67	60	.027W*	.020W* @ 200 RPM	48	.117W*	.009W*			3.2
WB3230		3	0.66	32:1	48.48		.016W*	.009W* @ 200 RPM	35		.003W*	343	220	
(R)WB1150				11:1	11	100	.038W*	.029W* @ 200 RPM	49.3	.177W*	.013W*			
(R)WB3250	50 ton	4	1.0	32:1	32		.020W*	.012W* @ 200 RPM	37.5		.005W*	614	460	4.8

Important Note: Ball Screw Jacks are not self-locking. Brake motors or external locking systems are required.

(R): Reverse Base Jack.
*W: Load in pounds.

Tare Torque: Initial torque to overcome seal and normal assembly drag. This value must be added to starting torque or operating torque values.

Starting Torque: Torque value required to start moving a given load (dissipates to operating torque values once the load begins moving).

Operating Torque: Torque required to continuously raise a given load at the input RPM listed.

Note: If your actual input RPM is 20% higher or lower than the listed RPM, please refer to our JAX® program to determine actual torque values at your RPM.

Screw Torque: Torque required to resist screw rotation (Translating Design Jacks) and traveling nut rotation (Keyed for Traveling Nut Design Jacks).

Worm Holding Torque: Torque required to prevent input shaft (worm) from backdriving.

Lead: The distance traveled axially in one rotation of the lifting screw.

Pitch: The distance from a point on a screw thread to a corresponding point on the next thread, measured axially.

