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Other algorithms: LDA, Polynomial expansion

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#### Starting point :

- Outcome measurement Y (also called dependent variable, response, target, label);
- Vector of p predictor measurements X<sub>i</sub> (also called inputs, regressors, covariates, features, independent variables). X is a matrix of dimension (N,p), where N is the number of measurements;
- In the regression problem, Y is quantitative (e.g price, sales, categories, blood pressure);
- We have training data  $(x_1, y_1), ..., (x_N, y_N)$ . These are observations (examples, instances) of these measurements.



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#### Linear Regression model with one variable

- Pattern / Model :  $Y_i = \beta_0 + \beta_1 X_i + \epsilon_i$  for  $0 \le i \le N$  $Price_{house30} = \beta_0 + \beta_1 Surface_{House30} + \epsilon$
- In fact, we could imagine the price depends from severals factors, so we come with Linear Regression with several variables:

$$Price_{house30} = K + \beta_1 Surface_{House30} + \beta_2 NbOfRooms_{House30} + \beta_3 Location_{House30} + \epsilon$$

• In general :

$$Y_i = h(X^i) = \beta_0 + \beta_1 X_{i,1} + \beta_2 X_{i,2} + \dots + \beta_i X_{i,p} + \epsilon$$

 Traditionally p is called the number of features. We will use matrix notation, so there will be double indices.



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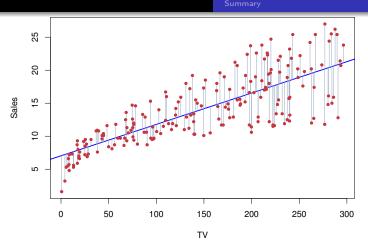


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Sales  $\approx \beta_0 + \beta_1 TV$ 



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- The parameters in the linear regression model are very easy to interpret.
- $\beta_j, 1 \leq j \leq p$  is the average increase in Y when  $X_j$  is increased by one and all other  $X_i$  are held constant.
- Vocabulary :  $\beta_0$  is the intercept (i.e. the average value for Y if all the Xs are zero),  $\beta_j$  is the slope for the jth variable  $X_j$

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- Historical method : Least Square Regression ;
- Modern method: numerical iterative process: gradient descent and a huge family of similar algorithms (Maths: (Numerical)(Convex or not) Optimization.

Cost function, traditionally noted  $J(\beta)$  is given by :  $J(\beta) = \frac{1}{2N} \sum_{i=1}^{N} (h(X^i) - Y_i)^2$ 

Recall naming and indices are not universal, you will find sometimes n instead of N or p, or m instead of N, etc.

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- We want to minimize the quantity  $\sum_{i=1}^{N} (h(X^i) Y_i)^2$  called MSE Mean Square Error
- Solution in one dimension : write partial derivatives in  $\beta_0$  and  $\beta_1$  of the cost function. To be done
- Solution in p dimension : Matrix

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• In one dimension you will derive a 2x2 linear system :

$$\begin{cases} \beta_0 \sum_{i=1}^{N} x_i & +\beta_1 \sum_{i=1}^{N} x_i^2 = \sum_{i=1}^{N} x_i y_i, \\ N\beta_0 & +\beta_1 \sum_{i=1}^{N} x_i = \sum_{i=1}^{N} y_i. \end{cases}$$

- To recall : you can shift the variables  $(x_i, y_i)$  to be centred on the mean, new variables  $(\bar{x_i}, \bar{y_i})$ , verifies  $\sum_i \bar{x_i} = 0$ ,  $\sum_i \bar{y_i} = 0$  it gives directly the well-known slope coefficient  $\beta_1 = \frac{\sum_{i=1}^N \bar{x_i} \bar{y_i}}{\sum_{i=1}^N \bar{x_i}^2}$
- Solution in p dimensions : Matrix X including a column vector of 1, verify  $(X^TX)\beta = X^TY$  gives  $\beta = (X^TX)^{-1}(X^TY)$  assuming that the square matrix  $X^TX$  is invertible. This is the **Normal Equation**.



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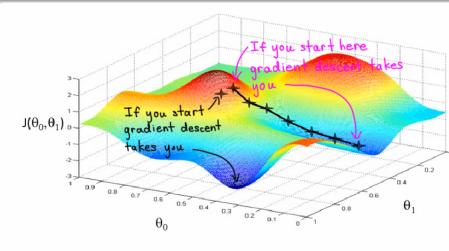
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- Levels on a curve or surface, directions of steepest descent
- Stochastic approach steps :
  - Initialize  $\beta_0$ ,  $\beta_1$ , ...  $\beta_p$
  - Compute the new direction :  $\beta_j := \beta_j \alpha_j \frac{\partial J(\beta)}{\partial \beta_j}$  , for j = 0, ..., p
  - Evaluate  $J(\beta)$  and iterate
- Compare the complexity of the 2 methods

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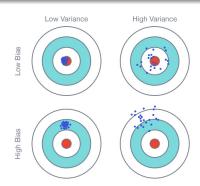
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### Bias-Variance definition

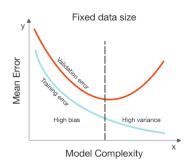


- Informal definition
- So-called Bias-Variance trade-off



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#### Train vs Test set error

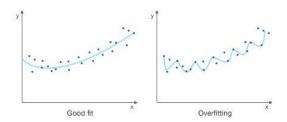


Graphical model tuning



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# Overfitting



• Polynomial expansion (chapter Beyond Linearity)

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- LDA
- Polynomial expansion : beyond the linearity (another chapter)

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- Linearity is a limitation but solving principles are more general;
- Introducing complexity/flexibility of a model vs interpretability

