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VarioStack[™] Functional Description

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Revision History

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		Added component specs in Appendix B	
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		Added remaining safety component specs	
		Added light curtain distance calculation	
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1. System Overview

1.1 Purpose of VarioStack[™] Workstation

The primary purpose of VarioStackTM is to facilitate the manual process of transferring incoming goods from the original packaging into totes that can be used for conveyance to a storage location. To accomplish this, VarioStack must provide:

- 1. Stable surface for the operator to place the package
- Access to accessories such as thin client computer, monitor, and hand-scanner for entering tote and item data into customer's computer system. Note VarioStack does not include these items, but must provide proper mounting and power accommodations.
- 3. Provide an ergonomic placement of an empty tote to be filled by the operator.
- 4. Manual interface to allow the operator to push the empty tote onto a take-away conveyor.

Figure 1 below depicts an overview of this operation within a customer facility. Notice that a pair of operators are working at a dual-sided workstation. Multiple dual stations (not

shown) would be located along the same "Incoming Packages" conveyor shown in the figure.

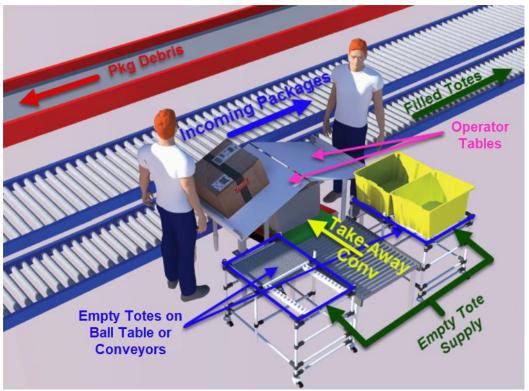


Figure 1. System Overview

Note: The figures in this section are used only to describe the functionality of the system. The system shown is a model of a previously developed prototype and was not developed by Siemens.

Typically, the operator must perform the following tasks.

- 1. Retrieve package from an incoming conveyor
- 2. Open the package
- 3. Scan the license plate on the tote (See Figure 2). This task may be automated using a static mounted scanner over the empty totes.
- 4. Scan the 1st item from the package and place it in the tote.
- 5. Repeat until the tote is full.
- 6. Push the full tote onto the take-away conveyor.
- 7. Place the empty packaging onto the package debris conveyor
- 8. VarioStack should present a new empty tote to the operator and the cycle should repeat.

This description is simply to better understand the purpose of the workstation. The actual workflow of the operator may vary.





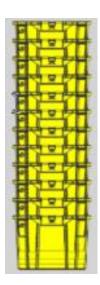


Figure 3. Stack of nested totes

The secondary purpose of VarioStack is to reduce the manual handling of empty totes by converting a stack of up to twelve nested totes to sequentially fed individual totes presented to the operator as needed. Figure 3 shows how these totes nest within each other when stacked properly.

VarioStack is currently designed for tote sizes of approximately 600mm wide x 400mm long x 272mm deep. Because VarioStack interfaces with the tote handles, the dimensions illustrated below are also required. Minor customization to VarioStack may allow compatibility with other tote sizes.

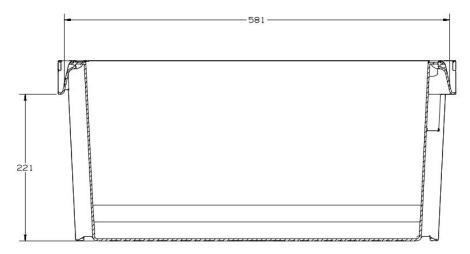


Figure 4. Tote Handle Dimensions (mm)

Two more modules are included with VarioStack to manage the tote stacks: the Buffer Module and the Destacker Module (see Figure 5). Together, these two modules provide automatic replenishment of empty totes to the operator.

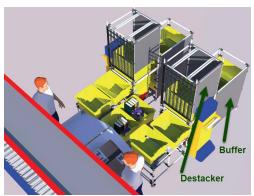


Figure 5. Empty Tote Supply: Buffer and Destacker

2. External Interfaces – Site Requirements

Prior to installing VarioStack within the customer site, the following infrastructure must be in place.

2.1 Power Drop:

2.1.1 Power Requirement:

Each VarioStack will require a drop for each control cabinet (Two cabinets per dual sided workstation)

208Y120 ±10% VAC, 60 Hz, 3-phase, 5 wire (L1, L2, L3, N, G)

The full load amps (FLA) required for each leg of the supply power are shown below:

LOAD FLA	<u>L1</u>	<u>L2</u>	<u>L3</u>
System DC Power Supply	3.9		3.9
DC Roller Power Supply		3.9	3.9
Servo Power Supply	9.3	9.3	
Convenience Outlet			8
Total	13.2	13.2	15.8

Table 1. Full Load Amps

With the assumptions above, each control cabinet is capable of pulling just below 16 Amps. Therefore, a 20A service is required.

2.1.1.1 Power Drop Location:

VarioStack will include a power cord for each unit (2 per dual sided workstation). On the workstation side, the cord will connect to the Power Inlet Enclosure and lay in the cable trough shown below.

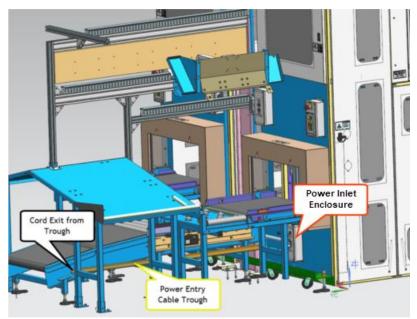


Figure 6. Power Cord Location



Figure 7. Power Inlet Enclosure

The Power Inlet Enclosure shown above is the central location for all external interfaces to VarioStack. This box includes connections to:

- Power cord (provided with VarioStack)
- o External ethernet connection
- Dry contact M12 connections for safety signals.

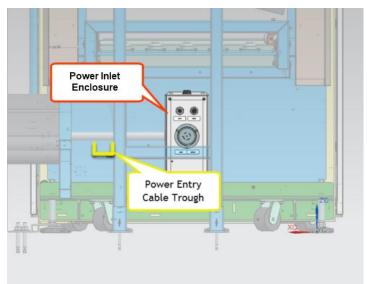


Figure 8. Power Inlet - Front View

2.1.1.2 Power Drop Receptacle/Plug

The site power drop should include following receptacle (not included with VarioStack) for powering each workstation (two per dual workstation). After VarioStacks are installed, the power cord will be connected to this receptacle to provide station power.

Receptacle:

20 Amp, 208Y120 Twist Lock Receptacle is a NEMA type L21-20R



Figure 9. Power Connection Plug provided at customer site

This receptacle should be installed onsite prior to VarioStack installation. It should be located within range of the power cord in the approximate area shown in the figures below, within 20" of the end of the cable trough.

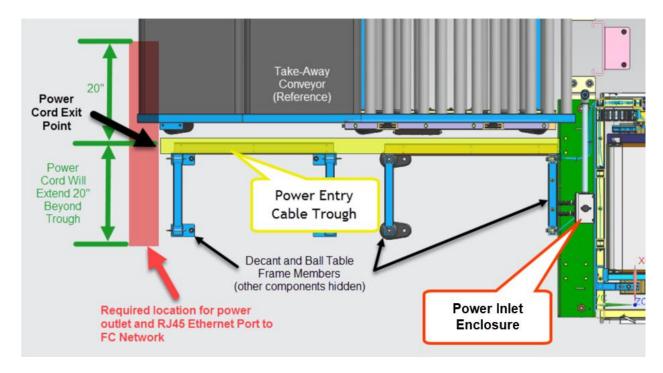


Figure 10. Power Drop - Top View

The power cord (provided with VarioStack) will include the following plug to connect to the site outlet:

20 Amp, 208Y120 Twist Lock Plug is a NEMA type L21-20P (load device)



Figure 11. Power cord plug included with VarioStack

2.1.2 External Dry Contacts

Dry contact connection points will be provided in each VarioStack unit to provide an external electrical interface for the signals below.

2.1.2.1 Signal Descriptions

- VarioStack Safety Input
 - § Purpose: Input signal to each workstation that a higher level e-stop has been initiated. The workstation will treat this input internally as it would

any safety rated signal and bring the machine to a safe, immediate stopped state.

VarioStack Safety Output

§ Purpose: Notify downstream controllers that one of the E-Stop buttons on the workstation has been pressed. Once an E-Stop is triggered, this signal will not be reset until the "Reset" button is pressed on the station's control panel.

VarioStack Enabled

§ Purpose: Output signal from the workstation to notify downstream systems that the workstation is starting. If the site chooses, this signal could be used to start the downstream conveyor line when any workstation is enabled. Alternatively, if no workstations are running, the downstream conveyors can be disabled.

These contacts will be available for each unit (two sets per dual sided workstation)

2.1.2.2 Dry Contact Specification

Contact type	1 PDT
Type of switch contact	Single contact
Contact material	AgNi
Maximum switching voltage	250 V AC/DC (The separating plate PLC-ATP should be installed for voltages larger than 250 V (L1, L2, L3) between identical terminal blocks in adjacent modules. Potential bridging is then carried out with FBST 8- PLC orFBST 500)
Minimum switching voltage	12 V DC (at 10 mA)
Min. switching current	10 mA (at 12 V)
Maximum inrush current	30 A (300 ms)
Limiting continuous current	10 A
	6 A (value applies to connections 12. If connections 12 are bridged, the normal value applies.)
Interrupting rating (ohmic load) max.	240 W (at 24 V DC)
	58 W (at 48 V DC)
	48 W (at 60 V DC)
	50 W (at 110 V DC)
	80 W (at 220 V DC)
	2500 VA (for 250 V AC)
Interrupting rating (ohmic load) max. bridged	144 W (for 24 V DC. Value applies to connections 12. If connections 12 are bridged, the normal value applies.) 1500 VA (for 250 V AC. Value applies to connections 12. If connections 12 are bridged, the normal value applies.)
Switching capacity	2 A (at 24 V, DC13)
	0.2 A (at 110 V, DC13)
	0.2 A (at 250 V, DC13)
	6 A (at 24 V, AC15)
	6 A (at 120 V, AC15)
	6 A (at 250 V, AC15)

Table 2. Dry Contact Specification

2.1.2.3 M12 Dry Contact Connections

Each workstation will provide one male and one female M12 connection at the Power Inlet Enclosure. The figure below shows these connectors:



Figure 12. VarioStack Dry Contact Connections

The first connector, CON1 includes the outputs from the station (wiring instructions will be shown below):

- o VarioStack Safety Output
- VarioStack Enabled

The other connector, CON2, includes the safety input to the station, "VarioStack Safety Input".

Below are excerpts from the VarioStack station electrical schematics that define this interface:

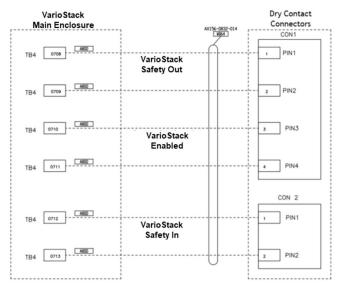


Figure 13. VarioStack Interconnect Diagram - External Interface

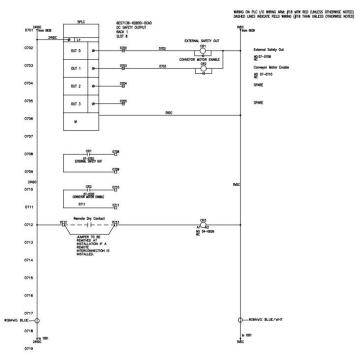


Figure 14. VarioStack Main Panel Schematic - External Interfaces

The site integrator is responsible for providing cables for this interface that are connectorized with the mating M12 connectors. The connectors are defined in the picture below:



Figure 15. Dry Contact Connectors

During installation, these cables can be installed in the Power Inlet Cable Trough, along with the Power Entry Cord. From the "Power Cord Exit Point" location in Figure 10, a minimum cord length of 87" will be required to reach the connection points on the Power Inlet Enclosure.

2.1.3 Site Level Data Interface

The VarioStack controller will be able to report status to the customer site network. A standard RJ45 TCP/IP connection must be provided for this purpose.

For this connection, the workstation provides an Ethernet port as shown below:



Figure 16. Ethernet Connections To Power Entry Enclosure

The site integrator should provide a standard CAT6 cable to this port, routed alongside the power cord described in the previous section.

2.1.3.1 IP Addresses

VarioStack will include an HMI screen to allow on-site maintenance technicians and customer IT specialists to set the IP address for the station.

2.1.3.2 Shared Tags

Each VarioStack will provide a data block which can be accessed through the Ethernet interface using standard OPC UA architecture. This datablock will be called "dbPublicHMI_Statistic[DB25] and will contain status tags for:

- o Statistics (See below)
- o Error Tags
- o PackML Data
- o "Overall Equipment Effectiveness" (OEE) data

These statistics are available on the workstation HMI and included in the public tags:

Statistic	Units	Description
State	Machine State	Possible Values: § E-Stop § Fault § Idle § Initialize § Running
		<u>Throughput</u>
Run - Avg	Totes/Minute	Average runtime throughput (since last Reset Statistics). Defined as Totes Out / Runtime (described below).
Run – Max	Totes/Minute	Maximum runtime throughput (since last Reset Statistics)
Unconstrained – Avg	Totes/Minute	Average un-constrained runtime throughput. Defined as Totes Out / Unconstrained time (described below)
Unconstrained – Max	Totes/Minute	Maximum un-constrained runtime throughput (since last Reset Statistics)
		<u>Piece Counts</u>
Totes Out	Totes	Count of totes exiting the machine (since last Reset Statistics). Specifically, counter increments upon completion of successful tote transfer from the Destacker to the Exit Conveyor.
Stacks In	Tote Stacks	Count of tote stacks entering the machine (since last Reset Statistics). Specifically, counter increments upon completion of successful stack transfer from Buffer 1.
		Operational Times
Total	Minutes	Total elapsed minutes since last Reset Statistics.

E-Stop	Minutes	Total time spent in E-stopped condition (since last Reset Statistics) prior to associate pressing Reset button. E-Stop time starts when an E-Stop or Interlock (door open, etc) is detected;	
Fault	Minutes	Total time spent in Fault condition (since last Reset Statistics) prior to associate pressing E-Stop, triggering Interlock, or pressing Reset button.	
Idle	Minutes	Total time spent in idle condition (since last Reset Statistics). Idle time starts when machine wakes up without fault/estop detected, when machine is taken from Fault or E-Stop condition by associate pressing Reset, or when machine is Stopped while running by associate. It ends when Run is pressed.	
Init	Minutes	Total time spent initializing e.g. homing of lifts, etc (since last Reset Statistics). Idle time starts when Run is pressed and ends upon ejection of first tote from Destacker.	
Runtime	Minutes	Total time spent in Running state (since last Reset Statistics). Runtime starts when initializing is completed, and ends when operator presses Stop, or a Fault or Estop is detected.	
Op Starved	Minutes	Total time (since last Reset Statistics) that the Operator of the DOWNSTREAM equipment was starved, inhibited from being productive: i.e. Ball Table was empty, but Exit Conveyor had no tote yet in place ready to transfer. This is a Key Performance Indicator from a Plant Operations point of view.	
Starved	Minutes	Total time spent in Starved state (since last Reset Statistics). That is, VarioStack was prevented from being productive due to lack of available incoming product. Starved time starts when machine is running, Destacker conveyor is in low position ready to accept a tote-stack, but Buffer 2 has none yet in place ready to transfer. Starved time ends upon start of stack transfer from Buffer 2 onto Destacker, or when Run state is ended (e.g. Stop, E-Stop, Fault, etc.)	
Blocked	Minutes	Machine ready to discharge (specifically Destacker ready to eject next tote onto Exit Conveyor), but blocked from downstream being not ready (specifically, Exit Conveyor is not yet ready to receive – transferring to or waiting on Ball Table)	
Held	Minutes	Total time spent being inhibited from productive operation by lack of timely operator action (since last Reset Statistics). Specifically, Destacker Lift was prevented from moving because the buffer entry light curtain had been breached and operator failed to press start button. Held time	

		starts when machine is running, and the lift is ready to move, but prevented to do so by a buffer entry light curtain breach. Held time ends upon pressing start button on Buffer OCP, or when Run state is ended (e.g. Stop, E-Stop, Fault, etc.)
Unconstrained	Minutes	Total Runtime when machine was able to operate productively, unconstrained by being Starved, Blocked, or Held (see above).

Table 3. Definition of Statistics

3. VarioStack Design

3.1 Sub-Modules

The major components of VarioStack are:

Buffer Module

This module accepts stacks of incoming totes. It is typically loaded manually by another operator referred to as the tote handler in this document. The buffer module can hold two stacks of empty totes and each stack can include up to twelve totes.

Destacker Module

The destacker will accept a stack of totes. When necessary, it will automatically pull the bottom tote from the stack and convey it to the next module.

Exit Module

This module provides placement for up to two totes at any given time. In one position, the operator will be placing items into the tote. This position must therefore be ergonomically located near the operator. When the tote is full, the operator will push it onto the takeaway conveyor, leaving the load position open. The other tote position on this module includes an active conveyor. When the load position is empty, the conveyor drives another tote into its position. The destacker is then triggered to eject another empty tote onto the conveyor, where it is buffered until needed at the load position.

Operator Table

This module is simply to support a package of incoming goods while the operator is loading the tote. This table also provides a location for the operator to store the hand held scanner. There are no active components on this module.

Beyond the major components, the workstation will also include:

- · Safe, intuitive interface to the operator and the tote handler
- Control panel for electrical housing
- Mounting provisions for thin client, keyboard, monitor, and hand-scanner.

TakeAway Conveyor

VarioStack will provide space for a takeaway conveyor between the two units in a dual station layout. The takeaway conveyor is not included as a component of VarioStack. It is a part of the downstream conveyor system and has a simple mechanical interface to

VarioStack. The takeaway conveyor should be no longer than 72" and no wider than 28" as shown in the figure below:

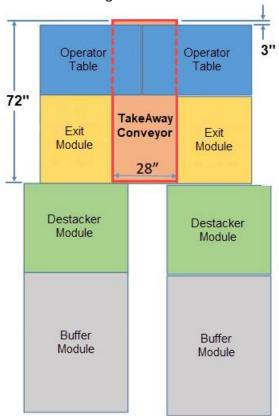


Figure 17. Takeaway Conveyor Max Dimensions

3.2 Layout

As necessary, each submodule within VarioStack will exist in a left-handed and right-handed version. However, all attempts have been made to ensure individual parts on both versions are identical or exact mirror images of each other. Frames, for example, will likely include extra holes to allow components to be assembled on either side, depending on left or right version.

Figure 18 and Figure 19 below define the mechanical layout of the workstation and it's submodules. Figure 20 shows some basic dimensions with a standard layout of a left and a right handed workstation.

Decant Workstation

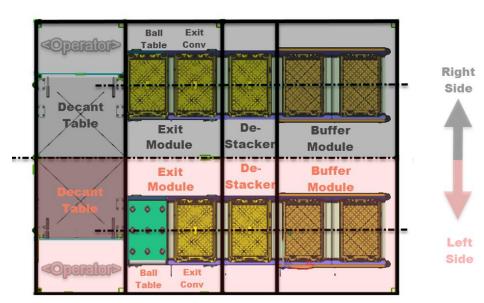


Figure 18. Top View Layout

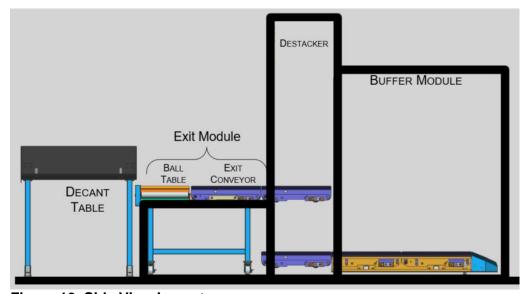


Figure 19. Side View Layout

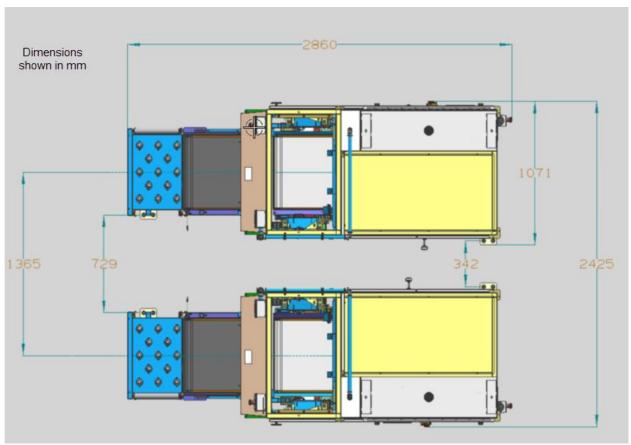


Figure 20. Dimensioned Top View Layout

3.3 Safety System

This section describes the high level concept the safety system and related hardware components. Detailed specifications of individual components can be found in Appendix B – Section 10 of this document.

3.3.1 Safety PLC and Safety I/O

Component descriptions of the PLC and I/O modules provided in this section were taken directly from Siemens online brochure:

https://w3.siemens.com/mcms/distributed-io/en/ip20-systems/et-200sp/failsafe-io/pages/default.aspx



Figure 21. Siemens ET200SP Fail-Safe CPU (6ES7512-1SK01-0AB0)

- The fail-safe SIMATIC controllers enable the processing of standard and safety programs on a single controller.
- The CPU 1512SP F fail-safe controllers are extended standard ET 200SP CPUs.
- They are certified according to EN 61508 (2nd Edition) for functional safety and are suitable for use in safety-related applications up to SIL 3 according to IEC 62061 and PL e according to ISO 13849.
- The CPUs 1512SP F can be expanded both centrally with standard and fail-safe ET 200SP modules, and distributed via PROFINET/PROFIsafe with any ET 200 systems.

3.3.1.1 Fail-safe digital input module (F-DI)



Figure 22. PROFINET Safety Input Module (6ES7136-6BA00-0CA0)

- F-DI 8x24VDC High Feature
- 8 fail-safe inputs (SIL 3, PL e)
- Integrated discrepancy evaluation with 2v2 signals
- · Devices connected:
 - o E-Stops
 - Safety Interlocks (detects present of doors and critical frames)
 - Safety Light Curtains
 - External Safety In Signal 24V dry contact signal from external system. Used to trigger safety stop when other adjacent equipment is E-Stopped as deemed necessary by customer or integrator Safety teams

3.3.1.2 Fail-safe digital output module (F-DQ)

- F-DQ 4x24V DC/2A PM High Feature
- 4 fail-safe outputs
- · 2-channel F-control (P/M-switching) of actuators up to 2A
- Devices connected:
 - External Safety Out signal 24V dry contact signal to external system. Used to trigger safety stop of other equipment located adjacent to VarioStack as deemed necessary by necessary by customer or integrator Safety teams
 - Conveyor Motor Enable Provides safe shut down of all VarioStack conveyor motors.



Figure 23. . PROFINET Safety Output Module (6ES7136-6DB00-0CA0)

When any device connected to one of the 8 inputs of the F-DI (safety input) module is activated, the following actions will occur to ensure a safe shutdown of the VarioStack unit.

- All devices connected F-DQ (safety output) module will immediately drop power.
 - Conveyor motors stop
 - External dry contact sends the safety E-Stop signal to any external devices connected to it.
- The Lift motor controller will immediately receive the STO command (described below) and will come to an immediate controlled stop.

3.3.2 PROFIsafe and PROFIdrive

PROFIsafe is a comprehensive network-based safety communication technology suitable for safety functions up to SIL3 according to international standard IEC 61508 and IEC 61784-3-3. PROFIsafe uses a standard communication fieldbus (Ethernet) and implements the following safety measures to ensure safe, reliable operation:

- The consecutive numbering of the PROFIsafe messages ("sign-of-life")
- A time expectation with acknowledgement ("watch-dog")

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- A codename between sender and receiver ("F-Address")
- Data integrity checks (CRC = cyclic redundancycheck)

PROFIsafe will enable VarioStack to safely and reliably shut off all safety outputs when any safety input is activated or fails.

The safety PLC will communicate safety signals to the Lift motor controller via PROFIdrive. PROFIdrive safety features are defined IEC 61800-5-2 for drives with integrated safety. The two PROFIdrive features used on VarioStack are:

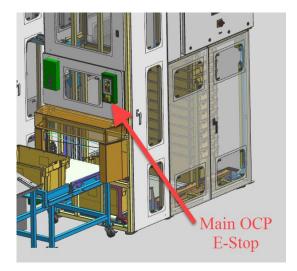
3.3.2.1 Safe Torque Off (STO)

- When STO is activated, a brake is applied and the torque power cannot reach the drive (de-energize), thus stopping and preventing any motor shaft rotation
- The STO will not be cleared from the lift until the operator presses the "Reset" push button on the Buffer OCP.

3.3.2.2 Safe Operating Stop (SOS)

- When SOS is activated, the controller can use the full torque power available to bring the motor to a stop.
- The drive will have a set time to stop and will then monitor to ensure it holds position.
- The SOS will remain in effect until the safety PLC clears it (after verifying the safety concern is gone).
- As long as the drive stops and remains stopped, the drive will not fault out.
 However, if the drive fails to stop within the allotted time, or does no hold position, the drive will respond with an STO (as previously described) and will fault.

3.3.3 E-Stop buttons



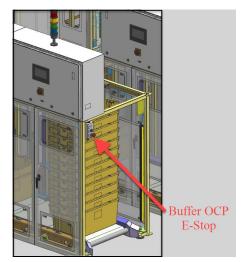




Figure 24. E-Stop and E-Stop Locations

VarioStack has an E-Stop on each end of the machine. The E-Stop on the Main OCP is to be within reach distance (36 inches) to the operator. The Buffer OCP E-Stop is located next to the tote stack entry doorway for use by the tote loader.

Device Description:

EMERGENCY STOP mushroom pushbutton, illuminable, 22 mm, round, metal, shiny, red, 40 mm, **positive latching**, acc. to EN ISO 13850, **rotate-to-unlatch**. Protection class to IP67.

There are 2 E-Stop pushbuttons: one on the Buffer Entry Operator Panel and another on the Main Operator Panel. Both E-Stop signals will be connected to the Fail-safe digital input module (F-DI) and will therefore trigger fail-safe response from the control system. The E-Stop triggers STO to Lift servo and turns off all safety outputs (conveyor motors and external dry contact). All motion will stop immediately. These inputs also trigger the external safety output signal to be off and potentially cause an E-Stop condition on surrounding systems (depending on site implementation).

The E-Stop state is not cleared until all E-Stop buttons are twisted back to normal position. The machine will not restart until the operator presses the Reset button on the main control panel and the Start button. At startup, the safety horn will sound.

3.3.4 Safety Interlocks

VarioStack provides two doors on the Buffer Module and one on the Destacker Module to allow for simple access for clearing jams, etc. These doors (shown in the figure below) can be opened with a simple, unlocked door latch. However, opening these doors will activate a safety interlock switch that will be treated by the system as an E-Stop. The lift will be issued an STO command. The external safety output signal will not be affected by safety interlock signals.

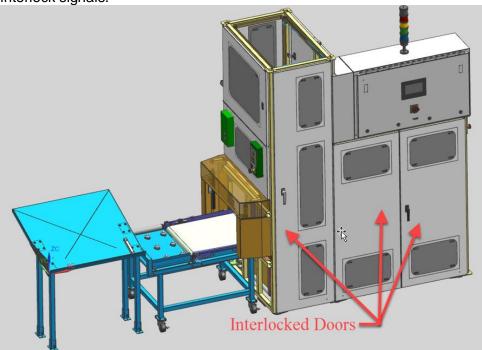


Figure 25. Door and Frame Interlock Switches

The HMI will display intuitive information to indicate which interlock sensor was activated.

3.3.5 Tote Entry Safety Curtain Logic

Within the buffer module, a safety rated light curtain will guard the open entry into the Destacker as shown in the figure below.

Light Curtain

Figure 26. Tote Entry Safety Curtain

This light curtain is intended to protect operators from the vertical motion of the lift in the Destacker. This device will meet or exceed the safety certifications shown below.

Safety classification		
ISO 13849-1		category 2, PL e
IEC 61508		SIL 3
IEC 62061		SILCL 3
Mission time TM	[h]	175200
Safety-related reliability PFHD	[1/h]	8.2E-09

Figure 27. Tote Entry Safety Curtain Classification

Anytime this curtain is breached by any object, an STO will be issued to the lift motor drive as previously described in section 3.3.2.1.

As a part of normal operation, the tote handler will regularly breach this light curtain as totes are loaded into Buffer 1. Until the condition is manually cleared by the tote handler (using the Buffer OCP), conveyors will remain active, but the lift will not move. It is important for the operator to reset the system as soon as conditions are safe to maximize utilization of the system.

After 30 seconds, an audible signal will be triggered to remind operator of the need to reset. The HMI will also log a warning for this condition.

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3.3.6 Tote Exit Safety Curtain Logic

Another light curtain will guard the exit end of the Destacker. This device will meet or exceed the safety certifications shown below.

Safety classification		
ISO 13849-1		Category 4, PL e
IEC 61508		SIL 3
IEC 62061		SILCL 3
MIssion time TM	[h]	175200
Safety-related reliability PFHD	[1/h]	1.5E-08

Figure 28. Tote Exit Safety Curtain Classification

As with the Entry Safety Curtain, standard machine operation will require totes to pass through this device. Unlike with tote entry, however, stopping the Lift motor will not impact system performance at the exit end of the Destacker. For this reason, the PLC will choose between SOS and STO (both are safety rated stop mechanisms) anytime the safety curtain is blocked. The decision between SOS and STO will depend on whether the PLC is expecting a tote to convey through. If a tote is expected, an SOS will be issued. As previously described, unexpected behavior during an SOS could trigger the STO. Any other time the curtain is breached, an STO will be issued.

Using this approach, non-safety rated PLC logic is only being used to choose between the two different safety rated stopping mechanisms (STO vs SOS, with STO being the default) to ensure the motor stops and remains stopped anytime the curtain is blocked.

Any unexpected breach of the exit safety curtain (resulting in an STO to the lift), will be treated by the control system as an E-Stop condition except the external safety output signal will not be affected.

3.3.6.1 Tote Exit Safety Curtain Position

The minimum distance between the exit safety curtain and the danger point within the lift is calculated according to the following formula:

The safety distance (Ds) from the sensing field to the point of operation should be greater than the distance determined by the following formula: Ds = (63 inches/seconds) X (Ts) +Dpf Where: Ds = minimum safety distance (inches) 63 inches/second = hand speed constant Ts = stopping time **Dpf:** Maximum travel towards the hazard within the presence sensing safety guarding device field that may occur before a stop is signaled. Also known as Depth of penetration.

Figure 29. Safety Distance Calculation

Using the actual loads on the lift and the lift motor performance parameters, the following calculations were used to determine the minimum safe distance between the light curtain and the pinch point between at the lift mechanism would be no less than 4.0 inches:

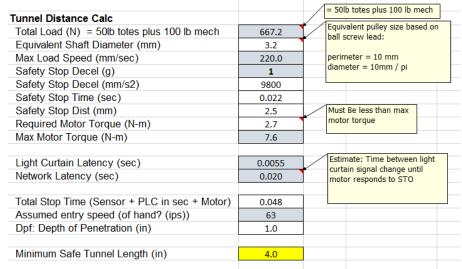


Figure 30. Exit Light Curtain Position Calculation

Figure 31 below shows the current distance from the light curtain to the pinch point between the Destacker Lift Conveyor and the Exit Conveyor.

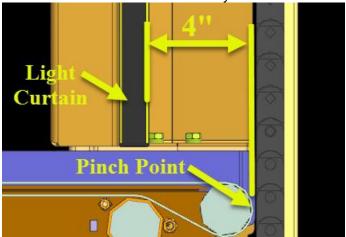


Figure 31. Light Curtain Configuration

4. Spare Parts

A recommended spare parts list is provided with the Proposal for the Customer to purchase. This list includes most active components

The recommended Spares list includes a limited number of the consumable wear items (e.g. Belts, etc.). It is recommended that these items be monitored closely for replacement rate and adequate stock kept in house.

Siemens keeps limited stock of all these parts for sale upon request.

5. Training

Siemens offers onsite training to the Customer. Siemens can provide training to Customer's designated employees to operate and maintain the units so that Customer's employees will have the capability to (1) operate, (2) diagnose the reasons for failures, (3) identify defective components, (4) remove the defective components, and (5) install new or repaired components. The cost for the training is as set forth in the Proposal.

6. Exclusions

The Proposal (NOT this document) is the official document listing what is included and not included in the purchase of a Siemens VarioStack.

This document (Functional Description) is for reference as a guide for planning use of a Siemens VarioStack within a logistics facility.

7. Software Limited Warranty and License

Siemens warrants that the software provided by Siemens ("Software") under a purchase order will conform to its published specifications and will not prevent the RUBUS® from achieving the performance criteria and guarantees set forth in the Functional Requirements Specification for a period of one (1) year from the date of acceptance. Siemens shall pass through any additional or extended warranties provided by the original manufacturer or other third-party software provider to the extent permitted by the terms of Siemens's license with the third-party manufacturer or software provider.

8. Warranty Disclaimer

Siemens makes no warranty, express or implied, regarding the software sold under the price schedule other than the warranties expressly set forth in this functional specification. Without limitation and to the maximum extent permitted by law, Siemens makes no and expressly disclaims any warranty of merchantability or fitness for a particular purpose. Without waiving or modifying Siemens's warranty obligations under the functional specifications, Siemens further disclaims any warranty that operation of the software or any third-party software will be uninterrupted or error free.

9. Appendix A – Footprint Requirements

The combined length requirement of the Operator Table, Exit Module, Destacker, and Buffer Module is assumed to be no more than 3,488mm based on the lengths of components described below.

The overall width requirement of 2,780mm is based on the width and spacing of the two destackers. These dimensions are also further described below.

9.1 Length Requirement For Operator Table And Exit Module

The dimensions below were extracted from initial customer requirements.

A file called "Station Design V11.pdf", referenced within the original describes the layout of the Operator Table and Roller Table.

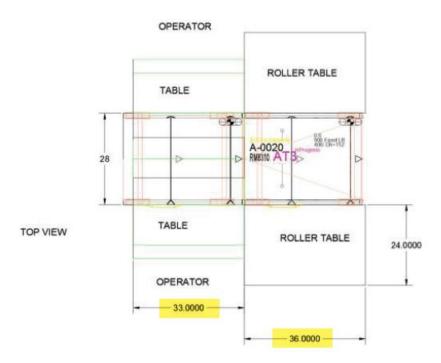


Figure 32. RFP Definition of Operator Table and Roller Table Dimentions (In Inches)

Siemens will replace the Roller Table in this figure with a driven belt conveyor section along with a passive ball table. These two components will be the Exit Module. Siemens designed the Exit Module to fit in the same footprint as the Roller Table defined above.

9.2 Length Requirement For Destacker And Buffer Module

Siemens later received Autocad layouts that defined the overall size of the Destacker and Buffer Modules to be no more than 2780mm wide and 1735mm long (direction of tote travel). This is also shown below in Figure 33.

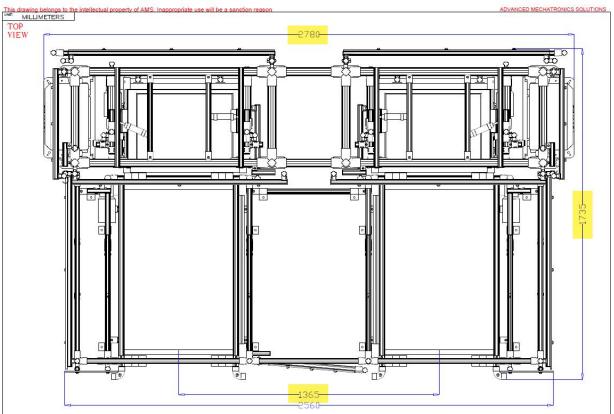


Figure 33. Required outer dimensions (previous Destacker prototype)

10. Appendix B – Safety Components

Individual component specifications can be provided upon request.

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1 ... 60 999; subdivided into: number range that can be used by the user: 1 ... 59 999, and number range of DBs created via SFC 86: 60 000 ... 60 999

DRAWING NUMBER 660.123890

SHEET 4

1 Mbyte; For DBs with absolute addre KB

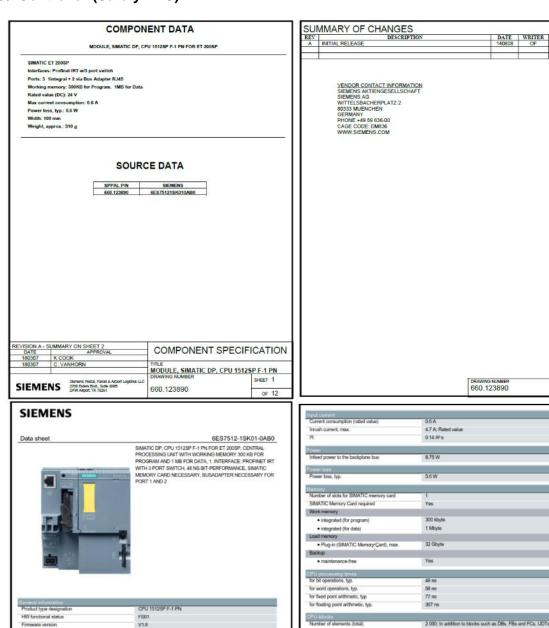
300 kbyte

300 kbyte

100

SHEET 2

10.1 Controller (Safety PLC)



Use or disclosure of data on this sheet is subject to the restriction on the title page of this document.

• Number range

• Size, max.

• Size, max.

• Size, max.

Number of free cycle OBs

permissible range, lower limit (DC) permissible range, upper limit (DC) Reverse polarity protection

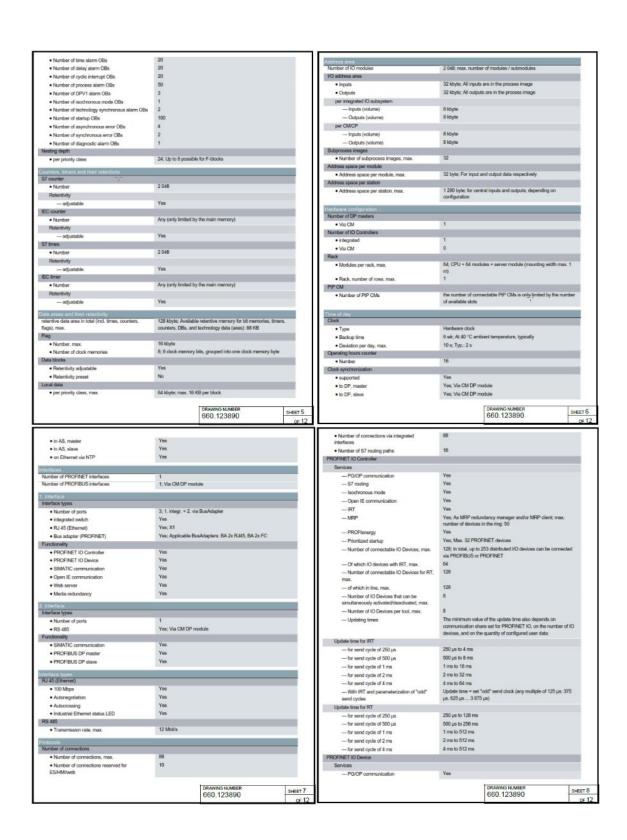
Mains buffering

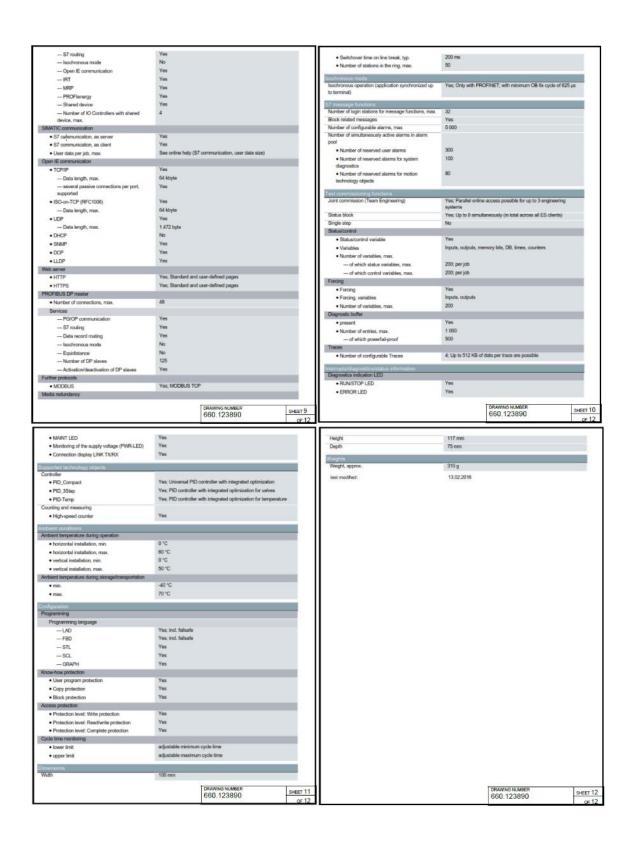
Firmware version

V13 SP1 Update 4

660.123890

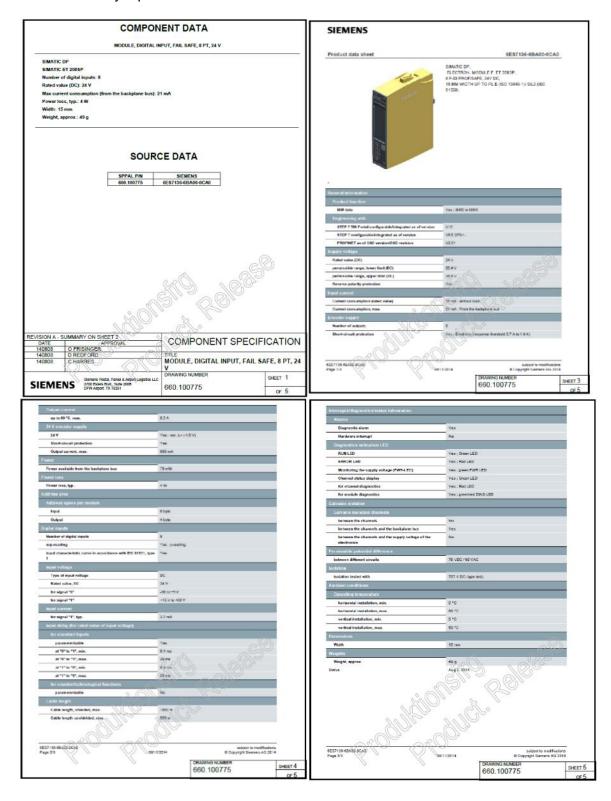
SHEET 3



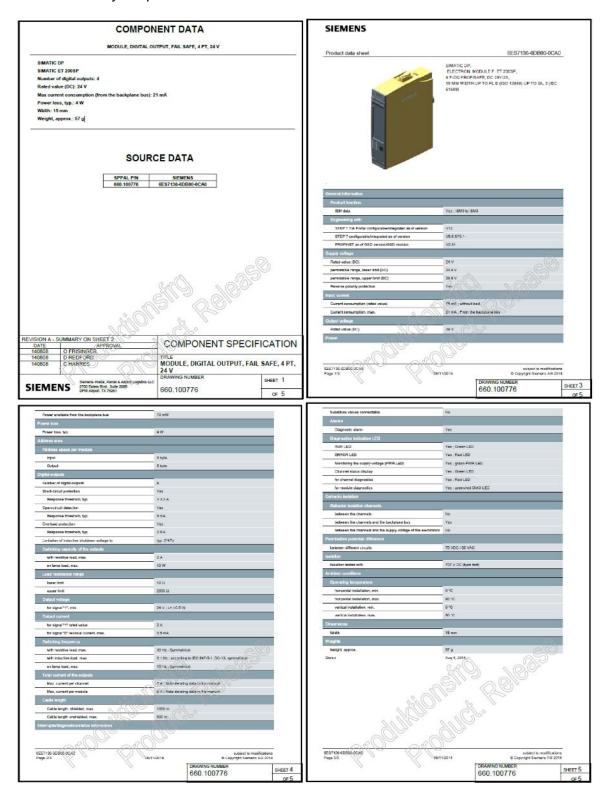


10.2 Safety I/O Modules

10.2.1 Safety Input Module



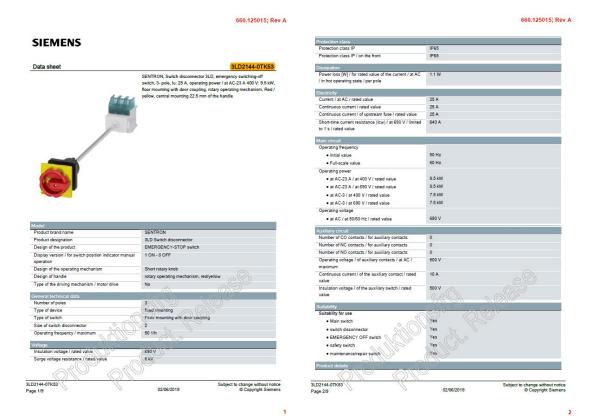
10.2.2 Safety Output Module

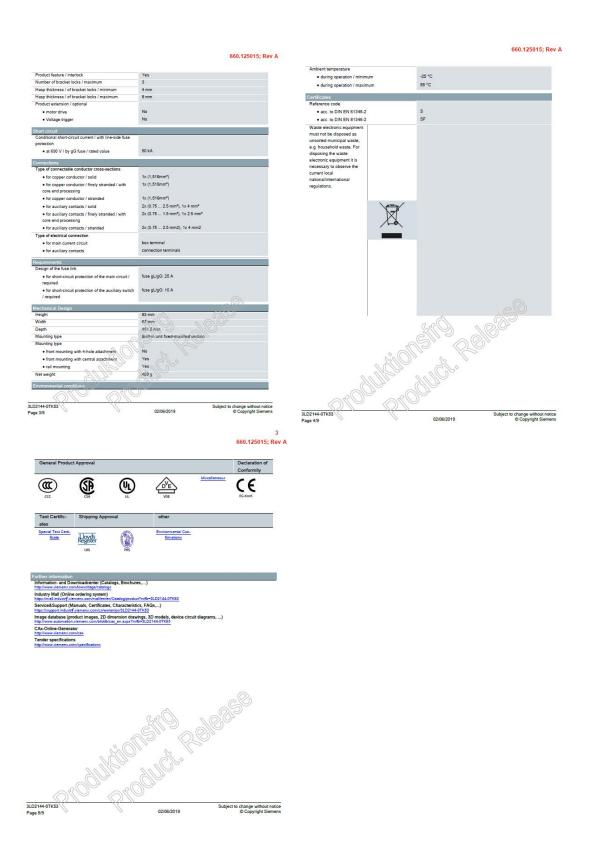


10.3 Safety Disconnect Switch

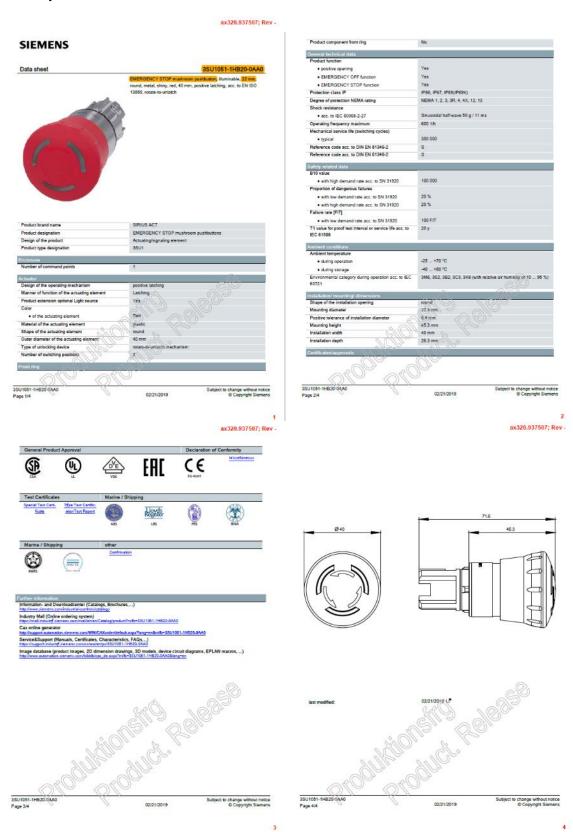
The prescribed disconnect switch provides the following safety features:

- When panel door is open, system power will be completely disconnected and touch-safe.
- Switch can be overridden, but tools are required for that.
- · Lockout feature prevents ability to override disconnect switch, even with tools.



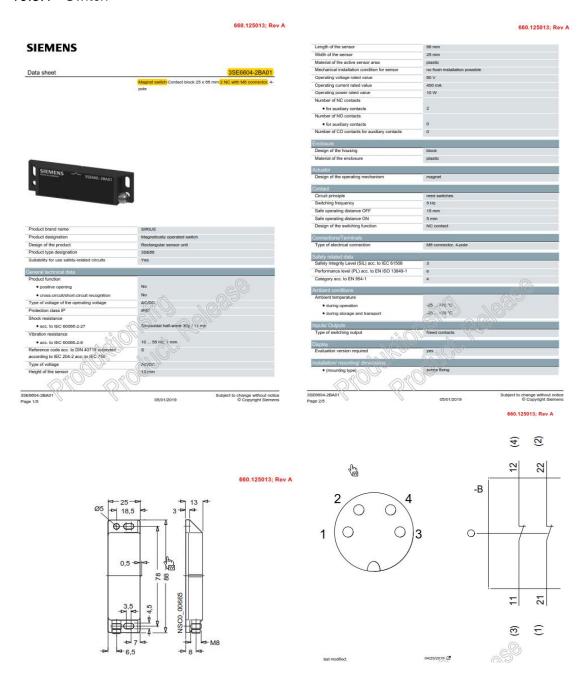


10.4 E-Stop Push Button



10.5 Safety Interlock Switches

10.5.1 Switch

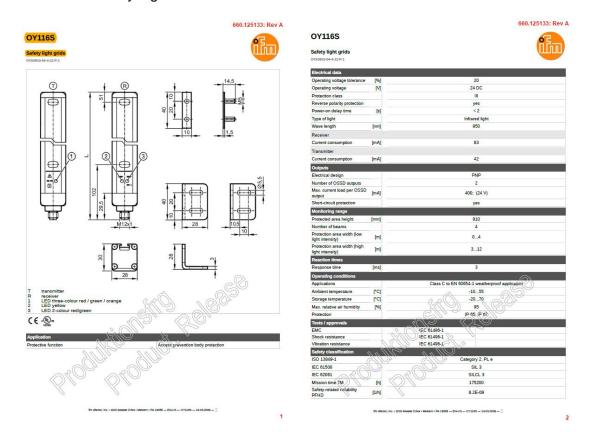


10.5.2 Interlock Magnet

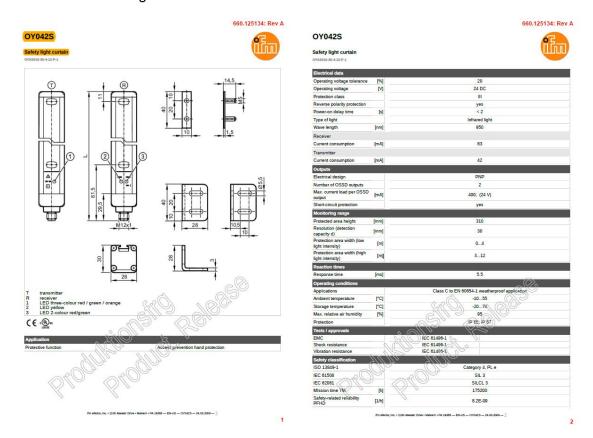


10.6 Safety Light Curtains

10.6.1 Tote Entry Light Curtain



10.6.2 Tote Exit Light Curtain

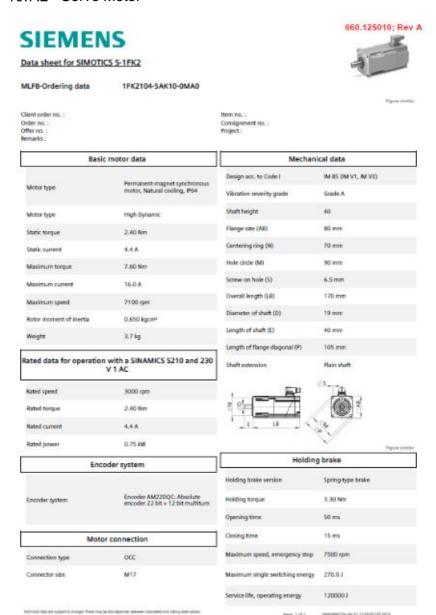


10.7 Lift Motor

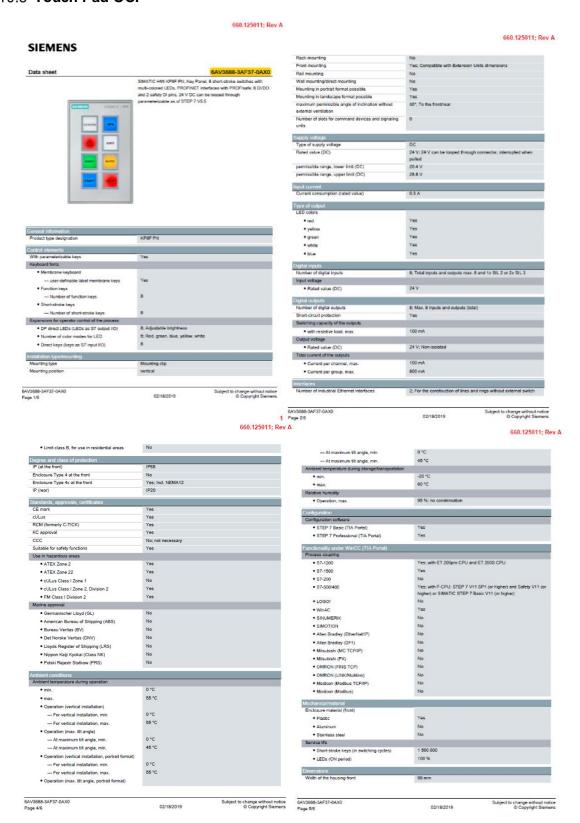
10.7.1 Motor Controller



10.7.2 Servo Motor



10.8 Touch Pad OCP



10.9 Phase Monitor - PN 660.005953



11. Appendix C – Acronyms

Acronym	Definition
SOW	Statement of Work
DFMA	Design for Manufacture and
	Assembly
DTC	Design to Cost
ВОМ	Bill of Materials
TDP	Technical Data Package
R&D	Research and Development
VFD	Variable Frequency Drive
SCM	Supply Chain Management
SCD	Source Control Documents
НМІ	Human Machine Interface
GDU	Graphic Display Unit
MCP	Main Control Panel
PE	Photoeye
PLC	Programmable Logic Controller
STO	Safe Torque Off
LH	Left Hand
RH	Right Hand
CW	Clock Wise
CCW	Counter Clock Wise