Maintenance Job Planning/Estimating Worksheet								
Planner: WO#:					Date:			
Job Contact: Location:					Asset ID#:			
Job Description: RWC4 EoAT Side Clamp adjustment								
	ans Required: 2 Time: 0.75 hours							
Elapsed Time: 0.75 hours Job Scope								
			JOD 300	ope	T .			
Job Plan Seq.	Task Description		Task Duration	Technicians Required	Estimated Labor Hours	Reference Pictures		
10	Create a project work order and populate the equipment field with the EoAT asset of the specific workcell. The asset should have profile JRWCV5 applied.		0.02	1	0.02			
20	Always follow OSHA, LOTO, PTP, NFPA, and Amazon Safety Policies before placing hands on equipment.		0.01	2	0.02			
30	"Take 2 for Safety". Review the area you will be working in, inspect for potential barriers or unsafe conditions.		0.03	2	0.06			
40	Use required PPE as needed to complete the job. Gloves, safety glasses, etc.		0.01	2	0.02			
50	Ensure there is a minimum of 50 full, unprocessed totes offstacked or at the infeed for adequate testing after the job is complete.		0.02	1	0.02			
Visual Inspection								
60	Request access to the cell, apply the coil wristband, remove pallet 5, and return the robot to operation.		0.01	2	0.02	Pallet location 6 Pallet location 6 Pallet location 7 Pallet location 1		
70	Select Navigation Menu (1) on the HMI and select Login. Enter the username MAINT and the password 1234, and select Login. Tap Login in the popup menu. Select Setup and access the Robot Control screen. Press the cycle stop and fault reset pushbuttons on the HMI pedestal. Place the machine in Manual Mode (2), move the robot to Maintenance Position 1 (3), and press Side Clamps to Work (4).		0.02	2	0.04	To move Robot to maintenance position, meet the following conditions: Maintenance position, meet the following conditions: Mort dawn Maintenance position for dawn Maintenan		
80	The work cell and EoAT should appear as in the photo. Press the e-stop pushbutton at the trap key interlock, request access to the cell, apply the coil wristband, and enter the cell.		0.01	2	0.02			
90	Notice the play in the side clamps as you manually attempt to open and close them, as if you are gripping and releasing a tote. Pull the side clamps fully apart, in the open direction, until they stop. Make an accurate and precise measurement using a measuring tape from the outside edge of the side clamp to the outside edge of the other side clamp. Ensure that the measuring tape is level and that the tension of the measuring tape does not pull the side clamps together.		0.02	2	0.04	Outside Edge of Side Clamp Class		

100	If the measurement is greater than or less than 16 9/16, you will need to make a side clamp adjustment. Proceed to line 110 of this task plan. If the measurement is exactly 16 9/16", proceed to Line 200 for corner sensor recalibration.	0.01	2	0.02	16 X 7 1				
	Lock Out Tag Out								
110	Note: Two technicians are required to make an accurate adjustment. Ensure that the side clamps are in the closed (At Work) position. Turn the air supply to EXH to remove the air from the system. Turn off the main power switch on the Fanuc controller. Apply LOTO to the air supply and the Fanuc controller.	0.04	2	0.08					
120	Use 4 mm hex socket with a 3/8 drive ratchet to loosen the 12 screws from the overheight tote detection plates. DO NOT STRIP OUT THE SCREWS. DO NOT USE ANY RATCHET EXTENSIONS. ENSURE THE SCREW HEADS ARE CLEANED OUT AND THAT YOU HAVE FULL ENGAGEMENT BEFORE ATTEMPTING TO LOOSEN. Lower the overheight plates from the EoAT and store your ratchet and socket. Re-installation will be performed with a 4 mm T-handle wrench. Retain the fastener that threads into the center of the main shaft. Discard the remaining five fasteners.	0.06	2	0.12					
130	Determine which clamp to adjust first by measuring the distance from the frame truss to the outside edge of the side clamps on both sides. If one is greater than the other, adjustments must be made such that both sides are equal when complete.				2 SS 3 connect 4 covers				
140	Locate the four jam nuts on the two tie rods that connect the rotary toggle to the side clamps. Using an adjustable wrench on the flat portion of the tie rod and loosen all four jam nuts with a 17 mm open-end wrench. NOTE: SOME NUTS ARE REVERSE-THREADED. Run the jam nuts out as far as possible so they do not interfere with adjustments. Ensure the side clamps are fully spread apart in the "At Work" position. Prepare to make an accurate and precise measurement of the side clamps. Ensure your tape measure is not measuring at an angle while hooked on the other clamp. Ensure that the tension of the tape measure does not pull the side clamps together.	0.06	2	0.12	dam Núts				
150	Note the original dimension. As one technician makes an accurate and precise measurement of the side clamps, the other technician will gently rotate the tie rod with their fingers. The measuring technician will guide the other technician if the dimension is getting larger or smaller. If you are reducing the side clamp dimension, rotate the tie rod such that you remove 1/16" of overall length. If more reduction is necessary, rotate the other tie rod by 1/16". Alternate tie rods until the overall dimension is 16 9/16". NOTE: MAKING ALL ADJUSTMENT ON ONE SIDE WILL OFF-CENTER THE SIDE CLAMPS AND COULD CAUSE CRASHES AT THE PICK POSITIONS. Final adjustments should be made by verifying equal distance as measured in step 130.	0.06	2	0.12	4 5				
160	Gently finger-tighten the jam nuts such that you do not disturb the tie rod adjustments. Repeat the finger-tightening process while attempting to use more force to seat the adjustment securely. Gently use an adjustable wrench on the flat portion of the tie rod and a 17 mm openend wrench to lock the jam nuts into place. Verify your dimensions.	0.03	2	0.06					

170 Meas meas	ck that the side clamps are centered on the EoAT. sure from the frame trusses to the edge of the side approximate as performed in step 130. The approximate surement should be between 2 and 2 1/16". Ensure two measurements do not vary more than 1/16".	0.02	2	0.04	202-1/19		
overh 180 disca screv	Use a 4 mm T-handle allen wrench to re-install the overheight tote detection plates. Replace the five discarded fasteners with Shcs Flat Steel M6-1.00 x 20mm screws. Use removeable threadlocking adhesive (Ex. Blue Loc-Tite). Do not over-tighten.		2	0.08	Shcs Flat Steel M6-1.00x20mm Pk100 9013378242@1 Min: 1 PK/100 Def.Ordoty: 1 Max: 2 PK/100 Part#: 29DH66		
190 resto suppli appro able	Remove the LOTO from the Fanuc controller first and restore power to the unit. Remove LOTO from the air supply and restore pneumatic pressure. It will take approximately three minutes after restoring power to be able to clear faults, regardless of HMI functionality. While waiting, perform corner sensor recalibration.		2	0.06			
for co 200 arrow is loc	in the horizontal surface of the side clamps to prepare corner sensor re-calibration. Press the up/down ws to determine if the sensor is locked. If the sensor cked, hold both arrow buttons simultaneously for three conds to unlock the sensor.	0.05	2	0.10			
blinki numb will b 210 Press setpo will re butto	I "SET" for three seconds until it blinks. When it stops king, look at the display and subtract 50 from the ber. (Ex: if the sensor reads 453, the new setpoint be 403.) Each sensor will read a different value. It is the up/down arrows until the sensor shows the oint. The setpoint will not remain on the screen, but revert back to the original reading. Press an arrow on once more to ensure the set point is still your ulated value.	0.02	2	0.04	KEYENCE A O		
220	both arrows for three seconds to lock the sensor. In to step 180 until all four sensors are calibrated.	0.02	2	0.04			
the trensur press 230 (infection Hermonia) (1), p Mach	e a new pallet in pallet location 5. Pull the estop(s) on trap key interlock panels, re-insert the trap key(s), are the request access buttons are not illuminated, so the blue safety reset buttons in the correct order, ed, jackpot, HMI), and press the fault reset button on HMI pedestal. Press the Side Clamps At Home button press the Abort to Home button (2), press the hine In Auto Mode button (3), and press the Cycle to button on the HMI pedestal. Log out of the HMI.	0.03	2	0.06	To move Robot Control To move Robot to maintenance position, meet the following Conditions Ministenance Position, meet the following Conditions Ministenance NoT Gear Robot Issue Robot I		
•	Retu	rn To Op	perations				
240 are ir	ore returning machine to operation, ensure all guards in place and all safety devices are functioning erly. Ensure none of these were removed or damaged ng machine service.	0.02	2	0.04			
750	Remove all tools from area and ensure they are all accounted for		2	0.04			
260 Make	Make sure the area is clean and free of any debris		2	0.04			
270 Remo	Remove Lock Out/Tag Out		2	0.04			
790	Restart equipment, verify proper operation, no unusual noises or vibrations		2	0.04			
280 store pickir	Watch the robot process the totes previously offstacked or stored in the upstream conveyance. Ensure proper picking and placing.		2	0.06			
Total Job Plan Duration: 0.75 Total Backlog Labor Hours: 1.46 Safety Requirements							
Permits: Co		Hot Work	rements	Lo	ockout/Tagout X		
Tools and Materials: 4 mm T-handle wrench, 4 mm hex socket, 3/8 drive ratchet, measuring tape, adjustable wrench, 17 mm open-end wrench, (5) Schs Flat Steel M6-1.00 x 20mm screws, removeable thread locker (Ex. Blue Loc-Tite).							